## 1 Table of Contents

1.1 Overview ................................................................................................................. 3
1.2 Install Guides ........................................................................................................... 20
1.3 Admin Guide ........................................................................................................... 37
1.4 Advanced Topics ..................................................................................................... 780
1.5 Questions & Answers ............................................................................................... 1006
1.6 Reference Implementation ...................................................................................... 1009
1.7 Troubleshooting ...................................................................................................... 1021
1.8 Developers ............................................................................................................. 1024
1.9 Need Help ............................................................................................................... 1042
1.10 Security Notices .................................................................................................... 1042
xCAT stands for Extreme Cloud Administration Toolkit.

xCAT offers complete management of clouds, clusters, HPC, grids, datacenters, renderfarms, online gaming infrastructure, and whatever tomorrow's next buzzword may be.

**xCAT enables the administrator to:**

1. Discover the hardware servers
2. Execute remote system management
3. Provision operating systems on physical or virtual machines
4. Provision machines in Diskful (stateful) and Diskless (stateless)
5. Install and configure user applications
6. Parallel system management
7. Integrate xCAT in Cloud

You've reached xCAT documentation site. The main page product page is [http://xcat.org](http://xcat.org)

xCAT is an open source project hosted on [GitHub](http://github.com). Go to GitHub to view the source, open issues, ask questions, and participate in the project.

Enjoy!
1.1 Overview

xCAT enables you to easily manage large number of servers for any type of technical computing workload. xCAT is known for exceptional scaling, wide variety of supported hardware and operating systems, virtualization platforms, and complete “day0” setup capabilities.

1.1.1 Differentiators

- **xCAT Scales**
  Beyond all IT budgets, up to 100,000s of nodes with distributed architecture.

- **Open Source**
  Eclipse Public License. Support contracts are also available, contact IBM.

- **Supports Multiple Operating Systems**
  RHEL, SLES, Ubuntu, Debian, CentOS, Fedora, Scientific Linux, Oracle Linux, Windows, Esxi, RHEV, and more!

- **Support Multiple Hardware**
  IBM Power, IBM Power LE, x86_64

- **Support Multiple Virtualization Infrastructures**
  IBM PowerKVM, KVM, IBM zVM, ESXI, XEN

- **Support Multiple Installation Options**
  Diskful (Install to Hard Disk), Diskless (Runs in memory), Cloning

- **Built in Automatic discovery**
  No need to power on one machine at a time for discovery. Nodes that fail can be replaced and back in action simply by powering the new one on.
• RestFUL API
  Provides a Rest API interface for the third-party software to integrate with

1.1.2 Features

1. Discover the hardware servers
   • Manually define
   • MTMS-based discovery
   • Switch-based discovery
   • Sequential-based discovery

2. Execute remote system management against the discovered server
   • Remote power control
   • Remote console support
   • Remote inventory/vitals information query
   • Remote event log query

3. Provision Operating Systems on physical (Bare-metal) or virtual machines
   • RHEL
   • SLES
   • Ubuntu
   • Debian
   • Fedora
   • CentOS
   • Scientific Linux
   • Oracle Linux
   • PowerKVM
   • Esxi
   • RHEV
   • Windows
   • AIX

4. Provision machines in
   • Diskful (Scripted install, Clone)
   • Stateless

5. Install and configure user applications
   • During OS install
   • After the OS install
   • HPC products - GPFS, Parallel Environment, LSF, compilers 
   • Big Data - Hadoop, Symphony
• Cloud - Openstack, Chef

6. Parallel system management
   • Parallel shell (Run shell command against nodes in parallel)
   • Parallel copy
   • Parallel ping

7. Integrate xCAT in Cloud
   • Openstack
   • SoftLayer

1.1.3 Operating System & Hardware Support Matrix

<table>
<thead>
<tr>
<th></th>
<th>Power</th>
<th>Power LE</th>
<th>zVM</th>
<th>Power KVM</th>
<th>x86_64</th>
<th>x86_64 KVM</th>
<th>x86_64 Esxi</th>
</tr>
</thead>
<tbody>
<tr>
<td>RHEL</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>SLES</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>Ubuntu</td>
<td>no</td>
<td>yes</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>CentOS</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
<tr>
<td>AIX</td>
<td>yes</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>no</td>
</tr>
<tr>
<td>Windows</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
</tr>
</tbody>
</table>

1.1.4 Architecture

The following diagram shows the basic structure of xCAT:
**xCAT Management Node (xCAT Mgmt Node):** The server where xCAT software is installed and used as the single point to perform system management over the entire cluster. On this node, a database is configured to store the xCAT node definitions. Network services (dhcp, tftp, http, etc) are enabled to respond in Operating system deployment.

**Service Node:** One or more defined “slave” servers operating under the Management Node to assist in system management to reduce the load (cpu, network bandwidth) when using a single Management Node. This concept is necessary when managing very large clusters.

**Compute Node:** The compute nodes are the target servers which xCAT is managing.

**Network Services (dhcp, tftp, http, etc):** The various network services necessary to perform Operating System deployment over the network. xCAT will bring up and configure the network services automatically without any intervention from the System Administrator.

**Service Processor (SP):** A module embedded in the hardware server used to perform the out-of-band hardware control. (e.g. Integrated Management Module (IMM), Flexible Service Processor (FSP), Baseboard Management Controller (BMC), etc)

**Management network:** The network used by the Management Node (or Service Node) to install operating systems and manage the nodes. The Management Node and in-band Network Interface Card (NIC) of the nodes are
connected to this network. If you have a large cluster utilizing Service Nodes, sometimes this network is
segregated into separate VLANs for each Service Node.

**Service network:** The network used by the Management Node (or Service Node) to control the nodes using out-of-
band management using the Service Processor. If the Service Processor is configured in shared mode (meaning
the NIC of the Service process is used for the SP and the host), then this network can be combined with the
management network.

**Application network:** The network used by the applications on the Compute nodes to communicate among each
other.

**Site (Public) network:** The network used by users to access the Management Nodes or access the Compute Nodes
directly.

**RestAPIs:** The RestAPI interface can be used by the third-party application to integrate with xCAT.

### 1.1.5 Quick Start Guide

If xCAT looks suitable for your requirement, following steps are recommended procedure to set up an xCAT cluster.

1. Find a server as your xCAT management node
   
   The server can be a bare-metal server or a virtual machine. The major factor for selecting a server is the number
   of machines in your cluster. The bigger the cluster is, the performance of server need to be better.

   **NOTE:** The architecture of xCAT management node is recommended to be same as the target compute node in
   the cluster.

2. Install xCAT on your selected server
   
   The server which installed xCAT will be the xCAT Management Node.

   Refer to the doc: xCAT Install Guide to learn how to install xCAT on a server.

3. Start to use xCAT management node
   
   Refer to the doc: xCAT Admin Guide.

4. Discover target nodes in the cluster
   
   You have to define the target nodes in the xCAT database before managing them.

   For a small cluster (less than 5), you can collect the information of target nodes one by one and then define them
   manually through mkdef command.

   For a bigger cluster, you can use the automatic method to discover the target nodes. The discovered nodes will
   be defined to xCAT database. You can use lsdef to display them.

   Refer to the doc: xCAT discovery Guide to learn how to discover and define compute nodes.

5. Try to perform the hardware control against the target nodes
   
   Now you have the node definition. Verify the hardware control for defined nodes is working. e.g. rpower
   <node> stat.

   Refer to the doc: Hardware Management to learn how to perform the remote hardware control.

6. Deploy OS on the target nodes
   
   - Prepare the OS images
   - Customize the OS images (Optional)
   - Perform the OS deployment

   Refer to the doc: Diskful Install, Diskless Install to learn how to deploy OS for a target node.
7. Update the OS after the deployment

You may require to update the OS of certain target nodes after the OS deployment, try the `updatenode` command. `updatenode` command can execute the following tasks for target nodes:

- Install additional software/application for the target nodes
- Sync some files to the target nodes
- Run some postscript for the target nodes

Refer to the doc: `Updatenode` to learn how to use `updatenode` command.

8. Run parallel commands

When managing a cluster with hundreds or thousands of nodes, operating on many nodes in parallel might be necessary. xCAT has some parallel commands for that.

- Parallel shell
- Parallel copy
- Parallel ping

Refer to the `Parallel Commands` to learn how to use parallel commands.

1. Contribute to xCAT (Optional)

While using xCAT, if you find something (code, documentation, ... ) that can be improved and you want to contribute that to xCAT, do that for your and other xCAT users benefit. And welcome to xCAT community!

Refer to the `Developers` to learn how to contribute to xCAT community.

### 1.1.6 xCAT2 Release Information

The following table is a summary of the new operating system (OS), hardware, and features that are added to each xCAT release. The OS and hardware listed in the table have been fully tested with xCAT. For a more detailed list of new function, bug fixes, restrictions and known problems, refer to the individual release notes for a specific release.

- **RHEL** - Red Hat Enterprise Linux
- **SLES** - Suse Linux Enterprise Server
- **UBT** - Ubuntu
## xCAT 2.14.x

<table>
<thead>
<tr>
<th>xCAT Version</th>
<th>New OS</th>
<th>New Hardware</th>
<th>New Feature</th>
</tr>
</thead>
</table>
| xCAT 2.14.5 2018/12/07 2.14.5 Release Notes | • RHEL7.6 | | • syslog tag refine  
• site:httpport support  
• localdisk GPT partition support  
• goconserver v0.3.2  
• xcat-inventory 0.1.6 |
| xCAT 2.14.4 2018/10/19 2.14.4 Release Notes | • UBT18.04.1 | |  |
| xCAT 2.14.3 2018/8/24 2.14.3 Release Notes | • SLES12.3 | | • OpenBMC rflash enhancement  
• xcat-inventory 0.1.5  
• goconserver v0.3.1 |
| xCAT 2.14.2 2018/7/13 2.14.2 Release Notes | • UBT 18.04  
• RHEL6.10 | |  |
| xCAT 2.14.1 2018/6/1 2.14.1 Release Notes | • RHV 4.2  
RHEL7.5 + p8 | | • OpenBMC in python enhancement: rinv enhance, issue #5176  
• Cumulus Switch OS - syncfile  
• Discover process enhancement  
• xcatprobe xcatmn enhancement  
• xcat-inventory enhancement(beta)  
• goconserver v0.2.2 |
| xCAT 2.14 2018/4/20 2.14 Release Notes | • RHEL 7.5 | | • OpenBMC support in python: rspconfig, reventlog  
• Performance Tuning doc update |
## xCAT 2.13.x

<table>
<thead>
<tr>
<th>xCAT Version</th>
<th>New OS</th>
<th>New Hardware</th>
<th>New Feature</th>
</tr>
</thead>
<tbody>
<tr>
<td>xCAT 2.13.11</td>
<td></td>
<td></td>
<td>- OpenBMC support in python: rpower, rbeacon, rsetboot, rinv, rvitals</td>
</tr>
<tr>
<td>2018/3/9</td>
<td></td>
<td></td>
<td>- goconserver enhancement: makegocons -q, -C cleanup</td>
</tr>
<tr>
<td>2.13.11 Release Notes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>xCAT 2.13.10</td>
<td></td>
<td></td>
<td>- OpenBMC support: rsconfig powersupplyredundancy, powerrestore-policy, bootmodereventlog implementation</td>
</tr>
<tr>
<td>2018/1/26</td>
<td></td>
<td></td>
<td>- goconserver enhancement: run goconserver on SN redirect console log</td>
</tr>
<tr>
<td>2.13.10 Release Notes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>xCAT 2.13.9</td>
<td></td>
<td></td>
<td>- OpenBMC support: rflash -a/-u enhancement, add -d reventlog implementation rsconfig dump, hostname, ntpserver, admin_passwd</td>
</tr>
<tr>
<td>2017/12/18</td>
<td></td>
<td></td>
<td>- goconserver for OpenBMC</td>
</tr>
<tr>
<td>2.13.9 Release Notes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>xCAT 2.13.8</td>
<td></td>
<td></td>
<td>- OpenBMC support: rflash/rpower run parallelly rsconfig sshcfg run parallelly</td>
</tr>
<tr>
<td>2017/11/3</td>
<td></td>
<td></td>
<td>- The document of MN HA</td>
</tr>
<tr>
<td>2.13.8 Release Notes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>xCAT 2.13.7</td>
<td></td>
<td></td>
<td>- OpenBMC support: rflash for OpenBMC and Host get/clear event log</td>
</tr>
<tr>
<td>2017/9/22</td>
<td></td>
<td></td>
<td>- xcatprobe cluster-status enhancement</td>
</tr>
<tr>
<td>2.13.7 Release Notes</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
## xCAT 2.12.x

<table>
<thead>
<tr>
<th>xCAT Version</th>
<th>New OS</th>
<th>New Hardware</th>
<th>New Feature</th>
</tr>
</thead>
<tbody>
<tr>
<td>xCAT 2.12.4</td>
<td>• RHEL 7.3 LE  &lt;br&gt;• RHEV 4.0</td>
<td>• noboot added to &lt;br&gt; dhcpinterface  &lt;br&gt;• new xcatprobe sub-&lt;br&gt;command: xcatmn, deploy and discover</td>
<td></td>
</tr>
<tr>
<td>2016/11/11</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.12.4 Release Notes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>xCAT 2.12.3</td>
<td>• UBT 16.04.1</td>
<td>• GitHub Issues re-&lt;br&gt; solved  &lt;br&gt;• rinv options for&lt;br&gt;OpenPOWER  &lt;br&gt;• switch based switch&lt;br&gt; discovery  &lt;br&gt;• additional options&lt;br&gt; added to xcatprobe&lt;br&gt; command  &lt;br&gt;• mkdef takes file&lt;br&gt; redirection</td>
<td></td>
</tr>
<tr>
<td>2016/09/30</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.12.3 Release Notes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>xCAT 2.12.2</td>
<td>• UBT 16.04.1</td>
<td>• nodeset &lt;noderange&gt; offline  &lt;br&gt;• Enhance: node status update  &lt;br&gt;• Support Bond for install nics  &lt;br&gt;• xcatprobe osdeploy -r (BETA)  &lt;br&gt;• New opt: packimage -m -c</td>
<td></td>
</tr>
<tr>
<td>2016/08/19</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.12.2 Release Notes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>xCAT 2.12.1</td>
<td>• RHEL 6.8  &lt;br&gt;• UBT 14.4.4 LE  &lt;br&gt;• UBT 16.04</td>
<td>• New xCAT install&lt;br&gt; tool: go-xcat  &lt;br&gt;• New opt: mkdef/lsdef –template  &lt;br&gt;• Support rinstall for all OS/ARCH  &lt;br&gt;• site.xcatdebugmode for diskless  &lt;br&gt;• Refine discovery&lt;br&gt; framework  &lt;br&gt;• rscan &lt;kvmhost&gt;  &lt;br&gt;• New: xcatprobe&lt;br&gt; (experimental)</td>
<td></td>
</tr>
<tr>
<td>2016/07/08</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.12.1 Release Notes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>xCAT 2.12</td>
<td>• RHEL 6.8  &lt;br&gt;• UBT 14.4.4 LE  &lt;br&gt;• UBT 16.04</td>
<td>• Docker: xCAT in&lt;br&gt;Docker  &lt;br&gt;• Docker: container life cycle mgt  &lt;br&gt;• New opt: packimage  &lt;br&gt;Docker Registry  &lt;br&gt;• New command: getadapter</td>
<td></td>
</tr>
<tr>
<td>2016/5/20</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.12 Release Notes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>xCAT 2.12.4</td>
<td>• RHEL 7.3 LE  &lt;br&gt;• RHEV 4.0</td>
<td>• noboot added to &lt;br&gt; dhcpinterface  &lt;br&gt;• new xcatprobe sub-&lt;br&gt;command: xcatmn, deploy and discover</td>
<td></td>
</tr>
<tr>
<td>2016/11/11</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.12.4 Release Notes</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
**xCAT 2.11.x**

<table>
<thead>
<tr>
<th>xCAT Version</th>
<th>New OS</th>
<th>New Hardware</th>
<th>New Feature</th>
</tr>
</thead>
<tbody>
<tr>
<td>xCAT 2.11.1</td>
<td>• RHEL 7.2 LE</td>
<td>• S822LC(GCA)</td>
<td>• Bug fix</td>
</tr>
<tr>
<td>2016/04/22</td>
<td>• UBT 14.4.3 LE</td>
<td>• S822LC(GTA)</td>
<td></td>
</tr>
<tr>
<td>2.11.1 Release Notes</td>
<td>• UBT 15.10 LE</td>
<td>• S812LC</td>
<td></td>
</tr>
<tr>
<td></td>
<td>• PowerKVM 3.1</td>
<td>• NeuCloud OP</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>• ZoomNet RP</td>
<td></td>
</tr>
<tr>
<td>xCAT 2.11</td>
<td></td>
<td></td>
<td>• NVIDIA GPU for OpenPOWER</td>
</tr>
<tr>
<td>2015/12/11</td>
<td></td>
<td></td>
<td>• Infiniband for OpenPOWER</td>
</tr>
<tr>
<td>2.11 Release Notes</td>
<td>• SW KIT support for OpenPOWER</td>
<td></td>
<td>• reenergy command for OpenPOWER</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• rflash command for OpenPOWER</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Add xCAT Troubleshooting Log</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• xCAT Log Classification</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• RAID Configuration</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Accelerate genimage process</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Add bmcdiscover Command</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Enhance xcatdebugmode</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• new xCAT doc in ReadTheDocs</td>
</tr>
</tbody>
</table>

1.1. Overview
## xCAT 2.10.x

<table>
<thead>
<tr>
<th>xCAT Version</th>
<th>New OS</th>
<th>New Hardware</th>
<th>New Feature</th>
</tr>
</thead>
<tbody>
<tr>
<td>xCAT 2.10</td>
<td>RHEL 7.1 LE</td>
<td>Power 8 LE</td>
<td>Ubuntu LE -&gt; RH 7.1 Mix</td>
</tr>
<tr>
<td>2015/07/31</td>
<td>UBT 15.4 LE</td>
<td></td>
<td>Cuda install for Ubuntu 14.4.2</td>
</tr>
<tr>
<td></td>
<td>SLES 12 LE</td>
<td></td>
<td>additional kernel parameters</td>
</tr>
<tr>
<td></td>
<td>RHEL 6.7</td>
<td></td>
<td>customized disk part (Ubuntu)</td>
</tr>
<tr>
<td></td>
<td>CentOS 7.1</td>
<td></td>
<td>RAID configure base iprconfig</td>
</tr>
<tr>
<td></td>
<td>SLES 11 SP4</td>
<td></td>
<td>New command: switchdiscover</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>New command: makenp</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>New command: bmcdiscovery</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Support getmacs –noping</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>site.xcatdebugmode</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>validate netboot attribute</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>buildcore on local server</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>copycds generates fewer osimage</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>nodeset only accepts osimage=</td>
</tr>
</tbody>
</table>
## xCAT 2.9.x

<table>
<thead>
<tr>
<th>xCAT Version</th>
<th>New OS</th>
<th>New Hardware</th>
<th>New Feature</th>
</tr>
</thead>
<tbody>
<tr>
<td>xCAT 2.9.3 for AIX</td>
<td>• AIX 7.2.0</td>
<td>• Power 8 for AIX</td>
<td>• new format in synclist (node)</td>
</tr>
<tr>
<td>2016/03/11</td>
<td>• AIX 7.1.4.1</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.9.3 Release Notes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>xCAT 2.9.2 for AIX</td>
<td>• AIX 6.1.8.6</td>
<td>• Power 8 for AIX</td>
<td>• ssl version control in xcatd</td>
</tr>
<tr>
<td>2015/11/11</td>
<td>• AIX 6.1.9.5</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.9.2 Release Notes</td>
<td>• AIX 7.1.3.5</td>
<td></td>
<td></td>
</tr>
<tr>
<td>xCAT 2.9.1(^1)</td>
<td>• RHEL 7.1</td>
<td>• Nvidia GPU</td>
<td></td>
</tr>
<tr>
<td>2015/03/20</td>
<td>• UBT 14.04.2</td>
<td>• Ubuntu Local Mirror</td>
<td></td>
</tr>
<tr>
<td>2.9.1 Release Notes</td>
<td>• SLES 11 SP3 and later ONLY</td>
<td>• SLES12 diskless</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Energy management for Power 8</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>• RHEL 7.1 LE -&gt; BE mix cluster</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>• nics.nicextraparams</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>• xCAT in Docker Image</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>• confluent replaces conserver</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>• TLSv1 in xcatd</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>• New GPG key for xCAT packages</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>• fast restart xcatd (systemd)</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>• netboot method: grub2-tftp</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>• netboot method: grub2-http</td>
<td></td>
</tr>
<tr>
<td>xCAT 2.9</td>
<td>• UBT 14.4 LE</td>
<td>• Power 8 LE</td>
<td></td>
</tr>
<tr>
<td>2014/12/12</td>
<td>• UBT 14.4.1 LE</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.9 Release Notes</td>
<td>• UBT 14.10</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• SLES 12</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• RHIEL 6.6</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• AIX 7.1.3.15</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• PowerKVM</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• Power 8 LE</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

\(^1\) xCAT 2.9.1 onwards provides support for Kernel-based Virtual Machines (KVM) and requires an operating system that ships the...
perl-Sys-Virt package.
## xCAT 2.8.x

<table>
<thead>
<tr>
<th>xCAT Version</th>
<th>New OS</th>
<th>New Hardware</th>
<th>New Feature</th>
</tr>
</thead>
</table>
| xCAT 2.8.4   | • RHEL 6.5  
               • RHEL 5.10 | • RHEL 7 experimental,  
               • support xCAT cluster zones  
               • commands enhancements |
| 2014/03/23   |        |              |             |
| 2.8.4 Release Notes |        |              |             |
| xCAT 2.8.3   | • AIX 7.3.1.1  
               • AIX 7.3.1.0  
               • AIX 7.1.2 | • Xeon Phi (P2)  
               • NS nx360M4 | • xcatd flow control  
               • sysclone x86_64 image  
               • enhance genitird and nodeset  
               • enhance confignics, KIT  
               • enhance sequential discovery  
               • deploy OpenStack on Ubuntu |
| 2013/11/15   |        |              |             |
| 2.8.3 Release Notes |        |              |             |
| xCAT 2.8.2   | • SLES 11 SP3 | • Xeon Phi (P1) | • HPC KIT for ppc64  
               • sysclone x86_64 image (P1)  
               • enhance xdsh, updatenode  
               • localdisk for diskless  
               • enhance sequential discovery  
               • deploy OpenStack on Ubuntu |
| 2013/06/26   |        |              |             |
| 2.8.2 Release Notes |        |              |             |
| xCAT 2.8.1   | • RHEL 6.4  
               • RHEL 5.9 | • energy management for flex  
               • sequential discovery  
               • KIT enhancements  
               • osimage enhancements  
               • IPv6 enhancements  
               • def/xdsh/xdcp enhancements  
               • updatenode enhancements |
| 2013/06/26   |        |              |             |
| 2.8.1 Release Notes |        |              |             |
| xCAT 2.8     | • UBT 12.04  
               • WIN S 2012  
               • WIN 8 Hv | • Flex IMM setup  
               • Multiple Hostname  
               • KIT support  
               • KVM/zVM enhancements |
| 2013/02/28   |        |              |             |
| 2.8 Release Notes |        |              |             |

### 1.1. Overview

- RHEV Support
- Localdisk for statelite
- Manage MN itslef
- site auditskipcmds
### xCAT 2.7.x

<table>
<thead>
<tr>
<th>xCAT Version</th>
<th>New OS</th>
<th>New Hardware</th>
<th>New Feature</th>
</tr>
</thead>
</table>
| xCAT 2.7.8   | • AIX 7.1.3.1  
2014/01/24  
• AIX 7.1.3.0  
• AIX 6.1.9.1  
2.7.8 Release Notes | • RHEL 6.4 | • sinv for devices  
• Flex energy mgt and rbeacon |
| xCAT 2.7.7   | • RHEL 6.4 | 2013/03/17  
• SLES 10 SP4  
• AIX 6.1.8  
• AIX 7.1.2  
2.7.7 Release Notes | • HPC Integration updates |
| xCAT 2.7.6   | • SLES 10 SP4  
2012/11/30  
• AIX 6.1.8  
• AIX 7.1.2  
• HPC Integration updates  
2.7.6 Release Notes | • Flex  
• virtualization with RHEV  
• hardware discovery for x Flex  
• enhanced AIX HASN |
| xCAT 2.7.5   | • SLES 11 SP2  
2012/10/29  
• RHEL 6.3  
• HPC Integration updates  
2.7.5 Release Notes | • Flex  
• improved IPMI for large systems |
| xCAT 2.7.4   | • SLES 11 SP2  
2012/08/27  
• RHEL 6.2  
• HPC Integration updates  
2.7.4 Release Notes | • Flex  
• RHEV  
• power discovery for x Flex  
• enhanced AIX HASN |
| xCAT 2.7.3   | • AIX 7.1.1.3  
2012/06/22  
• Power 775  
• Flex for P  
2.7.3 Release Notes | • SLES 11 kdump  
• HPC Integration updates |
| xCAT 2.7.2   | • RHEL 6.3 | 2012/05/25  
• Power 775  
• Flex for P  
2.7.2 Release Notes | • minor enhancements  
• bug fixes |
| xCAT 2.7.1   | • RHEL 6.3 | 2012/04/20  
2.7.1 Release Notes | • xcatd memory usage reduced  
• xcatdebug for xcatd and plugins  
• lsetup command  
• x86_64 genesis boot image |
| xCAT 2.7     | • RHEL 6.2 | 2012/03/19  
2.7 Release Notes | • SLES 11 kdump  
• HPC Integration updates |
1.2 Install Guides

1.2.1 Installation Guide for Red Hat Enterprise Linux

For the current list of operating systems supported and verified by the development team for the different releases of xCAT, see the xCAT2 Release Notes.

Disclaimer These instructions are intended to only be guidelines and specific details may differ slightly based on the operating system version. Always refer to the operating system documentation for the latest recommended procedures.

Prepare the Management Node

These steps prepare the Management Node for xCAT Installation

Install an OS on the Management Node

Install one of the supported operating systems on your target management node.

The system requirements for your xCAT management node largely depend on the size of the cluster you plan to manage and the type of provisioning used (diskful, diskless, system clones, etc). The majority of system load comes during cluster provisioning time.

Memory Requirements:

<table>
<thead>
<tr>
<th>Cluster Size</th>
<th>Memory (GB)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Small (&lt; 16)</td>
<td>4-6</td>
</tr>
<tr>
<td>Medium</td>
<td>6-8</td>
</tr>
<tr>
<td>Large</td>
<td>&gt; 16</td>
</tr>
</tbody>
</table>

Configure the Base OS Repository

xCAT uses the yum package manager on RHEL Linux distributions to install and resolve dependency packages provided by the base operating system. Follow this section to create the repository for the base operating system on the Management Node

1. Copy the DVD iso file to /tmp on the Management Node. This example will use file RHEL-LE-7.1-20150219.1-Server-ppc64le-dvd1.iso

2. Mount the iso to /mnt/iso/rhels7.1 on the Management Node.

   ```
   mkdir -p /mnt/iso/rhels7.1
   mount -o loop /tmp/RHEL-LE-7.1-20150219.1-Server-ppc64le-dvd1.iso /mnt/iso/rhels7.1
   ```

3. Create a yum repository file /etc/yum.repos.d/rhels71-dvd.repo that points to the locally mounted iso image from the above step. The file contents should appear as the following:

   ```
   [rheil-7.1-dvd-server]
   name=RHEL 7 SERVER packages
   baseurl=file:///mnt/iso/rhels7.1/Server
   enabled=1
   gpgcheck=1
   ```
Configure the Management Node

By setting properties on the Management Node before installing the xCAT software will allow xCAT to automatically configure key attributes in the xCAT site table during the install.

1. Ensure a hostname is configured on the management node by issuing the `hostname` command. [It’s recommended to use a fully qualified domain name (FQDN) when setting the hostname]
   
   (a) To set the hostname of `xcatmn.cluster.com`:
   ```bash
   hostname xcatmn.cluster.com
   ```
   
   (b) Add the hostname to the `/etc/sysconfig/network` in order to persist the hostname on reboot.
   
   (c) Reboot the server and verify the hostname by running the following commands:
   ```bash
   • hostname
   • hostname -d - should display the domain
   ```

2. Reduce the risk of the Management Node IP address being lost by setting the IP to STATIC in the `/etc/sysconfig/network-scripts/ifcfg-<dev>` configuration files.

3. Configure any domain search strings and nameservers to the `/etc/resolv.conf` file.

Installing xCAT

The following sections describe the different methods for installing xCAT.

Automatic Install Using `go-xcat`

go-xcat is a tool that can be used to fully install or update xCAT. go-xcat will automatically download the correct package manager repository file from xcat.org and use the public repository to install xCAT. If the xCAT management node does not have internet connectivity, use process described in the Manual Installation section of the guide.

1. Download the `go-xcat` tool using `wget`:
   ```bash
   wget https://raw.githubusercontent.com/xcat2/xcat-core/master/xCAT-server/share/
   →xcat/tools/go-xcat -O - >/tmp/go-xcat
   chmod +x /tmp/go-xcat
   ```

2. Run the `go-xcat` tool:
   ```bash
   /tmp/go-xcat install # installs the latest stable version of xCAT
   /tmp/go-xcat -x devel install # installs the latest development version of xCAT
   ```

Manual Install Using Software Repositories

xCAT consists of two software packages: `xcat-core` and `xcat-dep`

1. **xcat-core** xCAT’s main software package and is provided in one of the following options:
   - Latest Release (Stable) Builds
     
     *This is the latest GA (Generally Availability) build that has been tested thoroughly*
   - Latest Snapshot Builds
This is the latest snapshot of the GA version build that may contain bug fixes but has not yet been tested thoroughly

- **Development Builds**
  
  This is the snapshot builds of the new version of xCAT in development. This version has not been released yet, use as your own risk

2. **xcat-dep** xCAT’s dependency package. This package is provided as a convenience for the user and contains dependency packages required by xCAT that are not provided by the operating system.

xCAT is installed by configuring software repositories for **xcat-core** and **xcat-dep** and using yum package manager. The repositories can be publicly hosted or locally hosted.

## Configure xCAT Software Repository

xCAT software and repo files can be obtained from: [http://xcat.org/download.html](http://xcat.org/download.html)

### Internet Repository

**[xcat-core]**

For the xCAT build you want to install, download the **xcat-core.repo** file and copy to /etc/yum.repos.d

**[xcat-dep]**

From the **xCAT-dep Online Repository**, navigate to the correct subdirectory for the target machine and download the **xcat-dep.repo** file and copy to /etc/yum.repos.d.

If using internet repositories, continue to the next step to install xCAT.

### Local Repository

**[xcat-core]**

1. Download xcat-core:

```
# downloading the latest development build, core-rpms-snap.tar.bz2
mkdir -p ~/xcat
cd ~/xcat/
wget http://xcat.org/files/xcat/xcat-core/devel/Linux/core-snap/core-rpms-snap.tar.bz2
```

2. Extract xcat-core:

```
tar jxvf core-rpms-snap.tar.bz2
```

3. Configure the local repository for xcat-core by running **mklocalrepo.sh** script in the **xcat-core** directory:

```
cd ~/xcat/xcat-core
./mklocalrepo.sh
```

**[xcat-dep]**

Unless you are downloading **xcat-dep** to match a specific package tested with a GA release, it’s recommended to download the latest version of xcat-dep.
1. Download xcat-dep:

```bash
# if downloading xcat-dep from June 11, 2015, xcat-dep-201506110324.tar.bz2
mkdir -p ~/xcat/
cd ~/xcat
wget http://xcat.org/files/xcat/xcat-dep/2.x_Linux/xcat-dep-201506110324.tar.bz2
```

2. Extract xcat-dep:

```bash
tar jxvf xcat-dep-201506110324.tar.bz2
```

3. Configure the local repository for xcat-dep by switching to the architecture and os subdirectory of the node you are installing on, then run the mklocalrepo.sh script:

```bash
cd ~/xcat/xcat-dep/
# Example, on redhat 7.1 ppc64le: cd rh7/ppc64le
cd <os>/<arch>/
./mklocalrepo.sh
```

### Install xCAT

Install xCAT with the following command:

```bash
yum clean all (optional)
yum install xCAT
```

**Note:** During the install, you must accept the xCAT Security Key to continue:

```
Retrieving key from file:///root/xcat/xcat-dep/rh6/ppc64/repodata/repomd.xml.key
Importing GPG key 0xC6565BC9:
    Userid: "xCAT Security Key <xcat@cn.ibm.com>"
    From : /root/xcat/xcat-dep/rh6/ppc64/repodata/repomd.xml.key
Is this ok [y/N]:
```

### Verify xCAT Installation

Quick verification of the xCAT Install can be done running the following steps:

1. Source the profile to add xCAT Commands to your path:

   ```bash
   source /etc/profile.d/xcat.sh
   ```

2. Check the xCAT version:

   ```bash
   lsxcatd -a
   ```

3. Check to verify that the xCAT database is initialized by dumping out the site table:

   ```bash
   tabdump site
   ```

   The output should be similar to the following:
#key,value,comments,disable
"blademaxp","64",,,
"domain","pok.stglabs.ibm.com",,,
"fsptimeout","0",,,
"installdir","/install",,,
"ipmimaxp","64",,,
"ipmiretries","3",,,
...

Starting and Stopping

xCAT is started automatically after the installation, but the following commands can be used to start, stop, restart, and check xCAT status.

- **start xCAT:**
  ```
  service xcatd start
  [systemd] systemctl start xcatd.service
  ```

- **stop xCAT:**
  ```
  service xcatd stop
  [systemd] systemctl stop xcatd.service
  ```

- **restart xCAT:**
  ```
  service xcatd restart
  [systemd] systemctl restart xcatd.service
  ```

- **check xCAT status:**
  ```
  service xcatd status
  [systemd] systemctl status xcatd.service
  ```

Updating xCAT

If at a later date you want to update xCAT, first, update the software repositories and then run:

```
yum clean metadata # or, yum clean all
yum update '*xCAT*' # To check and update the packages provided by xcat-dep:
yum update '*xcat*'
```

1.2.2 Installation Guide for SUSE Linux Enterprise Server

For the current list of operating systems supported and verified by the development team for the different releases of xCAT, see the xCAT2 Release Notes.

**Disclaimer** These instructions are intended to only be guidelines and specific details may differ slightly based on the operating system version. Always refer to the operating system documentation for the latest recommended procedures.
Prepare the Management Node

These steps prepare the Management Node for xCAT Installation

Install an OS on the Management Node

Install one of the supported operating systems on your target management node.

The system requirements for your xCAT management node largely depend on the size of the cluster you plan to manage and the type of provisioning used (diskful, diskless, system clones, etc). The majority of system load comes during cluster provisioning time.

Memory Requirements:

<table>
<thead>
<tr>
<th>Cluster Size</th>
<th>Memory (GB)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Small (&lt; 16)</td>
<td>4-6</td>
</tr>
<tr>
<td>Medium</td>
<td>6-8</td>
</tr>
<tr>
<td>Large</td>
<td>&gt; 16</td>
</tr>
</tbody>
</table>

Configure the Base OS Repository

xCAT uses the zypper package manager on SLES Linux distributions to install and resolve dependency packages provided by the base operating system. Follow this section to create the repository for the base operating system on the Management Node

1. Copy the DVD iso file to /tmp on the Management Node:

   # This example will use SLE-12-Server-DVD-ppc64le-GM-DVD1.iso

2. Mount the iso to /mnt/iso/sles12 on the Management Node.

   ```
   mkdir -p /mnt/iso/sles12
   mount -o loop /tmp/SLE-12-Server-DVD-ppc64le-GM-DVD1.iso /mnt/iso/sles12
   ```

3. Create a zypper repository file /etc/zypp/repos.d/sles12le-base.repo that points to the locally mounted iso image from the above step. The file contents should appear as the following:

   ```
   [sles-12-le-server]
   name=SLES 12 ppc64le Server Packages
   baseurl=file:///mnt/iso/sles12/suse
   enabled=1
   gpgcheck=1
   ```

Configure the Management Node

By setting properties on the Management Node before installing the xCAT software will allow xCAT to automatically configure key attributes in the xCAT site table during the install.

1. Ensure a hostname is configured on the management node by issuing the hostname command. [It’s recommended to use a fully qualified domain name (FQDN) when setting the hostname]

   a) To set the hostname of xcatmn.cluster.com:
hostname xcatmn.cluster.com

(b) Add the hostname to the /etc/hostname in order to persist the hostname on reboot.
(c) Reboot the server and verify the hostname by running the following commands:
   • hostname
   • hostname -d should display the domain

2. Reduce the risk of the Management Node IP address being lost by setting the IP to STATIC in the /etc/sysconfig/network/ifcfg-<dev> configuration files.
3. Configure any domain search strings and nameservers to the /etc/resolv.conf file.

Installing xCAT

The following sections describe the different methods for installing xCAT.

Automatic Install Using go-xcat

go-xcat is a tool that can be used to fully install or update xCAT. go-xcat will automatically download the correct package manager repository file from xcat.org and use the public repository to install xCAT. If the xCAT management node does not have internet connectivity, use process described in the Manual Installation section of the guide.

1. Download the go-xcat tool using wget:

   ```bash
   chmod +x /tmp/go-xcat
   ```

2. Run the go-xcat tool:

   ```bash
   /tmp/go-xcat install          # installs the latest stable version of xCAT
   /tmp/go-xcat -x devel install  # installs the latest development version of xCAT
   ```

Manual Install Using Software Repositories

xCAT consists of two software packages: xcat-core and xcat-dep

1. **xcat-core** xCAT's main software package and is provided in one of the following options:
   - Latest Release (Stable) Builds
     
     *This is the latest GA (Generally Availability) build that has been tested thoroughly*
   - Latest Snapshot Builds
     
     *This is the latest snapshot of the GA version build that may contain bug fixes but has not yet been tested thoroughly*
   - Development Builds
     
     *This is the snapshot builds of the new version of xCAT in development. This version has not been released yet, use at your own risk*

2. **xcat-dep** xCAT's dependency package. This package is provided as a convenience for the user and contains dependency packages required by xCAT that are not provided by the operating system.
xCAT is installed by configuring software repositories for xcat-core and xcat-dep and using yum package manager. The repositories can be publicly hosted or locally hosted.

Configure xCAT Software Repository

xCAT software and repo files can be obtained from: http://xcat.org/download.html

Internet Repository

[xcat-core]
For the xCAT build you want to install, download the xcat-core.repo file and copy to /etc/zypp/repos.d

[xcat-dep]
From the xCAT-dep Online Repository, navigate to the correct subdirectory for the target machine and download the xcat-dep.repo file and copy to /etc/zypp/repos.d.

If using internet repositories, continue to the next step to install xCAT.

Local Repository

[xcat-core]
1. Download xcat-core:

```
# downloading the latest development build, core-rpms-snap.tar.bz2
mkdir -p ~/xcat
cd ~/xcat/
wget http://xcat.org/files/xcat/xcat-core/devel/Linux/core-snap/core-rpms-snap.tar.bz2
```

2. Extract xcat-core:

```
tar jxvf core-rpms-snap.tar.bz2
```

3. Configure the local repository for xcat-core by running mklocalrepo.sh script in the xcat-core directory:

```
cd ~/xcat/xcat-core
./mklocalrepo.sh
```

[xcat-dep]
Unless you are downloading xcat-dep to match a specific package tested with a GA release, it’s recommended to download the latest version of xcat-dep.

1. Download xcat-dep:

```
# if downloading xcat-dep from June 11, 2015, xcat-dep-201506110324.tar.bz2
mkdir -p ~/xcat/
cd ~/xcat/
wget http://xcat.org/files/xcat/xcat-dep/2.x_Linux/xcat-dep-201506110324.tar.bz2
```

2. Extract xcat-dep:
tar jxvf xcat-dep-201506110324.tar.bz2

3. Configure the local repository for xcat-dep by switching to the architecture and os subdirectory of the node you are installing on, then run the mklocalrepo.sh script:

```bash
cd ~/xcat/xcat-dep/
# Example, on redhat 7.1 ppc64le: cd rh7/ppc64le
cd <os>/<arch>
./mklocalrepo.sh
```

Install xCAT

Install xCAT with the following command:

```
zypper clean all (optional)
zypper install xCAT
```

Note: During the install, you must accept the xCAT Security Key to continue

Verify xCAT Installation

Quick verification of the xCAT Install can be done running the following steps:

1. Source the profile to add xCAT Commands to your path:

```
source /etc/profile.d/xcat.sh
```

2. Check the xCAT version:

```
lsxcad -a
```

3. Check to verify that the xCAT database is initialized by dumping out the site table:

```
tabdump site
```

The output should be similar to the following:

```
#key,value,comments,disable
"blademaxp","64",,
"domain","pok.stglabs.ibm.com",,
"fsptimeout","0",,
"installdir","/install",,
"ipmimaxp","64",,
"ipmiretries","3",,
...
```

Starting and Stopping

xCAT is started automatically after the installation, but the following commands can be used to start, stop, restart, and check xCAT status.

- start xCAT:
service xcatd start
  [systemd] systemctl start xcatd.service

• stop xCAT:
  service xcatd stop
  [systemd] systemctl stop xcatd.service

• restart xCAT:
  service xcatd restart
  [systemd] systemctl restart xcatd.service

• check xCAT status:
  service xcatd status
  [systemd] systemctl status xcatd.service

**Updating xCAT**

If at a later date you want to update xCAT, first, update the software repositories and then run:

zypper refresh
zypper update "*xCAT*"

# To check and update the packages provided by xcat-dep:
zypper update "*xcat*"

### 1.2.3 Installation Guide for Ubuntu Server LTS

For the current list of operating systems supported and verified by the development team for the different releases of xCAT, see the [xCAT2 Release Notes](#).

**Disclaimer** These instructions are intended to only be guidelines and specific details may differ slightly based on the operating system version. Always refer to the operating system documentation for the latest recommended procedures.

**Prepare the Management Node**

These steps prepare the Management Node or xCAT Installation

**Install an OS on the Management Node**

Install one of the supported operating systems on your target management node.

The system requirements for your xCAT management node largely depend on the size of the cluster you plan to manage and the type of provisioning used (diskful, diskless, system clones, etc). The majority of system load comes during cluster provisioning time.

**Memory Requirements:**
Configure the Base OS Repository

xCAT uses the apt package manager on Ubuntu Linux distributions to install and resolve dependency packages provided by the base operating system. Follow this section to create the repository for the base operating system on the Management Node

1. Copy the DVD iso file to /tmp on the Management Node:

```bash
# This example will use ubuntu-18.04-server-ppc64el.iso
cp /path/to/ubuntu-18.04-server-ppc64el.iso /tmp
```

2. Mount the iso to /mnt/iso/ubuntu on the Management Node.

```bash
mkdir -p /mnt/iso/ubuntu
mount -o loop /tmp/ubuntu-18.04-server-ppc64el.iso /mnt/iso/ubuntu
```

3. Create an apt repository file /etc/apt.repos.d/ubuntu18-dvd.repo that points to the locally mounted iso image from the above step. The file contents should appear as the following:

```bash
[ubuntu-dvd-server]
name=Ubuntu 18.04 Server packages
baseurl=file:///mnt/iso/ubuntu/Server
enabled=1
gpgcheck=1
```

Configure the Management Node

By setting properties on the Management Node before installing the xCAT software will allow xCAT to automatically configure key attributes in the xCAT site table during the install.

1. Ensure a hostname is configured on the management node by issuing the `hostname` command. [It’s recommended to use a fully qualified domain name (FQDN) when setting the hostname]

   (a) To set the hostname of `xcatmn.cluster.com`:

   ```bash
   hostname xcatmn.cluster.com
   ```

   (b) Add the hostname to the `/etc/hostname` and `/etc/hosts` to persist the hostname on reboot.

   (c) Reboot or run `service hostname restart` to allow the hostname to take effect and verify the `hostname` command returns correctly:

   ```bash
   hostname
   hostname -d
   ```
   - should display the domain

2. Reduce the risk of the Management Node IP address being lost by setting the interface IP to `STATIC` in the `/etc/network/interfaces` configuration file.

3. Configure any domain search strings and nameservers using the `resolvconf` command.
Installing xCAT

The following sections describe the different methods for installing xCAT.

Automatic Install Using go-xcat

go-xcat is a tool that can be used to fully install or update xCAT. go-xcat will automatically download the correct package manager repository file from xcat.org and use the public repository to install xCAT. If the xCAT management node does not have internet connectivity, use process described in the Manual Installation section of the guide.

1. Download the go-xcat tool using wget:

   ```bash
   chmod +x /tmp/go-xcat
   ```

2. Run the go-xcat tool:

   ```bash
   /tmp/go-xcat install               # installs the latest stable version of xCAT
   /tmp/go-xcat -x devel install      # installs the latest development version of xCAT
   ```

Manual Install Using Software Repositories

xCAT consists of two software packages: xcat-core and xcat-dep

1. **xcat-core** xCAT’s main software package and is provided in one of the following options:
   - **Latest Release (Stable) Builds**
     
     This is the latest GA (Generally Availability) build that has been tested thoroughly
   - **Latest Snapshot Builds**
     
     This is the latest snapshot of the GA version build that may contain bug fixes but has not yet been tested thoroughly
   - **Development Builds**
     
     This is the snapshot builds of the new version of xCAT in development. This version has not been released yet, use at your own risk

2. **xcat-dep** xCAT’s dependency package. This package is provided as a convenience for the user and contains dependency packages required by xCAT that are not provided by the operating system.

xCAT is installed by configuring software repositories for xcat-core and xcat-dep and using yum package manager. The repositories can be publicly hosted or locally hosted.

Configure xCAT Software Repository

xCAT software and repo files can be obtained from: http://xcat.org/download.html

Internet Repository

[xcat-core]

From the xCAT download page, find the build you want to install and add to /etc/apt/sources.list.
To configure the xCAT development build, add the following line to /etc/apt/sources.list:

```
[For x86_64 servers]
deb [arch=amd64] http://xcat.org/files/xcat/repos/apt/devel/core-snap bionic main
[For ppc64el servers]
deb [arch=ppc64el] http://xcat.org/files/xcat/repos/apt/devel/core-snap bionic main
```

[xcat-dep]
To configure the xCAT deps online repository, add the following line to /etc/apt/sources.list:

```
[For x86_64 servers]
[For ppc64el servers]
deb [arch=ppc64el] http://xcat.org/files/xcat/repos/apt/latest/xcat-dep bionic main
```

If using internet repositories, continue to the next step to install xCAT.

**Local Repository**

**[xcat-core]**

1. Download xcat-core:

   ```
   # downloading the latest development build, core-rpms-snap.tar.bz2
   mkdir -p ~/xcat
   cd ~/xcat/
   ```

2. Extract xcat-core:

   ```
   tar jxvf core-debs-snap.tar.bz2
   ```

3. Configure the local repository for xcat-core by running mklocalrepo.sh script in the xcat-core directory:

   ```
   cd ~/xcat/xcat-core
   ./mklocalrepo.sh
   ```

**[xcat-dep]**

Unless you are downloading xcat-dep to match a specific package tested with a GA release, it’s recommended to download the latest version of xcat-dep.

1. Download xcat-dep:

   ```
   # if downloading xcat-dep from June 11, 2015, xcat-dep-ubuntu-snap20150611.tar.bz
   mkdir -p ~/xcat/
   cd ~/xcat/
   wget http://xcat.org/files/xcat/xcat-dep/2.x_Ubuntu/xcat-dep-ubuntu-snap20150611.tar.bz
   ```

2. Extract xcat-dep:

   ```
   tar jxvf xcat-dep-ubuntu-snap20150611.tar.bz
   ```

3. Configure the local repository for xcat-dep by running the mklocalrepo.sh script:
Install xCAT

The xCAT GPG Public Key must be added for apt to verify the xCAT packages

```
wget -O - "http://xcat.org/files/xcat/repos/apt/apt.key" | apt-key add -
```

Add the necessary apt-repositories to the management node

```
# Install the add-apt-repository command
apt-get install software-properties-common

# For x86_64:
add-apt-repository "deb http://archive.ubuntu.com/ubuntu $(lsb_release -sc) main"
add-apt-repository "deb http://archive.ubuntu.com/ubuntu $(lsb_release -sc)-updates main"
add-apt-repository "deb http://archive.ubuntu.com/ubuntu $(lsb_release -sc) universe"
add-apt-repository "deb http://archive.ubuntu.com/ubuntu $(lsb_release -sc)-updates universe"

# For ppc64el:
add-apt-repository "deb http://ports.ubuntu.com/ubuntu-ports $(lsb_release -sc) main"
add-apt-repository "deb http://ports.ubuntu.com/ubuntu-ports $(lsb_release -sc)-updates main"
add-apt-repository "deb http://ports.ubuntu.com/ubuntu-ports $(lsb_release -sc) universe"
add-apt-repository "deb http://ports.ubuntu.com/ubuntu-ports $(lsb_release -sc)-updates universe"
```

Install xCAT \(^1\) with the following command:

```
apt-get clean all
apt-get update
apt-get install xcat
```

**Verify xCAT Installation**

Quick verification of the xCAT Install can be done running the following steps:

1. Source the profile to add xCAT Commands to your path:

   ```
   source /etc/profile.d/xcat.sh
   ```

2. Check the xCAT version:

   ```
   lsxcatd -a
   ```

3. Check to verify that the xCAT database is initialized by dumping out the site table:

   ```
   tabdump site
   ```

\(^1\) Starting with Ubuntu 16.04, the package name “xCAT” is required to be all lowercase.
## Starting and Stopping

xCAT is started automatically after the installation, but the following commands can be used to start, stop, restart, and check xCAT status.

- **start xCAT:**
  ```
  service xcatd start
  [systemd] systemctl start xcatd.service
  ```

- **stop xCAT:**
  ```
  service xcatd stop
  [systemd] systemctl stop xcatd.service
  ```

- **restart xCAT:**
  ```
  service xcatd restart
  [systemd] systemctl restart xcatd.service
  ```

- **check xCAT status:**
  ```
  service xcatd status
  [systemd] systemctl status xcatd.service
  ```

## Updating xCAT

If at a later date you want to update xCAT, first, update the software repositories and then run:

```
apt-get update
apt-get -y --only-upgrade install .*xcat.*
```

## 1.2.4 Maintenance

### Backup and Restore xCAT

It’s useful to backup xcat data sometime. For example, you need to upgrading to another version of xCAT, or you need to change management server and move xcat form one to another, or you need to make backups regularly and restore production environment for any accident. Below section will help you backup and restore xcat data.
Backup User Data

If need to backup xcat database, you can use `dumpxCATdb` command like below.

```
dumpxCATdb -p <path_to_save_the_database>
```

[Note] Maybe you need to dump some environment data for problem report when you hit defect, you can use `xcatsnap` command like below.

```
xcatsnap -B -d <path_to_save_the_data>
```

Restore User Data

If need to restore xCAT environment, after xCAT software installation, you can restore xCAT DB using the `restorexCATdb` command pointing to the data files dumped in the past.

```
restorexCATdb -p <path_to_save_the_database>
```

Remove xCAT

We’re sorry to see you go! Here are some steps for removing the xCAT product.

Clean Up xCAT Related Configuration

1. To clean up the node information from dhcp

```
makedhcp -d -a
```

2. To clean up the node information in tftpboot

```
nodeset all offline
```

3. To clean up the node information from `/etc/hosts` (optional)

   Keeping xCAT nodes information in `/etc/hosts` is harmless, but if you really want to remove them from `/etc/hosts` run:

```
makehosts -d all
```

4. To clean up the node information from DNS (optional)

   After removing all the nodes from `/etc/hosts`, run below command to clean up the node information from DNS.

```
makedns -n
```

Stop xCAT Service

1. Stop xCAT service
2. Stop xCAT related services (optional)

xCAT uses various network services on the management node and service nodes, the network services setup by xCAT may need to be cleaned up on the management node and service nodes before uninstalling xCAT.

- **NFS**: Stop nfs service, unexport all the file systems exported by xCAT, and remove the xCAT file systems from /etc/exports.
- **HTTP**: Stop http service, remove the xcat.conf in the http configuration directory.
- **TFTP**: Stop tftp service, remove the tftp files created by xCAT in tftp directory.
- **DHCP**: Stop dhcp service, remove the configuration made by xCAT in dhcp configuration files.
- **DNS**: Stop the named service, remove the named entries created by xCAT from the named database.

### Remove xCAT Files

1. Remove xCAT Packages

To automatically remove all xCAT packages, run the following command

```
/opt/xcat/share/xcat/tools/go-xcat uninstall
```

There is no easy way to identify all xCAT packages. For packages shipped by xCAT, you can manually remove them by using one of the commands below.

[RHEL]

```
yum remove conserver-xcat elilo-xcat goconserver grub2-xcat ipmitool-xcat perl-xCAT syslinux-xcat xCAT xCAT-SoftLayer xCAT-buildkit xCAT-client xCAT-confluent xCAT-csm xCAT-genesis-base-ppc64 xCAT-genesis-base-x86_64 xCAT-genesis-scripts-ppc64 xCAT-genesis-scripts-x86_64 xCAT-openbmc-py xCAT-probe xCAT-server xnba-undi yaboot-xcat
```

[SLES]

```
zypper remove conserver-xcat elilo-xcat goconserver grub2-xcat ipmitool-xcat perl-xCAT syslinux-xcat xCAT xCAT-SoftLayer xCAT-buildkit xCAT-client xCAT-confluent xCAT-csm xCAT-genesis-base-ppc64 xCAT-genesis-base-x86_64 xCAT-genesis-scripts-ppc64 xCAT-genesis-scripts-x86_64 xCAT-openbmc-py xCAT-probe xCAT-server xnba-undi yaboot-xcat
```

[Ubuntu]

```
```

To do an even more thorough cleanup, use links below to get a list of RPMs installed by xCAT. Some RPMs may not to be installed in a specific environment.

- **XCAT Core Packages List (xcat-core)**

  [RHEL and SLES]
When `yum install xCAT` is used to install xCAT, dependency RPMs provided by the Operating System will be installed. Keeping those rpms installed on the system is harmless.

2. Remove xCAT certificate file

   ```bash
   rm -rf /root/.xcat
   ```

3. Remove xCAT data files

   By default, xCAT uses SQLite, remove SQLite data files under `/etc/xcat/`.

   ```bash
   rm -rf /etc/xcat
   ```

4. Remove xCAT related files (optional)

   XCAT might have also created additional files and directories below. Take caution when removing these files as they may be used for other purposes in your environment.

   ```bash
   /install
   /tftpboot
   /etc/yum.repos.d/xCAT-*
   /etc/sysconfig/xcat
   /etc/apache2/conf.d/xCAT-*
   /etc/logrotate.d/xCAT-*
   /etc/rsyslogd.d/xCAT-*
   /var/log/xcat
   /opt/xcat/
   /mnt/xcat
   ```

Remove Databases

- Removing xCAT DB from PostgreSQL.
- Removing xCAT DB from MySQL/MariaDB.

1.3 Admin Guide

The admin guide is intended to help with learning how to manage a cluster using xCAT with the following major sections:
• **Basic Concepts** Introduces some of the basic concepts in xCAT.

• **Manage Cluster** Describes managing clusters under xCAT. The management procedures are organized based on the hardware type since management may vary depending on the hardware architecture.

• **Reference** xCAT reference sections.

### 1.3.1 Basic Concepts

xCAT is not hard to use but you still need to learn some basic concepts of xCAT before starting to manage a real cluster.

• **xCAT Objects**
  
The unit which can be managed in the xCAT is defined as an object. xCAT abstracts several types of objects from the cluster information to represent the physical or logical entities in the cluster. Each xCAT object has a set of attributes, each attribute is mapped from a specified field of a xCAT database table. The xCAT users can get cluster information and perform cluster management work through operations against the objects.

• **xCAT Database**
  
All the data for the xCAT Objects (node, group, network, osimage, policy ... and global configuration) are stored in xCAT Database. Tens of tables are created as the back-end of xCAT Objects. Generally the data in the database is used by user through xCAT Object. But xCAT also offers a bunch of commands to handle the database directly.

• **Global Configuration**
  
xCAT has a bunch of Global Configuration for xCAT user to control the behaviors of xCAT. Some of the configuration items are mandatory for an xCAT cluster that you must set them correctly before starting to use xCAT.

• **xCAT Network**
  
xCAT’s goal is to manage and configure a significant number of servers remotely and automatically through a central management server. All the hardware discovery/management, OS deployment/configuration and application install/configuration are performed through network. You need to have a deep understand of how xCAT will use network before setting up a cluster.

Get Into the Detail of the Concepts:

### xCAT Objects

Basically, xCAT has 20 types of objects. They are:

<table>
<thead>
<tr>
<th>auditlog</th>
<th>boottarget</th>
<th>eventlog</th>
<th>firmware</th>
<th>group</th>
</tr>
</thead>
<tbody>
<tr>
<td>kit</td>
<td>kitcomponent</td>
<td>kitrepo</td>
<td>monitoring</td>
<td>network</td>
</tr>
<tr>
<td>node</td>
<td>notification</td>
<td>osdistro</td>
<td>osdistroupdate</td>
<td>osimage</td>
</tr>
<tr>
<td>policy</td>
<td>rack</td>
<td>route</td>
<td>site</td>
<td>zone</td>
</tr>
</tbody>
</table>

This section will introduce you to several important types of objects and give you an overview of how to view and manipulate them.

You can get the detail description of each object by `man <object type>` e.g. `man node`.

• **node Object**
  
The node is the most important object in xCAT. Any physical server, virtual machine or SP (Service Processor for Hardware Control) can be defined as a node object.
For example, I have a physical server which has the following attributes:

```
grids: all,x86_64
arch: x86_64
bmc: 10.4.14.254
bmcusername: ADMIN
bmcpassword: admin
mac: 6C:AE:8B:1B:E8:52
mgt: ipmi
netboot: xnba
provmethod: rhels7.1-x86_64-install-compute
```

The groups that this node belongs to.
The architecture of the server is x86_64.
The IP of BMC which will be used for hardware control.
The username of BMC.
The password of BMC.
The mac address of the ethernet adapter that will be used to deploy OS for the node.
The management method which will be used to manage the node.
The network bootloader that will be used to deploy OS for the node.
The osimage that will be deployed to the node.

I want to name the node to be cn1 (Compute Node #1) in xCAT. Then I define this node in xCAT with following command:

```
$mkdef -t node cn1 groups=all,x86_64 arch=x86_64 bmc=10.4.14.254
   bmcusername=ADMIN bmcpassword=admin mac=6C:AE:8B:1B:E8:52
   mgt=ipmi netboot=xnba provmethod=rhels7.1-x86_64-install-
   →compute
```

After the define, I can use lsdef command to display the defined node:

```
$lsdef cn1
Object name: cn1
   arch=x86_64
   bmc=10.4.14.254
   bmcusername=ADMIN
   bmcpassword=admin
   groups=all,x86_64
   mac=6C:AE:8B:1B:E8:52
   mgt=ipmi
   netboot=xnba
   postbootscripts=otherpkgs
   postscripts=syslog,remoteshell,syncfiles
   provmethod=rhels7.1-x86_64-install-compute
```

Then I can try to remotely power on the node cn1:

```
$rpower cn1 on
```

- **group Object**

  `group` is an object which includes multiple node object. When you set `group` attribute for a node object to a group name like `x86_64`, the group `x86_64` is automatically generated and the node is assigned to the group.

  The benefits of using `group object`:
  - Handle multiple nodes through group
I defined another server `cn2` which is similar with `cn1`, then my group `x86_64` has two nodes: `cn1` and `cn2`.

```
$ lsdef -t group x86_64
Object name: x86_64
  cons=ipmi
  members=cn1,cn2
```

Then I can power on all the nodes in the group `x86_64`.

```
$ rpower x86_64 on
```

**Inherit attributes from group**

If the group object of node object has certain attribute that node object does not have, the node will inherit this attribute from its group.

I set the `cons` attribute for the group object `x86_64`.

```
$ chdef -t group x86_64 cons=ipmi
1 object definitions have been created or modified.
```

```
$ lsdef -t group x86_64
Object name: x86_64
  cons=ipmi
  members=cn1,cn2
```

I can see the `cn1` inherits the attribute `cons` from the group `x86_64`:

```
$ lsdef cn1
Object name: cn1
  arch=x86_64
  bmc=10.4.14.254
  bmcpassword=admin
  bmcusername=ADMIN
  cons=ipmi
  groups=all,x86_64
  mac=6C:AE:8B:1B:E8:52
  mgt=ipmi
  netboot=xnba
  postbootscripts=otherpkgs
  postscripts=syslog,remoteshell,syncfiles
  provmethod=rhel5.1-x86_64-install-compute
```

It is useful to define common attributes in group object so that newly added node will inherit them automatically. Since the attributes are defined in the group object, you don’t need to touch the individual nodes attributes.

**Use Regular Expression to generate value for node attributes**

This is powerful feature in xCAT that you can generate individual attribute value from node name instead of assigning them one by one. Refer to Use Regular Expression in xCAT Database Table.

- **osimage Object**

  An osimage object represents an Operating System which can be deployed in xCAT. xCAT always generates several default osimage objects for certain Operating System when executing copycds command to generate the package repository for the OS.

  You can display all the defined osimage object:
Display the detail attributes of one osimage named **rhels7.1-x86_64-install-compute**:

```
$ lsdef -t osimage rhels7.1-x86_64-install-compute
```

Object name: rhels7.1-x86_64-install-compute

- **imagetype=linux**
- **osarch=x86_64**
- **osdistroname=rhels7.1-x86_64**
- **osname=Linux**
- **osvers=rhels7.1**
- **otherpkgdir=/install/post/otherpkgs/rhels7.1/x86_64**
- **pkgdir=/install/rhels7.1/x86_64**
- **pkglist=/opt/xcat/share/xcat/install/rh/compute.rhels7.pkglist**
- **profile=compute**
- **provmethod=install**
- **synclists=/root/syncfiles.list**
- **template=/opt/xcat/share/xcat/install/rh/compute.rhels7.tmpl**

This **osimage** represents a **Linux rhels7.1** Operating System. The package repository is in `/install/rhels7.1/x86_64` and the packages which will be installed is listed in the file `/opt/xcat/share/xcat/install/rh/compute.rhels7.pkglist`...

I can bind the **osimage** to **node** when I want to deploy osimage **rhels7.1-x86_64-install-compute** on my **node cn1**:

```
$ nodeset cn1 osimage=rhels7.1-x86_64-install-compute
```

Then in the next network boot, the node **cn1** will start to deploy **rhels7.1**.

**• Manipulating Objects**

You already saw that I used the commands **mkdef, lsdef, chdef** to manipulate the objects. xCAT has 4 objects management commands to manage all the xCAT objects.

- **mkdef**: create object definitions
- **chdef**: modify object definitions
- **lsdef**: list object definitions
- **rmdef**: remove object definitions

To get the detail usage of the commands, refer to the man page. e.g. man **mkdef**

Get Into the Detail of the xCAT Objects:

**node**

**Description**

The definition of physical units in the cluster, such as lpar, virtual machine, frame, cec, hmc, switch.

**Key Attributes**

- **os**: The operating system deployed on this node. Valid values: AIX, rhels*, rhele*, rhas*, centos*, SL*, fedora*, sles* (where * is the version #)
• **arch**: The hardware architecture of this node. Valid values: x86_64, ppc64, x86, ia64.

• **groups**: Usually, there are a set of nodes with some attributes in common, xCAT admin can define a node group containing these nodes, so that the management task can be issued against the group instead of individual nodes. A node can be a member of different groups, so the value of this attributes is a comma-delimited list of groups. At least one group is required to create a node. The new created group names should not be prefixed with “__” as this token has been preserved as the internal group name.

• **mgt**: The method to do general hardware management of the node. This attribute can be determined by the machine type of the node. Valid values: ipmi, blade, hmc, ivm, fsp, bpa, kvm, esx, rhevm.

• **mac**: The mac address of the network card on the node, which is connected with the installation server and can be used as the network installation device.

• **ip**: The IP address of the node.

• **netboot**: The type of network boot method for this node, determined by the OS to provision, the architecture and machine type of the node. Valid values:

<table>
<thead>
<tr>
<th>Arch and Machine Type</th>
<th>OS</th>
<th>valid netboot options</th>
</tr>
</thead>
<tbody>
<tr>
<td>x86, x86_64</td>
<td>ALL</td>
<td>pxelinux, xenb2</td>
</tr>
<tr>
<td>ppc64</td>
<td>&lt;=rhel6, &lt;=sles11.3</td>
<td>yaboot</td>
</tr>
<tr>
<td>ppc64</td>
<td>&gt;=rhel7, &gt;=sles11.4</td>
<td>grub2, grub2-http, grub2-tftp</td>
</tr>
<tr>
<td>ppc64le NonVirtualize</td>
<td>ALL</td>
<td>petitboot</td>
</tr>
<tr>
<td>ppc64le PowerKVM Guest</td>
<td>ALL</td>
<td>grub2, grub2-http, grub2-tftp</td>
</tr>
</tbody>
</table>

• **postscripts**: Comma separated list of scripts, that should be run on this node after diskful installation or diskless boot, finish some system configuration and maintenance work. For installation of RedHat, CentOS, Fedora, the scripts will be run before the reboot. For installation of SLES, the scripts will be run after the reboot but before the init.d process.

• **postbootscripts**: Comma separated list of scripts, that should be run on this node as a SysV init job on the 1st reboot after installation or diskless boot, finish some system configuration and maintenance work.

• **provmethod**: The provisioning method for node deployment. Usually, this attribute is an osimage object name.

• **status**: The current status of the node, which is updated by xCAT. This value can be used to monitor the provision process. Valid values: powering-off, installing, booting/netbooting, booted.

**Use Cases**

• **Case 1**: There is a ppc64le node named “cn1”, the mac of installation NIC is “ca:68:d3:ae:db:03”, the ip assigned is “10.0.0.100”, the network boot method is “grub2”, place it into the group “all”. Use the following command

```bash
mkdef -t node -o cn1 arch=ppc64 mac="ca:68:d3:ae:db:03" ip="10.0.0.100" netboot="grub2" groups="all"
```

• **Case 2**:

List all the node objects

```bash
nodes
```

This can also be done with

```bash
lsdef -t node
```
• Case 3: List the mac of object “cn1”

```bash
lsdef -t node -o cn1 -i mac
```

• Case 4: There is a node definition “cn1”, modify its network boot method to “yaboot”

```bash
chdef -t node -o cn1 netboot=yaboot
```

• Case 5: There is a node definition “cn1”, create a node definition “cn2” with the same attributes with “cn1”, except the mac addr (ca:68:d3:ae:db:04) and ip address (10.0.0.101)

  step 1: write the definition of “cn1” to a stanza file named “cn.stanza”

```bash
lsdef -z cn1 > /tmp/cn.stanza
```

The content of “/tmp/cn.stanza” will look like

```xml
# <xCAT data object stanza file>
cn1:
  objtype=node
  groups=all
  ip=10.0.0.100
  mac=ca:68:d3:ae:db:03
  netboot=grub2
```

  step 2: modify the “/tmp/cn.stanza” according to the “cn2” attributes

```xml
# <xCAT data object stanza file>
cn2:
  objtype=node
  groups=all
  ip=10.0.0.101
  mac=ca:68:d3:ae:db:04
  netboot=grub2
```

  step 3: create “cn2” definition with “cn.stanza”

```bash
cat /tmp/cn.stanza | mkdef -z
```

**group**

xCAT supports both static and dynamic groups. A static group is defined to contain a specific set of cluster nodes. A dynamic node group is one that has its members determined by specifying a selection criteria for node attributes. If a nodes attribute values match the selection criteria then it is dynamically included as a member of the group. The actual group membership will change over time as nodes have attributes set or unset. This provides flexible control over group membership by defining the attributes that define the group, rather than the specific node names that belong to the group. The selection criteria is a list of `attr<operator>val` pairs that can be used to determine the members of a group, (see below).

**Note:** Dynamic node group support is available in xCAT version 2.3 and later.

In xCAT, the definition of a static group has been extended to include additional attributes that would normally be assigned to individual nodes. When a node is part of a static group definition, it can inherit the attributes assigned to the group. This feature can make it easier to define and manage cluster nodes in that you can generally assign nodes to the appropriate group and then just manage the group definition instead of multiple node definitions. This feature is not supported for dynamic groups.
To list all the attributes that may be set for a group definition you can run

```
lsdef -t group -h
```

When a node is included in one or more static groups, a particular node attribute could actually be stored in several different object definitions. It could be in the node definition itself or it could be in one or more static group definitions. The precedence for determining which value to use is to choose the attribute value specified in the node definition if it is provided. If not, then each static group that the node belongs to will be checked to see if the attribute is set. The first value that is found is the value that is used. The static groups are checked in the order that they are specified in the `groups` attribute of the node definition.

**NOTE:** In a large cluster environment it is recommended to focus on group definitions as much as possible and avoid setting the attribute values in the individual node definition. (Of course some attribute values, such as a MAC addresses etc., are only appropriate for individual nodes.) Care must be taken to avoid confusion over which values will be inherited by the nodes.

Group definitions can be created using the `mkdef` command, changed using the `chdef` command, listed using the `lsdef` command and removed using the `rmdef` command.

### Creating a static node group

There are two basic ways to create xCAT static node groups. You can either set the `groups` attribute of the node definition or you can create a group definition directly.

You can set the `groups` attribute of the node definition when you are defining the node with the `mkdef` or `nodeadd` command or you can modify the attribute later using the `chdef` or `nodech` command. For example, if you want a set of nodes to be added to the group “aixnodes”, you could run `chdef` or `nodech` as follows

```
chdef -t node -p -o node01,node02,node03 groups=aixnodes
```

or

```
nodech node01,node02,node03 groups=aixnodes
```

The `-p` (plus) option specifies that “aixnodes” be added to any existing value for the `groups` attribute. The `-p` (plus) option is not supported by `nodech` command.

The second option would be to create a new group definition directly using the `mkdef` command as follows

```
mkdef -t group -o aixnodes members="node01,node02,node03"
```

These two options will result in exactly the same definitions and attribute values being created in the xCAT database.

### Creating a dynamic node group

The selection criteria for a dynamic node group is specified by providing a list of `attr<operator>val` pairs that can be used to determine the members of a group. The valid operators include: `==, !=, =~` and `!~`. The `attr` field can be any node definition attribute returned by the `lsdef` command. The `val` field in selection criteria can be a simple string or a regular expression. A regular expression can only be specified when using the `=~` or `!~` operators. See [http://www.perl.com/doc/manual/html/pod/perlre.html](http://www.perl.com/doc/manual/html/pod/perlre.html) for information on the format and syntax of regular expressions.

**Operator descriptions**
== Select nodes where the attribute value is exactly this value.
!= Select nodes where the attribute value is not this specific value.
=~ Select nodes where the attribute value matches this regular expression.
!~ Select nodes where the attribute value does not match this regular expression.

The selection criteria can be specified using one or more \(-w\) \(\text{attr<operator>val}\) options on the command line.

If the \(\text{val}\) field includes spaces or any other characters that will be parsed by shell then the \(\text{attr<operator>val}\) needs to be quoted.

For example, to create a dynamic node group called “mygroup”, where the hardware control point is “hmc01” and the partition profile is not set to service

\[
\text{mkdef -t group -o mygroup -d -w hcp==hmc01 -w pprofile!=service}
\]

To create a dynamic node group called “pslesnodes”, where the operating system name includes “sles” and the architecture includes “ppc”

\[
\text{mkdef -t group -o pslesnodes -d -w os=~sles[0-9]+ -w arch=~ppc}
\]

To create a dynamic node group called nonpbladenodes where the node hardware management method is not set to blade and the architecture does not include ppc

\[
\text{mkdef -t group -o nonpbladenodes -d -w mgt!=blade -w 'arch!~ppc'}
\]

osimage

Description

A logical definition of image which can be used to provision the node.

Key Attributes

- **imagetype**: The type of operating system this definition represents (linux, AIX).
- **osarch**: The hardware architecture of the nodes this image supports. Valid values: x86_64, ppc64, ppc64le.
- **osvers**: The Linux distribution name and release number of the image. Valid values: rhels*, rhele*, rhas*, centos*, SL*, fedora*, sles* (where * is the version #).
- **pkgdir**: The name of the directory where the copied OS distro content are stored.
- **pkglist**: The fully qualified name of a file, which contains the list of packages shipped in Linux distribution ISO which will be installed on the node.
- **otherpkgdir** When xCAT user needs to install some additional packages not shipped in Linux distribution ISO, those packages can be placed in the directory specified in this attribute. xCAT user should take care of dependency problems themselves, by putting all the dependency packages not shipped in Linux distribution ISO in this directory and creating repository in this directory.
- **otherpkglist**: The fully qualified name of a file, which contains the list of user specified additional packages not shipped in Linux distribution ISO which will be installed on the node.
- **template**: The fully qualified name of the template file that will be used to create the OS installer configuration file for stateful installation (e.g. kickstart for RedHat, autoyast for SLES and preseed for Ubuntu).
Use Cases

• Case 1:
List all the osimage objects

`lsdef -t osimage`

• Case 2:
Create a osimage definition “customized-rhels7-ppc64-install-compute” based on an existing osimage “rhels7-ppc64-install-compute”, the osimage “customized-rhels7-ppc64-install-compute” will inherit all the attributes of “rhels7-ppc64-install-compute” except installing the additional packages specified in the file “/tmp/otherpkg.list”:

**step 1**: write the osimage definition “rhels7-ppc64-install-compute” to a stanza file “osimage.stanza”

```
lsdef -z -t osimage -o rhels7-ppc64-install-compute > /tmp/osimage.stanza
```

The content will look like

```
# <xCAT data object stanza file>
rhels7-ppc64-install-compute:
  objtype=osimage
  imagetype=linux
  osarch=ppc64
  osdistrioname=rhels7-ppc64
  osname=Linux
  osvers=rhels7
  otherpkgdir=/install/post/otherpkgs/rhels7/ppc64
  pkgdir=/install/rhels7/ppc64
  pkglist=/opt/xcat/share/xcat/install/rh/compute.rhels7.pkglist
  profile=compute
  provmethod=install
  template=/opt/xcat/share/xcat/install/rh/compute.rhels7.tmpl
```

**step 2**: modify the stanza file according to the attributes of “customized-rhels7-ppc64-install-compute”

```
# <xCAT data object stanza file>
customized-rhels7-ppc64-install-compute:
  objtype=osimage
  imagetype=linux
  osarch=ppc64
  osdistrioname=rhels7-ppc64
  osname=Linux
  osvers=rhels7
  otherpkglist=/tmp/otherpkg.list
  otherpkgdir=/install/post/otherpkgs/rhels7/ppc64
  pkgdir=/install/rhels7/ppc64
  pkglist=/opt/xcat/share/xcat/install/rh/compute.rhels7.pkglist
  profile=compute
  provmethod=install
  template=/opt/xcat/share/xcat/install/rh/compute.rhels7.tmpl
```

**step 3**: create the osimage “customized-rhels7-ppc64-install-compute” from the stanza file

```
cat /tmp/osimage.stanza |mkdef -z
```
xCAT Database

All of the xCAT Objects and Configuration data are stored in xCAT database. By default, xCAT uses SQLite - an OS contained simple database engine. The powerful open source database engines like MySQL, MariaDB, PostgreSQL are also supported for a large cluster.

xCAT defines about 70 tables to store different data. You can get the xCAT database definition from file /opt/xcat/lib/perl/xCAT/Schema.pm.

You can run tabdump command to get all the xCAT database tables. Or run tabdump -d <tablename> or man <tablename> to get the detail information on columns and table definitions.

```bash
$ tabdump
$ tabdump site
$ tabdump -d site
$ man site
```

For a complete reference, see the man page for xcatdb: man xcatdb.

The tables in xCAT:

- **site table**
  Global settings for the whole cluster. This table is different from the other tables. Each entry in site table is a key=>value pair. Refer to the Global Configuration page for the major global attributes or run man site to get all global attributes.

- **policy table**
  Controls who has authority to run specific xCAT operations. It is the Access Control List (ACL) in xCAT.

- **passwd table**
  Contains default userids and passwords for xCAT to access cluster components. In most cases, xCAT will also set the userid/password in the relevant component (Generally for SP like bmc, fsp.) when it is being configured or installed. The default userids/passwords in passwd table for specific cluster components can be overridden by the columns in other tables, e.g. mpa, ipmi, ppchcp, etc.

- **networks table**
  Contains the network definitions in the cluster.

  You can manipulate the networks through *def command against the network object.

  ```bash
  $ lsdef -t network
  ```

- **...**

Manipulate xCAT Database Tables

xCAT offers 5 commands to manipulate the database tables:

- **tabdump**
  Displays the header and all the rows of the specified table in CSV (comma separated values) format.

- **tabedit**
  Opens the specified table in the user’s editor, allows them to edit any text, and then writes changes back to the database table. The table is flattened into a CSV (comma separated values) format file before giving it to the editor. After the editor is exited, the CSV file will be translated back into the database format.

- **tabgrep**
  List table names in which an entry for the given node appears.
• dumpxCATdb

Dumps all the xCAT db tables to CSV files under the specified directory, often used to backup the xCAT database for xCAT reinstallation or management node migration.

• restorexCATdb

Restore the xCAT db tables from the CSV files under the specified directory.

Advanced Topic: How to use Regular Expression in xCAT tables:

Groups and Regular Expressions in Tables

Using Regular Expressions in the xCAT Tables

The xCAT database has a number of tables, some with rows that are keyed by node name (such as noderes and nodehm) and others that are not keyed by node name (for example, the policy table). The tables that are keyed by node name have some extra features that enable a more template-based style to be used:

Any group name can be used in lieu of a node name in the node field, and that row will then provide “default” attribute values for any node in that group. A row with a specific node name can then override one or more attribute values for that specific node. For example, if the nodehm table contains

```
#node,power,mgt,cons,termserver,termport,conserver,serialport,serialspeed,serialflow,
--getmac,cmdmapping,comments,disable
"mygroup","ipmi","","19200","",
"node1",,,,,,,,,,115200",,,,
```

In the above example, the node group called “mygroup” sets mgt=ipmi and serialspeed=19200. Any nodes that are in this group will have those attribute values, unless overridden. For example, if “node2” is a member of “mygroup”, it will automatically inherit these attribute values (even though it is not explicitly listed in this table). In the case of “node1” above, it inherits mgt=ipmi, but overrides the serialspeed to be 115200, instead of 19200.

A useful, typical way to use this capability is to create a node group for your nodes and for all the attribute values that are the same for every node, set them at the group level. Then you only have to set attributes for each node that vary from node to node.

xCAT extends the group capability so that it can also be used for attribute values that vary from node to node in a very regular pattern. For example, if in the ipmi table you want the bmc attribute to be set to whatever the nodename is with “-bmc” appended to the end of it, then use this in the ipmi table

```
#node,bmc,bmcport,taggedvlan,bmcid,username,password,comments,disable
"compute","/\z/-bmc/",,,,,,\n```

In this example, “compute” is a node group that contains all of the compute nodes. The 2nd attribute (bmc) is a regular expression that is similar to a substitution pattern. The 1st part \z matches the end of the node name and substitutes -bmc, effectively appending it to the node name.

Another example is if “node1” is assigned the IP address “10.0.0.1”, node2 is assigned the IP address “10.0.0.2”, etc., then this could be represented in the hosts table with the single row

```
#node,ip,hostnames,otherinterfaces,comments,disable
"compute","|node(\d+)|10.0.0.($1+0)|",,,,,
```

In this example, the regular expression in the ip attribute uses | to separate the 1st and 2nd part. This means that xCAT will allow arithmetic operations in the 2nd part. In the 1st part, \(\d+\), will match the number part of the node name and put that in a variable called $1. The 2nd part is what value to give the ip attribute. In this case it will set it to the string “10.0.0.” and the number that is in $1. (Zero is added to $1 just to remove any leading zeros.)
A more involved example is with the `vm` table. If your kvm nodes have node names `c01f01x01v01`, `c01f02x03v04`, etc., and the kvm host names are `c01f01x01`, `c01f02x03`, etc., then you might have an `vm` table like

```
#node,mgr,host,migrationdest,storage,storagemodel,storagecache,storageformat, 
→cfgstore, memory, cpus, nics, nicmodel, bootorder, clockoffset, virtflags, master, vncport, 
→textconiole, powerstate, beacon, datacenter, cluster, guestostype, othersettings, physlots, 
→vidmodel, vidproto, vidpassword, comments, disable

"kvms",","|D+(\d+)|D+(\d+)|D+(\d+)|D+(\d+)|c($1)f($2)x($3)|",", "|D+(\d+)|D+(\d+)|D+(\d+)|D+(\d+)|dir:///install/vms/vm($4+0)|",", "3072",",", "virbr2","virtio" ,,,,,,,,,,,,,,,,, , "
```

Before you panic, let me explain each column:

**kvms**

This is a group name. In this example, we are assuming that all of your kvm nodes belong to this group. Each time the xCAT software accesses the `vm` table to get the kvm host `host` and storage file `vmstorage` of a specific kvm node (e.g. `c01f02x03v04`), this row will match (because `c01f02x03v04` is in the `kvms` group). Once this row is matched for `c01f02x03v04`, then the processing described in the following items will take place.

```
|\D+(\d+)|D+(\d+)|D+(\d+)|D+(\d+)|c($1)f($2)x($3) |
```

This is a perl substitution pattern that will produce the value for the 3rd column of the table (the kvm host). The text `\D+(\d+)\D+(\d+)` between the 1st two vertical bars is a regular expression that matches the node name that was searched for in this table (in this example `c01f02x03v04`). The text that matches within the 1st set of parentheses is set to $1, 2nd set of parentheses is set to $2, 3rd set of parentheses is set to $3. and so on. In our case, the \D+ matches the non-numeric part of the name ("c","f","x","v") and the \d+ matches the numeric part ("01","02","03","04"). So $1 is set to "01", $2 is set to "02", $3 is set to "03", and $4 is set to "04". The text `c($1)f($2)x($3)` between the 2nd and 3rd vertical bars produces the string that should be used as the value for the `host` attribute for `c01f02x03v04`, i.e., "c01f02x03".

```
|\D+(\d+)|D+(\d+)|D+(\d+)|D+(\d+)|dir:///install/vms/vm($4+0)|
```

This item is similar to the one above. This substitution pattern will produce the value for the 5th column (a list of storage files or devices to be used). Because this row was the match for "c01f02x03v04", the produced value is "dir:///install/vms/vm4".

Just as the explained above, when the node definition “c01f02x03v04” is created with

```
# mkdef -t node -o c01f02x03v04 groups=kvms
1 object definitions have been created or modified.
```

The generated node definition is

```
# lsdef c01f02x03v04
Object name: c01f02x03v04
  groups=kvms
  postbootscripts=otherpkgs
  postscripts=syslog,remoteshell,syncfiles
  vmcpus=2
  vmhost=c01f02x03
  vmmemory=3072
  vmnicnicmodel=virtio
  vmnics=virbr2
  vmstorage=dir:///install/vms/vm4
```

See [perlre](#) for more information on perl regular expressions.
Easy Regular expressions

As of xCAT 2.8.1, you can use a modified version of the regular expression support described in the previous section. You do not need to enter the node information (1st part of the expression), it will be derived from the input nodename. You only need to supply the 2nd part of the expression to determine the value to give the attribute.

For example:

If node1 is assigned the IP address 10.0.0.1, node2 is assigned the IP address 10.0.0.2, etc., then this could be represented in the hosts table with the single row:

Using full regular expression support you would put this in the hosts table.

```
chdef -t group compute ip="|node\(\d+\)|10.0.0.\(\$1+0\)|"
```

```
tabdump hosts
#node,ip,hostnames,otherinterfaces,comments,disable
"compute","|node\(\d+\)|10.0.0.\(\$1+0\)|",,,,,
```

Using easy regular expression support you would put this in the hosts table.

```
chdef -t group compute ip="|10.0.0.\(\$1+0\)|"
```

```
tabdump hosts
#node,ip,hostnames,otherinterfaces,comments,disable
"compute","|10.0.0.\(\$1+0\)|",,,,,
```

In the easy regx example, the expression only has the 2nd part of the expression from the previous example. xCAT will evaluate the node name, matching the number part of the node name, and create the 1st part of the expression. The 2nd part supplied is what value to give the ip attribute. The resulting output is the same.

Regular Expression Helper Functions

xCAT provides several functions that can simplify regular expressions.

**a2idx ASCII Character to Index** Usage: `a2idx(character)`

Turns a single character into a 1-indexed index. ‘a’ maps to 1 and ‘z’ maps to 26.

**a2zidx ASCII Character to 0-Index** Usage: `a2zidx(character)`

Turns a single character into a 0-indexed index. ‘a’ maps to 0 and ‘z’ maps to 25.

**dim2idx Dimensions to Index** Usage: `dim2idx(value, [count, value...])`

Converts dimensions (such as row, column, chassis, etc) into an index. An example system consists of 8 racks, two rows with four columns each.

```
row1-col1  row1-col2  row1-col3  row1-col4
row2-col1  row2-col2  row2-col3  row2-col4
```

To obtain the rack index, use `|row\(\d+\)-col\(\d+\)|\(dim2idx\(\$1, 4, \$2\)\)`.

This maps the racks to:

```
1 2 3 4
5 6 7 8
```

Note that the size of the highest dimension (2 rows) is not needed, and all values are one-indexed.
If each rack contains 20 nodes, use \( \text{dim2idx}(\text{row}(d)-\text{col}(d)-\text{node}(d)) \) to determine a node index (useful for determining IP addresses).

**skip Skip indices**

Usage: \( \text{skip}(\text{index}, \text{skiplist}) \)

Return an index with certain values skipped. The skip list uses the format \( \text{start}[\text{count}][, \text{start}[\text{count}][,...] \). Using the example above, to skip racks 3 and 4, use:

\[ \text{dim2idx}(\text{row}(d)-\text{col}(d)){\text{skip}(\text{dim2idx}(d, 4, 2), '3:2')} \]

The result would be:

| 1 | 2 | 3 | 4 | 5 | 6 |

**ipadd Add to an IP address**

Usage: \( \text{ipadd}(\text{octet1}, \text{octet2}, \text{octet3}, \text{octet4}, \text{toadd}, \text{skipstart}, \text{skipend}) \)

This function is useful when you need to cross octets. Optionally skip addresses at the start and end of octets (like .0 or .255 - technically those are valid IP addresses, but sometimes software makes poor assumptions about which broadcast and gateway addresses).

**Verify your regular expression**

After you create your table with regular expression, make sure they are evaluating as you expect.

```
lsdef node1 | grep ip
  ip=10.0.0.1
```

**Global Configuration**

All the xCAT global configurations are stored in site table, xCAT Admin can adjust the configuration by modifying the site attribute with `tabedit`.

This section only presents some key global configurations, for the complete reference on the xCAT global configurations, refer to the `tabdump -d site`.

**Database Attributes**

- **excludenodes**: A set of comma separated nodes and/or groups that would automatically be subtracted from any noderange, it can be used for excluding some failed nodes from any xCAT command. See `noderange` for details on supported formats.

- **nodestatus**: If set to n, the `nodelist.status` column will not be updated during the node deployment, node discovery and power operations. The default is to update.

**DHCP Attributes**

- **dhcpinterfaces**: The network interfaces DHCP should listen on. If it is the same for all nodes, use a simple comma-separated list of NICs. To specify different NICs for different nodes

  \[
xcatmn|eth1,eth2;service|bond0.
  \]
In this example xcatmn is the name of the xCAT MN, and DHCP there should listen on eth1 and eth2. On all of the nodes in group service DHCP should listen on the bond0 nic.

- dhcplease: The lease time for the dhcp client. The default value is 43200.

- managedaddressmode: The mode of networking configuration during node provision. If set to static, the network configuration will be configured in static mode based on the node and network definition on MN. If set to dhcp, the network will be configured with dhcp protocol. The default is dhcp.

### DNS Attributes

- domain: The DNS domain name used for the cluster.

- forwarders: The DNS servers at your site that can provide names outside of the cluster. The makedns command will configure the DNS on the management node to forward requests it does not know to these servers. Note that the DNS servers on the service nodes will ignore this value and always be configured to forward requests to the management node.

- master: The hostname of the xCAT management node, as known by the nodes.

- nameservers: A comma delimited list of DNS servers that each node in the cluster should use. This value will end up in the nameserver settings of the /etc/resolv.conf on each node. It is common (but not required) to set this attribute value to the IP addr of the xCAT management node, if you have set up the DNS on the management node by running makedns. In a hierarchical cluster, you can also set this attribute to <xcatmaster> to mean the DNS server for each node should be the node that is managing it (either its service node or the management node).

- dnsinterfaces: The network interfaces DNS server should listen on. If it is the same for all nodes, use a simple comma-separated list of NICs. To specify different NICs for different nodes

```bash
xcatmn|eth1,eth2;service|bond0.
```

In this example xcatmn is the name of the xCAT MN, and DNS there should listen on eth1 and eth2. On all of the nodes in group service DNS should listen on the bond0 nic.

**NOTE**: if using this attribute to block certain interfaces, make sure the ip that maps to your hostname of xCAT MN is not blocked since xCAT needs to use this ip to communicate with the local DNS server on MN.

### Install/Deployment Attributes

- installdir: The local directory name used to hold the node deployment packages.

- runbootscripts: If set to yes the scripts listed in the postbootscripts attribute in the osimage and postscripts tables will be run during each reboot of stateful (diskful) nodes. This attribute has no effect on stateless nodes. Run the following command after you change the value of this attribute

```bash
updatenode <nodes> -P setuppostbootscripts
```

- precreatemypostscripts: (yes/1 or no/0). Default is no. If yes, it will instruct xCAT at nodeset and updatenode time to query the db once for all of the nodes passed into the cmd and create the mypostscript file for each node, and put them in a directory of tftpdir(such as: /tftpboot). If no, it will not generate the mypostscript file in the tftpdir.

- xcatdebugmode: the xCAT debug level. xCAT provides a batch of techniques to help user debug problems while using xCAT, especially on OS provision, such as collecting logs of the whole installation process and accessing the installing system via ssh, etc. These techniques will be enabled according to different xCAT debug levels specified by ‘xcatdebugmode’, currently supported values:
For the details on ‘basic debug mode’ and ‘expert debug mode’, refer to xCAT documentation.

Remoteshell Attributes

- `sshbetweennodes`: Comma separated list of groups of compute nodes to enable passwordless root ssh during install, or `xdsh -K`. Default is `ALLGROUPS`. Set to `NOGROUPS` if you do not wish to enable it for any group of compute nodes. If using the `zone` table, this attribute in not used.

Services Attributes

- `consoleondemand`: When set to `yes`, conserver connects and creates the console output only when the user opens the console. Default is `no` on Linux, `yes` on AIX.
- `timezone`: The timezone for all the nodes in the cluster (e.g. `America/New_York`).
- `tftpdir`: Tftp directory path. Default is `/tftpboot`.
- `tftpflags`: The flags used to start tftpd. Default is `-v -l -s /tftpboot -m /etc/tftpmapfile4xcat.conf` if `tftpflags` is not set.

Virtualization Attributes

- `persistkvmguests`: Keep the kvm definition on the kvm hypervisor when you power off the kvm guest node. This is useful for you to manually change the kvm xml definition file in `virsh` for debugging. Set anything means enable.

xCAT Daemon attributes

- `xcatdport`: The port used by xcatd daemon for client/server communication.
- `xcatiport`: The port used by xcatd to receive installation status updates from nodes.
- `xcatlport`: The port used by xcatd command log writer process to collect command output.
- `xcatsslversion`: The ssl version by xcatd. Default is `SSLv3`.
- `xcatsslciphers`: The ssl cipher by xcatd. Default is `3DES`.

Network Planning

For a cluster, several networks are necessary to enable the cluster management and production.

- **Management network**
  This network is used by the management node to install and manage the OS of the nodes. The MN and in-band NIC of the nodes are connected to this network. If you have a large cluster with service nodes, sometimes this network is segregated into separate VLANs for each service node.

  Following network services need be set up in this network to supply the OS deployment, application install/configuration service.
– DNS (Domain Name Service)
  The dns server, usually the management node or service node, provides the domain name service for the entire cluster.

– HTTP (HyperText Transfer Protocol)
  The http server, usually the management node or service node, acts as the download server for the initrd and kernel, the configuration file for the installer and repository for the online installation.

– DHCP (Dynamic Host Configuration Protocol)
  The dhcp server, usually the management node or service node, provides the dhcp service for the entire cluster.

– TFTP (Trivial File Transfer Protocol)
  The tftp server, usually the management node or service node, acts as the download server for bootloader binaries, bootloader configuration file, initrd and kernel.

– NFS (Network File System)
  The NFS server, usually the management node or service node, provides the file system sharing between the management node and service node, or persistent file system support for the stateless node.

– NTP (Network Time Protocol)
  The NTP server, usually the management node or service node, provides the network time service for the entire cluster.

- **Service network**
  This network is used by the management node to control the nodes out of band via the SP like BMC, FSP. If the BMCs are configured in shared mode\(^1\), then this network can be combined with the management network.

- **Application network**
  This network is used by the applications on the compute nodes. Usually an IB network for HPC cluster.

- **Site (Public) network**
  This network is used to access the management node and sometimes for the compute nodes to provide services to the site.

From the system management perspective, the **Management network** and **Service network** are necessary to perform the hardware control and OS deployment.

**xCAT Network Planning for a New Cluster:**

**xCAT Network Planning**

Before setting up your cluster, there are a few things that are important to think through first, because it is much easier to go in the direction you want right from the beginning, instead of changing course midway through.

**Do You Need Hierarchy in Your Cluster?**

**Service Nodes**

For very large clusters, xCAT has the ability to distribute the management operations to service nodes. This allows the management node to delegate all management responsibilities for a set of compute or storage nodes to a service node so that the management node doesn’t get overloaded. Although xCAT automates a lot of the aspects of deploying

\(^1\) shared mode: In “Shared” mode, the BMC network interface and the in-band network interface will share the same network port.
and configuring the services, it still adds complexity to your cluster. So the question is: at what size cluster do you need to start using service nodes? The exact answer depends on a lot of factors (mgmt node size, network speed, node type, OS, frequency of node deployment, etc.), but here are some general guidelines for how many nodes a single management node (or single service node) can handle:

- **[Linux]:**
  - Stateful or Stateless: 500 nodes
  - Statelite: 250 nodes

- **[AIX]:** 150 nodes

These numbers can be higher (approximately double) if you are willing to “stage” the more intensive operations, like node deployment.

Of course, there are some reasons to use service nodes that are not related to scale, for example, if some of your nodes are far away (network-wise) from the mgmt node.

**Network Hierarchy**

For large clusters, you may want to divide the management network into separate subnets to limit the broadcast domains. (Service nodes and subnets don’t have to coincide, although they often do.) xCAT clusters as large as 3500 nodes have used a single broadcast domain.

Some cluster administrators also choose to sub-divide the application interconnect to limit the network contention between separate parallel jobs.

**Design an xCAT Cluster for High Availability**

Everyone wants their cluster to be as reliable and available as possible, but there are multiple ways to achieve that end goal. Availability and complexity are inversely proportional. You should choose an approach that balances these 2 in a way that fits your environment the best. Here’s a few choices in order of least complex to more complex.

**Service Node Pools With No HA Software**

**Service node pools** is an xCAT approach in which more than one service node (SN) is in the broadcast domain for a set of nodes. When each node netboots, it chooses an available SN by which one responds to its DHCP request 1st. When services are set up on the node (e.g. DNS), xCAT configures the services to use at that SN and one other SN in the pool. That way, if one SN goes down, the node can keep running, and the next time it netboots it will automatically choose another SN.

This approach is most often used with stateless nodes because that environment is more dynamic. It can possibly be used with stateful nodes (with a little more effort), but that type of node doesn’t netboot nearly as often so a more manual operation (snmove) is needed in that case move a node to different SNs.

It is best to have the SNs be as robust as possible, for example, if they are diskful, configure them with at least 2 disks that are RAID’ed together.

In smaller clusters, the management node (MN) can be part of the SN pool with one other SN.

In larger clusters, if the network topology dictates that the MN is only for managing the SNs (not the compute nodes), then you need a plan for what to do if the MN fails. Since the cluster can continue to run if the MN is down temporarily, the plan could be as simple as have a backup MN w/o any disks. If the primary MN fails, move its RAID’ed disks to the backup MN and power it on.
HA Management Node

If you want to use HA software on your management node to synchronize data and fail over services to a backup MN, see [TODO Highly_Available_Management_Node], which discusses the different options and the pros and cons.

It is important to note that some HA-related software like DRDB, Pacemaker, and Corosync is not officially supported by IBM, meaning that if you have a problem specifically with that software, you will have to go to the open source community or another vendor to get a fix.

HA Service Nodes

When you have NFS-based diskless (statelite) nodes, there is sometimes the motivation make the NFS serving highly available among all of the service nodes. This is not recommended because it is a very complex configuration. In our opinion, the complexity of this setup can nullify much of the availability you hope to gain. If you need your compute nodes to be highly available, you should strongly consider stateful or stateless nodes.

If you still have reasons to pursue HA service nodes:
  - For [AIX] , see [TODO XCAT_HASN_with_GPFS]
  - For [Linux] , a couple prototype clusters have been set up in which the NFS service on the SNs is provided by GPFS CNFS (Clustered NFS). A howto is being written to describe the setup as an example. Stay tuned.

xCAT Cluster OS Running Type

Whether a node is a physical server or a virtual machine, it needs to run an Operating System to support user applications. Generally, the OS is installed in the hard disk of the compute node. But xCAT also support the type that running OS in the RAM.

This section gives the pros and cons of each OS running type, and describes the cluster characteristics that will impact from each.

Stateful (diskful)

Traditional cluster with OS on each node’s local disk.
  - Main advantage
    This approach is familiar to most admins, and they typically have many years of experience with it.
  - Main disadvantage
    Admin has to manage all of the individual OS copies, has to face the failure of hard disk. For certain application which requires all the compute nodes have exactly same state, this is also changeable for admin.

Stateless (diskless)

Nodes boot from a RAMdisk OS image downloaded from the xCAT mgmt node or service node at boot time.
  - Main advantage
    Central management of OS image, but nodes are not tethered to the mgmt node or service node it booted from. Whenever you need a new OS for the node, just reboot the node.
• Main disadvantage

You can’t use a large image with many different applications in the image for varied users, because it uses too much of the node’s memory to store the ramdisk. (To mitigate this disadvantage, you can put your large application binaries and libraries in shared storage to reduce the ramdisk size. This requires some manual configuration of the image).

Each node can also have a local “scratch” disk for swap, /tmp, /var, log files, dumps, etc. The purpose of the scratch disk is to provide a location for files that are written to by the node that can become quite large or for files that you don’t want to disappear when the node reboots. There should be nothing put on the scratch disk that represents the node’s “state”, so that if the disk fails you can simply replace it and reboot the node. A scratch disk would typically be used for situations like: job scheduling preemption is required (which needs a lot of swap space), the applications write large temp files, or you want to keep gpfs log or trace files persistently. (As a partial alternative to using the scratch disk, customers can choose to put /tmp /var/tmp, and log files (except GPFS logs files) in GPFS, but must be willing to accept the dependency on GPFS). This can be done by enabling the ‘localdisk’ support. For the details, refer to the section [TODO Enabling the localdisk Option].

**OSimage Definition**

The attribute **provmethod** is used to identify that the osimage is diskful or diskless:

```
$ lsdef -t osimage rhels7.1-x86_64-install-compute -i provmethod
Object name: rhels7.1-x86_64-install-compute
  provmethod=install
```

- **install**: Diskful
- **netboot**: Diskless

1.3.2 Manage Clusters

The following provides detailed information to help start managing your cluster using xCAT.

The sections are organized based on hardware architecture.

**IBM POWER LE / OpenPOWER**

Most of the content is general information for xCAT, the focus and examples are for management of IBM OpenPOWER servers.

**IBM OpenPOWER Servers**

- based on POWER8 Processor Technology is IPMI managed
- based on POWER9 Processor Technology is OpenBMC managed [Alpha]

**Configure xCAT**

After installing xCAT onto the management node, configure some basic attributes for your cluster into xCAT.
Set attributes in the \textit{site} table

1. Verify the following attributes have been correctly set in the xCAT \textit{site} table.
   
   - domain
   - forwarders
   - master\(^1\)
   - nameservers

   For more information on the keywords, see the DHCP ATTRIBUTES in the \textit{site} table.

   If the fields are not set or need to be changed, use the xCAT \texttt{chdef} command:

   
   \begin{verbatim}
   chdef -t site domain="domain_string"
   chdef -t site forwarders="forwarders"
   chdef -t site master="xcat_master_ip"
   chdef -t site nameservers="nameserver1,nameserver2,etc"
   \end{verbatim}

Initialize DNS services

1. Initialize the DNS\(^2\) services on the xCAT Management Node:

   \begin{verbatim}
   makedns -n
   \end{verbatim}

   Verify DNS is working by running \texttt{nslookup} against your Management Node:

   \begin{verbatim}
   nslookup <management_node_hostname>
   \end{verbatim}

   For more information on DNS, refer to \textit{Cluster Name Resolution}

Set attributes in the \textit{networks} table

1. Display the network settings defined in the xCAT \textit{networks} table using: \texttt{tabdump networks}

   \begin{verbatim}
   #netname,net,mask,mgtifname,gateway,dhcpserver,tftpserver,nameservers,ntpservers,logservers,dynamicrange,staticrange,staticrangeincrement,nodehostname,ddnsdomain,vlanid,domain,mtu,comments,disable
   "10_0_0_0-255_0_0_0","10.0.0.0","255.0.0.0","eth0","10.0.0.101",,"10.4.27.5",,,,,,,
   \end{verbatim}

   A default network is created for the detected primary network using the same netmask and gateway. There may be additional network entries in the table for each network present on the management node where xCAT is installed.

2. To define additional networks, use one of the following options:

   - \textbf{[Recommended]} Use \texttt{mkdef} to create/update an entry into \textit{networks} table.

     To create a network entry for 192.168.X.X/16 with a gateway of 192.168.1.254:

\footnotesize
\begin{itemize}
  \item \textit{\texttt{Chdef -t site domain="domain_string"}}
  \item \textit{\texttt{Chdef -t site forwarders="forwarders"}}
  \item \textit{\texttt{Chdef -t site master="xcat_master_ip"}}
  \item \textit{\texttt{Chdef -t site nameservers="nameserver1,nameserver2,etc"}}
\end{itemize}

\texttt{makedns -n}

\texttt{nslookup <management_node_hostname>}

\textit{Cluster Name Resolution}}

\footnotesize
\begin{itemize}
  \item The value of the \texttt{master} attribute in the site table should be set as the IP address of the management node responsible for the compute node.
  \item Setting up name resolution and the ability to have hostname resolved to IP addresses is \textbf{required} for xCAT.
\end{itemize}
mkdef -t network -o net1 net=192.168.0.0 mask=255.255.0.0 gateway=192.168.1.254

- Use the `tabedit` command to modify the networks table directly in an editor:

  tabedit networks

- Use the `makenetworks` command to automatically generate an entry in the `networks` table:

  makenetworks

3. Verify the network statements

  **Domain** and **nameserver** attributes must be configured in the `networks` table or in the `site` table for xCAT to function properly.

**Initialize DHCP services**

Configure DHCP to listen on different network interfaces [Optional]

The default behavior of xCAT is to configure DHCP to listen on all interfaces defined in the `networks` table.

The `dhcpietfaces` keyword in the `site` table allows administrators to limit the interfaces that DHCP will listen over. If the management node has 4 interfaces, (eth0, eth1, eth2, and eth3), and you want DHCP to listen only on “eth1” and “eth3”, set `dhcpietfaces` using:

```
chdef -t site dhcpietfaces="eth1,eth3"
```

To set “eth1” and “eth3” on the management node and “bond0” on all nodes in the `nodegroup=service`, set `dhcpietfaces` using:

```
chdef -t site dhcpietfaces="eth1,eth3;service|bond0"
```

or, to explicitly identify the management node with hostname `xcatmn`:

```
chdef -t site dhcpietfaces="xcatmn|eth1,eth3;service|bond0"
```

**noboot**

For the **IBM OpenPOWER S822LC for HPC (“Minsky”)** nodes, the BMC and compute “eth0” share the left-side integrated ethernet port and compute “eth1” is the right-side integrated ethernet port. For these servers, it is recommended to use two physical cables allowing the BMC port to be dedicated and “eth1” used by the OS. When an open range is configured on the two networks, the xCAT Genesis kernel will be sent to the BMC interface and causes problems during hardware discovery. To support this scenario, on the xCAT management node, if “eth1” is connected to the BMC network and “eth3” is connected to the compute network, disable genesis boot for the BMC network by setting :noboot in `dhcpietfaces` using:

```
chdef -t site dhcpietfaces="eth1:noboot,eth3"
```

# run the mknb command to remove the genesis configuration file for the specified network
mknb ppc64
For more information, see `dhcpi` keyword in the `site` table.

After making any DHCP changes, create a new DHCP configuration file with the networks defined using the `makedhcp` command.

```
makedhcp -n
```

## Configure passwords

1. Configure the system password for the `root` user on the compute nodes.
   - Set using the `chtab` command:
     ```
     chtab key=system passwd.username=root passwd.password=abc123
     ```
   
   To encrypt the password using `openssl`, use the following command:
   ```
   chtab key=system passwd.username=root passwd.password=`openssl passwd -1 abc123`
   ```

2. Configure the passwords for Management modules of the compute nodes.
   - For OpenBMC managed systems:
     ```
     chtab key=openbmc passwd.username=root passwd.password=OpenBmc
     ```
   - For IPMI/BMC managed systems:
     ```
     chtab key=ipmi passwd.username=ADMIN passwd.password=admin
     ```
   - For HMC managed systems:
     ```
     chtab key=hmc passwd.username=hscroot passwd.password=abc123
     ```
   
   If the username/password is different for multiple HMCs, set the `username` and `password` attribute for each HMC node object in xCAT.
   - For Blade managed systems:
     ```
     chtab key=blade passwd.username=USERID passwd.password=PASSW0RD
     ```
   - For FSP/BPA (Flexible Service Processor/Bulk Power Assembly) the factory default passwords must be changed before running commands against them.
     ```
     rspconfig frame general_passwd=general,<newpassword>
     rspconfig frame admin_passwd=admin,<newpassword>
     rspconfig frame HMC_passwd=,<newpassword>
     ```

3. If using the xCAT REST API
   - Create a non-root user that will be used to make the REST API calls.
     ```
     useradd xcatws
     passwd xcatws # set the password
     ```
   - Create an entry for the user into the xCAT `passwd` table.
(c) Set a policy in the xCAT policy table to allow the user to make calls against xCAT.

```
chtab key=xcat passwd.username=xcatws passwd.password=<xcatws_password>
```

When making calls to the xCAT REST API, pass in the credentials using the following attributes: userName and userPW

**Hardware Discovery & Define Node**

In order to manage machines using xCAT, the machines need to be defined as xCAT node objects in the database. The xCAT Objects documentation describes the process for manually creating node objects one by one using the xCAT mkdef command. This is valid when managing a small sizes cluster but can be error prone and cumbersome when managing large sized clusters.

xCAT provides several automatic hardware discovery methods to assist with hardware discovery by helping to simplify the process of detecting service processors (SP) and collecting various server information. The following are methods that xCAT supports:

**MTMS-based Discovery**

MTMS stands for Machine Type/Model and Serial. This is one way to uniquely identify each physical server.

MTMS-based hardware discovery assumes the administrator has the model type and serial number information for the physical servers and a plan for mapping the servers to intended hostname/IP addresses.

**Overview**

1. Automatically search and collect MTMS information from the servers
2. Write discovered-bmc-nodes to xCAT (recommended to set different BMC IP address)
3. Create predefined-compute-nodes to xCAT providing additional properties
4. Power on the nodes which triggers xCAT hardware discovery engine

**Pros**

- Limited effort to get servers defined using xCAT hardware discovery engine

**Cons**

- When compared to switch-based discovery, the administrator needs to create the predefined-compute-nodes for each of the discovered-bmc-nodes. This could become difficult for a large number of servers.

**Verification**

Before starting hardware discovery, ensure the following is configured to make the discovery process as smooth as possible.
Password Table

In order to communicate with IPMI-based hardware (with BMCs), verify that the xCAT passwd table contains an entry for `ipmi` which defines the default username and password to communicate with the IPMI-based servers.

```
tabdump passwd | grep ipmi
```

If not configured, use the following command to set `username=ADMIN` and `password=admin`.

```
chtab key=ipmi passwd.username=ADMIN passwd.password=admin
```

Genesis Package

The xCAT-genesis packages provides the utility to create the genesis network boot rootimage used by xCAT when doing hardware discovery. It should be installed during the xCAT install and would cause problems if missing.

Verify that the genesis-scripts and genesis-base packages are installed:

- [RHEL/SLES]:
  ```
  rpm -qa | grep -i genesis
  ```

- [Ubuntu]:
  ```
  dpkg -l | grep -i genesis
  ```

If missing:

1. Install them from the xcat-dep repository using the Operating Specific package manager (yum, zypper, apt-get, etc)

   - [RHEL]:
     ```
     yum install xCAT-genesis
     ```

   - [SLES]:
     ```
     zypper install xCAT-genesis
     ```

   - [Ubuntu]:
     ```
     apt-get install xCAT-genesis
     ```

2. Create the network boot rootimage with the following command: `mknb ppc64`.

   The genesis kernel should be copied to `/tftpboot/xcat`.

Discovery

When the IPMI-based servers are connected to power, the BMCs will boot up and attempt to obtain an IP address from an open range dhcp server on your network. In the case for xCAT managed networks, xCAT should be configured serve an open range dhcp IP addresses with the `dynamicrange` attribute in the networks table.

When the BMCs have an IP address and is pingable from the xCAT management node, administrators can discover the BMCs using the xCAT’s `bmcdiscover` command and obtain basic information to start the hardware discovery process.
xCAT Hardware discover uses the xCAT genesis kernel (diskless) to discover additional attributes of the compute node and automatically populate the node definitions in xCAT.

**Set static BMC IP using different IP address (recommended)**

The following example outlines the MTMS based hardware discovery for a single IPMI-based compute node.

<table>
<thead>
<tr>
<th>Compute Node Information</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Model Type</td>
<td>8247.22l</td>
</tr>
<tr>
<td>Serial Number</td>
<td>10112CA</td>
</tr>
<tr>
<td>Hostname</td>
<td>cn01</td>
</tr>
<tr>
<td>IP address</td>
<td>10.0.101.1</td>
</tr>
</tbody>
</table>

The BMC IP address is obtained by the open range dhcp server and the plan in this scenario is to change the IP address for the BMC to a static IP address in a different subnet than the open range addresses. The static IP address in this example is in the same subnet as the open range to simplify the networking configuration on the xCAT management node.

<table>
<thead>
<tr>
<th>BMC Information</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>IP address - dhcp</td>
<td>50.0.100.1</td>
</tr>
<tr>
<td>IP address - static</td>
<td>50.0.101.1</td>
</tr>
</tbody>
</table>

1. Detect the BMCs and add the node definitions into xCAT.

Use the `bmcdiscover` command to discover the BMCs responding over an IP range and write the output into the xCAT database. This discovered BMC node is used to control the physical server during hardware discovery and will be deleted after the correct server node object is matched to a pre-defined node. You must use the `-w` option to write the output into the xCAT database.

To discover the BMC with an IP address range of 50.0.100.1-100:

```bash
bmcdiscover --range 50.0.100.1-100 -z -w
```

The discovered nodes will be written to xCAT database. The discovered BMC nodes are in the form `node-model_type-serial`. To view the discovered nodes:

```bash
lsdef /node-.*
```

Note: The `bmcdiscover` command will use the username/password from the `passwd` table corresponding to `key=ipmi`. To overwrite with a different username/password use the `-u` and `-p` option to `bmcdiscover`.

2. Pre-define the compute nodes:

Use the `bmcdiscover` command to help discover the nodes over an IP range and easily create a starting file to define the compute nodes into xCAT.

To discover the compute nodes for the BMCs with an IP address of 50.0.100.1, use the command:

```bash
bmcdiscover --range 50.0.100.1 -z > predefined.stanzas
```

The discovered nodes have the naming convention: `node-<model_type>-<serial-number>`

```bash
# cat predefined.stanzas
node-8247-221-10112ca:
  objtype=node
```

(continues on next page)
3. Edit the predefined.stanzas file and change the discovered nodes to the intended hostname and IP address.

(a) Edit the predefined.stanzas file:

```
vi predefined.stanzas
```

(b) Rename the discovered object names to their intended compute node hostnames based on the MTMS mapping:

```
node-8247-22L-10112CA ==> cn01
```

(c) Add a `ip` attribute and give it the compute node IP address:

```
ip=10.0.101.1
```

(d) Remove `nodetype` and `hwtype` if defined in the predefined.stanza.

(e) Repeat for additional nodes in the predefined.stanza file based on the MTMS mapping.

In this example, the predefined.stanzas file now looks like the following:

```
# cat predefined.stanzas
cn01:
  objtype=node
  groups=all
  bmc=50.0.100.1
  cons=ipmi
  mgt=ipmi
  mtm=8247-22L
  serial=10112CA
  ip=10.0.101.1
```

4. Define the compute nodes into xCAT:

```
cat predefined.stanzas | mkdef -z
```

5. Set the chain table to run the bmcsetup script, this will set the BMC IP to static.

```
chdef cn01 chain="runcmd=bmcsetup"
```

6. [Optional] More operation plan to do after hardware discovery is done, ondiscover option can be used. For example, configure console, copy SSH key for OpenBMC, then disable powersupplyredundancy

```
chdef cn01 -p chain="ondiscover=makegocons|rspconfig:sshcfg|rspconfig:powersupplyredundancy=disabled"
```

**Note:** `|` is used to split commands, and `:` is used to split command with its option.
7. Set the target *osimage* into the chain table to automatically provision the operating system after the node discovery is complete.

```bash
chdef cn01 -p chain="osimage=<osimage_name>"
```

8. Change the BMC IP address

Set the BMC IP address to a different value for the **predefined** compute node definitions.

To change the dhcp obtained IP address of 50.0.100.1 to a static IP address of 50.0.101.1, run the following command:

```bash
chdef cn01 bmc=50.0.101.1
```

[Optional] If more configuration planed to be done on BMC, the following command is also needed.

```bash
chdef cn01 bmcvlantag=<vlanid>  # tag VLAN ID for BMC
chdef cn01 bmcusername=<desired_username>
chdef cn01 bmcpassword=<desired_password>
```

9. Add the compute node IP information to `/etc/hosts`:

```bash
makehosts cn01
```

10. Refresh the DNS configuration for the new hosts:

```bash
makedns -n
```

11. [Optional] Monitor the node discovery process using `rcons`

Configure the conserver for the **discovered** node to watch the discovery process using `rcons`:

```bash
makegocons node-8247-22l-10112ca
```

In another terminal window, open the remote console:

```bash
rcons node-8247-22l-10112ca
```

12. Start the discovery process by booting the **discovered** node definition:

```bash
rsetboot node-8247-22l-10112ca net
rpower node-8247-22l-10112ca on
```

13. The discovery process will network boot the machine into the diskless xCAT genesis kernel and perform the discovery process. When the discovery process is complete, doing `lsdef` on the compute nodes should show discovered attributes for the machine. The important `mac` information should be discovered, which is necessary for xCAT to perform OS provisioning.

### Set static BMC IP using dhcp provided IP address

The following example outlines the MTMS based hardware discovery for a single IPMI-based compute node.

<table>
<thead>
<tr>
<th>Compute Node Information</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Model Type</td>
<td>8247-22l</td>
</tr>
<tr>
<td>Serial Number</td>
<td>10112CA</td>
</tr>
<tr>
<td>Hostname</td>
<td>cn01</td>
</tr>
<tr>
<td>IP address</td>
<td>10.0.101.1</td>
</tr>
</tbody>
</table>
The BMC IP address is obtained by the open range dhcp server and the plan is to leave the IP address the same, except we want to change the IP address to be static in the BMC.

<table>
<thead>
<tr>
<th>BMC Information</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>IP address - dhcp</td>
<td>50.0.100.1</td>
</tr>
<tr>
<td>IP address - static</td>
<td>50.0.100.1</td>
</tr>
</tbody>
</table>

1. **Pre-define** the compute nodes:

   Use the `bmcdiscover` command to help discover the nodes over an IP range and easily create a starting file to define the compute nodes into xCAT.

   To discover the compute nodes for the BMCs with an IP address of 50.0.100.1, use the command:

   ```bash
   bmcdiscover --range 50.0.100.1 -z > predefined.stanzas
   ```

   The discovered nodes have the naming convention: node-<model-type>-<serial-number>

   ```bash
   # cat predefined.stanzas
   node-8247-22l-10112ca:
     objtype=node
     groups=all
     bmc=50.0.100.1
     cons=ipmi
     mgt=ipmi
     mtm=8247-22L
     serial=10112CA
   ```

2. **Edit** the `predefined.stanzas` file and change the discovered nodes to the intended hostname and IP address.

   (a) Edit the `predefined.stanzas` file:

   ```bash
   vi predefined.stanzas
   ```

   (b) Rename the discovered object names to their intended compute node hostnames based on the MTMS mapping:

   ```bash
   node-8247-22l-10112ca ==> cn01
   ```

   (c) Add a `ip` attribute and give it the compute node IP address:

   ```bash
   ip=10.0.101.1
   ```

   (d) Repeat for additional nodes in the `predefined.stanza` file based on the MTMS mapping.

   In this example, the `predefined.stanzas` file now looks like the following:

   ```bash
   # cat predefined.stanzas
   cn01:
     objtype=node
     groups=all
     bmc=50.0.100.1
     cons=ipmi
     mgt=ipmi
     mtm=8247-22L
     serial=10112CA
     ip=10.0.101.1
   ```
3. Define the compute nodes into xCAT:

```
cat predefined.stanzas | mkdef -z
```

4. Set the chain table to run the bmcsetup script, this will set the BMC IP to static.

```
chdef cn01 chain="runcmd=bmcsetup"
```

5. [Optional] More operation plan to do after hardware discovery is done, ondiscover option can be used. For example, configure console, copy SSH key for OpenBMC, then disable powersupplyredundancy

```
chdef cn01 -p chain="ondiscover=makegocons|rspconfig:sshcfg|rspconfig:power-supply-redundancy=disabled"
```

**Note:** | is used to split commands, and : is used to split command with its option.

6. Set the target osimage into the chain table to automatically provision the operating system after the node discovery is complete.

```
chdef cn01 -p chain="osimage=<osimage_name>"
```

7. Add the compute node IP information to /etc/hosts:

```
makehosts cn01
```

8. Refresh the DNS configuration for the new hosts:

```
makedns -n
```

9. [Optional] Monitor the node discovery process using rcons

Configure the goconserver for the predefined node to watch the discovery process using rcons:

```
makegocons cn01
```

In another terminal window, open the remote console:

```
rcons cn01
```

10. Start the discovery process by booting the predefined node definition:

```
rsetboot cn01 net
rpower cn01 on
```

11. The discovery process will network boot the machine into the diskless xCAT genesis kernel and perform the discovery process. When the discovery process is complete, doing `lsdef` on the compute nodes should show discovered attributes for the machine. The important mac information should be discovered, which is necessary for xCAT to perform OS provisioning.

**Switch-based Discovery**

For switch based hardware discovery, the servers are identified through the switches and switchposts they are directly connected to.

In this document, the following configuration is used in the example

Management Node info:
MN Hostname: xcat1
MN NIC info for Management Network (Host network): eth1, 10.0.1.1/16
MN NIC info for Service Network (FSP/BMC network): eth2, 50.0.1.1/16
Dynamic IP range for Hosts: 10.0.100.1-10.0.100.100
Dynamic IP range for FSP/BMC: 50.0.100.1-50.0.100.100

Compute Node info:

CN Hostname: cn1
Machine type/model: 8247-22L
Serial: 10112CA
IP Address: 10.0.101.1
Root Password: cluster
Desired FSP/BMC IP Address: 50.0.101.1
DHCP assigned FSP/BMC IP Address: 50.0.100.1
FSP/BMC username: ADMIN
FSP/BMC Password: admin

Switch info:

Switch name: switch1
Switch username: xcat
Switch password: passw0rd
Switch IP Address: 10.0.201.1
Switch port for Compute Node: port0

Configure xCAT

Configure network table

Normally, there will be at least two entries for the two subnet on MN in networks table after xCAT is installed:

```
#tabdump networks
#netname,net,mask,mgtifname,gateway,dhcpserver,tftpserver,nameservers,ntpservers,logservers,dynamicrange,staticrange,staticrangeincrement,nodehostname,ddnsdomain,vlanid,domain,mtu,comments,disable
"10_0_0_0-255_255_0_0","10.0.0.0","255.255.0.0","eth1","<xcatmaster>","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","","",""
chdef -t network 10.0.0.0-255.255.0.0 dynamicrange="10.0.100.1-10.0.100.100"
chdef -t network 50.0.0.0-255.255.0.0 dynamicrange="50.0.100.1-50.0.100.100"

Update DHCP configuration file:

makedhcp -n
makedhcp -a

**Config passwd table**

Set required passwords for xCAT to do hardware management and/or OS provisioning by adding entries to the xCAT passwd table:

```bash
# tabedit passwd
# key,username,password,cryptmethod,authdomain,comments,disable
```

For hardware management with ipmi, add the following line:

```
"ipmi","ADMIN","admin",,,
```

**Verify the genesis packages**

The `xcat-genesis` packages should have been installed when xCAT was installed, but would cause problems if missing. `xcat-genesis` packages are required to create the genesis root image to do hardware discovery and the genesis kernel sits in `/tftpboot/xcat/`. Verify that the `genesis-scripts` and `genesis-base` packages are installed:

- **[RHEL/SLES]:** `rpm -qa | grep -i genesis`
- **[Ubuntu]:** `dpkg -l | grep -i genesis`

If missing, install them from the `xcat-deps` package and run `mknbp ppc64` to create the genesis network boot root image.

**Predefined Nodes**

In order to differentiate one node from another, the admin needs to predefine node in xCAT database based on the switches information. This consists of two parts:

1. **Predefine Switches**
2. **Predefine Server Node**

Predefine Switches

The predefined switches will represent devices that the physical servers are connected to. xCAT need to access those switches to get server related information through SNMP v3.

So the admin need to make sure those switches are configured correctly with SNMP v3 enabled. <TODO: The document that Configure Ethernet Switches>

Then, define switch info into xCAT:

```
nodeadd switch1 groups=switch,all
chdef switch1 ip=10.0.201.1
chdef switch1 ip=10.0.201.1
chdef switch1 ip=10.0.201.1
```

(continues on next page)
Add switch into DNS using the following commands:

```bash
makehosts switch1
makedns -n
```

**Predefine Server node**

After switches are defined, the server node can be predefined with the following commands:

```bash
nodeadd cn1 groups=powerLE,all
chdef cn1 mgt=ipmi cons=ipmi ip=10.0.101.1 bmc=50.0.101.1 netboot=petitboot
chdef cn1 installnic=mac primarynic=mac
chdef cn1 switch=switch1 switchport=0
```

**[Optional]** If more configuration planned to be done on BMC, the following command is also needed.

```bash
chdef cn1 bmcvlantag=<vlanid>  # tag VLAN ID for BMC
chdef cn1 bmcusername=<desired_username>
chdef cn1 bmcpassword=<desired_password>
```

In order to do BMC configuration during the discovery process, set `runcmd=bmcsetup`.

```bash
chdef cn1 chain="runcmd=bmcsetup"
```

**[Optional]** More operation plan to do after hardware discovery is done, `ondiscover` option can be used.

For example, configure console, copy SSH key for OpenBMC, then disable powersupplyredundancy

```bash
chdef cn01 -p chain="ondiscover=makegocons|rspconfig:sshcfg|rspconfig:powersupplyredundancy=disabled"
```

**Note:** `|` is used to split commands, and `:` is used to split command with its option.

Set the target `osimage` into the chain table to automatically provision the operating system after the node discovery is complete.

```bash
chdef cn1 -p chain="osimage=<osimage_name>"
```

For more information about chain, refer to **Chain**

Add cn1 into DNS:

```bash
makehosts cn1
makedns -n
```

**Discover server and define**

After environment is ready, and the server is powered, we can start server discovery process. The first thing to do is discovering the FSP/BMC of the server. It is automatically powered on when the physical server is powered.

Use the `bmdiscover` command to discover the BMCs responding over an IP range and write the output into the xCAT database. This discovered BMC node is used to control the physical server during hardware discovery and will be...
deleted after the correct server node object is matched to a pre-defined node. You must use the \(-w\) option to write the output into the xCAT database.

To discover the BMC with an IP address range of 50.0.100.1-100:

```
bmcdiscover --range 50.0.100.1-100 -z -w
```

The discovered nodes will be written to xCAT database. The discovered BMC nodes are in the form `node-model_type-serial`. To view the discovered nodes:

```
lsdef /node-.*
```

Note: The `bmcdiscover` command will use the username/password from the `passwd` table corresponding to `key=ipmi`. To overwrite with a different username/password use the `-u` and `-p` option to `bmcdiscover`.

Start discovery process

To start discovery process, just need to power on the PBMC node remotely with the following command, and the discovery process will start automatically after the host is powered on:

```
rpower node-8247-421-10112ca on
```

[Optional] If you’d like to monitor the discovery process, you can use:

```
makegocons node-8247-421-10112ca
rcons node-8247-421-10112ca
```

Verify node definition

The following is an example of the server node definition after hardware discovery:

```
#lsdef cn1
Object name: cn1
  arch=ppc64
  bmc=50.0.101.1
  cons=ipmi
  cpucount=192
  cputype=POWER8E (raw), altivec supported
  groups=powerLE,all
  installnic=mac
  ip=10.0.101.1
  mac=6c:ae:8b:02:12:50
  memory=65118MB
  mgt=ipmi
  mtm=8247-22L
  netboot=petitboot
  postbootscripts=otherpkgs
  postscripts=syslog,remoteshell,syncfiles
  primarynic=mac
  serial=10112CA
  supportedarchs=ppc64
  switch=switch1
  switchport=0
```
Sequential-based Discovery

When the physical location of the server is not so important, sequential-based hardware discovery can be used to simplify the discovery work. The idea is: provided a node pool, each node in the pool will be assigned an IP address for host and an IP address for FSP/BMC, then the first physical server discovery request will be matched to the first free node in the node pool, and IP addresses for host and FSP/BMC will be assigned to that physical server.

In this document, the following configuration is used in the example

Management Node info:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>MN Hostname</td>
<td>xcat1</td>
</tr>
<tr>
<td>MN NIC info for Management Network (Host network)</td>
<td>eth1, 10.0.1.1/16</td>
</tr>
<tr>
<td>MN NIC info for Service Network (FSP/BMC network)</td>
<td>eth2, 50.0.1.1/16</td>
</tr>
<tr>
<td>Dynamic IP range for Hosts</td>
<td>10.0.100.1-10.0.100.100</td>
</tr>
<tr>
<td>Dynamic IP range for FSP/BMC</td>
<td>50.0.100.1-50.0.100.100</td>
</tr>
</tbody>
</table>

Compute Node info:

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>CN Hostname</td>
<td>cn1</td>
</tr>
<tr>
<td>Machine type/model</td>
<td>8247-22L</td>
</tr>
<tr>
<td>Serial</td>
<td>10112CA</td>
</tr>
<tr>
<td>IP Address</td>
<td>10.0.101.1</td>
</tr>
<tr>
<td>Root Password</td>
<td>cluster</td>
</tr>
<tr>
<td>Desired FSP/BMC IP Address</td>
<td>50.0.101.1</td>
</tr>
<tr>
<td>DHCP assigned FSP/BMC IP Address</td>
<td>50.0.100.1</td>
</tr>
<tr>
<td>FSP/BMC username</td>
<td>ADMIN</td>
</tr>
<tr>
<td>FSP/BMC Password</td>
<td>admin</td>
</tr>
</tbody>
</table>

Configure xCAT

Configure network table

Normally, there will be at least two entries for the two subnet on MN in networks table after xCAT is installed:

```
#tabdump networks
#netname,net,mask,mgtifname,gateway,dhcpserver,tftpserver,nameservers,ntpservers,
    logservers,dynamicrange,staticrange,staticrangeincrement,nodehostname,ddnsdomain,
    vlanid,domain,mtu,comments,disable
"10_0_0_0-255_255_0_0","10.0.0.0","255.255.0.0","eth1","<xcatmaster>",,"10.0.1.1",,,,
    ,,",,,,,,,
"50_0_0_0-255_255_0_0","50.0.0.0","255.255.0.0","eth2","<xcatmaster>",,"50.0.1.1",,,,
    ,,",,,,,,,
```

Run the following command to add networks in networks table if there are no entries in it:

```
makenetworks
```

Setup DHCP

Set the correct NIC from which DHCP server provide service:

```
chdef -t site dhcpietfaces=eth1,eth2
```
Add dynamic range in purpose of assigning temporary IP address for FSP/BMCs and hosts:

```
chdef -t network 10_0_0_0-255_255_0_0 dynamicrange="10.0.100.1-10.0.100.100"
chdef -t network 50_0_0_0-255_255_0_0 dynamicrange="50.0.100.1-50.0.100.100"
```

Update DHCP configuration file:

```
makedhcp -n
makedhcp -a
```

**Config passwd table**

Set required passwords for xCAT to do hardware management and/or OS provisioning by adding entries to the xCAT passwd table:

```
# tabedit passwd
# key,username,password,cryptmethod,authdomain,comments,disable
```

For hardware management with ipmi, add the following line:

```
"ipmi","ADMIN","admin",,,
```

**Verify the genesis packages**

The `xcat-genesis` packages should have been installed when xCAT was installed, but would cause problems if missing. `xcat-genesis` packages are required to create the genesis root image to do hardware discovery and the genesis kernel sits in `/tftpboot/xcat/`. Verify that the `genesis-scripts` and `genesis-base` packages are installed:

- **[RHEL/SLES]:** `rpm -qa | grep -i genesis`
- **[Ubuntu]:** `dpkg -l | grep -i genesis`

If missing, install them from the `xcat-deps` package and run `mknbp ppc64` to create the genesis network boot root image.

**Prepare node pool**

To prepare the node pool, shall predefine nodes first, then initialize the discovery process with the predefined nodes.

**Predefine nodes**

Predefine a group of nodes with desired IP address for host and IP address for FSP/BMC:

```
nodeadd cn1 groups=powerLE,all
chdef cn1 mgt=ipmi cons=ipmi ip=10.0.101.1 bmc=50.0.101.1 netboot=petitboot
     →installnic=mac primarynic=mac
```

**[Optional]** If more configuration planed to be done on BMC, the following command is also needed.

```
chdef cn1 bmcvlantag=<vlanid>  # tag VLAN ID for BMC
chdef cn1 bmcusername=<desired_username>
chdef cn1 bmcpassword=<desired_password>
```
In order to do BMC configuration during the discovery process, set `runcmd=bmcsetup`.

```
chdef cn1 chain="runcmd=bmcsetup"
```

[Optional] More operation plan to do after hardware discovery is done, `ondiscover` option can be used.

For example, configure console, copy SSH key for OpenBMC, then disable powersupplyredundancy

```
chdef cn01 -p chain="ondiscover=makegocons|rspconfig:sshcfg|rspconfig:powersupplyredundancy=disabled"
```

**Note:** `|` is used to split commands, and `:` is used to split command with its option.

Set the target `osimage` into the chain table to automatically provision the operating system after the node discovery is complete.

```
chdef cn1 -p chain="osimage=<osimage_name>"
```

For more information about chain, refer to *Chain*

### Initialize the discovery process

Specify the predefined nodes to the `nodediscoverstart` command to initialize the discovery process:

```
nodediscoverstart noderange=cn1
```

See `nodediscoverstart` for more information.

### Display information about the discovery process

There are additional `nodediscover*` commands you can run during the discovery process. See the man pages for more details.

Verify the status of discovery using `nodediscoverstatus`:

```
nodediscoverstatus
```

Show the nodes that have been discovered using `nodediscoverls`:

```
nodediscoverls -t seq -l
```

Stop the current sequential discovery process using: `nodediscoverstop`:

```
nodediscoverstop
```

**Note:** The sequential discovery process will stop automatically when all of the node names in the pool are consumed.

### Start discovery process

To start the discovery process, the system administrator needs to power on the servers one by one manually. Then the hardware discovery process will start automatically.
Verify Node Definition

After discovery of the node, properties of the server will be added to the xCAT node definition. Display the node definition and verify that the MAC address has been populated.

Manually Define Nodes

Manually Define Node means the admin knows the detailed information of the physical server and manually defines it into xCAT database with mkdef commands.

In this document, the following configuration is used in the example

Management Node info:

<table>
<thead>
<tr>
<th>MN Hostname: xcat1</th>
</tr>
</thead>
<tbody>
<tr>
<td>MN NIC info for Management Network (Host network): eth1, 10.0.1.1/16</td>
</tr>
<tr>
<td>MN NIC info for Service Network (FSP/BMC network): eth2, 50.0.1.1/16</td>
</tr>
<tr>
<td>Dynamic IP range for Hosts: 10.0.100.1-10.0.100.100</td>
</tr>
<tr>
<td>Dynamic IP range for FSP/BMC: 50.0.100.1-50.0.100.100</td>
</tr>
</tbody>
</table>

Compute Node info:

<table>
<thead>
<tr>
<th>CN Hostname: cn1</th>
</tr>
</thead>
<tbody>
<tr>
<td>Machine type/model: 8247-22L</td>
</tr>
<tr>
<td>Serial: 10112CA</td>
</tr>
<tr>
<td>IP Address: 10.0.101.1</td>
</tr>
<tr>
<td>Root Password: cluster</td>
</tr>
<tr>
<td>Desired FSP/BMC IP Address: 50.0.101.1</td>
</tr>
<tr>
<td>DHCP assigned FSP/BMC IP Address: 50.0.100.1</td>
</tr>
<tr>
<td>FSP/BMC username: ADMIN</td>
</tr>
<tr>
<td>FSP/BMC Password: admin</td>
</tr>
</tbody>
</table>

Manually Define Node

Execute mkdef command to define the node:

```
mkdef -t node cn1 groups=powerLE,all mgt=ipmi cons=ipmi ip=10.0.101.1
   netboot=petitboot bmc=50.0.101.1 bmcusername=ADMIN bmcpassword=admin installnic=mac
   primarynic=mac mac=6c:ae:8b:6a:d4:e4
```

The manually defined node will be like this:

```
# lsdef cn1
Object name: cn1
   bmc=50.0.101.1
   bmcpassword=admin
   bmcusername=ADMIN
   cons=ipmi
   groups=powerLE,all
   installnic=mac
   ip=10.0.101.1
   mac=6c:ae:8b:6a:d4:e4
   mgt=ipmi
   netboot=petitboot
```

(continues on next page)
mkdef --template can be used to create node definitions easily from the typical node definition templates or existing node definitions, some examples:

- creating node definition “cn2” with an existing node definition “cn1”

```bash
# mkdef -t node -o cn2 --template cn1 mac=66:55:44:33:22:11 ip=172.12.139.2
  -> bmc=172.11.139.2
1 object definitions have been created or modified.
```

except the attributes specified (mac, ip and bmc attribute here), other attributes of the newly created node “cn2” inherit the values of template node “cn1”

- creating a node definition “cn2” with the template “ppc64le-openbmc-template” (openbmc controlled ppc64le node) shipped by xCAT

```bash
  -> ip=172.12.139.2 bmc=172.11.139.2
  -> bmcpassword=USERID bmcusername=PASSW0RD
1 object definitions have been created or modified.
```

the unspecified attributes of newly created node “cn2” will be assigned with the default values in the template

to list all the node definition templates available in xCAT, run

```bash
# lsdef --template
```

to display the full definition of template “ppc64le-openbmc-template”, run

```bash
# lsdef -t node --template ppc64le-openbmc-template
```

the mandatory attributes, which must be specified while creating definitions with templates, are denoted with the value MANDATORY:<attribute description> in template definition.

the optional attributes, which can be specified optionally, are denoted with the value OPTIONAL:<attribute description> in template definition

**Manually Discover Nodes**

If you have a few nodes which were not discovered by automated hardware discovery process, you can find them in discoverydata table using the nodediscoverls command. The undiscovered nodes are those that have a discovery method value of ‘undef’ in the discoverydata table.

Display the undefined nodes with the nodediscoverls command:

```bash
# nodediscoverls -t undef
```

If you want to manually define an ‘undefined’ node to a specific free node name, use the nodediscoverdef(TODO) command.

Before doing that, a node with desired IP address for host and FSP/BMC must be defined first:
nodeadd cn1 groups=powerLE,all
chdef cn1 mgt=ipmi cons=ipmi ip=10.0.101.1 bmc=50.0.101.1 netboot=petitboot
→installnic=mac primarynic=mac

For example, if you want to assign the undefined node whose uuid is fa2cec8a-b724-4840-82c7-3313811788cd to cn1, run:

```
nodediscoverdef -u fa2cec8a-b724-4840-82c7-3313811788cd -n cn1
```

After manually defining it, the ‘node name’ and ‘discovery method’ attributes of the node will be changed. You can display the changed attributes using the `nodediscoverls` command:

```
<table>
<thead>
<tr>
<th>UUID</th>
<th>NODE</th>
<th>METHOD</th>
<th>MTM</th>
</tr>
</thead>
<tbody>
<tr>
<td>fa2cec8a-b724-4840-82c7-3313811788cd</td>
<td>cn1</td>
<td>manual</td>
<td>8247-22L</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>10112CA</td>
</tr>
</tbody>
</table>
```

Following are the brief characteristics and adaptability of each method, you can select a proper one according to your cluster size and other consideration.

- **Manually Define Nodes**
  
  Manually collect information for target servers and manually define them to xCAT **Node Object** through `mkdef` command.
  
  This method is recommended for small cluster which has less than 10 nodes.
  
  - **pros**
    
    No specific configuration and procedure required and very easy to use.
  
  - **cons**
    
    It will take additional time to configure the SP (Management Modules like: BMC, FSP) and collect the server information like MTMS (Machine Type and Machine Serial) and Host MAC address for OS deployment . . .

    This method is inefficient and error-prone for a large number of servers.

- **MTMS-based Discovery**
  
  **Step1:** Automatically search all the servers and collect server MTMS information.
  
  **Step2:** Define the searched server to a **Node Object** automatically. In this case, the node name will be generated based on the MTMS string. The admin can rename the **Node Object** to a reasonable name like `r1u1` (It means the physical location is in Rack1 and Unit1).
  
  **Step3:** Power on the nodes, xCAT discovery engine will update additional information like the **MAC for deployment** for the nodes.

  This method is recommended for the medium scale of cluster which has less than 100 nodes.

  - **pros**
    
    With limited effort to get the automatic discovery benefit.
  
  - **cons**
    
    Compared to **Switch-based Discovery**, the admin needs to be involved to rename the automatically discovered node to a reasonable name (optional). It’s hard to rename the node to a location-based name for a large number of server.
• **Switch-based Discovery**

  **Step1:** **Pre-define** the **Node Object** for all the nodes in the cluster. The **Pre-defined** node must have the attributes **switch** and **switchport** defined to specify which **Switch and Port** this server connected to. xCAT will use this **Switch and Port** information to map a discovered node to certain **Pre-defined** node.

  **Step2:** Power on the nodes, xCAT discovery engine will discover node attributes and update them to certain **Pre-defined** node.

  – **pros**

    The whole discovery process is totally automatic.

    Since the node is physically identified by the **Switch and Port** that the server connected, if a node fail and replaced with a new one, xCAT will automatically discover the new one and assign it to the original node name since the **Switch and Port** does not change.

  – **cons**

    You need to plan the cluster with planned **Switch and Port** mapping for each server and switch. All the Switches need be configured with snmpv3 accessible for xCAT management node.

• **Sequential-based Discovery**

  **Step1:** **Pre-define** the **Node Object** for all the nodes in the cluster.

  **Step2:** Manually power on the node one by one. The booted node will be discovered, each new discovered node will be assigned to one of the **Pre-defined** node in **Sequential**.

  – **pros**

    No special configuration required like **Switch-based Discovery**. No manual rename node step required like **MTMS-based Discovery**.

  – **cons**

    You have to strictly boot on the node in order if you want the node has the expected name. Generally you have to waiting for the discovery process finished before power on the next one.

**Hardware Management**

**Basic Operations**

**rbeacon - Beacon Light**

See **rbeacon manpage** for more information.

Most enterprise level servers have LEDs on their front and/or rear panels, one of which is a beacon light. If turned on, this light can assist the system administrator in locating one physical machine in the cluster.

Using xCAT, administrators can turn on and off the beacon light using: **rbeacon <node> on|off**

**rpower - Remote Power Control**

See **rpower manpage** for more information.

Use the **rpower** command to remotely power on and off a single server or a range of servers.

```
rpower <noderange> on
rpower <noderange> off
```
Other actions include:

- To get the current power state of a server: `rpower <noderange> state`
- To boot/reboot a server: `rpower <noderange> boot`
- To hardware reset a server: `rpower <noderange> reset`

**rcons - Remote Console**

See `rcons manpage` for more information.

Most enterprise servers do not have video adapters installed with the machine and often do not provide a method for attaching a physical monitor/keyboard/mouse to get the display output. For this purpose xCAT can assist the system administrator to view the console over a “Serial-over-LAN” (SOL) connection through the BMC.

Configure the correct console management by modifying the node definition:

- For OpenPOWER, **IPMI** managed server:
  ```
  chdef -t node -o <noderange> cons=ipmi
  ```

- For OpenPOWER, **OpenBMC** managed servers:
  ```
  chdef -t node -o <noderange> cons=openbmc
  ```

Open a console to `compute1`:
```
rcosn compute1
```

**Note:** The keystroke `ctrl+e c` will disconnect you from the console.

**Troubleshooting**

**General**

xCAT has been integrated with 3 kinds of console server service, they are

- `conserver`
- `goconserver`
- `confluent`

`rcons` command relies on one of them. The `conserver` and `goconserver` packages should have been installed with xCAT as they are part of the xCAT dependency packages. If you hope to try `confluent`, see `confluent`.

For systemd based systems, `goconserver` is used by default. If you are having problems seeing the console, try the following.

1. Make sure `goconserver` is configured by running `makegocons`.
2. Check if `goconserver` is up and running
   ```
   systemctl status goconserver.service
   ```
3. If `goconserver` is not running, start the service using:
   ```
   systemctl start goconserver.service
   ```
4. Try `makegocons -q [<node>]` to verify if the node has been registered.
5. Invoke the console again: `rcons <node>`

More details for goconserver, see goconserver documentation.

[Deprecated] If conserver is used, try the following.

1. Make sure `conserver` is configured by running `makeconservercf`.

2. Check if `conserver` is up and running

   ```
   [sysvinit] service conserver status
   [systemd] systemctl status conserver.service
   ```

3. If `conserver` is not running, start the service using:

   ```
   [sysvinit] service conserver start
   [systemd] systemctl start conserver.service
   ```

4. Invoke the console again: `rcons <node>`

**Advanced Operations**

**rinv** - Remote Hardware Inventory

See `rinv manpage` for more information.

Use `rinv` command to remotely obtain inventory information of a physical machine. This will help to distinguish one machine from another and aid in mapping the model type and/or serial number of a machine with its host name.

To get all the hardware information for node `cn1`:

```
rinv cn1 all
```

To get just the firmware information for `cn1`:

```
rinv cn1 firm
```

**rvitals** - Remote Hardware Vitals

See `rvitals manpage` for more information.

Collecting runtime information from a running physical machine is an important part of system administration. Data can be obtained from the service processor including temperature, voltage, cooling fans, etc.

Use the `rvitals` command to obtain this information.

```
rvitals <noderange> all
```

To only get the temperature information of machines in a particular noderange:

```
rvitals <noderange> temp
```

**rflash** - Remote Firmware Flashing

See `rflash manpage` for more information.
**IPMI Firmware Update**

The `rflash` command is provided to assist the system administrator in updating firmware.

To check the current firmware version on the node’s BMC and the HPM file:

```
rflash <noderange> -c /firmware/8335_810.1543.20151021b_update.hpm
```

To update the firmware on the node’s BMC to version in the HPM file:

```
rflash <noderange> /firmware/8335_810.1543.20151021b_update.hpm
```

**OpenBMC Firmware Update**

**Manual Firmware Flash**

The sequence of events that must happen to flash OpenBMC firmware is the following:

1. Power off the Host
2. Upload and Activate BMC
3. Reboot the BMC (applies BMC)
4. Upload and Activate Host
5. Power on the Host (applies Host)

**Power off Host**

Use the `rpower` command to power off the host:

```
rpower <noderange> off
```

**Upload and Activate BMC Firmware**

Use the `rflash` command to upload and activate the Host firmware:

```
rflash <noderange> -a /path/to/obmc-phosphor-image-witherspoon.ubi.mtd.tar
```

If running `rflash` in Hierarchy, the firmware files must be accessible on the Service Nodes.

**Note:** If a `.tar` file is provided, the `-a` option does an upload and activate in one step. If an ID is provided, the `-a` option just does activate the specified firmware. After firmware is activated, use the `rflash <noderange> -l` to view. The `rflash` command shows `(*)` as the active firmware and `(+)` on the firmware that requires reboot to become effective.

**Reboot the BMC**

Use the `rpower` command to reboot the BMC:

```
rpower <noderange> bmcreboot
```
The BMC will take 2-5 minutes to reboot, check the status using: `rpower <noderange> bmcstate` and wait for BMCReady to be returned.

**Known Issue:** On reboot, the first call to the BMC after reboot, xCAT will return Error: BMC did not respond within 10 seconds, retry the command. Please retry.

### Upload and Activate Host Firmware

Use the `rflash` command to upload and activate the Host firmware:

```plaintext
rflash <noderange> -a /path/to/witherspoon.pnor.squashfs.tar
```

If running `rflash` in Hierarchy, the firmware files must be accessible on the Service Nodes.

**Note:** The `-a` option does an upload and activate in one step, after firmware is activated, use the `rflash <noderange> -l` to view. The `rflash` command shows (*) as the active firmware and (+) on the firmware that requires reboot to become effective.

### Power on Host

Use the `rpower` command to power on the Host:

```plaintext
rpower <noderange> on
```

### Validation

Use one of the following commands to validate firmware levels are in sync:

- Use the `rinv` command to validate firmware level:
  ```plaintext
  rinv <noderange> firm -V | grep -i ibm | grep "\*" | xcoll
  ```

- Use the `rflash` command to validate the firmware level:
  ```plaintext
  rflash <noderange> -l | grep "\*" | xcoll
  ```

### Unattended Firmware Flash

Unattended flash of OpenBMC firmware will do the following events:

1. Upload both BMC firmware file and Host firmware file
2. Activate both BMC firmware and Host firmware
3. If BMC firmware becomes activate, reboot BMC to apply new BMC firmware, or else, `rflash` will exit
4. If BMC itself state is `NotReady`, `rflash` will exit
5. If BMC itself state is `Ready`, and use `--no-host-reboot` option, `rflash` will not reboot the compute node
6. If BMC itself state is `Ready`, and do not use `--no-host-reboot` option, `rflash` will reboot the compute node to apply Host firmware

Use the following command to flash the firmware unattended:
Use the following command to flash the firmware unattended and not reboot the compute node:

```bash
rflash <noderange> -d /path/to/directory
```

If there are errors encountered during the flash process, take a look at the manual steps to continue flashing the BMC.

**Validation**

Use one of the following commands to validate firmware levels are in sync:

- **Use the rinv command to validate firmware level:**

  ```bash
  rinv <noderange> firm -V | grep -i ibm | grep "\*" | xcoll
  ```

- **Use the rflash command to validate the firmware level:**

  ```bash
  rflash <noderange> -l | grep "\*" | xcoll
  ```

**rspconfig - Remote Configuration of Service Processors**

See `rspconfig manpage` for more information.

The `rspconfig` command can be used to configure the service processor, or Baseboard Management Controller (BMC), of a physical machine.

For example, to turn on SNMP alerts for node `cn5`:

```bash
rspconfig cn5 alert=on
```

**reventlog - Remote Event Log of Service Processors**

See `reventlog manpage` for more information.

The `reventlog` command can be used to display and clear event log information on the service processor, or Baseboard Management Controller (BMC), of a physical machine.

For example, to display all event log entries for node `cn5`:

```bash
reventlog cn5
```

To clear all event log entries for node `cn5`:

```bash
reventlog cn5 clear
```

**Diskful Installation**

**Select or Create an osimage Definition**

Before creating an image on xCAT, the distro media should be prepared ahead. That can be ISOs or DVDs.
XCAT use ‘copycds’ command to create an image which will be available to install nodes. *copycds* will copy all contents of Distribution DVDs/ISOs or Service Pack DVDs/ISOs to a destination directory, and create several relevant osimage definitions by default.

If using an ISO, copy it to (or NFS mount it on) the management node, and then run:

```
copycds <path>/<specific-distro>.iso
```

**Note:** while sle15 contains installer medium and packages medium, need *copycds* copy all contents of DVD1 of the installer medium and DVD1 of the packages medium, for example:

```
```

If using a DVD, put it in the DVD drive of the management node and run:

```
copycds /dev/<dvd-drive-name>
```

To see the list of osimages:

```
lsdef -t osimage
```

To see the attributes of a particular osimage:

```
lsdef -t osimage <osimage-name>
```

Initially, some attributes of osimage are assigned default values by xCAT - they all can work correctly because the files or templates invoked by those attributes are shipped with xCAT by default. If you need to customize those attributes, refer to the next section *Customize osimage*.

Below is an example of osimage definitions created by *copycds*:

```
# lsdef -t osimage
rhels7.2-ppc64le-install-compute (osimage)
rhels7.2-ppc64le-install-service (osimage)
rhels7.2-ppc64le-netboot-compute (osimage)
rhels7.2-ppc64le-stateful-mgmtnode (osimage)
```

In these osimage definitions shown above

- `<os>-<arch>-install-compute` is the default osimage definition used for diskful installation
- `<os>-<arch>-netboot-compute` is the default osimage definition used for diskless installation
- `<os>-<arch>-install-service` is the default osimage definition used for service node deployment which shall be used in hierarchical environment

**Note:** There are more things needed for *ubuntu ppc64le* osimages:

For pre-18.04 version of Ubuntu for ppc64el, the initrd.gz shipped with the ISO does not support network booting. In order to install ubuntu with xCAT, you need to follow the steps below to complete the osimage definition.

- Download mini.iso from
  
  [ubuntu 16.04]: http://xcat.org/files/netboot/ubuntu16.04/ppc64el/mini.iso
• Mount mini.iso

```
mkdir /tmp/iso
mount -o loop mini.iso /tmp/iso
```

• Copy the netboot initrd.gz to osimage

```
mkdir -p /install/<ubuntu-version>/ppc64el/install/netboot
cp /tmp/iso/install/initrd.gz /install/<ubuntu-version>/ppc64el/install/netboot
```

[Below tips maybe helpful for you]

[Tips 1]
If this is the same distro version as what your management node uses, create a .repo file in /etc/yum.repos.d with contents similar to:

```
[local-<os>-<arch>]
name=xCAT local <os> <version>
baseurl=file:/install/<os>/<arch>
enabled=1
gpgcheck=0
```

In this way, if you need to install some additional RPMs into your MN later, you can simply install them with `yum`. Or if you are installing a software on your MN that depends some RPMs from this distro, those RPMs will be found and installed automatically.

[Tips 2]
You can create/modify an osimage definition easily with any existing osimage definition, the command is

```
mkdef -t osimage -o <new osimage> --template <existing osimage> [attribute=value, ...
```

Except the specified attributes `<attribute>`, the attributes of `<new osimage>` will inherit the values of template osimage `<existing osimage>`.

As an example, the following command creates a new osimage “myosimage.rh7.compute.netboot” based on the existing osimage “rhels7.4-ppc64le-netboot-compute” with some customized attributes

```
mkdef -t osimage -o myosimage.rh7.compute.netboot --template rhels7.4-ppc64le-netboot-compute
--netboot/3rdpkgs/ otherpkglist=/install/custom/osimage/myosimage.rh7.compute.
```

Customize osimage (Optional)

Optional means all the subitems in this page are not necessary to finish an OS deployment. If you are new to xCAT, you can just jump to Initialize the Compute for Deployment.

Configure RAID before deploying the OS
Overview

xCAT provides an user interface `linuximage.partitionfile` to specify the customized partition script for diskful provision, and provides some default partition scripts.

Deploy Diskful Nodes with RAID1 Setup on RedHat

xCAT provides a partition script `raid1_rh.sh` which configures RAID1 across 2 disks on RHEL 7.x operating systems. In most scenarios, the sample partitioning script is sufficient to create a basic RAID1 across two disks and is provided as a sample to build upon.

1. Obtain the partition script:

```bash
mkdir -p /install/custom/partition/
wget https://raw.githubusercontent.com/xcat2/xcat-extensions/master/partition/ → raid1_rh.sh \
-O /install/custom/partition/raid1_rh.sh
```

2. Associate the partition script to the osimage:

```bash
chdef -t osimage -o rhels7.3-ppc64le-install-compute \partitionfile="s:/install/custom/partition/raid1_rh.sh"
```

3. Provision the node:

```bash
rinstall cn1 osimage=rhels7.3-ppc64le-install-compute
```

After the diskful nodes are up and running, you can check the RAID1 settings with the following process:

The `mount` command shows the `/dev/mdx` devices are mounted to various file systems, the `/dev/mdx` indicates that the RAID is being used on this node.

```bash
# mount
... 
/dev/md1 on / type xfs (rw,relatime,attr2,inode64,noquota)
/dev/md0 on /boot type xfs (rw,relatime,attr2,inode64,noquota)
/dev/md2 on /var type xfs (rw,relatime,attr2,inode64,noquota)
```

The file `/proc/mdstat` includes the RAID devices status on the system, here is an example of `/proc/mdstat` in the non-multipath environment:

```bash
# cat /proc/mdstat
Personalities : [raid1]
md2 : active raid1 sdk2[0] sjd2[1]
  1047552 blocks super 1.2 [2/2] [UU] 
  resync=DELAYED 
  bitmap: 1/1 pages [64KB], 65536KB chunk
md3 : active raid1 sdk3[0] sjd3[1]
  1047552 blocks super 1.2 [2/2] [UU] 
  resync=DELAYED 
md0 : active raid1 sdk5[0] sjd5[1]
  524224 blocks super 1.0 [2/2] [UU] 
  bitmap: 0/1 pages [0KB], 65536KB chunk
```

(continues on next page)
md1 : active raid1 sdk6[0] sdj6[1]
  973998080 blocks super 1.2 [2/2] [UU]
  [==>.....................] resync = 12.8% \(125356224/973998080\) finish=138.1min
  speed=102389K/sec
  bitmap: 1/1 pages [64KB], 65536KB chunk

unused devices: <none>

On the system with multipath configuration, the /proc/mdstat looks like:

```
# cat /proc/mdstat
Personalities : [raid1]
md2 : active raid1 dm-11[0] dm-6[1]
  291703676 blocks super 1.1 [2/2] [UU]
  bitmap: 1/1 pages [64KB], 65536KB chunk
md1 : active raid1 dm-8[0] dm-3[1]
  1048568 blocks super 1.1 [2/2] [UU]
md0 : active raid1 dm-9[0] dm-4[1]
  204788 blocks super 1.0 [2/2] [UU]
unused devices: <none>
```

The command `mdadm` can query the detailed configuration for the RAID partitions:

```
mdadm --detail /dev/md2
```

**Deploy Diskful Nodes with RAID1 Setup on SLES**

xCAT provides one sample autoyast template files with the RAID1 settings `/opt/xcat/share/xcat/install/sles/service.raid1.sles11.tmpl`. You can customize the template file and put it under `/install/custom/install/<platform>/` if the default one does not match your requirements.

Here is the RAID1 partitioning section in `service.raid1.sles11.tmpl`:

```
<partitioning config:type="list">
  <drive>
    /dev/sda
  </drive>
  <partitions config:type="list">
    <partition>
      <format config:type="boolean">false</format>
      <partition_id config:type="integer">65</partition_id>
      <partition_nr config:type="integer">1</partition_nr>
      <partition_type>primary</partition_type>
      <size>24M</size>
    </partition>
    <partition>
      <format config:type="boolean">false</format>
      <partition_id config:type="integer">253</partition_id>
      <partition_nr config:type="integer">2</partition_nr>
      <raid_name>/dev/md0</raid_name>
      <raid_type>raid</raid_type>
      <size>2G</size>
    </partition>
  </partitions>
</partitioning>
```
The samples above created one 24MB PReP partition on each disk, one 2GB mirrored swap partition and one mirrored / partition uses all the disk space. If you want to use different partitioning scheme in your cluster, modify this RAID1 section in the autoyast template file accordingly.

Since the PReP partition cannot be mirrored between the two disks, some additional postinstall commands should be run to make the second disk bootable, here the commands needed to make the second disk bootable:

```
# Set the second disk to be bootable for RAID1 setup
parted -s /dev/sdb mkfs 1 fat16
parted /dev/sdb set 1 type 6
parted /dev/sdb set 1 boot on
dd if=/dev/sda1 of=/dev/sdb1
bootlist -m normal sda sdb
```

The procedure listed above has been added to the file /opt/xcat/share/xcat/install/scripts/post.sles11.raid1 to make it be automated. The autoyast template file service.raid1.sles11.tmpl will include the content of post.sles11.raid1, so no manual steps are needed here.

After the diskful nodes are up and running, you can check the RAID1 settings with the following commands:

Mount command shows the /dev/mdx devices are mounted to various file systems, the /dev/mdx indicates that the RAID is being used on this node.

```
server:~ # mount
/dev/md1 on / type reiserfs (rw)
proc on /proc type proc (rw)
sysfs on /sys type sysfs (rw)
debugfs on /sys/kernel/debug type debugfs (rw)
devtmpfs on /dev type devtmpfs (rw,mode=0755)
tmpfs on /dev/shm type tmpfs (rw,mode=1777)
devpts on /dev/pts type devpts (rw,mode=0620,gid=5)
```

The file /proc/mdstat includes the RAID devices status on the system, here is an example of /proc/mdstat:

```
server:~ # cat /proc/mdstat
Personalties : [raid1] [raid0] [raid10] [raid6] [raid5] [raid4]
md0 : active (auto-read-only) raid1 sda2[0] sdb2[1]
      2104500 blocks super 1.0 [2/2] [UU]
      bitmap: 0/1 pages [0KB], 128KB chunk
md1 : active raid1 sda3[0] sdb3[1]
      18828108 blocks super 1.0 [2/2] [UU]
```

(continues on next page)
The command `mdadm` can query the detailed configuration for the RAID partitions:

```
mdadm --detail /dev/md1
```

**Disk Replacement Procedure**

If any one disk fails in the RAID1 array, do not panic. Follow the procedure listed below to replace the failed disk and you will be fine.

Faulty disks should appear marked with an (F) if you look at `/proc/mdstat`:

```
# cat /proc/mdstat
Personalities : [raid1]
md2 : active raid1 dm-11[0](F) dm-6[1]
    291703676 blocks super 1.1 [2/1] [U]
    bitmap: 1/1 pages [64KB], 65536KB chunk

md1 : active raid1 dm-8[0](F) dm-3[1]
    1048568 blocks super 1.1 [2/1] [U]

md0 : active raid1 dm-9[0](F) dm-4[1]
    204788 blocks super 1.0 [2/1] [U]

unused devices: <none>
```

We can see that the first disk is broken because all the RAID partitions on this disk are marked as (F).

**Remove the failed disk from RAID array**

`mdadm` is the command that can be used to query and manage the RAID arrays on Linux. To remove the failed disk from RAID array, use the command:

```
mdadm --manage /dev/mdx --remove /dev/xxx
```

Where the `/dev/mdx` are the RAID partitions listed in `/proc/mdstat` file, such as md0, md1 and md2; the `/dev/xxx` are the backend devices like dm-11, dm-8 and dm-9 in the multipath configuration and sda5, sda3 and sda2 in the non-multipath configuration.

Here is the example of removing failed disk from the RAID1 array in the non-multipath configuration:

```
mdadm --manage /dev/md0 --remove /dev/sda3
mdadm --manage /dev/md1 --remove /dev/sda2
mdadm --manage /dev/md2 --remove /dev/sda5
```

Here is the example of removing failed disk from the RAID1 array in the multipath configuration:

```
mdadm --manage /dev/md0 --remove /dev/dm-9
mdadm --manage /dev/md1 --remove /dev/dm-8
mdadm --manage /dev/md2 --remove /dev/dm-11
```
After the failed disk is removed from the RAID1 array, the partitions on the failed disk will be removed from `/proc/mdstat` and the “mdadm --detail” output also.

```bash
# cat /proc/mdstat
Personalities : [raid1]
md2 : active raid1 dm-6[1]
  291703676 blocks super 1.1 [2/1] [_U]
  bitmap: 1/1 pages [64KB], 65536KB chunk

md1 : active raid1 dm-3[1]
  1048568 blocks super 1.1 [2/1] [_U]

md0 : active raid1 dm-4[1]
  204788 blocks super 1.0 [2/1] [_U]

unused devices: <none>

# mdadm --detail /dev/md0
/dev/md0:
  Version : 1.0
  Creation Time : Tue Jul 19 02:39:03 2011
  Raid Level : raid1
  Array Size : 204788 (200.02 MiB 209.70 MB)
  Used Dev Size : 204788 (200.02 MiB 209.70 MB)
  Raid Devices : 2
  Total Devices : 1
  Persistence : Superblock is persistent
  Update Time : Wed Jul 20 02:00:04 2011
  State : clean, degraded
  Active Devices : 1
  Working Devices : 1
  Failed Devices : 0
  Spare Devices : 0

  Name : c250f17c0lap01:0 (local to host c250f17c0lap01)
  UUID : eba4d8ad:8f08f231:3c60e20f:1f929144
  Events : 26

  Number Major Minor RaidDevice State
    0    0    0      0      0    removed
    1   253    4      1      1    active sync  /dev/dm-4
```

Replace the disk

Depending on the hot swap capability, you may simply unplug the disk and replace with a new one if the hot swap is supported; otherwise, you will need to power off the machine and replace the disk and the power on the machine.

Create partitions on the new disk

The first thing we must do now is to create the exact same partitioning as on the new disk. We can do this with one simple command:

```bash
sfdisk -d /dev/<good_disk> | sfdisk /dev/<new_disk>
```

For the non-multipath configuration, here is an example:
sfdisk -d /dev/sdb | sfdisk /dev/sda

For the multipath configuration, here is an example:

sfdisk -d /dev/dm-1 | sfdisk /dev/dm-0

If you got error message “sfdisk: I don’t like these partitions - nothing changed.”, you can add “--force” option to the sfdisk command:

sfdisk -d /dev/sdb | sfdisk /dev/sda --force

You can run:

fdisk -l

To check if both hard drives have the same partitioning now.

**Add the new disk into the RAID1 array**

After the partitions are created on the new disk, you can use command:

mdadm --manage /dev/mdx --add /dev/xxx

To add the new disk to the RAID1 array. Where the /dev/mdx are the RAID partitions like md0, md1 and md2; the /dev/xxx are the backend devices like dm-11, dm-8 and dm-9 in the multipath configuration and sda5, sda3 and sda2 in the non-multipath configuration.

Here is an example for the non-multipath configuration:

```
mdadm --manage /dev/md0 --add /dev/sda3
mdadm --manage /dev/md1 --add /dev/sda2
mdadm --manage /dev/md2 --add /dev/sda5
```

Here is an example for the multipath configuration:

```
mdadm --manage /dev/md0 --add /dev/dm-9
mdadm --manage /dev/md1 --add /dev/dm-8
mdadm --manage /dev/md2 --add /dev/dm-11
```

All done! You can have a cup of coffee to watch the fully automatic reconstruction running…

While the RAID1 array is reconstructing, you will see some progress information in /proc/mdstat:

```
# cat /proc/mdstat
Personalities : [raid1]
md2 : active raid1 dm-11[0] dm-6[1]    291703676 blocks super 1.1 [2/1] [U]
       [>....................] recovery = 0.7% (2103744/291703676) finish=86.2min_
->speed=55960K/sec
        bitmap: 1/1 pages [64KB], 65536KB chunk
md1 : active raid1 dm-8[0] dm-3[1]    1048568 blocks super 1.1 [2/1] [U]
       [==================>.......] recovery = 65.1% (683904/1048568) finish=0.1min_
->speed=48850K/sec
```

(continues on next page)
After the reconstruction is done, the `/proc/mdstat` becomes like:

```
# cat /proc/mdstat
Personalities : [raid1]
md0 : active raid1 dm-9[0] dm-4[1]
     204788 blocks super 1.0 [2/2] [U] [==================> ] recovery = 96.5% (198016/204788) finish=0.0min
     speed=14144K/sec
unused devices: <none>
```

Make the new disk bootable

If the new disk does not have a PReP partition or the PReP partition has some problem, it will not be bootable, here is an example on how to make the new disk bootable, you may need to substitute the device name with your own values.

- **[RHEL]:**

  ```
  mkofboot .b /dev/sda
  bootlist -m normal sda sdb
  ```

- **[SLES]:**

  ```
  parted -s /dev/sda mkfs 1 fat16
  parted /dev/sda set 1 type 6
  parted /dev/sda set 1 boot on
  dd if=/dev/sdb1 of=/dev/sdal
  bootlist -m normal sda sdb
  ```

Load Additional Drivers

Overview

During the installing or netbooting of a node, the drivers in the initrd will be used to drive the devices like network cards and IO devices to perform the installation/netbooting tasks. But sometimes the drivers for the new devices were not included in the default initrd shipped by Red Hat or Suse. A solution is to inject the new drivers into the initrd to drive the new device during the installation/netbooting process.

Generally there are two approaches to inject the new drivers: **Driver Update Disk** and **Drive RPM package**.

A **“Driver Update Disk”** is media which contains the drivers, firmware and related configuration files for certain devices. The driver update disk is always supplied by the vendor of the device. One driver update disk can contain
multiple drivers for different OS releases and different hardware architectures. Red Hat and Suse have different driver update disk formats.

The ‘**Driver RPM Package**’ is the rpm package which includes the drivers and firmware for the specific devices. The Driver RPM is the rpm package which is shipped by the Vendor of the device for a new device or a new kernel version.

xCAT supports both. But for ‘**Driver RPM Package**’ is only supported in xCAT 2.8 and later.

No matter which approach chosen, there are two steps to make new drivers work. one is locate the new driver’s path, another is inject the new drivers into the initrd.

### Locate the New Drivers

#### For Driver Update Disk

There are two approaches for xCAT to find the driver disk (pick one):

1. Specify the location of the driver disk in the osimage object (**This is ONLY supported in 2.8 and later**)

   The value for the ‘driverupdatesrc’ attribute is a comma separated driver disk list. The tag ‘dud’ must be specified before the full path of ‘driver update disk’ to specify the type of the file:

   ```
   chdef -t osimage <osimagename> driverupdatesrc=dud:<full path of driver disk>
   ```

1. Put the driver update disk in the directory `<installroot>/driverdisk/<os>/<arch>` (example: `/install/driverdisk/sles11.1/x86_64`).

   During the running of the `genimage`, `geninitrd`, or `nodeset` commands, xCAT will look for driver update disks in the directory `<installroot>/driverdisk/<os>/<arch>`.

##### For Driver RPM Packages

The Driver RPM packages must be specified in the osimage object.

Three attributes of osimage object can be used to specify the Driver RPM location and Driver names. If you want to load new drivers in the initrd, the ‘netdrivers’ attribute must be set. And one or both of the ‘driverupdatesrc’ and ‘osupdatename’ attributes must be set. If both of ‘driverupdatesrc’ and ‘osupdatename’ are set, the drivers in the ‘driverupdatesrc’ have higher priority.

- netdrivers - comma separated driver names that need to be injected into the initrd. The postfix ‘.ko’ can be ignored.

The ‘netdrivers’ attribute must be set to specify the new driver list. If you want to load all the drivers from the driver rpms, use the keyword allupdate. Another keyword for the netdrivers attribute is updateonly, which means only the drivers located in the original initrd will be added to the newly built initrd from the driver rpms. This is useful to reduce the size of the new built initrd when the distro is updated, since there are many more drivers in the new kernel rpm than in the original initrd. Examples:

```
chdef -t osimage <osimagename> netdrivers=megaraid_sas.ko,igb.ko
chdef -t osimage <osimagename> netdrivers=allupdate
chdef -t osimage <osimagename> netdrivers=updateonly,igb.ko,new.ko
```

- driverupdatesrc - comma separated driver rpm packages (full path should be specified)

A tag named ‘rpm’ can be specified before the full path of the rpm to specify the file type. The tag is optional since the default format is ‘rpm’ if no tag is specified. Example:
chdef -t osimage <osimagenname> driverupdatesrc=rpm:<full path of driver disk1>,rpm:<full path of driver disk2>


When geninitrd is run, kernel-*.rpm will be searched in the osdistroupdate.dirpath to get all the rpm packages and then those rpms will be searched for drivers. Example:

mkdef -t osdistroupdate update1 dirpath=/install/<os>/<arch>
chdef -t osimage <osimagenname> osupdatename=update1

If ‘osupdatename’ is specified, the kernel shipped with the ‘osupdatename’ will be used to load the newly built initrd, then only the drivers matching the new kernel will be kept in the newly built initrd. If trying to use the ‘osupdatename’, the ‘allupdate’ or ‘updateonly’ should be added in the ‘netdrivers’ attribute, or all the necessary driver names for the new kernel need to be added in the ‘netdrivers’ attribute. Otherwise the new drivers for the new kernel will be missed in newly built initrd. ..

Inject the Drivers into the initrd

For Driver Update Disk

- If specifying the driver disk location in the osimage, there are two ways to inject drivers:
  1. :: nodeset <noderange> osimage=<osimagenname>
  2. :: geninitrd <osimagenname> nodeset <noderange> osimage=<osimagenname> --noupdateinitrd

Note: ‘geninitrd’ + ‘nodeset –noupdateinitrd’ is useful when you need to run nodeset frequently for a diskful node. ‘geninitrd’ only needs be run once to rebuild the initrd and ‘nodeset –noupdateinitrd’ will not touch the initrd and kernel in /tftpboot/xcat/osimage/<osimagenname>/.

- If putting the driver disk in <installroot>/driverdisk/<os>/<arch>:

Running ‘nodeset <noderange>’ in anyway will load the driver disk

For Driver RPM Packages

There are two ways to inject drivers:

1. Using nodeset command only:

   nodeset <noderange> osimage=<osimagenname> [--ignorekernelchk]

2. Using geninitrd with nodeset command:

   geninitrd <osimagenname> [--ignorekernelchk]
   nodeset <noderange> osimage=<osimagenname> --noupdateinitrd

Note: ‘geninitrd’ + ‘nodeset –noupdateinitrd’ is useful when you need to run nodeset frequently for diskful nodes. ‘geninitrd’ only needs to be run once to rebuild the initrd and ‘nodeset –noupdateinitrd’ will not touch the initrd and kernel in /tftpboot/xcat/osimage/<osimagenname>/.

The option ‘--ignorekernelchk’ is used to skip the kernel version checking when injecting drivers from osimage.driverupdatesrc. To use this flag, you should make sure the drivers in the driver rpms are usable for the target kernel. ..
Notes

- If the drivers from the driver disk or driver rpm are not already part of the installed or booted system, it's necessary to add the rpm packages for the drivers to the .pkglist or .otherpkglist of the osimage object to install them in the system.
- If a driver rpm needs to be loaded, the osimage object must be used for the 'nodeset' and 'genimage' command, instead of the older style profile approach.
- Both a Driver disk and a Driver rpm can be loaded in one 'nodeset' or 'genimage' invocation.

Configure Disk Partition

By default, xCAT will install the operating system on the first disk and with default partitions layout in the node. However, you may choose to customize the disk partitioning during the install process and define a specific disk layout. You can do this in one of two ways: 'partition definition file' or 'partition definition script'.

Note: partition definition file can be used for RedHat, SLES, and Ubuntu. Because disk configuration for Ubuntu is different from RedHat, there may be some special sections required for Ubuntu.

Warning: partition definition script has only been tested on RedHat and Ubuntu, use at your own risk for SLES.

Partition Definition File

You could create a customized osimage partition file, say /install/custom/my-partitions, that contains the disk partitioning definition, then associate the partition file with osimage, the nodeset command will insert the contents of this file directly into the generated autoinst configuration file that will be used by the OS installer.

Create Partition File

The partition file must follow the partitioning syntax of the installer(e.g. kickstart for RedHat, AutoYaST for SLES, Preseed for Ubuntu), you could refer to the Kickstart documentation or Autoyast documentation or Preseed documentation write your own partitions layout. Meanwhile, RedHat and SuSE provides some tools that could help generate kickstart/autoyast templates, in which you could refer to the partition section for the partitions layout information:

- [RedHat]
  - The file /root/anaconda-ks.cfg is a sample kickstart file created by RedHat installer during the installation process based on the options that you selected.
  - system-config-kickstart is a tool with graphical interface for creating kickstart files
- [SLES]
  - Use yast2 autoyast in GUI or CLI mode to customize the installation options and create autoyast file
  - Use yast2 clone_system to create autoyast configuration file /root/autoinst.xml to clone an existing system
- [Ubuntu]
  - For detailed information see the files partman-auto-recipe.txt and partman-auto-raid-recipe.txt included in the debian-installer package. Both files are also available from the debian-installer source repository. Note that the supported functionality may change between releases.
Here is partition definition file example for Ubuntu standard partition in ppc64le machines

```
ubuntu-boot ::
8 1 1 prep
  $primary( ) $bootable( ) method( prep )
  .
500 10000 1000000000 ext4
  method( format ) format( ) use_filesystem( ) filesystem( ext4 ) mountpoint( / )
  .
2048 512 300% linux-swap
  method( swap ) format( )
  .
```

**Associate Partition File with Osimage**

Run the following commands to associate the partition with the osimage:

```
chdef -t osimage <osimagename> partitionfile=/install/custom/my-partitions
nodeset <nodename> osimage=<osimage>
```

- For RedHat, when nodeset runs and generates the /install/autoinst file for a node, it will replace the 
  #XCAT_PARTITION_START#...#XCAT_PARTITION_END# directives from your osimage template with the contents of your custom partition file.
- For Ubuntu, when nodeset runs and generates the /install/autoinst file for a node, it will generate a script to write the partition configuration to /tmp/partitionfile, this script will replace the 
  #XCA_PARTMAN_RECIPE_SCRIPT# directive in /install/autoinst/<node>.pre.

**Partitioning disk file(For Ubuntu only)**

The disk file contains the name of the disks to partition in traditional, non-devfs format and delimited with space " ", for example :

```
/dev/sda /dev/sdb
```

If not specified, the default value will be used.

**Associate partition disk file with osimage**

```
chdef -t osimage <osimagename> -p partitionfile='d:/install/custom/partitiondisk'
nodeset <nodename> osimage=<osimage>
```

- the ‘d:’ preceding the filename tells nodeset that this is a partition disk file.
- For Ubuntu, when nodeset runs and generates the /install/autoinst file for a node, it will generate a script to write the content of the partition disk file to /tmp/install_disk, this context to run the script will replace the 
  #XCA_PARTMAN_DISK_SCRIPT# directive in /install/autoinst/<node>.pre.

**Additional preseed configuration file(For Ubuntu only)**

To support other specific partition methods such as RAID or LVM in Ubuntu, some additional preseed configuration entries should be specified.
If using file way, 'c:<the absolute path of the additional preseed config file>', the additional preseed config file contains the additional preseed entries in “d-i ...” syntax. When “nodeset”, the #XCA_PARTMAN_ADDITIONAL_CFG# directive in /install/autoinst/<node> will be replaced with content of the config file. For example:

```
d-i partman-auto/method string raid
d-i partman-md/confirm boolean true
```

If not specified, the default value will be used. ..

**Partition Definition Script**

Create a shell script that will be run on the node during the install process to dynamically create the disk partitioning definition. This script will be run during the OS installer %pre script on RedHat or preseed/early_command on Unbuntu execution and must write the correct partitioning definition into the file /tmp/partitionfile on the node

**Create Partition Script**

The purpose of the partition script is to create the /tmp/partitionfile that will be inserted into the kickstart/autoyast/preseed template, the script could include complex logic like select which disk to install and even configure RAID, etc

**Note:** the partition script feature is not thoroughly tested on SLES, there might be problems, use this feature on SLES at your own risk.

Here is an example of the partition script on RedHat and SLES, the partitioning script is /install/custom/my-partitions.sh:

```bash
instdisk="/dev/sda"

modprobe ext4 >/dev/null
modprobe ext4dev >/dev/null
if grep ext4dev /proc/filesystems > /dev/null; then
    FSTYPE=ext3
elif grep ext4 /proc/filesystems > /dev/null; then
    FSTYPE=ext4
else
    FSTYPE=ext3
fi

BOOTFSTYPE=ext3
EFIFSTYPE=vfat
if uname -r | grep ^3.*el7 > /dev/null; then
    FSTYPE=xfs
    BOOTFSTYPE=xfs
    EFIFSTYPE=efi
fi

if [ `uname -m` = "ppc64" ]; then
    echo 'part None --fstype "PPC PReP Boot" --ondisk "$instdisk" --size 8' >> /tmp/
    ->partitionfile
fi
if [ -d /sys/firmware/efi ]; then
    echo 'bootloader --driveorder="$instdisk" >> /tmp/partitionfile
    echo 'part /boot/efi --size 50 --ondisk "$instdisk" --fstype $EFIFSTYPE' >> /tmp/
    ->partitionfile
else
```
echo 'bootloader' >> /tmp/partitionfile
fi

echo "part /boot --size 512 --fstype $BOOTFSTYPE --ondisk $instdisk" >> /tmp/
˓ partitionfile

echo "part swap --recommended --ondisk $instdisk" >> /tmp/partitionfile

echo "part / --size 1 --grow --ondisk $instdisk --fstype $FSTYPE" >> /tmp/
˓ partitionfile

The following is an example of the partition script on Ubuntu, the partitioning script is /install/custom/my-partitions.sh:

```bash
if [ -d /sys/firmware/efi ]; then
    echo "ubuntu-efi ::" > /tmp/partitionfile
    echo " 512 512 1024 fat16" >> /tmp/partitionfile
    echo ' $iflabel{ gpt } $reusemethod{ } method{ efi } format{ }' >> /tmp/
    echo "." >> /tmp/partitionfile
else
    echo "ubuntu-boot ::" > /tmp/partitionfile
    echo "100 50 100 ext3" >> /tmp/partitionfile
    echo ' $primary{ } $bootable{ } method{ format } format{ } use_filesystem{
    \rightarrow filesystem{ ext3 } mountpoint{ /boot }' >> /tmp/partitionfile
    echo "." >> /tmp/partitionfile
fi

echo "500 10000 1000000000 ext3" >> /tmp/partitionfile

echo " method{ format } format{ } use_filesystem{ } filesystem{ ext3 } mountpoint{ / }" >> /tmp/partitionfile

echo "." >> /tmp/partitionfile

echo "2048 512 300% linux-swap" >> /tmp/partitionfile

echo " method{ swap } format{ }" >> /tmp/partitionfile

echo "." >> /tmp/partitionfile
```

**Associate partition script with osimage**

Run below commands to associate partition script with osimage:

```
chdef -t osimage <osimagename> partitionfile='s:/install/custom/my-partitions.sh'
nodeset <nodename> osimage=<osimage>
```

- The "s:" preceding the filename tells nodeset that this is a script.
- For RedHat, when nodeset runs and generates the /install/autoinst file for a node, it will add the execution of the contents of this script to the $pre section of that file. The nodeset command will then replace the #XCAT_PARTITION_START#...#XCAT_PAR...
- PARTITION_END# directives from the osimage template file with "#include /tmp/
- partitionfile" to dynamically include the tmp definition file your script created.
- For Ubuntu, when nodeset runs and generates the /install/autoinst file for a node, it will replace the "#$XCA_PARTMAN_RECIPE_SCRIPT#" directive and add the execution...of the contents of this script to the /install/autoinst/<node>.pre, the /install/
- autoinst/<node>.pre script will be run in the preseed/early_command.

**Partitioning disk script(For Ubuntu only)**

The disk script contains a script to generate a partitioning disk file named “/tmp/install_disk”. for example:
rm /tmp/devs-with-boot 2>/dev/null || true;
for d in $(list-devices partition); do
  mkdir -p /tmp/mymount;
  rc=0;
  mount $d /tmp/mymount || rc=$?
  if [[ $rc -eq 0 ]]; then
    [[ -d /tmp/mymount/boot ]] && echo $d >>/tmp/devs-with-boot;
    umount /tmp/mymount;
  fi
done;
if [[ -e /tmp/devs-with-boot ]]; then
  head -n1 /tmp/devs-with-boot | egrep -o \S+[^0-9] >/tmp/install_disk;
  rm /tmp/devs-with-boot 2>/dev/null || true;
else
  DEV=`ls /dev/disk/by-path/* -l | egrep -o '/dev.*[s|h|v]d[^0-9]$' | sort -t : -k 1 -k 2 -k 3 -k 4 -k 5 -k 6 -k 7 -k 8 -g | head -n1 | egrep -o '[s|h|v]d.*$'`;
  if [[ "$DEV" == "" ]]; then DEV="sda"; fi;
  echo "/dev/$DEV" >/tmp/install_disk;
fi;

If not specified, the default value will be used.

## Associate partition disk script with osimage

```
chdef -t osimage <osimagnname> -p partitionfile='s:d:/install/custom/
  PartitionDiskScript'
```

- the ‘s:’ prefix tells nodeset that is a script, the ‘s:d:’ preceding the filename tells nodeset that this is a script to generate the partition disk file.
- For Ubuntu, when nodeset runs and generates the /install/autoinst file for a node, this context to run the script will replace the #XCA_PARTMAN_DISK_SCRIPT# directive in /install/autoinst/<node>.pre.

### Additional preseed configuration script (For Ubuntu only)

To support other specific partition methods such as RAID or LVM in Ubuntu, some additional preseed configuration entries should be specified.

If using script way, ‘s:cc:<the absolute path of the additional preseed config script>’, the additional preseed config script is a script to set the preseed values with “debconf-set”. When “nodeset”, the #XCA_PARTMAN_ADDITIONAL_CONFIG_SCRIPT# directive in /install/autoinst/<node>.pre will be replaced with the content of the script. For example:

```
debconf-set partman-auto/method string raid
debconf-set partman-md/confirm boolean true
```

If not specified, the default value will be used. ..

## Prescripts and Postscripts

### Using Prescript

The prescript table will allow you to run scripts before the install process. This can be helpful for performing advanced actions such as manipulating system services or configurations before beginning to install a node, or to prepare
application servers for the addition of new nodes. Check the man page for more information.

`man prescripts`

The scripts will be run as root on the MASTER for the node. If there is a service node for the node, then the scripts will be run on the service node.

Identify the scripts to be run for each node by adding entries to the prescripts table:

```bash
tabedit prescripts
Or:
chdef -t node -o <noderange> prescripts-begin=<beginscripts> prescripts-end=<endscripts>
Or:
chdef -t group -o <nodegroup> prescripts-begin=<beginscripts> prescripts-end=<endscripts>
tabdump prescripts
#node,begin,end,comments,disable
```

**Format for naming prescripts**

The general format for the prescripts-begin or prescripts-end attribute is:

```
[action1:]s1,s2...[|action2:s3,s4,s5...]
```

where:

- `action1` and `action2` are the nodeset actions (‘install’, ‘netboot’, etc) specified in the command.
- `s1` and `s2` are the scripts to run for `action1` in order.
- `s3`, `s4`, and `s5` are the scripts to run for `action2`.

If actions are omitted, the scripts apply to all actions.

Examples:

- `myscript1,myscript2` - run scripts for all supported commands
- `install:myscript1,myscript2|netboot:myscript3`

Run scripts 1, 2 for nodeset(install), runs script3 for nodeset(netboot).

All the scripts should be copied to /install/prescripts directory and made executable for root and world readable for mounting. If you have service nodes in your cluster with a local /install directory (i.e. /install is not mounted from the xCAT management node to the service nodes), you will need to synchronize your /install/prescripts directory to your service node anytime you create new scripts or make changes to existing scripts.

The following two environment variables will be passed to each script:

- `NODES` - a comma separated list of node names on which to run the script
- `ACTION` - current nodeset action.
By default, the script will be invoked once for all nodes. However, if `#xCAT setting:MAX_INSTANCE=number` is specified in the script, the script will be invoked for each node in parallel, but no more than number of instances specified in number will be invoked at a time.

**Exit values for prescripts**

If there is no error, a prescript should return with 0. If an error occurs, it should put the error message on the stdout and exit with 1 or any non zero values. The command (nodeset for example) that runs prescripts can be divided into 3 sections.

1. run begin prescripts
2. run other code
3. run end prescripts

If one of the prescripts returns 1, the command will finish the rest of the prescripts in that section and then exit out with value 1. For example, a node has three begin prescripts s1, s2 and s3, three end prescripts s4, s5, s6. If s2 returns 1, the prescript s3 will be executed, but other code and the end prescripts will not be executed by the command.

If one of the prescripts returns 2 or greater, then the command will exit out immediately. This only applies to the scripts that do not have `#xCAT setting:MAX_INSTANCE=number`.

**Using Postscript**

xCAT automatically runs a few postscripts and postbootscripts that are delivered with xCAT to set up the nodes. You can also add your own scripts to further customize the nodes. This explains the xCAT support to do this.

**Types of scripts**

There are two types of scripts in the postscripts table (postscripts and postbootscripts). The types are based on when in the install process they will be executed. Run the following for more information:

```
man postscripts
```

- **postscripts attribute** - List of scripts that should be run on this node after diskful installation or diskless boot.
  - [RHEL]
    Postscripts will be run before the reboot.
  - [SLES]
    Postscripts will be run after the reboot but before the init.d process. For Linux diskless deployment, the postscripts will be run at the init.d time, and xCAT will automatically add the list of postscripts from the postbootscripts attribute to run after postscripts list.

- **postbootscripts attribute** - list of postbootscripts that should be run on this Linux node at the init.d time after diskful installation reboot or diskless boot

- xCAT, by default, for diskful installs only runs the postbootscripts on the install and not on reboot. In xCAT a site table attribute runbootscripts is available to change this default behavior. If set to yes, then the postbootscripts will be run on install and on reboot.

xCAT automatically adds the postscripts from the xcatdefaults.postscripts attribute of the table to run first on the nodes after install or diskless boot.
Adding your own postscripts

To add your own script, place it in /install/postscripts on the management node. Make sure it is executable and world readable. Then add it to the postscripts table for the group of nodes you want it to be run on (or the “all” group if you want it run on all nodes in the appropriate attribute, according to when you want it to run).

To check what scripts will be run on your node during installation:

```
lsdef node1 | grep scripts
posscripts=otherpkgs
posscripts=syslog,remoteshell,syncfiles
```

You can pass parameters to the postscripts. For example:

```
script1 p1 p2,script2,....
```

p1 p2 are the parameters to script1.

Postscripts could be placed in the subdirectories in /install/postscripts on management node, and specify “sub-dir/postscriptname” in the postscripts table to run the postscripts in the subdirectories. This feature could be used to categorize the postscripts for different purposes. Here is an example:

```
mkdir -p /install/postscripts/subdir1
mkdir -p /install/postscripts/subdir2
cp postscript1 /install/postscripts/subdir1/
cp postscript2 /install/postscripts/subdir2/
chdef node1 -p postscripts=subdir1/postscript1,subdir2/postscript2
updatenode node1 -P
```

If some of your postscripts will affect the network communication between the management node and compute node, like restarting network or configuring bond, the postscripts execution might not be able to be finished successfully because of the network connection problems, even if we put this postscript be the last postscript in the list, xCAT still may not be able to update the node status to be “booted”. The recommendation is to use the Linux “at” mechanism to schedule this network-killing postscript to be run at a later time. Here is an example:

The user needs to add a postscript to customize the nics bonding setup, the nics bonding setup will break the network between the management node and compute node, then we could use “at” to run this nic bonding postscripts after all the postscripts processes have been finished.

We could write a script, say, /install/postscripts/nicbondscript, the nicbondscript simply calls the confignicsbond using “at”:

```
[root@xcatmn ~]# cat /install/postscripts/nicbondscript
#!/bin/bash
at -f ./confignicsbond now + 1 minute
[root@xcatmn ~]#
```

Then

```
chdef <nodename> -p postbootscripts=nicbondscript
```
Recommended Postscript design

- Postscripts that you want to run anywhere, Linux, should be written in shell. This should be available on all OS’s. If only on the service nodes, you can use Perl.

- Postscripts should log errors using the following command `local4` is the default xCAT syslog class. `logger -t xCAT -p local4.info “your info message”`.

- Postscripts should have good and error exit codes (i.e 0 and 1).

- Postscripts should be well documented. At the top of the script, the first few lines should describe the function and inputs and output. You should have comments throughout the script. This is especially important if using regx.

PostScript/PostbootScript execution

When your script is executed on the node, all the attributes in the site table are exported as variables for your scripts to use. You can add extra attributes for yourself. See the sample mypostscript file below.

To run the postscripts, a script is built, so the above exported variables can be input. You can usually find that script in `/xcatpost` on the node and for example in the Linux case it is called mypostscript. A good way to debug problems is to go to the node and just run mypostscript and see errors. You can also check the syslog on the Management Node for errors.

When writing you postscripts, it is good to follow the example of the current postscripts and write errors to syslog and in shell. See Suggestions for writing scripts.

All attributes in the site table are exported and available to the postscript/postbootscript during execution. See the mypostscript file, which is generated and executed on the nodes to run the postscripts.

Example of mypostscript

```bash
# subroutine used to run postscripts
run_ps () {
    logdir="/var/log/xcat"
    mkdir -p $logdir
    logfile="/var/log/xcat/xcat.log"
    if [ -f $1 ]; then
        echo "Running postscript: $1" | tee -a $logfile
        ./$1 2>&1 | tee -a $logfile
    else
        echo "Postscript $1 does NOT exist." | tee -a $logfile
    fi
}
# subroutine end
AUDITSKIPCMDS='tabdump,nodels'
echo AUDITSKIPCMDS
export AUDITSKIPCMDS
TEST='test'
echo TEST
export TEST
NAMESERVERS='7.114.8.1'
echo NAMESERVERS
export NAMESERVERS
NTPSERVERS='7.113.47.250'
echo NTPSERVERS
export NTPSERVERS
INSTALLLOC='/install'
echo INSTALLLOC
export INSTALLLOC
DEFSERIALPORT='0'
echo DEFSERIALPORT
export DEFSERIALPORT
DEFSERIALSPEED='19200'
```

(continues on next page)
export DEFSERIALSPEED
export DHCPINTERFACES="'xcat20RRmn|eth0;rra000-m|eth1'"
export FORWARDERS='7.113.8.1,7.114.8.2'
export NAMESERVER='7.113.8.1,7.114.47.250'
export DB='postg'
export BLADEMAXP='64'
export FSPTIMEOUT='0'
export INSTALLDIR="/install"
export IPMIXP='64'
export IPMIRETRIES='3'
export IPMITIMEOUT='2'
export CONSOLEONDEMAND='no'
export SITEMASTER=7.113.47.250
export MASTER=7.113.47.250
export MAXSSH='8'
export PPCMAXP='64'
export PPCRETRY='3'
export PPCTIMEOUT='0'
export SHAREDFTFP='1'
export SNSYNCFILEDIR='/var/xcat/syncfiles'
export TFTPDIR="/tftpboot"
export XCATDPORT='3001'
export XCATIPORT='3002'
export XCATCONFDIR="/etc/xcat"
export TIMEZONE='America/New_York'
export USENMAPFROMMN='no'
export USESSHONAIX='no'
export NODE=rra000-m
The mypostscript file is generated according to the mypostscript.tmpl file.

**Using the mypostscript template**

**Using the mypostscript template**

xCAT provides a way for the admin to customize the information that will be provided to the postscripts/postbootscripts when they run on the node. This is done by editing the mypostscript.tmpl file. The attributes that are provided in the shipped mypostscript.tmpl file should not be removed. They are needed by the default xCAT postscripts.

The mypostscript.tmpl is shipped in the `/opt/xcat/share/xcat/mypostscript` directory.

If the admin customizes the mypostscript.tmpl, they should copy the mypostscript.tmpl to `/install/postscripts/mypostscript.tmpl`, and then edit it. The mypostscript for each node will be named mypostscript.<nodename>. The generated mypostscript.<nodename> will be put in the `/tftpboot/mypostscripts` directory.
site table precreatemypostscripts attribute

If the site table precreatemypostscripts attribute is set to 1 or yes, it will instruct xCAT at nodeset and updatenode time to query the db once for all of the nodes passed into the command and create the mypostscript file for each node and put them in a directory in STFTPDIR (for example /tftpboot). The created mypostscript.<nodename>. file in the /tftpboot/mypostscripts directory will not be regenerated unless another nodeset or updatenode command is run to that node. This should be used when the system definition has stabilized. It saves time on the updatenode or reboot by not regenerating the mypostscript file.

If the precreatemypostscripts attribute is yes, and a database change is made or xCAT code is upgraded, then you should run a new nodeset or updatenode to regenerate the /tftpboot/mypostscript/mypostscript.<nodename>. file to pick up the latest database setting. The default for precreatemypostscripts is no/0.

When you run nodeset or updatenode, it will search the /install/postscripts/mypostscript.tmpl first. If the /install/postscripts/mypostscript.tmpl exists, it will use that template to generate the mypostscript for each node. Otherwise, it will use /opt/xcat/share/xcat/mypostscript/mypostscript.tmpl.

Content of the template for mypostscript

The attributes that are defined in the shipped mypostscript.tmpl file should not be removed. The xCAT default postscripts rely on that information to run successfully. The following will explain the entries in the mypostscript.tmpl file.

The SITE_TABLE_ALL_ATTRIBS_EXPORT line in the file directs the code to export all attributes defined in the site table. Note: the attributes are not always defined exactly as in the site table to avoid conflict with other table attributes of the same name. For example, the site table master attribute is named SITEMASTER in the generated mypostscript file.

```
#SITE_TABLE_ALL_ATTRIBS_EXPORT#
```

The following line exports ENABLESSHBETWEENNODES by running the internal xCAT routine (enablesshbetweennodes).

```
ENABLESSHBETWEENNODES=#Subroutine:xCAT::Template::enablesshbetweennodes:$NODE#
export ENABLESSHBETWEENNODES
```

`tabdump(<TABLENAME>)` is used to get all the information in the `<TABLENAME>` table

```

tabdump(networks)
```

These line export the node name based on its definition in the database.

```
NODE=$NODE
export NODE
```

These lines get a comma separated list of the groups to which the node belongs.

```
GROUP=#TABLE:nodelist:$NODE:groups#
export GROUP
```

These lines reads the nodesres table, the given attributes (nfsserver,installnic,primarynic,xcatmaster,routenames) for the node ($NODE), and exports it.

```
NFSSERVER=#TABLE:noderes:$NODE:nfsserver#
export NFSSERVER
```

(continues on next page)
INSTALLNIC=
export INSTALLNIC
PRIMARYNIC=
export PRIMARYNIC
MASTER=
export MASTER
NODEROUTENAMES=
export NODEROUTENAMES

The following entry exports multiple variables from the routes table. Not always set.

#ROUTES_VARS_EXPORT#

The following lines export nodetype table attributes.

OSVER=
export OSVER
ARCH=
export ARCH
PROFILE=
export PROFILE
PROVMETHOD=
export PROVMETHOD

The following adds the current directory to the path for the postscripts.

PATH=`dirname $0`:$PATH
export PATH

The following sets the NODESETSTATE by running the internal xCAT getnodesetstate script.

NODESETSTATE=\#Subroutine:xCAT::Postage::getnodesetstate:$NODE#
export NODESETSTATE

The following says the postscripts are not being run as a result of updatenode. (This is changed =1, when updatenode runs).

UPDATENODE=0
export UPDATENODE

The following sets the NTYPE to compute, service or MN.

NTYPE=$NTYPE
export NTYPE

The following sets the mac address.

MACADDRESS=
export MACADDRESS

If vlan is setup, then the #VLAN_VARS_EXPORT# line will provide the following exports:

VMNODE='YES'
export VMINODE
VLANID=vlan1...
export VLANID

(continues on next page)
If monitoring is setup, then the #MONITORING_VARS_EXPORT# line will provide:

MONSERVER=11.10.34.108
export MONSERVER
MONMASTER=11.10.34.108
export MONMASTER
#MONITORING_VARS_EXPORT#

The OSIMAGE_VARS_EXPORT# line will provide, for example:

OSPKGDIR=/install/<os>/<arch>
export OSPKGDIR
OSPKGS='bash,nfs-utils,openssl,dhclient,kernel,openssh-server,openssh-clients,busybox,˓
→wget,rsyslog,dash,vim-minimal,ntp,rsyslog,rpm,rsync,
ppc64-utils,iutils,dracut,dracut-network,e2fsprogs,bc,lsvpd,irqbalance,procps,yum'
export OSPKGS
#OSIMAGE_VARS_EXPORT#

THE NETWORK_FOR_DISKLESS_EXPORT# line will provide diskless networks information, if defined.

NETMASK=255.255.255.0
export NETMASK
GATEWAY=8.112.34.108
export GATEWAY
..
#NETWORK_FOR_DISKLESS_EXPORT#

Note: the #INCLUDE_POSTSCRIPTS_LIST# and the #INCLUDE_POSTBOOTSCRIPTS_LIST# sections in /tftpboot/mypostscript(mypostbootscripts) on the Management Node will contain all the postscripts and postbootscripts defined for the node. When running an updatenode command for only some of the scripts, you will see in the /xcatpost/mypostscript file on the node, the list has been redefined during the execution of updatenode to only run the requested scripts. For example, if you run updatenode <nodename> -P syslog.

The #INCLUDE_POSTSCRIPTS_LIST# flag provides a list of postscripts defined for this $NODE.

#INCLUDE_POSTSCRIPTS_LIST#

For example, you will see in the generated file the following stanzas:

# postscripts-start-here
# defaults-postscripts-start-here
syslog
remoteshell
# defaults-postscripts-end-here
# node-postscripts-start-here
syncfiles
# node-postscripts-end-here

The #INCLUDE_POSTBOOTSCRIPTS_LIST# provides a list of postbootscripts defined for this $NODE.

#INCLUDE_POSTBOOTSCRIPTS_LIST#
For example, you will see in the generated file the following stanzas:

```plaintext
# postbootscripts-start-here
# defaults-postbootscripts-start-here
otherpkgs
# defaults-postbootscripts-end-here
# node-postbootscripts-end-here
# postbootscripts-end-here
```

### Kinds of variables in the template

**Type 1:** For the simple variable, the syntax is as follows. The mypostscript.tmpl has several examples of this. `$NODE` is filled in by the code. `UPDATENODE` is changed to 1, when the postscripts are run by `updatenode`. `$NTYPE` is filled in as either compute, service or MN.

```plaintext
NODE=$NODE
export NODE
UPDATENODE=0
export UPDATENODE
NTYPE=$NTYPE
export NTYPE
```

**Type 2:** This is the syntax to get the value of one attribute from the `<tablename>` and its key is `$NODE`. It does not support tables with two keys. Some of the tables with two keys are (litefile, prodkey, deps, monsetting, mpa, networks).

```plaintext
VARNAME=#TABLE:tablename:$NODE:attribute#
```

For example, to get the new updatestatus attribute from the nodelist table:

```plaintext
UPDATESTATUS=#TABLE:nodelist:$NODE:updatestatus#
export UPDATESTATUS
```

**Type 3:** The syntax is as follows:

```plaintext
VARNAME=#Subroutine:modulename::subroutinename:$NODE#
```

or

```plaintext
VARNAME=#Subroutine:modulename::subroutinename#
```

Examples in the mypostscript.tmpl are the following:

```plaintext
NODESETSTATE=#Subroutine:xCAT::Postage::getnodesetstate:$NODE#
export NODESETSTATE
ENABLESSHBEWETWEENNODESD#Subroutine:xCAT::Template::enablesshbetweennodes:$NODE#
export ENABLESSHBEWETWEENNODES
```

Note: Type 3 is not an open interface to add extensions to the template.

**Type 4:** The syntax is `#FLAG#`. When parsing the template, the code generates all entries defined by `#FLAG#`, if they are defined in the database. For example: To export all values of all attributes from the site table. The tag is

```plaintext
#SITE_TABLE_ALL_ATTRIBS_EXPORT#
```

For the `#SITE_TABLE_ALL_ATTRIBS_EXPORT#` flag, the related subroutine will get the attributes’ values and deal with the special case. such as: the site.master should be exported as “SITEMASTER”. And if the noderes.xcatmaster exists, the noderes.xcatmaster should be exported as “MASTER”, otherwise, we also should export site.master as the “MASTER”.

110 Chapter 1. Table of Contents
Other examples are:

```
#VLAN_VARS_EXPORT# - gets all vlan related items
#MONITORING_VARS_EXPORT# - gets all monitoring configuration and setup data
#OSIMAGE_VARS_EXPORT# - gets osimage related variables, such as ospkgdir, ospkgs ...
#NETWORK_FOR_DISKLESS_EXPORT# - gets diskless network information
#INCLUDE_POSTSCRIPTS_LIST# - includes the list of all postscripts for the node
#INCLUDE_POSTBOOTSCRIPTS_LIST# - includes the list of all postbootscripts for the node
```

Note: Type4 is not an open interface to add extensions to the template.

**Type 5:** Get all the data from the specified table. The `<TABLENAME>` should not be a node table, like nodelist. This should be handles with TYPE 2 syntax to get specific attributes for the `$NODE`. `tabdump` would result in too much data for a nodetype table. Also the auditlog, eventlog should not be in tabdump for the same reason. site table should not be specified, it is already provided with the `#SITE_TABLE_ALL_ATTRIBS_EXPORT#` flag. It can be used to get the data from the two key tables (like switch).

The syntax is:

```
tabdump(<TABLENAME>)
```

**Edit mypostscript.tmpl**

**Add new attributes into mypostscript.tmpl**

When you add new attributes into the template, you should edit the `/install/postscripts/mypostscript.tmpl` which you created by copying `/opt/xcat/share/xcat/mypostscript/mypostscript.tmpl`. Make all additions before the `# postscripts-start-here` section. xCAT will first look in `/install/postscripts/mypostscript.tmpl` for a file and then if not found will use the one in `/opt/xcat/share/xcat/mypostscript/mypostscript.tmpl`.

For example:

```
UPDATESTATUS=#TABLE:nodelist:$NODE:updatestatus#
export UPDATESTATUS
...
# postscripts-start-here
#INCLUDE_POSTSCRIPTS_LIST#
## The following flag postscripts-end-here must not be deleted.
# postscripts-end-here
```

Note: If you have a hierarchical cluster, you must copy your new mypostscript.tmpl to `/install/postscripts/mypostscript.tmpl` on the service nodes, unless `/install/postscripts` directory is mounted from the MN to the service node.

**Remove attribute from mypostscript.tmpl**

If you want to remove an attribute that you have added, you should remove all the related lines or comment them out with `##`. For example, comment out the added lines.

```
##UPDATESTATUS=#TABLE:nodelist:$NODE:updatestatus#
##export UPDATESTATUS
```

**Test the new template**

There are two quick ways to test the template.

#. If the node is up:
updatenode <nodename> -P syslog

Check your generated template:

Check the generated mypostscript file on compute node /xcatpost.

#. Another way, is set the precreate option

chdef -t site -o clustersite precreatemypostscripts=1

Then run

nodeset <nodename> ....

Check your generated template

vi /tftpboot/mypostscripts/mypostscript.<nodename>

Sample /xcatpost/mypostscript

This is an example of the generated postscript for a servicenode install. It is found in /xcatpost/mypostscript on the node.

```bash
# global value to store the running status of the postbootscripts, the value is non-zero if one postbootscript failed
return_value=0
# subroutine used to run postscripts
run_ps () {
    local ret_local=0
    logdir="/var/log/xcat"
    mkdir -p $logdir
    logfile="/var/log/xcat/xcat.log"
    if [ -f $1 ]; then
        echo "`date` Running postscript: $@" | tee -a $logfile
        #./$@ 2>&1 1> /tmp/tmp4xcatlog
        #cat /tmp/tmp4xcatlog | tee -a $logfile
        ./$@ 2>&1 | tee -a $logfile
        ret_local=${PIPESTATUS[0]}
        if [ "$ret_local" -ne "0" ]; then
            return_value=$ret_local
        fi
        echo "Postscript: $@ exited with code $ret_local"
    else
        echo "`date` Postscript $1 does NOT exist." | tee -a $logfile
        return_value=-1
        fi
    return 0
}
# subroutine end
SHAREDTFTP='1'
export SHAREDTFTP
TFTPDIR="/tftpboot"
export TFTPDIR
CONSOLEONDEMAND='yes'
export CONSOLEONDEMAND
```

(continues on next page)
CAT3 Documentation, Release 2.14.5

(continued from previous page)

```bash
PPCTIMEOUT='300'
export PPCTIMEOUT
VSFTP='y'
export VSFTP
DOMAIN='cluster.com'
export DOMAIN
XCATIPORT='3002'
export XCATIPORT
DHCPINTERFACES="xcatmn2|eth1;service|eth1"
export DHCPINTERFACES
MAXSSH='10'
export MAXSSH
SITEMASTER=10.2.0.100
export SITEMASTER
TIMEZONE='America/New_York'
export TIMEZONE
INSTALLDIR='/install'
export INSTALLDIR
NTPSERVERS='xcatmn2'
export NTPSERVERS
EA_PRIMARY_HMC='c76v2hmc01'
export EA_PRIMARY_HMC
NAMESERVERS='10.2.0.100'
export NAMESERVERS
SNSYNCFILEDIR='/var/xcat/syncfiles'
export SNSYNCFILEDIR
DISJOINTDHCP='0'
export DISJOINTDHCP
FORWARDERS='8.112.8.1,8.112.8.2'
export FORWARDERS
VLANNETS='|\d+|10.10.($1+0).0|'
export VLANNETS
XCATDPORT='3001'
export XCATDPORT
USENMAPFROMMN='no'
export USENMAPFROMMN
DNSHANDLER='ddns'
export DNSHANDLER
ROUTENAMES='r1,r2'
export ROUTENAMES
INSTALLLOC='/install'
export INSTALLLOC
ENABLESSHBETWEENNODES=YES
export ENABLESSHBETWEENNODES
NETWORKS_LINES=4
export NETWORKS_LINES
NETWORKS_LINE1='netname=public_net||net=8.112.154.64||mask=255.255.255.0||mgtifname=eth0||gateway=8.112.154.126||dhcpserver=||tftpserver=8.112.8.69||nameservers=8.112.8.1,8.112.8.2,8.112.8.3||ntpservers=||logservers=||dynamicrange=||staticrange=||staticrangeincrement=||nodehostname=||ddnsdomain=||vlanid=||domain=||mtu=||disable=||comments=|
export NETWORKS_LINE2
NETWORKS_LINE3='netname=sn21_net||net=10.2.1.0||mask=255.255.255.0||mgtifname=eth1||gateway=<xcatmaster>||dhcpserver=||tftpserver=||nameservers=10.2.1.100,10.2.1.101,10.2.1.102,10.2.1.103||ntpservers=||logservers=||dynamicrange=||staticrange=||staticrangeincrement=||nodehostname=||ddnsdomain=||vlanid=||domain=||mtu=||disable=||comments=|
```
(continues on next page)
export NETWORKS_LINE3
NETWORKS_LINE4='netname=sn22_net||net=10.2.2.0||mask=255.255.255.255
-gateway=10.2.2.100||dhcpserver=10.2.2.100||tftpserver=10.2.2.100
-nameservers=10.2.2.100||ntpservers=||logservers=||dynamicrange=10.2.2.120-10.2.2.250
-staticrange=||staticrangeincrement=||nodehostname=||ddnsdomain=||vlanid=||domain=||mtu=||disable=||comments=
'
export NETWORKS_LINE4
NODE=xcatsn23
export NODE
NFSSERVER=10.2.0.100
export NFSSERVER
INSTALLNIC=eth0
export INSTALLNIC
PRIMARYNIC=eth0
export PRIMARYNIC
MASTER=10.2.0.100
export MASTER
OSVER=sles11
export OSVER
ARCH=ppc64
export ARCH
PROFILE=service-xcattest
export PROFILE
PROVMETHOD=netboot
export PROVMETHOD
PATH=`dirname $0`:$PATH
export PATH
NODESETSTATE=netboot
export NODESETSTATE
UPDATENODE=1
export UPDATENODE
NTYPE=service
export NTYPE
MACADDRESS=16:3d:05:fa:4a:02
export MACADDRESS
NODEID=EA163d05fa4a02EA
export NODEID
MONSERVER=8.112.154.69
export MONSERVER
MONMASTER=10.2.0.100
export MONMASTER
MONMASTER=10.2.0.100
export MONMASTER
MS_NODEID=0360238fe61815e6
export MS_NODEID
OSPKG='kernel-ppc64,udev,sysconfig,aaa_base,klogd,device-mapper,bash,openssl,nfs-utils,sh,syslog-ng,openssl-askpass,busybox,vim,rpm,bind,fast-utilities,bind-utils,dhcp,dhcpcd,dhcp-server,dhcp-client,dhcp-relay,bzip2,cron,wget-vsftpd,util-linux,modprobe-utils,mkinitrd,apache2,apache2-prefork,perl-Bootloader,psmisc,procps,dbus-1,hal tiempo,rsync,rsync-powerpc-utils,binutils,uuid-runtime,unixODBC,gcc,zypper,tar'
export OSPKG
export OTHERPKG
OTHERPKG_INDEX=1
export OTHERPKG_INDEX
## get the diskless networks information. There may be no information.
NETMASK=255.255.255.0
export NETMASK
GATEWAY=10.2.0.100
export GATEWAY
# NIC related attributes for the node for confignics postscript
NICIPS=""
export NICIPS
NICHOSTNAMESUFFIXES=""
export NICHOSTNAMESUFFIXES
NICTYPES=""
export NICTYPES
NICCUSTOMSCRIPTS=""
export NICCUSTOMSCRIPTS
NICNETWORKS=""
export NICNETWORKS
NICCOMMENTS=
export NICCOMMENTS
# postscripts-start-here
# defaults-postscripts-start-here
run_ps test1
run_ps syslog
run_ps remoteshell
run_ps syncfiles
run_ps confNagios
run_ps configmncnode
# defaults-postscripts-end-here
# node-postscripts-start-here
run_ps servicenode
run_ps configeth_new
# node-postscripts-end-here
run_ps setbootfromnet
# postscripts-end-here
# postbootscripts-start-here
# defaults-postbootscripts-start-here
run_ps otherpkgs
# defaults-postbootscripts-end-here
# node-postbootscripts-start-here
run_ps test
# The following line node-postbootscripts-end-here must not be deleted.
# node-postbootscripts-end-here
# postbootscripts-end-here
exit $return_value

Suggestions

For writing scripts

- Some compute node profiles exclude perl to keep the image as small as possible. If this is your case, your postscripts should obviously be written in another shell language, e.g. `bash,ksh`.
- If a postscript is specific for an os, name your postscript `mypostscript.osname`.
- Add logger statements to send errors back to the Management Node. By default, xCAT configures the syslog service on compute nodes to forward all syslog messages to the Management Node. This will help debug.
Using Hierarchical Clusters

If you are running a hierarchical cluster, one with Service Nodes. If your /install/postscripts directory is not mounted on the Service Node. You are going to need to sync or copy the postscripts that you added or changed in the /install/postscripts on the MN to the SN, before running them on the compute nodes. To do this easily, use the xdcpc command and just copy the entire /install/postscripts directory to the servicenodes (usually in /xcatpost).

```
xdcp service -R /install/postscripts/* /xcatpost
or
prsync /install/postscripts service:/xcatpost
```

If your /install/postscripts is not mounted on the Service Node, you should also:

```
xdcp service -R /install/postscripts/* /install
or
prsync /install/postscripts service:/install
```

Synchronizing Files

Overview

Synchronizing (sync) files to the nodes is a feature of xCAT used to distribute specific files from the management node to the new-deploying or deployed nodes.

This function is supported for diskful or RAMdisk-based diskless nodes. Generally, the specific files are usually the system configuration files for the nodes in the /etc/directory, like /etc/hosts, /etc/resolve.conf; it also could be the application programs configuration files for the nodes. The advantages of this function are: it can parallel sync files to the nodes or nodegroup for the installed nodes; it can automatically sync files to the newly-installing node after the installation. Additionally, this feature also supports the flexible format to define the synced files in a configuration file, called ‘synclist’.

The synclist file can be a common one for a group of nodes using the same profile or osimage, or can be the special one for a particular node. Since the location of the synclist file will be used to find the synclist file, the common synclist should be put in a given location for Linux nodes or specified by the osimage.

```
xdcp command supplies the basic Syncing File function. If the ‘-F synclist’ option is specified in the xdcpc command, it syncs files configured in the synclist to the nodes. If the ‘-i PATH’ option is specified with ‘-F synclist’, it syncs files to the root image located in the PATH directory. (Note: the ‘-i PATH’ option is only supported for Linux nodes)
```

```
xdcp supports hierarchy where service nodes are used. If a node is serviced by a service node, xdcpc will sync the files to the service node first, then sync the files from service node to the compute node. The files are place in an intermediate directory on the service node defined by the SNsyncfiledir attribute in the site table. The default is /var/xcat/syncfiles.
```

Since updatenode -F calls the xdcpc to handle the Syncing File function, the updatenode -F also supports the hierarchy.

For a new-installing nodes, the Syncing File action will be triggered when performing the postscripts for the nodes. A special postscript named ‘synfiles’ is used to initiate the Syncing File process.

```
The postscript ‘synfiles’ is located in the /install/postscripts/. When running, it sends a message to the xcatd on the management node or service node, then the xcatd figures out the corresponding synclist file for the node and calls the xdcpc command to sync files in the synclist to the node.
```

If installing nodes in a hierarchical configuration, you must sync the Service Nodes first to make sure they are updated. The compute nodes will be sync’d from their service nodes. You can use the updatenode <computenodes> -f command to sync all the service nodes for range of compute nodes provided.
For an installed nodes, the Syncing File action happens when performing the `updatenode -F` or `xdcp -F` `synclist` command to update a nodes. If performing the `updatenode -F`, it figures out the location of the synclist files for all the nodes and classify the nodes which using same synclist file and then calls the `xdcp -F` `synclist` to sync files to the nodes.

**The synclist file**

**The Format of synclist file**

The synclist file contains the configuration entries that specify where the files should be synced to. In the synclist file, each line is an entry which describes the location of the source files and the destination location of files on the target node.

The basic entry format looks like following:

```
path_of_src_file1 -> path_of_dst_file1
path_of_src_file1 -> path_of_dst_directory
path_of_src_file1 path_of_src_file2 ... -> path_of_dst_directory
```

The `path_of_src_file*` should be the full path of the source file on the Management Node.

The `path_of_dst_file*` should be the full path of the destination file on target node. Make sure `path_of_dst_file*` is not a existing directory on target node, otherwise, the file sync with `updatenode -r /usr/bin/scp` or `xdcp -r /usr/bin/scp` will fail.

The `path_of_dst_directory` should be the full path of the destination directory. Make sure `path_of_dst_directory` is not a existing file on target node, otherwise, the file sync with `updatenode -r /usr/bin/scp` or `xdcp -r /usr/bin/scp` will fail.

Since the synclist file is for common purpose, the target node need not be configured in it.

Example: the following synclist formats are supported:

sync file `/etc/file2` to the file `/etc/file2` on the node (with same file name)

```
/etc/file2 -> /etc/file2
```

sync file `/etc/file2` to the file `/etc/file3` on the node (with different file name)

```
/etc/file2 -> /etc/file3
```

sync file `/etc/file4` to the file `/etc/tmp/file5` on the node (different file name and directory). The directory will be automatically created for you.

```
/etc/file4 -> /etc/tmp/file5
```

sync the multiple files `/etc/file1`, `/etc/file2`, `/etc/file3`, ... to the directory `/tmp/etc` (/tmp/etc must be a directory when multiple files are synced at one time). If the directory does not exist, `xdcp` will create it.

```
/etc/file1 /etc/file2 /etc/file3 -> /tmp/etc
```

sync file `/etc/file2` to the file `/etc/file2` on the node

```
/etc/file2 -> /etc/
```

sync all files in `/home/mikev` to directory `/home/mikev` on the node
Note: Don’t try to sync files to the read only directory on the target node.

**An example of synclist file**

Assume a user wants to sync files to a node as following, the corresponding entries should be added in a synclist file.

Sync the file `/etc/common_hosts` to the two places on the target node: put one to the `/etc/hosts`, the other to the `/tmp/etc/hosts`. Following configuration entries should be added:

```
/etc/common_hosts -> /etc/hosts
/etc/common_hosts -> /tmp/etc/hosts
```

Sync files in the directory `/tmp/prog1` to the directory `/prog1` on the target node, and the postfix `.tmpl` needs to be removed on the target node. (directory `/tmp/prog1` contains two files: `conf1.tmpl` and `conf2.tmpl`) Following configuration entries should be added:

```
/tmp/prog1/conf1.tmpl -> /prog1/conf1
/tmp/prog1/conf2.tmpl -> /prog1/conf2
```

Sync the files in the directory `/tmp/prog2` to the directory `/prog2` with same name on the target node. (directory `/tmp/prog2` contains two files: `conf1` and `conf2`) Following configuration entries should be added:

```
/tmp/prog2/conf1 /tmp/prog2/conf2 -> /prog2
```

Sample synclist file

```
/etc/common_hosts -> /etc/hosts
/etc/common_hosts -> /tmp/etc/hosts
/tmp/prog1/conf1.tmpl -> /prog1/conf1
/tmp/prog1/conf2.tmpl -> /prog1/conf2
/tmp/prog2/conf1 /tmp/prog2/conf2 -> /prog2
/tmp/ -> /tmp/
/etc/testfile -> /etc/
```

If the above synclist is performed by the `updatenode/xdeep` commands, or performed in a node installation process, the following files will exist on the target node with the following contents.

```
/etc/hosts (It has the same content with `/etc/common_hosts` on the MN)
/tmp/etc/hosts (It has the same content with `/etc/common_hosts` on the MN)
/prog1/conf1 (It has the same content with `/tmp/prog1/conf1.tmpl` on the MN)
/prog1/conf2 (It has the same content with `/tmp/prog1/conf2.tmpl` on the MN)
/prog2/conf1 (It has the same content with `/tmp/prog2/conf1` on the MN)
/prog2/conf2 (It has the same content with `/tmp/prog2/conf2` on the MN)
```

**Support nodes in synclist file**

Note: From xCAT 2.9.2 on AIX and from xCAT 2.12 on Linux, xCAT support a new format for synclist. The new format is

```
file -> (noderange for permitted nodes) file
```

The noderange would have several format. Following examples show that `/etc/hosts` file is synced to the nodes which is specified before the file name.
/etc/hosts -> (node1,node2) /etc/hosts # The /etc/hosts file is synced to node1 and node2
/etc/hosts -> (node1-node4) /etc/hosts # The /etc/hosts file is synced to node1,node2,node3 and node4
/etc/hosts -> (node[1-4]) /etc/hosts # The /etc/hosts file is synced to node1, node2, node3 and node4
/etc/hosts -> (node1,node[2-3],node4) /etc/hosts # The /etc/hosts file is synced to node1, node2, node3 and node4
//etc/hosts -> (group1) /etc/hosts # The /etc/hosts file is synced to nodes in group1
/etc/hosts -> (group1,group2) /etc/hosts # The /etc/hosts file is synced to nodes in group1 and group2

postscript support

Putting the filename.post in the rsync file to rsync to the node is required for hierarchical clusters. It is optional for non-hierarchical clusters.

Advanced synclist file features

After you define the files to rsync in the syncfile, you can add an EXECUTEALWAYS clause in the synclist file. The EXECUTEALWAYS clause will list all the postscripts you would always like to run after the files are sync’d, whether or not any file is actually updated. The files in this list must be added to the list of files to rsync, if hierarchical.

For example, your rsync file may look like this. .. note:: the path to the file to EXECUTE, is the location of the .post file on the MN*.

/tmp/share/file2 -> /tmp/file2
/tmp/share/file2.post -> /tmp/file2.post (required for hierarchical clusters)
/tmp/share/file3 -> /tmp/file3
/tmp/share/file3.post -> /tmp/file3.post (required for hierarchical clusters)
/tmp/myscript1 -> /tmp/myscript1
/tmp/myscript2 -> /tmp/myscript2
# the below are postscripts
EXECUTE:
/tmp/share/file2.post
/tmp/share/file3.post
EXECUTEALWAYS:
/tmp/myscript1
/tmp/myscript2

If /tmp/file2 is updated on the node in /tmp/file2, then /tmp/file2.post is automatically run on that node. If /tmp/file3 is updated on the node in /tmp/file3, then /tmp/file3.post is automatically run on that node.

You can add an APPEND clause to your synclist file.

The APPEND clause is used to append the contents of the input file to an existing file on the node. The file to be appended must already exist on the node and not be part of the synclist that contains the APPEND clause.

For example, your synclist file may look like this:

/tmp/share/file2 -> /tmp/file2
/tmp/share/file2.post -> /tmp/file2.post
/tmp/share/file3 -> /tmp/file3
/tmp/share/file3.post -> /tmp/file3.post

(continues on next page)
When you use the **APPEND** clause, the file (left) of the arrow is appended to the file right of the arrow. In this example, `/etc/myappenddir/appendfile` is appended to `/etc/mysetup/setup` file, which must already exist on the node. The `/opt/xcat/share/xcat/scripts/xdcpappend.sh` is used to accomplish this.

The script creates a backup of the original file on the node in the directory defined by the site table nodesyncfiledir attribute, which is `/var/xcat/node/syncfiles` by default. To update the original file when using the function, you need to rsync a new original file to the node, removed the old original from the `/var/xcat/node/syncfiles/org` directory. If you want to cleanup all the files for the append function on the node, you can use the `xdsh -c` flag. See man page for `xdsh`.

**Note:** no order of execution may be assumed by the order that the **EXECUTE,** **EXECUTEALWAYS** and **APPEND** clause fall in the synclist file.

You can add an **MERGE** clause to your synclist. This is only supported on Linux.

The **MERGE** clause is used to append the contents of the input file to either the `/etc/passwd`, `/etc/shadow` or `/etc/group` files. They are the only supported files. You must not put the `/etc/passwd`, `/etc/shadow` or `/etc/group` files in an **APPEND** clause if using a **MERGE** clause. For these three file you should use an **MERGE** clause. The **APPEND** will add the information to the end of the file. The **MERGE** will add or replace the information and insure that there are no duplicate entries in these files.

For example, your synclist file may look like this

```
/tmp/share/file2  ->  /tmp/file2
/tmp/share/file2.post  ->  /tmp/file2.post
/tmp/share/file3  ->  /tmp/file3
/tmp/share/file3.post  ->  /tmp/file3.post
/tmp/myscript  ->  /tmp/myscript
# the below are postscripts
EXECUTE:
/tmp/share/file2.post
/tmp/share/file3.post
EXECUTEALWAYS:
/tmp/myscript
MERGE:
/etc/mydir/mergepasswd  ->  /etc/passwd
/etc/mydir/mergeshadow  ->  /etc/shadow
/etc/mydir/mergegroup  ->  /etc/group
```

When you use the **MERGE** clause, the file (left) of the arrow is merged into the file right of the arrow. It will replace any common userid’s found in those files and add new userid’s. The `/opt/xcat/share/xcat/scripts/xdcpmerge.sh` is used to accomplish this.

**Note:** no order of execution may be assumed by the order that the **EXECUTE,** **EXECUTEALWAYS,** **APPEND** and
**The location of synclist file for updatenode and install process**

In the installation process or updatenode process, xCAT needs to figure out the location of the synclist file automatically, so the synclist should be put into the specified place with the proper name.

If the provisioning method for the node is an osimage name, then the path to the synclist will be read from the osimage definition synclists attribute. You can display this information by running the following command, supplying your osimage name.

```
lsdef -t osimage -l <os>-<arch>-netboot-compute
```

Object name: `<os>-<arch>-netboot-compute`

```
exlist=/opt/xcat/share/xcat/netboot/<os>/compute.exlist
imagetype=linux
osarch=<arch>
osname=Linux
osvers=<os>
otherpkgdir=/install/post/otherpkgs/<os>/<arch>
pkgdir=/install/<os>/<arch>
pkglist=/opt/xcat/share/xcat/netboot/<os>/compute.pkglist
provmethod=netboot
rootimgdir=/install/netboot/<os>/<arch>/compute
**synclists=/install/custom/netboot/compute.synclist**
```

You can set the synclist path using the following command

```
chdef -t osimage -o <os>-<arch>-netboot-compute synclists="/install/custom/netboot/compute.synclist"
```

If the provisioning method for the node is install, or netboot then the path to the synclist should be of the following format

```
/install/custom/<inst_type>/<distro>/<profile>.<os>.<arch>.synclist
```

**<inst_type>:** "install", "netboot"

**<distro>:** "rh", "centos", "fedora", "sles"

**<profile>, <os> and <arch> are what you set for the node**

For example: The location of synclist file for the diskful installation of `<os>` with ‘compute’ as the profile

```
/install/custom/<inst_type>/<distro>/<profile>.<os>.<arch>.synclist
```

The location of synclist file for the diskless netboot of `<os>` with ‘<profile>’ as the profile

```
/install/custom/<inst_type>/<distro>/<profile>.<os>.synclist
```

**Run xdcpc command to perform Syncing File action**

`xdcp` command supplies three options ‘-F’, -s, and ‘-i’ to support the Syncing File function.

- `-F`-File rsync input file

Specifies the full path to the synclist file that will be used to build the `rsync` command
• -s

Specifies to rsync to the service nodes only for the input compute noderange.

• -il-rootimg install image for Linux

Specifies the full path to the install image on the local node. By default, if the -F option is specified, the ‘rsync’ command is used to perform the syncing file function. For the rsync in xdcps, only the *ssh remote shell is supported for rsync. xdcps uses the ‘-Lpotz’ as the default flags to call the rsync command. More flags for rsync command can be specified by adding ‘-o’ flag to the call to xdcps.

For example:

Using xdcps ‘-F’ option to sync files which are listed in the /install/custom/
→commonsynfiles/<profile>.synclist directory to the node group named 'compute'. If
→the node group compute is serviced by servincnodes, then the files will be
→automatically staged to the correct service nodes, and then synced to the compute
→nodes from those service nodes. The files will be stored in /var/xcat/syncfiles
→directory on the service nodes by default, or in the directory indicated in the
→site.SNsyncfiledir attribute. See -s option below.

xdcp compute -F /install/custom/commonsynfiles/<profile>.synclist

For Linux nodes, using xdcps ‘-i’ option with ‘-F’ to sync files created in the /in-
→stall/<inst_type>/<os><profile>.synclist to the osimage in the directory /in-
→stall/<inst_type>/<os>/<arch>/<profile>/rootimg:

xdcp -i /install/<inst_type>/<os>/<arch>/<profile>/rootimg -F /install/custom/<inst_-
→type>/<os>/<profile>.synclist

Using the xdcps ‘-s’ option to sync the files only to the service nodes for the node group named ‘compute’. The files will be placed in the default /var/xcat/syncfiles directory or in the directory as indicated in the site.SNsyncfiledir attribute. If you want the files synced to the same directory on the service node that they come from on the Management Node, set site.SNsyncfiledir=/. This can be setup before a node install, to have the files available to be synced during the install:

xdcp compute -s -F /install/custom/<inst_type>/<os>/<profile>.synclist

Synchronizing Files during the installation process

The policy table must have the entry to allow syncfiles postscript to access the Management Node. Make sure this entry is in your table:

```
tabdump policy

#priority, name, host, commands, noderange, parameters, time, rule, comments, disable
.
.
"4.6","syncfiles","allow",".
.
```

Hierarchy and Service Nodes

If using Service nodes to manage you nodes, you should make sure that the service nodes have been synchronized with the latest files from the Management Node before installing. If you have a group of compute nodes (compute) that are
going to be installed that are serviced by SN1, then run the following before the install to sync the current files to SN1.

Note: the noderange is the compute node names, updatenode will figure out which service nodes need updating.

```
updatenode compute -f
```

**Diskful installation**

The ‘syncfiles’ postscript is in the defaults section of the postscripts table. To enable the syn files postscript to sync files to the nodes during install the user need to do the following:

- Create the synclist file with the entries indicating which files should be synced. (refer to *The Format of synclist file*)
- Put the synclist into the proper location for the node type (refer to *The location of synclist file for updatenode and install process*)

Make sure your postscripts table has the syncfiles postscript listed

```
tabdump postscripts

#node,postscripts,postbootscripts,comments,disable
"xcatdefaults","syslog,remoteshell,syncfiles","otherpkgs",,
```

**Diskless Installation**

The diskless boot is similar with the diskful installation for the synchronizing files operation, except that the packimage commands will sync files to the root directories of image during the creating image process.

Creating the synclist file as the steps in Diskful installation section, then the synced files will be synced to the os image during the packimage and mkdsklsnode commands running.

Also the files will always be re-synced during the booting up of the diskless node.

**Run the Sync’ing File action in the creating diskless image process**

Different approaches are used to create the diskless image. The **Sync’ing** File action is also different.

The `packimage` command is used to prepare the root image files and package the root image. The Syncing File action is performed here.

Steps to make the **Sync’ing** File working in the packimage command:

1. Prepare the synclist file and put it into the appropriate location as describe above in (refer *The location of synclist file for updatenode and install process*)
2. Run packimage as is normally done.

**Run the Syncing File action in the updatenode process**

If run `updatenode` command with `-F` option, it syncs files which configured in the synclist to the nodes. `updatenode` does not sync images, use `xdcp -i -F` option to sync images.

`updatenode` can be used to sync files to to diskful or diskless nodes. `updatenode` cannot be used to sync files to satelite nodes.

Steps to make the Syncing File working in the `updatenode -F` command:
1. Create the synclist file with the entries indicating which files should be synced. (refer to The Format of synclist file)

2. Put the synclist into the proper location (refer to The location of synclist file for updatenode and install process).

3. Run the updatenode node -F command to initiate the Syncing File action.

Note: Since Syncing File action can be initiated by the updatenode -F flag, the updatenode -P does NOT support to re-run the ‘syncfiles’ postscript, even if you specify the ‘syncfiles’ postscript in the updatenode command line or set the ‘syncfiles’ in the postscripts.postscripts attribute.

Run the Syncing File action periodically

If the admins want to run the Syncing File action automatically or periodically, the xdcp -F, xdcp -i -F and updatenode -F commands can be used in the script, crontab or FAM directly.

For example:

Use the cron daemon to sync files in the /install/custom/<inst_type>/<distro>/<profile>.<os>.synclist to the node-group ‘compute’ every 10 minutes by the xdcp command by adding this to crontab:

```
*/10 * * * * root /opt/xcat/bin/xdcp compute -F /install/custom/<inst_type>/<distro>/‐<profile>.<distro>.synclist
```

Use the cron daemon to sync files for the nodegroup ‘compute’ every 10 minutes by updatenode command.

```
*/10 * * * * root /opt/xcat/bin/updatenode compute -F
```

** Related To do** Add reference

Add Additional Software Packages

Overview

The name of the packages that will be installed on the node are stored in the packages list files. There are two kinds of package list files:

- The package list file contains the names of the packages that comes from the os distro. They are stored in .pkglist file.
- The other package list file contains the names of the packages that do NOT come from the os distro. They are stored in .otherpkgs.pkglist file.

The path to the package lists will be read from the osimage definition. Which osimage a node is using is specified by the provmethod attribute. To display this value for a node:

```
lsdef node1 -i provmethod
Object name: node
provmethod=<osimagename>
```

You can display this details of this osimage by running the following command, supplying your osimage name:

```
lsdef -t osimage <osimagename>
Object name: <osimagename>
exlist=/opt/xcat/share/xcat/<inst_type>/<os>/<profile>.exlist
imagetype=linux
```

(continues on next page)
You can set the pkglist and otherpkglist using the following command:

```bash
chdef -t osimage <osimagename> pkglist=/opt/xcat/share/xcat/<inst_type>/<distro>/*<profile>*.pkglist
otherpkglist=/install/custom/<inst_type>/my.otherpkgs.pkglist
```

**Install Additional OS Packages for RHEL and SLES**

**Install Additional Packages using OS Packages steps**

For rpms from the OS distro, add the new rpm names (without the version number) in the .pkglist file. For example, file `/install/custom/<inst_type>/<os>/<profile>.pkglist` will look like this after adding perl-DBI:

```bash
bash
nfs-utils
openssl
dhcpcd
kernel-smp
openssh
procps
pysmisc
resmgr
wget
rsync
timezone
perl-DBI
```

For the format of the .pkglist file, see [File Format for .ospkgs.pkglist File](#)

If you have newer updates to some of your operating system packages that you would like to apply to your OS image, you can place them in another directory, and add that directory to your osimage pkgdir attribute. For example, with the osimage defined above, if you have a new openssl package that you need to update for security fixes, you could place it in a directory, create repository data, and add that directory to your pkgdir:

```bash
mkdir -p /install/osupdate/<os>/<arch>
cd /install/osupdate/<os>/<arch>
cp <your new openssl rpm> .
createrepo .
chdef -t osimage <os>-<arch>-<inst_type>-<profile> pkgdir=/install/<os>/<arch>,/
"install/osupdates/<os>/<arch>"
```
Note: If the objective node is not installed by xCAT, make sure the correct osimage pkgdir attribute so that you could get the correct repository data.

**File Format for .ospkgs.ppkglist File**

The .pklist file is used to specify the rpm and the group/pattern names from os distro that will be installed on the nodes. It can contain the following types of entries:

- rpm name without version numbers
- group/pattern name marked with a '@' (for full install only)
- rpms to removed after the installation marked with a '-' (for full install only)

These are described in more details in the following sections.

**RPM Names**

A simple .pklist file just contains the name of the rpm file without the version numbers.

For example

```
openssl
xntp
rsync
glibc-devel.i686
```

**Include pkglist Files**

The `#INCLUDE` statement is supported in the pkglist file.

You can group some rpms in a file and include that file in the pkglist file using `#INCLUDE:<file>` format.

```
openssl
xntp
rsync
glibc-devel.i686
#INCLUDE:/install/post/custom/<distro>/myotherlist#
```

where `/install/post/custom/<distro>/myotherlist` is another package list file that follows the same format.

Note: the trailing “#” character at the end of the line. It is important to specify this character for correct pkglist parsing.

**Group/Pattern Names**

It is only supported for stateful deployment.

In Linux, a groups of rpms can be packaged together into one package. It is called a group on RedHat, CentOS, Fedora and Scientific Linux. To get the a list of available groups, run

- [RHEL]
  ```bash
yum grouplist
  ```
- [SLES]
You can specify in this file the group/pattern names by adding a ‘@’ and a space before the group/pattern names. For example:

@ base

**Remove RPMs After Installing**

It is only supported for stateful deployment.

You can specify in this file that certain rpms to be removed after installing the new software. This is done by adding ‘-’ before the rpm names you want to remove. For example:

- ntp

**Install Additional Other Packages for RHEL and SLES**

**Install Additional Other Packages Steps**

If you have additional rpms (rpms not in the distro) that you also want installed, make a directory to hold them, create a list of the rpms you want installed, and add that information to the osimage definition:

- Create a directory to hold the additional rpms:

  ```bash
  mkdir -p /install/post/otherpkgs/<distro>/<arch>
  cd /install/post/otherpkgs/<distro>/<arch>
  cp /myrpms/* .
  createrepo .
  ```

- Create a file that lists the additional rpms that should be installed. For example, in `/install/custom/<inst_type>/<distro>/<profile>.otherpkgs.pkglist` put:

  myrpm1
  myrpm2
  myrpm3

- Add both the directory and the file to the osimage definition:

  ```bash
  chdef -t osimage mycomputeimage otherpkgdir=/install/post/otherpkgs/<os>/<arch>...
  → otherpkglist=/install/custom/<inst_type>/<os>/<profile>.otherpkgs.pkglist
  ```

If you add more rpms at a later time, you must run createrepo again. The createrepo command is in the createrepo rpm, which for RHEL is in the 1st DVD, but for SLES is in the SDK DVD.

If you have multiple sets of rpms that you want to keep separate to keep them organized, you can put them in separate sub-directories in the otherpkgdir. If you do this, you need to do the following extra things, in addition to the steps above:

- Run createrepo in each sub-directory

- In your otherpkgs.pkglist, list at least 1 file from each sub-directory. (During installation, xCAT will define a yum or zypper repository for each directory you reference in your otherpkgs.pkglist.) For example:
There are some examples of otherpkgs.pkglist in /opt/xcat/share/xcat/<inst_type>/<distro>/<profile>.*.otherpkgs.pkglist that show the format.

Note: the otherpkgs postbootstrap script should by default be associated with every node. Use Isdef to check:

```
isdef node1 -i postbootscripts
```

If it is not, you need to add it. For example, add it for all of the nodes in the “compute” group:

```
chdef -p -t group compute postbootscripts=otherpkgs
```

For the format of the .Otherpkgs file, see *File Format for .otherpkgs.pkglist File*

**File Format for .otherpkgs.pkglist File**

The otherpkgs.pkglist file can contain the following types of entries:

- rpm name without version numbers
- otherpkgs subdirectory plus rpm name
- blank lines
- comment lines starting with #
- #INCLUDE: <full file path> to include other pkglist files
- #NEW_INSTALLLIST# to signify that the following rpms will be installed with a new rpm install command (zypper, yum, or rpm as determined by the function using this file)
- #ENV:<variable list> to specify environment variable(s) for a separate rpm install command
- rpms to remove before installing marked with a "-"
- rpms to remove after installing marked with a "--"

These are described in more details in the following sections.

**RPM Names**

A simple otherpkgs.pkglist file just contains the name of the rpm file without the version numbers.

For example, if you put the following three rpms under /install/post/otherpkgs/<os>/<arch>/ directory,

```
rsct.core-2.5.3.1-09120.ppc.rpm
rsct.core.utils-2.5.3.1-09118.ppc.rpm
src-1.3.0.4-09118.ppc.rpm
```

The otherpkgs.pkglist file will be like this:

```
src
rsct.core
rsct.core.utils
```
RPM Names with otherpkgs Subdirectories

If you create a subdirectory under `/install/post/otherpkgs/<os>/<arch>/`, say rsct, the otherpkgs.pkglist file will be like this:

```
rsc/src
rsct/rsct.core
rsct/rsct.core.utils
```

Include Other pkglist Files

You can group some rpms in a file and include that file in the otherpkgs.pkglist file using `#INCLUDE:<file>#$` format.

```
rsc/src
rsct/rsct.core
rsct/rsct.core.utils
#INCLUDE:/install/post/otherpkgs/myotherlist#
```

where `/install/post/otherpkgs/myotherlist` is another package list file that follows the same format.

Note the trailing “#” character at the end of the line. It is important to specify this character for correct pkglist parsing.

Multiple Install Lists

You can specify that separate calls should be made to the rpm install program (zypper, yum, rpm) for groups of rpms by specifying the entry `#NEW_INSTALL_LIST#$` on a line by itself as a separator in your pkglist file. All rpms listed up to this separator will be installed together. You can have as many separators as you wish in your pkglist file, and each sublist will be installed separately in the order they appear in the file.

For example:

```
compilers/vacpp.rte
compilers/vac.lib
compilers/vacpp.lib
compilers/vacpp.rte.lnk
#NEW_INSTALL_LIST#
pe/IBM_pe_license
```

Environment Variable List

You can specify environment variable(s) for each rpm install call by entry “`#ENV:<variable list>$`”. The environment variables also apply to rpm(s) remove call if there is rpm(s) needed to be removed in the sublist.

For example:

```
#ENV:INUCLIENTS=1 INUBOSTYPE=1#
rsc/rsct.core
rsct/rsct.core.utils
rsct/src
```

Be same as,
Remove RPMs Before Installing

You can also specify in this file that certain rpms to be removed before installing the new software. This is done by adding `-` before the rpm names you want to remove. For example:

```
rsrc
rsct/rsct.core
rsct/rsct.core.utils
#INCLUDE:/install/post/otherpkgs/myotherlist#
-pperl-doc
```

If you have `#NEW_INSTALL_LIST#` separators in your pkglist file, the rpms will be removed before the install of the sublist that the "-<rpmname>" appears in.

Remove RPMs After Installing

You can also specify in this file that certain rpms to be removed after installing the new software. This is done by adding `--` before the rpm names you want to remove. For example:

```
pe/IBM_pe_license
--ibm-java2-ppc64-jre
```

If you have `#NEW_INSTALL_LIST#` separators in your pkglist file, the rpms will be removed after the install of the sublist that the "--<rpmname>" appears in.

Install Additional Other Packages with Ubuntu official mirror

The Ubuntu ISO used to install the compute nodes only include packages to run a minimal base operating system, it is likely that users will want to install additional Ubuntu packages from the internet Ubuntu repositories or local repositories, this section describes how to install additional Ubuntu packages.

Compute nodes can access the internet

1. Specify the repository

Define the `otherpkgdir` attribute in osimage to use the internet repository directly:

```bash
chdef -t osimage <osimage name> otherpkgdir="http://us.archive.ubuntu.com/ubuntu/\n\n$(lsb_release -sc) main,http://us.archive.ubuntu.com/ubuntu/ $(lsb_release -sc)-\n\n-update main"
```

2. Define the otherpkglist file

   create an `otherpkglist` file: /install/custom/install/ubuntu/compute.otherpkgs.pkglst, add the package names into this file, and modify the `otherpkglist` attribute in the osimage.
3. Run `updatenode <noderange> -S` or `updatenode <noderange> -P otherpkglist`

- **Run updatenode** `-S` to **install/update** the packages on the compute nodes
- **Run updatenode** `-P otherpkglist` to **install/update** the packages on the compute nodes

### Compute nodes can not access the internet

If compute nodes cannot access the internet, there are two ways to install additional packages:

- **Use local mirror** Please refer the Ubuntu document below for how to set up your own local Ubuntu mirror. [https://help.ubuntu.com/community/Rsyncmirror](https://help.ubuntu.com/community/Rsyncmirror)
- **Use apt-proxy** Please refer the Ubuntu document below for how to setup an apt-proxy server. [https://help.ubuntu.com/community/AptProxy](https://help.ubuntu.com/community/AptProxy)
- **Setting up apt-get to use a http-proxy.** Please refer the Ubuntu document below for how to do set up it. [https://help.ubuntu.com/community/AptGet/Howto#Setting_up_apt-get_to_use_a_http-proxy](https://help.ubuntu.com/community/AptGet/Howto#Setting_up_apt-get_to_use_a_http-proxy)

### Use new kernel patch

This procedure assumes there are kernel RPM in /tmp, we take the osimage `rhels7.3-ppc64le-install-compute` as an example. The RPM names below are only examples, substitute your specific level and architecture.

- **[RHEL]**
  1. The RPM kernel package is usually named: `kernel-<kernelver>.rpm`. Append new kernel packages directory to osimage pkgdir

```bash
mkdir -p /install/kernels/<kernelver>
cp /tmp/kernel-*.rpm /install/kernels/<kernelver>
createrepo /install/kernels/<kernelver>/
chdef -t osimage rhels7.3-ppc64le-install-compute -p pkgdir=/install/kernels/<kernelver>
```

  2. Inject the drivers from the new kernel RPMs into the initrd

```bash
mkdir -t osdistroupdate kernelupdate dirpath=/install/kernels/<kernelver>/
chdef -t osimage rhels7.3-ppc64le-install-compute osupdatename=kernelupdate
chdef -t osimage rhels7.3-ppc64le-install-compute netdrivers=updateonly
genitrd rhels7.3-ppc64le-install-compute --ignorekernelchk
nodeset <CN> osimage=rhels7.3-ppc64le-install-compute --noupdateinitrd
```

  3. Boot CN from net normally.
Customize network adapter

This section describes how to configure network adapters with persistent configuration using xCAT. The confignetwork postscript can be used to configure the network interfaces on the compute nodes to support Ethernet adapters, VLAN, BONDs, and BRIDGES.

Configure Additional Network Interfaces - confignetwork

The confignetwork postscript can be used to configure the network interfaces on the compute nodes to support Ethernet adapters, VLAN, BONDs, and BRIDGES. confignetwork can be used in postscripts during OS provision, it can also be executed in updatenode. The way the confignetwork postscript decides what IP address to give the secondary adapter is by checking the nics table, in which the nic configuration information is stored. In order for the confignetwork postscript to run successfully, the following attributes must be configured for the node in the nics table:

- nicips
- nictypes
- nicnetworks

If configuring VLAN, BOND, or BRIDGES, nicdevices in nics table must be configured. VLAN, BOND or BRIDGES is only supported on RHEL.

- nicdevices - resolves the relationship among the physical network interface devices

The following scenarios are examples to configure Ethernet adapters/BOND/VLAN/Bridge.

1. Configure Ethernet adapters:
   - Scenario 1: Configure Ethernet Network Interface To configure Ethernet install NIC or other Ethernet network adapters as static

2. Configure BOND [RHEL]:
   - Scenario 2: Configure Bond using two Ethernet Adapters

3. Configure VLAN [RHEL]:
   - Scenario 3: Configure VLAN Based on Ethernet Adapter
   - Scenario 4: Configure VLAN Based on Bond Adapters

4. Configure Bridge [RHEL]:
   - Scenario 5: Configure Bridge Based On Ethernet NIC
   - Scenario 6: Configure Bridge Based on Bond Adapters
   - Scenario 7: Configure Bridge Based on VLAN
   - Scenario 8: Configure Bridge Based on VLAN,VLAN use BOND adapter

5. Advanced topics:
   - Use Customized Scripts To Configure NIC
   - Use Extra Parameters In NIC Configuration File
   - Configure Aliases
Configure Additional Network Interfaces old version - confignics - (deprecated)

The nics table and the confignics postscript can be used to automatically configure additional network interfaces (multiple ethernets adapters, InfiniBand, etc) on the nodes as they are being deployed.

The way the confignics postscript decides what IP address to give the secondary adapter is by checking the nics table, in which the nic configuration information is stored.

To use the nics table and confignics postscript to define a secondary adapter on one or more nodes, follow these steps:

Define configuration information for the Secondary Adapters in the nics table

There are 3 ways to complete this operation.

1. Using the mkdef and chdef commands

   # mkdef cni1 groups=all nicips.eth1="11.1.89.7|12.1.89.7" nicnetworks.eth1="net11|net12" nictypes.eth1="Ethernet"
   1 object definitions have been created or modified.

   # chdef cni1 nicips.eth2="13.1.89.7|14.1.89.7" nicnetworks.eth2="net13|net14" nictypes.eth2="Ethernet"
   1 object definitions have been created or modified.

2. Using an xCAT stanza file

   • Prepare a stanza file <filename>.stanza with content similar to the following:

   ```
   # <xCAT data object stanza file>
   cni1:
      objtype=node
      arch=x86_64
      groups=kvm,vm,all
      nichostnamesuffixes.eth1=-eth1-1|-eth1-2
      nichostnamesuffixes.eth2=-eth2-1|-eth2-2
      nicips.eth1=11.1.89.7|12.1.89.7
      nicips.eth2=13.1.89.7|14.1.89.7
      nicnetworks.eth1=net11|net12
      nicnetworks.eth2=net13|net14
      nictypes.eth1=Ethernet
      nictypes.eth2=Ethernet
   ```

   • Using the mkdef -z option, define the stanza file to xCAT:

   ```
   # cat <filename>.stanza | mkdef -z
   ```

3. Using tabedit to edit the nics database table directly

   The tabedit command opens the specified xCAT database table in a vi like editor and allows the user to edit any text and write the changes back to the database table.

   **WARNING:** Using the tabedit command is not the recommended method because it is tedious and error prone.

   After changing the content of the nics table, here is the result from tabdump nics
After you have defined the configuration information in any of the ways above, run the `makehosts` command to add the new configuration to the `/etc/hosts` file.

```
# makehosts cn1
# cat /etc/hosts
11.1.89.7 cn1-eth1-1 cn1-eth1-1.ppd.pok.ibm.com
12.1.89.7 cn1-eth1-2 cn1-eth1-2.ppd.pok.ibm.com
13.1.89.7 cn1-eth2-1 cn1-eth2-1.ppd.pok.ibm.com
14.1.89.7 cn1-eth2-2 cn1-eth2-2.ppd.pok.ibm.com
```

### Add confignics into the node’s postscripts list

Use command below to add confignics into the node’s postscripts list

```
chdef cn1 -p postscripts=confignics
```

By default, confignics does not configure the install nic. if need, using flag “-s” to allow the install nic to be configured.

```
chdef cn1 -p postscripts="confignics -s"
```

Option “-s” writes the install nic’s information into configuration file for persistence. All install nic’s data defined in nics table will be written also.

### Add network object into the networks table

The `nicnetworks` attribute only defines the nic that uses the IP address. Other information about the network should be defined in the `networks` table.

Use the `tabedit` command to add/modify the networks in the ‘networks’ table

```
tabdump networks
#netname,net,mask,mgtifname,gateway,dhcpserver,tftpserver,nameservers,ntpservers,
   →logservers,dynamicrange,staticrange,staticrangeincrement,nodehostname,ddnsdomain,
   →vlanid,domain,mtu,comments,disable
...
"net11", "11.1.89.0", "255.255.255.0", "eth1",,,,,,,,,,,,,,,
"net12", "12.1.89.0", "255.255.255.0", "eth1",,,,,,,,,,,,,,,
"net13", "13.1.89.0", "255.255.255.0", "eth2",,,,,,,,,,,,,,,
"net14", "14.1.89.0", "255.255.255.0", "eth2",,,,,,,,,,,,,,,
```

### Option -r to remove the undefined NICS

If the compute node’s nics were configured by confignics and the nics configuration changed in the nics table, user the `confignics -r` to remove the undefined nic.
For example, if on a compute node the eth0, eth1, and eth2 nics were configured:

```
# ifconfig
eth0 Link encap:Ethernet HWaddr 00:14:5e:d9:6c:e6
...  
eth1 Link encap:Ethernet HWaddr 00:14:5e:d9:6c:e7
...  
eth2 Link encap:Ethernet HWaddr 00:14:5e:d9:6c:e8
...  
```

Delete the eth2 definition in nics table using the chdef command. Then run the following to remove the undefined eth2 nic on the compute node:

```
updatenode <noderange> -P "confignics -r"
```

The result should have eth2 disabled:

```
# ifconfig
eth0 Link encap:Ethernet HWaddr 00:14:5e:d9:6c:e6
...  
eth1 Link encap:Ethernet HWaddr 00:14:5e:d9:6c:e7
...  
```

Deleting the installnic will result in strange problems, so confignics -r will not delete the nic set as the installnic.

### Configure routes

There are 2 ways to configure OS route in xCAT:

- **makeroutes**: command to add or delete routes on the management node or any given nodes.
- **setroute**: script to replace/add the routes to the node, it can be used in postscripts/postbootscripts.

makeroutes or setroute will modify OS temporary route, it also modifies persistent route in `/etc/sysconfig/static-routes` file.

Before using makeroutes or setroute to configure OS route, details of the routes data such as routename, subnet, net mask and gateway should be stored in `routes` table.

**Notes**: the gateway in the networks table assigns gateway from DHCP to compute node, so if use makeroutes or setroute to configure OS static route for compute node, make sure there is no gateway for the specific network in networks table.

### Configure routes table

1. Store default route data in routes table:

   ```
   chdef -t route defaultroute net=default mask=255.0.0.0 gateway=10.0.0.101
   ```

2. Store additional route data in routes table:

   ```
   chdef -t route 20net net=20.0.0.0 mask=255.0.0.0 gateway=0.0.0.0 ifname=eth1
   ```

3. Check data in routes table:
tabdump routes
#routename,net,mask,gateway,ifname,comments,disable
"30net","30.0.0.0","255.0.0.0","0.0.0.0","eth2",,
"20net","20.0.0.0","255.0.0.0","0.0.0.0","eth1",,
"defaultroute","default","255.0.0.0","10.0.0.101",,

Use **makeroutes** to configure OS route on xCAT management node

1. define the names of the routes to be setup on the management node in **site** table:

   ```bash
   chdef -t site mnroutenames="defaultroute,20net"
   lsdef -t site clustersite -i mnroutenames
   Object name: clustersite
   mnroutenames=defaultroute,20net
   ```

2. add all routes from the **mnroutenames** to the OS route table for the management node:

   ```bash
   makeroutes
   ```

3. add route **20net** and **30net** to the OS route table for the management node:

   ```bash
   makeroutes -r 20net,30net
   ```

4. delete route **20net** from the OS route table for the management node:

   ```bash
   makeroutes -d -r 20net
   ```

Use **makeroutes** to configure OS route for compute node

1. define the names of the routes to be setup on the compute node:

   ```bash
   chdef -t cn1 routenames="defaultroute,20net"
   ```

2. add all routes from the **routenames** to the OS route table for the compute node:

   ```bash
   makeroutes cn1
   ```

3. add route **20net** and **30net** to the OS route table for the compute node:

   ```bash
   makeroutes cn1 -r 20net,30net
   ```

4. delete route **20net** from the OS route table for the compute node:

   ```bash
   makeroutes cn1,cn2 -d -r 20net
   ```

Use **setroute** to configure OS route for compute node

1. define the names of the routes to be setup on the compute node:

   ```bash
   chdef -t cn1 routenames="defaultroute,20net"
   ```
2. If adding `setroute [replace | add]` into the node’s postscripts list, `setroute` will be executed during OS deployment on compute node to replace/add routes from routenames:

```
chdef cnl -p postscripts="setroute replace"
```

3. Or if the compute node is already running, use `updatenode` command to run `setroute [replace | add]` postscript:

```
updatenode cnl -P "setroute replace"
```

Check result

1. Use `route` command in xCAT management node to check OS route table.
2. Use `xdsh cnl route` to check compute node OS route table.

Initialize the Compute for Deployment

xCAT use ‘nodeset’ command to associate a specific image to a node which will be installed with this image.

```
nodeset <nodename> osimage=<osimage>
```

There are more attributes of nodeset used for some specific purpose or specific machines, for example:

- **runimage**: If you would like to run a task after deployment, you can define that task with this attribute.
- **runcmd**: This instructs the node to boot to the xCAT nbfs environment and proceed to configure BMC for basic remote access. This causes the IP, netmask, gateway, username, and password to be programmed according to the configuration table.
- **shell**: This instructs the node to boot to the xCAT genesis environment, and present a shell prompt on console. The node will also be able to be sshed into and have utilities such as wget, tftp, scp, nfs, and cifs. It will have storage drivers available for many common systems.

Choose such additional attribute of nodeset according to your requirement, if want to get more information about nodeset, refer to nodeset’s man page.

Start the OS Deployment

Start the deployment involves two key operations. First specify the boot device of the next boot to be network, then reboot the node:

For **Power servers**, those two operations can be completed by one command `rnetboot`:

```
rnetboot <node>
```

For **x86_64 servers**, those two operations need two independent commands.

1. set the next boot device to be from the “network”

```
rsetboot <node> net
```

2. Reboot the xSeries server: ::
Diskless Installation

Select or Create an osimage Definition

Before creating an image on xCAT, the distro media should be prepared ahead. That can be ISOs or DVDs.

XCAT use ‘copycds’ command to create an image which will be available to install nodes. copycds will copy all contents of Distribution DVDs/ISOs or Service Pack DVDs/ISOs to a destination directory, and create several relevant osimage definitions by default.

If using an ISO, copy it to (or NFS mount it on) the management node, and then run:

```
copycds <path>/<specific-distro>.iso
```

**Note:** while sle15 contains installer medium and packages medium, need copycds copy all contents of DVD1 of the installer medium and DVD1 of the packages medium, for example:

```
```

If using a DVD, put it in the DVD drive of the management node and run:

```
copycds /dev/<dvd-drive-name>
```

To see the list of osimages:

```
lsdef -t osimage
```

To see the attributes of a particular osimage:

```
lsdef -t osimage <osimage-name>
```

Initially, some attributes of osimage are assigned default values by xCAT - they all can work correctly because the files or templates invoked by those attributes are shipped with xCAT by default. If you need to customize those attributes, refer to the next section Customize osimage

Below is an example of osimage definitions created by copycds:

```
# lsdef -t osimage
rhels7.2-ppc64le-install-compute  (osimage)
rhels7.2-ppc64le-install-service  (osimage)
rhels7.2-ppc64le-netboot-compute  (osimage)
rhels7.2-ppc64le-stateful-mgmtnode (osimage)
```

In these osimage definitions shown above

- `<os>-<arch>-install-compute` is the default osimage definition used for diskful installation
- `<os>-<arch>-netboot-compute` is the default osimage definition used for diskless installation
- `<os>-<arch>-install-service` is the default osimage definition used for service node deployment which shall be used in hierarchical environment

**Note:** There are more things needed for ubuntu ppc64le osimages:

For pre-18.04 version of Ubuntu for ppc64el, the initrd.gz shipped with the ISO does not support network booting. In order to install ubuntu with xCAT, you need to follow the steps below to complete the osimage definition.
• Download mini.iso from
  [ubuntu 16.04]: http://xcat.org/files/netboot/ubuntu16.04/ppc64el/mini.iso
  [ubuntu 16.04.1]: http://xcat.org/files/netboot/ubuntu16.04.1/ppc64el/mini.iso

• Mount mini.iso

  mkdir /tmp/iso
  mount -o loop mini.iso /tmp/iso

• Copy the netboot initrd.gz to osimage

  mkdir -p /install/<ubuntu-version>/ppc64el/install/netboot
  cp /tmp/iso/install/initrd.gz /install/<ubuntu-version>/ppc64el/install/netboot

[Below tips maybe helpful for you]

[Tips 1]
If this is the same distro version as what your management node uses, create a .repo file in /etc/yum.repos.d with contents similar to:

```
[local-<os>-<arch>]
name=xCAT local <os> <version>
baseurl=file:/install/<os>/<arch>
enabled=1
gpgcheck=0
```

In this way, if you need to install some additional RPMs into your MN later, you can simply install them with `yum`. Or if you are installing a software on your MN that depends some RPMs from this distro, those RPMs will be found and installed automatically.

[Tips 2]
You can create/modify an osimage definition easily with any existing osimage definition, the command is

```
mkdef -t osimage -o <new osimage> --template <existing osimage> [attribute]=<value>, ...
```

Except the specified attributes `<attribute>`, the attributes of `<new osimage>` will inherit the values of template osimage `<existing osimage>`.

As an example, the following command creates a new osimage "myosimage.rh7.compute.netboot" based on the existing osimage "rhels7.4-ppc64le-netboot-compute" with some customized attributes

```
mkdef -t osimage -o myosimage.rh7.compute.netboot --template rhels7.4-ppc64le-netboot-compute synclists=/tmp/synclist otherpkgdir=/install/custom/osimage/myosimage.rh7. compute.netboot/3rdpkgs/ otherpkglist=/install/custom/osimage/myosimage.rh7.compute.netboot/3rd.pkglist
```
Customize osimage (Optional)

Optional means all the subitems in this page are not necessary to finish an OS deployment. If you are new to xCAT, you can just jump to Initialize the Compute for Deployment.

Load Additional Drivers

Overview

During the installing or netbooting of a node, the drivers in the initrd will be used to drive the devices like network cards and IO devices to perform the installation/netbooting tasks. But sometimes the drivers for the new devices were not included in the default initrd shipped by Red Hat or Suse. A solution is to inject the new drivers into the initrd to drive the new device during the installation/netbooting process.

Generally there are two approaches to inject the new drivers: Driver Update Disk and Drive RPM package.

A “Driver Update Disk” is media which contains the drivers, firmware and related configuration files for certain devices. The driver update disk is always supplied by the vendor of the device. One driver update disk can contain multiple drivers for different OS releases and different hardware architectures. Red Hat and Suse have different driver update disk formats.

The ‘Driver RPM Package‘ is the rpm package which includes the drivers and firmware for the specific devices. The Driver RPM is the rpm package which is shipped by the Vendor of the device for a new device or a new kernel version. xCAT supports both. But for ‘Driver RPM Package‘ is only supported in xCAT 2.8 and later.

No matter which approach chosen, there are two steps to make new drivers work. one is locate the new driver’s path, another is inject the new drivers into the initrd.

Locate the New Drivers

For Driver Update Disk

There are two approaches for xCAT to find the driver disk (pick one):

1. Specify the location of the driver disk in the osimage object (This is ONLY supported in 2.8 and later)

   The value for the ‘driverupdatesrc’ attribute is a comma separated driver disk list. The tag ‘dud’ must be specified before the full path of ‘driver update disk’ to specify the type of the file:

   \[ chdef -t osimage <osimagename> driverupdatesrc=dud:<full path of driver disk> \]

1. Put the driver update disk in the directory <installroot>/driverdisk/<os>/<arch> (example: /install/driverdisk/sles11.1/x86_64).

   During the running of the genimage, geninitrd, or nodeset commands, xCAT will look for driver update disks in the directory <installroot>/driverdisk/<os>/<arch>.

For Driver RPM Packages

The Driver RPM packages must be specified in the osimage object.

Three attributes of osimage object can be used to specify the Driver RPM location and Driver names. If you want to load new drivers in the initrd, the ‘netdrivers’ attribute must be set. And one or both of the ‘driverupdatesrc’ and
‘osupdatename’ attributes must be set. If both of ‘driverupdatesrc’ and ‘osupdatename’ are set, the drivers in the ‘driverupdatesrc’ have higher priority.

- netdrivers - comma separated driver names that need to be injected into the initrd. The postfix ‘.ko’ can be ignored.

The ‘netdrivers’ attribute must be set to specify the new driver list. If you want to load all the drivers from the driver rpms, use the keyword allupdate. Another keyword for the netdrivers attribute is updateonly, which means only the drivers located in the original initrd will be added to the newly built initrd from the driver rpms. This is useful to reduce the size of the new built initrd when the distro is updated, since there are many more drivers in the new kernel rpm than in the original initrd. Examples:

```
chdef -t osimage <osimagename> netdrivers=megaraid_sas.ko,igb.ko
chdef -t osimage <osimagename> netdrivers=allupdate
chdef -t osimage <osimagename> netdrivers=updateonly,igb.ko,new.ko
```

- driverupdatesrc - comma separated driver rpm packages (full path should be specified)

A tag named ‘rpm’ can be specified before the full path of the rpm to specify the file type. The tag is optional since the default format is ‘rpm’ if no tag is specified. Example:

```
chdef -t osimage <osimagename> driverupdatesrc=rpm:<full path of driver disk1>,rpm:<full path of driver disk2>
```


When geninitrd is run, kernel-*.rpm will be searched in the osdistroupdate.dirpath to get all the rpm packages and then those rpms will be searched for drivers. Example:

```
mkdef -t osdistroupdate update1 dirpath=/install/<os>/<arch>
chdef -t osimage <osimagename> osupdatename=update1
```

If ‘osupdatename’ is specified, the kernel shipped with the ‘osupdatename’ will be used to load the newly built initrd, then only the drivers matching the new kernel will be kept in the newly built initrd. If trying to use the ‘osupdatename’, the ‘allupdate’ or ‘updateonly’ should be added in the ‘netdrivers’ attribute, or all the necessary driver names for the new kernel need to be added in the ‘netdrivers’ attribute. Otherwise the new drivers for the new kernel will be missed in newly built initrd. ..

**Inject the Drivers into the initrd**

**For Driver Update Disk**

- If specifying the driver disk location in the osimage

Run the following command:

```
genimage <osimagename>
```

- If putting the driver disk in <installroot>/driverdisk/<os>/<arch>:

Running ‘genimage’ in anyway will load the driver disk..

**For Driver RPM Packages**

Run the following command:
The option ‘--ignorekernelchk’ is used to skip the kernel version checking when injecting drivers from osimage.driverupdatesrc. To use this flag, you should make sure the drivers in the driver rpms are usable for the target kernel.

Notes

- If the drivers from the driver disk or driver rpm are not already part of the installed or booted system, it’s necessary to add the rpm packages for the drivers to the .pkglist or .otherpkglist of the osimage object to install them in the system.
- If a driver rpm needs to be loaded, the osimage object must be used for the ‘nodeset’ and ‘genimage’ command, instead of the older style profile approach.
- Both a Driver disk and a Driver rpm can be loaded in one ‘nodeset’ or ‘genimage’ invocation.

Prescripts and Postscripts

Using postinstall scripts

While running genimage to generate diskless or statelite osimage, you may want to customize the root image after the package installation step. The postinstall attribute of the osimage definition provides a hook to run user specified script(s), in non-chroot mode, against the directory specified by rootimgdir attribute.

xCAT ships a default postinstall script for the diskless/statelite osimages that must be executed to ensure a successful provisioning of the OS:

```
lsdef -t osimage -o rhels7.3-ppc64le-netboot-compute -i postinstall
Object name: rhels7.3-ppc64le-netboot-compute
postinstall=/opt/xcat/share/xcat/netboot/rh/compute.rhels7.ppc64le.postinstall
```

Customizing the postinstall script, can be done by either one of the methods below:

- **Append your own postinstall scripts**

```
chdef -t osimage -o <osimage> -p postinstall=/install/custom/postinstall/rh7/‐‐>mypostscript
```

- **Create your own postinstall script based on the default postinstall script**

```
cp /opt/xcat/share/xcat/netboot/rh/compute.rhels7.ppc64le.postinstall /install/‐‐>custom/postinstall/rh7/mypostscript
# edit /install/custom/postinstall/rh7/mypostscript
chdef -t osimage -o <osimage> postinstall=/install/custom/postinstall/rh7/‐‐>mypostscript
```

Common questions about the usage of postinstall scripts:

**When do postinstall scripts run?**

High level flow of genimage process:
1. install the packages specified by pkglist into rootimgdir directory
2. customize the rootimgdir directory
3. generate the initrd based on the rootimgdir directory

The postinstall scripts are executed in step b).

**Do postinstall scripts execute in chroot mode under rootimgdir directory?**

No. Unlike postscripts and postbootscripts, the postinstall scripts are run in non-chroot environment, directly on the management node. In the postinstall scripts, all the paths of the directories and files are based on / of the management node. To reference inside the rootimgdir, use the $IMG_ROOTIMGDIR environment variable, exported by genimage.

**What are some of the environment variables available to my customized postinstall scripts?**

Environment variables, available to be used in the postinstall scripts are listed in postinstall attribute section of linuximage

**Synchronizing Files**

**Add Additional Software Packages**

**Customize network adapter**

This section describes how to configure network adapters with persistent configuration using xCAT. The confignetwork postscript can be used to configure the network interfaces on the compute nodes to support Ethernet adapters, VLAN, BONDs, and BRIDGES.

**Configure Additional Network Interfaces - confignetwork**

The confignetwork postscript can be used to configure the network interfaces on the compute nodes to support Ethernet adapters, VLAN, BONDs, and BRIDGES. confignetwork can be used in postscripts during OS provision, it can also be executed in updatenode. The way the confignetwork postscript decides what IP address to give the secondary adapter is by checking the nics table, in which the nic configuration information is stored. In order for the confignetwork postscript to run successfully, the following attributes must be configured for the node in the nics table:

- nicips
- nictypes
- nicnetworks

If configuring VLAN, BOND, or BRIDGES, nicdevices in nics table must be configured. VLAN, BOND or BRIDGES is only supported on RHEL.

- nicdevices - resolves the relationship among the physical network interface devices

The following scenarios are examples to configure Ethernet adapters/BOND/VLAN/Bridge:

1. Configure Ethernet adapters:
• Scenario 1: Configure Ethernet Network Interface To configure Ethernet install NIC or other Ethernet network adapters as static

2. Configure BOND [RHEL]:
   • Scenario 2: Configure Bond using two Ethernet Adapters

3. Configure VLAN [RHEL]:
   • Scenario 3: Configure VLAN Based on Ethernet Adapter
   • Scenario 4: Configure VLAN Based on Bond Adapters

4. Configure Bridge [RHEL]:
   • Scenario 5: Configure Bridge Based On Ethernet NIC
   • Scenario 6: Configure Bridge Based on Bond Adapters
   • Scenario 7: Configure Bridge Based on VLAN
   • Scenario 8: Configure Bridge Based on VLAN,VLAN use BOND adapter

5. Advanced topics:
   • Use Customized Scripts To Configure NIC
   • Use Extra Parameters In NIC Configuration File
   • Configure Aliases

Configure Additional Network Interfaces old version - confignics - (deprecated)

The nics table and the confignics postscript can be used to automatically configure additional network interfaces (multiple ethernets adapters, InfiniBand, etc) on the nodes as they are being deployed.

The way the confignics postscript decides what IP address to give the secondary adapter is by checking the nics table, in which the nic configuration information is stored.

To use the nics table and confignics postscript to define a secondary adapter on one or more nodes, follow these steps:

Define configuration information for the Secondary Adapters in the nics table

There are 3 ways to complete this operation.

1. Using the mkdef and chdef commands

```bash
# mkdef cn1 groups=all nicips.eth1="11.1.89.7|12.1.89.7" nicnetworks.eth1="net11|net12" nictypes.eth1="Ethernet"
1 object definitions have been created or modified.

# chdef cn1 nicips.eth2="13.1.89.7|14.1.89.7" nicnetworks.eth2="net13|net14" nictypes.eth2="Ethernet"
1 object definitions have been created or modified.
```

2. Using an xCAT stanza file
   • Prepare a stanza file `<filename>.stanza` with content similiar to the following:
# <xCAT data object stanza file>

cn1:
  objtype=node
  arch=x86_64
  groups=kvm,vm,all
  nichostnamesuffixes.eth1=-eth1-1|-eth1-2
  nichostnamesuffixes.eth2=-eth2-1|-eth2-2
  nicips.eth1=11.1.89.7|12.1.89.7
  nicips.eth2=13.1.89.7|14.1.89.7
  nicnetworks.eth1=net11|net12
  nicnetworks.eth2=net13|net14
  nictypes.eth1=Ethernet
  nictypes.eth2=Ethernet

• Using the mkdef -z option, define the stanza file to xCAT:

```
# cat <filename>.stanza | mkdef -z
```

3. Using tabedit to edit the nics database table directly

The tabedit command opens the specified xCAT database table in a vi like editor and allows the user to edit any text and write the changes back to the database table.

WARNING: Using the tabedit command is not the recommended method because it is tedious and error prone.

After changing the content of the nics table, here is the result from tabdump nics

```
# tabdump nics
node,nicips,nichostnamesuffixes,nictypes,niccustomscripts,nicnetworks,nicaliases,comments,disable
"cn1","eth1!11.1.89.7|12.1.89.7,eth2!13.1.89.7|14.1.89.7","eth1!-eth1-1|-eth1-2,eth2!-eth2-1|-eth2-2,"eth1!Ethernet,eth2!Ethernet",,"
```

After you have defined the configuration information in any of the ways above, run the makehosts command to add the new configuration to the /etc/hosts file.

```
# makehosts cn1
```

```
# cat /etc/hosts
11.1.89.7 cn1-eth1-1 cn1-eth1-1.ppd.pok.ibm.com
12.1.89.7 cn1-eth1-2 cn1-eth1-2.ppd.pok.ibm.com
13.1.89.7 cn1-eth2-1 cn1-eth2-1.ppd.pok.ibm.com
14.1.89.7 cn1-eth2-2 cn1-eth2-2.ppd.pok.ibm.com
```

Add confignics into the node’s postscripts list

Use command below to add confignics into the node’s postscripts list

```
chdef cn1 -p postscripts=confignics
```

By default, confignics does not configure the install nic. if need, using flag “-s” to allow the install nic to be configured.

```
chdef cn1 -p postscripts="confignics -s"
```
Option “-s” writes the install nic’s information into configuration file for persistence. All install nic’s data defined in nics table will be written also.

**Add network object into the networks table**

The nicnetworks attribute only defines the nic that uses the IP address. Other information about the network should be defined in the networks table.

Use the tabedit command to add/modify the networks in the ‘networks’ table.

```
$tabdump networks
inetname,network,mask,mgtifname,gateway,dhcpserver,tftpserver,nameservers,ntpservers,...
"net11", "11.1.89.0", "255.255.255.0", "eth1",,,,,,,,,,,,,,,,
"net12", "12.1.89.0", "255.255.255.0", "eth1",,,,,,,,,,,,,,,,
"net13", "13.1.89.0", "255.255.255.0", "eth2",,,,,,,,,,,,,,,,
"net14", "14.1.89.0", "255.255.255.0", "eth2",,,,,,,,,,,,,,,,
```

**Option -r to remove the undefined NICS**

If the compute node’s nics were configured by confignics and the nics configuration changed in the nics table, use the confignics -r to remove the undefined nic.

For example, if on a compute node the eth0, eth1, and eth2 nics were configured:

```
# ifconfig
eth0   Link encap:Ethernet HWaddr 00:14:5e:d9:6c:e6 ...
eth1   Link encap:Ethernet HWaddr 00:14:5e:d9:6c:e7 ...
eth2   Link encap:Ethernet HWaddr 00:14:5e:d9:6c:e8 ...
```

Delete the eth2 definition in nics table using the chdef command. Then run the following to remove the undefined eth2 nic on the compute node:

```
updatenode <noderange> -P "confignics -r"
```

The result should have eth2 disabled:

```
# ifconfig
eth0   Link encap:Ethernet HWaddr 00:14:5e:d9:6c:e6 ...
eth1   Link encap:Ethernet HWaddr 00:14:5e:d9:6c:e7 ...
```

Deleting the installnic will result in strange problems, so confignics -r will not delete the nic set as the installnic.

**Configure routes**

There are 2 ways to configure OS route in xCAT:
• **makeroutes**: command to add or delete routes on the management node or any given nodes.

• **setroute**: script to replace/add the routes to the node, it can be used in postscripts/postbootscripts.

**makeroutes** or **setroute** will modify OS temporary route, it also modifies persistent route in `/etc/sysconfig/static-routes` file.

**Before using makeroutes or setroute to configure OS route**, details of the routes data such as routename, subnet, net mask and gateway should be stored in **routes table**.

**Notes**: the **gateway** in the **networks** table assigns gateway from DHCP to compute node, so if use **makeroutes** or **setroute** to configure OS static route for compute node, make sure there is no **gateway** for the specific network in **networks** table.

**Configure routes table**

1. Store default route data in **routes** table:

   ```
   chdef -t route defaultroute net=default mask=255.0.0.0 gateway=10.0.0.101
   ```

2. Store additional route data in **routes** table:

   ```
   chdef -t route 20net net=20.0.0.0 mask=255.0.0.0 gateway=0.0.0.0 ifname=eth1
   ```

3. Check data in **routes** table:

   ```
   tabdump routes
   #routename,net,mask,gateway,ifname,comments,disable
   "30net","30.0.0.0","255.0.0.0","0.0.0.0","eth2",,,
   "20net","20.0.0.0","255.0.0.0","0.0.0.0","eth1",,,
   "defaultroute","default","255.0.0.0","10.0.0.101",,,
   ```

**Use makeroutes to configure OS route on xCAT management node**

1. define the names of the routes to be setup on the management node in **site** table:

   ```
   chdef -t site mnroutenames="defaultroute,20net"
   lsdef -t site clustersite -i mnroutenames
   Object name: clustersite
   mnroutenames=defaultroute,20net
   ```

2. add all routes from the **mnroutenames** to the OS route table for the management node:

   ```
   makeroutes
   ```

3. add route **20net** and **30net** to the OS route table for the management node:

   ```
   makeroutes -r 20net,30net
   ```

4. delete route **20net** from the OS route table for the management node:

   ```
   makeroutes -d -r 20net
   ```
Use `makeroutes` to configure OS route for compute node

1. define the names of the routes to be setup on the compute node:
   ```bash
   chdef -t cn1 routenames="defaultroute,20net"
   ```

2. add all routes from the `routenames` to the OS route table for the compute node:
   ```bash
   makeroutes cn1
   ```

3. add route `20net` and `30net` to the OS route table for the compute node:
   ```bash
   makeroutes cn1 -r 20net,30net
   ```

4. delete route `20net` from the OS route table for the compute node:
   ```bash
   makeroutes cn1,cn2 -d -r 20net
   ```

Use `setroute` to configure OS route for compute node

1. define the names of the routes to be setup on the compute node:
   ```bash
   chdef -t cn1 routenames="defaultroute,20net"
   ```

2. If adding `setroute [replace | add]` into the node's postscripts list, `setroute` will be executed during OS deployment on compute node to replace/add routes from `routenames`:
   ```bash
   chdef cn1 -p postscripts="setroute replace"
   ```

3. Or if the compute node is already running, use `updatenode` command to run `setroute [replace | add]` postscript:
   ```bash
   updatenode cn1 -P "setroute replace"
   ```

Check result

1. Use `route` command in xCAT management node to check OS route table.
2. Use `xdsh cn1 route` to check compute node OS route table.

Enable kdump Over Ethernet

Overview

kdump is a feature of the Linux kernel that allows the system to be booted from the context of another kernel. This second kernel reserves a small amount of memory and its only purpose is to capture the core dump in the event of a kernel crash. The ability to analyze the core dump helps to determine causes of system failures.
xCAT Interface

The following attributes of an osimage should be modified to enable kdump:

- pkglist
- exlist
- postinstall
- dump
- crashkernelsize
- postscripts

Configure the pkglist file

The pkglist for the osimage needs to include the appropriate RPMs. The following list of RPMs are provided as a sample, always refer to the Operating System specific documentataion to ensure the required packages are there for kdump support.

- [RHELS]
  
  kexec-tools
  crash

- [SLES]
  
  kdump
  kexec-tools
  makedumpfile

- [Ubuntu]
  
  <TODO>

Modify the exlist file

The default diskless image created by copycds excludes the /boot directory in the exclude list file, but this is required for kdump.

Update the exlist for the target osimage and remove the line /boot:

```
./boot*  # <-- remove this line
```

Run packimage to update the diskless image with the changes.

The postinstall file

The kdump will create a new initrd which used in the dumping stage. The /tmp or /var/tmp directory will be used as the temporary directory. These 2 directory only are allocated 10M space by default. You need to enlarge it to 200M. Modify the postinstall file to increase /tmp space.

- [RHELS]
The dump attribute

To support kernel dumps, the dump attribute must be set on the osimage definition. If not set, kdump service will not be enabled. The dump attribute defines the NFS remote path where the crash information is to be stored.

Use the chdef command to set a value of the dump attribute:

```
chdef -t osimage <image name> dump=nfs://<nfs_server_ip>/<kdump_path>
```

If the NFS server is the Service Node or Management Node, the server can be left out:

```
chdef -t osimage <image name> dump=nfs:///<kdump_path>
```

Note: Only NFS is currently supported as a storage location. Make sure the NFS remote path(nfs://<nfs_server_ip>/<kdump_path>) is exported and it is read-writeable to the node where kdump service is enabled.

The crashkernelsize attribute

To allow the Operating System to automatically reserve the appropriate amount of memory for the kdump kernel, set crashkernelsize=auto.

For setting specific sizes, use the following example:

- For System X machines, set the crashkernelsize using this format:

```
chdef -t osimage <image name> crashkernelsize=<size>M
```

- For Power System AC922, set the crashkernelsize using this format:

```
chdef -t osimage <image name> crashkernelsize=<size>M
```

- For System P machines, set the crashkernelsize using this format:

```
chdef -t osimage <image name> crashkernelsize=<size>@32M
```

Notes: the value of the crashkernelsize depends on the total physical memory size on the machine. For more about size, refer to Appendix

If kdump start error like this:

```
Your running kernel is using more than 70% of the amount of space you reserved for kdump, you should consider increasing your crashkernel
```

The crashkernelsize is not large enough, you should change the crashkernelsize larger until the error message disappear.
The enablekdump postscript

xCAT provides a postscript enablekdump that can be added to the Nodes to automatically start the kdump service when the node boots. Add to the nodes using the following command:

```
chdef -t node <node range> -p postscripts-enablekdump
```

Manually trigger a kernel panic on Linux

Normally, kernel panic() will trigger booting into capture kernel. Once the kernel panic is triggered, the node will reboot into the capture kernel, and a kernel dump (vmcore) will be automatically saved to the directory on the specified NFS server (<nfs_server_ip>).

Check your Operating System specific documentation for the path where the kernel dump is saved. For example:

- [RHELS6]
  ```
  <kdump_path>/var/crash/<node_ip>-<time>/
  ```

- [SLES11]
  ```
  <kdump_path>/<node_hostname>/<date>
  ```

To trigger a dump, use the following commands:

```
echo 1 > /proc/sys/kernel/sysrq
echo c > /proc/sysrq-trigger
```

This will force the Linux kernel to crash, and the address-YYYY-MM-DD-HH:MM:SS/vmcore file should be copied to the location you set on the NFS server.

Dump Analysis

Once the system has returned from recovering the crash, you can analyze the kernel dump using the crash tool.

1. Locate the recent vmcore dump file.
2. Locate the kernel file for the crash server. The kernel is under /tftpboot/xcat/netboot/<OS name="/<ARCH>/profile/kernel on the managenent node.
3. Once you have located a vmcore dump file and kernel file, call crash:

```
crash <vmcore_dump_file> <kernel_file>
```

Note: If crash cannot find any files, make sure you have the kernel-debuginfo package installed.

Appendix

1. OS Documentations on kdump configuration:
Installing a New Kernel in the Diskless Image

[TODO : Verify on ppc64le]

Note: This procedure assumes you are using xCAT 2.6.1 or later.

To add a new kernel, create a directory named <kernelver> under /install/kernels directory, and genimage will pick them up from there.

The following examples assume you have the kernel RPM in /tmp and is using a new kernel in the directory /install/kernels/<kernelver>.

The RPM names below are only examples, substitute your specific level and architecture.

- [RHEL]
  The RPM kernel package is usually named: kernel-<kernelver>.rpm. For example, kernel-3.10.0-229.ael7b.ppc64le.rpm means kernelver=3.10.0-229.ael7b.ppc64le.

  ```bash
  mkdir -p /install/kernels/3.10.0-229.ael7b.ppc64le
  cp /tmp/kernel-3.10.0-229.ael7b.ppc64le.rpm /install/kernels/3.10.0-229.ael7b.ppc64le
  createrepo /install/kernels/3.10.0-229.ael7b.ppc64le/
  
  Append kernel directory /install/kernels/<kernelver> in pkgdir of specific osimage.

  ```bash
  chdef -t osimage <imagename> -p pkgdir=/install/kernels/3.10.0-229.ael7b.ppc64le/
  ```

  Run genimage/packimage to update the image with the new kernel. Note: If downgrading the kernel, you may need to first remove the rootimg directory.

  ```bash
  genimage <imagename> -k 3.10.0-229.ael7b.ppc64le
  packimage <imagename>
  ```

- [SLES]
  The RPM kernel package is usually separated into two parts: kernel-<arch>-base and kernel<arch>. For example, /tmp contains the following two RPMs:

  ```bash
  kernel-default-3.12.28-4.6.ppc64le.rpm
  kernel-default-base-3.12.28-4.6.ppc64le.rpm
  kernel-default-devel-3.12.28-4.6.ppc64le.rpm
  
  3.12.28-4.6.ppc64le is NOT the kernel version,3.12.28-4-ppc64le is the kernel version. The "4.6.ppc64le" is replaced with "4-ppc64le".

  ```bash
  mkdir -p /install/kernels/3.12.28-4-ppc64le/
  cp /tmp/kernel-default-3.12.28-4.6.ppc64le.rpm /install/kernels/3.12.28-4-ppc64le/
  cp /tmp/kernel-default-base-3.12.28-4.6.ppc64le.rpm /install/kernels/3.12.28-4-ppc64le/
  cp /tmp/kernel-default-devel-3.12.28-4.6.ppc64le.rpm /install/kernels/3.12.28-4-ppc64le/
  ```

  (continues on next page)
Append kernel directory `/install/kernels/<kernelver>` in pkgdir of specific osimage.

```
cndef -t osimage <imagename> -p pkgdir=/install/kernels/3.12.28-4-ppc64le/
```

Run genimage/packimage to update the image with the new kernel. Note: If downgrading the kernel, you may need to first remove the rootimg directory.

Since the kernel version name is different from the kernel rpm package name, the `-k` flag MUST to be specified on the genimage command.

```
genimage <imagename> -k 3.12.28-4-ppc64le 3.12.28-4.6
packimage <imagename>
```

### Installing New Kernel Drivers to Diskless Inittrd

The kernel drivers in the diskless initrd are used for the devices during the netboot. If you are missing one or more kernel drivers for specific devices (especially for the network device), the netboot process will fail. xCAT offers two approaches to add additional drivers to the diskless initrd during the running of genimage.

Use the `-n` flag to add new drivers to the diskless initrd:

```
genimage <imagename> -n <new driver list>
```

Generally, the genimage command has a default driver list which will be added to the initrd. But if you specify the `-n` flag, the default driver list will be replaced with your `<new driver list>`. That means you need to include any drivers that you need from the default driver list into your `<new driver list>`.

The default driver list:

```
rh-x86: tg3 bnx2 bnx2x e1000 e1000e igb mlx_en virtio_net be2net
rh-ppc: e1000 e1000e igb ibmveth ehea
rh-ppcle: ext3 ext4
sles-x86: tg3 bnx2 bnx2x e1000 e1000e igb mlx_en be2net
sles-ppc: tg3 e1000 e1000e igb ibmveth ehea be2net
sles-ppcle: scsi_mod libata scsi_tgt jbd2 mbcache crc16 virtio virtio_ring libahci
  --crc-t10dif scsi_transport_srp af_packet ext3 ext4 virtio_pci virtio_blk scsi_dh
  --ahci megaraid_sas sd_mod ibmvscsi
```

Note: With this approach, xCAT will search for the drivers in the rootimage. You need to make sure the drivers have been included in the rootimage before generating the initrd. You can install the drivers manually in an existing rootimage (using chroot) and run genimage again, or you can use a postinstall script to install drivers to the rootimage during your initial genimage run.

Use the driver rpm package to add new drivers from rpm packages to the diskless initrd. Refer to the `Configure Additional Network Interfaces old version - confignics - (deprecated)` for details.

### Accelerating the diskless initrd and rooting generating

Generating diskless initrd with `genimage` and compressed rooting with `packimage` and `liteimg` is a time-consuming process, it can be accelerated by enabling parallel compression tool `pigz` on the management node with multiple processors and cores. See Appendix for an example on `packimage` performance optimized with `pigz` enabled.
Enabling the **pigz** for diskless initrd and rootimg generating

The parallel compression tool **pigz** can be enabled by installing **pigz** package on the management server or diskless rootimg. Depending on the method of generating the initrd and compressed rootimg, the steps differ in different Linux distributions.

- **[RHEL]**

  The package **pigz** is shipped in Extra Packages for Enterprise Linux (or EPEL) instead of RedHat iso, this involves some complexity.

  Extra Packages for Enterprise Linux (or EPEL) is a Fedora Special Interest Group that creates, maintains, and manages a high quality set of additional packages for Enterprise Linux, including, but not limited to, Red Hat Enterprise Linux (RHEL), CentOS and Scientific Linux (SL), Oracle Linux (OL).

  EPEL has an `epel-release` package that includes gpg keys for package signing and repository information. Installing this package for your Enterprise Linux version should allow you to use normal tools such as `yum` to install packages and their dependencies.

  Refer to the [http://fedoraproject.org/wiki/EPEL](http://fedoraproject.org/wiki/EPEL) for more details on EPEL.

  1. Enabling the **pigz** in *genimage* (only supported in RHEL56 or above)

     **pigz** should be installed in the diskless rootimg. Download **pigz** package from [https://dl.fedoraproject.org/pub/epel/](https://dl.fedoraproject.org/pub/epel/), then customize the diskless osimage to install **pigz** as the additional packages, see [Install Additional Other Packages](#) for more details.

     2. Enabling the **pigz** in *packimage*

     **pigz** should be installed on the management server. Download **pigz** package from [https://dl.fedoraproject.org/pub/epel/](https://dl.fedoraproject.org/pub/epel/), then install the **pigz** with `yum` or `rpm`.

- **[UBUNTU]**

  Make sure the **pigz** is installed on the management node with the following command:

  ```bash
dpkg -l | grep pigz
  ```

  If not, **pigz** can be installed with the following command:

  ```bash
apt-get install pigz
  ```

- **[SLES]**

  1. Enabling the **pigz** in *genimage* (only supported in SLES12 or above)

     **pigz** should be installed in the diskless rootimg, since **pigz** is shipped in the SLES iso, this can be done by adding **pigz** into the pkglist of diskless osimage.

  2. Enabling the **pigz** in *packimage*

     Make sure the **pigz** is installed on the management node with the following command:

     ```bash
rpm -qa | grep pigz
  ```

     If not, **pigz** can be installed with the following command:

     ```bash
zypper install pigz
  ```
Appendix: An example on **packimage** performance optimization with “pigz” enabled

This is an example on performance optimization with **pigz** enabled.

In this example, a xCAT command **packimage rhels7-ppc64-netboot-compute** is run on a Power 7 machine with 4 cores.

The system info:

```bash
# uname -a
Linux c910f03c01p03 3.10.0-123.el7.ppc64 #1 SMP Mon May 5 11:18:37 EDT 2014 ppc64 → ppc64 ppc64 GNU/Linux

# cat /etc/os-release
NAME="Red Hat Enterprise Linux Server"
VERSION="7.0 (Maipo)"
ID="rhel"
ID_LIKE="fedora"
VERSION_ID="7.0"
PRETTY_NAME="Red Hat Enterprise Linux Server 7.0 (Maipo)"
ANSI_COLOR="0;31"
CPE_NAME="cpe:/o:redhat:enterprise_linux:7.0:GA:server"
HOME_URL="https://www.redhat.com/"
BUG_REPORT_URL="https://bugzilla.redhat.com/"

REDHAT_BUGZILLA_PRODUCT="Red Hat Enterprise Linux 7"
REDHAT_BUGZILLA_PRODUCT_VERSION=7.0
REDHAT_SUPPORT_PRODUCT="Red Hat Enterprise Linux"
REDHAT_SUPPORT_PRODUCT_VERSION=7.0
```

The CPU info:

```bash
# cat /proc/cpuinfo
processor : 0
cpu : POWER7 (architected), altivec supported
clock : 3550.000000MHz
revision : 2.0 (pvr 003f 0200)

processor : 1
cpu : POWER7 (architected), altivec supported
clock : 3550.000000MHz
revision : 2.0 (pvr 003f 0200)

processor : 2
cpu : POWER7 (architected), altivec supported
clock : 3550.000000MHz
revision : 2.0 (pvr 003f 0200)

processor : 3
cpu : POWER7 (architected), altivec supported
clock : 3550.000000MHz
revision : 2.0 (pvr 003f 0200)

timebase : 51200000
platform : pSeries
model : IBM,8233-E8B
machine : CHRP IBM,8233-E8B
```

The time spent on **packimage** with gzip:
The time spent on `packimage` with `pigz`:

```
# time packimage rhels7-ppc64-netboot-compute
Packing contents of /install/netboot/rhels7/ppc64/compute/rootimg
compress method: pigz
real 0m23.177s
user 0m0.176s
sys 0m0.016s
```

Trim diskless rootimg

To reduce the memory and boot-up time for the diskless node, the initrd and rootimg.gz should be kept as compact as possible under the premise of meeting the user’s requirements.

Exclude list

xCAT provides an attribute `exlist` in the `osimage` object definition, that allows the user to select files to exclude when building the `rootimg.gz` file for the diskless node.

Take the osimage `sles12.1-ppc64le-netboot-compute` for example:

```
# lsdef -t osimage -o sles12.1-ppc64le-netboot-compute -i exlist
Object name: sles12.1-ppc64le-netboot-compute
  exlist=/opt/xcat/share/xcat/netboot/sles/compute.sles12.ppc64le.exlist
```

Content of the Exclude List file

The file specified in `linuximage.exlist` includes relative path of the directories and files that will be excluded from the `rootimg.gz` generated by `packimage`. The relative path assumes the `rootimg` directory, `/install/netboot/sles12.1/ppc64le/compute/rootimg` here, to be the base directory.\(^1\)

The following is a sample of `exlist` file

```
... 
./usr/share/X11/locale/* 
./usr/lib/perl[0-9]/[0-9.]*/ppc64le-linux-thread-multi/Encode/JP*
+./usr/share/X11/locale/C*
...
```

The content above presents some syntax supported in `exlist` file:

\(^1\) The `exlist` file entry should not end with a slash `/`. For example, this entry will never match anything: `./usr/lib/perl[0-9]/[0-9.]*/ppc64le-linux-thread-multi/Encode/`. 
• Exclude files:
  
  .:/usr/share/X11/locale/*

  All the files and subdirectories under rootimg/usr/share/X11/locale/ will be excluded.

• Exclude Files using Patterns:
  
  ./usr/lib/perl[0-9]/[0-9.]*/ppc64le-linux-thread-multi/Encode/JP*

  Use regular expression to easily exclude files. The above example will exclude any Perl library installed under /usr/lib/ matching ppc64le-linux-thread-multi/Encode/JP*

• Include files:
  
  +./usr/share/locale/C*

  It is useful to include files following an exclude entry to quickly remove a larger set of files using a wildcard and then adding back the few necessary files using the + sign. In the above example, all the files and sub-directories matching the pattern /usr/share/locale/C* will be included in the rootimg.gz file.

Customize the exlist file and the osimage definition

Check the default exlist file and make sure:

• all files and directories you do not want in the image will be excluded from the rootimg.
• no file or directory you need will be excluded from the rootimg.

If you want to customize the osimage sles12.1-ppc64le-netboot-compute with your own exlist file, follow the following steps:

```bash
# create a customized exlist file based on the default one
cp /opt/xcat/share/xcat/netboot/sles/compute.sles12.ppc64le.exlist /install/custom/
  →netboot/sles/compute.sles12.ppc64le.exlist

# edit the newly created exlist file according to your need
vi /install/custom/netboot/sles/compute.sles12.ppc64le.exlist

# specify the newly created exlist file in the osimage definition
chdef -t osimage -o sles12.1-ppc64le-netboot-compute exlist=/install/custom/netboot/
  →sles/compute.sles12.ppc64le.exlist
```

Enabling the localdisk option

**Note:** You can skip this section if not using the localdisk option in your litefile table.

Define how to partition the local disk

When a node is deployed, the local hard disk needs to be partitioned and formatted before it can be used. This section explains how provide a configuration file that tells xCAT to partition a local disk and make it ready to use for the

---

2 Pattern match test applies to the whole file name, starting from one of the start points specified in the exlist file entry. The regex syntax should comply with the regex syntax of system command `find -path`, refer to its doc for details.
directories listed in the litefile table.

The configuration file needs to be specified in the partitionfile attribute of the osimage definition. The configuration file includes several sections:

- Global parameters to control enabling or disabling the function
- [disk] section to control the partitioning of the disk
- [localspace] section to control which partition will be used to store the localdisk directories listed in the litefile table
- [swapspace] section to control the enablement of the swap space for the node.

An example localdisk configuration file:

```plaintext
enable=yes
enablepart=no

[disk]
dev=/dev/sda
clear=yes
parts=10,20,30

[disk]
dev=/dev/sdb
clear=yes
parts=100M-200M,1G-2G

[disk]
dev=/dev/sdc
ptype=gpt
clear=yes
parts=10,20,30

[localspace]
dev=/dev/sda1
fstype=ext3

[swapspace]
dev=/dev/sda2
```

The two global parameters enable and enablepart can be used to control the enabling/disabling of the functions:

- enable: The localdisk feature only works when enable is set to yes. If it is set to no, the localdisk configuration will not be run.
- enablepart: The partition action (refer to the [disk] section) will be run only when enablepart=yes.

The [disk] section is used to configure how to partition a hard disk:

- dev: The path of the device file.
- clear: If set to yes it will clear all the existing partitions on this disk.
- ptype: The partition table type of the disk. For example, msdos or gpt, and msdos is the default.
- fstype: The file system type for the new created partitions. ext3 is the default.
- parts: A comma separated list of space ranges, one for each partition that will be created on the device. The valid format for each space range is <startpoint>-<endpoint> or <percentage of the disk>. For example, you could set it to 100M-10G or 50. If set to 50, 50% of the disk space will be assigned to that partition.
The [localspace] section is used to specify which partition will be used as local storage for the node.

- **dev**: The path of the partition.
- **fstype**: The file system type on the partition.

The [swapspace] section is used to configure the swap space for the statelite node.

- **dev**: The path of the partition file which will be used as the swap space.

To enable the local disk capability, create the configuration file (for example in `/install/custom`) and set the path in the partitionfile attribute for the osimage:

```
chdef -t osimage <osimage> partitionfile=/install/custom/cfglocaldisk
```

Now all nodes that use this osimage (i.e. have their provmethod attribute set to this osimage definition name), will have its local disk configured.

**Configure the files in the litefile table**

For the files/directories to store on the local disk, add an entry in the litefile table:

```
"ALL","/tmp/","localdisk",
```

**Note**: you do not need to specify the swap space in the litefile table. Just putting it in the partitionfile config file is enough.

Add an entry in policy table to permit the running of the getpartition command from the node

```
chtab priority=7.1 policy.commands=getpartition policy.rule=allow
```

Run genimage and packimage for the osimage

**Note**: enablepart=yes in partition file will partition the local disk at every boot. If you want to preserve the contents on local disk at next boot, change to enablepart=no after the initial provision. A log file `/.sllocal/log/localdisk.log` on the target node can be used for debugging.

**Generate Diskless Image**

The copycds command copies the contents of the Linux media to `/install/<os>/<arch>` so that it will be available for installing nodes or creating diskless images. After executing copycds, there are several osimage definitions created by default. Run tabdump osimage to view these images:

```
tabdump osimage
```

The output should be similar to the following:

```
"rhels7.1-ppc64le-install-compute",,"compute","linux",,"install",,"rhels7.1-ppc64le",, ˓→,"Linux","rhels7.1","ppc64le","",,  
"rhels7.1-ppc64le-install-service",,"service","linux",,"install",,"rhels7.1-ppc64le",, ˓→,"Linux","rhels7.1","ppc64le",,
```

(continues on next page)
The netboot-compute is the default diskless osimage created rhels7.1 ppc64le. Run genimage to generate a diskless image based on the "rhels7.1-ppc64le-netboot-compute" definition:

```
genimage rhels7.1-ppc64le-netboot-compute
```

Before packing the diskless image, you have the opportunity to change any files in the image by changing to the rootimgdir and making modifications. (e.g. /install/netboot/rhels7.1/ppc64le/compute/rootimg).

However it’s recommended that all changes to the image are made via post install scripts so that it’s easily repeatable. Although, instead, we recommend that you make all changes to the image via your postinstall script, so that it is repeatable. Refer to Prescripts and Postscripts for more details.

Pack Diskless Image

After you run genimage to create the image, you can go ahead to pack the image to create the ramdisk:

```
packimage rhels7.1-ppc64le-netboot-compute
```

Export and Import Image

Overview

Note: There is a current restriction that exported 2.7 xCAT images cannot be imported on 2.8 xCAT https://sourceforge.net/p/xcat/bugs/3813/. This is no longer a restrictions, if you are running xCAT 2.8.3 or later.

We want to create a system of making xCAT images more portable so that they can be shared and prevent people from reinventing the wheel. While every install is unique there are some things that can be shared among different sites to make images more portable. In addition, creating a method like this allows us to create snap shots of images we may find useful to revert to in different situations.

Image exporting and importing are supported for stateful (diskful) and stateless (diskless) clusters. The following documentation will show how to use imgexport to export images and imgimport to import images.

Exporting an image

1. The user has a working image and the image is defined in the osimage table and linuximage table. example:

```
lsdef -t osimage myimage
Object name: myimage
exlist=/install/custom/netboot/sles/compute1.exlist
imagetype=linux
netdrivers=e1000
osarch=ppc64le
osname=Linux
osvers=sles12
```

(continues on next page)
2. The user runs the imgexport command. example:

```
imgexport myimage -p node1 -e /install/postscripts/myscript1 -e /install/postscripts/myscript2
(-p and -e are optional)
```

A bundle file called myimage.tgz will be created under the current directory. The bundle file contains the ramdisk, boot kernel, the root image and all the configuration files for generating the image for a diskless cluster. For diskful, it contains the kickstart/autoyast configuration file. (see appendix). The -p flag puts the names of the postscripts for node1 into the image bundle. The -e flags put additional files into the bundle. In this case two postscripts myscript1 and myscript2 are included. This image can now be used on other systems.

### Importing an image

1. User downloads an image bundle file from somewhere. (Sumavi.com will be hosting many of these).
2. User runs the imgimport command.

   example:
   ```
   imgimport myimage.tgz -p group1
   (-p is optional)
   ```

This command fills out the osimage and linuximage tables, and populates file directories with appropriate files from the image bundle file such as ramdisk, boot kernel, root image, configuration files for diskless. Any additional files that come with the bundle file will also be put into the appropriate directories. If -p flag is specified, the postscript names that come with the image will be put the into the postscripts table for the given node or group.

### Copy an image to a new image name on the MN

Very often, the user wants to make a copy of an existing image on the same xCAT mn as a start point to make modifications. In this case, you can run imgexport first as described on chapter 2, then run imgimport with -f flag to change the profile name of the image. That way the image will be copied into a different directory on the same xCAT mn.

   example:
   ```
   imgimport myimage.tgz -p group1 -f compute2
   ```

### Modify an image (optional)

Skip this section if you want to use the image as is.
1. The use can modify the image to fit his/her own need. The following can be modified.
   
   - Modify .pkglist file to add or remove packages that are from the os distro
   - Modify .otherpkgs.pkglist to add or remove packages from other sources. Refer to Using_Updatenode for details
   - For diskful, modify the .tmpl file to change the kickstart/autoyast configuration
   - Modify .synclist file to change the files that are going to be synchronized to the nodes
   - Modify the postscripts table for the nodes to be deployed
   - Modify the osimage and/or linuximage tables for the location of the source rpms and the rootimage location

2. Run genimage:
   
   genimage image_name

3. Run packimage:
   
   packimage image_name

**Deploying nodes**

You can change the provmethod of the node to the new image_name if different:

chdef <noderange> provmethod=<image_name>
nodeset <noderange> osimage=<image_name>

and the node is ready to deploy.

**Appendix**

You can only export/import one image at a time. Each tarball will have the following simple structure:

manifest.xml
<files>
extra/ (optional)

**manifest.xml**

The manifest.xml will be analogous to an autoyast or windows unattend.xml file where it tells xCAT how to store the items. The following is an example for a diskless cluster:

manifest.xml:

```xml
<?xml version="1.0"?>
<xcatimage>
<exlist>/install/custom/netboot/sles/compute1.exlist</exlist>
<extra>
<dest>/install/postscripts</dest>
<src>/install/postscripts/myscript1</src>
</extra>
<imagename>myimage</imagename>
```

(continues on next page)
In the above example, we have a directive of where the files came from and what needs to be processed.

Note that even though source destination information is included, all files that are standard will be copied to the appropriate place that xCAT thinks they should go.

### Exported files

The following files will be exported, assuming x is the profile name:

For diskful:

- x.pkglist
- x.otherpkgs.pkglist
- x.tmpl
- x.synclist

For diskless:

- kernel
- initrd.gz
- rootimg.gz
- x.pkglist
- x.otherpkgs.pkglist
- x.synclist
- x.postinstall
- x.exlist

Note: Although the postscripts names can be exported by using the -p flag. The postscripts themselves are not included in the bundle file by default. The use has to use -e flag to get them included one by one if needed.

### Initialize the Compute for Deployment

XCAT use `nodeset` command to associate a specific image to a node which will be installed with this image.
There are more attributes of nodeset used for some specific purpose or specific machines, for example:

- **runimage**: If you would like to run a task after deployment, you can define that task with this attribute.
- **runcmd**: This instructs the node to boot to the xCAT nbfs environment and proceed to configure BMC for basic remote access. This causes the IP, netmask, gateway, username, and password to be programmed according to the configuration table.
- **shell**: This instructs the node to boot to the xCAT genesis environment, and present a shell prompt on console. The node will also be able to be sshed into and have utilities such as wget, tftp, scp, nfs, and cifs. It will have storage drivers available for many common systems.

Choose such additional attribute of nodeset according to your requirement, if want to get more information about nodeset, refer to nodeset’s man page.

### Start the OS Deployment

Start the deployment involves two key operations. First specify the boot device of the next boot to be network, then reboot the node:

For **Power servers**, those two operations can be completed by one command `rnetboot`:

```
rnetboot <node>
```

For **x86_64 servers**, those two operations need two independent commands.

1. set the next boot device to be from the “network”

```
rsetboot <node> net
```

2. Reboot the xSeries server::

```
rpower <node> reset
```

### Statelite Installation

#### Overview

This document details the design and setup for the statelite solution of xCAT. **Statelite** is an intermediate mode between **diskful** and **diskless**.

Statelite provides two kinds of efficient and flexible solutions, most of the OS image can be NFS mounted read-only, or the OS image can be in the ramdisk with tmpfs type. Different from the stateless solution, statelite provides a configurable list of directories and files that can be read-write. These read-write directories and files can be configured to either persist or not persist across reboots.

#### Solutions

There are two solutions: **NFSROOT-based** and **RAMdisk-based**.

1. **NFSROOT-based**(default):

   (a) `rootfstype` in the osimage xCAT data objects is left as blank, or set to `nfs`, the **NFSROOT-base** statelite solution will be enabled.

   (b) the `ROOTFS` is NFS mounted read-only.
2. RAMdisk-based:

(a) rootfstype in the osimage xCAT data objects is set to ramdisk.

(b) one image file will be downloaded when the node is booting up, and the file will be extracted to the ramdisk, and used as the ROOTFS.

Advantages

Statelite offers the following advantages over xCAT’s stateless (RAMdisk) implementation:

1. Some files can be made persistent over reboot. This is useful for license files or database servers where some state is needed. However, you still get the advantage of only having to manage a single image.

2. Changes to hundreds of machines can take place instantly, and automatically, by updating one main image. In most cases, machines do not need to reboot for these changes to take affect. This is only for the NFSROOT-based solution.

3. Ease of administration by being able to lock down an image. Many parts of the image can be read-only, so no modifications can transpire without updating the central image.

4. Files can be managed in a hierarchical manner. For example: Suppose you have a machine that is in one lab in Tokyo and another in London. You could set table values for those machines in the xCAT database to allow machines to sync from different places based on their attributes. This allows you to have one base image with multiple sources of file overlay.

5. Ideal for virtualization. In a virtual environment, you may not want a disk image (neither stateless nor stateful) on every virtual node as it consumes memory and disk. Virtualizing with the statelite approach allows for images to be smaller, easier to manage, use less disk, less memory, and more flexible.

Disadvantages

However, there’re still several disadvantages, especially for the NFSROOT-based solution.

1. NFS Root requires more network traffic to run as the majority of the disk image runs over NFS. This may depend on your workload, but can be minimized. Since the bulk of the image is read-only, NFS caching on the server helps minimize the disk access on the server, and NFS caching on the client helps reduce the network traffic.

2. NFS Root can be complex to set up. As more files are created in different places, there are greater chances for failures. This flexibility is also one of the great virtues of Statelite. The image can work in nearly any environment.

Configuration

Statelite configuration is done using the following tables in xCAT:

- litefile
- litetree
- statelite
- policy
- noderes

litefile table

The litefile table specifies the directories and files on the statelite nodes that should be read/write, persistent, or read-only overlay. All other files in the statelite nodes come from the read-only statelite image.
1. The first column in the litefile table is the image name this row applies to. It can be an exact osimage definition name, an osimage group (set in the groups attribute of osimages), or the keyword ALL.

2. The second column in the litefile table is the full path of the directory or file on the node that you are setting options for.

3. The third column in the litefile table specifies options for the directory or file:
   (a) tmpfs - It provides a file or directory for the node to use when booting, its permission will be the same as the original version on the server. In most cases, it is read-write; however, on the next statelite boot, the original version of the file or directory on the server will be used, it means it is non-persistent. This option can be performed on files and directories.
   (b) rw - Same as above. Its name “rw” does NOT mean it always be read-write, even in most cases it is read-write. Do not confuse it with the “rw” permission in the file system.
   (c) persistent - It provides a mounted file or directory that is copied to the xCAT persistent location and then over-mounted on the local file or directory. Anything written to that file or directory is preserved. It means, if the file/directory does not exist at first, it will be copied to the persistent location. Next time the file/directory in the persistent location will be used. The file/directory will be persistent across reboots. Its permission will be the same as the original one in the statelite location. It requires the statelite table to be filled out with a spot for persistent statelite. This option can be performed on files and directories.
   (d) con - The contents of the pathname are concatenated to the contents of the existing file. For this directive the searching in the litetree hierarchy does not stop when the first match is found. All files found in the hierarchy will be concatenated to the file when found. The permission of the file will be “-rw-r--r--”, which means it is read-write for the root user, but readonly for the others. It is non-persistent, when the node reboots, all changes to the file will be lost. It can only be performed on files. Do not use it for one directory.
   (e) ro - The file/directory will be overmounted read-only on the local file/directory. It will be located in the directory hierarchy specified in the litetree table. Changes made to this file or directory on the server will be immediately seen in this file/directory on the node. This option requires that the file/directory to be mounted must be available in one of the entries in the litetree table. This option can be performed on files and directories.
   (f) tmpfs,rw - Only for compatibility it is used as the default option if you leave the options column blank. It has the same semantics with the link option, so when adding new items into the _litefile table, the link option is recommended.
   (g) link - It provides one file/directory for the node to use when booting, it is copied from the server, and will be placed in tmpfs on the booted node. In the local file system of the booted node, it is one symbolic link to one file/directory in tmpfs. And the permission of the symbolic link is “lrwxrwxrwx”, which is not the real permission of the file/directory on the node. So for some application sensitive to file permissions, it will be one issue to use “link” as its option, for example, “/root/.ssh/”, which is used for SSH, should NOT use “link” as its option. It is non-persistent, when the node is rebooted, all changes to the file/directory will be lost. This option can be performed on files and directories.
   (h) link,ro - The file is readonly, and will be placed in tmpfs on the booted node. In the local file system of the booted node, it is one symbolic link to the tmpfs. It is non-persistent, when the node is rebooted, all changes to the file/directory will be lost. This option requires that the file/directory to be mounted must be available in one of the entries in the litetree table. The option can be performed on files and directories.
   (i) link,con - Similar to the “con” option. All the files found in the litetree hierarchy will be concatenated to the file when found. The final file will be put to the tmpfs on the booted node. In the local file system of the booted node, it is one symbolic link to the file/directory in tmpfs. It is non-persistent, when the node is rebooted, all changes to the file will be lost. The option can only be performed on files.
   (j) link,persistent - It provides a mounted file or directory that is copied to the xCAT persistent location and then over-mounted to the tmpfs on the booted node, and finally the symbolic link in the local file system
will be linked to the over-mounted tmpfs file/directory on the booted node. The file/directory will be persistent across reboots. The permission of the file/directory where the symbolic link points to will be the same as the original one in the statelite location. It requires the statelite table to be filled out with a spot for persistent statelite. The option can be performed on files and directories.

(k) localdisk - The file or directory will be stored in the local disk of the statelite node. Refer to the section To enable the localdisk option to enable the ‘localdisk’ support.

Currently, xCAT does not handle the relative links very well. The relative links are commonly used by the system libraries, for example, under /lib/ directory, there will be one relative link matching one .so file. So, when you add one relative link to the litefile table (Not recommend), make sure the real file also be included, or put its directory name into the litefile table.

Note: It is recommended that you specify at least the entries listed below in the litefile table, because most of these files need to be writeable for the node to boot up successfully. When any changes are made to their options, make sure they won’t affect the whole system. If you want to run a command like /bin/ping using non-root users, add this command into litefile, then root user have privilege to authorize the command for non-root users.

Sample Data for Redhat statelite setup

This is the minimal list of files needed, you can add additional files to the litefile table.

<table>
<thead>
<tr>
<th>#image, file, options, comments, disable</th>
</tr>
</thead>
<tbody>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/adjtime&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/securetty&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/lvm/&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/ntp.conf&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/rsyslog.conf&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/xsyslog.conf.XCATORIG&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/rsyslog.d/&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/udev/&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/ntp.conf.prdhclient&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/resolv.conf&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/ypp.conf&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/resolv.conf.prdhclient&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/sysconfig/&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/ssh/&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/rc3.d/&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/rc2.d/&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/rc5.d/&quot;,&quot;tmpfs&quot;,</td>
</tr>
<tr>
<td>&quot;ALL&quot;,&quot;/etc/rc5.d/&quot;,&quot;tmpfs&quot;,</td>
</tr>
</tbody>
</table>

Sample Data for SLES statelite setup

This is the minimal list of files needed, you can add additional files to the litefile table.

1.3. Admin Guide 167
litetree table

The litetree table controls where the initial content of the files in the litefile table come from, and the long term content of the ro files. When a node boots up in statelite mode, it will by default copy all of its tmpfs files from the .default directory of the root image, for example /install/netboot/rhels7.3/x86_64/compute/rootimg/.default, so there is not required to set up a litetree table. If you decide that you want some of the files pulled from different locations that are different per node, you can use this table.

You can choose to use the defaults and not set up a litetree table.

statelite table

The statelite table specifies location on an NFS server where a node's persistent files are stored. This is done by entering the information into the statelite table.

In the statelite table, the node or node groups in the table must be unique; that is a node or group should appear only once in the first column table. This makes sure that only one statelite image can be assigned to a node. An example would be:

```
"compute",,"<nfssvr_ip>:/gpfs/state",
```

Any nodes in the compute node group will have their state stored in the /gpfs/state directory on the machine with <nfssvr_ip> as its IP address.

When the node boots up, then the value of the statemnt attribute will be mounted to /.statelite/persistent. The code will then create the following subdirectory /.statelite/persistent/<nodename>, if there are persistent files that have been added in the litefile table. This directory will be the root of the image for this node's persistent files. By default, xCAT will do a hard NFS mount of the directory. You can change the mount options by setting the mntopts attribute in the statelite table.

Also, to set the statemnt attribute, you can use variables from xCAT database. It follows the same grammar as the litetree table. For example:
Note: Do not name your persistent storage directory with the node name, as the node name will be added in the directory automatically. If you do, then a directory named /state/cn1 will have its state tree inside /state/cn1/cn1.

Policy

Ensure policies are set up correctly in the Policy Table. When a node boots up, it queries the xCAT database to get the litefile and litetree table information. In order for this to work, the commands (of the same name) must be set in the policy table to allow nodes to request it. This should happen automatically when xCAT is installed, but you may want to verify that the following lines are in the policy table:

```
chdef -t policy -o 4.7 commands=litefile rule=allow
chdef -t policy -o 4.8 commands=litetree rule=allow
```

noderes

noderes.nfsserver attribute can be set for the NFSroot server. If this is not set, then the default is the Management Node.
noderes.nfsdir can be set. If this is not set, the default is /install

Provision statelite

Show current provisioning method

To determine the current provisioning method of your node, execute:

```
lsdef <noderange> -i provmethod
```

Note: syncfiles is not currently supported for statelite nodes.

Generate default statelite image from distoro media

In this example, we are going to create a new compute node osimage for rhels7.3 on ppc64le. We will set up a test directory structure that we can use to create our image. Later we can just move that into production.

Use the copycds command to copy the appropriate iso image into the /install directory for xCAT. The copycds commands will copy the contents to /install/rhels7.3/<arch>. For example:

```
copycds RHEL-7.3-20161019.0-Server-ppc64le-dvd1.iso
```

The contents are copied into /install/rhels7.3/ppc64le/

The configuration files pointed to by the attributes are the defaults shipped with xCAT. We will want to copy them to the /install directory, in our example the /install/test directory and modify them as needed.
Statelite Directory Structure

Each statelite image will have the following directories:

- `.statelite/tmpfs/`
- `.default/`
- `/etc/init.d/statelite`

All files with link options, which are symbolic links, will link to `.statelite/tmpfs`. tmpfs files that are persistent link to `.statelite/persistent/<nodename>/`, `.statelite/persistent/<nodename>` is the directory where the node’s individual storage will be mounted to. `/default` is where default files will be copied to from the image to tmpfs if the files are not found in the litetree hierarchy.

Customize your statelite osimage

Create the osimage definition

Setup your osimage/linuximage tables with new test image name, osvers, osarch, and paths to all the files for building and installing the node. So using the above generated `rhels7.3-ppc64le-statelite-compute` as an example, I am going to create my own image. The value for the provisioning method attribute is osimage in my example:

```
mkdef rhels7.3-custom-statelite -u profile=compute provmethod=statelite
```

Check your setup:

```
lsdef -t osimage rhels7.3-custom-statellite
```

Customize the paths to your pkglist, syncfile, etc to the osimage definition, that you require. Note, if you modify the files on the `/opt/xcat/share/...` path then copy to the appropriate `/install/custom/...` path. Remember all files must be under `/install` if using hierarchy (service nodes).

Copy the sample *list files and modify as needed:

```
mkdir -p /install/test/netboot/rh
 cp -p /opt/xcat/share/xcat/netboot/rh/compute.rhels7.ppc64le.pkglist 
   /install/test/netboot/rh/compute.rhels7.ppc64le.pkglist
 cp -p /opt/xcat/share/xcat/netboot/rh/compute.exlist 
   /install/test/netboot/rh/compute.exlist
 chdef -t osimage -o rhels7.3-custom-statellite 
   pkgdir=/install/rhels7.3/ppc64le 
   pkglist=/install/test/netboot/rh/compute.rhels7.ppc64le.pkglist 
   exlist=/install/test/netboot/rh/compute.exlist 
   rootimgdir=/install/test/netboot/rh/ppc64le/compute
```

Setup pkglists

In the above example, you have defined your pkglist to be in `/install/test/netboot/rh/compute. rhels7.ppc64le.pkglist`. Edit `compute.rhels7.ppc64le.pkglist` and `compute.exlist` as needed.
vi /install/test/netboot/rh/compute.rhels7.ppc64le.pkglist
vi /install/test/netboot/rh/compute.exlist

Make sure nothing is excluded in compute.exlist that you need.

**Install other specific packages**

Make the directory to hold additional rpms to install on the compute node.

```bash
mkdir -p /install/test/post/otherpkgs/rh/ppc64le
```

Now copy all the additional OS rpms you want to install into /install/test/post/otherpkgs/rh/ppc64le.

At first you need to create one text file which contains the complete list of files to include in the repository. The name of the text file is rpms.list and must be in /install/test/post/otherpkgs/rh/ppc64le directory. Create rpms.list:

```bash
cd /install/test/post/otherpkgs/rh/ppc64le
ls *.rpm > rpms.list
```

Then, run the following command to create the repodata for the newly-added packages:

```bash
createrepo -i rpms.list /install/test/post/otherpkgs/rh/ppc64le
```

The `createrepo` command with `-i rpms.list` option will create the repository for the rpm packages listed in the `rpms.list` file. It won’t destroy or affect the rpm packages that are in the same directory, but have been included into another repository.

Or, if you create a sub-directory to contain the rpm packages, for example, named other in /install/test/post/otherpkgs/rh/ppc64le. Run the following command to create repodata for the directory /install/test/post/otherpkgs/rh/ppc64le.

```bash
createrepo /install/post/otherpkgs/<os>/<arch>/**other**
```

Note: Replace other with your real directory name.

Define the location of of your otherpkgs in your osimage:

```bash
chdef -t osimage -o rhels7.3-custom-statelite \ 
otherpkgdir=/install/test/post/otherpkgs/rh/ppc64le \ 
otherpkglist=/install/test/netboot/rh/compute.otherpkg.pkglist
```

There are examples under /opt/xcat/share/xcat/netboot/<platform> of typical `*otherpkgs.pkglist` files that can used as an example of the format.

**Set up Post scripts for statelite**

The rules to create post install scripts for statelite image is the same as the rules for stateless/diskless install images.

There’re two kinds of postscripts for statelite (also for stateless/diskless).

The first kind of postscript is executed at genimage time, it is executed again the image itself on the MN. It was setup in The postinstall file section before the image was generated.
The second kind of postscript is the script that runs on the node during node deployment time. During init.d timeframe, /etc/init.d/gettyset calls /opt/xcat/xcatdsklspost that is in the image. This script uses wget to get all the postscripts under mn:/install/postscripts and copy them to the /xcatpost directory on the node. It uses openssl or stunnel to connect to the xcatd on the mn to get all the postscript names for the node from the postscripts table. It then runs the postscripts for the node.

**Setting up postinstall files (optional)**

Using postinstall files is optional. There are some examples shipped in /opt/xcat/share/xcat/netboot/<platform>.

If you define a postinstall file to be used by genimage, then

```
chdef -t osimage -o rhels7.3-custom-statelite postinstall=<your postinstall file path>
```

**Generate the image**

Run the following command to generate the image based on your osimage named rhels7.3-custom-statelite. Adjust your genimage parameters to your architecture and network settings. See man genimage.

```
genimage rhels7.3-custom-statelite
```

The genimage will create a default /etc/fstab in the image, if you want to change the defaults, on the management node, edit fstab in the image:

```
cd /install/netboot/rhels7/ppc64le/compute/rootimg/etc
cp fstab fstab.ORIG
vi fstab
```

Note: adding /tmp and /var/tmp to /etc/fstab is optional, most installations can simply use /. It was documented her to show that you can restrict the size of filesystems, if you need to. The indicated values are just and example, and you may need much bigger filesystems, if running applications like OpenMPI.

**Pack the image**

Execute liteimg

```
liteimg rhels7.3-custom-statelite
```

**Boot the statelite node**

Execute rinstall

```
rinstall node1 osimage=rhels7.3-custom-statelite
```

**Switch to the RAMdisk based solution**

It is optional, if you want to use RAMdisk-based solution, follow this section.
Set rootfstype

If you want the node to boot with a RAMdisk-based image instead of the NFS-base image, set the rootfstype attribute for the osimage to ramdisk. For example:

```
chdef -t osimage -o rhels7.3-custom-statelite rootfstype=ramdisk
```

Run liteimg command

The `liteimg` command will modify your statelite image (the image that `genimage` just created) by creating a series of links. Once you are satisfied with your image contains what you want it to, run `liteimg <osimagename>`:

```
liteimg rhels7.3-custom-statelite
```

For files with link options, the `liteimg` command creates two levels of indirection, so that files can be modified while in their image state as well as during runtime. For example, a file like `$imageroot/etc/ntp.conf` with link option in the litefile table, will have the following operations done to it:

In our case `$imageroot` is `/install/netboot/rhels5.3/x86_64/compute/rootimg`

The `liteimg` script, for example, does the following to create the two levels of indirection.

```
mkdir -p $imageroot/.default/etc
mkdir -p $imageroot/.statelite/tmpfs/etc
mv $imgroot/etc/ntp.conf $imageroot/.default/etc
cd $imgroot/.statelite/tmpfs/etc
ln -sf ../../../.default/etc/ntp.conf .
cd $imgroot/etc
ln -sf ../.statelite/tmpfs/etc/ntp.conf .
```

When finished, the original file will reside in `$imgroot/.default/etc`. `$imgroot/etc/ntp.conf` will link to `$imgroot/.statelite/tmpfs/etc/ntp.conf` which will in turn link to `$imgroot/.default/etc/ntp.conf`.

But for files without link options, the `liteimg` command only creates clones in `$imageroot/.default/` directory, when the node is booting up, the mount command with `--bind` option will get the corresponding files from the `litetree` places or `.default` directory to the sysroot directory.

**Note:** If you make any changes to your litefile table after running `liteimg` then you will need to rerun `liteimg` again. This is because files and directories need to have the two levels of redirects created.

Boot the statelite node

Make sure you have set up all the attributes in your node definitions correctly following the node installation instructions corresponding to your hardware:

You can now deploy the node by running the following command:

```
rinstall <noderange>
```

You can then use `rcons` or `wcons` to watch the node boot up.
Adding/updating software and files for the running nodes

Make changes to the files which configured in the litefile table

During the preparation or booting of node against statelite mode, there are specific processes to handle the files which configured in the litefile table. The following operations need to be done after made changes to the statelite files.

1. Run `liteimg` against the osimage and reboot the node: Added, removed or changed the entries in the litefile table.
2. Reboot the node:
   - Changed the location directory in the litetree table.
   - Changed the location directory in the statelite table.
   - Changed, removed the original files in the location of litetree or statelite table.

Note: Thing should not do:

- When there are node running on the nfs-based statelite osimage, do not run the packimage against this osimage.

Make changes to the common files

Because most of system files for the nodes are NFS mounted on the Management Node with read-only option, installing or updating software and files should be done to the image. The image is located under `/install/netboot/<os>/<arch>/<profile>/rootimg` directory.

To install or update an rpm, do the following:

- Install the rpm package into rootimg
  
  ```
  rpm --root /install/netboot/<os>/<arch>/<profile>/rootimg -ivh rpm_name
  ```

- Restart the software application on the nodes
  
  ```
  xdsh <noderange> <restart_this_software_command>
  ```

It is recommended to follow the section (Adding third party software) to add the new rpm to the otherpkgs.pkglist file, so that the rpm will get installed into the new image next time the image is rebuilt.

Note: The newly added rpms are not shown when running `rpm -qa` on the nodes although the rpm is installed. It will shown next time the node is rebooted.

To create or update a file for the nodes, just modify the file in the image and restart any application that uses the file.

For the ramdisk-based node, you need to reboot the node to take the changes.

Hierarchy Support

In the `statelite` environment, the service node needs to provide NFS service for the compute node with `statelite` the service nodes must to be setup with diskfull installation.

Setup the diskfull service node

1. Setup one diskfull service node at first.
2. Since statelite is a kind of NFS-hybrid method, you should remove the installloc attribute in the site table. This makes sure that the service node does not mount the /install directory from the management node on the service node.

**Generate the statelite image**

To generate the statelite image for your own profile follow instructions in *Customize your statelite osimage*.

**NOTE**: if the NFS directories defined in the litetree table are on the service node, it is better to setup the NFS directories in the service node following the chapter.

**Sync the /install directory**

The command prsync is used to sync the /install directory to the service nodes.

Run the following:

```
cd /
p sync install <sn>:/
```

<sn> is the hostname of the service node you defined.

Since the prsync command will sync all the contents in the /install directory to the service nodes, the first time will take a long time. But after the first time, it will take very short time to sync.

**NOTE**: if you make any changes in the /install directory on the management node, and the changes can affect the statelite image, you need to sync the /install directory to the service node again.

**Set the boot state to statelite**

You can now deploy the node:

```
reinstall <noderange> osimage=rhel5.3-x86_64-statelite-compute
```

This will create the necessary files in /tftpboot for the node to boot correctly.

**Advanced features**

**Both directory and its child items coexist in litefile table**

As described in the above chapters, we can add the files/directories to litefile table. Sometimes, it is necessary to put one directory and also its child item(s) into the litefile table. Due to the implementation of the statelite on Linux, some scenarios works, but some doesn’t work.

Here are some examples of both directory and its child items coexisting:

Both the parent directory and the child file coexist:

```
"ALL","/root/testblank/",,,
"ALL","/root/testblank/tempfschild","tempfs",,
```

One more complex example:
Another more complex example, but we don’t intend to support such one scenario:

```
"ALL","/root/",,,
"ALL","/root/testblank/tempfschild","tempfs",,
```

For example, in scenario 1, the parent is `/root/testblank/`, and the child is `/root/testblank/tempfschild`. In scenario 2, the parent is `/root/`, and the child is `/root/testblank/tempfschild`.

In order to describe the hierarchy scenarios we can use \( P \) to denote parent, and \( C \) to denote child.
<table>
<thead>
<tr>
<th>Option</th>
<th>Example</th>
<th>Remarks</th>
</tr>
</thead>
<tbody>
<tr>
<td>P:tmpfs</td>
<td>“ALL”,’/root/testblank/’,, “ALL”,’/root/testblank/testpersfile’,,</td>
<td>Both the parent and the child are mounted to tmpfs on the booted node following their respective options. Only the parent are mounted to the local file system.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P:tmpfs C:persistent</td>
<td>“ALL”,’/root/testblank/’,, “ALL”,’/root/testblank/testpersfile’,,</td>
<td>Both parent and child are mounted to tmpfs on the booted node following their respective options. Only the parent is mounted to the local file system.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P: persistent C: persistent</td>
<td>“ALL”,’/root/testblank/’,, “persistent”, “ALL”,’/root/testblank/testpersfile’,,</td>
<td>Both parent and child are mounted to tmpfs on the booted node following their respective options. Only the parent is mounted to the local file system.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P:ro C: any</td>
<td></td>
<td>Not permitted</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P:tmpfs C:ro</td>
<td></td>
<td>Both parent and child are mounted to tmpfs on the booted node following their respective options. Only the parent is mounted to the local file system.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P:tmpfs C:con</td>
<td></td>
<td>Both parent and child are mounted to tmpfs on the booted node following their respective options. Only the parent is mounted to the local file system.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P:link C:link</td>
<td>“ALL”,’/root/testlink/’,, “link”, “ALL”,’/root/testlink/testlinkchild’,,</td>
<td>Both parent and child are created in tmpfs on the booted node following their respective options; there’s only one symbolic link of the parent is created in the local file system.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P: link, persistent C: link</td>
<td>“ALL”,’/root/testlinkpers/’,, “link”, “ALL”,’/root/testlink/testlinkchild’,, “link,persistent”</td>
<td>Both parent and child are created in tmpfs on the booted node following their respective options; there’s only one symbolic link of the parent is created in the local file system.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P: link, persistent C: link, persistent</td>
<td>“ALL”,’/root/testlinkpers/’,, “link”, “ALL”,’/root/testlink/testlinkchild’,, “link,persistent”</td>
<td>Both parent and child are created in tmpfs on the booted node following “link,persistent” way; there’s only one symbolic link of the parent is created in the local file system.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P: link C:link, ro</td>
<td>“ALL”,’/root/testlink/’,, “link”, “ALL”,’/root/testlink/testlinkro’,, “link,ro”</td>
<td>Both parent and child are created in tmpfs on the booted node, there’s only one symbolic link of the parent is created in the local file system.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P: link C:link, con</td>
<td>“ALL”,’/root/testlink/’,, “link”, “ALL”,’/root/testlink/testlinkconchild’,, “link,con”</td>
<td>Both parent and child are created in tmpfs on the booted node, there’s only one symbolic link of the parent is created in the local file system.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P: link, persistent C: link, ro</td>
<td>“ALL”,’/root/testlinkpers/’,, “link&quot;, “ALL”,’/root/testlink/testlinkro’,, “link,ro”</td>
<td>NOT Permitted</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>P:link, persistent C:link, con</td>
<td>“ALL”,’/root/testlink/’,, “link&quot;, “ALL”,’/root/testlink/testlinkconchild’,, “link,con”</td>
<td>NOT Permitted</td>
</tr>
</tbody>
</table>
litetree table

The litetree table controls where the initial content of the files in the litefile table come from, and the long term content of the ro files. When a node boots up in statelite mode, it will by default copy all of its tmpfs files from the ./default directory of the root image, so there is not requirement to setup a litetree table. If you decide that you want some of the files pulled from different locations that are different per node, you can use this table.

See litetree man page for description of attributes.

For example, a user may have two directories with a different /etc/motd that should be used for nodes in two locations:

| 10.0.0.1:/syncdirs/newyork-590Madison/rhels5.4/x86_64/compute/etc/motd |
| 10.0.0.1:/syncdirs/shanghai-11foo/rhels5.4/x86_64/compute/etc/motd |

You can specify this in one row in the litetree table:

| 1,,10.0.0.1:/syncdirs/$nodepos.room/$nodetype.os/$nodetype.arch/$nodetype.profile |

When each statelite node boots, the variables in the litetree table will be substituted with the values for that node to locate the correct directory to use. Assuming that /etc/motd was specified in the litefile table, it will be searched for in all of the directories specified in the litetree table and found in this one.

You may also want to look by default into directories containing the node name first:

| $noderes.nfsserver:/syncdirs/$node |

The litetree prioritizes where node files are found. The first field is the priority. The second field is the image name (ALL for all images) and the final field is the mount point.

Our example is as follows:

| 1,,$noderes.nfsserver:/statelite/$node |
| 2,,cnfs:/gpfs/dallas/ |

The two directories /statelite/$node on the node’s $noderes.nfsserver and the /gpfs/dallas on the node cnfs contain root tree structures that are sparsely populated with files that we want to place in those nodes. If files are not found in the first directory, it goes to the next directory. If none of the files can be found in the litetree hierarchy, then they are searched for in ./default on the local image.

Installing a new Kernel in the statelite image

Obtain you new kernel and kernel modules on the MN, for example here we have a new SLES kernel.

1. Copy the kernel into /boot :

```
cp **vmlinux-2.6.32.10-0.5-ppc64** /boot
```

2. Copy the kernel modules into /lib/modules/<new kernel directory>

```
/`/lib/modules # ls -al
 total 16
 drwxr-xr-x 4 root root 4096 Apr 19 10:39 .
 drwxr-xr-x 17 root root 4096 Apr 13 08:39 ..
 drwxr-xr-x 3 root root 4096 Apr 13 08:51 2.6.32.10-0.4-ppc64
 **drwxr-xr-x 4 root root 4096 Apr 19 10:12 2.6.32.10-0.5-ppc64**
```
3. Run genimage to update the statelite image with the new kernel

```
genimage -k 2.6.32.10-0.5-ppc64 <osimage_name>
```

4. Then after a nodeset command and netbooti, shows the new kernel:

```
uname -a
```

Enabling the localdisk option

**Note:** You can skip this section if not using the `localdisk` option in your `litefile` table.

Define how to partition the local disk

When a node is deployed, the local hard disk needs to be partitioned and formatted before it can be used. This section explains how provide a configuration file that tells xCAT to partition a local disk and make it ready to use for the directories listed in the litefile table.

The configuration file needs to be specified in the `partitionfile` attribute of the osimage definition. The configuration file includes several sections:

- Global parameters to control enabling or disabling the function
- `[disk]` section to control the partitioning of the disk
- `[localspace]` section to control which partition will be used to store the `localdisk` directories listed in the `litefile` table
- `[swapspace]` section to control the enablement of the swap space for the node.

An example `localdisk` configuration file:

```bash
enable=yes
enablepart=no

[disk]
dev=/dev/sda
clear=yes
parts=10,20,30

[disk]
dev=/dev/sdb
clear=yes
parts=100M-200M,1G-2G

[disk]
dev=/dev/sdc
ptype=gpt

clear=yes
parts=10,20,30

[localspace]
dev=/dev/sdal
fstype=ext3
```

(continues on next page)
The two global parameters `enable` and `enablepart` can be used to control the enabling/disabling of the functions:

- **enable**: The `localdisk` feature only works when `enable` is set to `yes`. If it is set to `no`, the `localdisk` configuration will not be run.
- **enablepart**: The partition action (refer to the `[disk]` section) will be run only when `enablepart=yes`.

The `[disk]` section is used to configure how to partition a hard disk:

- **dev**: The path of the device file.
- **clear**: If set to `yes` it will clear all the existing partitions on this disk.
- **ptype**: The partition table type of the disk. For example, `msdos` or `gpt`, and `msdos` is the default.
- **fstype**: The file system type for the new created partitions. `ext3` is the default.
- **parts**: A comma separated list of space ranges, one for each partition that will be created on the device. The valid format for each space range is `<startpoint>-<endpoint>` or `<percentage of the disk>`. For example, you could set it to `100M-10G` or `50`. If set to `50`, 50% of the disk space will be assigned to that partition.

The `[localspace]` section is used to specify which partition will be used as local storage for the node:

- **dev**: The path of the partition.
- **fstype**: The file system type on the partition.

The `[swapspace]` section is used to configure the swap space for the statelite node.

- **dev**: The path of the partition file which will be used as the swap space.

To enable the local disk capability, create the configuration file (for example in `/install/custom`) and set the path in the `partitionfile` attribute for the osimage:

```
chdef -t osimage <osimage> partitionfile=/install/custom/cfglocaldisk
```

Now all nodes that use this osimage (i.e. have their `provmethod` attribute set to this osimage definition name), will have its local disk configured.

**Configure the files in the litefile table**

For the files/directories to store on the local disk, add an entry in the `litefile` table:

```
"ALL","/tmp","localdisk",
```

**Note**: you do not need to specify the swap space in the litefile table. Just putting it in the `partitionfile` config file is enough.

Add an entry in policy table to permit the running of the `getpartition` command from the node

```
chtab priority=7.1 policy.commands=getpartition policy.rule=allow
```

Run `genimage` and `packimage` for the osimage
If Using the RAMdisk-based Image

If you want to use the local disk option with a RAMdisk-based image, remember to follow the instructions in *Switch to the RAMdisk based solution.*

If your reason for using a RAMdisk image is to avoid compute node runtime dependencies on the service node or management node, then the only entries you should have in the litefile table should be files/dirs that use the localdisk option.

Debugging techniques

When a node boots up in statelite mode, there is a script that runs called statelite that is in the root directory of `$imageroot/etc/init.d/statelite`. This script is not run as part of the rc scripts, but as part of the pre-switch root environment. Thus, all the linking is done in this script. There is a `set x` near the top of the file. You can uncomment it and see what the script runs. You will then see lots of mkdirs and links on the console.

You can also set the machine to shell. Just add the word `shell` on the end of the px.boot file of the node in the append line. This will make the init script in the initramfs pause 3 times before doing a switch_root.

When all the files are linked they are logged in `/.statelite/statelite.log` on the node. You can get into the node after it has booted and look in the `/.statelite` directory.

Using Updatenode

Introduction

After initial node deployment, you may need to make changes/updates to your nodes. The `updatenode` command is for this purpose. It allows you to add or modify the followings on your nodes:

1. Add additional software
2. Re-run postscripts or run additional postscripts
3. Synchronize new/updated configuration files
4. Update ssh keys and xCAT certificates

Each of these will be explained in the document. The basic way to use `updatenode` is to set the definition of nodes on the management node the way you want it and then run `updatenode` to push those changes out to the actual nodes. Using options to the command, you can control which of the above categories `updatenode` pushes out to the nodes.

Most of what is described in this document applies to stateful and stateless nodes. In addition to the information in this document, check out the `updatenode` man page.

Add Additional Software

The packages that will be installed on the node are stored in the packages list files. There are two kinds of package list files:

1. The **package list file** contains the names of the packages that come from the os distro. They are stored in `.pkglist` file.
2. The **other package list file** contains the names of the packages that do NOT come from the os distro. They are stored in `.otherpkgs.pkglist` file.
Installing Additional OS Distro Packages

For packages from the OS distro, add the new package names (without the version number) in the .pkglist file. If you have newer updates to some of your operating system packages that you would like to apply to your OS image, you can place them in another directory, and add that directory to your osimage pkgdir attribute. How to add additional OS distro packages, go to Install Additional OS Packages for RHEL and SLES

Note: If the objective node is not installed by xCAT, make sure the correct osimage pkgdir attribute so that you could get the correct repository data.

Install Additional non-OS Packages

If you have additional packages (packages not in the distro) that you also want installed, make a directory to hold them, create a list of the packages you want installed, and add that information to the osimage definition. How to add Additional Other Packages, go to Install Additional Other Packages for RHEL and SLES

Update Nodes

Run the updatenode command to push the new software to the nodes:

```
updatenode <noderange> -S
```

The -S flag updates the nodes with all the new or updated packages specified in both .pkglist and .otherpkg.pkglist.

If you have a configuration script that is necessary to configure the new software, then instead run:

```
cp myconfigscript /install/postscripts/
chdef -p -t compute postbootscripts=myconfigscript
updatenode <noderange> ospkgs,otherpkg,myconfigscript
```

The next time you re-install these nodes, the additional software will be automatically installed.

If you update stateless nodes, you must also do this next step, otherwise the next time you reboot the stateless nodes, the new software won’t be on the nodes. Run genimage and packimage to install the extra rpms into the image:

```
genimage <osimage>
packimage <osimage>
```

Update the delta changes in Sysclone environment

Updatenode can also be used in Sysclone environment to push delta changes to target node. After capturing the delta changes from the golden client to management node, just run below command to push delta changes to target nodes. See Sysclone environment related section: Update Nodes Later On for more information.

```
updatenode <targetnoderange> -S
```

Rerun Postscripts or Run Additional Postscripts

You can use the updatenode command to perform the following functions after the nodes are up and running:

- Rerun postscripts defined in the postscripts table.
- Run any additional postscript one time.
Go to *Using Postscript* to see how to configure postscript.

Go to *Using Prescript* to see how to configure prepostscript.

To rerun all the postscripts for the nodes. (In general, xCAT postscripts are structured such that it is not harmful to run them multiple times.)

```bash
updatenode <noderange> -P
```

To rerun just the syslog postscript for the nodes:

```bash
updatenode <noderange> -P syslog
```

To run a list of your own postscripts, make sure the scripts are copied to /install/postscripts directory, then:

```bash
updatenode <noderange> -P "script1,script2"
```

If you need to, you can also pass arguments to your scripts:

```bash
updatenode <noderange> -P "script1 p1 p2,script2"
```

**mypostscript template for updatenode**

You can customize what attributes you want made available to the postscript, using the shipped mypostscript.tmpl file *Using the mypostscript template.*

**Synchronize new/updated configuration files**

**Setting up synfile**

Use instructions in doc: *The synclist file.*

**Syncfiles to the nodes**

After compute node is installed, you would like to sync files to the nodes:

```bash
updatenode <noderange> -F
```

With the `updatenode` command the synfiles postscript cannot be used to sync files to the nodes. Therefore, if you run `updatenode <noderange> -P synfiles`, nothing will be done. A message will be logged that you must use `updatenode <noderange> -F` to sync files.

**Update the ssh Keys and Credentials on the Nodes**

If after node deployment, the ssh keys or xCAT ssl credentials become corrupted, xCAT provides a way to quickly fix the keys and credentials on your service and compute nodes:

```bash
updatenode <noderange> -K
```

Note: this option can’t be used with any of the other updatenode options.
Appendix : Debugging Tips

Internally updatenode command uses the xdsh in the following ways:

Linux: xdsh <noderange> -e /install/postscripts/xcatdksps.post -m <server> <scripts&gt;

where <scripts> is a comma separated postscript like ospkgs,otherpkgs etc.

- wget is used in xcatdksps.post/xcataixpost to get all the postscripts from the <server> to the node. You can check 
  /tmp/wget.log file on the node to see if wget was successful or not. You need to make sure the /xcatpost directory 
  has enough space to hold the postscripts.

- A file called /xcatpost/mypostscript (Linux) is created on the node which contains the environmental variables 
  and scripts to be run. Make sure this file exists and it contains correct info. You can also run this file on the node 
  manually to debug.

- For ospkgs/otherpkgs, if /install is not mounted on the <server>, it will download all the rpms from the 
  <server> to the node using wget. Make sure /tmp and /xcatpost have enough space to hold the rpms and check 
  /tmp/wget.log for errors.

- For ospkgs/otherpkgs, If zypper or yum is installed on the node, it will be used the command to install the rpms. 
  Make sure to run createrepo on the source directory on the <server> every time a rpm is added or removed. 
  Otherwise, the rpm command will be used, in this case, make sure all the necessary depended rpms are copied 
  in the same source directory.

- You can append -x on the first line of ospkgs/otherpkgs to get more debug info.

Parallel Commands

xCAT provides a set of commands that can run common remote commands (ssh, scp, rsh, rcp, rsync, 
ping, cons) in parallel on xCAT managed nodes. The xCAT commands will format the output making the results 
easier to parse and help administrators manage large clusters.

The following commands are provided:

- pcons - runs a command on the noderange using the out-of-band console
- pping - parallel ping
- ppping - parallel ping between nodes in a cluster
- prsync - parallel rsync
- pscp - parallel remote copy ( supports scp and not hierarchy)
- psh - parallel remote shell ( supports ssh and not hierarchy)
- pasu - parallel ASU utility
- xdcp - concurrently copies files to and from multiple nodes. ( scp/rcp and hierarchy)
- xdsh - concurrently runs commands on multiple nodes. ( supports ssh/rsh and hierarchy)
- xdshbak - formats the output of the xdsh command
- xcoll - Formats command output of the psh, xdsh, rinv command

Examples for xdsh

- To set up the SSH keys for root on node1, run as root:
• To run the `ps -ef` command on node targets node1 and node2, enter:

```
xdsh node1,node2 "ps -ef"
```

• To run the `ps` command on node targets node1 and run the remote command with the `-v` and `-t` flag, enter:

```
xdsh node1,node2 -o"-v -t" ps =item *
```

• To execute the commands contained in myfile in the XCAT context on several node targets, with a fanout of 1, enter:

```
xdsh node1,node2 -f 1 -e myfile
```

• To run the `ps` command on node1 and ignore all the dsh environment variable except the DSH_NODE_OPTS, enter:

```
xdsh node1 -X `DSH_NODE_OPTS' ps
```

• To run on Linux, the xdsh command `dpkg -l| grep vim` on the node ubuntu diskless image, enter:

```
xdsh -i /install/netboot/ubuntu14.04.2/ppc64el/compute/rootimg "dpkg -l|grep vim"
```

• To run xdsh with the non-root userid “user1” that has been setup as an xCAT userid and with sudo on node1 and node2 to run as root, do the following, see Granting users xCAT privileges:

```
xdsh node1,node2 --sudo -l user1 "cat /etc/passwd"
```

Examples for xdcp

• To copy the `/etc/hosts` file from all nodes in the cluster to the `/tmp/hosts.dir` directory on the local host, enter:

```
xdcp all -P /etc/hosts /tmp/hosts.dir
```

A suffix specifying the name of the target is appended to each file name. The contents of the `/tmp/hosts.dir` directory are similar to:

```
hosts._node1 hosts._node4 hosts._node7
hosts._node2 hosts._node5 hosts._node8
hosts._node3 hosts._node6
```

• To copy `/localnode/smallfile` and `/tmp/bigfile` to `/tmp` on node1 using rsync and input `-t` flag to rsync, enter:

```
xdcp node1 -r /usr/bin/rsync -o "-t" /localnode/smallfile /tmp/bigfile /tmp
```

• To copy the `/etc/hosts` file from the local host to all the nodes in the cluster, enter:

```
xdcp all /etc/hosts /etc/hosts
```

• To rsync the `/etc/hosts` file to your compute nodes:

```
Create a rsync file /tmp/myrsync, with this line:
```

```
1.3. Admin Guide 185
```
/etc/hosts -> /etc/hosts

or

/etc/hosts -> /etc/ (last / is required)

Run:

```
xdcp compute -F /tmp/myrsync
```

- To rsync the /etc/file1 and file2 to your compute nodes and rename to filex and filey:

Create a rsync file /tmp/myrsync, with these line:

```
/etc/file1 -> /etc/filex
/etc/file2 -> /etc/filey
```

Run:

```
xdcp compute -F /tmp/myrsync
```

- To rsync files in the Linux image at /install/netboot/ubuntu14.04.2/ppc64el/compute/rootimg on the MN:

Create a rsync file /tmp/myrsync, with this line:

```
/etc/hosts /etc/passwd -> /etc
```

Run:

```
xdcp -i /install/netboot/ubuntu14.04.2/ppc64el/compute/rootimg -F /tmp/myrsync
```

**Virtual Machines**

xCAT supports the following virtualization infrastructures:

**Kernel-based Virtual Machine (KVM):** A full virtualization solution for Enterprise Linux distributions, known as the de facto open source virtualization mechanism and currently used by many software companies.

**IBM PowerKVM:** A product that leverages the Power resilience and performance with the openness of KVM, which provides several advantages:

- Higher workload consolidation with processors overcommitment and memory sharing
- Dynamic addition and removal of virtual devices
- Microthreading scheduling granularity
- Integration with IBM PowerVC and OpenStack
- Simplified management using open source software
- Avoids vendor lock-in
- Uses POWER8 hardware features, such as SMT8 and microthreading

The xCAT based KVM solution offers users the ability to:

- provision the hypervisor on bare metal nodes
- provision virtual machines with the any OS supported in xCAT
• migrate virtual machines to different hosts
• install copy on write instances of virtual machines
• clone virtual machines

This section introduces the steps of management node preparation, hypervisor setup and virtual machine management, and presents some typical problems and solutions on xCAT kvm support.

Set Up the Management Node for KVM

Install the kvm related packages

Additional packages need to be installed on the management node for kvm support. Please make sure the following packages have been installed on the management node, if not, install them manually.

perl-Sys-Virt

Set Up the kvm storage directory on the management node (optional)

It is a recommended configuration to create a shared file system for virtual machines hosting. The shared file system, usually on a SAN, NAS or GPFS, is shared among KVM hypervisors, which simplifies VM migration from one hypervisor to another with xCAT.

The easiest shared file system is /install directory on the management node, it can be shared among hypervisors via NFS. Please refer to the following steps:

• Create a directory to store the virtual disk files

```bash
mkdir -p /install/vms
```

• export the storage directory

```bash
echo "/install/vms *(rw,no_root_squash,sync,fsid=0)" >> /etc/exports
exportfs -r
```

Note: make sure the root permission is turned on for nfs clients (i.e. use the no_root_squash option). Otherwise, the virtual disk file can not work.

Install and Configure Hypervisor

Provision Hypervisor

[PowerKVM]

Obtain a PowerKVM ISO and create PowerKVM osimages with it:

```bash
copycds ibm-powerkvm-3.1.0.0-39.0-ppc64le-gold-201511041419.iso
```

The following PowerKVM osimage will be created
Red Hat Virtualization (formerly known as RHEV or Red Hat Enterprise Virtualization) is a virtualization solution provided by Red Hat.

At the time of this writing there is no RHEV-H prebuilt hypervisor image on Power LE. The method for creating a Red Hat Hypervisor on Power LE is to first install RHEL and apply the KVM support on top with the provided RPMs.

Obtain and download the RHEV RPM packages from the Red Hat download site.

- Management-Agent-Power-7
- Power_Tools-7

In the following example, the RPMs are downloaded to /install/post/otherpkgs/rhels7.3/ppc64le/RHEV4/4.0-GA

- Create a yum repository for the downloaded RPMs

```
createrepo /install/post/otherpkgs/rhels7.3/ppc64le/RHEV4/4.0-GA
```

- Create new osimage definition based on an existing RHEL7 osimage definition

```
mkdef -t osimage -o rhels7.3-ppc64le-RHEV4-install-compute --template rhels7.3-ppc64le-install-compute
```

- Modify otherpkgdir attribute to point to the package directory with downloaded RPMs

```
chdef -t osimage rhels7.3-ppc64le-RHEV4-install-compute 
   otherpkgdir=/install/post/otherpkgs/rhels7.3/ppc64le/RHEV4/4.0-GA
```

- Create a new package list file /install/custom/rhels7.3/ppc64le/rhelv4.pkglist to include necessary packages provided from the OS.

```
#INCLUDE:/opt/xcat/share/xcat/install/rh/compute.rhels7.pkglist#
yum libvirt screen bridge-utils
```

- Modify pkglist attribute to point to the package list file from the step above
**Note:** If diskless RHEV osimage is needed, localdisk option can be used to preserve VMs over RHEV hypervisor reprovision. For instructions see *Enabling the localdisk option*. Set `/var/lib/libvirt/` directory where by default VM images are stored to localdisk.

1. Customize the hypervisor node definition to create network bridge

xCAT ships a postscript xHRM to create a network bridge on kvm host during installation/netbooting. Specify the xHRM with appropriate parameters in `postscripts` attribute. For example:

- To create a bridge named ‘br0’ against the installation network device specified by `installnic`:

  ```
  chdef kvmhost1 -p postscripts="xHRM bridgeprereq br0"
  ```

- To create a bridge with default name ‘default’ against the installation network device specified by `installnic`:

  ```
  chdef kvmhost1 -p postscripts="xHRM bridgeprereq"
  ```

- To create a bridge named ‘br0’ against the network device ‘eth0’:
Note: The network bridge name you use should not be the virtual bridges (vbrX) created by libvirt installation¹.

1. Customize the hypervisor node definition to mount the shared kvm storage directory on management node (optional)

If the shared kvm storage directory on the management node has been exported, it can be mounted on PowerKVM hypervisor for virtual machines hosting.

An easy way to do this is to create another postscript named “mountvms” which creates a directory /install/vms on hypervisor and then mounts /install/vms from the management node, the content of “mountvms” can be:

```
logger -t xcat "Install: setting vms mount in fstab"
mkdir -p /install/vms
echo "${MASTER}:/install/vms /install/vms nfs \rsize=8192,wsize=8192,timeo=14,intr,nfsvers=2 1 2" >> /etc/fstab
```

Then set the file permission and specify the script in postscripts attribute of hypervisor node definition:

```
chmod 755 /install/postscripts/mountvms
chdef kvmhost1 -p postscripts=mountvms
```

2. Provision the hypervisor node with the osimage

```
rinstall kvmhost1 osimage=<osimage_name>
```

Create network bridge on hypervisor

To launch VMs, a network bridge must be created on the KVM hypervisor.

If the hypervisor is provisioned successfully according to the steps described above, a network bridge will be created and attached to a physical interface. This can be checked by running `brctl show` on the hypervisor to show the network bridge information, please make sure a network bridge has been created and configured according to the parameters passed to postscript “xHRM”

```
# brctl show
bridge name   bridge id         STP enabled  interfaces
br0           8000.000000000000   no           eth0
```

If the network bridge is not created or configured successfully, run “xHRM” with `updatenode` on management node to create it manually):

```
updatenode kvmhost1 -P "xHRM bridgeprereq eth0:br0"
```

Start libvirtd service

Verify `libvirtd` service is running:

¹ Every standard libvirt installation provides NAT based connectivity to virtual machines out of the box using the “virtual bridge” interfaces (virbr0, virbr1, etc) Those will be created by default.
Manage Virtual Machine (VM)

Now the PowerKVM hypervisor “kvmhost1” is ready, this section introduces the VM management in xCAT, including examples on how to create, remove and clone VMs.

Create Virtual Machine

Create VM Node Definition

Create a virtual machine node object “vm1”, assign it to be a member of group “vm”, its ip is “192.168.0.1”, run makehost to add an entry in /etc/hosts file:

```
mkdef vm1 groups=vm,all
chdef vm1 ip=192.168.0.1
makehosts vm1
```

Update DNS configuration and database:

```
makedns -n
makedns -a
```

Specify VM attributes

After the VM object is created, several key attributes need to be specified with chdef:

1. the hardware management module, “kvm” for PowerKVM:

```
chdef vm1 mgt=kvm
```

2. the number of virtual cpus in the VM:

```
chdef vm1 vmcpus=2
```

3. the kvm hypervisor of the VM:

```
chdef vm1 vmhost=kvmhost1
```

4. the virtual memory size, with the unit “Megabit”. Specify 1GB memory to “vm1” here:

```
chdef vm1 vmmemory=1024
```

Note: For diskless node, the vmmemory should be at least 2048 MB, otherwise the node cannot boot up.

5. Define the virtual network card, it should be set to the bridge “br0” which has been created in the hypervisor. If no bridge is specified, no network device will be created for the VM node “vm1”:
chdef vm1 vmnics=br0

6. The `vmnicnicmodel` attribute is used to set the type and corresponding driver for the nic. If not set, the default value is `virtio`.

chdef vm1 vmnicnicmodel=virtio

7. Define the storage for the vm1, three types of storage source format are supported.
   (a) Create storage on a NFS server
       The format is `nfs://<IP_of_NFS_server>/dir`, that means the kvm disk files will be created at `nfs://<IP_of_NFS_server>/dir`:

       chdef vm1 vmstorage=nfs://<IP_of_NFS_server>/install/vms/

   (b) Create storage on a device of hypervisor
       The format is `phy:/dev/sdb1`:

       chdef vm1 vmstorage=phy:/dev/sdb1

   (c) Create storage on a directory of hypervisor
       The format is `dir:///var/lib/libvirt/images`:

       chdef vm1 vmstorage=dir:///var/lib/libvirt/images

Note: The attribute `vmstorage` is only valid for diskful VM node.

8. Define the `console` attributes for VM:

chdef vm1 serialport=0 serialspeed=115200

9. (optional) For monitoring and access the VM with vnc client, set `vidpassword` value:

chtab node=vm1 vm.vidpassword=abc123

10. (optional) For assigning PCI devices to the VM, set `othersettings` value:

chtab node=vm1 vm.othersettings="devpassthrough:0000:01:00.2"

Or:

chtab node=vm1 vm.othersettings="devpassthrough:pci_0000_01_00_2"

Take assigning SR-IOV VFs to the VM as an example:

- Use `lspci` to get VFs PCI from hypervisor:

```
lspci|grep -i "Virtual Function"
0000:01:00.1 Infiniband controller: Mellanox Technologies MT27700 Family ...
    [ConnectX-4 Virtual Function]
0000:01:00.2 Infiniband controller: Mellanox Technologies MT27700 Family ...
    [ConnectX-4 Virtual Function]
```

- Set the VFs PCI into vm table on MN:
11. Set `netboot` attribute

- **[x86_64]**
  ```
  chdef vm1 netboot=xnba
  ```

- **[PPC64LE]**
  ```
  chdef vm1 netboot=grub2
  ```

Make sure “grub2” had been installed on the management node:

```bash
# rpm -aq | grep grub2
grub2-xcat-1.0-1.noarch
```

### Make virtual machine

If `vmstorage` is a NFS mounted directory or a device on hypervisor, run

```bash
mkvm vm1
```

To create the virtual machine “vm1” with 20G hard disk on a hypervisor directory, run

```bash
mkvm vm1 -s 20G
```

When “vm1” is created successfully, a VM hard disk file with a name like “vm1.sda.qcow2” will be found in the location specified by `vmstorage`. What’s more, the `mac` attribute of “vm1” is set automatically, check it with:

```bash
lsdef vm1 -i mac
```

Now a VM “vm1” is created, it can be provisioned like any other nodes in xCAT. The VM node can be powered on by:

```bash
rpower vm1 on
```

If “vm1” is powered on successfully, the VM status can be obtained by running the following command on management node

```bash
rpower vm1 status
```

or running the following command on the kvm hypervisor “kvmhost1”

```bash
# virsh list
    Id  Name       State
    ----------------------
     6  vm1       running
```

### Monitoring the Virtual Machine

When the VM has been created and powered on, choose one of the following methods to monitor and access it.

- Open the console on kvm hypervisor:
virsh console vm1

- Use rcons/wcons on xCAT management node to open text console:

  chdef vm1 cons=kvm
  makegocons vm1
  rcons vm1

- Connect to virtual machine through vnc console

  In order to connect the virtual machine’s vnc server, a new set of credentials need to be generated by running:

  xcatclient getrvidparms vm1
  vm1: method: kvm
  vm1: textconsole: /dev/pts/0
  vm1: password: JOQTUtn0dUOBv9o3
  vm1: vidproto: vnc
  vm1: server: kvmhost1
  vm1: vidport: 5900

  Note: Now just pick a favorite vnc client to connect the hypervisor, with the password generated by getrvidparms. If the vnc client complains “the password is not valid”, the reason might be that the hypervisor and headnode clocks are out of sync! Please try to sync them by running `ntpdate <ntp server>` on both the hypervisor and the headnode.

- Use wvid on management node

  Make sure firewalld service is stopped, disable it if not:

  `chkconfig firewalld off`

  or

  `systemctl disable firewalld`

  Then, run wvid on MN:

  `wvid vm1`

- For PowerKVM, kimchi on the kvm hypervisor can be used to monitor and access the VM.

**Remove the virtual machine**

Remove the VM “vm1” even when it is in “power-on” status:

`rmvm vm1 -f`

Remove the definition of “vm1” and related storage:

`rmvm vm1 -p`

**Clone the virtual machine**

Clone is an operation that creating a VM from an existed one by inheriting most of its attributes and data.
The general step of clone a VM is like this: first creating a VM master, then creating a VM with the newly created VM master in attaching or detaching mode.

In attaching mode

In this mode, all the newly created VMs are attached to the VM master. Since the image of the newly created VM only includes the differences from the VM master, which requires less disk space. The newly created VMs can NOT run without the VM master.

An example is shown below:

Create the VM master “vm5” from a VM node “vm1”:

```
#clonevm vm1 -t vm5
vm1: Cloning vm1.sda.qcow2 (currently is 1050.6640625 MB and has a capacity of 4096MB)
vm1: Cloning of vm1.sda.qcow2 complete (clone uses 1006.74609375 for a disk size of 4096MB)
vm1: Rebasing vm1.sda.qcow2 from master
vm1: Rebased vm1.sda.qcow2 from master
```

The newly created VM master “vm5” can be found in the vmmaster table.

```
#tabdump vmmaster
name,os,arch,profile,storage,storagemodel,nics,vintage,originator,comments,disable
"vm5","<os>","<arch>","compute","nfs://<storage_server_ip>/vms/kvm","","
→"root",,
```

Clone a new node vm2 from VM master vm5:

```
clonevm vm2 -b vm5
```

In detaching mode

Create a VM master “vm6”.

```
#clonevm vm2 -t vm6 -d
vm2: Cloning vm2.sda.qcow2 (currently is 1049.4765625 MB and has a capacity of 4096MB)
vm2: Cloning of vm2.sda.qcow2 complete (clone uses 1042.21875 for a disk size of 4096MB)
```

Clone a VM “vm3” from the VM master “vm6” in detaching mode:

```
#clonevm vm3 -b vm6 -d
vm3: Cloning vm6.sda.qcow2 (currently is 1042.21875 MB and has a capacity of 4096MB)
```

Migrate Virtual Machines

Virtual machine migration is a process that moves the virtual machines (guests) between different hypervisors (hosts).

Note: The VM storage directory should be accessible from both hypervisors (hosts).

Migrate the VM “kvm1” from hypervisor “hyp01” to hypervisor “hyp02”:

```
#rmigrate kvm1 hyp02
kvm1: migrated to hyp02
```
Trouble Shooting

VNC client complains the credentials are not valid

Issue: While connecting to the hypervisor with VNC, the vnc client complains “Authentication failed”.

Solution: Check whether the clocks on the hypervisor and headnode are synched

rpower fails with “Error: internal error Process exited while reading console log qemu: Permission denied”

Issue:

```
rpower vml on
vml: Error: internal error Process exited while reading console log output: char device redirected to /dev/pts/1
qemu: could not open disk image /var/lib/xcat/pools/2e66895a-e09a-53d5-74d3-eccdd9746eb5/vml.sda.qcow2: Permission denied: internal error Process exited while reading console log output: char device redirected to /dev/pts/1
qemu: could not open disk image /var/lib/xcat/pools/2e66895a-e09a-53d5-74d3-eccdd9746eb5/vml.sda.qcow2: Permission denied
```

Solution: Usually caused by incorrect permission in NFS server/client configuration. NFSv4 is enabled in some Linux distributions such as CentOS6 by default. The solution is simply to disable NFSv4 support on the NFS server by uncommenting the following line in “/etc/sysconfig/nfs”:

```
RPCNFSDARGS="-N 4"
```

Then restart the NFS services and try to power on the VM again…

Note: For stateless hypervisor, purge the VM by rmvm -p vml, reboot the hypervisor and then create the VM.

rpower fails with “Error: internal error: process exited while connecting to monitor qemu: Permission denied”

Issue:

```
rpower vml on
vml: Error: internal error: process exited while connecting to monitor: 2016-02-03T08:28:54.104601Z qemu-system-ppc64: -drive file=/var/lib/xcat/pools/c7953a80-89ca-53c7-64fb-2d0c549db45/vml.sda.qcow2, if=none, id=drive-scsi0-0-0-0, format=qcow2, cache=none: Could not open '/var/lib/xcat/pools/c7953a80-89ca-53c7-64fb-2d0c549db45/vml.sda.qcow2': Permission denied
```

Solution: Usually caused by SELinux policies. The solution is simply to disable SELinux on the vmhost/hypervisor by editing “/etc/selinux/config” and change the SELINUX line to SELINUX=disabled:

```
SELINUX=disabled
```

Then reboot the hypervisor…
rmigrate fails with “Error: libvirt error code: 38, message: unable to connect to server at ‘c910f05c35:49152’: No route to host.”

**Issue:**

```
#rmigrate vml kvmhost2
vml: Error: libvirt error code: 38, message: unable to connect to server at ←'kvmhost2:49152': No route to host: Failed migration of vml from kvmhost1→ to kvmhost2
```

**Solution:** Usually caused by active firewall. To disable the firewall issue:

```
systemctl disable firewalld
```

rmigrate fails with “Error: 38, message: failed to create directory ‘<dir-name>’: File exists: Unknown issue libvirt error code.”

**Issue:**

```
#rmigrate vml kvmhost2
vml: Error: 38, message: failed to create directory '<dir-name>': File exists: Unknown issue libvirt error code.
```

**Solution:** Usualy happens when `nfs:` is specified for vmstorage attribute but that NFS directory is no longer mounted. Make sure the directory `/var/lib/xcat/pools` is empty on the destination kvmhost.

**Error: Cannot communicate via libvirt to kvmhost1**

**Issue:** The kvm related commands complain “Error: Cannot communicate via libvirt to kvmhost1”

**Solution:** Usually caused by incorrect ssh configuration between xCAT management node and hypervisor. Make sure it is possible to access the hypervisor from management node via ssh without password.

**Fail to ping the installed VM**

**Issue:** The newly installed stateful VM node is not pingable, the following message can be observed in the console during VM booting:

```
ADDRCONF(NETDEV_UP): eth0 link is not ready.
```

**Solution:** Usually caused by the incorrect VM NIC model. Try the following steps to specify “virtio”:

```
rmvm vml
chdef vml vmnicnicmodel=virtio
mkvm vml
```

**x86_64**

This section is not available at this time.

Refer to xCAT Documentation on SourceForge for information on System X servers.
1.3.3 References

xCAT Man Pages

These man pages are auto generated from .pod files to .rst files using the create_man_pages.py script under xcat-core

man1
addkit.1

NAME

addkit - Adds product software Kits to an xCAT cluster environment.

SYNOPSIS

addkit [ -? | -h | --help] [-v | --version]
addkit [ -i | --inspection] kitlist
addkit [ -V | --verbose] [-p | --path path] kitlist

DESCRIPTION

The addkit command installs a kit on the xCAT management node from a kit tarfile or directory. It creates xCAT database definitions for the kit, kitrepo, and kitcomponent.

Note: xCAT Kit support is ONLY available for Linux operating systems.

OPTIONS

-? | --help
   Display usage message.

-V | --verbose
   Verbose mode.

-v | --version
   Command version.

-i | --inspection
   Show the summary of the given kits

-p | --path path
   The destination directory to which the contents of the kit tarfiles and/or kit deploy directories will be copied. When this option is not specified, the default destination directory will be formed from the installldir site attribute with ./kits subdirectory.

kitlist
A comma delimited list of kit_tarball_files or kit_deploy_directories to be added to the xCAT environment. Each entry can be an absolute or relative path. See xCAT documentation for more information on building kits.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To add kits from tarball files:
   ```
   addkit kit-test1.tar.bz2,kit-test2.tar.bz2
   ```

2. To add kits from directories:
   ```
   addkit kit-test1,kit-test2
   ```

3. To add kits from tarball kit-test1.tar.bz2 to target path /install/test:
   ```
   addkit -p /install/test kit-test1.tar.bz2
   ```

4. To see general information about kit kit-test1.tar.bz2 without adding the kit to xCAT:
   ```
   addkit -i kit-test1.tar.bz2
   ```

SEE ALSO

lskit(1)|lskit.1, rmkit(1)|rmkit.1, addkitcomp(1)|addkitcomp.1, rmkitcomp(1)|rmkitcomp.1, chkkitcomp(1)|chkkitcomp.1

addkitcomp.1

NAME

addkitcomp - Assign Kit components to an xCAT osimage.

SYNOPSIS

addkitcomp [-? | -h | --help] [-v | --version]
DESCRIPTION

The `addkitcomp` command will assign kit components to an xCAT osimage. The kit component meta rpm, package rpm and deploy parameters will be added to osimage’s otherpkg.pkglist and postbootscripts will be added to osimages’s postbootscripts attribute.

Note: xCAT Kit support is ONLY available for Linux operating systems.

OPTIONS

- `--adddeps`  
  Assign kitcomponent dependencies to the osimage.

- `--help`  
  Display usage message.

- `--verbose`  
  Verbose mode.

- `--version`  
  Command version.

- `--force`  
  Add kit component to osimage even if there is a mismatch in OS, version, arch, serverrole, or kitcompdeps

- `osimage`  
  The osimage name that the kit component is assigning to.

- `--noupgrade`  
  1. Allow multiple versions of kitcomponent to be installed into the osimage, instead of kitcomponent upgrade.
  
  2. Kit components added by addkitcomp -n will be installed separately behind all other ones which have been added.

- `--noscripts`  
  Do not add kitcomponent’s postbootscripts to osimage

- `kitcompname_list`  
  A comma-delimited list of valid full kit component names or kit component basenames that are to be added to the osimage.

RETURN VALUE

0 The command completed successfully.

1 An error has occurred.

EXAMPLES

1. To add a single kit component to osimage “rhels6.2-ppc64-netboot-compute”: 
2. To add a kit component to osimage with dependencies, use the -a (addeps) option:

```
addkitcomp -a -i rhels6.2-ppc64-netboot-compute comp-test2-1.0-1-rhels-6.2-ppc64
```

3. To add a kit component to osimage with incompatible osarch, osversion or ostype, use the -f (force) option:

```
addkitcomp -f -i rhels6.2-ppc64-netboot-compute comp-test1-1.0-1-rhels-6.2-ppc64
```

4. To add a new version of kit component to osimage without upgrade, use the -n (noupgrade) option:

```
addkitcomp -n -i rhels6.2-ppc64-netboot-compute comp-test2-1.0-1-rhels-6.2-ppc64
```

SEE ALSO

lskit(1)|lskit.1, addkit(1)|addkit.1, rmkit(1)|rmkit.1, rmkitcomp(1)|rmkitcomp.1, chkkitcomp(1)|chkkitcomp.1

bmcdiscover.1

NAME

bmcdiscover - Discover Baseboard Management Controllers (BMCs) using a scan method

SYNOPSIS

```
bmcdiscover [-? | -h | --help]
bmcdiscover [-v | --version]
```

DESCRIPTION

The `bmcdiscover` command will discover Baseboard Management Controllers (BMCs) using a scan method.

The command uses `nmap` to scan active nodes over a specified IP range. The IP range format should be a format that is acceptable by `nmap`.

The `bmcdiscover` command can also obtain some information about the BMC. (Check username/password, IP address source, DHCP/static configuration)

Note: The scan method currently supports `nmap`.

OPTIONS

--range

Specify one or more IP ranges acceptable to nmap. IP range can be hostnames, IP addresses, networks, etc. A single IP address (10.1.2.3), several IPs with commas (10.1.2.3,10.1.2.10), Ip range with “-” (10.1.2.0-100) or an IP range (10.1.2.0/24) can be specified. If the range is very large, the `bmcdiscover` command may take a long time to return.
--sn
Specify one or more service nodes on which bmcdiscover will run. In hierarchical cluster, the MN may not be able to access the BMC of CN directly, but SN can. With this option, bmcdiscover will be dispatched to the specified SNs. Then, the nodename of the service node that `bmcdiscover` is running on will be set to the `servicenode` attribute of the discovered BMC node.

-s
Scan method (The only supported scan method at this time is nmap)

-z
List the data returned in xCAT stanza format

-w
Write to the xCAT database.

-il--bmcip
BMC IP address.

-ul--bmcuser
BMC user name.

-pl--bmcpasswd
BMC user password.

-h|--help
Display usage message

-v|--version
Display version information

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To get all responding BMCs from IP range “10.4.23.100-254” and 50.3.15.1-2”:

```bash
bmcdiscover -s nmap --range "10.4.23.100-254  50.3.15.1-2"
```

Note: Input for IP range can be in the form: scanme.nmap.org, microsoft.com/24, 192.168.0.1; 10.0.0-255.1-254.

2. To get all BMCs in IP range “10.4.22-23.100-254”, displayed in xCAT stanza format:

```bash
bmcdiscover -s nmap --range "10.4.22-23.100-254" -z
```

3. To discover BMCs through sn01:

```bash
bmcdiscover --sn sn01 -s nmap --range "10.4.22-23.100-254" -z
```

Output is similar to:
4. Discover the BMCs and write the discovered-node definitions into the xCAT database and write out the stanza format to the console:

```
bmcdiscover -s nmap --range "10.4.22-23.100-254" -w -z
```

SEE ALSO

lsslp(1)|lsslp.1

buildkit.1

NAME

buildkit - Used to build a software product Kit which may be used to install software in an xCAT cluster.

SYNOPSIS

```
buildkit [-? | -h | --help] [-v | --version]
To build a new Kit
buildkit [-V | --verbose] subcommand [kit_name] [repo_name | all] [-l | --kitloc kit_location]
To add packages to an existing Kit.
```

DESCRIPTION

The buildkit command provides a collection of utilities that may be used to package a software product as a Kit tarfile that can be used to install software on the nodes of an xCAT cluster. A Kit contains the product software packages, configuration and control information, and install and customization scripts.

Note: The xCAT support for Kits is only available for Linux operating systems.

You will need to run the buildkit command several times with different subcommands to step through the process of building a kit:

By default the buildkit subcommands will operate in the current working directory, (ie. look for files, create directories etc.). You could specify a different location by using the “-l --kitloc kit_location” option.

The kit_location is the full path name of the directory that contains the kit files. You would use the same location value for all the buildkit subcommands.
For example, to create a new kit named “prodkit” in the directory /home/mykits/ either run:

1. If no location is provided then the command will create a subdirectory called “prodkit” in the current directory “/home/mykits” and the new kit files will be created there.

   cd /home/mykits
   buildkit create prodkit

   or

2. If a location is provided then the Kit files will be created there. Note that the Kit name does not necessarily have to be the directory name where the kit files are located.

   buildkit create prodkit -l /home/mykits/prodkit

In both cases the /home/mykits/prodkit directory is created and the initial files for the kit are created in that directory.

The following example illustrates the basic process for building a new Kit. In this example we are building a Kit named “mytstkit”.

1. Change to the directory where you wish to create the Kit.
2. Create a template directory for your kit:

   buildkit create mytstkit

3. Change directory to the new “mytstkit” subdirectory that was just created.

   cd mytstkit

4. Edit the buildkit configuration file for your kit:

   vi buildkit.conf

   (See xCAT Kit documentation for details.)

5. Create all required files, scripts, plugins, and packages for your kit.
6. Validate your kit build configuration and fix any errors that are reported:

   buildkit chkconfig

7. List the repos defined in your buildkit configuration file:

   buildkit listrepo

8. For each repo name listed, build the repository. Note that if you need to build repositories for OS distributions, versions, or architectures that do not match the current system, you may need to copy your kit template directory to an appropriate server to build that repository, and then copy the results back to your main build server. For example, to build a repo named “rhels6.3” you would run the following command.

   buildkit builddrepo rhels6.3

   or, you can build all of the repos at one time if there are no OS or architecture dependencies for kitcomponent package builds or kitpackage builds:

   buildkit builddrepo all

9. Build the kit tar file:

   buildkit buildtar
OPTIONS

- **-h**|--help
  Display usage message.

- **-k|--kitversion** *version*
  Product version.

- **-l|--kitloc** *kit_location*
  The directory location of the Kit files.

- **-p|--pkgdir** *package_directory_list*
  A comma-separated list of directory locations for product RPMs.

- **-r|--kitrelease** *release*
  Product release.

- **-V|--verbose**
  Verbose mode.

- **-v|--version**
  Command version.

SUB-COMMANDS

**create** *kit_basename*

Creates a new kit build directory structure for kit *kit_basename* using the location specified on the command line or the current directory. The sample kit files from /opt/xcat/share/xcat/kits/kit_template are copied over, and the buildkit.conf file is modified for the specified *kit_basename*.

**chkconfig**

Reads the buildkit.conf file, verifies that the file syntax is correct and that all specified files exist.

**listrepo**

Reads the buildkit.conf file, lists all Kit package repositories listed in the file, and reports the build status for each repository.

**buildrepo** { *repo_name* | all }

Reads the buildkit.conf file, and builds the specified Kit package repository. The built packages are placed in the directory *kit_location*/build/kit_repodir/*repo_name*. If all is specified, all kit repositories are built.

**cleanrepo** { *repo_name* | all }

Reads the buildkit.conf file, and deletes all the package files and package meta data files from the *kit_location*/build/kit_repodir/*repo_name* directory. If all is specified, all kit repository files are deleted.

**buildtar**

Reads the buildkit.conf file, validates that all kit repositories have been built, and builds the Kit tar file *kit_location*/kitname.tar.bz2.

**cleantar**
Reads the <kit_location>/buildkit.conf file and deletes the following:

- Kit tar files matching <kit_location>/kit_name.tar.bz2*.
- <kit_location>/build/kit_name
- <kit_location>/rpmbuild
- <kit_location>/tmp
- <kit_location>/debuild

Caution: Make sure you back up any tar files you would like to keep before running this subcommand.

**cleanall**

Equivalent to running `buildkit cleanrepo all` and `buildkit cleantar`.

**addpkgs**

```
kit_tarfile [p | --pkgdir package_directory_list] [-k | --kitversion version] [-r | --kitrelease release]
```

Add product package rpms to a previously built kit tar file. This is used for partial product kits that are built and shipped separately from the product packages, and are identified with a `kit_tarfile` name of `kitname.NEED_PRODUCT_PKGS.tar.bz2`. Optionally, change the kit release and version values when building the new kit tarfile. If kitcomponent version and/or release values are defaulted to the kit values, those will also be changed and new kitcomponent rpms will be built. If kit or kitcomponent scripts, plugins, or other files specify name, release, or version substitution strings, these will all be replaced with the new values when built into the new complete kit tarfile `kit_location/new_kitname.tar.bz2`.

**RETURN VALUE**

- `<B>0`
  The command completed successfully.
- `<B>1`
  An error has occurred.

**EXAMPLES**

1. To create the sample kit shipped with the xCAT-buildkit rpm on a RHELS 6.3 server and naming it `mykit`, run the following commands:
   ```
   cd /home/myuserid/kits
   buildkit create mykit
   cd mykit
   vi buildkit.conf
   buildkit chkconfig
   buildkit listrepo
   buildkit buildrepo all
   buildkit buildtar
   ```
2. To clean up a kit repository directory after build failures on a RHEL 6.3 server to prepare for a new kit repository build, run:
   `buildkit cleanrepo rhels6.3`

3. To clean up all kit build files, including a previously built kit tar file, run
   `buildkit cleanall`

4. To create a kit named “tstkit” located in /home/foobar/tstkit instead of the current working directory.
   `buildkit create tstkit -l /home/foobar/tstkit`

**FILES**

```
/opt/xcat/bin/buildkit
/opt/xcat/share/xcat/kits/kit_template
/opt/xcat/share/xcat/kits/kitcomponent.spec.template
<kit location>/buildkit.conf
<kit location>/kitname/kit.conf
<kit location>/kitname.tar.bz2
```

**SEE ALSO**

addkit(1), lskit(1), rmkit(1), addkitcomp(1), rmkitcomp(1), chkkitcomp(1)

**cfgve.1**

**NAME**

`cfgve` - Configure the elements for a virtual environment.

**SYNOPSIS**

```
cfgve -t dc -m manager -o object [-c -k nfs | localfs | -r]
cfgve -t cl -m manager -o object [-c -p cpu type | -r -f]
cfgve -t sd -m manager -o object [-c | -g | -s | -a | -b | -r -f]
cfgve -t nw -m manager -o object [-c -d data center -n vlan ID | -a -l cluster | -b | -r]
cfgve -t tpl -m manager -o object [-r]
```

**DESCRIPTION**

The `cfgve` command can be used to configure a virtual environment for ‘Storage Domain’, ‘Network’ and ‘Template’ objects.

The mandatory parameter `-m manager` is used to specify the address of the manager of virtual environment. xCAT needs it to access the RHEV manager.
The mandatory parameter `-t type` is used to specify the type of the target object.

Basically, `cfgve` command supports five types of object: `dc`, `cl`, `sd`, `nw` and `tpl`.

- **dc**: The `create` and `remove` operations are supported.
- **cl**: The `create` and `remove` operations are supported.
- **sd**: The `create`, `attach`, `detach`, `activate`, `deactivate` and `remove` operations are supported.
- **nw**: The `create`, `attach`, `detach` and `remove` operations are supported.
- **tpl**: The `remove` operation is supported.

The mandatory parameter `-o object` is used to specify which object to configure.

**OPTIONS**

- `-a` To attach the target object.
- `-b` To detach the target object.
- `-c` To create the target object.

For creating of `Storage Domain`, the target storage domain will be created first, then attached to data center and activated.

The parameters that used to create the storage domain are gotten from ‘virtsd’ table. The detail parameters in the virtsd table:

- **virtsd.node** - The name of the storage domain.
- **virtsd.sdtype** - The type of storage domain. Valid value: data, iso, export. Default value is ‘data’.
- **virtsd.stype** - The storage type. “nfs” or “localfs”.
- **virtsd.location** - The location of the storage. nfs: Format: [nfsserver:nfspath]. The NFS export directory must be configured for read write access and must be owned by vdsm:kvm. localfs: “/data/images/rhev” is set by default.
- **virtsd.host** - A host must be specified for a storage domain as SPM (Storage Pool Manager) when initialize the storage domain. The role of SPM may be migrated to other host by rhev-m during the running of the datacenter (For example, when the current SPM encountered issue or going to maintenance status.
- **virtsd.datacenter** - The storage will be attached to. ‘Default’ data center is the default value.

- `-d data center`

  The name of data center.

  Specify the ‘Data Center’ that will be used for the object to be attached to. It is used by `<nw>` type.

- `-f` It can be used with `-r` to remove the target object by force.

  For removing of `Storage Domain`, if `-f` is specified, the storage domain will be deactivated and detached from data center before the removing.

- `-g` To activate the target object.

- `-h` Display usage message.

- `-k storage type`

  To specify the type of the storage type when creating the data center.

  Supported type: nfs; localfs.
-l cluster
   Specify the cluster for the network to attach to.

-m manager
   Specify the manager of the virtual environment.
   For RHEV, the FQDN (Fully Qualified Domain Name) of the rhev manager have to be specified.

-n vlan ID
   To specify the vlan number when creating a network.

-o object
   The name of the target object.

-p cpu type
   To specify the cpu type when creating the cluster. Intel Penryn Family is default type.
   Supported type: Intel Conroe Family, Intel Penryn Family, Intel Nehalem Family, Intel Westmere Family, AMD Opteron G1, AMD Opteron G2, AMD Opteron G3

-r To remove the target object.
   For removing of Storage Domain, the storage space will be formatted after removing.

-s To deactivate the target object.

-t type
   Specify the type of the target object.
   Supported types: dc - Data Center cl - Cluster sd - Storage Domain nw - Network tpl - Template

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To create the Storage Domain ‘sd1’, enter:

   ```
   cfgve -t sd -m <FQDN of rhev manager> -o sd1 -c
   ```

2. To deactivate the Storage Domain ‘sd1’ from data center, enter:

   ```
   cfgve -t sd -m <FQDN of rhev manager> -o sd1 -s
   ```

3. To remove the Storage Domain ‘sd1’, enter:

   ```
   cfgve -t sd -m <FQDN of rhev manager> -o sd1 -r
   ```

4. To create the network ‘nw1’, enter:

   ```
   cfgve -t nw -m <FQDN of rhev manager> -o nw1 -c
   ```

5. To remove the template ‘tpl01’, enter:
**FILES**

```
/opt/xcat/bin/cfgve
```

**SEE ALSO**

lsve(1) | lsve.1

cfm2xcat.1

**NAME**

cfm2xcat - Migrates the CFM setup in CSM to the xdcp rsync setup in xCAT.

**SYNOPSIS**

```
cfm2xcat [-i path of the CFM distribution files generated] [-o path of the xdcp rsync files generated from the CFM distribution files]
cfm2xcat [-h]
```

**DESCRIPTION**

Copy the cfm2xcat command to the CSM Management Server. Run the command, indicating where you want your files saved with the -i and -o flags. They can be in the same directory.

The cfm2xcat command will run cfmupdatenode -a, saving the generated CFM distribution files in the directory indicates with (-i). From those distribution files, it will generate xdcp rsync input files (-F option on xdcp) in the directory indicated by (-o).

Check the rsync files generated. There will be a file generated (rsyncfiles) from the input -o option on the command, and the same file with a (.nr) extension generated for each different noderange that will used to sync files based on your CFM setup in CSM. The rsyncfiles will contain the rsync file list. The rsyncfiles.nr will contain the noderange. If multiple noderanges then the file name (rsyncfiles) will be appended with a number.

**OPTIONS**

- `-h` Display usage message.
- `-i` Path of the CFM distribution files generated from the cfmupdatenode -a command.
- `-o` Path of the xdcp rsync input file generated from the CFM distribution files.
RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To build xCAT rsync files to use with xdcpg -F, enter on the CSM Management Server, make sure the path exists:

```
cfm2xcat -i /tmp/cfm/cfmdistfiles -o /tmp/cfm/rsyncfiles
```

2. To use the file on the xCAT Management Node copy to /tmp/cfm on the xCAT MN:

```
xdcp ^/tmp/cfm/rsyncfiles.nr -F /tmp/cfm/rsyncfiles
xdcp ^/tmp/cfm/rsyncfiles.nr1 -F /tmp/cfm/rsyncfiles1
xdcp ^/tmp/cfm/rsyncfiles.nr2 -F /tmp/cfm/rsyncfiles2
```

FILES

```
/opt/xcat/share/xcat/tools/cfm2xcat
```

chdef.1

NAME

chdef - Change xCAT data object definitions.

SYNOPSIS

```
chdef [-h | --help] [-t object-types]
chdef [-t object-types] [-o object-names] [-n new-name] [node]
```

DESCRIPTION

This command is used to change xCAT object definitions which are stored in the xCAT database. The default is to replace any existing attribute value with the one specified on the command line. The command will also create a new definition if one doesn’t exist.

This command also can be used to change the xCAT object name to a new name. Note: the site, monitoring types can NOT be supported.
OPTIONS

attr=val [attr=val ...]
   Specifies one or more “attribute equals value” pairs, separated by spaces. Attr=val pairs must be specified last on the command line. Use the help option to get a list of valid attributes for each object type.

-dl--dynamic
   Use the dynamic option to change dynamic node groups definition. This option must be used with -w option.

-hl--help
   Display usage message.

-ml--minus
   If the value of the attribute is a list then this option may be used to remove one or more items from the list.

-n new-name
   Change the current object name to the new-name which is specified by the -n option. Objects of type site, group and monitoring cannot be renamed with the -n option. Note: For the -n option, only one node can be specified. For some special nodes such as fsp, bpa, frame, cec etc., their name is referenced in their own hcp attribute, or the hcp attribute of other nodes. If you use -n option, you must manually change all hcp attributes that refer to this name.

noderange
   A set of comma delimited node names and/or group names. (must be the first parameter) See the “noderange” man page for details on supported formats.

-o object-names
   A set of comma delimited object names.

-pl--plus
   This option will add the specified values to the existing value of the attribute. It will create a comma-separated list of values.

-t object-types
   A set of comma delimited object types. Use the help option to get a list of valid object types.

-Vl--verbose
   Verbose mode.

-w attr==val -w attr!=val ...
   Use one or multiple -w flags to specify the selection string that can be used to select objects. The operators ==, !=, =~ and !~ are available. Use the help option to get a list of valid attributes for each object type.

   **Operator descriptions:**
   == Select nodes where the attribute value is exactly this value. != Select nodes where the attribute value is not this specific value. =~ Select nodes where the attribute value matches this regular expression. !~ Select nodes where the attribute value does not match this regular expression.

   Note: the operator !~ will be parsed by shell, if you want to use !~ in the selection string, use single quote instead. For example:-w ‘mgt!~ipmi’.

-zl--stanza
Indicates that the file being piped to the command is in stanza format. See the xcatstanzafile man page for details on using xCAT stanza files.

-\u

Fill in the attributes such as template file, pkglst file and otherpkglst file of osimage object based on the specified parameters. It will search “/install/custom/” directory first, and then “/opt/xcat/share/”.

Note: this option only works for objtype osimage.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.

**EXAMPLES**

1. To change a site definition.

   chdef -t site -o clustersite installdir=/xcatinstall

2. To change a basic node definition.

   chdef -t node -o node01 groups="all,aix"

   (The group definitions are also created if they don’t already exist.)

3. To add another group to the “groups” attribute in the previous example.

   chdef -p -t node -o node01 groups="compute"

4. To remove the “all” group from the “groups” attribute in the previous example.

   chdef -m -t node -o node01 groups="all"

5. To replace the current “groups” attribute value of “node01”.

   chdef -t node -o node01 groups="linux"

6. To add “node01” to the “members” attribute of a group definition called “LinuxNodes”.

   chdef -p -t group -o LinuxNodes members="node01"

7. To update a set of definitions based on information contained in the stanza file mystanzafile.

   cat mystanzafile | chdef -z

8. To update a dynamic node group definition to add the cons=hmc wherevals pair.

   chdef -t group -o dyngp -d -p -w cons==hmc

9. To change the node object name from node1 to node2.

   chdef -t node -o node1 -n node2

10. To change the node hwtype, this command will change the value of ppc.nodetype.
11. To change the policy table for policy number 7.0 for admin1
   chdef -t policy -o 7.0 name=admin1 rule=allow

12. To change the node nic attributes
   chdef -t node -o cn1 nicips.eth0="1.1.1.1|1.2.1.1" nicnetworks.eth0="net1|net2"
   nictypes.eth0="Ethernet"

13. To update an osimage definition.
   chdef redhat6img -u provmethod=install

FILES

$XCATROOT/bin/chdef
(The XCATROOT environment variable is set when xCAT is installed. The default value is “/opt/xcat”.)

NOTES

This command is part of the xCAT software product.

SEE ALSO

mkdef(1)|mkdef.1, lsdef(1)|lsdef.1, rmdef(1)|rmdef.1, xcatstanzafile(5)|xcatstanzafile.5

chhypervisor.1

NAME

chhypervisor - Configure the virtualization hosts.

SYNOPSIS

RHEV specific :
chhypervisor noderange [-a]
chhypervisor noderange [-n]
chhypervisor noderange [-p]
chhypervisor noderange [-e]
chhypervisor noderange [-d]

zVM specific :
chhypervisor noderange [--adddisk2pool function region volume group]
chhypervisor noderange [--addscsi device_number device_path option persist]
chhypervisor noderange [--addvlan name owner type transport]
chhypervisor noderange [--addvswitch name osa_dev_addr osa_exp_adapter controller connect (0, 1, or 2) memory_queue router transport vlan_id port_type update gvrp native_vlan]
chhypervisor noderange [--addzfcp2pool pool status wwpn lun size owner]
chhypervisor noderange [--removediskfrompool function region group]
chhypervisor noderange [--removescsi device_number persist (YES or NO)]
chhypervisor noderange [--removevlan name owner]
chhypervisor noderange [--removevswitch name]
chhypervisor noderange [--removezfcpfrompool pool lun wwpn]
chhypervisor noderange [--smcli function arguments]

DESCRIPTION

The `chhypervisor` command can be used to configure the RHEV-h.

The rhev-h host will register to the rhev-m automatically, but admin needs to approve the host can be added to the ‘cluster’ with `-a` flag.

After registering, the network interfaces of host need to be added to the ‘network’ of RHEV. And the power management for the host should be configured so that rhev-m could make proper decision when certain host encountered error.

The `chhypervisor` command can also be used to configure the zVM host.

For each host, an entry should be added to the hypervisor table:

The columns of hypervisor table:

`hypervisor.node` - rhev-h host name or zVM host name (lower-case).

`hypervisor.type` - Must be set to ‘rhev’ or ‘zvm’.

`hypervisor.mgr` - The rhev manager (The FQDN of rhev-m server) for the host.

`hypervisor.interface` - The configuration for the nics. Refer to `-n`.

`hypervisor.cluster` - The cluster that the host will be added to. The default is ‘Default’ cluster if not specified.

OPTIONS

RHEV specific:

- `a` Approve the host that to be added to cluster.
  
  Before approve, the status of the host must be ‘pending_approval’.

- `n` Configure the network interfaces for the host.
  
  Note: This operation only can be run when host is in ‘maintenance mode’. Use `-d` to switch the host to ‘maintenance’ mode.

  The interfaces which configured in hypervisor.interface will be added to the network of RHEV.
The format of hypervisor.interface is multiple [network:interfacename: protocol:IP:netmask:gateway] sections separated with ‘|’. For example: [rhevm2:eth0:static:10.1.0.236:255.255.255.0:0.0.0.0].

- **network** - The logic network which has been created by ‘cfgve -t nw’ or the default management network ‘rhevm’.
- **interfacename** - Physical network name: ‘eth0’, ‘eth1’…
- **protocol** - To identify which boot protocol to use for the interface: dhcp or static.
- **IP** - The IP address for the interface.
- **netmask** - The network mask for the interface.
- **gateway** - The gateway for the interface. This field only can be set when the interface is added to ‘rhevm’ network.

- **-p** Configure the power management for the host.

The power management must be configured for the rhev-h host to make the rhev-m to monitor the power status of the host, so that when certain host failed to function, rhev-m will fail over certain role like SPM to other active host.

For rack mounted server, the bmc IP and user:password need to be set for the power management (These parameters are gotten from ipmi table). rhev-m uses the ipmi protocol to get the power status of the host.

- **-e** To activate the host.
- **-d** To deactivate the host to maintenance mode.
- **-h** Display usage message.

**zVM specific:**

- **--adddisk2pool function region volume group**
  Add a disk to a disk pool defined in the EXTENT CONTROL. Function type can be either: (4) Define region as full volume and add to group OR (5) Add existing region to group. If the volume already exists in the EXTENT CONTROL, use function 5. If the volume does not exist in the EXTENT CONTROL, but is attached to SYSTEM, use function 4.

- **--addscsi device_number device_path option persist**
  Dynamically add a SCSI disk to a running z/VM system.

- **--addvlan name owner type transport**
  Create a virtual network LAN.

- **--addvswitch name osa_dev_addr osa_exp_adapter controller connect (0, 1, or 2) memory_queue router transport vlan_id port_type update gvrp native_vlan**
  Create a virtual switch.

- **--addzfcp2pool pool status wwpn lun size owner**
  Add a zFCP device to a device pool defined in xCAT. The device must have been carved up in the storage controller and configured with a WWPN/LUN before it can be added to the xCAT storage pool. z/VM does not have the ability to communicate directly with the storage controller to carve up disks dynamically.

- **--removediskfrompool function region group**
Remove a disk from a disk pool defined in the EXTENT CONTROL. Function type can be either: (1) Remove region, (2) Remove region from group, (3) Remove region from all groups, OR (7) Remove entire group.

--removescsi device_number persist (YES or NO)
Delete a real SCSI disk.

--removevlan name owner
Delete a virtual network LAN.

--removevswitch name
Delete a virtual switch.

--removezfcpfrompool pool lun
Remove a zFCP device from a device pool defined in xCAT.

--smcli function arguments
Execute a SMAPI function. A list of APIs supported can be found by using the help flag, e.g. chhypervisor pokdev61 --smcli -h. Specific arguments associated with a SMAPI function can be found by using the help flag for the function, e.g. chhypervisor pokdev61 --smcli Image_Query_DM -h. Only z/VM 6.2 and older SMAPI functions are supported at this time. Additional SMAPI functions will be added in subsequent zHCP versions.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

RHEV specific:

1. To approve the host ‘host1’, enter:

   chhypervisor host1 -a

2. To configure the network interface for the host ‘host1’, enter:

   chhypervisor host1 -n

3. To configure the power management for the host ‘host1’, enter:

   chhypervisor host1 -p

4. To activate the host ‘host1’, enter:

   chhypervisor host1 -e

5. To deactivate the host ‘host1’, enter:

   chhypervisor host1 -d
zVM specific:

1. To add a disk to a disk pool defined in the EXTENT CONTROL, enter:
   ```
   chhypervisor pokdev61 --adddisk2pool 4 DM1234 DM1234 POOL1
   ```

2. To add a zFCP device to a device pool defined in xCAT, enter:
   ```
   chhypervisor pokdev61 --addzfcp2pool zfcp1 free 500501234567C890
   ```
   ```
   → 4012345600000000 8G
   ```

3. To remove a region from a group in the EXTENT CONTROL, enter:
   ```
   chhypervisor pokdev61 --removediskfrompool 2 DM1234 POOL1
   ```

4. To remove a zFCP device from a device pool defined in xCAT, enter:
   ```
   chhypervisor pokdev61 --removezfcpfrompool zfcp1 4012345600000000
   ```
   ```
   → 500501234567C890
   ```

5. To execute a SMAPI function (Image_Query_DM), enter:
   ```
   chhypervisor pokdev61 --smcli Image_Query_DM -T LNX3
   ```

**FILES**

`/opt/xcat/bin/chhypervisor`

chkkitcomp.1

**NAME**

chkkitcomp - Check if Kit components are compatible with an xCAT osimage.

**SYNOPSIS**

chkkitcomp [-? | -h | --help] [-v | --version]

chkkitcomp [-V | --verbose] -i osimage kitcompname_list

**DESCRIPTION**

The chkkitcomp command will check if the kit components are compatible with the xCAT osimage.

This command will ignore the current osimage.kitcomponents setting and check if the kitcompname_list is compatible with the osimage and kit component dependencies.

Note: xCAT Kit support is ONLY available for Linux operating systems.
OPTIONS

-\(\text{-h|--help}\)
  Display usage message.

-\(\text{-V|--verbose}\)
  Verbose mode.

-\(\text{-v|--version}\)
  Command version.

-\(i\) \text{osimage}
  The name of the osimage to check against.

\text{kitcompname_list}
  A comma-delimited list of valid full kit component names or kit component basenames that are to be
  checked against the osimage.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To check if a kit component, \text{comp-test1-1.0-1-rhels-6.2-ppc64} can be added to osimage \text{rhels6.2-ppc64-
netboot-compute}:

\begin{verbatim}
chkkitcomp -i rhels6.2-ppc64-netboot-compute comp-test1-1.0-1-rhels-6.2-ppc64
\end{verbatim}

SEE ALSO

\text{liskit(1)|liskit.1, addkit(1)|addkit.1, rmkit(1)|rmkit.1, addkitcomp(1)|addkitcomp.1, rmkitcomp(1)|rmkitcomp.1}

\text{chkosimage.1}

NAME

\text{chkosimage} - Use this xCAT command to check an xCAT osimage.

SYNOPSIS

\text{chkosimage [-h|--help]}
\text{chkosimage [-V|--clean] osimage_name}
DESCRIPTION

This command is currently supported for AIX osimages only.

Use this command to verify if the NIM lpp_source directories contain the correct software. The lpp_source directory must contain all the software that is specified in the “installp_bundle” and “otherpkgs” attributes of the osimage definition.

The command gets the name of the lpp_source resource from the xCAT osimage definition and the location of the lpp_source directory from the NIM resource definition.

It will check for installp, rpm and emgr type packages.

Note: Remember to use the prefixes, “I:”, “R:”, and “E:”, respectively, when specifying package names in an installp_bundle file or an otherpkgs list.

In addition to checking for missing software the chkosimage command will also check to see if there are multiple matches. This could happen when you use wildcards in the software file names. For example, if you have perl-xCAT* in a bundle file it could match multiple versions of the xCAT rpm package saved in your lpp_source directory.

If this happens you must remove the unwanted versions of the rpms. If the extra rpms are not removed you will get install errors.

To help with this process you can use the “-c|--clean” option. This option will keep the rpm package with the most recent timestamp and remove the others.

The chkosimage command should always be used to verify the lpp_source content before using the osimage to install any AIX cluster nodes.

OPTIONS

-c |--clean
Remove any older versions of the rpms. Keep the version with the latest timestamp.

-h |--help
Display usage message.

osimage_name
The name of the xCAT for AIX osimage definition.

-V |--verbose
Verbose mode.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. Check the XCAT osimage called “61image” to verify that the lpp_source directories contain all the software that is specified in the “installp_bundle” and “otherpkgs” attributes.
2. Clean up the lpp_source directory for the osimage named “61img” by removing any older rpms with the same names but different versions.

```
chkosimage -c 61img
```

**FILES**

```
/opt/xcat/bin/chkosimage
```

**NOTES**

This command is part of the xCAT software product.

**SEE ALSO**

mknimimage(1)|mknimimage.1

**NAME**

`chvlan` - It adds or removes nodes for the vlan.

**SYNOPSIS**

```
chvlan
vlanid  -n | --nodes noderange [-i | --interface nic]
chvlan
vlanid  -n | --nodes noderange  -d | --delete
chvlan
   [-h | --help]
chvlan
   [-v | --version]
```

**DESCRIPTION**

The `chvlan` command adds nodes to the given vlan. If `-d` is specified, the nodes will be removed from the vlan.

For added security, the root guard and bpdu guard will be enabled for the ports added to this vlan. However, the guards will not be disabled if the ports are removed from the vlan using chvlan (-d) or rmvlan commands. To disable them, you need to use the switch command line interface. Please refer to the switch command line interface manual to see how to disable the root guard and bpdu guard for a port.

**Parameters**

`vlanid` is a unique vlan number.
OPTIONS

-n|--nodes The nodes or groups to be added or removed. It can be stand alone nodes or KVM guests. It takes the noderange format. Please check the man page for noderange for details.

-i|--interface (For adding only). The interface name where the vlan will be tagged on. If omitted, the xCAT management network will be assumed. For KVM, it is the interface name on the host.

-h|--help Display usage message.

-v|--version The Command Version.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To add node1, node2 and node3 to vlan 3.

   chvlan 3 -n node1,node2,node3

2. To add node1, node2 and node3 to vlan 3 using eth1 interface.

   chvlan 3 -n node1,node2,node3 -i eth1

3. TO remove node1, node2 and node3 from vlan 3.

   chvlan -n node1,node2,node3 -d

4. To add KVM guests node1 and node2 to vlan 3

   mkdef node1 arch=x86_64 groups=kvm,all installnic=mac primarynic=mac mgt=kvm
   → netboot=pxe nfsserver=10.1.0.204 os=rhels6 profile=compute provmethod=install
   → serialport=0 serialspeed=115200 vmcpus=1 vmhost=x3650n01 vmmemory=512
   → vmnics=br0 vmstorage=nfs://10.1.0.203/vms

   mkdef node2 arch=x86_64 groups=kvm,all installnic=mac primarynic=mac mgt=kvm
   → netboot=pxe nfsserver=10.1.0.204 os=rhels6 profile=compute provmethod=install
   → serialport=0 serialspeed=115200 vmcpus=1 vmhost=x3650n01 vmmemory=512
   → vmnics=br0 vmstorage=nfs://10.1.0.203/vms

   chvlan 3 -n node1,node2

   mkvm node1,node2 -s 20G

   rpower node1,node2 on

   rinstall node1,node2

5. To remove KVM guests node1 and node2 from vlan 3
**NAME**

chvlanports - It adds or removes nodes’ switch interfaces for the vlan.

**SYNOPSIS**

chvlanports \( vlanid \) \( -n \) | \(--nodes \) \( noderange \) \( -i \) | \(--interface \) \( nic \)
chvlanports \( vlanid \) \( -n \) | \(--nodes \) \( noderange \) \( -i \) | \(--interface \) \( nic \) \( -d \) | \(--delete \)
chvlanports \([-h \) | \|--help \]
chvlanports \( -v \) | \|--version \]

**DESCRIPTION**

The **chvlanports** command adds nodes switch interfaces to the given vlan. If **-d** is specified, the nodes switch interfaces will be removed from the vlan.

This command won’t create/remove vlans on switches, it just add node’s switch ports into existing vlan or remove them from existing vlan on switch. Before calling chvlanports, the nodes switch interfaces should be configured in table switch, and vlan must already existing in switches. =head1 Parameters

\( vlanid \) is a unique vlan number.

**OPTIONS**

\(-n\) | \(--nodes\) The nodes or groups to be added or removed. It takes the noderange format. Check the man page for noderange for details.

\(-i\) | \(--interface\) The interface name where the vlan will be tagged on.

\(-h\) | \(--help\) Display usage message.

\(-v\) | \(--version\) The Command Version.
**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.

**EXAMPLES**

1. To add node1, node2 and node3 to vlan 3 using eth1 interface.
   
   ```
   chvlanports 3 -n node1,node2,node3 -i eth1
   ```

2. To remove eth1 interface of node1, node2 and node3 from vlan 3.
   
   ```
   chvlanports 3 -n node1,node2,node3 -i eth1 -d
   ```

**FILES**

```
/opt/xcat/bin/chvlanports
```

**SEE ALSO**

mkvlan(1)|mkvlan.1, rmvlan(1)|rmvlan.1, lsvlan(1)|lsvlan.1, chvlan(1)|chvlan.1

chvm.1

**NAME**

**chvm** - Changes HMC-, DFM-, IVM-, and zVM-managed partition profiles or virtual machines. For Power 775, chvm could be used to change the octant configuration values for generating LPARs; change the I/O slots assignment to LPARs within the same CEC.

**SYNOPSIS**

```
chvm [-h|--help]
chvm [-v|--version]
```

**PPC (with HMC) specific:**

```
chvm [-V|--verbose] noderange [-p profile]
chvm [-V|--verbose] noderange attr=val [attr=val...]
```
**PPC (using Direct FSP Management) specific:**

```bash
chvm noderange --p775 [-p profile]
chvm noderange --p775 -i id [-m memory_interleaving] -r partition_rule
chvm noderange [parname]=[* | name]
chvm noderange [vmcpus= min/req/max] [vmmemory= min/req/max] [vmothersetting=hugepage:N,bsr:N]
[chadd_physlots= drc_index1,drc_index2... ] [add_vmnics= vlan1,vlan2... ] [add_vmstorage=<N|viosnode:slotid>]
[--vios] [del_physlots= drc_index1,drc_index2... ] [del_vadapter= slotid]
```

**KVM specific:**

```bash
chvm noderange [-cpupin hostcpuset]
chvm noderange [--membind numanodeset]
chvm noderange [--devpassthru pcidevice... ]
chvm noderange [--devdetach pcidevice... ]
```

**VMware/KVM specific:**

```bash
```

**zVM specific:**

```bash
chvm noderange [--add3390 disk_pool device_address size mode read_password write_password multi_password]
chvm noderange [--add3390active device_address mode]
chvm noderange [--add9336 disk_pool device_address size mode read_password write_password multi_password]
chvm noderange [--adddisk2pool function region volume group]
chvm noderange [--addnic device_address type device_count]
chvm noderange [--addpagespool volume_address volume_label volume_use system_config_name system_config_type parm_disk_owner parm_disk_number parm_disk_password]
chvm noderange [--addprocessor device_address]
chvm noderange [--addprocessoractive device_address type]
chvm noderange [--addvdisk device_address size]
chvm noderange [--addzfcp pool device_address loaddev size tag wwpn lun]
chvm noderange [--connectnic2guestlan device_address lan owner]
chvm noderange [--connectnic2vswitch device_address vswitch]
chvm noderange [--copydisk target_address source_node source_address]
chvm noderange [--dedicatedevice virtual_device real_device mode]
chvm noderange [--deleteipl]
chvm noderange [--disconnectnic device_address]
chvm noderange [--formatdisk device_address multi_password]
```
chvm noderange [--grantvswitch vsswitch]
chvm noderange [--purgerdr]
chvm noderange [--removedisk device_address]
chvm noderange [--removenenic device_address]
chvm noderange [--removeprocessor device_address]
chvm noderange [--removeloaddev wwpn lun]
chvm noderange [--removezfcp device_address wwpn lun]
chvm noderange [--replacevs directory_entry]
chvm noderange [--setipl ipl_target load_parms parms]
chvm noderange [--setpassword password]
chvm noderange [--setloaddev wwpn lun]
chvm noderange [--sharevolume volume_address share_enable]
chvm noderange [--undedicatedevice device_address]

DESCRIPTION

PPC (with HMC) specific:

The chvm command modifies the partition profile for the partitions specified in noderange. A partition's current profile can be read using lsvm, modified, and piped into the chvm command, or changed with the -p flag.

This command also supports changing specific partition attributes by specifying one or more “attribute equals value” pairs in command line directly, without whole partition profile.

PPC (using Direct FSP Management) specific:

For Power 755 (use option –p775 to specify):

chvm could be used to change the octant configuration values for generating LPARs. chvm is designed to set the Octant configure value to split the CPU and memory for partitions, and set Octant Memory interleaving value. The chvm will only set the pending attributes value. After chvm, the CEC needs to be rebooted manually for the pending values to be enabled. Before reboot the cec, the administrator can use chvm to change the partition plan. If the partition needs I/O slots, the administrator should use chvm to assign the I/O slots.

chvm is also designed to assign the I/O slots to the new LPAR. Both the current IO owning lpar and the new IO owning lpar must be powered off before an IO assignment. Otherwise, if the I/O slot is belonged to an Lpar and the LPAR is power on, the command will return an error when trying to assign that slot to a different lpar.

The administrator should use lsvm to get the profile content, and then edit the content, and add the node name with “:” manually before the I/O which will be assigned to the node. And then the profile can be piped into the chvm command, or changed with the -p flag.

For normal power machine:

chvm could be used to modify the resources assigned to partitions. The admin shall specify the attributes with options vncpus, vmmemory, add_physlots, vmothersetting, add_vmnics and/or add_vmstorage. If nothing specified, nothing will be returned.
zVM specific:

The chvm command modifies the virtual machine’s configuration specified in noderange.

OPTIONS

Common:

-h
   Display usage message.

-v
   Command Version.

PPC (with HMC) specific:

-p profile
   Name of an existing partition profile.

attr=val
   Specifies one or more “attribute equals value” pairs, separated by spaces.

-V
   Verbose output.

PPC (using Direct FSP Management) specific:

--p775
   Specify the operation is for Power 775 machines.

-i
   Starting numeric id of the newly created partitions. For Power 775 using Direct FSP Management, the id value only could be 1, 5, 9, 13, 17, 21, 25 and 29. Shall work with option --p775.

-m
   memory interleaving. The setting value only could be 1 or 2. 2 means non-interleaved mode (also 2MC mode), the memory cannot be shared across the processors in an octant. 1 means interleaved mode (also 8MC mode), the memory can be shared. The default value is 1. Shall work with option --p775.

-r
   partition rule. Shall work with option --p775.
   If all the octants configuration value are same in one CEC, it will be ”-r 0-7:value”. 
   If the octants use the different configuration value in one cec, it will be “-r 0:value1,1-7:value2,…7:value7”, or “-r 0:value1,1-7:value2” and so on.
   The octants configuration value for one Octant could be 1, 2, 3, 4, 5. The meanings of the octants configuration value are as following:
CAT3 Documentation, Release 2.14.5

1 -- 1 partition with all cpus and memory of the octant
2 -- 2 partitions with a 50/50 split of cpus and memory
3 -- 3 partitions with a 25/25/50 split of cpus and memory
4 -- 4 partitions with a 25/25/25/25 split of cpus and memory
5 -- 2 partitions with a 25/75 split of cpus and memory

-p profile
Name of I/O slots assignment profile. Shall work with option --p775.

lparname={\* | name}
Set LPAR name for the specified lpars. If ‘*’ specified, it means to get names from xCAT database and then set them for the specified lpars. If a string is specified, it only supports single node and the string will be set for the specified lpar. The user can use lsqm to check the lparnames for lpars.

vmcpus=value vmmemory=value add_physlots=value vmothersetting=value
To specify the parameters that will be modified.

add_vmnics=value add_vmstorage=value [--vios]
To create new virtual adapter for the specified node.

del_physlots=drc_index1,drc_index2...
To delete physical slots which are specified by the drc_index1,drc_index2...

del_vadapter=slotid
To delete a virtual adapter specified by the slotid.

VMware/KVM specific:

-a size
Add a new Hard disk with size defaulting to GB. Multiple can be added with comma separated values.

--cpus count
Set the number of CPUs.

-d disk
Deregister the Hard disk but leave the backing files. Multiple can be done with comma separated values. The disks are specified by SCSI id.

--mem memory
Set the memory, defaults to MB.

-p disk
Purge the Hard disk. Deregisters and deletes the files. Multiple can be done with comma separated values. The disks are specified by SCSI id.

--resize disk=size
Change the size of the Hard disk. The disk in qcow2 format can not be set to less than its current size. The disk in raw format can be resized smaller, use caution. Multiple disks can be resized by using comma separated disk=size pairs. The disks are specified by SCSI id. Size defaults to GB.
KVM specific:

--cpupin hostcpuset

To pin guest domain virtual CPUs to physical host CPUs specified with hostcpuset. hostcpuset is a list of physical CPU numbers. Its syntax is a comma separated list and a special markup using ‘-’ and ‘^’ (ex. ‘0-4’, ‘0-3,^2’) can also be allowed. The ‘-’ denotes the range and the ‘^’ denotes exclusive.

Note: The expression is sequentially evaluated, so “0-15,^8” is identical to “9-14,0-7,15” but not identical to “^8,0-15”.

--membind numanodeset

It is possible to restrict a guest to allocate memory from the specified set of NUMA nodes numanodeset. If the guest vCPUs are also pinned to a set of cores located on that same set of NUMA nodes, memory access is local and improves memory access performance.

--devpassthru pcidevice1,pcidevice2...

The PCI passthrough gives a guest VM direct access to I/O devices pcidevice1,pcidevice2... The PCI devices are assigned to a virtual machine, and the virtual machine can use this I/O exclusively. The devices list are a list of comma separated PCI device names delimited with comma, the PCI device names can be obtained by running virsh nodedev-list on the host.

--devdetach pcidevice1,pcidevice2...

To detaching the PCI devices which are attached to VM guest via PCI passthrough from the VM guest. The devices list are a list of comma separated PCI device names delimited with comma, the PCI device names can be obtained by running virsh nodedev-list on the host.

zVM specific:

--add3390 disk_pool device_address size mode read_password write_password multi_password

Adds a 3390 (ECKD) disk to a virtual machine's directory entry. The device address can be automatically assigned by specifying ‘auto’. The size of the disk can be specified in GB, MB, or the number of cylinders.

--add3390active device_address mode

Adds a 3390 (ECKD) disk that is defined in a virtual machine’s directory entry to that virtual server’s active configuration.

--add9336 disk_pool device_address size mode read_password write_password multi_password

Adds a 9336 (FBA) disk to a virtual machine’s directory entry. The device address can be automatically assigned by specifying ‘auto’. The size of the disk can be specified in GB, MB, or the number of blocks.

--adddisk2pool function region volume group

Add a disk to a disk pool defined in the EXTENT CONTROL. Function type can be either: (4) Define region as full volume and add to group OR (5) Add existing region to group. The disk has to already be attached to SYSTEM.

--addnic device_address type device_count

Adds a network adapter to a virtual machine’s directory entry (case sensitive).

--addpagespool volume_addr volume_label volume_use system_config_name system_config_type parm_disk_owner parm_disk_number parm_disk_password

Add a full volume page or spool disk to the virtual machine.

--addprocessor device_address
Adds a virtual processor to a virtual machine’s directory entry.

`--addprocessoractive device_address type`

Adds a virtual processor to a virtual machine’s active configuration (case sensitive).

`--addvdisk device_address size`

Adds a v-disk to a virtual machine’s directory entry.

`--addzfcp pool device_address loaddev size tag wwpn lun`

Add a zFCP device to a device pool defined in xCAT. The device must have been carved up in the storage controller and configured with a WWPN/LUN before it can be added to the xCAT storage pool. z/VM does not have the ability to communicate directly with the storage controller to carve up disks dynamically. xCAT will find the a zFCP device in the specified pool that meets the size required, if the WWPN and LUN are not given. The device address can be automatically assigned by specifying ‘auto’. The WWPN/LUN can be set as the LOADDEV in the directory entry if (1) is specified as the ‘loaddev’.

`--connectnic2guestlan device_address lan owner`

Connects a given network adapter to a GuestLAN.

`--connectnic2vswitch device_address vswitch`

Connects a given network adapter to a VSwitch.

`--copydisk target_address source_node source_address`

Copy a disk attached to a given virtual server.

`--dedicatedevice virtual_device real_device mode`

Adds a dedicated device to a virtual machine’s directory entry.

`--deleteipl`

Deletes the IPL statement from the virtual machine’s directory entry.

`--disconnectnic device_address`

Disconnects a given network adapter.

`--formatdisk disk_address multi_password`

Formats a disk attached to a given virtual server (only ECKD disks supported). The disk should not be linked to any other virtual server. This command is best used after add3390().

`--grantvswitch vswitch`

Grant vSwitch access for given virtual machine.

`--purgerdr`

Purge the reader belonging to the virtual machine

`--removedisk device_address`

Removes a minidisk from a virtual machine’s directory entry.

`--removenic device_address`

Removes a network adapter from a virtual machine’s directory entry.

`--removeprocessor device_address`

Removes a processor from an active virtual machine’s configuration.

`--removeloaddev wwpn lun`
Removes the LOADDEV statement from a virtual machines’s directory entry.

```
--removezfcp device_address wwpn lun
```

Removes a given SCSI/FCP device belonging to the virtual machine.

```
--replaces directory_entry
```

Replaces a virtual machine’s directory entry. The directory entry can be echoed into stdin or a text file.

```
--setipl ipl_target load_parms parms
```

Sets the IPL statement for a given virtual machine.

```
--setpassword password
```

Sets the password for a given virtual machine.

```
--setloaddev wwpn lun
```

Sets the LOADDEV statement in the virtual machine’s directory entry.

```
--undedicatedevice device_address
```

Delete a dedicated device from a virtual machine’s active configuration and directory entry.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.

**EXAMPLES**

**PPC (with HMC) specific:**

1. To change the partition profile for lpar4 using the configuration data in the file /tmp/lparfile, enter:

```
cat /tmp/lparfile | chvm lpar4
```

Output is similar to:

```
lpar4: Success
```

2. To change the partition profile for lpar4 to the existing profile ‘prof1’, enter:

```
chvm lpar4 -p prof1
```

Output is similar to:

```
lpar4: Success
```

3. To change partition attributes for lpar4 by specifying attribute value pairs in command line, enter:

```
chvm lpar4 max_mem=4096
```

Output is similar to:

```
lpar4: Success
```
**PPC (using Direct FSP Management) specific:**

1. For Power 775, to create a new partition lpar1 on the first octant of the cec cec01, lpar1 will use all the cpu and memory of the octant 0, enter:

   ```bash
   mkdef -t node -o lpar1 mgt=fsp groups=all parent=cec01 nodetype=lpar hcp=cec01
   then:
   chvm lpar1 --p775 -i 1 -m 1 -r 0:1
   Output is similar to:
   lpar1: Success
   cecc01: Please reboot the CEC cec1 firstly, and then use chvm to assign the I/O slots to the LPARs
   
   2. For Power 775, to create new partitions lpar1-lpar8 on the whole cec cec01, each LPAR will use all the cpu and memory of each octant, enter:

   ```bash
   mkdef -t node -o lpar1-lpar8 nodetype=lpar mgt=fsp groups=all parent=cec01 hcp=cec01
   then:
   chvm lpar1-lpar8 --p775 -i 1 -m 1 -r 0-7:1
   Output is similar to:
   lpar1: Success
   lpar2: Success
   lpar3: Success
   lpar4: Success
   lpar5: Success
   lpar6: Success
   lpar7: Success
   lpar8: Success
   cecc01: Please reboot the CEC cec1 firstly, and then use chvm to assign the I/O slots to the LPARs
   
   3. For Power 775 cec1, to create new partitions lpar1-lpar9, the lpar1 will use 25% CPU and 25% memory of the first octant, and lpar2 will use the left CPU and memory of the first octant. lpar3-lpar9 will use all the cpu and memory of each octant, enter:

   ```bash
   mkdef -t node -o lpar1-lpar9 mgt=fsp groups=all parent=cec1 nodetype=lpar hcp=cec1
   then:
   chvm lpar1-lpar9 --p775 -i 1 -m 1 -r 0:5,1-7:1
   Output is similar to:
   lpar1: Success
   lpar2: Success
   lpar3: Success
   lpar4: Success
   lpar5: Success
   lpar6: Success
   (continues on next page)
4. To change the I/O slot profile for lpar4 using the configuration data in the file /tmp/lparfile, the I/O slots information is similar to:

```
4: 514/U78A9.001.0123456-P1-C17/0x21010202/2/1
4: 513/U78A9.001.0123456-P1-C15/0x21010201/2/1
4: 512/U78A9.001.0123456-P1-C16/0x21010200/2/1
```

then run the command:

```
cat /tmp/lparfile | chvm lpar4 --p775
```

5. To change the I/O slot profile for lpar1-lpar8 using the configuration data in the file /tmp/lparfile. Users can use the output of lsvm and remove the cec information, and modify the lpar id before each I/O, and run the command as following:

```
chvm lpar1-lpar8 --p775 -p /tmp/lparfile
```

6. To change the LPAR name, enter:

```
chvm lpar1 lparname=test_lpar01
```

Output is similar to:

```
lpar1: Success
```

7. For Normal Power machine, to modify the resource assigned to a partition:

Before modify, the resource assigned to node ‘lpar1’ can be shown with:

```
lsvm lpar1
```

The output is similar to:

```
lpar1: Lpar Processor Info:
  Curr Processor Min: 1.
  Curr Processor Max: 16.
  lpar1: Lpar Memory Info:
  Curr Memory Min: 1.00 GB(4 regions).
  Curr Memory Req: 4.00 GB(16 regions).
  Curr Memory Max: 32.00 GB(128 regions).
  lpar1: 1,513,U78AA.001.WZSGVU7-P1-T7,0x21010201,0xc03(USB Controller)
  lpar1: 1,512,U78AA.001.WZSGVU7-P1-T9,0x21010200,0x104(RAID Controller)
  lpar1: 1/2/2
  lpar1: 128.
```

To modify the resource assignment:

```
chvm lpar1 vmpcups=1/2/16 vmmemory=1G/8G/32G add_physlots=0x21010202
```

The output is similar to:

```
1.3. Admin Guide 233
```
The resource information after modification is similar to:

```
lpar1: Lpar Processor Info:
Curr Processor Min: 1.
Curr Processor Req: 2.
Curr Processor Max: 16.
lpar1: Lpar Memory Info:
Curr Memory Min: 1.00 GB(4 regions).
Curr Memory Req: 8.00 GB(32 regions).
Curr Memory Max: 32.00 GB(128 regions).
lpar1: 1,514,U78AA.001.WZSGVU7-P1-C19,0x21010202,0xffff (Empty Slot)
lpar1: 1,513,U78AA.001.WZSGVU7-P1-T7,0x21010201,0xc03 (USB Controller)
lpar1: 1,512,U78AA.001.WZSGVU7-P1-T9,0x21010200,0x104 (RAID Controller)
lpar1: 1/2/2
lpar1: 128.
```

Note: The physical I/O resources specified with add_physlots will be appended to the specified partition. The physical I/O resources which are not specified but belonged to the partition will not be removed. For more information about add_physlots, refer to lsvm(1)|lsvm.1.

**VMware/KVM specific:**

```
chvm vm1 -a 8,16 --mem 512 --cpus 2
```

Output is similar to:

```
vm1: node successfully changed
```

**zVM specific:**

1. To adds a 3390 (ECKD) disk to a virtual machine’s directory entry:

```
chvm gpok3 --add3390 POOL1 0101 2G MR
```

Output is similar to:

```
gpok3: Adding disk 0101 to LNX3... Done
```

2. To add a network adapter to a virtual machine’s directory entry:

```
chvm gpok3 --addnic 0600 QDIO 3
```

Output is similar to:

```
gpok3: Adding NIC 0900 to LNX3... Done
```

3. To connects a given network adapter to a GuestLAN:

```
chvm gpok3 --connectnic2guestlan 0600 GLAN1 LN1OWNR
```

Output is similar to:
gpok3: Connecting NIC 0600 to GuestLan GLAN1 on LN1OWNR... Done

4. To connects a given network adapter to a vSwitch:

```
chvm gpok3 --connectnic2vswitch 0600 VSW1
```

Output is similar to:

```
gpok3: Connecting NIC 0600 to vSwitch VSW1 on LNX3... Done
```

5. To removes a minidisk from a virtual machine’s directory entry:

```
chvm gpok3 --removedisk 0101
```

Output is similar to:

```
gpok3: Removing disk 0101 on LNX3... Done
```

6. To Removes a network adapter from a virtual machine’s directory entry:

```
chvm gpok3 --removenic 0700
```

Output is similar to:

```
gpok3: Removing NIC 0700 on LNX3... Done
```

7. To replaces a virtual machine’s directory entry:

```
cat /tmp/dirEntry.txt | chvm gpok3 --replacevs
```

Output is similar to:

```
gpok3: Replacing user entry of LNX3... Done
```

8. To resize virtual machine’s disk sdb to 10G and sdc to 15G:

```
chvm gpok3 --resize sdb=10G,sdc=15G
```

FILES

```
/opt/xcat/bin/chvm
```

SEE ALSO

```
mkv(1)|mkvm.1, lsvm(1)|lsvm.1, rmvm(1)|rmvm.1
```

chzone.1

NAME

```
chzone - Changes a zone defined in the cluster.
```
SYNOPSIS

chzone zonename [--defaultzone] [-K] [-k full path to the ssh RSA private key] [-a noderange | -r noderange] [-g] [-f] [-s {yes|no}] [-V]

chzone [-h | -v]

DESCRIPTION

The chzone command is designed to change the definition of a zone previous defined in the cluster. The chzone command is only supported on Linux (No AIX support). The nodes are not updated with the new root ssh keys by chzone. You must run updatenode -k or xdsh -K to the nodes to update the root ssh keys to the new generated zone keys. This will also sync any service nodes with the zone keys, if you have a hierarchical cluster. Note: if any zones in the zone table, there must be one and only one defaultzone. Otherwise, errors will occur.

OPTIONS

-h | --help
  Displays usage information.

-v | --version
  Displays command version and build date.

-k | --sshkeypath
  full path to the ssh RSA private key
  This is the path to the id_rsa key that will be used to build new root’s ssh keys for the zone. If -k is used, it will generate the ssh public key from the input ssh RSA private key, and store both in /etc/xcat/sshkeys/<zonename>/.ssh directory.

-K | --genkeys
  Using this flag, will generate new ssh RSA private and public keys for the zone into the /etc/xcat/sshkeys/<zonename>/.ssh directory. The nodes are not automatically updated with the new root ssh keys by chzone. You must run updatenode -k or xdsh -K to the nodes to update the root ssh keys to the new generated zone keys. This will also sync any service nodes with the zone keys, if you have a hierarchical cluster.

--defaultzone
  if --defaultzone is input, then it will set the zone defaultzone attribute to yes. if --defaultzone is input and another zone is currently the default, then the -f flag must be used to force a change to the new defaultzone. If -f flag is not use an error will be returned and no change made. Note: if any zones in the zone table, there must be one and only one defaultzone. Otherwise, errors will occur.

-a | --addnoderange noderange
  For each node in the noderange, it will set the zonename attribute for that node to the input zonename. If the -g flag is also on the command, then it will add the group name “zonename” to each node in the noderange.

-r | --rmnoderange noderange
  For each node in the noderange, if the node is a member of the input zone, it will remove the zonename attribute for that node. If any of the nodes in the noderange is not a member of the zone, you will get an error and nothing will be changed. If the -g flag is also on the command, then it will remove the group name “zonename” from each node in the noderange.
-s|--sshhetweennodes yes|no

If -s entered, the zone sshbetweennodes attribute will be set to yes or no based on the input. When this is set to yes, then ssh will be setup to allow passwordless root access between nodes. If no, then root will be prompted for a password when running ssh between the nodes in the zone.

-f|--force

Used with the --defaultzone flag to override the current default zone.

-g|--assigngroup

Used with the -a or -r flag to add or remove the group zonename for all nodes in the input noderange.

-V|--verbose

Verbose mode.

EXAMPLES

1. To chzone zone1 to the default zone, enter:

```
chzone> zone1 --default -f
```

2. To generate new root ssh keys for zone2A using the ssh id_rsa private key in /root/.ssh:

```
chzone zone2A -k /root/.ssh
```

Note: you must use xdsh -K or updatenode -k to update the nodes with the new keys

3. To generate new root ssh keys for zone2A, enter:

```
chzone zone2A -K
```

Note: you must use xdsh -K or updatenode -k to update the nodes with the new keys

4. To add a new group of nodes (compute3) to zone3 and add zone3 group to the nodes, enter:

```
chzone zone3 -a compute3 -g
```

5. To remove a group of nodes (compute4) from zone4 and remove zone4 group from the nodes, enter:

```
chzone> zone4 -r compute4 -g
```

6. To change the sshbetweennodes setting on the zone to not allow passwordless ssh between nodes, enter:

```
chzone zone5 -s no
```

Note: you must use xdsh -K or updatenode -k to update the nodes with this new setting.

FILES

```
/opt/xcat/bin/chzone/
```

Location of the chzone command.
SEE ALSO

mkzone(1)|mkzone.1, rmzone(1)|rmzone.1, xdsh(1)|xdsh.1, updatenode(1)|updatenode.1

clonem1

NAME

clonem - Create masters from virtual machines and virtual machines from masters.

SYNOPSIS

clonem noderange [ -t master_to_be_made | -b master_to_base_vms_upon ] [ -d|--detached ] [ -f|--force ]

DESCRIPTION

Command to promote a VM’s current configuration and storage to a master as well as performing the converse operation of creating VMs based on a master.

By default, attempting to create a master from a running VM will produce an error. The --force argument will request that a master be made of the VM anyway.

Also, by default a VM that is used to create a master will be rebased as a thin clone of that master. If the --force argument is used to create a master of a powered on vm, this will not be done. Additionally, the --detached option can be used to explicitly request that a clone not be tethered to a master image, allowing the clones to not be tied to the health of a master, at the cost of additional storage.

When promoting a VM’s current state to master, all related virtual disks will be copied and merged with any prerequisite images. A master will not be tethered to other masters.

OPTIONS

-hl|--help
     Display usage message.

-b master_to_base_vms_upon
     The master to base the clones upon

-t master_to_be_made
     The target master to copy a single VM’s state to

-d|--detached
     Explicitly request that the noderange be untethered from any masters.

-f|--force
     Force cloning of a powered on VM. Implies -d if the VM is on.

-v|--version
     Command Version.

-V|--verbose
Verbose output.

**RETURN VALUE**

0: The command completed successfully.
Any other value: An error has occurred.

**EXAMPLES**

1. Creating a master named `appserver` from a node called `vm1`:

   ```
   clonevm vm1 -t appserver
   ```

2. Creating 30 VMs from a master named `appserver`:

   ```
   clonevm vm1-vm30 -b appserver
   ```

**FILES**

`/opt/xcat/bin/clonevm`

**SEE ALSO**

`chvm(1)` | `chvm.1`, `lsvm(1)` | `lsvm.1`, `rmvm(1)` | `rmvm.1`, `mkvm(1)` | `mkvm.1`, `vmmaster(5)` | `vmmaster.5`

`configfpc.1`

**NAME**

`configfpc` - discover the Fan Power Controllers (FPCs) and configure the FPC interface

**SYNOPSIS**

`configfpc -i interface`

`configfpc -i interface --ip default ip address`

`configfpc [-V | --verbose]`

`configfpc [-h | --help | -?]`

**DESCRIPTION**

`configfpc` will discover and configure all FPCs that are set to the default IP address. If not supplied the default ip is 192.168.0.100.

The `-i interface` is required to direct `configfpc` to the xCAT MN interface which is on the same VLAN as the FPCs.

There are several bits of information that must be included in the xCAT database before running this command.
You must create the FPC node definitions for all FPCs being discovered including the IP address and switch port information.

The `configfpc` command discovers the FPCs and collects the MAC address. The MAC address is used to relate the FPC to a FPC node using the switch information for this MAC. Once the relationship is discovered the FPC is configured with the FPC node IP settings.

This process is repeated until no more FPCs are discovered.

For more information on xCAT support of NeXtScale and configfpc see the following doc: XCAT_NeXtScale_Clusters

**OPTIONS**

- `-i interface`
  
  Use this flag to specify which xCAT MN interface (example: eth4) that is connected to the NeXtScale FPCs. This option is required.

- `--ip default ip address`
  
  Use this flag to override the default ip address of 192.168.0.100 with a new address.

- `-V | --verbose`
  
  Verbose mode

**EXAMPLES**

1. To discover and configure all NeXtScale Fan Power Controllers (FPCs) connected on eth0 interface.

   ```
   configfpc -i eth0
   ```

2. To override the default ip address and run in Verbose mode.

   ```
   configfpc -i eth0 --ip 196.68.0.100 -V
   ```

csm2xcat.1

**NAME**

`csm2xcat` - Allows the migration of a CSM database to an xCAT database.

**SYNOPSIS**

`csm2xcat [--dir path]`

`csm2xcat [-h]`
DESCRIPTION

The csm2xcat command must be run on the Management Server of the CSM system that you want to migrate to xCAT. The command will build two xCAT stanza files that can update the xCAT database with the chdef command.

Copy the csm2xcat command to the CSM Management Server. Run the command, indicating where you want your stanza files saved with the --dir parameter. Check the stanza files to see if the information is what you want put in the xCAT database. Copy the two stanza files: node.stanza, device.stanza back to your xCAT Management node, and run the chdef command to input into the xCAT database.

OPTIONS

- `h` Display usage message.
- `--dir` Path to the directory containing the stanza files.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To build xCAT stanza files, enter on the CSM Management Server:

   ```
   csm2xcat --dir /tmp/mydir
   ```

2. To put the data in the xCAT database on the xCAT Management Node:

   ```
   cat node.stanza | chdef -z
   cat device.stanza | chdef -z
   ```

FILES

```
/opt/xcat/share/xcat/tools/csm2xcat
$dir/conversion.log
```

SEE ALSO

chdef(1)|chdef.1
db2sqlsetup.1

NAME

```
db2sqlsetup - Sets up the IBM DB2 for xCAT to use.
```
SYNOPSIS

```
<db2sqlsetup [-h | --help] >
<db2sqlsetup [-v | --version] >
<db2sqlsetup [-i | --init] [-S | --setupDBC] [-o | --setupODBC] [-V | --verbose] >
<db2sqlsetup [-o | --setupDBC] [-S | --C] [-V | --verbose] >
<db2sqlsetup [-p | --passwd] [-S | --C] >
```

DESCRIPTION

**db2sqlsetup** - Sets up the IBM DB2 database for xCAT to use. The db2sqlsetup script is run on the Management Node, after the DB2 Server code has been installed, to setup the DB2 Server (-S). The xcatd daemon will be stopped during migration on the MN. No xCAT commands should be run during the init process, because we will be migrating the xCAT database to DB2 and restarting the xcatd daemon.

The db2sqlsetup script must be run on each Service Node, after the DB2 Client code has been installed, to setup the DB2 Client (-C). There are two postscripts that are provided (db2install and odbcsetup) that will automatically setup you Service Node as a DB2 client.

For full information on the setup of DB2, see Setting_Up_DB2_as_the_xCAT_DB.

When running db2sqlsetup on the MN: One password must be supplied for the setup, a password for the xcatdb unix id which will be used as the DB2 instance id and database name. The password will be prompted for interactively or can be input with the XCATDB2PW environment variable. The script will create the xcat database instance (xcatdb) in the /var/lib/db2 directory unless overridden by setting the site.databaseloc attribute. This attribute should not be set to the directory that is defined in the installloc attribute and it is recommended that the databaseloc be a new filesystem dedicated to the DB2 database, especially in very large clusters.

When running db2sqlsetup on the SN: Not only will the password for the DB2 instance Id be prompted for and must match the one on the Management Node; but also the hostname or ip address of the Management Node as known by the Service Node must be supplied, unless the XCATDB2SERVER environment variable is set. You can automatically install and setup of DB2 on the SN using the db2install and odbcsetup postscripts and not need to manually run the command. See the full documentation.

Note: On AIX, root must be running ksh and on Linux, bash shell.

OPTIONS

- **-h | --help**
  
  Displays the usage message.

- **-v | --version**
  
  Displays the release version of the code.

- **-V | --verbose**
  
  Displays verbose messages.

- **-i | --init**
  
  Displays the usage message.
The init option is used to setup an installed DB2 database on AIX or Linux (p-Series) so that xCAT can use the database. This must be combined with either the -S or -C flag to indicate whether we are setting up the Server or the Client. With the -S flag, it involves creating the xcatdb database, the xcatdb instance id, allowing access to the xcatdb database by the Management Node. It also backs up the current xCAT database and restores it into the newly setup xcatdb DB2 database. It creates the /etc/xcat/cfgloc file to point the xcatd daemon to the DB2 database and restarts the xcatd daemon using the database.

-p|--passwd

The password change option is to change the database access password for the DB2 xcatdb database. If -S is input then it will only change the password on the DB2 Server (MN). If -C is input it will only change on the DB2 clients (SN). If neither -S or -C are input with this flag, then it will change both the DB2 Server and Clients. When changing the password the xcatd daemon will be stopped and restarted. Any other tools accessing the database should also be stopped before changing and restarted after changing.

-S|--S

This options says whether to setup the Server (-S) on the Management Node, or the Client (-C) on the Service Nodes.

-N|--nostart

This option with the -S flag will create the database, but will not backup and restore xCAT tables into the database. It will create the cfgloc file such that the next start of xcatd will try and contact the database. This can be used to setup the xCAT DB2 database during or before install.

-o|--setupODBC

This option sets up the ODBC /etc/../.odbcinst.ini, /etc/../.odbc.ini and the .odbc.ini file in roots home directory will be created and initialized to run off the xcatdb DB2 database.

ENVIRONMENT VARIABLES

* XCATDB2INSPATH overrides the default install path for DB2 which is /opt/ibm/db2/V9.7 for Linux and /opt/IBM/db2/V9.7 for AIX.

* DATABASELOC override the where to create the xcat DB2 database, which is /var/lib/db2 by default of taken from the site.databaseloc attribute.

* XCATDB2PW can be set to the password for the xcatdb DB2 instance id so that there will be no prompting for a password when the script is run.

EXAMPLES

1. To setup DB2 Server for xCAT to run on the DB2 xcatdb database, on the MN:

   db2sqlsetup -i -S

2. To setup DB2 Client for xCAT to run on the DB2 xcatdb database, on the SN:

   db2sqlsetup -i -C

3. To setup the ODBC for DB2 xcatdb database access, on the MN:

   db2sqlsetup -o -S

4. To setup the ODBC for DB2 xcatdb database access, on the SN:
To setup the DB2 database but not start xcat running with it:

```
db2sqlsetup -o -C
```

To change the DB2 xcatdb password on both the Management and Service Nodes:

```
db2sqlsetup -p
```

dumpxCATdb.1

**NAME**

dumpxCATdb - dumps the xCAT db tables.

**SYNOPSIS**

```
dumpxCATdb [-a] [-V] [{-p | --path} path]
dumpxCATdb [-b] [-V] [{-p | --path} path]
dumpxCATdb [-h | --help] [-v | --version]
```

**DESCRIPTION**

If not using the binary dump option (-b), then the dumpxCATdb command creates .csv files for xCAT database tables and puts them in the directory given by the -p flag. These files can be used by the restorexCATdb command to restore the database. The command will read the list of tables in the site.skiptables attribute and not backup those tables. Supports using XCAT_SKIPTABLES env variable to provide a list of skip tables. The command will never backup TEAL or ISNM tables, except isnm_config. To dump TEAL tables use the documented process for TEAL. For ISNM use tabdump, after using tabprune to get to prune unnecessary records.

If using the binary dump option for the DB2 or PostgreSQL database, then the routine will use the Database provide utilities for backup of the entire database.

**OPTIONS**

- `-h` Display usage message.
- `-v` Command Version.
- `-V` Verbose.
- `-a` All, without this flag the eventlog and auditlog will be skipped.
- `-b` This flag is only used for the DB2 or PostgreSQL database. The routine will use the database backup utilities to create a binary backup of the entire database. Note to use this backup on DB2, you will have first had to modify the logging of the database and have taken an offline initial backup. Refer to the xCAT DB2 documentation for more instructions.
- `-p` Path to the directory to dump the database. It will be created, if it does not exist.
RETURN VALUE

0  The command completed successfully.
1  An error has occurred.

EXAMPLES

1. To dump the xCAT database into the /tmp/db directory, enter:
   
   dumpxCATdb -p /tmp/db

2. To dump the xCAT database into the /tmp/db directory, including the auditlog and eventlog enter:
   
   dumpxCATdb -a -p /tmp/db

3. To have dumpxCATdb not backup the hosts or passwd table:
   
   chtab key=skiptables site.value="hosts,passwd"
   
   dumpxCATdb -p /tmp/db

4. To have dumpxCATdb not backup the hosts or passwd table:
   
   export XCAT_SKIPTABLES="hosts,passwd"
   
   dumpxCATdb -p /tmp/db

5. To have dumpxCATdb use DB2 utilities to backup the DB2 database:
   
   dumpxCATdb -b -p /install/db2backup

FILES

/opt/xcat/sbin/dumpxCATdb

SEE ALSO

restorexCATdb(1) restorexCATdb.1
genimage.1

NAME

genimage - Generates a stateless image to be used for a diskless install.

SYNOPSIS

genimage

DESCRIPTION

Generates a stateless and a statelite image that can be used to boot xCAT nodes in a diskless mode.

genimage will use the osimage definition for information to generate this image. Additional options specified on the command line will override any corresponding previous osimage settings, and will be written back to the osimage definition.

If genimage runs on the management node, both the osimage table and linuximage table will be updated with the given values from the options.

The genimage command will generate two initial ramdisks for stateless and statelite, one is initrd-stateless.gz, the other one is initrd-statelite.gz.

After your image is generated, you can chroot to the image, install any additional software you would like, or make modifications to files, and then run the following command to prepare the image for deployment.

for stateless: packimage

for statelite: liteimg

Besides prompting for some parameter values, the genimage command takes default guesses for the parameters not specified or not defined in the osimage and linuximage tables. It also assumes default answers for questions from the yum/zypper command when installing rpms into the image. Use --interactive flag if you want the yum/zypper command to prompt you for the answers.

If --onlyinitrd is specified, genimage only regenerates the initrd for a stateless image to be used for a diskless install.

The genimage command must be run on a system that is the same architecture and same distro with same major release version as the nodes it will be used on. If the management node is not the same architecture or same distro level, copy the contents of /opt/xcat/share/xcat/netboot/<os> to a system that is the proper architecture, and mount /install from the management node to that system. Then change directory to /opt/xcat/share/xcat/netboot/<os> and run ./genimage.

Parameters

imagename specifies the name of an os image definition to be used. The specification for the image is stored in the osimage table and linuximage table.

OPTIONS

-a arch

The hardware architecture of this node: x86_64, ppc64, x86, ia64, etc. If omitted, the current hardware architecture will be used.

-o osver

The operating system for the image: fedora8, rhel5, sles10, etc. The OS packages must be in /install/<osvers>/<arch> (use copycds(8)|copycds.8).

-p profile
The profile (e.g. compute, service) to use to create the image. This determines what package lists are used from /opt/xcat/share/xcat/netboot/<os> to create the image with. When deploying nodes with this image, the nodes’ nodetype.profile attribute must be set to this same value.

-i nodebootif

This argument is now optional, and allows you to specify the network boot interface to be configured in the image (e.g. eth0). If not specified, the interface will be determined and configured during the network boot process.

-n nodenetdrivers

This argument is now optional, and allows you to specify the driver modules needed for the network interface(s) on your stateless nodes. If you do not specify this option, the default is to include all recent IBM xSeries network drivers.

If specified, nodenetdrivers should be a comma separated list of network drivers to be used by the stateless nodes (Ie.: -n tg3,e1000). Note that the drivers will be loaded in the order that you list them, which may prove important in some cases.

-l rootlimit

The maximum size allowed for the root file system in the image. Specify in bytes, or can append k, m, or g.

--onlyinitrd

Regenerates the initrd for a stateless image to be used for a diskless install.

Regenerates the initrd that is part of a stateless/statelite image that is used to boot xCAT nodes in a stateless/stateli te mode.

The genimage --onlyinitrd command will generate two initial ramdisks, one is initrd-statelite.gz for statelite mode, the other one is initrd-stateless.gz for stateless mode.

--permission permission

The mount permission of /statelite directory for statelite mode, which is only used for statelite mode, and the default permission is 755.

-r otherifaces

Other network interfaces (e.g. eth1) in the image that should be configured via DHCP.

-k kernelver

Use this flag if you want to use a specific version of the kernel in the image. Defaults to the first kernel found in the install image.

-g krpmver

Use this flag to specify the rpm version for kernel packages in the image. It must be present if -k flag is specified in the command for SLES. Generally, the value of -g is the part after linux- and before .rpm in a kernel rpm name.

-m statelite

This flag is for Ubuntu, Debian and Fedora12 only. Use this flag to specify if you want to generate statelite image. The default is to generate stateless image for these three operating systems. For others, this flag is invalid because both stateless and statelite images will be generated with this command.

--interactive
This flag allows the user to answer questions from `yum/zypper` command when installing rpms into the image. If it is not specified, ‘-y’ will be passed to the `yum` command and ‘–non-interactive –no-gpg-checks’ will be passed to the `zypper` command as default answers.

--dryrun

This flag shows the underlying call to the os specific `genimage` function. The user can copy and paste the output to run the command on another machine that does not have xCAT installed.

-t tmplimit

(Deprecated) This flag allows the user to setup the /tmp and the /var/tmp file system sizes. This flag is no longer supported. You can overwrite any file system size using the .postinstall script where you can create a new /etc/fstab file.

--ignorekernelchk

Skip the kernel version checking when injecting drivers from `osimage.driverupdatesrc`. That means all drivers from `osimage.driverupdatesrc` will be injected to initrd for the specific target kernel.

--noupdate

This flag allows the user to bypass automatic package updating when installing other packages.

-v|--version

Display version.

-h|--help

Display usage message.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1 To prompt the user for inputs:

   genimage

2 To generate an image using information from an osimage definition:

   genimage myimagename

3 To run `genimage` in test mode without actually generating an image:

   genimage --dryrun myimagename

4 To generate an image and have `yum/zypper` prompt for responses:

   genimage myimagename --interactive

5 To generate an image, replacing some values in the osimage definition:

   genimage -i eth0 -n tg3 myimagename
FILES

/opt/xcat/bin/genimage
/opt/xcat/share/xcat/netboot/<OS>/genimage

SEE ALSO

packimage(1)|packimage.1, liteimg(1)|liteimg.1

NAME

geninitrd - Generate an initrd (initial ramfs) which to be used for stateful install or stateless netboot.

SYNOPSIS

geninitrd imagename [--ignorekernelchk]
geninitrd [-h | --help]

DESCRIPTION

Generate the initrd for the osimage: imagename which is an xCAT object of osimage type.

Diskful Osimage

If the imagename is a stateful one (The provmethod attribute for the osimage is ‘install’), this command is used to rebuild the initrd to inject the new drivers from driver rpms or ‘update distro’ and copy the rebuilt initrd and new kernel (If there’s new kernel in ‘update distro’) to the directory /tftpboot/xcat/<imagename>.

If the initrd has been rebuilt by geninitrd, when run nodeset, the --noupdateinitrd option should be used to skip the rebuilding of initrd to improve the performance.

Three attributes of osimage object can be used to specify the Driver RPM location and Driver names for injecting new drivers to initrd.

netdrivers - comma separated driver names that need to be injected to the initrd. The postfix ‘.ko’ can be ignored. The netdrivers attribute must be set to specify the new driver list. If you want to load all the drivers from the driver rpms, using the keyword allupdate.

driverupdatesrc - comma separated driver rpm packages (full path should be specified)

osupdatename - comma separated ‘osdistrupdate’ object. Each ‘osdistrupdate’ object specifies a Linux distro update. When run geninitrd, ‘kernel-*.rpm’ will be searched from osdistrupdate.dirpath to get all the rpm packages and then search the drivers from the rpm packages.

Refer to the doc: Using_Linux_Driver_Update_Disk

Stateless Osimage

If the imagename is a stateless one (The provmethod attribute for the osimage is ‘netboot’), this command is used to generate the initrd from the rootimg which generated by ‘genimage’ command. So the ‘genimage’ must be run once before running the geninitrd command.
Two attributes of osimage object can be used to specify the Driver RPM location and Driver names for injecting new drivers to initrd.

**netdrivers** - comma separated driver names that need to be injected to the initrd. The postfix `.ko` can be ignored. The netdrivers attribute must be set to specify the new driver list. If you want to load all the drivers from the driver rpms, using the keyword allupdate.

**driverupdatesrc** - comma separated driver rpm packages (full path should be specified)

**Parameters**

*imagename* specifies the name of an os image definition to be used. The specification for the image is stored in the *osimage* table and *linuximage* table.

**--ignorekernelchk**

Skip the kernel version checking when injecting drivers from osimage.driverupdatesrc. That means all drivers from osimage.driverupdatesrc will be injected to initrd for the specific target kernel.

**RETURN VALUE**

0 The command completed successfully.

1 An error has occurred.

**EXAMPLES**

1 To generate initrd for the osimage *myimagename*:

```
geninitrd myimagename
```

**FILES**

```
/opt/xcat/bin/geninitrd
/opt/xcat/bin/genimage
/opt/xcat/share/xcat/netboot/<OS>/genimage
```

**SEE ALSO**

`geninitrd(1)` | `geninitrd.1`, `genimage(1)` | `genimage.1`

**getmacs.1**

**NAME**

*getmacs* - Collects node MAC address.
SYNOPSIS

Common:

getmacs [-h] --help | -v --version]

PPC specific:

getmacs noderange [-F filter]
getmacs noderange [-M]

blade specific:

getmacs noderange [-V] --verbose] [-d] [-arp] [-i ethN \ enN]

DESCRIPTION

The getmacs command collects MAC address from a single or range of nodes. Note that on AIX systems, the returned MAC address is not colon-separated (for example 8ee2245cf004), while on Linux systems the MAC address is colon-separated (for example 8e:e2:24:5c:f0:04). If no ping test performed, getmacs writes the first adapter MAC to the xCAT database. If ping test performed, getmacs will write the first successfully pinged MAC to xCAT database.

For PPC (using Direct FSP Management) specific:

Note: If network adapters are physically assigned to LPARs, getmacs cannot read the MAC addresses unless perform Discovery with option “-D”, since there is no HMC command to read them and getmacs has to login to open firmware. And if the LPARs has never been activated before, getmacs need to be performed with the option “-D” to get theirs MAC addresses.

For PPC (using HMC) specific:

Note: The option “-D” must be used to get MAC addresses of LPARs.

For IBM Flex Compute Node (Compute Node for short) specific:

Note: If “-d” is specified, all the MAC of the blades will be displayed. If no option specified, the first MAC address of the blade will be written to mac table.

OPTIONS

--arp
Read MAC address with ARP protocol.

-C
Specify the IP address of the partition for ping test. The default is to read from xCAT database if no -C specified.

-d
Display MAC only. The default is to write the first valid adapter MAC to the xCAT database.
Perform discovery for mac address. By default, it will run ping test to test the connection between adapter and xCAT management node. Use ‘--noping’ can skip the ping test to save time. Be aware that in this way, the lpars will be reset.

-f
Force immediate shutdown of the partition. This flag must be used with -D flag.

-F
Specify filters to select the correct adapter. Acceptable filters are Type, MAC_Address, Phys_Port_Loc, Adapter, Port_Group, Phys_Port, Logical_Port, VLan, VSwitch, Curr_Conn_Speed.

-G
Gateway IP address of the partition. The default is to read from xCAT database if no -G specified.

-h
Display usage message.

-M
Return multiple MAC addresses for the same adapter or port, if available from the hardware. For some network adapters (e.g. HFI) the MAC can change when there are some recoverable internal errors. In this case, the hardware can return several MACs that the adapter can potentially have, so that xCAT can put all of them in DHCP. This allows successful booting, even after a MAC change, but on Linux at this time, it can also cause duplicate IP addresses, so it is currently not recommended on Linux. By default (without this flag), only a single MAC address is returned for each adapter.

--noping
Only can be used with ‘-D’ to display all the available adapters with mac address but do NOT run ping test.

-o
Read MAC address when the lpar is in openfirmware state. This option must be used with [-D] option to perform ping test. Before use -o, the lpar must be in openfirmware state.

-S
The IP address of the machine to ping. The default is to read from xCAT database if no -S specified.

-v
Command Version.

-V
Verbose output.

-i
Specify the interface whose mac address will be collected and written into mac table. If 4 mac addresses are returned by option ‘-d’, they all are the mac addresses of the blade. The N can start from 0(map to the eth0 of the blade) to 3. If 5 mac addresses are returned, the 1st mac address must be the mac address of the blade’s FSP, so the N will start from 1(map to the eth0 of the blade) to 4.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.
EXAMPLES

1. To retrieve the MAC address for the HMC-managed partition lpar4 and write the first valid adapter MAC to the xCAT database, enter:

```bash
getmacs lpar4
```

Output is similar to:

```plaintext
lpar4:
#Type MAC_Address Phys_Port_Loc Adapter Port_Group Phys_Port Logical_Port VLan VSwitch Curr_Conn_Speed
hea 7607DFB07F02 N/A N/A N/A N/A 1 ETHERNET0 N/A
ent U78A1.001.99203B5-P1-T6 00145eb55788 /lhea@23c00614/ethernet@23e00514
→unsuccessful physical
```

2. To retrieve the MAC address with ARP protocol:

```bash
getmacs lpar4 --arp
```

Output is similar to:

```plaintext
lpar4:
#IP MAC_Address
192.168.0.10 00145eb55788
```

3. To retrieve the MAC address for the HMC-managed partition lpar4 and display the result only, enter:

```bash
getmacs lpar4 -d
```

Output is similar to:

```plaintext
lpar4:
#Type MAC_Address Phys_Port_Loc Adapter Port_Group Phys_Port Logical_Port VLan VSwitch Curr_Conn_Speed
hea 7607DFB07F02 N/A N/A N/A N/A 1 ETHERNET0 N/A
ent U78A1.001.99203B5-P1-T6 00145eb55788 /lhea@23c00614/ethernet@23e00514
→unsuccessful physical
```

4. To retrieve the MAC address for the HMC-managed partition lpar4 with filter Type=hea,VSwitch=ETHERNET0.

```bash
getmacs lpar4 -F Type=hea,VSwitch=ETHERNET0
```

Output is similar to:

```plaintext
lpar4:
#Type MAC_Address Phys_Port_Loc Adapter Port_Group Phys_Port Logical_Port VLan VSwitch Curr_Conn_Speed
hea 7607DFB07F02 N/A N/A N/A N/A 1 ETHERNET0 N/A
```

5. To retrieve the MAC address while performing a ping test for the HMC-managed partition lpar4 and display the result only, enter:

```bash
getmacs lpar4 -d -D -S 9.3.6.49 -G 9.3.6.1 -C 9.3.6.234
```

Output is similar to:
6. To retrieve the MAC address for Power 775 LPAR using Direct FSP Management without ping test and display the result only, enter:

```
getmacs lpar4 -d
```

Output is similar to:

```
lpar4:
# Type Phys_Port_Loc MAC_Address Adapter Port_Group Phys_Port Logical_Port VLan
   HFI N/A 02:00:02:00:00:04 N/A N/A N/A N/A N/A N/A
```

7. To retrieve multiple MAC addresses from Power 775 HFI network adapter using Direct FSP Management, enter:

```
getmacs lpar4 -M
```

Output is similar to:

```
lpar4:
# Type Phys_Port_Loc MAC_Address Adapter Port_Group Phys_Port Logical_Port VLan
   HFI N/A 02:00:02:00:00:04 N/A N/A N/A N/A N/A N/A
```

8. To retrieve the MAC address for Power Lpar by ‘-D’ but without ping test.

```
getmacs lpar4 -D --noping
```

Output is similar to:

```
lpar4:
# Type Location Code MAC Address Full Path Name Device Type
   ent U8233.E8B.103A4DP-V3-C3-T1 da:08:4c:4d:d5:03 /vdevice/l-lan@30000003 virtual
   ent U8233.E8B.103A4DP-V3-C4-T1 da:08:4c:4d:d5:04 /vdevice/l-lan@30000004 virtual
   ent U78A0.001.DNWHYT2-P1-C6-T1 00:21:5e:a9:50:42 /lhea@2000000000000000 ethernet@200000000000003 physical
```

FILES

```
/opt/xcat/bin/getmacs
```

SEE ALSO

```
makedhcp(8)|makedhcp.8
getslnodes.1
```
NAME

getslnodes - queries your SoftLayer account and gets attributes for each server.

SYNOPSIS

getslnodes [-v | --verbose] [hostname-match]
getslnodes [-? | -h | --help]

DESCRIPTION

The getslnodes command queries your SoftLayer account and gets attributes for each server. The attributes can be piped to `mkdef -z` to define the nodes in the xCAT DB so that xCAT can manage them.

Before using this command, you must download and install the SoftLayer API perl module. For example:

```
cd /usr/local/lib
git clone https://github.com/softlayer/softlayer-api-perl-client.git
```

You also need to follow these directions to get your SoftLayer API key: [http://knowledgelayer.softlayer.com/procedure/retrieve-your-api-key](http://knowledgelayer.softlayer.com/procedure/retrieve-your-api-key)

getslnodes requires a .slconfig file in your home directory that contains your SoftLayer userid, API key, and location of the SoftLayer API perl module, in attr=val format. For example:

```
# Config file used by the xcat cmd getslnodes
userid = joe_smith
apikey = 1234567890abcdef1234567890abcdef1234567890abcdef
apidir = /usr/local/lib/softlayer-api-perl-client
```

OPTIONS

-?|-h|--help
   Display usage message.

-v|--version
   Command Version.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. Display information about all of the nodes in your SoftLayer account:

```
getslnodes
```
2. Display information about all of the nodes whose hostname starts with foo:

```
getslnodes foo
```

3. Create xCAT node definitions in the xCAT DB for all of the nodes in your SoftLayer account:

```
getslnodes | mkdef -z
```

**FILES**

```
/opt/xcat/bin/getslnodes
```

**SEE ALSO**

pushinitrd(1)|pushinitrd.1
gettab.1

**NAME**

gettab - select table rows, based on attribute criteria, and display specific attributes.

**SYNOPSIS**

```
gettab [-H|--with-fieldname] key=value,... table.attribute ...
gettab [-?|--help]
```

**DESCRIPTION**

The `gettab` command uses the specified key values to select a row in each of the tables requested. For each selected row, the specified attributes are displayed. The `gettab` command can be used instead of `nodels` for tables that are not keyed by nodename (e.g. the `site` table), or to select rows based on an attribute value other than nodename.

**OPTIONS**

- `-H|--with-fieldname`

  Always display table.attribute name next to result. By default, this is done only if more than one table.attribute is requested.

- `-?|--help`

  Display usage message.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.
EXAMPLES

1. To display setting for master (management node) in the site table:

   ```
   gettab -H key=master site.value
   ```

   The output would be similar to:

   ```
   site.value: mgmtnode.cluster.com
   ```

2. To display the first node or group name that has mgt set to blade in the nodehm table:

   ```
   gettab mgt=blade nodehm.node
   ```

   The output would be similar to:

   ```
   blades
   ```

FILES

```
/opt/xcat/bin/gettab
```

SEE ALSO

nodels(1), nodels.1, chtab(8), chtab.8, tabdump(8), tabdump.8

groupfiles4dsh.1

NAME

**groupfiles4dsh** - Builds a directory of files for each defined nodegroup in xCAT.

SYNOPSIS

```
groupfiles4dsh [-p | --path] path
```

```
groupfiles4dsh [-h | --help] [-v | --version]
```

DESCRIPTION

This tool will build a directory of files, one for each defined nodegroup in xCAT. The file will be named the nodegroup name and contain a list of nodes that belong to the nodegroup. The file can be used as input to the AIX dsh command. The purpose of this tool is to allow backward compatibility with scripts that were created using the AIX or CSM dsh command.

Reference: man dsh.
OPTIONS

-\(h\) Display usage message.
-\(v\) Command Version.
-\(p\) Path to the directory to create the nodegroup files (must exist).

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To create the nodegroup files in directory /tmp/nodegroupfiles, enter:

```sh
groupfiles4dsh -p /tmp/nodegroupfiles
```

To use with dsh:

```sh
export DSH_CONTEXT=DSH \{( default unless CSM is installed)\}
export DSH_NODE_RSH=/bin/ssh \{default is rsh\}
export DSH_NODEGROUP_PATH= /tmp/nodegroupfiles

dsh -N all date \{where all is a group defined in xCAT\}
dsh -a date \{will look in all nodegroupfiles and build a list of all nodes\}
```

FILES

/opt/xcat/share/xcat/tools/groupfiles4dsh

SEE ALSO

xdsh(1)/xdsh.1

imgcapture.1

NAME

imgcapture - Captures an image from a Linux diskful node and create a diskless or diskful image on the management node.

SYNOPSIS

```
imgcapture node -t --type \{diskless \| sysclone\} -o \|--osimage osimage [-i nodebootif] \|[-n nodenetdrivers] \|[-V \|--verbose]
```

```sh
imgcapture \[-h \|--help\] \|--version\]
```
DESCRIPTION

The `imgcapture` command will capture an image from one running diskful Linux node and create a diskless or diskful image for later use.

The `node` should be one diskful Linux node, managed by the xCAT MN, and the remote shell between MN and the `node` should have been configured. AIX is not supported. VMs are not supported.

The `imgcapture` command supports two image types: `diskless` and `sysclone`. For the `diskless` type, it will capture an image from one running diskful Linux node, prepares the rootimg directory, kernel and initial ramdisks for the `liteimg/packimage` command to generate the statelite/stateless rootimg. For the `sysclone` type, it will capture an image from one running diskful Linux node, create an osimage which can be used to clone other diskful Linux nodes.

The `diskless` type:

The attributes of osimage will be used to capture and prepare the root image. The `osver`, `arch` and `profile` attributes for the stateless/statelite image to be created are duplicated from the `node`’s attribute. If the `-p|--profile profile` option is specified, the image will be created under “/<installroot>/netboot/<osver>/<arch>/<profile>/rootimg”.

The default files/directories excluded in the image are specified by /opt/xcat/share/xcat/netboot/<os>/<osver>.<arch>.imgcapture.exlist; also, you can put your customized file (<profile>.<osver>.<arch>.imgcapture.exlist) to /install/custom/netboot/<osplatform>. The directories in the default .imgcapture.exlist file are necessary to capture the image from the diskful Linux node managed by xCAT, don’t remove it.

The image captured will be extracted into the /<installroot>/netboot/<osver>/<arch>/<profile>/rootimg directory.

After the `imgcapture` command returns without any errors, you can customize the rootimg and run the `liteimg/packimage` command with the options you want.

The `sysclone` type:

xCAT leverages the Open Source Tool - Systemimager to capture the osimage from the `node`, and put it into /<installroot>/sysclone/images directory.

The `imgcapture` command will create the `osimage` definition after the image is captured successfully, you can use this osimage and `nodeset` command to clone diskful nodes.

OPTIONS

- `--type`  
  Specify the osimage type you want to capture, two types are supported: diskless and sysclone.

- `-p|--profile profile`  
  Assign `profile` as the profile of the image to be created.

- `-o|--osimage osimage`  
  The osimage name.

- `-i nodebootif`  
  The network interface the diskless node will boot over (e.g. eth0), which is used by the `genimage` command to generate initial ramdisks.

- `-n nodenetdrivers`  
  The driver modules needed for the network interface, which is used by the `genimage` command to generate initial ramdisks.

  By default, the `genimage` command can provide drivers for the following network interfaces:
For x86 or x86_64 platform:

```
tg3 bnx2 bnx2x e1000 e1000e igb mlx_en
```

For ppc64 platform:

```
e1000 e1000e igb ibmveth ehea
```

For S390x:

```
qdio ccwgroup
```

If the network interface is not in the above list, you'd better specify the driver modules with this option.

- **-h|--help**
  Display the usage message.

- **-v|--version**
  Display the version.

- **-V|--verbose**
  Verbose output.

**RETRUN VALUE**

0 The command completed successfully.
1 An error has occurred.

**EXAMPLES**

**node1** is one diskful Linux node, which is managed by xCAT.

1. There’s one pre-defined osimage. In order to capture and prepare the diskless root image for osimage, run the command:

```
imgcapture node1 -t diskless -o osimage
```

2. In order to capture the diskful image from node1 and create the osimage img1, run the command:

```
imgcapture node1 -t sysclone -o img1
```

**FILES**

```
/opt/xcat/bin/imgcapture
```

**SEE ALSO**

genimage(1)|genimage.1, imgimport(1)|imgimport.1, imgexport(1)|imgexport.1, packimage(1)|packimage.1, liteimg(1)|liteimg.1, nodeset(8)|nodeset.8
NAME

imgexport - Exports an xCAT image.

SYNOPSIS

imgexport [-h|--help]
imgexport image_name [destination] [[-e|--extra file:dir] ... ] [-p|--postscripts node_name] [-v|--verbose]

DESCRIPTION

The imgexport command will export an image that is being used by xCAT. To export images, you must have the images defined in the osimage table. All the columns in the osimage and linuximage tables will be exported. If kits are used in stateful or stateless images, kit, kitcomponent and kitrepo tables will be exported. In addition, the following files will also be exported.

For stateful:  x.pkglist x.otherpkgs.pkglist x.tmpl x.synclist kits related files
For stateless: kernel initrd.gz rootimg.cpio.xz or rootimg.cpio.gz or rootimg.tar.gz or rootimg.gz(for backward-compatibility) x.pkglist x.otherpkgs.pkglist x.synclist x.postinstall x.exlist kits related files
For statelite: kernel initrd.gz root image tree x.pkglist x.synclist x.otherpkgs.pkglist x.postinstall x.exlist

where x is the name of the profile.

Any files specified by the -e flag will also be exported. If -p flag is specified, the names of the postscripts and the postbootscripts for the given node will be exported. The postscripts themselves need to be manually exported using -e flag.

For statelite, the litefile table settings for the image will also be exported. The litetree and statelite tables are not exported.

OPTIONS

-el|--extra srcfile:destdir

Pack up extra files. If destdir is omitted, the destination directory will be the same as the source directory.

-h|--help

Display usage message.

-pl|--postscripts node_name

Get the names of the postscripts and postbootscripts for the given node and pack them into the image.

-v|--verbose

Verbose output.

image_name

The name of the image. Use lsdef -t osimage to find out all the image names.

destination
The output bundle file name.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.

**EXAMPLES**

1. Simplest way to export an image. If there is an image in the osimage table named ‘foo’, then run:

   ```
   imgexport foo
   ```

   foo.tgz will be built in the current working directory. Make sure that you have enough space in the directory that you are in to run imgexport if you have a big image to tar up.

2. To include extra files with your image:

   ```
   imgexport Default_Stateless_1265981465 foo.tgz -e /install/postscripts/myscript1 -e /tmp/mydir:/usr/mydir
   ```

   In addition to all the default files, this will export /install/postscripts/myscript1 and the whole directory /tmp/dir into the file called foo.tgz. And when imgimport is called /install/postscripts/myscript1 will be copied into the same directory and /tmp/mydir will be copied to /usr/mydir.

3. To include postscript with your image:

   ```
   imgexport Default_Stateless_1265981465 foo.tgz -p node1 -e /install/postscripts/myscript1
   ```

   The postscripts and the postbootscripts names specified in the postscripts table for node1 will be exported into the image. The postscript myscript1 will also be exported.

**FILES**

```
/opt/xcat/bin/imgexport
```

**SEE ALSO**

imgimport(1) | imgimport.1

**NAME**

`imgimport` - Imports an xCAT image or configuration file into the xCAT tables so that you can immediately begin deploying with it.
SYNOPSIS

imgimport [-hl--help]

imgimport bundle_file_name [-p | --postscripts nodelist] [-f | --profile new_profile] [-v | --verbose]

DESCRIPTION

The imgimport command will import an image that has been exported by imgexport from xCAT. This is the easiest way to transfer, backup, change or share images created by xCAT whether they be stateless or stateful. The bundle file will be unpacked in the current working directory. The xCAT configuration such as osimage and linuximage tables will then be updated.

For stateful, the following files will be copied to the appropriate directories.  x.pkglist x.otherpkgs.pkglist xtmpl
x.synclist kits related files

For stateless, the following files will be copied to the appropriate directories.  kernel initrd.gz rootimg.cpio.xz or rootimg.cpio.gz or rootimg.tar.xz or rootimg.tar.gz or rootimg.gz(for backward-compatibility) x.pkglist
x.otherpkgs.pkglist x.synclist x.postinstall x.exlist kits related files

For statelite, the following files will be copied to the appropriate directories.  kernel initrd.gz root image tree
x.pkglist x.synclist x.otherpkgs.pkglist x.postinstall x.exlist

where x is the profile name.

Any extra files, included by --extra flag in the imgexport command, will also be copied to the appropriate directories.

For statelite, the litefile table will be updated for the image. The litetree and statelite tables are not imported.

If -p flag is specified, the postscripts table will be updated with the postscripts and the postbootscripts names from the image for the nodes given by this flag.

If -f flag is not specified, all the files will be copied to the same directories as the source. If it is specified, the old profile name x will be changed to the new and the files will be copied to the appropriate directories for the new profiles. For example, /opt/xcat/share/xcat/netboot/sles/x.pkglist will be copied to /install/custom/netboot/sles/compute_new.pkglist and /install/netboot/sles11/ppc64/x/kernel will be copied to /install/netboot/sles11/ppc64/compute_new/kernel. This flag is commonly used when you want to copy the image on the same xCAT mn so you can make modification on the new one.

After this command, you can run the nodeset command and then start deploying the nodes. You can also choose to modify the files and run the following commands before the node deployment.

For stateful:   nodeset

For stateless:   genimage packimage nodeset

For statelite  genimage liteimg nodeset

OPTIONS

-fl--profile new_profile

Import the image with a new profile name.

-hl--help

Display usage message.

-pl--postscripts nodelist
Import the postscripts. The postscripts contained in the image will be set in the postscripts table for
node
list.

-v|--verbose

Verbose output.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. Simplest way to import an image. If there is a bundle file named ‘foo.gz’, then run:

   `imgimport foo.gz`

2. Import the image with postscript names.

   `imgimport foo.gz -p node1,node2`

   The postscripts table will be updated with the name of the postscripts and the postbootstrap scripts for node1 and node2.

3. Import the image with a new profile name

   `imgimport foo.gz -f compute_test`

FILES

/opt/xcat/bin/imgimport

SEE ALSO

imgexport(1)|imgexport.1

NAME

liteimg - Modify statelite image by creating a series of links.

SYNOPSIS

liteimg [-h|--help]
liteimg [-v|--version]
liteimg imagename
DESCRIPTION

This command modifies the statelite image by creating a series of links. It creates 2 levels of indirection so that files can be modified while in their image state as well as during runtime. For example, a file like <$imgroot>/etc/ntp.conf will have the following operations done to it:

* mkdir -p $imgroot/.default/etc*
* mkdir -p $imgroot/.statelite/tmpfs/etc*
* mv $imgroot/etc/ntp.conf $imgroot/.default/etc*
* cd $imgroot/.statelite/tmpfs/etc*
* ln -sf ../../../.default/etc/ntp.conf .*
* cd $imgroot/etc*
* ln -sf ../.statelite/tmpfs/etc/ntp.conf .*

When finished, the original file will reside in $imgroot/.default/etc/ntp.conf. $imgroot/etc/ntp.conf will link to $imgroot/.statelite/tmpfs/etc/ntp.conf which will in turn link to $imgroot/.default/etc/ntp.conf

Note: If you make any changes to your litefile table after running liteimg then you will need to rerun liteimg again.

PARAMETERS

imagename specifies the name of a os image definition to be used. The specification for the image is stored in the osimage table and linuximage table.

OPTIONS

-h|--help Display usage message.
-v|--version Command Version.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To lite a RHEL 6.6 statelite image for a compute node architecture x86_64 enter:

   liteimg rhels6.6-x86_64-statelite-compute

FILES

/opt/xcat/bin/liteimg
NOTES

This command is part of the xCAT software product.

SEE ALSO

genimage(1)|genimage.1

lsdef.1

NAME

lsdef - Use this command to list xCAT data object definitions.

SYNOPSIS

lsdef [-h | --help] [-t object-types] [-i attr-list]

DESCRIPTION

This command is used to display xCAT object definitions which are stored in the xCAT database and xCAT object definition templates shipped in xCAT.

OPTIONS

-ai--all
   Display all definitions. For performance consideration, the auditlog and eventlog objects will not be listed. To list auditlog or eventlog objects, use lsdef -t auditlog or lsdef -t eventlog instead.

-cl--compress
   Display information in compressed mode, each output line has format “<object name>: <data>”. The output can be passed to command xcoll or xdshbak for formatted output. The -c flag must be used with -i flag.

-hl--help
   Display usage message.

-li attr-list
   Comma separated list of attribute names to display.

-sl--long
   List the complete object definition.

-sl--short
Only list the object names.

-S
List all the hidden nodes (FSP/BPA nodes) with other ones.

noderange
A set of comma delimited node names and/or group names. See the “noderange” man page for details on supported formats.

-o object-names
A set of comma delimited object names.

--template [template-object-name]
Show the object definition templates template-object-name shipped in xCAT. If no template-object-name is specified, all the object definition templates of the specified type `-t object-types` will be listed. Use `-all` option to list all the object definition templates.

--osimage
Show all the osimage information for the node.

--nics
Show the nics configuration information for the node.

-t object-types
A set of comma delimited object types. Use the help option to get a list of valid objects.

-V|--verbose
Verbose mode.

-w attr==val -w attr=~val . . .
Use one or multiple -w flags to specify the selection string that can be used to select objects. The operators `==`, `!=`, `~=` and `!~` are available. Use the help option to get a list of valid attributes for each object type.

**Operator descriptions:**
- `==` Select nodes where the attribute value is exactly this value.
- `!=` Select nodes where the attribute value is not this specific value.
- `=~` Select nodes where the attribute value matches this regular expression.
- `!~` Select nodes where the attribute value does not match this regular expression.

Note: if the “val” fields includes spaces or any other characters that will be parsed by shell, the “attr<operator>val” needs to be quoted. If the operator is “!~”, the “attr<operator>val” needs to be quoted using single quote.

-z|--stanza
Display output in stanza format. See the xcatstanzafile man page for details on using xCAT stanza files.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.
EXAMPLES

1. To display a description of all the valid attributes that could be used when defining an xCAT node.
   
   ```
   lsdef -t node -h
   ```

2. To get a list of all the objects that have been defined.
   
   ```
   lsdef
   OR
   lsdef -a
   ```

3. To get all the attributes of the node1
   
   ```
   lsdef node1
   OR
   lsdef -t node node1
   OR
   lsdef -t node -o node1
   ```

4. To get the object name of node1 instead of all the attributes
   
   ```
   lsdef -s node1
   ```

5. To get a list of all the network definitions.
   
   ```
   lsdef -t network
   ```

6. To get a complete listing of all network definitions.
   
   ```
   lsdef -l -t network
   ```

7. To list the whole xCAT database and write it to a stanza file. (backup database)
   
   ```
   lsdef -a -l -z > mydbstanzafile
   ```

8. To list the MAC and install adapter name for each node.
   
   ```
   lsdef -t node -i mac,installnic
   ```

9. To list an osimage definition named “aix53J”.
   
   ```
   lsdef -t osimage -l -o aix53J
   ```

10. To list all node definitions that have a status value of “booting”.
    
    ```
    lsdef -t node -w status==booting
    ```

11. To list all the attributes of the group “service”.
    
    ```
    lsdef -l -t group -o service
    ```

12. To list all the attributes of the nodes that are members of the group “service”.
    
    ```
    lsdef -t node -l service
    ```

13. To get a listing of object definitions that includes information about what xCAT database tables are used to store the data.
lsdef -V -l -t node -o node01

14. To list the hidden nodes that can’t be seen with other flags. The hidden nodes are FSP/BPAs.

lsdef -S

15. To list the nodes status and use xcoll to format the output.

lsdef -t node -i status -c | xcoll

16. To display the description for some specific attributes that could be used when defining an xCAT node.

lsdef -t node -h -i profile,pprofile

17. To display the nics configuration information for node cn1.

lsdef cn1 --nics

18. To list all the object definition templates shipped in xCAT.

lsdef --template -a

19. To display the details of “node” object definition template “ppc64le-template” shipped in xCAT.

lsdef -t node --template ppc64le-template

20. To list all the “node” object definition templates shipped in xCAT.

lsdef -t node --template

FILES

/opt/xcat/bin/lsdef

NOTES

This command is part of the xCAT software product.

SEE ALSO

mkdef(1)|mkdef.1, chdef(1)|chdef.1, rmdef(1)|rmdef.1, xcatstanzafile(5)|xcatstanzafile.5

lsdocker.1

NAME

lsdocker - List docker instance.
SYNOPSIS

lsdocker noderange [-l | --logs]
lsdocker dockerhost
lsdocker [-h | --help]
lsdocker [-v | --version]

DESCRIPTION

lsdocker To list docker instance info or all the running docker instance info if dockerhost is specified.

OPTIONS

-ll--logs
To return the logs of docker instance. Only works for docker instance.

EXAMPLES

1. To get info for docker instance “host01c01”

   lsdocker host01c01

   Output is similar to:

   host01c01: 50800ddf8b5f ubuntu /bin/bash 2016-01-13T06:32:59 running /host01c01

2. To get info for running docker instance on dockerhost “host01”

   lsdocker host01

   Output is similar to:

   host01: 50800ddf8b5f ubuntu /bin/bash 2016-01-13 - 1:32:59 Up 12 minutes /host01c01
   host01: 875cellid5987 ubuntu /bin/bash 2016-1-21 - 1:12:37 Up 5 seconds /host01c02

SEE ALSO

mkdocker(1)|mkdocker.1, rmdocker(1)|rmdocker.1
lsflexnode.1

NAME

lsflexnode - Display the information of flexible node
SYNOPSIS

lsflexnode [-h | --help]
lsflexnode [-v | --version]
lsflexnode noderange

DESCRIPTION

IBM BladeCenter HX5 offers flexibility ideal that the blades can be combined together for scalability.

There are several concepts to support the HX5 multiple blades combination:

Complex: Multiple blades which combined by a scalability card is a complex.

Partition: A logic concept which containing part of the Blade slot node in a complex. Each partition can map to a system to install Operating System. Each partition could have 1HX5, 1HX5+1MD or 2HX5+2MD. (MD is the Memory Drawer)

Blade slot node: The physical blade which installed in the slot of a chassis. It can be a HX5 or MD.

A Complex will be created automatically when a multiple blades combination is installed. In this Complex, every blade belongs to it is working as a Blade slot node.

A Partition can be created base on the Complex, each Partition can have one or multiple Blade slot node.

The noderange in the SYNOPSIS can be a AMM node or a blade node.

OPTIONS

-h | --help
    Display the usage message.

-v | --version
    Display the version information.

ATTRIBUTES

The meaning of attributes which displayed by the lsflexnode. The word ‘node’ in this section means Blade slot node.

Complex
    The unique numeric identifier for a complex installed in the chassis.

Partition number
    The number of partitions currently defined for this complex.

Complex node number
    The number of nodes existing in this complex, regardless of their assignment to any given partition.

Partition
    The unique numeric identifier for a partition defined within a complex installed in the chassis.

Partition Mode
    The currently configured mode of this partition. It can be ‘partition’ or ‘standalone’.
Partition node number

The number of nodes currently defined for this partition.

Partition status

The current power status of this partition when the partition has a valid partition configuration. It can be ‘poweredoff’, ‘poweredon’, ‘resetting’ or ‘invalid’.

Node

The unique numeric identifier for this node, unique within the partition. If this node does not belong to a partition, the slot number will be displayed.

Node state

The physical power state of this node. It can be ‘poweredoff’, ‘poweredon’ or ‘resetting’.

Node slot

The base slot number where the node exists in the chassis.

Node resource

A string providing a summary overview of the resources provided by this node. It includes the CPU number, CPU frequency and Memory size.

Node type

The general categorization of the node. It can be ‘processor’, ‘memory’ or ‘io’.

Node role

Indicates if the node is assigned to a partition, and if so, provides an indication of whether the node is the primary node of the partition or not.

Flexnode state

The state of a flexible node. It is the state of the partition which this node belongs to. If this node does NOT belong to a partition, the value should be ‘invalid’.

It can be ‘poweredoff’, ‘poweredon’, ‘resetting’ or ‘invalid’.

Complex id

The identifier of the complex this node belongs to.

Partition id

The identifier of the partition this node belongs to.

EXAMPLES

1 Display all the Complex, Partition and Blade slot node which managed by a AMM.

```
lsflexnode amm1
```

The output:

```
amm1: Complex - 24068
amm1: ..Partition number - 1
amm1: ..Complex node number - 2
amm1: ..Partition = 1
amm1: ....Partition Mode - partition
```
2 Display a flexible node.

```bash
lsflexnode bladel
```

The output:

```bash
bladel: Flexnode state - poweredoff
bladel: Complex id - 24068
bladel: Partition id - 1
bladel: Slot14: Node state - poweredoff
bladel: Slot14: Node slot - 14
bladel: Slot14: Node type - processor
bladel: Slot14: Node resource - 2 (1866 MHz) / 8 (2 GB)
bladel: Slot14: Node role - secondary
```

FILES

`/opt/xcat/bin/lsflexnode`

SEE ALSO

`mkflexnode(1)`|`mkflexnode.1`, `rmflexnode(1)`|`rmflexnode.1`

`lshwconn.1`

NAME

`lshwconn` - Use this command to display the connection status for CEC and Frame nodes.

SYNOPSIS

```
lshwconn [-h|--help]
lshwconn [-v|--version]
```
PPC (with HMC) specific:

lshwconn [-V|--verbose] noderange

PPC (without HMC, using FSPAPI) specific:

lshwconn noderange -T tooltype

DESCRIPTION

This command is used to display the connection status for CEC and Frame node.

OPTIONS

-\*\*\*hl--help\*\*

Display usage message.

-V|--verbose

Verbose output.

-T

The tooltype is used to communicate to the CEC/Frame. The value could be lpar or fnm. The tooltype value lpar is for xCAT and fnm is for CNM.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To display connection status for all CEC nodes in node group CEC:

   lshwconn cec

   Output is similar to:

   cec1: ipaddr=192.168.200.245,alt_ipaddr=unavailable,state=Connected
   cec2: Connection not found

2. To display connection status for Frame node frame1:

   lshwconn frame1

   Output is similar to:

   frame1: side=a,ipaddr=192.168.200.247,alt_ipaddr=unavailable,state=Connected
   frame1: side=b,ipaddr=192.168.200.248,alt_ipaddr=unavailable,state=Connected
3. To display connection status for all CEC nodes in node group CEC to hardware server, and using lpar tooltype:

```
lshwconn cec -T lpar
```

Output is similar to:

```
cec1: sp=primary,ipadd=40.3.7.1,alt_ipadd=unavailable,state=LINE_UP
cec2: Connection not found
```
OPTIONS

-F|--framework kit_path_name

Use this option to display the framework values of the specified Kit tarfile. This information is retrieved directly from the tarfile and can be done before the Kit has been defined in the xCAT database. This option cannot be combined with other options.

-K|--kitattr kitattr_names

Where kitattr_names is a comma-delimited list of kit attribute names. The names correspond to attribute names in the kit table. The lskit command will only display the specified kit attributes.

-R|--repoattr repoattr_names

Where repoattr_names is a comma-delimited list of kit repository attribute names. The names correspond to attribute names in the kitrepo table. The lskit command will only display the specified kit repository attributes.

-C|--compattr compattr_names

Where compattr_names is a comma-delimited list of kit component attribute names. The names correspond to attribute names in the kitcomponent table. The lskit command will only display the specified kit component attributes.

kit_names

is a comma-delimited list of kit names. The lskit command will only display the kits matching these names.

-x|--xml|--XML

Need XCATXMLTRACE=1 env when using -x|--xml|--XML, for example: XCATXMLTRACE=1 lskit -x testkit-1.0.0 Return the output with XML tags. The data is returned as:

```
<data>
  <kitinfo>
    ...
  </kitinfo>
</data>
...
<data>
  <kitinfo>
    ...
  </kitinfo>
</data>
```

Each <kitinfo> tag contains info for one kit. The info inside <kitinfo> is structured as follows:

- The <kit> sub-tag contains the kit's basic info.
- The <kitrepo> sub-tags store info about the kit's repositories.
- The <kitcomponent> sub-tags store info about the kit's components.

The data inside <kitinfo> is returned as:

```
<kitinfo>
  <kit>
    ...
  </kit>
```

(continues on next page)
**-V|--verbose**
Display additional progress and error messages.

**-v|--version**
Command Version.

**-?|--help**
Display usage message.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.

**EXAMPLES**

1. To list all kits, enter:

   
   lskit

2. To list the kit “kit-test1-1.0-Linux”, enter:

   
   lskit kit-test1-1.0-Linux

3. To list the kit “kit-test1-1.0-Linux” for selected attributes, enter:

   
   lskit -K basename,description -R kitreponame -C kitcompname kit-test1-1.0-Linux

4. To list the framework value of a Kit tarfile.

   
   lskit -F /myhome/mykits/pperte-1.3.0.2-0-x86_64.tar.bz2

Output is similar to:

   
   Extracting the kit.conf file from /myhome/mykits/pperte-1.3.0.2-0-x86_64.tar.bz2. Please wait.
   
   kitframework=2
   compatible_kitframeworks=0,1,2
5. To list kit “testkit-1.0-1” with XML tags, enter:

```
xCATXMLTRACE=1 lskit -x testkit-1.0-1
```

**FILES**

```
/opt/xcat/bin/lskit
```

**SEE ALSO**

```
lskitcomp(1) lskitcomp.1, lskitdeployparam(1) lskitdeployparam.1, addkit(1) addkit.1, rmkit(1) rmkit.1, addkitcomp(1) addkitcomp.1, rmkitcomp(1) rmkitcomp.1
```

**NAME**

```
lskitcomp - Used to list information for one or more kit components.
```

**SYNOPSIS**

```
lskitcomp [-V | --verbose] [-x | --xml | --XML] [-C | --compattr compattr_names] [-O | --osdistro os_distro] [-S | --serverrole server_role] [kitcomp_names]
lskitcomp [-? | -h | --help | -v | --version]
```

**DESCRIPTION**

The `lskitcomp` command is used to list information for one or more kit components. A kit is made up of one or more kit components. Each kit component is a meta package used to install a software product component on one or more nodes in an xCAT cluster.

The `lskitcomp` command outputs the kit component info in two formats: human-readable format (default), and XML format. Use the -x option to view the info in XML format.

Input to the command can specify any number or combination of the input options.

Note: The xCAT support for Kits is only available for Linux operating systems.

**OPTIONS**

```
-C | --compattr compattr_names
```

where `compattr_names` is a comma-delimited list of kit component attribute names. The names correspond to attribute names in the `kitcomponent` table. The `lskitcomp` command will only display the specified kit component attributes.

```
-O | --osdistro os_distro
```

where `os_distro` is the name of an osdistro in `osdistro` table. The `lskitcomp` command will only display the kit components matching the specified osdistro.
-sl--serverrole server_role

where server_role is the name of a server role. The typical server roles are: mgtnode, servicenode, computenode, loginnode, storagennode. The lskitcomp command will only display the kit components matching the specified server role.

kitcomp_names

is a comma-delimited list of kit component names. The lskitcomp command will only display the kit components matching the specified names.

-xl--xml--XML

Need XCATXMLTRACE=1 env when using -xl--xml--XML. Return the output with XML tags. The data is returned as:

```xml
<data>
  <kitinfo>
    ...
  </kitinfo>
</data>
...
<data>
  <kitinfo>
    ...
  </kitinfo>
</data>
```

Each <kitinfo> tag contains info for a group of kit components belonging to the same kit. The info inside <kitinfo> is structured as follows:

The <kit> sub-tag contains the kit's name.
The <kitcomponent> sub-tags store info about the kit's components.

The data inside <kitinfo> is returned as:

```xml
<kitinfo>
  <kit>
    ...
  </kit>
  ...
  <kitinfo>
    ...
  </kitinfo>
</kitinfo>
```

-V|--verbose

Display additional progress and error messages.

-v|--version

Command Version.

-?|--help

Display usage message.
RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To list all kit components, enter:
   lskitcomp

2. To list the kit component “comp-server-1.0-1-rhels-6-x86_64”, enter:
   lskitcomp comp-server-1.0-1-rhels-6-x86_64

3. To list the kit component “comp-server-1.0-1-rhels-6-x86_64” for selected kit component attributes, enter:
   lskitcomp -C kitcompname,desc comp-server-1.0-1-rhels-6-x86_64

4. To list kit components compatible with “rhels-6.2-x86_64” osdistro, enter:
   lskitcomp -O rhels-6.2-x86_64

5. To list kit components compatible with “rhels-6.2-x86_64” osdistro and “computenode” server role, enter:
   lskitcomp -O rhels-6.2-x86_64 -S computenode

6. To list the kit component “testkit-compute-1.0-1-ubuntu-14.04-ppc64el” with XML tags, enter:
   XCATXMLTRACE=1 lskitcomp -x testkit-compute-1.0-1-ubuntu-14.04-ppc64el

FILES

/opt/xcat/bin/lskitcomp

SEE ALSO

lskit(1) lskit.1, lskitdeployparam(1) lskitdeployparam.1, addkit(1) addkit.1, rmkit(1) rmkit.1, addkit-
comp(1) addkitcomp.1, rmkitcomp(1) rmkitcomp.1

lskitdeployparam.1

NAME

lskitdeployparam - Lists the deployment parameters for one or more Kits or Kit components
SYNOPSIS

lskitdeployparam [-V | --verbose] [-x | --xml | --XML] [-k | --kitname kit_names] [-c | --compname comp_names]
lskitdeployparam [-? | -h | --help | -v | --version]

DESCRIPTION

The lskitdeployparam command is used to list the kit deployment parameters for one or more kits, or one or more kit components. Kit deployment parameters are used to customize the installation or upgrade of kit components.

The lskitdeployparam command outputs the kit component information in two formats: human-readable format (default), and XML format. Use the -x option to view the information in XML format.

Input to the command can specify any combination of the input options.

Note: The xCAT support for Kits is only available for Linux operating systems.

OPTIONS

-kl--kitname kit_names

Where kit_names is a comma-delimited list of kit names. The lskitdeployparam command will only display the deployment parameters for the kits with the matching names.

-cl--compname comp_names

Where comp_names is a comma-delimited list of kit component names. The lskitdeployparam command will only display the deployment parameters for the kit components with the matching names.

-xl--xml|--XML

Return the output with XML tags. The data is returned as:

```xml
<data>
  <kitdeployparam>
    <name>KIT_KIT1_PARAM1</name>
    <value>value11</value>
  </kitdeployparam>
  <data>
  <data>
    <kitdeployparam>
      <name>KIT_KIT1_PARAM2</name>
      <value>value12</value>
    </kitdeployparam>
  </data>
  ...
</data>
```

-Vl--verbose

Display additional progress and error messages.

-vl--version

Command Version.

-?l--help

Display usage message.
RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To list kit deployment parameters for kit “kit-test1-1.0-Linux”, enter:
   
   lskitdeployparam -k kit-test1-1.0-Linux

2. To list kit deployment parameters for kit component “comp-server-1.0-1-rhel-6-x86_64”, enter:
   
   lskitdeployparam -c comp-server-1.0-1-rhel-6-x86_64

FILES

/opt/xcat/bin/lskitdeployparam

SEE ALSO

lskit(1)|lskit.1, lskitcomp(1)|lskitcomp.1, addkit(1)|addkit.1, rmkit(1)|rmkit.1, addkitcomp(1)|addkitcomp.1, rmkit-comp(1)|rmkitcomp.1

lskmodules.1

NAME

lskmodules - list kernel driver modules in rpms or driver disk image files

SYNOPSIS

lskmodules [-V | --verbose] [i | --osimage osimage_names] [-c | --kitcomponent kitcomp_names] [-o | --osdistro osdistro_names] [-u | --osdistropdate osdistropdate_names] [-x | --xml | --XML]

lskmodules [-? | -h | --help | -v | --version]

DESCRIPTION

The lskmodules command finds the kernel driver module files (*.ko) in the specified input locations, runs the modinfo command against each file, and returns the driver name and description. If -x is specified, the output is returned with XML tags.

Input to the command can specify any number or combination of the input options.
OPTIONS

-il--osimage osimage_names

where osimage_names is a comma-delimited list of xCAT database osimage object names. For each osimage_name, lskmodules will use the entries in osimage.driverupdatesrc for the rpms and driver disk image files to search.

-cl--kitcomponent kitcomponent_names

where kitcomponent_names is a comma-delimited list of xCAT database kitcomponent object names. For each kitcomponent_name, lskmodules will use the entries in kitcomponent.driverpacks for the rpm list and the repodir of the kitcomponent.kitreponame for the location of the rpm files to search.

-ol--osdistro osdistro_names

where osdistro_names is a comma-delimited list of xCAT database osdistro object names. For each osdistro_name, lskmodules will search each <osdistro.dirpaths>/Packages/kernel-<kernelversion>.rpm file.

-ul--osdistroupdate osdistroupdate_names

where osdistroupdate_names is a comma-delimited list of xCAT database osdistroupdate table entries. For each osdistroupdate_name, lskmodules will search the <osdistroupdate.dirpath>/kernel-<kernelversion>.rpm file.

-xl--xml--XML

Return the output with XML tags. The data is returned as:

```
<module>
  <name> xxx.ko </name>
  <description> this is module xxx </description>
</module>
```

This option is intended for use by other programs. The XML will not be displayed. To view the returned XML, set the XCATSHOWXML=yes environment variable before running this command.

-V|--verbose

Display additional progress and error messages.

-V|--version

Command Version.

-?|-h|--help

Display usage message.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To list the kernel modules included in the driverpacks shipped with kitcomponent kit1_comp1-x86_64, enter:
**NAME**

Lsllite - Display a summary of the statelite information.

**SYNOPSIS**

```
lsllite [-h | --help]
lsllite [-V | --verbose] [-i imagename] [noderange]
```

**DESCRIPTION**

The **lsllite** command displays a summary of the statelite information that has been defined for a noderange or an image.

**OPTIONS**

- **-h|--help**
  Display usage message.

- **-V|--verbose**
  Verbose mode.

- **-i imagename**
  The name of an existing xCAT osimage definition.

- **noderange**
  A set of comma delimited node names and/or group names. See the “noderange” man page for details on additional supported formats.

**RETURN VALUE**

0 The command completed successfully.

1 An error has occurred.
EXAMPLES

1. To list the statelite information for an xCAT node named “node01”.

   lslite node01

   Output is similar to:

   >>>Node: node01
   Osimage: 61img
   Persistent directory (statelite table):
     xcatmn1:/statelite
   Litefiles (litefile table):
     tmpfs,rw /etc/adjtime
     tmpfs,rw /etc/lvm/.cache
     tmpfs,rw /etc/mtab
     ........
   Litetree path (litetree table):
     1,MN:/etc
     2,server1:/etc

2. To list the statelite information for an xCAT osimage named “osimage01”.

   lslite -i osimage01

   Output is similar to:

   tmpfs,rw /etc/adjtime
   tmpfs,rw /etc/lvm/.cache
   tmpfs,rw /etc/mtab
   ........

FILES

/opt/xcat/bin/lslite

SEE ALSO

noderange(3)noderange.3, tabdump(8)tabdump.8

lsslp.1

NAME

lsslp - Discovers selected networked services information within the same subnet.
SYNOPSIS

lsslp [-h|--help]
lsslp [-v|--version]

DESCRIPTION

The lsslp command discovers selected service types using the -s flag. All service types are returned if the -s flag is not specified. If a specific IP address is not specified using the -i flag, the request is sent out all available network adapters. The optional -r, -x, -z and --vpdtable flags format the output. If you can’t receive all the hardware, use -T to increase the waiting time.

NOTE: SLP broadcast requests will propagate only within the subnet of the network adapter broadcast IPs specified by the -i flag.

OPTIONS

noderrange The nodes which the user wants to discover. If the user specifies the noderrange, lsslp will just return the nodes in the node range. Which means it will help to add the new nodes to the xCAT database without modifying the existed definitions. But the nodes’ name specified in noderrange should be defined in database in advance. The specified nodes’ type can be frame/cec/hmc/fsp/bpa. If the it is frame or cec, lsslp will list the bpa or fsp nodes within the nodes(bap for frame, fsp for cec). Do not use noderrange with the flag -s.

-i IP(s) the command will send out (defaults to all available adapters).

-h Display usage message.

-n Only display and write the newly discovered hardware.

-u Do unicast to a specified IP range. Must be used with -s and --range. The -u flag is not supported on AIX.

--range Specify one or more IP ranges. Must be use in unicast mode. It accepts multiple formats. For example, 192.168.1.1/24, 40-41.1-2.3-4.1-100. If the range is huge, for example, 192.168.1.1/8, lsslp may take a very long time for node scan. So the range should be exactly specified.

-r Display Raw SLP response.

-C The number of the expected responses specified by the user. When using this flag, lsslp will not return until the it has found all the nodes or time out. The default max time is 3 seconds. The user can use -T flag the specify the time they want to use. A short time will limit the time costing, while a long time will help to find all the nodes.

-T The number in seconds to limit the time of lsslp.

-s Service type interested in discovering.

-t Number or service-request attempts.

--vpdtable Output the SLP response in vpdtable formatting. Easy for writing data to vpd table.

-v Command Version.

-V Verbose output.

-w Writes output to xCAT database.

-x XML format.
-z Stanza formatted output.
-I Give the warning message for the nodes in database which have no SLP responses. Note that this flag can only be used after the database migration finished successfully.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.

**EXAMPLES**

1. To list all discovered HMC service types in tabular format, enter:

```bash
lsslp -s HMC
```

Output is similar to:

<table>
<thead>
<tr>
<th>device</th>
<th>type-model</th>
<th>serial-number</th>
<th>ip-addresses</th>
<th>hostname</th>
</tr>
</thead>
<tbody>
<tr>
<td>HMC</td>
<td>7310CR2</td>
<td>103F55A</td>
<td>1.1.1.115</td>
<td>hmc01</td>
</tr>
<tr>
<td>HMC</td>
<td>7310CR2</td>
<td>105369A</td>
<td>3.3.3.103</td>
<td>hmc02</td>
</tr>
<tr>
<td>HMC</td>
<td>7310CR3</td>
<td>KPHHK24</td>
<td>3.3.3.154</td>
<td>hmc03</td>
</tr>
</tbody>
</table>

2. list all discovered FSP service types in raw response format on subnet 30.0.0.255, enter:

```bash
lsslp -i 3.0.0.255 -s CEC -r
```

Output is similar to:

```
(type=cec-service-processor),(serial-number=10A3AEB),(machinetype-model=9117-570),
(frumerial-number=YL11C5338102),(hostname=),(frame-number=0),(cage-number=0),(ip-
address=3.0.0.94,1.1.1.147), (web-url=https://3.0.0.94:473 ), (slot=1), (bpc-
machinetype-model=0), (bpc-serial-number=0), (Image=fips240/b0630a_0623.240)
(type=cec-service-processor),(serial-number=10A3E2B),(machinetype-model=9117-570),
(frumerial-number=YL11C5338250),(hostname=),(frame-number=0),(cage-number=0),(ip-
address=3.0.0.95,1.1.1.147), (web-url=https://3.0.0.95:473 ), (slot=1), (bpc-
machinetype-model=0), (bpc-serial-number=0), (Image=fips240/b0630a_0623.240)
```

3. To list all discovered MM service types in XML format and write the output to the xCAT database, enter:

```bash
lsslp -s MM -x -w
```

Output is similar to:

```
<Node>
  <groups>mm,all</groups>
  <id>00:14:5E:E0:CB:1E</id>
  <mgt>blade</mgt>
  <mtm>029310C</mtm>
  <node>Server-029310C-SN100485A-A</node>
  <nodetype>mm</nodetype>
  <otherinterfaces>9.114.47.229</otherinterfaces>
  <serial>100485A</serial>
</Node>
```
4. To list all discovered service types in stanza format and write the output to the xCAT database, enter:

```
lsllp -z -w
```

Output is similar to:

```
c76v1hmc02:
  objtype=node
  hcp=c76v1hmc02
  nodetype=hmc
  mtm=7315CR2
  serial=10407DA
  ip=192.168.200.125
  groups=hmc,all
  mgt=hmc
  mac=00:1a:64:fb:7d:50
  hidden=0

192.168.200.244:
  objtype=node
  hcp=192.168.200.244
  nodetype=fsp
  mtm=9125-F2A
  serial=0262662
  side=A-0
  otherinterfaces=192.168.200.244
  groups=fsp,all
  mgt=fsp
  id=4
  parent=Server-9125-F2A-SN0262662
  mac=00:1a:64:fa:01:fe
  hidden=1

Server-8205-E6B-SN1074CDP:
  objtype=node
  hcp=Server-8205-E6B-SN1074CDP
  nodetype=cec
  mtm=8205-E6B
  serial=1074CDP
  groups=cec,all
  mgt=fsp
  id=0
  hidden=0

192.168.200.33:
  objtype=node
  hcp=192.168.200.33
  nodetype=bpa
  mtm=9458-100
  serial=99201NM
  side=B-0
  otherinterfaces=192.168.200.33
  groups=bpa,all
  mgt=bpa
  id=0
  mac=00:09:6b:ad:19:90
  hidden=1

Server-9125-F2A-SN0262652:
  objtype=node
  hcp=Server-9125-F2A-SN0262652
  nodetype=frame
```

(continues on next page)
5. To list all discovered service types in stanza format and display the IP address, enter:

```
lsssl -w
```

Output is similar to:

```
mm01:
    objtype=node
    nodetype=fsp
    mtm=8233-E8B
    serial=1000ECP
    side=A-0
    groups=fsp,all
    mgt=fsp
    id=0
    mac=00:14:5E:F0:5C:FD
    otherinterfaces=50.0.0.5

bpa01:
    objtype=node
    nodetype=bpa
    mtm=9A01-100
    serial=0P1N746
    side=A-1
    groups=bpa,all
    mgt=bpa
    id=0
    mac=00:1A:64:54:8C:A5
    otherinterfaces=50.0.0.1
```

6. To list all the CECs, enter:

```
lsssl -s CEC
```

```
device type-model serial-number side ip-addresses  hostname
FSP  9117-MMB  105EBEP  A-1  20.0.0.138  20.0.0.138
FSP  9117-MMB  105EBEP  B-1  20.0.0.139  20.0.0.139
CEC  9117-MMB  105EBEP  Server-9117-MMB-SN105EBEP
```

7. To list all the nodes defined in database which have no SLP response.

```
lsssl -I
```

Output is similar to:

```
These nodes defined in database but can't be discovered: f17c00bpcb_b,f17c01bpcb_a,
   →f17c01bpcb_b,f17c02bpcb_a,
  device type-model serial-number side ip-addresses hostname
```

(continues on next page)
8. To find the nodes within the user specified. Make sure the noderange input have been defined in xCAT database.

<table>
<thead>
<tr>
<th>device</th>
<th>type-model</th>
<th>serial-number</th>
<th>side</th>
<th>ip-addresses</th>
<th>hostname</th>
</tr>
</thead>
<tbody>
<tr>
<td>FSP</td>
<td>9A01-100</td>
<td>0P1P336</td>
<td>A-0</td>
<td>192.168.200.34 192.168.200.34</td>
<td></td>
</tr>
<tr>
<td>FSP</td>
<td>9A01-100</td>
<td>0P1P336</td>
<td>B-0</td>
<td>192.168.200.35 192.168.200.35</td>
<td></td>
</tr>
<tr>
<td>FSP</td>
<td>9A01-100</td>
<td>0P1P336</td>
<td>A-1</td>
<td>50.0.0.27      50.0.0.27</td>
<td></td>
</tr>
<tr>
<td>FSP</td>
<td>9A01-100</td>
<td>0P1P336</td>
<td>B-1</td>
<td>50.0.0.28      50.0.0.28</td>
<td></td>
</tr>
<tr>
<td>CEC</td>
<td>9A01-100</td>
<td>0P1P336</td>
<td></td>
<td></td>
<td>CEC1</td>
</tr>
<tr>
<td>FSP</td>
<td>8233-E8B</td>
<td>1040C7P</td>
<td>A-0</td>
<td>192.168.200.36 192.168.200.36</td>
<td></td>
</tr>
<tr>
<td>FSP</td>
<td>8233-E8B</td>
<td>1040C7P</td>
<td>B-0</td>
<td>192.168.200.37 192.168.200.37</td>
<td></td>
</tr>
<tr>
<td>FSP</td>
<td>8233-E8B</td>
<td>1040C7P</td>
<td>A-1</td>
<td>50.0.0.29      50.0.0.29</td>
<td></td>
</tr>
<tr>
<td>FSP</td>
<td>8233-E8B</td>
<td>1040C7P</td>
<td>B-1</td>
<td>50.0.0.30      50.0.0.30</td>
<td></td>
</tr>
<tr>
<td>CEC</td>
<td>8233-E8B</td>
<td>1040C7P</td>
<td></td>
<td></td>
<td>CEC2</td>
</tr>
<tr>
<td>FSP</td>
<td>8205-E6B</td>
<td>1000ECP</td>
<td>A-0</td>
<td>192.168.200.38 192.168.200.38</td>
<td></td>
</tr>
<tr>
<td>FSP</td>
<td>8205-E6B</td>
<td>1000ECP</td>
<td>B-0</td>
<td>192.168.200.39 192.168.200.39</td>
<td></td>
</tr>
<tr>
<td>FSP</td>
<td>8205-E6B</td>
<td>1000ECP</td>
<td>A-1</td>
<td>50.0.0.31      50.0.0.27</td>
<td></td>
</tr>
<tr>
<td>FSP</td>
<td>8205-E6B</td>
<td>1000ECP</td>
<td>B-1</td>
<td>50.0.0.32      50.0.0.28</td>
<td></td>
</tr>
<tr>
<td>CEC</td>
<td>8205-E6B</td>
<td>1000ECP</td>
<td></td>
<td></td>
<td>CEC3</td>
</tr>
</tbody>
</table>

9. To list all discovered CMM in stanza format, enter: lsslp -s CMM -m -z

```
e114ngmm1:
   objtype=node
   mpa=e114ngmm1
   nodetype=cmm
   mtm=98939AX
   serial=102537A
   groups=cmm,all
   mgt=blade
   hidden=0
   otherinterfaces=70.0.0.30
   hwtype=cmm
```

10. To use lsslp unicast, enter:

```
lsslp -u -s CEC --range 40-41.1-2.1-2.1-2
```

FILES

`/opt/xcat/bin/lsslp`

SEE ALSO

`rscan(1)`| `rscan.1` | `lstree.1`
NAME

lstree - Display the tree of service node hierarchy, hardware hierarchy, or VM hierarchy.

SYNOPSIS

lstree [-h | --help]

lstree [-s | --servicenode] [-H | --hardwaremgmt] [-v | --virtualmachine] [noderange]

DESCRIPTION

The lstree command can display the tree of service node hierarchy for the xCAT nodes which have service node defined or which are service nodes, display the tree of hardware hierarchy only for the physical objects, display the tree of VM hierarchy for the xCAT nodes which are virtual machines or which are the hosts of virtual machines. If a noderange is specified, only show the part of the hierarchy that involves those nodes. For ZVM, we only support to display VM hierarchy. By default, lstree will show both the hardware hierarchy and the VM hierarchy for all the nodes.

OPTIONS

-h|--help

Display usage message.

-s|--servicenode

Show the tree of service node hierarchy.

-H|--hardwaremgmt

Show the tree of hardware hierarchy.

-v|--virtualmachine

Show the tree of VM hierarchy.

noderange

A set of comma delimited node names and/or group names. See the “noderange” man page for details on additional supported formats.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To display the tree of service node hierarchy for all the nodes.

   lstree -s

   Output is similar to:
2. To display the tree of service node hierarchy for service node “mysn01”.

\texttt{lstree -s mysn01}

Output is similar to:

Service Node: mysn01
|  |__mycn01
|  |__mycn02
|  |__mycn03

3. To display the tree of hardware hierarchy for all the nodes.

\texttt{lstree -H}

Output is similar to:

HMC: myhm01
|  |__Frame: myframe01
|   |__CEC: mycec01
|   |__CEC: mycec02
|   ......

Service Focal Point: myhm02
|  |__Frame: myframe01
|   |__CEC: mycec01
|   |__CEC: mycec02
|   |__CEC: mycec03
|   ......

Management Module: mymm01
|  |__Blade 1: js22n01
|  |__Blade 2: js22n02
|  |__Blade 3: js22n03
|  ......

BMC: 192.168.0.1
|  |__Server: x3650n01

4. To display the tree of hardware hierarchy for HMC “myhm01”.

\texttt{lstree -H myhm01}

Output is similar to:
5. To display the tree of VM hierarchy for all the nodes.

```
ls tree -v
```

Output is similar to:

```
Server: hs22n01
    |__ hs22vm1

Server: x3650n01
    |__ x3650n01kvm1
    |__ x3650n01kvm2
```

6. To display the tree of VM hierarchy for the node “x3650n01”.

```
ls tree -v x3650n01
```

Output is similar to:

```
Server: x3650n01
    |__ x3650n01kvm1
    |__ x3650n01kvm2
```

7. To display both the hardware tree and VM tree for all nodes.

```
ls tree
```

Output is similar to:

```
HMC: myhmc01
    |__ Frame: myframe01
    |    |__ CEC: mycec01
    |    |__ CEC: mycec02
    ......

Service Focal Point: myhmc02
    |__ Frame: myframe01
    |    |__ CEC: mycec01
    |    |__ LPAR 1: node01
    |    |__ LPAR 2: node02
    |    |__ LPAR 3: node03
    ......
    |__ CEC: mycec02
    |    |__ LPAR 1: node11
    |    |__ LPAR 2: node12
    |    |__ LPAR 3: node13
    ......
```

(continues on next page)
FILES

/opt/xcat/bin/lstree

SEE ALSO

noderange(3) noderange.3, tabdump(8) tabdump.8

lsve.1

NAME

lsve - Lists detail attributes for a virtual environment.

SYNOPSIS

lsve [-t type] [-m manager] [-o object]

DESCRIPTION

The lsve command can be used to list a virtual environment for ‘Data Center’, ‘Cluster’, ‘Storage Domain’, ‘Network’ and ‘Template’ objects.

The mandatory parameter -m manager is used to specify the address of the manager of virtual environment. xCAT needs it to access the RHEV manager.

The mandatory parameter -t type is used to specify the type of the target object.

Basically, lsve command supports three types of object: dc, cl, sd, nw and tpl.

The parameter -o object is used to specify which object to list. If no -o is specified, all the objects with the -t type will be displayed.
OPTIONS

-h Display usage message.

-m Specify the manager of the virtual environment.

    For RHEV, the FQDN (Fully Qualified Domain Name) of the rhev manager have to be specified.

-o The target object to display.

-t Specify the type of the target object.

    Supported types:

    B<dc> - Data Center (For type of 'dc', all the elements belongs to the data center will be listed.)
    B<cl> - Cluster
    B<sd> - Storage Domain (To get the status of Storage Domain, show it from I <data center> it attached to.
    B<nw> - Network
    B<td> - Template

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To list the data center ‘Default’, enter:

   lsve -t dc -m <FQDN of rhev manager> -o Default

   Output is similar to:

   datacenters: [Default]
   description: The default Data Center
   state: up
   storageformat: v1
   storagetype: nfs
   clusters: [Default]
       cpu: Intel Westmere Family
       description: The default server cluster
       memory_hugepage: true
       memory_overcommit: 100
   storagedomains: [image]
       available: 55834574848
       committed: 13958643712
       ismaster: true
       status: active
       storage_add: <Address of storage domain>
       storage_format: v1
       storage_path: /vfsimg
       storage_type: nfs
       type: data

(continues on next page)
used: 9663676416
networks: [rhevm2]
  description:
  state: operational
  stp: false
networks: [rhevm]
  description: Management Network
  state: operational
  stp: false
templates: [Blank]
  bootorder: hd
  cpucore: 1
  cpusocket: 1
  creation_time: 2008-04-01T00:00:00.000-04:00
  display: spice
  memory: 536870912
  state: ok
  stateless: false
  type: desktop

2. To list the cluster ‘Default’, enter:

   lsve -t cl -m <FQDN of rhev manager> -o Default

   Output is similar to:

   cpu: Intel Westmere Family
   description: The default server cluster
   memory_hugepage: true
   memory_overcommit: 10

3. To list the Storage Domain ‘image’, enter:

   lsve -t sd -m <FQDN of rhev manager> -o image

   Output is similar to:

   storagedomains: [image]
     available: 55834574848
     committed: 13958643712
     ismaster: true
     status:
     storage_add: <Address of storage domain>
     storage_format: v1
     storage_path: /vfsimg
     storage_type: nfs
     type: data
     used: 9663676416

4. To list the network ‘rhevm’, enter:

   lsve -t nw -m <FQDN of rhev manager> -o rhevm

   Output is similar to:
5. To list the template ‘tpl01’, enter:

```
lsve -t tpl -m <FQDN of rhev manager> -o tpl01
```

Output is similar to:

```
templates: [tpl01]
  bootorder: network
cpucore: 2
cpusocket: 2
creation_time: 2012-08-22T23:52:35.953-04:00
display: vnc
memory: 1999634432
state: ok
stateless: false
type: server
```

FILES

```
/opt/xcat/bin/lsve
```

SEE ALSO

```
cfgve(1)cfgve.1
lsvlan.1
```

NAME

lsvlan - It lists the existing vlans for the cluster.

SYNOPSIS

```
lsvlan
lsvlan [vlanid]
lsvlan [-h | --help]
lsvlan [-v | --version]
```

DESCRIPTION

The lsvlan command lists all the vlans for the cluster. If vlanid is specified it will list more details about this vlan including the nodes in the vlan.
PARAMETERS

`vlanid` is a unique vlan number. If it is omitted, all vlans will be listed.

OPTIONS

- **-h|--help** Display usage message.
- **-v|--version** Command Version.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To list all the vlans in the cluster

   `lsvlan`

   Output is similar to:

   ```
   vlan 3:
   subnet 10.3.0.0
   netmask 255.255.0.0
   vlan 4:
   subnet 10.4.0.0
   netmask 255.255.0.0
   ```

2. To list the details for vlan3

   `lsvlan 3`

   Output is similar to:

   ```
   vlan 3
   subnet 10.3.0.0
   netmask 255.255.0.0
   hostname    ip address    node    vm host
   v3n1  10.3.0.1    c68m4hsp06
   v3n2  10.3.0.2    x3455n01
   v3n3  10.3.0.3    x3650n01
   v3n4  10.3.0.4    x3650n01kvm1  x3650n01
   v3n5  10.3.0.5    x3650n01kvm2  x3650n01
   ```

FILES

```
/opt/xcat/bin/lsvlan
```
SEE ALSO

mkvlan(1)|mkvlan.1, rmvlan(1)|rmvlan.1, chvlan(1)|chvlan.1

NAME

lsvm - Lists partition profile information for HMC-, DFM-, IVM-, KVM-, VMware- and zVM-managed nodes. For Power 775, it lists the LPARs' I/O slots information and CEC configuration.

SYNOPSIS

lsvm [-h | --help]

lsvm [-v | --version]

lsvm [-V | --verbose] noderange

lsvm [-a | --all] noderange

For PPC (using Direct FSP Management):

lsvm [-l | --long] --p775 noderange

lsvm noderange

For KVM and VMware

lsvm noderange

For zVM:

lsvm noderange

DESCRIPTION

The lsvm command lists all partition profiles defined for the partitions specified in noderange. If noderange is a CEC, all the partitions associated with that CEC are displayed.

For PPC (using Direct FSP Management):

For Power 775 (use option --p775 to specify), lsvm lists all partition I/O slots information for the partitions specified in noderange. If noderange is a CEC, it gets the CEC’s pump mode value, octant’s memory interleaving value, the all the octants configure value, and all the I/O slots information.

For DFM-managed (short for Direct FSP Management mode) normal power machine, lsvm lists the processor, memory, physical I/O slots, hugepage and BSR info for the specified partitions or CEC.
The pump mode value has the valid options: 1 - Node Pump Mode 2 - Chip Pump Mode

The Memory Interleaving Mode has 3 valid options: 0 - not Applicable 1 - interleaved 2 - non-interleaved

More information about this part, refer to the section Using the *vm commands to define partitions in xCAT DFM in the doc below:

XCAT_Power_775_Hardware_Management

For KVM and VMware

If noderange is a hypervisor, virtual machines defined on that hypervisor will be displayed. If noderange is a VM, details for that VM will be displayed.

Note: Only the virtual machine which is in power on state can be listed by lsvm command.

For zVM:

Show the directory entry for a given virtual machine.

OPTIONS

-h
Display usage message.

-v
Command version.

-V
Verbose output.

-a
List all the profiles for one partition

--p775
Specify the operation is for Power 775 machines.

-l
Show lparnames for lpars. It shall work with option --p775.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To list all partition profiles defined for HMC-managed partition lpar3, enter:

   lsvm lpar3

   Output is similar to:
2. To list all IVM-managed partitions associated with CEC cec01, enter:

```
lsvm cec01
```

Output is similar to:

```
cec01: name=10-B7D1G,lpar_name=10-B7D1G,lpar_id=1,os_type=vioserver,all_resources=0,min_mem=512, desired_mem=2048,max_mem=2048,proc_mode=shared,min_proc_units=0.10,desired_proc_units=0.10,max_proc_units=4.00, desired_proc=4,sharing_mode=uncap,uncap_weight=128, "io_slots=21010002/none/0,21010003/none/0,21020003/none/0,21020004/none/0,21030003/none/0,21030004/none/0",lpar_io_pool_ids=none,max_virtual_slots=48, "virtual_serial_adapters=0/server/1/any/any/1,0/server/1/any/any/1", virtual_scsi_adapters=2/"client/1/p6vios/4/1,virtual_eth_adapters=3/0/1/0/1,hca_adapters=none,boot_mode=norm,conn_monitoring=0,auto_start=0,power_ctrl_lpar_ids=none
```

3. For Power 775, to list the I/O slot information of lpar1, enter:

```
lsvm lpar1 --p775
```

Output is similar to:

```
1: 514/U78A9.001.0123456-P1-C17/0x21010202/2/1
1: 513/U78A9.001.0123456-P1-C15/0x21010201/2/1
1: 512/U78A9.001.0123456-P1-C16/0x21010200/2/1
```

4. To list the lparname of lpar1s, enter:

```
lsvm lpar1 -1 --p775
```

```
1.3. Admin Guide 301
```
Output is similar to:

```
lsvm cec1 --p775
```

Output is similar to:

```
lpar: 1: 514/U78A9.001.0123456-P1-C17/0x21010202/2/1
lpar: 1: 513/U78A9.001.0123456-P1-C15/0x21010201/2/1
lpar: 1: 512/U78A9.001.0123456-P1-C16/0x21010200/2/1
```

5. For Power 775, to list the I/O slot information and octant configuration of cec1, enter:

```
lsvm cec1 --p775
```

Output is similar to:

```
lpar1: 1: 514/U78A9.001.0123456-P1-C17/0x21010202/2/1: 32: 0/3/3
lpar1: 1: 513/U78A9.001.0123456-P1-C15/0x21010201/2/1: 32: 0/3/3
lpar1: 1: 512/U78A9.001.0123456-P1-C16/0x21010200/2/1: 32: 0/3/3
```

6. To list the lparname of lpars, enter:

```
lsvm cec1 -l --p775
```

Output is similar to:

```
lpar1: 1: 514/U78A9.001.0123456-P1-C17/0x21010202/2/1: 32: 0/3/3
lpar1: 1: 513/U78A9.001.0123456-P1-C15/0x21010201/2/1: 32: 0/3/3
lpar1: 1: 512/U78A9.001.0123456-P1-C16/0x21010200/2/1: 32: 0/3/3
```
7. To list the virtual machine’s directory entry:

```
lsvm gpok3
```

Output is similar to:

```
gpok3: USER LNX3 PWD 512M 1G G
gpok3: INCLUDE LNXDFLT
gpok3: COMMAND SET VSWITCH VSW2 GRANT LNX3
```

8. For DFM-managed normal power machine, list out the detailed resource information:

```
lsvm cec
```

Output is similar to:
<table>
<thead>
<tr>
<th>Task</th>
<th>Details</th>
</tr>
</thead>
<tbody>
<tr>
<td>HYP Configurable Processors</td>
<td>16, Avail Processors: 16.</td>
</tr>
<tr>
<td>HYP Configurable Memory</td>
<td>32.00 GB (128 regions)</td>
</tr>
<tr>
<td>HYP Available Memory</td>
<td>31.25 GB (125 regions)</td>
</tr>
<tr>
<td>HYP Memory Region Size</td>
<td>0.25 GB (256 MB)</td>
</tr>
<tr>
<td>All Physical I/O info</td>
<td></td>
</tr>
<tr>
<td>Available huge page memory (in pages)</td>
<td>2</td>
</tr>
<tr>
<td>Configurable huge page memory (in pages)</td>
<td>2</td>
</tr>
<tr>
<td>Page Size (in GB)</td>
<td>16</td>
</tr>
<tr>
<td>Maximum huge page memory (in pages)</td>
<td>4</td>
</tr>
<tr>
<td>Requested huge page memory (in pages)</td>
<td>2</td>
</tr>
<tr>
<td>Barrier Synchronization Register (BSR)</td>
<td></td>
</tr>
<tr>
<td>Number of BSR arrays</td>
<td>256</td>
</tr>
<tr>
<td>Bytes per BSR array</td>
<td>4096</td>
</tr>
<tr>
<td>Available BSR array</td>
<td>256</td>
</tr>
</tbody>
</table>

Note: The lines listed in “All Physical I/O info” section represent all the physical I/O resource information. The format is like “owner_lparid.slot_id,physical resource name,drc_index,slot_class_code(class description)”. The ‘drc index’ is short for Dynamic Resource Configuration Index, it uniquely indicates a physical I/O resource in a normal power machine.

9. For DFM-managed partition on normal power machine, list out the detailed information:

```bash
lsvm lpar1
```

Output is similar to:

```
lpar1: Lpar Processor Info:
Curr Processor Min: 1.
Curr Processor Req: 16.
Curr Processor Max: 16.
lpar1: Lpar Memory Info:
Curr Memory Min: 0.25 GB (1 regions).
Curr Memory Req: 30.75 GB (123 regions).
Curr Memory Max: 32.00 GB (128 regions).
lpar1: 1,519,U78AA.001.WZSGVU7-P1-C7,0x21010207,0xffff (Empty Slot)
lpar1: 1,518,U78AA.001.WZSGVU7-P1-C6,0x21010206,0xffff (Empty Slot)
lpar1: 1,517,U78AA.001.WZSGVU7-P1-C5,0x21010205,0xffff (Empty Slot)
lpar1: 1,516,U78AA.001.WZSGVU7-P1-C4,0x21010204,0xffff (Empty Slot)
lpar1: 1,514,U78AA.001.WZSGVU7-P1-C19,0x21010202,0xffff (Empty Slot)
lpar1: 1,513,U78AA.001.WZSGVU7-P1-T7,0x21010201,0xc03 (USB Controller)
lpar1: 1,512,U78AA.001.WZSGVU7-P1-T9,0x21010200,0x104 (RAID Controller)
lpar1: 1/2/2
lpar1: 256.
```

FILES

```
/opt/xcat/bin/lsvm
```
NAME

lsxcatd - lists xCAT daemon information.

SYNOPSIS

lsxcatd [-h | --help | -v | --version | -d | --database | -t | --nodetype | -a | --all ]

DESCRIPTION

The lsxcat command lists important xCAT daemon (xcatd) information.

OPTIONS

-v|--version
    Command Version.

-h|--help
    Display usage message.

-d|--database
    Displays information about the current database being used by xCAT.

-t|--nodetype
    Displays whether the node is a Management Node or a Service Node.

-a|--all
    Displays all information about the daemon supported by the command.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To display information about the current database:

    lsxcatd -d

    Output is similar to:
2. To display all information:

   lsxcatd -a

Output is similar to:

```
Version 2.8.5 (git commit 0d4888af5a7a96ed521cb0e32e2c918a9d13d7cc, built Tue Jul 29 02:22:47 EDT 2014)
This is a Management Node
```

FILES

```
/opt/xcat/bin/lsxcatd
```

SEE ALSO

makentp.1

SYNOPSIS

makentp [-h|--help]
makentp [-v|--version]
makentp [-a|--all] [-V|--verbose]

DESCRIPTION

makentp command sets up the NTP server on the xCAT management node and the service node.

By default, it sets up the NTP server for xCAT management node. If -a flag is specified, the command will setup the ntp servers for management node as well as all the service nodes that have `servicenode.ntpserver` set. It honors the site table attributes `extntpservers` and `ntpservers` described below:

- `site.extntpservers` – the NTP servers for the management node to sync with. If it is empty then the NTP server will use the management node’s own hardware clock to calculate the system date and time.

- `site.ntpservers` – the NTP servers for the service node and compute node to sync with. The keyword `<xcatmaster>` means that the node’s NTP server is the node that is managing it (either its service node or the management node).

To setup NTP on the compute node, add `setupntp` postscript to the `postscripts` table and run `updatenode node -P setupntp` command.
OPTIONS

-al|--all
   Setup NTP servers for both management node and the service node. If management node has SLES installed and used as ntpservers, it is recommended to use the setupntp postscript to set up NTP server for service nodes.

-h|--help
   Display usage message.

-v|--version
   Command Version.

-V|--verbose
   Verbose output.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To setup NTP server on the management node:

   makentp

2. To setup NTP servers on both management node and the service node:

   makentp -a

FILES

/opt/xcat/bin/makentp

SEE ALSO

mkdef.1

NAME

mkdef - Use this command to create xCAT data object definitions.
SYNOPSIS

mkdef [-h | --help] [-t object-types]


DESCRIPTION

This command is used to create xCAT object definitions which are stored in the xCAT database. If the definition already exists it will return an error message. The force option may be used to re-create a definition. In this case the old definition will be remove and the new definition will be created.

OPTIONS

attr=val [attr=val ...]

Specifies one or more “attribute equals value” pairs, separated by spaces. Attr=val pairs must be specified last on the command line. Use the help option to get a list of valid attributes for each object type.

Note: when creating node object definitions, the ‘groups’ attribute is required.

-d|--dynamic

Use the dynamic option to create dynamic node groups. This option must be used with -w option.

-f|--force

Use the force option to re-create object definitions. This option removes the old definition before creating the new one.

-h|--help

Display usage message.

noderange

A set of comma delimited node names and/or group names. (must be the first parameter) See the “noderange” man page for details on supported formats.

-o object-names

A set of comma delimited object names.

-t object-types

A set of comma delimited object types. Use the help option to get a list of valid object types.

--template template-object-name

Name of the xCAT shipped object definition template or an existing object, from which the new object definition will be created. The newly created object will inherit the attributes of the template definition unless the attribute is specified in the arguments of mkdef command. If there are a template and an existing object with the same name template-object-name, the template object takes precedence over the existing object. For the details of xCAT shipped object definition templates, refer to the manpage of --template option in lsdef(1)|lsdef.1.

-V|--verbose

Verbose mode.
-w attr==val -w attr!=val ...

Use one or multiple -w flags to specify the selection string that can be used to select objects. The operators ==, !=, =~ and !~ are available. For mkdef command, the -w flag only makes sense for creating dynamic node group. Use the help option to get a list of valid attributes for each object type.

**Operator descriptions:** == Select nodes where the attribute value is exactly this value. != Select nodes where the attribute value is not this specific value. =~ Select nodes where the attribute value matches this regular expression. !~ Select nodes where the attribute value does not match this regular expression.

Note: if the “val” fields includes spaces or any other characters that will be parsed by shell, the “attr<operator>val” needs to be quoted. If the operator is “!~”, the “attr<operator>val” needs to be quoted using single quote.

-z|--stanza

Indicates that the file being piped to the command is in stanza format. See the xcatstanzaf ile man page for details on using xCAT stanza files.

-u

Fill in the attributes such as template file, pkglist file and otherpkglist file of osimage object based on the specified parameters. It will search “/install/custom/” directory first, and then “/opt/xcat/share/”. The provmethod and profile must be specified. If osvers or osarch is not specified, the corresponding value of the management node will be used.

Note: this option only works for objtype osimage.

**RETURN VALUE**

0 The command completed successfully.

1 An error has occurred.

**EXAMPLES**

1. To create a site definition.

   mkdef -t site -o clustersite installdir=/xcatinstall

2. To create a basic node definition.

   mkdef -t node -o node01 groups="all,aix"

3. To re-create the current definition of “node01”.

   mkdef -f -t node -o node01 nodetype=osi groups="linux"

   (The group definitions are also created if they don’t already exist.)

4. To create a set of different types of definitions based on information contained in a stanza file.

   cat defstanzaf ile | mkdef -z

5. To create a group definition called LinuxNodes containing the nodes clstrn01 and clstrn02.
mkdef -t group -o LinuxNodes members="clstrn01,clstrn02"

6. To create a node definition for an FSP node using the attributes provided by the group fsnpnodes.
   mkdef -t node fsnp1 groups=fsnpnodes nodetype=fsp

7. To create node definitions for a set of node host names contained in the node range “node1,node2,node3”
   mkdef -t node node1,node2,node3 power=hmc groups="all,aix"

8. To create a dynamic node group definition called HMCMgtNodes containing all the HMC managed nodes
   mkdef -t group -o HMCMgtNodes -d -w mgt==hmc -w cons==hmc

9. To create a dynamic node group definition called SLESNodes containing all the SLES nodes
   mkdef -t group -o SLESNodes -d -w "os=~^sles[0-9]+$"

10. To create an entry (7.0) in the policy table for user admin1
    mkdef -t policy -o 7.0 name=admin1 rule=allow

11. To create a node definition with nic attributes
    mkdef -t node cn1 groups=all nicips.eth0="1.1.1.1|1.2.1.1" nicnetworks.eth0="net1|net2" nictypes.eth0="Ethernet"

12. To create an osimage definition and fill in attributes automatically.
    mkdef redhat6img -u profile=compute provmethod=statelite

13. To create a PowerLE kvm node definition with the xCAT shipped template “ppc64lekvmguest-template”.
    mkdef -t node cn1 --template ppc64lekvmguest-template ip=1.1.1.1
                   -mac=42:3d:0a:05:27:0b vmhost=1.1.0.1 vmnics=br0

14. To create a node definition from an existing node definition “cn1”
    mkdef -t node cn2 --template cn1 ip=1.1.1.2 mac=42:3d:0a:05:27:0c

FILES

$XCATROOT/bin/mkdef

(The XCATROOT environment variable is set when xCAT is installed. The default value is “/opt/xcat”.)

NOTES

This command is part of the xCAT software product.

SEE ALSO

chdef(1)chdef.1, lsdef(1)llsdef.1, rmdef(1)rmdef.1, xcatstanzafile(5)xcatstanzafile.5
mkdocker.1

NAME

mkdocker - Create docker instance.

SYNOPSIS

mkdocker noderange [image=image_name [command=command]] [dockerflag=flags_to_create_instance]
mkdocker [-h | --help]
mkdocker [-v | --version]

DESCRIPTION

mkdocker To create docker instances with the specified image, command and/or dockerflags.

OPTIONS

image
   The docker image name that the instance will use.

command
   The command that the instance will run based on the image specified. The image option must be specified in order to use this option.

dockerflag
   A JSON string which will be used as parameters to create a docker. Reference https://docs.docker.com/engine/reference/api/docker_remote_api_v1.22/ for more information about which parameters can be specified.

   Some useful flags are:

      AttachStdin=true | false
         Whether attaches to stdin.

      AttachStdout=true | false
         Whether attaches to stdout.

      AttachStderr=true | false
         Whether attaches to stderr.

      OpenStdin=true | false
         Whether opens stdin.

      Tty=true | false
         Attach standard streams to a tty, including stdin if it is not closed.

      ExposedPorts
         An object mapping ports to an empty object in the form of:
"ExposedPorts": { "<port>/\<tcp|udp>: {}" }

HostConfig: ("Binds")
A list of volume bindings for this docker instance, the form will be:

"HostConfig": {"Binds": ["<dir_on_dockerhost>:<dir_in_instance>"]}

EXAMPLES

1. To create a basic docker instance with stdin opened

```
mkdocker host01c01 image=ubuntu command=/bin/bash dockerflag="{"AttachStdin":true,"AttachStdout":true,"AttachStderr":true,"OpenStdin":true}"
```

Output is similar to:

```
host01c01: Pull image ubuntu start
host01c01: Pull image ubuntu done
host01c01: Remove default network connection
host01c01: Connecting customized network 'mynet0'
host01c01: success
```

2. To create a docker instance which have dir “destdir” in docker instance bind from “srcdir” on dockerhost, and have “Tty” opened with which the docker instance can be attached after started to check the files under “destdir”.

```
mkdocker host01c01 image=ubuntu command=/bin/bash dockerflag="{"AttachStdin":true,"AttachStdout":true,"AttachStderr":true,"OpenStdin":true,"Tty":true,"HostConfig":{"Binds": ["/srcdir:/destdir"]}}"
```

Output is similar to:

```
host01c01: Remove default network connection
host01c01: Connecting customized network 'mynet0'
host01c01: success
```

SEE ALSO

rmdocker(1) rmdocker.1, lsdocker(1) lsdocker.1

**mkdsklsnode.1**

**NAME**

mkdsklsnode - Use this xCAT command to define and initialize AIX/NIM diskless machines.

**SYNOPSIS**

mkdsklsnode [-hl--help ]

DESCRIPTION

This xCAT command can be used to define and/or initialize AIX/NIM diskless machines. Once this step is completed you can use either the xCAT `rnetboot` command or the `rbootseq/rpower` commands to initiate a network boot of the nodes.

The command can be used to define and initialize a new NIM machine object or it can be used to reinitialize an existing machine to use a different operating system image.

This command will also create a NIM `resolv_conf` resource to be used when installing the node. If a `resolv_conf` resource is not already included in the xCAT osimage definition and if the “domain” and “nameservers” values are set then a new NIM `resolv_conf` resource will be created and allocated to the nodes.

The “domain” and “nameservers” attributes can be set in either the xCAT “network” definition used by the nodes or in the xCAT cluster “site” definition. The setting in the “network” definition will take priority.

The “search” field of the resolv.conf file will contain a list all the domains listed in the xCAT network definitions and the xCAT site definition.

The “nameservers” value can either be set to a specific IP address or the “<xcatmaster>” key word. The “<xcatmaster>” key word means that the value of the “xcatmaster” attribute of the node definition will be used in the `/etc/resolv.conf` file. (i.e. The name of the install server as known by the node.)

You can set the “domain” and “nameservers” attributes by using the `chdef` command. For example:

```
chdef -t network -o clstr_net domain=cluster.com nameservers=<xcatmaster>
```

If the “domain” and “nameservers” attributes are not set in either the nodes “network” definition or the “site” definition then no new NIM `resolv_conf` resource will be created.

If you are using xCAT service nodes the `mkdsklsnode` command will automatically determine the correct server(s) for the node and create the NIM definitions on that server(s).

When creating a new NIM machine definition the default is to use the same name as the xCAT node name that is provided.

You can use the “-n” option of the `mkdsklsnode` command to create and initialize an alternate NIM machine definition for the same physical nodes. This option allows you to set up a new image to use when a node is next rebooted while the node is currently running. This is possible because the NIM name for a machine definition does not have to be the hostname of the node. This allows you to have multiple NIM machine definitions for the same physical node. The naming convention for the new NIM machine name is “<xcat_node_name>_<image_name>”, (Ex. “node01_61spot”). Since all the NIM initialization can be done while the node is running the downtime for for the node is reduced to the time it takes to reboot.

**Note:** When using the “-n” option make sure that the new osimage you specify and all the NIM resources that are used are different than what are currently being used on the nodes. The NIM resources should not be shared between the old osimage and the new osimage.

You can use the force option to reinitialize a node if it already has resources allocated or it is in the wrong NIM state. This option will reset the NIM node and deallocate resources before reinitializing. Use this option with caution since reinitializing a node will stop the node if it is currently running.

After the `mkdsklsnode` command completes you can use the `lsnim` command to check the NIM node definition to see if it is ready for booting the node. ("lsnim -l <nim_node_name>").

You can supply your own scripts to be run on the management node or on the service node (if their is hierarchy) for a node during the `mkdsklsnode` command. Such scripts are called `prescripts`. They should be copied to /install/prescripts directory. A table called `prescripts` is used to specify the scripts and their associated actions. The scripts to be run at the beginning of the `mkdsklsnode` command are stored in the ‘begin’ column of `prescripts` tabble. The scripts to be run at the end of the `mkdsklsnode` command are stored in the ‘end’ column of `prescripts`
table. Run `tabdump prescripts -d` command for details. An example for the ‘begin’ or the ‘end’ column is: *diskless:myscript1,myscript2*. The following two environment variables will be passed to each script: NODES contains all the names of the nodes that need to run the script for and ACTION contains the current nodeset action, in this case “diskless”. If #xCAT setting:*MAX_INSTANCE=number* is specified in the script, the script will get invoked for each node in parallel, but no more than *number* of instances will be invoked at a time. If it is not specified, the script will be invoked once for all the nodes.

**OPTIONS**

```
attr=val [attr=val ...]
```

Specifies one or more “attribute equals value” pairs, separated by spaces. Attr= val pairs must be specified last on the command line. These are used to specify additional values that can be passed to the underlying NIM commands.

Valid values:

**duplex**

Specifies the duplex setting (optional). Used when defining the NIM machine. Use this setting to configure the client’s network interface. This value can be full or half. The default is full. (ex. “duplex=full”)

**speed**

Specifies the speed setting (optional). Used when defining the NIM machine. This is the communication speed to use when configuring the client’s network interface. This value can be 10, 100, or 1000. The default is 100. (ex. “speed=100”)

**psize**

Specifies the size in Megabytes of the paging space for the diskless node. (optional) Used when initializing the NIM machine. The minimum and default size is 64 MB of paging space. (ex. “psize=256”)

**sparse_paging**

Specifies that the paging file should be created as an AIX sparse file, (ex. “sparse_paging=yes”). The default is “no”.

**dump_iscsi_port**

The tcpip port number to use to communicate dump images from the client to the dump resource server. Normally set by default. This port number is used by a dump resource server.

**configdump**

Specifies the type dump to be collected from the client. The values are “selective”, “full”, and “none”. If the configdump attribute is set to “full” or “selective” the client will automatically be configured to dump to an iSCSI target device. The “selective” memory dump will avoid dumping user data. The “full” memory dump will dump all the memory of the client partition. Selective and full memory dumps will be stored in subdirectory of the dump resource allocated to the client. This attribute is saved in the xCAT osimage definition.

**-b**|--backupSN

When using backup service nodes only update the backup. The default is to update both the primary and backup service nodes.

**-f**|--force

Use the force option to reinitialize the NIM machines.
-h |--help

Display usage message.

-i image_name

The name of an existing xCAT osimage definition. If this information is not provided on the command line the code checks the node definition for the value of the “provmethod” attribute. If the “-i” value is provided on the command line then that value will be used to set the “provmethod” attribute of the node definitions.

-kl|--skipsync

Use this option to have the mkdsklsnode command skip the NIM sync_roots operation. This option should only be used if you are certain that the shared_root resource does not have to be updated from the SPOT. Normally, when the SPOT is updated, you should do a sync_roots on the shared_root resource.

-li|--location

The directory location to use when creating new NIM resolv_conf resources. The default location is /install/nim.

-n|--newname

Create a new NIM machine object name for the xCAT node. Use the naming convention “<xcat_node_name>_<image_name>” for the new NIM machine definition.

-pl|--primarySN

When using backup service nodes only update the primary. The default is to update both the primary and backup service nodes.

-Sl|--setuphanfs

Setup NFSv4 replication between the primary service nodes and backup service nodes to provide high availability NFS for the compute nodes. This option only exports the /install directory with NFSv4 replication settings, the data synchronization between the primary service nodes and backup service nodes needs to be taken care of through some mechanism.

-ul|--updateSN

Use this option if you wish to update the osimages but do not want to define or initialize the NIM client definitions. This option is only valid when the xCAT “site” definition attribute “sharedinstall” is set to either “sns” or “all”.

noderange

A set of comma delimited node names and/or group names. See the “noderange” man page for details on additional supported formats.

-V |--verbose

Verbose mode.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.
EXAM PLES

1. Initialize an xCAT node named “node01” as an AIX diskless machine. The xCAT osimage named “61spot” should be used to boot the node.

   mkdsklsnode -i 61spot node01

2. Initialize all AIX diskless nodes contained in the xCAT node group called “aixnodes” using the image definitions pointed to by the “provmethod” attribute of the xCAT node definitions.

   mkdsklsnode aixnodes

3. Initialize diskless node “clstrn29” using the xCAT osimage called “61dskls”. Also set the paging size to be 128M and specify the paging file be an AIX sparse file.

   mkdsklsnode -i 61dskls clstrn29 psize=128 sparse_paging=yes

4. Initialize an xCAT node called “node02” as an AIX diskless node. Create a new NIM machine definition name with the osimage as an extension to the xCAT node name.

   mkdsklsnode -n -i 61spot node02

FILES

/opt/xcat/bin/mkdsklsnode

NOTES

This command is part of the xCAT software product.

SEE ALSO

rmdsklsnode(1)|rmdsklsnode.1

mkflexnode.1

NAME

mkflexnode - Create a flexible node.

SYNOPSIS

mkflexnode [-h | --help]
mkflexnode [-v | --version]
mkflexnode noderange
DESCRIPTION

A flexible node is a **Partition** in a complex. Creating a flexible node is to create a partition which including all the slots defined in the xCAT blade node.

Before creating a flexible node, a general xCAT blade node should be defined. The *id* attribute of this node should be a node range like ‘a-b’, it means the blades installed in slots ‘a-b’ need to be assigned to the partition. ‘a’ is the start slot, ‘b’ is the end slot. If this partition only have one slot, the slot range can be ‘a’.

The action of creating flexible node will impact the hardware status. Before creating it, the blades in the slot range should be in **power off** state.

After the creating, use the `lsflexnode` to check the status of the node.

The *noderange* only can be a blade node.

OPTIONS

- **-h | --help**
  
  Display the usage message.

- **-v | --version**
  
  Display the version information.

EXAMPLES

1. Create a flexible node base on the xCAT node blade1.
   
   The blade1 should belong to a complex, the *id* attribute should be set correctly and all the slots should be in **power off** state.

   ```
   mkflexnode blade1
   ```

FILES

`/opt/xcat/bin/mkflexnode`

SEE ALSO

`lsflexnode(1)`| `lsflexnode.1` | `rmflexnode(1)`| `rmflexnode.1`

`mkhwconn.1`

NAME

`mkhwconn` - Sets up connections for CEC and Frame nodes to HMC nodes or hardware server.
SYNOPSIS

mkhwconn [-h|--help]
mkhwconn [-v|--version]

PPC (with HMC) specific:

mkhwconn [-V|--verbose] noderange -t [--port port_value]
mkhwconn [-V|--verbose] noderange -s [hmcnode --port port_value]
mkhwconn [-V|--verbose] noderange -p hmc [-P passwd] [--port port_value]

PPC (using Direct FSP Management) specific:

mkhwconn noderange -t [-T tooltype] [--port port_value]

DESCRIPTION

For PPC (with HMC) specific:

This command is used to set up connections for CEC and Frame nodes to HMC nodes. (If the connection already exists, it will not break it.) This command is useful when you have multiple HMCs, each of which will manage a subset of the CECs/Frames. Use `mkhwconn` to tell each HMC which CECs/Frames it should manage. When using this, you should turn off the self-discovery on each HMC. You also need to put all the HMCs and all the Frames on a single flat service network.

When `-t` is specified, this command reads the connection information from the xCAT ppc table (e.g. the parent attribute), and read the user/password from the ppcdirect table. Then this command will assign CEC nodes and Frame nodes to HMC nodes.

When `-p` is specified, this command gets the connection information from command line arguments. If `-P` is not specified, the default password for CEC and Frame nodes is used.

The flag `-s` is used to make the connection between the frame and its Service focal point(HMC). Makehwconn will also set the connections between the CECs within this Frame and the HMC. The sfp of the frame/CEC can either be defined in ppc table beforehand or specified in command line after the flag `-s`. If the user use mkhwconn noderange `-s` HMC_name, it will not only make the connections but also set the sfp attributes for these nodes in PPC table.

In any case, before running this command, the CEC and Frame nodes need be defined with correct nodetype.nodetype value (cec or frame) and nodehm.mgt value (hmc).

Note: If a CEC belongs to a frame, which has a BPA installed, this CEC should not be assigned to an HMC individually. Instead, the whole frame should be assigned to the HMC.

For PPC (using Direct FSP Management) specific:

It is used to set up connections for CEC and Frame node to Hardware Server on management node (or service node ). It only could be done according to the node definition in xCAT DB. And this command will try to read the user/password from the ppcdirect table first. If fails, then read them from passwd table. Commonly , the username is HMC. If using the ppcdirect table, each CEC/Frame and user/password should be stored in ppcdirect table. If using the passwd table, the key should be “cec” or “frame”, and the related user/password are stored in passwd table.

When `--port` is specified, this command will create the connections for CECs/Frames whose side in vpd table is equal to port value.
OPTIONS

-h|--help
   Display usage message.

-t
   Read connection information from xCAT DB (ppc and ppcdirect tables). Use this option if you need to connect multiple CECs/Frames to multiple HMCs in a single command.

-p
   The HMC node name. Only one HMC nodes can be specified by this flag. To setup connection for multiple HMC nodes, use flag -t.

-P
   The password of HMC based CEC/Frame login user (Default user name is ‘HMC’). This flag is optional.

-T
   The tooltype is used to communicate to the CEC/Frame. The value could be lpar or fnm. The tooltype value lpar is for xCAT and fnm is for CNM. The default value is “lpar”.

--port
   The port value specifies which special side will be used to create the connection to the CEC/Frame. The value could only be specified as “0” or “1” and the default value is “0,1”. If the user wants to use all ports to create the connection, he should not specify this value. If the port value is specified as “0”, in the vpd table, the side column should be A-0 and B-0; If the port value is specified as “1”, the side column should be A-1 and B-1. When making hardware connection between CEC/Frame and HMC, the value is used to specify the fsp/bpa port of the cec/frame and will be organized in order of “A-0,A-1,B-0,B-1”. If any side does not exist, the side would simply be ignored. Generally, only one port of a fsp/bap can be connected while another port be used as backup.

-s
   The flag -s is used to make the connection between the frame and its Service Focal Point(HMC). -s flag is not supposed to work with other functional flags.

-V|--verbose
   Verbose output.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To setup the connection for all CEC nodes in node group cec to HMC node, according to the definition in xCAT DB:

   mkhwconn cec -t

2. To setup the connection for Frame nodes in node group frame to HMC node hmc1, with password ‘abc123’:
mkhwconn frame -p hmc1 -P abc123

3. To setup the connections for all CEC nodes in node group cec to hardware server, and the tooltype value is lpar:

mkhwconn cec -t -T lpar

4. To setup the connections for all cecs nodes in node group cec to hardware server, and the tooltype value is lpar, and the port value is 1:

mkhwconn cec -t -T lpar --port 1

5. To setup the connection between the frame and it’s SFP node. This command will also set the connections between the CECs within this frame and their SFP node. User need to define HMC_name in the database in advance, but no need to set the sfp attribute for these node, xCAT will set the HMC_name as ppc.sfp for these nodes. The CECs within this frame should have the same sfp attribute as the frame.

mkhwconn cec -s HMC_name -P HMC_passwd

FILES

$XCATROOT/bin/mkhwconn

(The XCATROOT environment variable is set when xCAT is installed. The default value is “/opt/xcat”.)

NOTES

This command is part of the xCAT software product.

SEE ALSO

lshwconn(1)|lshwconn.1, rmhwconn(1)|rmhwconn.1

mknimimage.1

NAME

mknimimage - Use this xCAT command to create xCAT osimage definitions and related AIX/NIM resources. The command can also be used to update an existing AIX diskless image(SPOT).

SYNOPSIS

mknimimage [-h | --help ]
mknimimage [-V] -u osimage_name [attr=val [attr=val ...]]
DESCRIPTION

This command will create both an xCAT osimage definition and the corresponding NIM resource definitions. The command can also be used to update an existing AIX diskless image (SPOT).

The command will also install the NIM master software and configure NIM if needed.

The naming convention for the NIM SPOT resource definition is to use the same name as the xCAT osimage. The naming convention for any other NIM resources that are created is "<osimage_name>_resource_type". (ex. "61image_lpp_source")

When creating a mksysb image definition you must specify either the "-n" or the "-b" option. The "-n" option can be used to create a mksysb image from an existing NIM client machine. The "-b" option can be used to specify an existing mksysb backup file.

Adding software and configuration files to the osimage.

When creating a diskless osimage definition you also have the option of automatically updating the NIM SPOT resource. You can have additional software installed or you can have configuration files added or updated. To have software installed you must provide either the names of NIM installp_bundle resources or fileset names on the command line using the "attr=val" option. You may also supply the installp flags, RPM flags, emgr flags to use when installing the software.

To have configuration files updated you must provide the full path name of a "synclists" file which contains the list of actual files to update. The xCAT osimage definition that is created will contain the installp_bundle, otherpkgs, and synclists files that are provided on the command line.

Updating an existing xCAT osimage

If you wish to update an existing diskless image after it has already been created you can use the "-u" (update) option. In this case the xCAT osimage definition will not be updated.

There are two ways to use the update feature.

You can update the osimage definition and run the mknimimage command with no "installp_bundle", "otherpkgs", or "synclists" command line values. The information for updating the SPOT will come from the osimage definition only. This has the advantage of keeping a record of any changes that were made to the SPOT.

Or, you could do a more ad hoc update by providing one or more of the "installp_bundle", "otherpkgs", or "synclists" values on the command line. If any of these values are provided the mknimimage command will use those values only. The osimage definition will not be used or updated.

WARNING: Installing random RPM packages in a SPOT may have unpredictable consequences. The SPOT is a very restricted environment and some RPM packages may corrupt the SPOT or even hang your management system. Try to be very careful about the packages you install. When installing RPMs, if the mknimimage command hangs or if there are file systems left mounted after the command completes you may need to reboot your management node to recover. This is a limitation of the current AIX support for diskless systems

Copying an xCAT osimage.

You can use the "-i" and "-p" options to copy an existing diskless osimage. To do this you must supply the name of an existing xCAT osimage definition and the name of the new osimage you wish to create. The mknimimage command will do the following:

• create a new xCAT osimage definition using the new name that was specified.
• copy the NIM SPOT resource to a new location and define it to NIM using a new name.
• if the original osimage included a NIM "shared_root" resource then a new shared_root resource will be created for the new SPOT.
• any other resources (or attributes) included in the original osimage will be included in the new osimage definition.
if the “-p” option is specified then the original NIM lpp_source resource will be copied to a new location and redefined to NIM. (The default would be to use the original lpp_source - to save file system space.)

Additional information
IMPORTANT: The NIM lpp_source and SPOT resources can get quite large. Always make sure that you have sufficient file system space available before running the mknimimage command.

To list the contents of the xCAT osimage definition use the xCAT lsdef command (“lsdef -t osimage -l -o <osimage_name>”).

To check the validity of a SPOT or lpp_source resource

To remove an xCAT osimage definition along with the associated NIM resource definitions use the rmnimimage command. Be careful not to accidently remove NIM resources if they are still needed.

To list a NIM resource definition use the AIX lsnim command (“lsnim -l <resource_name>”).

To check the validity of a SPOT or lpp_source resource use the AIX nim command (“nim -o check <resource-name>”).

To remove specific NIM resource definitions use the AIX nim command. (“nim -o remove <resource-name>”).

OPTIONS

attr=val [attr=val ...]

Specifies one or more “attribute equals value” pairs, separated by spaces. Attr=val pairs must be specified last on the command line.

Currently supported attributes:

bosinst_data
The name of a NIM bosinst_data resource.

dump
The name of the NIM dump resource.

fb_script
The name of a NIM fb_script resource.

home
The name of the NIM home resource.

installp_bundle
One or more comma separated NIM installp_bundle resources.

lpp_source
The name of the NIM lpp_source resource.

mksysb
The name of a NIM mksysb resource.

otherpkgs
One or more comma separated installp, emgr, or rpm packages. The packages must have prefixes of ‘I:’, ‘E:’, or ‘R:’, respectively. (ex. R:foo.rpm)

paging
The name of the NIM paging resource.
resolv_conf
The name of the NIM resolv_conf resource.

root
The name of the NIM root resource.

script
The name of a NIM script resource.

shared_home
The name of the NIM shared_home resource.

shared_root
A shared_root resource represents a directory that can be used as a / (root) directory by one or more diskless clients.

spot
The name of the NIM SPOT resource.

synclists
The fully qualified name of a file containing a list of files to synchronize on the nodes.

tmp
The name of the NIM tmp resource.

installp_flags
The alternate flags to be passed along to the AIX installp command. (The default for installp_flags is “-abgQXY”.)

rpm_flags
The alternate flags to be passed along to the AIX rpm command. (The default for rpm_flags is “-Uvh “.) The mknimimage command will check each rpm to see if it is installed. It will not be reinstalled unless you specify the appropriate rpm option, such as ‘--replacepkgs’.

emgr_flags
The alternate flags to be passed along to the AIX emgr command. (There is no default flags for the emgr command.)

dumpsize
The maximum size for a single dump image the dump resource will accept. Space is not allocated until a client starts to dump. The default size is 50GB. The dump resource should be large enough to hold the expected AIX dump and snap data.

max.dumps
The maximum number of archived dumps for an individual client. The default is one.

snapcollect
Indicates that after a dump is collected then snap data should be collected. The snap data will be collected in the clients dump resource directory. Values are “yes” or “no”. The default is “no”.

nfs_vers
Value Specifies the NFS protocol version required for NFS access.
nfs_sec
Value Specifies the security method required for NFS access.

Note that you may specify multiple “script”, “otherpkgs”, and “installp_bundle” resources by using a comma separated list. (ex. “script=ascript,bscript”). RPM names may be included in the “otherpkgs” list by using a “R:” prefix (ex. “R:whatever.rpm”). epkg (AIX interim fix package) file names may be included in the “otherpkgs” using the ‘E:’ prefix. (ex. “otherpkgs=E:IZ38930TL0.120304.epkg.Z”).

-b mksysbfile
Used to specify the path name of a mksysb file to use when defining a NIM mksysb resource.

-cl--completeosimage
Complete the creation of the osimage definition passed in on the command line. This option will use any additional values passed in on the command line and/or it will attempt to create required resources in order to complete the definition of the xCAT osimage. For example, if the osimage definition is missing a spot or shared_root resource the command will create those resources and add them to the osimage definition.

-fl--force
Use the force option to re-create xCAT osimage definition. This option removes the old definition before creating the new one. It does not remove any of the NIM resource definitions named in the osimage definition. Use the rmmnimimage command to remove the NIM resources associated with an xCAT osimage definition.

-h l--help
Display usage message.

osimage_name
The name of the xCAT osimage definition. This will be used as the name of the xCAT osimage definition as well as the name of the NIM SPOT resource.

-Dl--mdumpres
Create a diskless dump resource.

-i current_image
The name of an existing xCAT osimage that should be copied to make a new xCAT osimage definition. Only valid when defining a “diskless” or “dataless” type image.

-l location
The directory location to use when creating new NIM resources. The default location is /install/nim.

-m nimmethod
Used to specify the NIM installation method to use. The possible values are “rte” and “mksysb”. The default is “rte”.

-n mksysbnode
The xCAT node to use to create a mksysb image. The node must be a defined as a NIM client machine.

-pl--cplpp
Use this option when copying existing diskless osimages to indicate that you also wish to have the lpp_resource copied. This option is only valid when using the “-i” option.

-rl--sharedroot
Use this option to specify that a NIM “shared_root” resource be created for the AIX diskless nodes. The default is to create a NIM “root” resource. This feature is only available when using AIX version 6.1.4 or beyond. See the AIX/NIM documentation for a description of the “root” and “shared_root” resources.

-s image_source

The source of software to use when creating the new NIM lpp_source resource. This could be a source directory or a previously defined NIM lpp_source resource name.

-t nimtype

Used to specify the NIM machine type. The possible values are “standalone”, “diskless” or “dataless”. The default is “standalone”.

-u

Used to update an AIX/NIM SPOT resource with additional software and configuration files. This option is only valid for xCAT diskless osimage objects. The SPOT resource associated with the xCAT osimage definition will be updated. This option can also be used to update the nfs_vers attribute from NFSv3 to NFSv4 for the NIM resources associated with diskful or diskless image.

-V |--verbose

Verbose mode.

RETURN VALUE

0. The command completed successfully.
1. An error has occurred.

EXAMPLES

1. Create an osimage definition and the basic NIM resources needed to do a NIM “standalone” “rte” installation of node “node01”. Assume the software contained on the AIX product media has been copied to the /AIX/instimages directory.

   mknimimage -s /AIX/instimages 61image

2. Create an osimage definition that includes some additional NIM resources.

   mknimimage -s /AIX/instimages 61image installp_bundle=mybndlres,addswbnd

   This command will create lpp_source, spot, and bosinst_data resources using the source specified by the “-s” option. The installp_bundle information will also be included in the osimage definition. The mybndlres and addswbnd resources must be created before using this osimage definition to install a node.

3. Create an osimage definition that includes a mksysb image and related resources.

   mknimimage -m mksysb -n node27 newsysb spot=myspot bosinst_data=mybdata

   This command will use node27 to create a mksysb backup image and use that to define a NIM mksysb resource. The osimage definition will contain the name of the mksysb resource as well as the spot and bosinst_data resource.

4. Create an osimage definition using a mksysb image provided on the command line.

   mknimimage -m mksysb -b /tmp/backups/mysysbimage newsysb spot=myspot bosinst_data=mybdata
This command defines a NIM mksysb resource using mysysbimage.

5. Create an osimage definition and create the required spot definition using the mksysb backup file provided on the command line.

```
mknimimage -m mksysb -b /tmp/backups/mysysbimage newsysb bosinst_data=mybdata
```

This command defines a NIM mksysb resource and a spot definition using mysysbimage.

6. Create a diskless image called 61dskls using the AIX source files provided in the /AIX/instimages directory.

```
mknimimage -t diskless -s /AIX/instimages 61dskls
```

7. Create a diskless image called “614dskls” that includes a NIM “shared_root” and a “dump” resource. Use the existing NIM lpp_resource called “614_lpp_source”. Also specify verbose output.

```
mknimimage -V -r -D -t diskless -s 614_lpp_source 614dskls snapcollect=yes
```

The “snapcollect” attribute specifies that AIX “snap” data should be include when a system dump is initiated.

8. Create a new diskless image by copying an existing image.

```
mknimimage -t diskless -i 61cosi 61cosi_updt1
```

Note: If you also wish to have the original lpp_source copied and defined use the -p option.

```
mknimimage -t diskless -i 61cosi -p 61cosi_updt1
```

9. Create a diskless image using an existing lpp_source resource named “61cosi_lpp_source” and include NIM tmp and home resources. This assumes that the “mytmp” and “myhome” NIM resources have already been created by using NIM commands.

```
mknimimage -t diskless -s 61cosi_lpp_source 611cosi tmp=mytmp home=myhome
```

10. Create a diskless image and update it with additional software using rpm flags and configuration files.

```
mknimimage -t diskless -s 61cosi_lpp_source 61dskls otherpkgs=I:fset1,R:foo.rpm, E:IZ38930TL0.120304.epkg.Z synclists=/install/mysyncfile rpm_flags="-i --nodeps"
```

The xCAT osimage definition created by this command will include the “otherpkgs” and “synclists” values. The NIM SPOT resource associated with this osimage will be updated with the additional software using rpm flags “-i --nodeps” and configuration files.

11. Update an existing diskless image (AIX/NIM SPOT) using the information saved in the xCAT “61dskls” osimage definition. Also specify verbose messages.

```
mknimimage -V -u 61dskls
```

12. Update an existing diskless image called “61dskls”. Install the additional software specified in the NIM “bndres1” and “bndres2” installp_bundle resources using the installp flags “-agcQX”. (The NIM “bndres1” and “bndres2” definitions must be created before using them in this command.)

```
mknimimage -u 61dskls installp_bundle=bndres1,bndres2 installp_flags="-agcQX"
```

Note that when “installp_bundle”, “otherpkgs”, or “synclists” values are specified with the “-u” option then the xCAT osimage definition is not used or updated.

13. Update an existing image to support NFSv4. Also specify verbose messages.
mknimimage -V -u 61dskls nfs_vers=4

FILES

/opt/xcat/bin/mknimimage

NOTES

This command is part of the xCAT software product.

SEE ALSO

rmnimimage(1)|rmnimimage.1

mkvlan.1

NAME

mkvlan - It takes a list of nodes and create a private tagged vlan for them.

SYNOPSIS

mkvlan [vlanid] -n|--nodes noderange [-t|--net subnet] [-m|--mask netmask] [-p|--prefix hostname_prefix] [-i|--interface nic]

mkvlan [-h|--help]

mkvlan [-v|--version]

DESCRIPTION

The mkvlan command takes a list of nodes and move them to a private vlan.

This command will configure the switch to create a new tagged vlan on the given nic. The primary nic will be used if the nic is not specified. The new vlan ID is given by the command. However, if it is omitted, xCAT will automatically generate the new vlan ID by querying all the switches involved and finding out the smallest common number that is not used by any existing vlans. The subnet and the netmask for the vlan will be derived from the value of “vlannets” and “vlanmasks” from the site table if -t and -m are not specified. The following are the default site table entires:

```
vlannets="|\(\d+\)|10.(\$1+0).0.0|"
vlannmask="255.255.0.0"
```

The vlan network will be entered in the networks table. The nodes will be added to the vlan using the vlan tagging technique. And the new IP addresses and new hostnames will be assigned to the nodes. The -p flag specifies the node hostname prefix for the nodes. If it is not specified, by default, the hostnames for the nodes are having the following format:

v<vlanid>nY where Y is the node number. For example, the hostname for node 5 on vlan 10 is v10n5.
The `switch.vlan` will be updated with the new vlan id for the node for standaline nodes. For KVM guests, the `vm.nics` identifies which vlan this node belongs to. For example: vl3 means this node is in vlan 3.

If there are more than one switches involved in the vlan, the ports that connect to the switches need to entered in `switches.linkports` with the following format:

```
<port number>:switch,<port number>:switch....
```

For example:

```
"42:switch1,43:switch2"
```

This command will automatically configure the cross-over ports if the given nodes are on different switches.

For added security, the root guard and bpdu guard will be enabled for the ports in this vlan. However, the guards will not be disabled if the ports are removed from the vlan using chvlan or rmvlan commands. To disable them, you need to use the switch command line interface. Refer to the switch command line interface manual to see how to disable the root guard and bpdu guard for a port.

**PARAMETERS**

`vlanid` is a unique vlan number. If it is omitted, xCAT will automatically generate the new vlan ID by querying all the switches involved and finding out the smallest common number that is not used by any existing vlans. Use `lsvlan` to find out the existing vlan ids used by xCAT.

**OPTIONS**

- `--nodes` The nodes or groups to be included in the vlan. It can be stand alone nodes or KVM guests. It takes the noderange format. Check the man page for noderange for details.
- `--net` The subnet for the vlan.
- `--mask` The netmask for the vlan
- `--prefix` The prefix the the new hostnames for the nodes in the vlan.
- `--interface` The interface name where the vlan will be tagged on. If omitted, the xCAT management network will be assumed. For FVM, this is the interface name on the host.
- `--help` Display usage message.
- `--version` The Command Version.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.

**EXAMPLES**

To start, the xCAT switches and switches table needs to be filled with switch and port info for the nodes. For example, the switch table will look like this:
Note that the interface value for the management (primary) network can be empty, the word “primary” or “primary:ethx”. For other networks, the interface attribute must be specified.

The following is an example of the switches table

```sh
#switch,snmpversion,username,password,privacy,auth,linkports,sshusername,sshpassword,switchtype,comments,disable
"switch1","3","username","passw0rd","sha","48:switch2", "switch2","2","43:switch1",1
```

1. To make a private vlan for node1, node2 and node3

   ```bash
   mkvlan -n node1,node2,node3
   ```

   The vlan will be created on eth0 for the nodes.

2. To make a private vlan for node1, node2 and node3 on eth1,

   ```bash
   mkvlan -n node1,node2,node3 -i eth1
   ```

3. To make a private vlan for node1, node2 with given subnet and netmask.

   ```bash
   mkvlan -n node1,node2,node3 -t 10.3.2.0 -m 255.255.255.0
   ```

4. To make a private vlan for KVM guests node1 and node2

   ```bash
   chtab key=usexhrm site.value=1
   mkdef node1 arch=x86_64 groups=kvm,all installnic=mac primarynic=mac mgmt=kvm
   →netboot=pxe nfsserver=10.1.0.204 os=rhels6 profile=compute provmethod=install
   →serialport=0 serialspeed=115200 vmcpus=1 vmhost=x3650n01 vmmemory=512
   →vmnics=br0 vmstorage=nfs://10.1.0.203/vms
   mkdef node2 arch=x86_64 groups=kvm,all installnic=mac primarynic=mac mgmt=kvm
   →netboot=pxe nfsserver=10.1.0.204 os=rhels6 profile=compute provmethod=install
   →serialport=0 serialspeed=115200 vmcpus=1 vmhost=x3650n01 vmmemory=512
   →vmnics=br0 vmstorage=nfs://10.1.0.203/vms
   mkvlan -n node1,node2
   mkvm node1,node2 -s 20G
   rpower node1,node2 on
   rinstall node1,node2
   ```

**FILES**

```
/opt/xcat/bin/mkvlan
```

**SEE ALSO**

chvlan(1),chvlan.1, rmvlan(1),rmvlan.1, lsvlan(1),lslvlan.1
mkvm.1

NAME

mkvm - Creates HMC-, DFM-, IVM-, and zVM-managed partitions or other virtual machines.

SYNOPSIS

Common:

mkvm [-h|--help]
mkvm [-v|--version]

For PPC (with HMC) specific:

mkvm [-V|--verbose] noderange -i id -l singlenode
mkvm [-V|--verbose] noderange -c destsec -p profile
mkvm [-V|--verbose] noderange --full

For PPC (using Direct FSP Management) specific:

mkvm noderange [--full]
mkvm noderange [vmcpus= min/req/max] [vmmemory= min/req/max] [vmphyslots= drc_index1,drc_index2...]
[vmothersetting= hugepage:N,bsr:N] [vmnics= vlan1[,vlan2...]] [vmstorage= Nviosnode:slotid] [--vios]

For KVM:

mkvm noderange [-s|--size disksize] [--mem memsize] [--cpus cpucount] [-f|--force]

For VMware:

mkvm noderange [-s|--size disksize] [--mem memsize] [--cpus cpucount]

For zVM:

mkvm noderange [directory_entry_file_path]
mkvm noderange [source_virtual_machine] [pool= disk_pool]
DESCRIPTION

For PPC (with HMC) specific:

The first form of `mkvm` command creates new partition(s) with the same profile/resources as the partition specified by `singlenode`. The `-i` and `noderange` specify the starting numeric partition number and the `noderange` for the newly created partitions, respectively. The LHEA port numbers and the HCA index numbers will be automatically increased if they are defined in the source partition.

The second form of this command duplicates all the partitions from the source specified by `profile` to the destination specified by `destcec`. The source and destination CECs can be managed by different HMCs.

Make sure the nodes in the `noderange` is defined in the `nodelist` table and the `mgt` is set to ‘hmc’ in the `nodehm` table before running this command.

Note that the `mkvm` command currently only supports creating standard LPARs, not virtual LPARs working with VIOS server.

For PPC (using Direct FSP Management) specific:

With option `full`, a partition using all the resources on a normal power machine will be created.

If no option is specified, a partition using the parameters specified with attributes such as ‘vmcpus’, ‘vmmory’, ‘vm-physlots’, ‘vmothersetting’, ‘vmnics’, ‘vmstorage’ will be created. Those attributes can either be specified with ‘*def’ commands running before or be specified with this command.

For KVM and VMware:

The `mkvm` command creates new virtual machine(s) with the `disksize` size of hard disk, `memsize` size of memory and `cpucount` number of cpu.

For zVM:

The first form of `mkvm` creates a new virtual machine based on a directory entry.

The second form of this creates a new virtual machine with the same profile/resources as the specified node (cloning).

OPTIONS

`-h|--help`

Display usage message.

`-c`

The cec (fsp) name for the destination.

`--cpus`

The cpu count which will be created for the kvm/vmware virtual machine.

`--full`

Request to create a new full system partition for each CEC.
To specify the parameters which are used to create a partition. The *vmcpus*, *vmmemory* are necessary, and the value specified with this command have a more high priority. If the value of any of the three options is not specified, the corresponding value specified for the node object will be used. If any of the three attributes is neither specified with this command nor specified with the node object, error information will be returned. To reference to lsvm(1)llsvm.1 for more information about ‘drc_index’ for *vmphyslots*.

The option *vios* is used to specify the partition that will be created is a VIOS partition. If specified, the value for *vmstorage* shall be number which indicate the number of vSCSI server adapter will be created, and if no value specified for *vmphyslots*, all the physical slot of the power machine will be assigned to VIOS partition. If not specified, it shall be in form of *vios_name:server_slotid* to specify the vios and the virtual slot id of the vSCSI server adapter that will be connected from the Logical partition.

**-f|--force**

If the storage already exists, remove it before creating a new virtual machine.

**-i**

Starting numeric id of the newly created partitions.

**-l**

The partition name of the source.

**--mem**

The memory size which will be used for the new created kvm/vmware virtual machine. Unit is Megabyte.

**-p**

The file that contains the profiles for the source partitions.

**-s|--size**

The size of storage which will be created for the kvm/vmware virtual machine.

**-v|--version**

Command Version.

**-V|--verbose**

Verbose output.

**RETURN VALUE**

0 The command completed successfully.

1 An error has occurred.

**EXAMPLES**

1. To create a new HMC-managed partition lpar5 based on the profile/resources of lpar4, enter:

   ```shell
mkdef -t node -o lpar5 mgt=hmc groups=all
```

   then:
2. To create new HMC-managed partitions `lpar5-lpar8` based on the profile/resources of `lpar4`, enter:

```
mkdef -t node -o lpar5-lpar8 mgt=hmc groups=all
```

then:

```
mkvm lpar5-lpar8 -i 5 -l lpar4
```

Output is similar to:

```
lpar5: Success
lpar6: Success
lpar7: Success
lpar8: Success
```

3. To duplicate all the HMC-managed partitions associated with `ceco1` on `ceco2`, first save the lpars from `ceco1` to a file:

```
lsvm lpar01-lpar04 > /tmp/myprofile
```

then create lpars on `ceco2`:

```
mkvm lpar05-lpar08 -c ceco2 -p /tmp/myprofile
```

Output is similar to:

```
lpar5: Success
lpar6: Success
lpar7: Success
lpar8: Success
```

4. To duplicate all the HMC-managed partitions associated with `ceco1` on `ceco2`, one is for `ceco1`, the other is for `ceco2`:

```
mkdef -t node -o lpar5,lpar6 mgt=hmc groups=all
chtab node=lpar5 ppc.parent=ceco1
chtab node=lpar6 ppc.parent=ceco2
```

then create lpars on `ceco1` and `ceco2`:

```
mkvm lpar5,lpar6 --full
```

Output is similar to:

```
lpar5: Success
lpar6: Success
```

5. To create a new zVM virtual machine (`gpok3`) based on a directory entry:

```
mkvm gpok3 /tmp/dirEntry.txt
```

1.3. Admin Guide 333
Output is similar to:

```
gpok3: Creating user directory entry for LNX3... Done
```

6. To clone a new zVM virtual machine with the same profile/resources as the specified node:

```
mkvm gpok4 gpok3 pool=POOL1
```

Output is similar to:

```
gpok4: Cloning gpok3
gpok4: Linking source disk (0100) as (1100)
gpok4: Linking source disk (0101) as (1101)
gpok4: Stopping LNX3... Done
gpok4: Creating user directory entry
gpok4: Granting VSwitch (VSW1) access for gpok3
gpok4: Granting VSwitch (VSW2) access for gpok3
gpok4: Adding minidisk (0100)
gpok4: Adding minidisk (0101)
gpok4: Disks added (2). Disks in user entry (2)
gpok4: Linking target disk (0100) as (2100)
gpok4: Copying source disk (1100) to target disk (2100) using FLASHCOPY
gpok4: Mounting /dev/dasdg1 to /mnt/LNX3
gpok4: Setting network configuration
gpok4: Linking target disk (0101) as (2101)
gpok4: Copying source disk (1101) to target disk (2101) using FLASHCOPY
gpok4: Powering on
gpok4: Detatching source disk (0101) at (1101)
gpok4: Detatching source disk (0100) at (1100)
gpok4: Starting LNX3... Done
```

7. To create a new kvm/vmware virtual machine with 10G storage, 2048M memory and 2 cpus.

```
mkvm vml -s 10G --mem 2048 --cpus 2
```

8. To create a full partition on normal power machine.

First, define a node object:

```
mkdef -t node -o lpar1 mgt=fsp cons=fsp nodetype=ppc,osi id=1 hcp=cec parent=cec
   hwtype=lxpar groups=lxpar,all
```

Then, create the partition on the specified cec.

```
mkvm lpar1 --full
```

The output is similar to:

```
lpar1: Done
```

To query the resources allocated to node ‘lpar1’

```
lsvm lpar1
```

The output is similar to:

```
lpar1: Lpar Processor Info:
   Curr Processor Min: 1.
```

(continues on next page)
Note: The ‘parent’ attribute for node ‘lpar1’ is the object name of physical power machine that the full partition will be created on.

9. To create a partition using some of the resources on normal power machine.

Option 1:

After a node object is defined, the resources that will be used for the partition shall be specified like this:

```
chdef lpar1 vmcpus=1/4/16 vmmemory=1G/4G/32G vmphyslots=0x21010201,0x21010200
→vmothersetting=bsr:128,hugepage:2
```

Then, create the partition on the specified cec.

```
mkvm lpar1
```

Option 2:

```
mkvm lpar1 vmcpus=1/4/16 vmmemory=1G/4G/32G vmphyslots=0x21010201,0x21010200
→vmothersetting=bsr:128,hugepage:2
```

The output is similar to:

```
lpar1: Done
```

Note: The ‘vmphyslots’ specify the drc index of the physical slot device. Every drc index shall be delimited with ‘.’. The ‘vmothersetting’ specify two kinds of resource, bsr(Barrier Synchronization Register) specified the num of BSR arrays, hugepage(Huge Page Memory) specified the num of huge pages.

To query the resources allocated to node ‘lpar1’

```
lsvm lpar1
```

The output is similar to:

```
lpar1: Lpar Processor Info:
  Curr Processor Min: 1.
  Curr Processor Max: 16.
lpar1: Lpar Memory Info:
  Curr Memory Min: 1.00 GB(4 regions).
```
Curr Memory Req: 4.00 GB (16 regions).
Curr Memory Max: 32.00 GB (128 regions).
lpar1: 1,513, U78AA.001.WZSGVU7-P1-T7, 0x21010201, 0xc03 (USB Controller)
lpar1: 1,512, U78AA.001.WZSGVU7-P1-T9, 0x21010200, 0x104 (RAID Controller)
lpar1: 1/2/2
lpar1: 128.

10. To create a vios partition using some of the resources on normal power machine.

```bash
mkvm viosnode vmcpus=1/4/16 vmmemory=1G/4G/32G vmphyslots=0x21010201,0x21010200
vmnics=vlan1 vmstorage=5 --vios
```

The resources for the node is similar to:

<table>
<thead>
<tr>
<th>viosnode: Lpar Processor Info:</th>
</tr>
</thead>
<tbody>
<tr>
<td>Curr Processor Min: 1.</td>
</tr>
<tr>
<td>Curr Processor Max: 16.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>viosnode: Lpar Memory Info:</th>
</tr>
</thead>
<tbody>
<tr>
<td>Curr Memory Min: 1.00 GB (4 regions).</td>
</tr>
<tr>
<td>Curr Memory Req: 4.00 GB (16 regions).</td>
</tr>
<tr>
<td>Curr Memory Max: 32.00 GB (128 regions).</td>
</tr>
</tbody>
</table>

| viosnode: 1, 513, U78AA.001.WZSGVU7-P1-T7, 0x21010201, 0xc03 (USB Controller) |
| viosnode: 1, 512, U78AA.001.WZSGVU7-P1-T9, 0x21010200, 0x104 (RAID Controller) |
| viosnode: 1, 0, U8205.E6B.0612BAR-V1-C, 0x30000000, vSerial Server |
| viosnode: 1, 1, U8205.E6B.0612BAR-V1-C1, 0x30000001, vSerial Server |
| viosnode: 1, 3, U8205.E6B.0612BAR-V1-C3, 0x30000003, vEth (port_vlanid=1, mac_addr=4211509276a7) |
| viosnode: 1, 5, U8205.E6B.0612BAR-V1-C5, 0x30000005, vSCSI Server |
| viosnode: 1, 6, U8205.E6B.0612BAR-V1-C6, 0x30000006, vSCSI Server |
| viosnode: 1, 7, U8205.E6B.0612BAR-V1-C7, 0x30000007, vSCSI Server |
| viosnode: 1, 8, U8205.E6B.0612BAR-V1-C8, 0x30000008, vSCSI Server |
| viosnode: 1, 9, U8205.E6B.0612BAR-V1-C9, 0x30000009, vSCSI Server |
| viosnode: 0/0/0 |
| viosnode: 0. |

FILES

`/opt/xcat/bin/mkvm`

SEE ALSO

chvm(1), chvm.1, lsvm(1), lsvm.1, rmvm(1), rmvm.1

mkzone.1

NAME

`mkzone` - Defines a new zone in the cluster.
SYNOPSIS

mkzone zonename [--defaultzone] [-k full path to the ssh RSA private key] [-a noderange] [-g] [-f] [-s {yes|no}] [-V]
mkzone [-h | -v]

DESCRIPTION

The mkzone command is designed to divide the xCAT cluster into multiple zones. The nodes in each zone will share common root ssh keys. This allows the nodes in a zone to be able to as root ssh to each other without password, but cannot do the same to any node in another zone. All zones share a common xCAT Management Node and database including the site table, which defines the attributes of the entire cluster. The mkzone command is only supported on Linux (No AIX support). The nodes are not updated with the new root ssh keys by mkzone. You must run updatenode -k or xdsh -K to the nodes to update the root ssh keys to the new generated zone keys. This will also sync any service nodes with the zone keys, if you have a hierarchical cluster. Note: if any zones in the zone table, there must be one and only one defaultzone. Otherwise, errors will occur.

OPTIONS

-h | --help
Displays usage information.

-v | --version
Displays command version and build date.

-k | --sshkeypath full path to the ssh RSA private key
This is the path to the id_rsa key that will be used to build root’s ssh keys for the zone. If -k is used, it will generate the ssh public key from the input ssh RSA private key and store both in /etc/xcat/sshkeys/<zonename>/ssh directory. If -f is not used, then it will generate a set of root ssh keys for the zone and store them in /etc/xcat/sshkeys/<zonename>/ssh.

--default
if –defaultzone is input, then it will set the zone defaultzone attribute to yes; otherwise it will set to no.
if –defaultzone is input and another zone is currently the default, then the -f flag must be used to force a change to the new defaultzone. If -f flag is not used an error will be returned and no change made. Note: if any zones in the zone table, there must be one and only one defaultzone. Otherwise, errors will occur.

-a | --addnoderange noderange
For each node in the noderange, it will set the zonename attribute for that node to the input zonename. If the -g flag is also on the command, then it will add the group name “zonename” to each node in the noderange.

-s | --sshbetweennodes yes|no
If -s entered, the zone sshbetweennodes attribute will be set to yes or no. It defaults to yes. When this is set to yes, then ssh will be setup to allow passwordless root access between nodes. If no, then root will be prompted for a password when running ssh between the nodes in the zone.

-f | --force
Used with the (--defaultzone) flag to override the current default zone.

-g | --assigngroup
Used with the (-a) flag to create the group zonename for all nodes in the input noderange.
-V | --verbose

Verbose mode.

EXAMPLES

1. To make a new zone1 using defaults, enter:

```
mkzone zone1
```

Note: with the first `mkzone`, you will automatically get the xcatdefault zone created as the default zone. This zone uses ssh keys from <roothome>/.ssh directory.

2. To make a new zone2 using defaults and make it the default zone enter:

```
mkzone> zone2 --defaultzone -f
```

3. To make a new zone2A using the ssh id_rsa private key in /root/.ssh:

```
mkzone zone2A -k /root/.ssh
```

4. To make a new zone3 and assign the noderange compute3 to the zone enter:

```
mkzone zone3 -a compute3
```

5. To make a new zone4 and assign the noderange compute4 to the zone and add zone4 as a group to each node enter:

```
mkzone zone4 -a compute4 -g
```

6. To make a new zone5 and assign the noderange compute5 to the zone and add zone5 as a group to each node but not allow passwordless ssh between the nodes enter:

```
mkzone zone5 -a compute5 -g -s no
```

Files

```
/opt/xcat/bin/mkzone/
```

Location of the mkzone command.

SEE ALSO

chzone(1) chzone.1, rmzone(1) rrmzone.1, xdsh(1) lxds.1, updatenode(1) updatenode.1

monadd.1

NAME

```
monadd - Registers a monitoring plug-in to the xCAT cluster.
```
SYNOPSIS

monadd [-h|--help]
monadd [-v|--version]
monadd name [-n|--nodestatmon] [-s|--settings settings]

DESCRIPTION

This command is used to register a monitoring plug-in module to monitor the xCAT cluster. The plug-in module will be added to the xCAT monitoring database table and the configuration scripts for the monitoring plug-in, if any, will be added to the postscripts table. A monitoring plug-in module acts as a bridge that connects a 3rd party monitoring software and the xCAT cluster. A configuration script is used to configure the 3rd party software. Once added to the <postscripts> table, it will be invoked on the nodes during node deployment stage.

Parameters

name is the name of the monitoring plug-in module. For example, if the name is called xxx, then the actual file name that the xcalt looks for is /opt/xcat/lib/perl/xCAT_monitoring/xxx.pm. Use monls -a command to list all the monitoring plug-in modules that can be used.

settings is the monitoring plug-in specific settings. It is used to customize the behavior of the plug-in or configure the 3rd party software. Format: -s key-value -s key=value . . . Note that the square brackets are needed here. Use monls name -d command to look for the possible setting keys for a plug-in module.

OPTIONS

-h | --help
   Display usage message.
-n | --nodestatmon
   Indicate that this monitoring plug-in will be used for feeding the node liveness status to the xCAT nodelist table.
-s | --settings
   Specifies the plug-in specific settings. These settings will be used by the plug-in to customize certain entities for the plug-in or the third party monitoring software. e.g. -s mon_interval=10 -s toggle=1.
-v | --version
   Command Version.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.
EXAMPLES

1. To register gangliamon plug-in module (which interacts with Ganglia monitoring software) to monitor the xCAT cluster, enter:

   monadd gangliamon

2. To register rmcmon plug-in module (which interacts with IBM's RSCT monitoring software) to monitor the xCAT cluster and have it feed the node liveness status to xCAT's nodelist table, enter:

   monadd rmcmon -n

   This will also add the configrmcnode to the postscripts table. To view the content of the postscripts table, enter:

   tabdump postscripts

   #node,postscripts,comments,disable
   "service","servicenode",,
   "xcatdefaults","syslog,remoteshell,configrmcnode",,

3. To register xcatmon plug-in module to feed the node liveness status to xCAT's nodelist table, enter:

   monadd xcatmon -n -s ping-interval=2

   where 2 is the number of minutes between the pings.

FILES

/opt/xcat/bin/monadd

SEE ALSO

monls(1)|monls.1, monrm(1)|monrm.1, monstart(1)|monstart.1, monstop(1)|monstop.1, moncfg(1)|moncfg.1, mondecfg(1)|mondecfg.1

moncfg.1

NAME

moncfg - Configures a 3rd party monitoring software to monitor the xCAT cluster.

SYNOPSIS

moncfg [-hl --help]
moncfg [-vl --version]
moncfg name [noderange] [-rl--remote]
DESCRIPTION

This command is used to configure a 3rd party monitoring software to monitor the xCAT cluster. For example, it modifies the configuration file for the monitoring software so that the nodes can be included in the monitoring domain. The operation is performed on the management node and the service nodes of the given nodes. The operation will also be performed on the nodes if the -r option is specified, though the configuration of the nodes is usually performed during the node deployment stage.

Parameters

name is the name of the monitoring plug-in module. For example, if the name is called xxx, then the actual file name that the xcatd looks for is /opt/xcat/lib/perl/xCAT_monitoring/xxx.pm. Use monls -a command to list all the monitoring plug-in modules that can be used.

noderange specifies the nodes to be monitored. If omitted, all nodes will be monitored.

OPTIONS

-h | --help Display usage message.
-r | --remote Specifies that the operation will also be performed on the nodes.
-v | --version Command Version.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To configure the management node and the service nodes for ganglia monitoring, enter:

   moncfg gangliamon

2. To configure the management node, nodes and their service nodes for ganglia monitoring, enter:

   moncfg gangliamon -r

FILES

/opt/xcat/bin/moncfg

SEE ALSO

monls(1)|monls.1, mondecfg(1)|mondecfg.1, monadd(1)|monadd.1, monrm(1)|monrm.1, monstart(1)|monstart.1, monstop(1)|monstop.1
mondecfg.1

NAME

mondecfg - Deconfigures a 3rd party monitoring software from monitoring the xCAT cluster.

SYNOPSIS

mondecfg [-h|--help]
mondecfg [-v|--version]
mondecfg name [noderange] [-r|--remote]

DESCRIPTION

This command is used to deconfigure a 3rd party monitoring software from monitoring the xCAT cluster. The operation is performed on the management node and the service nodes of the given nodes. The operation will also be performed on the nodes if the -r option is specified. The deconfiguration operation will remove the nodes from the 3rd party software’s monitoring domain.

PARAMETERS

name is the name of the monitoring plug-in module. Use monls command to list all the monitoring plug-in modules that can be used.

noderange specified the nodes to be deconfigured. If omitted, all nodes will be deconfigured.

OPTIONS

-h | --help Display usage message.
-r | --remote Specifies that the operation will also be performed on the nodes.
-v | --version Command Version.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To deconfigure the management node and the service nodes from the ganglia monitoring, enter:

   mondecfg gangliamon

2. To deconfigure the management node, nodes and their service nodes from the ganglia monitoring, enter:
mondecfg gangliamon -r

FILES

/opt/xcat/bin/mondecfg

SEE ALSO

monls(1)|monls.1, moncfg(1)|moncfg.1, monadd(1)|monadd.1, monrm(1)|monrm.1, monstart(1)|monstart.1, monstop(1)|monstop.1

monls.1

NAME

monls - Lists monitoring plug-in modules that can be used to monitor the xCAT cluster.

SYNOPSIS

monls [-h | --help]
monls [-v | --version]
monls name [-d | --description]
monls [-a | --all] [-d | --description]

DESCRIPTION

This command is used to list the status, description, the configuration scripts and the settings of one or all of the monitoring plug-in modules.

Parameters

name is the name of the monitoring plug-in module.

OPTIONS

-a | --all Searches the XCATROOT/lib/perl/xCAT_monitoring directory and reports all the monitoring plug-in modules. If nothing is specified, the list is read from the monitoring table.
-d | --description Display the description of the plug-in modules. The description usually contains the possible settings.
-h | --help Display usage message.
-v | --version Command Version.
RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To list the status of all the monitoring plug-in modules from the monitoring table, enter:

   monls

   The output looks like this:

   xcatmon monitored node-status-monitored
   snmpmon not-monitored

2. To list the status of all the monitoring plug-in modules including the ones that are not in the monitoring table, enter:

   monls -a

   The output looks like this:

   xcatmon monitored node-status-monitored
   snmpmon not-monitored
   gangliamon not-monitored
   rmcmon monitored
   nagiosmon not-monitored

3. To list the status and the description for snmpmon module, enter:

   monls snmpmon -d

FILES

/opt/xcat/bin/monls

SEE ALSO

monadd(1)|monadd.1, monrm(1)|monrm.1, monstart(1)|monstart.1, monstop(1)|monstop.1, moncfg(1)|moncfg.1, mondecfg(1)|mondecfg.1

monrm.1

NAME

monrm - Unregisters a monitoring plug-in module from the xCAT cluster.
SYNOPSIS

monrm [-h|--help]
monrm [-v|--version]
monrm name

DESCRIPTION

This command is used to unregister a monitoring plug-in module from the monitoring table. It also removes any configuration scripts associated with the monitoring plug-in from the postscripts table. A monitoring plug-in module acts as a bridge that connects a 3rd party monitoring software and the xCAT cluster. A configuration script is used to configure the 3rd party software. Once added to the postscripts table, it will be invoked on the nodes during node deployment stage.

PARAMETERS

name is the name of the monitoring plug-in module in the monitoring table. Use monls command to list all the monitoring plug-in modules that can be used.

OPTIONS

-h|--help Display usage message.
-v|--version Command Version.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1.To unregister gangliamon plug-in module (which interacts with Ganglia monitoring software) from the xCAT cluster, enter:

    monrm gangliamon

Note that gangliamon must have been registered in the xCAT monitoring table. For a list of registered plug-in modules, use command monls.

FILES

/opt/xcat/bin/monrm
NAME

monshow - Shows event data for monitoring.

SYNOPSIS

monshow [-h|--help]
monshow [-v|--version]
monshow name [noderange] [-s] [-t time] [-a attributes] [-w attr < operator > val [-w attr < operator > val] ... ][-o {p|e}]

DESCRIPTION

This command displays the events that happened on the given nodes or the monitoring data that is collected from the given nodes for a monitoring plugin.

PARAMETERS

name is the name of the monitoring plug-in module to be invoked.
noderange is a list of nodes to be showed for. If omitted, the data for all the nodes will be displayed.

OPTIONS

-h | --help Display usage message.
-v | --version Command Version.
-s shows the summary data.
-t specifies a range of time for the data, The default is last 60 minutes. For example -t 6-4, it will display the data from last 6 minutes to 4 minutes; If it is -t 6, it will display the data from last 6 minutes until now.
-a specifies a comma-separated list of attributes or metrics names. The default is all.
-w specify one or multiple selection string that can be used to select events. The operators ==, !=, =,>,<,>=,<= are available. Wildcards % and _ are supported in the pattern string. % allows you to match any string of any length(including zero length) and _ allows you to match on a single character. The valid attributes are eventtype, monitor, monnode, application, component, id, severity, message, rawdata, comments. Valid severity are: Informational, Warning, Critical.

Operator descriptions:
== Select event where the attribute value is exactly this value.
!= Select event where the attribute value is not this specific value.

=~ Select event where the attribute value matches this pattern string. Not work with severity.

!~> Select event where the attribute value does not match this pattern string. Not work with severity.

> Select event where the severity is higher than this value. Only work with severity.

< Select event where the severity is lower than this value. Only work with severity.

>= Select event where the severity is higher than this value(include). Only work with severity.

<= Select event where the severity is lower than this value(include). Only work with severity.

Note: if the “val” or “operator” fields includes spaces or any other characters that will be parsed by shell, the “attr<operator>val” needs to be quoted. If the operator is “!~”, the “attr<operator>val” needs to be quoted using single quote.

-o specifies montype, it can be p or e. p means performance, e means events.

**RETURN VALUE**

0 The command completed successfully.

1 An error has occurred.

**EXAMPLES**

1. To show summary data about PctRealMemFree and PctTotalTimeIdle of cluster in last 6 minutes, enter:

   ```
   monshow rmcmon -s -a PctRealMemFree,PctTotalTimeIdle -t 6
   ```

2. To show all data of node1 and node2, enter:

   ```
   monshow rmcmon node1,node2
   ```

3. To show summary data of nodes which managed by servicenode1, enter:

   ```
   monshow rmcmon servicenode1 -s
   ```

4. To show RMC event with severity Critical, enter:

   ```
   monshow rmcmon -w severity==Critical
   ```

**FILES**

```
/opt/xcat/bin/monshow
```

**SEE ALSO**

```
monls(1)|monls.1, monstart(1)|monstart.1, monstop(1)|monstop.1, monadd(1)|monadd.1, monrm(1)|monrm.1, moncfg(1)|moncfg.1, mondecfg(1)|mondecfg.1
```
monstart.1

NAME

**monstart** - Starts a plug-in module to monitor the xCAT cluster.

SYNOPSIS

```
monstart [-h|--help]
monstart [-v|--version]
monstart name [noderange] [-r|--remote]
```

DESCRIPTION

This command is used to start a 3rd party software, (for example start the daemons), to monitor the xCAT cluster. The operation is performed on the management node and the service nodes of the given nodes. The operation will also be performed on the nodes if the `-r` option is specified.

PARAMETERS

`name` is the name of the monitoring plug-in module. For example, if the `name` is called `xxx`, then the actual file name that the xcatd looks for is `/opt/xcat/lib/perl/xCAT_monitoring/xxx.pm`. Use `monls -a` command to list all the monitoring plug-in modules that can be used.

`noderange` is the nodes to be monitored. If omitted, all nodes will be monitored.

OPTIONS

- `-h` | `--help` Display usage message.
- `-r` | `--remote` Specifies that the operation will also be performed on the nodes. For example, the 3rd party monitoring software daemons on the nodes will also be started.
- `-v` | `--version` Command Version.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To start gangliamon plug-in module (which interacts with Ganglia monitoring software) to monitor the xCAT cluster, enter:

   ```
   monstart gangliamon -r
   ```

2. To start xcatmon plug-in module to feed the node liveness status to xCAT’s `nodelist` table, enter:
monstart rmcmmon

FILES

/opt/xcat/bin/monstart

SEE ALSO

monls(1)|monls.1, monstop(1)|monstop.1, monadd(1)|monadd.1, monrm(1)|monrm.1, moncfg(1)|moncfg.1, mondecfg(1)|mondecfg.1

monstop.1

NAME

monstop - Stops a monitoring plug-in module to monitor the xCAT cluster.

SYNOPSIS

monstop [-h|--help]
 monstop [-v|--version]
 monstop name [noderange] [-r|--remote]

DESCRIPTION

This command is used to stop a 3rd party software, (for example stop the daemons), from monitoring the xCAT cluster. The operation is performed on the management node and the service nodes of the given nodes. The operation will also be performed on the nodes if the -r option is specified.

PARAMETERS

name is the name of the monitoring plug-in module in the monitoring table. Use monls command to list all the monitoring plug-in modules that can be used.

noderange is the nodes to be stopped for monitoring. If omitted, all nodes will be stopped.

OPTIONS

-h | -help Display usage message.
-r | --remote Specifies that the operation will also be performed on the nodes. For example, the 3rd party monitoring software daemons on the nodes will also be stopped.
-v | -version Command Version.
RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To stop gangliamon plug-in module (which interacts with Ganglia monitoring software) to monitor the xCAT cluster, enter:

   monstop gangliamon

   Note that gangliamon must have been registered in the xCAT monitoring table. For a list of registered plug-in modules, use command monls.

FILES

/opt/xcat/bin/monstop

SEE ALSO

monls(1) | monls.1, monstart(1) | monstart.1, monadd(1) | monadd.1, monrm(1) | monrm.1, moncfg(1) | moncfg.1, mondecfg(1) | mondecfg.1

mysqlsetup.1

NAME

mysqlsetup - Sets up the MySQL or MariaDB database for xCAT to use.

SYNOPSIS

mysqlsetup { -h | --help }
mysqlsetup { -v | --version }
mysqlsetup { -i | --init } [ -f | --hostfile ] [ -o | --odbc ] [ -L | --LL ] [ -V | --verbose ]
mysqlsetup { -u | --update } [ -f | --hostfile ] [ -o | --odbc ] [ -L | --LL ] [ -V | --verbose ]
mysqlsetup { -o | --odbc } [ -V | --verbose ]
mysqlsetup { -L | --LL } [ -V | --verbose ]

DESCRIPTION

mysqlsetup - Sets up the MySQL or MariaDB database (linux only for MariaDB) for xCAT to use. The mysqlsetup script is run on the Management Node as root after the MySQL code or MariaDB code has been installed. Before running the init option, the MySQL server should be stopped, if it is running. The xCAT daemon, xcatd, must be running, do not stop it. No xCAT commands should be run during the init process, because we will be migrating...
the xCAT database to MySQL or MariaDB and restarting the xcatd daemon as well as the MySQL daemon. For full information on all the steps that will be done, read the “Configure MySQL and Migrate xCAT Data to MySQL” sections in

**Setting_Up_MySQL_as_the_xCAT_DB**

Two passwords must be supplied for the setup, a password for the xcatadmin id and a password for the root id in the MySQL database. These will be prompted for interactively, unless the environment variables `XCATMYSQLADMIN_PW` and `XCATMYSQLROOT_PW` are set to the passwords for the xcatadmin id and root id in the database, resp.

Note below we refer to MySQL but it works the same for MariaDB.

**OPTIONS**

- **-h|--help**
  Displays the usage message.

- **-v|--version**
  Displays the release version of the code.

- **-V|--verbose**
  Displays verbose messages.

- **-i|--init**
  The init option is used to setup a xCAT database on an installed MySQL or MariaDB server for xCAT to use. The mysqlsetup script will check for the installed MariaDB server rpm first and will use MariaDB if it is installed. This involves creating the xcatdb database, the xcatadmin id, allowing access to the xcatdb database by the Management Node. It customizes the my.cnf configuration file for xcat and starts the MySQL server. It also backs up the current xCAT database and restores it into the newly setup xcatdb MySQL database. It creates the `/etc/xcat/cfgloc` file to point the xcatd daemon to the MySQL database and restarts the xcatd daemon using the database. On AIX, it additionally setups the mysql id and group and corrects the permissions in the MySQL install directories. For AIX, you should be using the MySQL rpms available from the xCAT website. For Linux, you should use the MySQL or MariaDB rpms shipped with the OS. You can chose the -f and/or the -o option, to run after the init.

- **-u|--update**
  To run the update option, you must first run the -i option and have xcat successfully running on the MySQL database. You can chose the -f and/or the -o option, to update.

- **-f|--hostfile**
  This option runs during update, it will take all the host from the input file (provide a full path) and give them database access to the xcatdb in MySQL for the xcatadmin id. Wildcards and ipaddresses may be used. xCAT must have been previously successfully setup to use MySQL. xcatadmin and MySQL root password are required.

- **-l|--odbc**
  This option sets up the ODBC `/etc/.../odbcinst.ini`, `/etc/.../odbc.ini` and the `.odbc.ini` file in roots home directory will be created and initialized to run off the xcatdb MySQL database. See “Add ODBC Support” in Setting_Up_MySQL_as_the_xCAT_DB

- **-L|--LL**
  Additional database configuration specifically for the LoadLeveler product. See “Add ODBC Support” in Setting_Up_MySQL_as_the_xCAT_DB
ENVIRONMENT VARIABLES

* XCATMYSQLADMIN_PW - the password for the xcatadmin id that will be assigned in the MySQL database.
* XCATMYSQLROOT_PW - the password for the root id that will be assigned to the MySQL root id, if the script creates it. The password to use to run MySQL command to the database as the MySQL root id. This password may be different than the unix root password on the Management Node.

EXAMPLES

1. To setup MySQL for xCAT to run on the MySQL xcatdb database:

   mysqlsetup -i

2. Add hosts from /tmp/xcat/hostlist that can access the xcatdb database in MySQL:

   mysqlsetup -u -f /tmp/xcat/hostlist

   Where the file contains a host per line, for example:

   node1
   1.115.85.2
   10.%.%.%
   nodex.cluster.net

3. To setup the ODBC for MySQL xcatdb database access:

   mysqlsetup -o

4. To setup MySQL for xCAT and add hosts from /tmp/xcat/hostlist and setup the ODBC in Verbose mode:

   mysqlsetup -i -f /tmp/xcat/hostlist -o -V

nimnodecust.1

NAME

nimnodecust - Use this xCAT command to customize AIX/NIM standalone machines.

SYNOPSIS

nimnodecust [-h|--help]
nimnodecust [-V] -s lpp_source_name [-p packages] [-b installp_bundles] noderange [attr=val [attr=val ...]]

DESCRIPTION

This xCAT command can be used to customize AIX/NIM standalone machines.

The software packages that you wish to install on the nodes must be copied to the appropriate directory locations in the NIM lpp_source resource provided by the “-s” option. For example, if the location of your lpp_source resource is “/install/nim/lpp_source/61lpp/” then you would copy RPM packages to “/install/nim/lpp_source/61lpp/RPMS/ppc”
and you would copy your installp packages to “/install/nim/lpp_source/61lpp/installp/ppc”. Typically you would want to copy the packages to the same lpp_source that was used to install the node. You can find the location for an lpp_source with the AIX lsnim command. (Ex. “lsnim -l <lpp_source_name>”)

The packages you wish to install on the nodes may be specified with either a comma-separated list of package names or by a comma-separated list of installp_bundle names. The installp_bundle names are what were used when creating the corresponding NIM installp_bundle definitions. The installp_bundle definitions may also be used when installing the nodes.

A bundle file contains a list of package names. The RPMs must have a prefix of “R:” and the installp packages must have a prefix of “I:”. For example, the contents of a simple bundle file might look like the following.

```
# RPM
R:expect-5.42.1-3.aix5.1.ppc.rpm
R:ping-2.4b2_to-1.aix5.3.ppc.rpm

#installp
I:openssh.base
I:openssh.license
```

To create a NIM installp_bundle definition you can use the “nim -o define” operation. For example, to create a definition called “mypackages” for a bundle file located at “/install/nim/mypkgs.bnd” you could issue the following command.

```
nim -o define -t installp_bundle -a server=master -a location=/install/nim/mypkgs.bnd
---mypackages
```

See the AIX documentation for more information on using installp_bundle files.

The xCAT nimnodecust command will automatically handle the distribution of the packages to AIX service nodes when using an xCAT hierarchical environment.

**OPTIONS**

```
attr=val [attr=val ...]
```

Specifies one or more “attribute equals value” pairs, separated by spaces. Attr=val pairs must be specified last on the command line. These are used to specify additional values that can be passed to the underlying NIM commands, (“nim -o cust...”). See the NIM documentation for valid “nim” command line options.

```
-b installp_bundle_names
```

A comma separated list of NIM installp_bundle names.

```
-h |--help
```

Display usage message.

```
-p package_names
```

A comma-separated list of software packages to install. Packages may be RPM or installp.

```
noderange
```

A set of comma delimited node names and/or group names. See the “noderange” man page for details on additional supported formats.

```
-V |--verbose
```

Verbose mode.
RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. Install the installp package “openssh.base.server” on an xCAT node named “node01”. Assume that the package has been copied to the NIM lpp_source resource called “61lppsource”.

```
nimnodecust -s 61lppsource -p openssh.base.server node01
```

2. Install the product software contained in the two bundles called “llbnd” and “pebnd” on all AIX nodes contained in the xCAT node group called “aixnodes”. Assume that all the software packages have been copied to the NIM lpp_source resource called “61lppsource”.

```
nimnodecust -s 61lppsource -b llbnd,pebnd aixnodes
```

FILES

```
/opt/xcat/bin/nimnodecust
```

NOTES

This command is part of the xCAT software product.

nimnodeset.1

NAME

nimnodeset - Use this xCAT command to initialize AIX/NIM standalone machines.

SYNOPSIS

```
nimnodeset [-h|--help ] [ -V|--verbose ] [ -f|--force ] [ -i osimage_name ] [ -l location ] [ -p|--primarySN ] [ -b|--backupSN ] noderange [ attr=val [ attr=val . . . ]]
```

DESCRIPTION

This xCAT command can be used to initialize AIX/NIM standalone machines. Once this step is completed the either the xCAT rnetboot command or the rbootseq/rpower commands to initiate a network boot of the nodes.

If you are using xCAT service nodes the nimnodeset command will automatically determine the correct server(s) for the node and do the initialization on that server(s).
The osimage_name is the name of an xCAT osimage definition that contains the list of NIM resources to use when initializing the nodes. If the osimage_name is not provided on the command line the code checks the node definition for the value of the “provmethod” attribute (which is the name of an osimage definition). If the osimage_image is provided on the command line then the code will also set the “provmethod” attribute of the node definitions.

This command will also create a NIM resolv_conf resource to be used when installing the node. If a resolv_conf resource is not already included in the xCAT osimage definition and if the “domain” and “nameservers” values are set then a new NIM resolv_conf resource will be created and allocated to the nodes.

The “domain” and “nameservers” attributes can be set in either the xCAT “network” definition used by the nodes or in the xCAT cluster “site” definition. The setting in the “network” definition will take priority.

The “search” field of the resolv.conf file will contain a list all the domains listed in the xCAT network definitions and the xCAT site definition.

The “nameservers” value can either be set to a specific IP address or the “<xcatmaster>” key word. The “<xcatmaster>” key word means that the value of the “xcatmaster” attribute of the node definition will be used in the /etc/resolv.conf file. (i.e. The name of the install server as known by the node.)

You can set the “domain” and “nameservers” attributes by using the chdef command. For example:

```
chdef -t network -o clstr_net domain=cluster.com nameservers=<xcatmaster>
```

If the “domain” and “nameservers” attributes are not set in either the nodes “network” definition or the “site” definition then no new NIM resolv_conf resource will be created.

You can specify additional attributes and values using the “attr=val” command line option. This information will be passed on to the underlying call to the NIM “nim -o bos_inst” command. See the NIM documentation for information on valid command line options for the nim command. The “attr” must correspond to a NIM attribute supported for the NIM “bos_inst” operation. Information provided by the “attr=val” option will take precedence over the information provided in the osimage definition.

The force option can be used to reinitialize a node if it already has resources allocated or it is in the wrong NIM state. This option will reset the NIM node and deallocate resources before reinitializing.

This command will also create a NIM script resource to enable the xCAT support for user-provided customization scripts.

After the nimnodeset command completes you can use the lsnim command to check the NIM node definition to see if it is ready for booting the node. (“lsnim -l <nim_node_name>”).

You can supply your own scripts to be run on the management node or on the service node (if there is hierarchy) for a node during the nimnodeset command. Such scripts are called prescripts. They should be copied to /install/prescripts directory. A table called prescripts is used to specify the scripts and their associated actions. The scripts to be run at the beginning of the nimnodeset command are stored in the ‘begin’ column of prescripts table. The scripts to be run at the end of the nimnodeset command are stored in the ‘end’ column of prescripts table. Run ‘tabdump prescripts -d’ command for details. An example for the ‘begin’ or the ‘end’ column is: standalone:myscript1,myscript2. The following two environment variables will be passed to each script: NODES contains all the names of the nodes that need to run the script for and ACTION contains the current noderset action, in this case “standalone”. If #xCAT setting:MAX_INSTANCE=number is specified in the script, the script will get invoked for each node in parallel, but no more than number of instances will be invoked at at a time. If it is not specified, the script will be invoked once for all the nodes.

**OPTIONS**

```
attr=val [attr=val ...]
```

Specifies one or more “attribute equals value” pairs, separated by spaces. Attr= val pairs must be specified last on the command line. These are used to specify additional values that can be passed to the underlying
NIM commands, ("nim -o bos_inst ..."). See the NIM documentation for valid “nim” command line options. Note that you may specify multiple “script” and “installp_bundle” values by using a comma separated list. (ex. “script=ascript,bscript”).

-b|--backupSN
When using backup service nodes only update the backup. The default is to update both the primary and backup service nodes

-f|--force
Use the force option to reinitialize the NIM machines.

-h|--help
Display usage message.

-i image_name
The name of an existing xCAT osimage definition.

-l|--location
The directory location to use when creating new NIM resolv_conf resources. The default location is /install/nim.

-p|--primarySN
When using backup service nodes only update the primary. The default is to update both the primary and backup service nodes.

-noderange
A set of comma delimited node names and/or group names. See the “noderange” man page for details on additional supported formats.

-V|--verbose
Verbose mode.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. Initialize an xCAT node named “node01”. Use the xCAT osimage named “61gold” to install the node.

\[nimnodeset -i 61gold node01\]

2. Initialize all AIX nodes contained in the xCAT node group called “aixnodes” using the image definitions pointed to by the “provmethod” attribute of the xCAT node definitions.

\[nimnodeset aixnodes\]

3. Initialize an xCAT node called “node02”. Include installp_bundle resources that are not included in the osimage definition. This assumes the NIM installp_bundle resources have already been created.
nimnodeset -i 6llimage node02 installp_bundle=sshbundle,addswbundle

FILES

/opt/xcat/bin/nimnodeset

NOTES

This command is part of the xCAT software product.

SEE ALSO

mknimimage(1)|mknimimage.1, rnetboot(1)|rnetboot.1
	nodeaddunmged.1

NAME

nodeaddunmged - Create a unmanaged node.

SYNOPSIS

nodeaddunmged [-h | --help] [-v | --version]
nodeaddunmged hostname=node-name ip=ip-address

DESCRIPTION

The nodeaddunmged command adds an unmanaged node to the __Unmanaged group. You can specify the node name and IP address of the node.

OPTIONS

- h|--help
Display usage message.

-v|--version
Command Version.

hostname=node-name
Sets the name of the new unmanaged node, where <node-name> is the name of the node.

ip=ip-address
Sets the IP address of the unmanaged node, where ip-address is the IP address of the new node in the form xxx.xxx.xxx.xxx
RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

To add an unmanaged node, use the following command:

```
nodeaddunmged hostname=unmanaged01 ip=192.168.1.100
```

SEE ALSO

nodech.1

NAME

nodech - Changes nodes’ attributes in the xCAT cluster database.

SYNOPSIS

```
nodech noderange table.column=value [...]  
nodech {-d | --delete} noderange table [...]  
nodech {-v | --version}  
nodech [-? | -h | --help]
```

DESCRIPTION

The nodech command changes the specified attributes for the given nodes. Normally, the given value will completely replace the current attribute value. But if “,”=” is used instead of “=”, the specified value will be prepended to the attribute’s comma separated list, if it is not already there. If “^=” is used, the specified value will be removed from the attribute’s comma separated list, if it is there. You can also use “^=” and “,”=” in the same command to essentially replace one item in the list with another. (See the Examples section.)

Additionally, as in nodels, boolean expressions can be used to further limit the scope of nodech from the given noderange. The operators supported are the same as nodels (=, !~, ==, and !=).

With these operators in mind, the unambiguous assignment operator is ‘=@’. If you need, for example, to set the nodelist.comments to =foo, you would have to do nodech n1 nodelist.comments==@=foo.

See the xcatdb man page for an overview of each table.

The nodech command also supports some short cut names as aliases to common attributes. See the nodels man page for details.
OPTIONS

-dl--delete
    Delete the nodes’ row in the specified tables.

-vl--version
    Command Version.

-?|-hl--help
    Display usage message.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To update nodes in noderange node1-node4 to be in only group all:
   ```bash
   nodech node1-node4 groups=all
   ```

2. To put all nodes with nodepos.rack value of 2 into a group called rack2:
   ```bash
   nodech all nodepos.rack==2 groups,=rack2
   ```

3. To add nodes in noderange node1-node4 to the nodetype table with os=rhel5:
   ```bash
   nodech node1-node4 groups=all,rhel5 nodetype.os=rhel5
   ```

4. To add node1-node4 to group1 in addition to the groups they are already in:
   ```bash
   nodech node1-node4 groups,=group1
   ```

5. To put node1-node4 in group2, instead of group1:
   ```bash
   nodech node1-node4 groups^=group1 groups,=group2
   ```

FILES

/opt/xcat/bin/nodech

SEE ALSO

nodels(1)|nodels.1, nodeadd(8)|nodeadd.8, noderange(3)|noderange.3
nodechmac

NAME

nodechmac - Updates the MAC address for a node.

SYNOPSIS

nodechmac [-h | --help | -v | --version]
nodechmac node-name mac=mac-address

DESCRIPTION

The nodechmac command changes the MAC address for provisioned node’s network interface.

You can use this command to keep an existing node configuration. For example, if an existing node has hardware problems, the replacement node can use the old configurations. By using the nodechmac command, the node name and network settings of the old node can be used by the new node.

OPTIONS

- -h | --help
Display usage message.
- -v | --version
Command Version.

node-name

Specifies the name of the node you want to update, where <node-name> is the node that is updated.

mac=mac-address

Sets the new MAC address for the NIC used by the provisioning node, where <mac-address> is the NICs new MAC address.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

You can update the MAC address for a node, by using the following command:

nodechmac compute-000 mac=2F:3C:88:98:7E:01
SEE ALSO

nodechprofile.1

NAME

nodechprofile - updates a profile used by a node

SYNOPSIS

nodechprofile [-h|--help | -v | --version]

nodechprofile noderange [imageprofile= image-profile] [networkprofile= network-profile] [hardwareprofile= hardware-profile]

DESCRIPTION

The nodechprofile command updates the profiles used by a node, including: the image profile, network profile, and hardware management profile.

If you update the image profile for a node, the operating system and provisioning settings for the node are updated.
If you update the network profile, the IP address and network settings for the node are updated.
If you update the hardware management profile, the hardware settings for the node are updated.

After nodes’ hardware profile or image profile are updated, the status for each node is changed to “defined”. A node with a “defined” status must be reinstalled.
After nodes’ network profile updated, the status for nodes is not changed. You’ll need to run noderegenips to re-generate the nodes’ IP address and nodes’ status may also be updated at this stage.

OPTIONS

-h|--help
Display usage message.

-v|--version
Command Version.

noderange
The nodes to be removed.

imageprofile= image-profile
Sets the new image profile name used by the node, where <image-profile> is the new image profile. An image profile defines the provisioning method, OS information, kit information, and provisioning parameters for a node. If the “__ImageProfile_imgprofile” group already exists in the nodehm table, then “imgprofile” is used as the image profile name.

networkprofile= network-profile
Sets the new network profile name used by the node, where <network-profile> is the new network profile. A network profile defines the network, NIC, and routes for a node. If the “__NetworkProfile_netprofile” group already exists in the nodehm table, then “netprofile” is used as the network profile name.
**hardwareprofile= hardware-profile**

Sets the new hardware profile name used by the node, where `<hardware-profile>` is the new hardware management profile used by the node. If a “__HardwareProfile_hwprofile” group exists, then “hwprofile” is the hardware profile name. A hardware profile defines hardware management related information for imported nodes, including: IPMI, HMC, CEC, CMM.

**RETURN VALUE**

0  The command completed successfully.
1  An error has occurred.

**EXAMPLES**

1. To change the image profile to rhels6.3_packaged for compute nodes compute-000 and compute-001, use the following command:

   ```
   nodechprofile compute-000,compute-001 imageprofile=rhels6.3_packaged
   ```

2. To change all of the profiles for compute node compute-000, enter the following command:

   ```
   nodechprofile compute-000 imageprofile=rhels6.3_packaged
   ->networkprofile=default_cn hardwareprofile=default_ipmi
   ```

**SEE ALSO**

nodepurge(1)|nodepurge.1, noderefresh(1)|noderefresh.1, nodeimport(1)|nodeimport.1, noderange(3)|noderange.3

**nodediscoverdef.1**

**NAME**

**nodediscoverdef** - Define the undefined discovery request to a predefined xCAT node, or clean up the discovery entries from the discoverydata table (which can be displayed by nodediscoverls command)

**SYNOPSIS**

```
nodediscoverdef -u uuid -n node
nodediscoverdef -r -u uuid
nodediscoverdef -r -t {seq | profile | switch | blade | manual | undef | all}
nodediscoverdef [-h | --help | -v | --version]
```
DESCRIPTION

The `nodediscoverdef` command defines the discovery entry from the discoverydata table to a predefined xCAT node. The discovery entry can be displayed by `nodediscoverls` command.

The options `-u` and `-n` have to be used together to define a discovery request to a node.

The `nodediscoverdef` command also can be used to clean up the discovery entries from the discoverydata table.

The option `-r` is used to remove discovery entries. If working with `-u`, the specific entry which uuid specified by `-u` will be removed.

You also can use the `-r -t` option to limit that only remove the nodes that were discovered in a particular method of discovery.

OPTIONS

```
-t seq|profile|switch|blade|manual|undef|all
```

Specify the nodes that have been discovered by the specified discovery method:

* `seq` - Sequential discovery (started via nodediscoverstart noderange=<noderange> ...).

* `profile` - Profile discovery (started via nodediscoverstart networkprofile=<network-profile> ...).

* `switch` - Switch-based discovery (used when the switch and switches tables are filled in).

* `blade` - Blade discovery (used for IBM Flex blades).

* `manual` - Manually discovery (used when defining node by nodediscoverdef command).

* `undef` - Display the nodes that were in the discovery pool, but for which xCAT has not yet received a discovery request.

* `all` - All discovered nodes.

```
-n node
```

The xCAT node that the discovery entry will be defined to.

```
-r
```

Remove the discovery entries from discoverydata table.

```
-u uuid
```

The uuid of the discovered entry.

```
-h|--help
```

Display usage message.

```
-v|--version
```

Command version.

RETURN VALUE

0 The command completed successfully.

1 An error has occurred.
EXAMPLES

1. Define the discovery entry which uuid is 51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB4 to node node1

   `nodediscoverdef -u 51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB4 -n node1`

   Output is similar to:

   Defined [51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB4] to node node1.

2. Remove the discovery entry which uuid is 51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB4 from the discovery-data table

   `nodediscoverdef -r -u 51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB4`

   Output is similar to:

   Removing discovery entries finished.

3. Remove the discovery entries which discover type is seq from the discovery-data table

   `nodediscoverdef -r -t seq`

   Output is similar to:

   Removing discovery entries finished.

SEE ALSO

nodediscoverstart(1), nodediscoverstatus(1), nodediscoverstop(1), nodediscoverdn(1), nodediscoverls(1)

nodediscoverls.1

NAME

nodediscoverls - List the discovered nodes

SYNOPSIS

nodediscoverls [-t seq | profile | switch | blade | manual | undef | all] [-l]
nodediscoverls [-u uuid] [-l]
nodediscoverls [-h | --help | -v | --version]

DESCRIPTION

The nodediscoverls command lists nodes that have recently been discovered. If discovery is currently in progress (i.e. nodediscoverstart has been run, but nodediscoverstop has not been), then nodediscoverls will list the nodes that have been discovered so far in this session. If discovery is not currently in progress, nodediscoverls will list all of the nodes that were discovered in the last discovery session.
You can use the `-t` option to limit the output to just the nodes that were discovered in a particular method of discovery.

**OPTIONS**

- `-t` `seq|profile|switch|blade|manual|undef|all`
  
  Display the nodes that have been discovered by the specified discovery method:
  
  * `-seq` - Sequential discovery (started via `nodediscoverstart noderange=<noderange>` ...).
  * `-profile` - Profile discovery (started via `nodediscoverstart networkprofile=<network-profile>` ...).
  * `-switch` - Switch-based discovery (used when the switch and switches tables are filled in).
  * `-blade` - Blade discovery (used for IBM Flex blades).
  * `-manual` - Manually discovery (used when defining node by `nodediscoverdef` command).
  * `-undef` - Display the nodes that were in the discovery pool, but for which xCAT has not yet received a discovery request.
  * `-all` - All discovered nodes.

- `-l`
  
  Display more detailed information about the discovered nodes.

- `-u` `uuid`
  
  Display the discovered node that has this `uuid`.

- `-h|--help`
  
  Display usage message.

- `-v|--version`
  
  Command version.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.

**EXAMPLES**

1. Display the discovered nodes when sequential discovery is running:

   ```
   nodediscoverls
   ```

   Output is similar to:

   ```
   UUID          NODE          METHOD
   ←−MTM SERIAL  distest1 sequential
   51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB2 distest1 sequential
   ←−786310X 1052EF2
   51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB3 distest2 sequential
   ←−786310X 1052EF3
   ```
2. Display the nodes that were in the discovery pool, but for which xCAT has not yet received a discovery request:

```bash
dodediscoverls -t undef
```

Output is similar to:

<table>
<thead>
<tr>
<th>UUID</th>
<th>NODE</th>
<th>METHOD</th>
</tr>
</thead>
<tbody>
<tr>
<td>51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB0</td>
<td>undefined</td>
<td>undefined</td>
</tr>
<tr>
<td>786310X 1052EF0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB1</td>
<td>undefined</td>
<td>undefined</td>
</tr>
<tr>
<td>786310X 1052EF1</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

3. Display all the discovered nodes:

```bash
didediscoverls -t all
```

Output is similar to:

<table>
<thead>
<tr>
<th>UUID</th>
<th>NODE</th>
<th>METHOD</th>
</tr>
</thead>
<tbody>
<tr>
<td>51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB0</td>
<td>undefined</td>
<td>undefined</td>
</tr>
<tr>
<td>786310X 1052EF0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB1</td>
<td>undefined</td>
<td>undefined</td>
</tr>
<tr>
<td>786310X 1052EF1</td>
<td></td>
<td></td>
</tr>
<tr>
<td>51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB2</td>
<td>distest1</td>
<td>sequential</td>
</tr>
<tr>
<td>786310X 1052EF2</td>
<td></td>
<td></td>
</tr>
<tr>
<td>51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB3</td>
<td>distest2</td>
<td>sequential</td>
</tr>
<tr>
<td>786310X 1052EF3</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

4. Display the discovered node whose uuid is 51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB2, with detailed information:

```bash
odediscoverls -u 51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB2 -l
```

Output is similar to:

```
Object uuid: 51E5F2D7-0D59-11E2-A7BC-3440B5BEDBB2
  node=distest1
  method=sequential
  discoverytime=03-31-2013 17:05:12
  arch=x86_64
  cpucount=32
  cputype=Intel(R) Xeon(R) CPU E5-2690 0 @ 2.90GHz
  memory=198460852
  mtm=786310X
  serial=1052EF2
  nicdriver=eth0!be2net,eth1!be2net
  nicipv4=eth0!10.0.0.212/8
  nichwaddr=eth0!34:40:B5:BE:DB:B0,eth1!34:40:B5:BE:DB:B4
  nicipci=eth0!0000:0c:00.0,eth1!0000:0c:00.1
  nicloc=eth0!Onboard Ethernet 1,eth1!Onboard Ethernet 2
  niconboard=eth0!1,eth1!2
  nicfirm=eth0!ServerEngines BE3 Controller,eth1!ServerEngines BE3
  switchname=eth0!c909f06sw01
  switchaddr=eth0!192.168.70.120
```

(continues on next page)
SEE ALSO

nodediscoverstart(1)nodediscoverstart.1, nodediscoverstatus(1)nodediscoverstatus.1, nodediscoverstop(1)nodediscoverstop.1, nodediscoverdef(1)nodediscoverdef.1

nodediscoverstart.1

NAME

nodediscoverstart - starts the node discovery process

SYNOPSIS

nodediscoverstart [-h | --help] [-v | --version]

Sequential Discovery Specific:

nodediscoverstart noderange=noderange [hostiprange=imageprofile] [bmciprange=bmciprange] [groups=groups] [rack=rack] [chassis=chassis] [height=height] [unit=unit] [osimage=osimagename] [-n | --dns] [-s | --skipbmcsetup] [-V|--verbose]

Profile Discovery Specific:

nodediscoverstart networkprofile=networkprofile imageprofile=imageprofile hostnameformat=hostnameformat [hardwareprofile=hardware-profile] [groups=node-groups] [rack=rack-name] [chassis=chassis-name] [height=rack-server-height] [unit=rack-server-unit-location] [rank=rank-num]

DESCRIPTION

The nodediscoverstart command starts either the Sequential Discovery or Profile Discovery process. They can not both be running at the same time.

Sequential Discovery Specific:

This is the simplest discovery approach. You only need to specify the noderange, hostiprange and bmciprange that should be given to nodes that are discovered. (If you pre-define the nodes (via nodeadd or mkdef) and specify their host and BMC IP addresses, then you only need to specify the noderange to the nodediscoverstart command.) Once you have run nodediscoverstart, then physically power on the nodes in the sequence that you want them to receive the node names and IPs, waiting a short time (e.g. 30 seconds) between each node.

Profile Discovery Specific:

This is the PCM discovery approach. networkprofile, imageprofile, hostnameformat arguments must be specified to start the Profile Discovery. All nodes discovered by this process will be associated with specified profiles and rack/chassis/unit locations.

When the nodes are discovered, PCM updates the affected configuration files on the management node automatically. Configuration files include the /etc/hosts service file, DNS configuration, and DHCP configuration. Kit plug-ins are automatically triggered to update kit related configurations and services.
When you power on the nodes, they PXE boot and DHCP/TFTP/HTTP on the management node give each node the xCAT genesis boot image, which inventories the node hardware and sends data to the management node. There, either the sequential discovery process or the profile discovery process assigns node attributes and defines the node in the database.

**OPTIONS**

- **noderange=noderange**
  
The set of node names that should be given to nodes that are discovered via the **Sequential Discovery** method. This argument is required to **Sequential Discovery**. Any valid xCAT **noderange** is allowed, e.g. node[01-10].

- **hostiprange=ip range**
  
The ip range which will be assigned to the host of new discovered nodes in the **Sequential Discovery** method. The format can be: `start_ip-end_ip` or `noderange`, e.g. 192.168.0.1-192.168.0.10 or 192.168.0.[1-10].

- **bmciprange=ip range**
  
The ip range which will be assigned to the bmc of new discovered nodes in the **Sequential Discovery** method. The format can be: `start_ip-end_ip` or `noderange`, e.g. 192.168.1.1-192.168.1.10 or 192.168.1.[1-10].

- **imageprofile=image-profile**
  
  Sets the new image profile name used by the discovered nodes in the **Profile Discovery** method. An image profile defines the provisioning method, OS information, kit information, and provisioning parameters for a node. If the “__ImageProfile_imgprofile” group already exists in the nodehm table, then “imgprofile” is used as the image profile name.

- **networkprofile=network-profile**
  
  Sets the new network profile name used by the discovered nodes in the **Profile Discovery** method. A network profile defines the network, NIC, and routes for a node. If the “__NetworkProfile_netprofile” group already exists in the nodehm table, then “netprofile” is used as the network profile name.

- **hardwareprofile=hardware-profile**
  
  Sets the new hardware profile name used by the discovered nodes in the **Profile Discovery** method. If a “__HardwareProfile_hwprofile” group exists, then “hwprofile” is the hardware profile name. A hardware profile defines hardware management related information for imported nodes, including: IPMI, HMC, CEC, CMM.

- **hostnameformat=nost-name-format**
  
  Sets the node name format for all discovered nodes in the **Profile Discovery** method. The two types of formats supported are prefix#NNNappendix and prefix#RRand#NNappendix, where wildcard #NNN and #NN are replaced by a system generated number that is based on the provisioning order. Wildcard #RR represents the rack number and stays constant.

  For example, if the node name format is compute-#NN, the node name is generated as: compute-00, compute-01, …, compute-99. If the node name format is blade#NNN-x64, the node name is generated as: blade001-x64, blade002-x64, …, blade999-x64

  For example, if the node name format is compute-#RR-#NN and the rack number is 2, the node name is generated as: compute-02-00, compute-02-01, …, compute-02-99. If node name format is node-#NN-in-#RR and rack number is 1, the node name is generated as: node-00-in-01, node-01-in-01, …, node-99-in-01
**groups=node-groups**

Sets the node groups that the discovered nodes should be put in for either the Sequential Discovery or Profile Discovery methods, where *node-group* is a comma-separated list of node groups.

**rack=rack-name**

Sets the rack name where the node is located for either the Sequential Discovery or Profile Discovery methods.

**chassis=chassis-name**

Sets the chassis name that the Blade server or PureFlex blade is located in, for either the Sequential Discovery or Profile Discovery methods. This option is used for the Blade server and PureFlex system only. You cannot specify this option with the rack option.

**height=rack-server-height**

Sets the height of a rack-mounted server in U units for either the Sequential Discovery or Profile Discovery methods. If the rack option is not specified, the default value is 1.

**unit=rack-server-unit-location**

Sets the start unit value for the node in the rack, for either the Sequential Discovery or Profile Discovery methods. This option is for a rack server only. If the unit option is not specified, the default value is 1.

**rank=rank-num**

Specifies the starting rack number that is used in the node name format, for the Profile Discovery method. The rank number must be a valid integer between 0 and 254. This option must be specified with node-nameformat option. For example, if your node name format is compute-#RR-#NN. The rack’s number is 2 and rank is specified as 5, the node name is generated as follows: compute-02-05, compute-02-06, . . . , compute-02-99.

**osimage=osimagename**

Specifies the osimage name that will be associated with the new discovered node, the os provisioning will be started automatically at the end of the discovery process.

**-n|--dns**

Specifies to run makedns <nodename> for any new discovered node. This is useful mainly for non-predefined configuration, before running the “nodediscoverstart -n”, the user needs to run makedns -n to initialize the named setup on the management node.

**-sl|--skipbmcsetup**

Specifies to skip the bmcsetup during the sequential discovery process, if the bmciprange is specified with nodediscoverstart command, the BMC will be setup automatically during the discovery process, if the user does not want to run bmcsetup, could specify the “-sl--skipbmcsetup” with nodediscoverstart command to skip the bmcsetup.

**-V|--verbose**

Enumerates the free node names and host/bmc ips that are being specified in the ranges given. Use this option with Sequential Discovery to ensure that you are specifying the ranges you intend.

**-hl|--help**

Display usage message.

**-vl|--version**

Command Version.
RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. **Sequential Discovery**: To discover nodes with noderange and host/bmc ip range:

   ```
   nodediscoverstart noderange=n[1-10] hostiprange='172.20.101.1-172.20.101.10'
   → bmciprange='172.20.102.1-172.20.102.10' -V
   ```

   Output is similar to:

   ```
   Sequential Discovery: Started:
   Number of free node names: 10
   Number of free host ips: 10
   Number of free bmc ips: 10
   ---------------------------------------Free Nodes---------------------------------------
   NODE HOST IP     BMC IP
   n01 172.20.101.1 172.20.102.1
   n02 172.20.101.2 172.20.102.2
   ...
   ...
   ```

2. **Profile Discovery**: To discover nodes using the default_cn network profile and the rhels6.3_packaged image profile, use the following command:

   ```
   nodediscoverstart networkprofile=default_cn imageprofile=rhels6.3_packaged
   → hostnameformat=compute#NNNN
   ```

SEE ALSO

nodediscoverstop.1, nodediscoverstatus.1, nodediscoverstatus(1)
OPTIONS

-\(h\)--help
Display usage message.

-\(v\)--version
Command Version.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

To determine if there are some nodes discovered and the discovered nodes’ status, enter the following command:

\texttt{nodediscoverstatus}

SEE ALSO

nodediscoverstart(1) nodediscoverstart.1, nodediscoverls(1) nodediscoverls.1, nodediscoverstatus(1) nodediscoverstatus.1

\texttt{nodediscoverstop.1}

NAME

\texttt{nodediscoverstop} - stops the node discovery process.

SYNOPSIS

\texttt{nodediscoverstop [-h | --help | -v | --version]}

DESCRIPTION

The \texttt{nodediscoverstop} command stops the sequential or profile node discovery process. Once this command has been run, newly discovered nodes will not be assigned node names and attributes automatically via the sequential or profile discovery process.
OPTIONS

-\(h\)--help
Display usage message.

-\(v\)--version
Command Version.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

nodediscoversstop

SEE ALSO

nodegrpch.1

NAME

nodegrpch - Changes attributes at the group level in the xCAT cluster database.

SYNOPSIS

nodegrpch group1,group2,... table.column=value [...]
nodegrpch [-v | --version]
nodegrpch [-? | -h | --help]

DESCRIPTION

The nodegrpch command is similar to the nodech command, but ensures that the parameters are declared at the group level rather than the node specific level, and clears conflicting node specific overrides of the specified groups. Using table.column=value will do a verbatim assignment. If “,”=“” is used instead of “=“”, the specified value will be prepended to the attribute’s comma separated list, if it is not already there. If “^=“” is used, the specified value will be removed from the attribute’s comma separated list, if it is there. You can also use “^=“” and “.=“” in the same command to essentially replace one item in the list with another. (See the Examples section.)

With these operators in mind, the unambiguous assignment operator is ‘=’@’. If you need, for example, to set the nodehm.comments to =foo, you would have to do nodegrpch group1 nodehm.comments= foo.
See the xcatdb man page for an overview of each table.
The nodegrpch command also supports some short cut names as aliases to common attributes. See the nodels man page for details.

OPTIONS

-\(v\)--version
    Command Version.
-\(?\|--h|--help
    Display usage message.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To declare all members of ipmi group to have nodehm.mgt be ipmi

   nodegrpch ipmi nodehm.mgt=ipmi

FILES

/opt/xcat/bin/nodegrpch

SEE ALSO

nodech(1)|nodech.1, nodels(1)|nodels.1, nodeadd(8)|nodeadd.8, noderange(3)|noderange.3

nodeimport.1

NAME

nodeimport - Create profiled nodes by importing hostinfo file.

SYNOPSIS

nodeimport  [-h | --help | -v | --version]

    nodeimport file= hostinfo-filename networkprofile= network-profile imageprofile= image-profile hostnameformat= node-name-format [hardwareprofile= hardware-profile] [groups= node-groups]
DESCRIPTION

The `nodeimport` command creates nodes by importing a hostinfo file which is following stanza format. In this hostinfo file, we can define node’s hostname, ip, mac, switch name, switch port and host location information like rack, chassis, start unit, server height etc.

After nodes imported, the configuration files related with these nodes will be updated automatically. For example: /etc/hosts, dns configuration, dhcp configuration. And the kits node plugins will also be triggered automatically to update kit related configuration/services.

OPTIONS

`-h|--help`
Display usage message.

`-v|--version`
Command Version.

`file=nodeinfo-filename`
Specifies the node information file, where `<nodeinfo-filename>` is the full path and file name of the node information file.

`imageprofile=image-profile`
Sets the new image profile name used by the node, where `<image-profile>` is the new image profile. An image profile defines the provisioning method, OS information, kit information, and provisioning parameters for a node. If the “__ImageProfile_imgprofile” group already exists in the nodehm table, then “imgprofile” is used as the image profile name.

`networkprofile=network-profile`
Sets the new network profile name used by the node, where `<network-profile>` is the new network profile. A network profile defines the network, NIC, and routes for a node. If the “__NetworkProfile_netprofile” group already exists in the nodehm table, then “netprofile” is used as the network profile name.

`hardwareprofile=hardware-profile`
Sets the new hardware profile name used by the node, where `<hardware-profile>` is the new hardware management profile used by the node. If a “__HardwareProfile_hwprofile” group exists, then “hwprofile” is the hardware profile name. A hardware profile defines hardware management related information for imported nodes, including: IPMI, HMC, CEC, CMM.

`hostnameformat=host-name-format`
Sets the node name format for all nodes discovered, where `<node-name-format>` is a supported format. The two types of formats supported are prefix#NNNappendix and prefix#RRand#NNappendix, where wildcard #NNN and #NN are replaced by a system generated number that is based on the provisioning order. Wildcard #RR represents the rack number and stays constant.

For example, if the node name format is compute-#NN, the node name is generated as: compute-00, compute-01, ... , compute-99. If the node name format is blade#NNN-x64, the node name is generated as: blade001-x64, blade002-x64, ... , blade999-x64

For example, if the node name format is compute-#RR-#NN and the rack number is 2, the node name is generated as: compute-02-00, compute-02-01, ... , compute-02-99. If node name format is node-#NN-in-#RR and rack number is 1, the node name is generated as: node-00-in-01, node-01-in-01, ... , node-99-in-01

`groups=node-groups`
Sets the node groups that the imported node belongs to, where <node-group> is a comma-separated list of node groups.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred while validating parameters.
2 An error has occurred while parsing hostinfo file.

**EXAMPLES**

To import nodes using a profile, follow the following steps:

1. Find all node groups and profiles, run the following command “tabdump nodegroups”. For detailed profile information run “lsdef -t group <groupname>”. Example of detailed profile information:

   ```
   # tabdump nodegroup
   # groupname, grouptype, members, membergroups, wherevals, comments, disable
   "compute","static","","","","
   "__HardwareProfile_default_ipmi","static","static","","","
   "__NetworkProfile_default_mn","static","static","","","
   "__NetworkProfile_default_cn","static","","","
   "__ImageProfile_rhels6.2-x86_64-install-compute","static","static","",""
   
   # lsdef -t group __NetworkProfile_default_cn
   Object name: __NetworkProfile_default_cn
   grouptype=static
   installnic=eth0
   members=compute-000,compute-001
   netboot=xnba
   nictypes=eth0:Ethernet
   primarynic=eth0
   
   # lsdef -t group __NetworkProfile_default_mn
   Object name: __NetworkProfile_default_mn
   grouptype=static
   installnic=eth0
   members=compute-000
   netboot=xnba
   nictypes=eth0:Ethernet
   primarynic=eth0
   
   # lsdef -t group __NetworkProfile_default_cn
   Object name: __NetworkProfile_default_cn
   grouptype=static
   installnic=eth0
   members=compute-000,compute-001
   netboot=xnba
   nictypes=eth0:Ethernet
   primarynic=eth0
   
   # lsdef -t group __NetworkProfile_default_mn
   Object name: __NetworkProfile_default_mn
   grouptype=static
   installnic=eth0
   members=compute-000
   netboot=xnba
   nictypes=eth0:Ethernet
   primarynic=eth0
   
   # lsdef -t group __NetworkProfile_default_cn
   Object name: __NetworkProfile_default_cn
   grouptype=static
   installnic=eth0
   members=compute-000,compute-001
   netboot=xnba
   nictypes=eth0:Ethernet
   primarynic=eth0
   
   # lsdef -t group __NetworkProfile_default_mn
   Object name: __NetworkProfile_default_mn
   grouptype=static
   installnic=eth0
   members=compute-000
   netboot=xnba
   nictypes=eth0:Ethernet
   primarynic=eth0
   
   # lsdef -t group __NetworkProfile_default_cn
   Object name: __NetworkProfile_default_cn
   grouptype=static
   installnic=eth0
   members=compute-000,compute-001
   netboot=xnba
   nictypes=eth0:Ethernet
   primarynic=eth0
   
   # lsdef -t group __NetworkProfile_default_mn
   Object name: __NetworkProfile_default_mn
   grouptype=static
   installnic=eth0
   members=compute-000
   netboot=xnba
   nictypes=eth0:Ethernet
   primarynic=eth0
   ```

2. Prepare a node information file.

Example of a node information file, a blade and a rack server defined:

```
# hostinfo begin
# This entry defines a blade.
__hostname__:
    mac=b8:ac:6f:37:59:24
    ip=192.168.1.20
    chassis=chassis01

# This entry defines a rack server.
__hostname__:
    mac=b8:ac:6f:37:59:25
    ip=192.168.1.20
    rack=rack01
    height=1
    unit=2

# hostinfo end.
```

(continues on next page)
Another example of a node information file, a PureFlex X/P node defined:

```
# hostinfo begin
# To define a PureFlex P/X node, chassis and slot id must be specified.
# The chassis must be a PureFlex chassis.
__hostname__:
  mac=b8:ac:6f:37:59:25
  chassis=cmm01
  slotid=1
# hostinfo end.
```

Example of a node information file, a switch auto discovery node defined:

```
# hostinfo begin
# This entry defines a blade.
__hostname__:
  switches=eth0!switch1!1,eth0!switch2!1!eth1
```

Example of a node information file that specifies a CEC-based rack-mounted Power node that uses direct FSP management:

```
# Node information file begins
# This entry defines a Power rack-mount node.
__hostname__:
  mac=b8:ac:6f:37:59:28
  cec=mycec
__hostname__:
  mac=b8:ac:6f:37:59:28
  cec=mycec
  lparid=2
# Node information file ends.
```

Example of a node information file that specifies a PowerKVM Guest node that uses KVM management:

```
# Node information file begins
# This entry defines a PowerKVM Guest node.
# Make sure the node 'vm01' is already created on Hypervisor
vm01:
  mac=b8:ef:3f:28:31:15
  vmhost=pkvm1
# Node information file ends.
```

The node information file includes the following items:

**__hostname__**: This is a mandatory item.

Description: The name of the node, where __hostname__ is automatically generated by the node name format. You can also input a fixed node name, for example “compute-node”.

**mac=<mac-address>** This is a mandatory item.

Description: Specify the MAC address for the NIC used by the provisioning node, where <mac-address> is the NICs MAC address.

**switches=<nic-name!switch-name!switch-port>** This is a mandatory item, when define switch, switchport and node nic name relationship.

Description: Specify nic name, switch name and switch port to define node and switch relationship. We can define multi nic-switch-port relations here, looks like: switches=eth0!switch1!1,eth1!switch1.2
slotid=<slot-id> This is a mandatory item while define a PureFlex node.
Description: The node position in the PureFlex Chassis.

cec=<cec-name> This is a mandatory option for defining Power rack-mounted nodes.
Description: Specifies the name of a Power rack-mount central electronic complex (CEC).

lpard=<lpard-id> This is a optional option for defining Power rack-mounted nodes.
Description: Specifies the LPAR ID of a Power rack-mounted node, where <lpard-id> is the ID number. The default value is 1 if it is not defined.

ip=<ip-address> This is an optional item.
Description: Specify the IP address used for provisioning a node, where <ip-address> is in the form xxx.xxx.xxx.xxx. If this item is not included, the IP address used to provision the node is generated automatically according to the Network Profile used by the node.

nicips=<nics-ip> This is an optional item.
Description: Lists the IP address for each network interface configuration (NIC) used by the node, excluding the provisioning network, where <nics-ip> is in the form <nic1>!<nic-ip1>,<nic2>!<nic-ip2>,.... For example, if you have 2 network interfaces configured, the nicips attribute should list both network interfaces: nicips=eth1!10.10.10.11,bmc!192.168.10.3. If the nicips attribute is not specified, the IP addresses are generated automatically according to the network profile.

rack=<rack-name> This is an optional item.
Description: node location info. Specify the rack name which this node will be placed into. If not specify this item, there will be no node location info set for this node. this item must be specified together with height + unit.

chassis=<chassis-name> This is an optional item.
Description: node location info, for blade(or PureFlex) only. Specify the chassis name which this blade will be placed into. this item can not be specified together with rack.

height=<chassis-height> This is an optional item.
Description: node location info, for rack server only. Specify the server height number, in U. this item must be specified together with rack and unit.

unit=<rack-server-unit-location> This is an optional item.
Description: node location info, for rack server only. Specify the node’s start unit number in rack, in U. this item must be specified together with rack and height.

vmhost=<PowerKVM Hypervisor Host Name> This is a mandatory option for defining PowerKVM Guest nodes.
Description: Specifies the vmhost of a Power KVM Guest node, where <vmhost> is the host name of PowerKVM Hypervisor.

3. Import the nodes, by using the following commands. Note: If we want to import PureFlex X/P nodes, hardware profile must be set to a PureFlex hardware type.

```
nodeimport file=/root/hostinfo.txt networkprofile=default_cn imageprofile=rhels6.3_
→packaged hostnameformat=compute-#NNN
```

4. After importing the nodes, the nodes are created and all configuration files used by the nodes are updated, including: /etc/hosts, DNS, DHCP.

5. Reboot the nodes. After the nodes are booted they are provisioned automatically.
SEE ALSO
nodepurge(1) nodepurge.1, nodechprofile(1) nodechprofile.1, noderefresh(1) noderefresh.1

nodels.1

NAME

nodels - lists the nodes, and their attributes, from the xCAT database.

SYNOPSIS

nodels [noderange] [-b | --blame] [-H | --with-fieldname] [-S | [table.column | shortname] [ ... ]
nodels [noderange] [-H | --with-fieldname] [table]
nodels [-? | --help | -v | --version]

DESCRIPTION

The nodels command lists the nodes specified in the node range. If no noderange is provided, then all nodes are listed. Additional attributes of the nodes will also be displayed if the table names and attribute names are specified after the noderange in the form: table.column. A few shortcut names can also be used as aliases to common attributes:

groups
   nodelist.groups

tags
   nodelist.groups

mgt
   nodehm.mgt

nodels can also select based on table value criteria. The following operators are available:

==
   Select nodes where the table.column value is exactly a certain value.

!=
   Select nodes where the table.column value is not a given specific value.

=~
   Select nodes where the table.column value matches a given regular expression.

!~
   Select nodes where the table.column value does not match a given regular expression.

The nodels command with a specific node and one or more table.attribute parameters is a good substitute for grep’ing through the tab files, as was typically done in xCAT 1.x. This is because nodels will translate any regular expression rows in the tables into their meaning for the specified node. The tab* commands will not do this, instead they will just display the regular expression row verbatim.
OPTIONS

-\vl--version
    Command Version.

-\Hl--with-fieldname
    Force display of table name and column name context for each result

-bl--blame
    For values inherited from groups, display which groups provided the inheritance

-S
    List all the hidden nodes (FSP/BPA nodes) with other ones.

-?!-hl--help
    Display usage message.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To list all defined nodes, enter:

   \begin{verbatim}
   nodels
   \end{verbatim}

   Output is similar to:

   \begin{verbatim}
   node1
   node2
   node3
   \end{verbatim}

2. To list all defined attributes in a table for a node or noderange, enter:

   \begin{verbatim}
   nodels rra001a noderes
   \end{verbatim}

   Output is similar to:

   \begin{verbatim}
   rra001a: noderes.primarynic: eth0
   rra001a: noderes.xcatmaster: rra000
   rra001a: noderes.installnic: eth0
   rra001a: noderes.netboot: pxe
   rra001a: noderes.servicenode: rra000
   rra001a: noderes.node: rra001a
   \end{verbatim}

3. To list nodes in node group ppc, enter:

   \begin{verbatim}
   nodels ppc
   \end{verbatim}

   Output is similar to:
4. To list the groups each node is part of:

```
nodels all groups
```

Output is similar to:

```
node1: groups: all
node2: groups: all, storage
node3: groups: all, blade
```

5. To list the groups each node is part of:

```
nodels all nodehm.power
```

Output is similar to:

```
node1: nodehm.power: blade
node2: nodehm.power: ipmi
node3: nodehm.power: ipmi
```

6. To list the out-of-band mgt method for blade1:

```
nodels blade1 nodehm.mgt
```

Output is similar to:

```
blade1: blade
```

7. Listing blades managed through an AMM named ‘amm1’

```
nodels all mp.mpa==amm1
```

Output is similar to:

```
blade1
blade10
blade11
blade12
blade13
blade2
blade3
blade4
blade5
blade6
blade7
blade8
blade9
```

8. Listing the switch.switch value for nodes in the second rack:

```
nodels all nodepos.rack==2 switch.switch
```

Output is similar to:
9. Listing the blade slot number for anything managed through a device with a name beginning with amm:

   nodels all mp.mpa=~/^amm.*/ mp.id

   Output looks like:
   
   blade1: mp.id: 1
   blade10: mp.id: 10
   blade11: mp.id: 11
   blade12: mp.id: 12
   blade13: mp.id: 13
   blade2: mp.id: 2
   blade3: mp.id: 3
   blade4: mp.id: 4
   blade5: mp.id: 5
   blade6: mp.id: 6
   blade7: mp.id: 7
   blade8: mp.id: 8
   blade9: mp.id: 9

10. To list the hidden nodes that can’t be seen with other flags. The hidden nodes are FSP/BPAs.

   lsdef -S

FILES

/opt/xcat/bin/nodels

SEE ALSO

noderange(3)noderange.3, tabdump(8)tabdump.8, lsdef(1)lsdef.1

depurge.1

NAME

nodepurge - Removes nodes.
SYNOPSIS

nodepurge [-h|--help | -v|--version]
nodepurge noderange

DESCRIPTION

The nodepurge automatically removes all nodes from the database and any related configurations used by the node. After the nodes are removed, the configuration files related to these nodes are automatically updated, including the following files: /etc/hosts, DNS, DHCP. Any kits that are used by the nodes are triggered to automatically update kit configuration and services.

OPTIONS

-hl|--help
Display usage message.

-vl|--version
Command Version

noderange
The nodes to be removed.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

To remove nodes compute-000 and compute-001, use the following command:

nodepurge compute-000,compute-001

SEE ALSO

nodeimport(1)|nodeimport.1, nodechprofile(1)|nodechprofile.1, noderefresh(1)|noderefresh.1, noderange(3)|noderange.3

noderefresh.1

NAME

noderefresh - Update nodes configurations by running associated kit plugins.
SYNOPSIS

noderefresh [-h|--help] [-v|--version]
noderefresh noderange

DESCRIPTION

The noderefresh command will update nodes settings, it will call all associated kit plug-in configurations and also services

OPTIONS

- hl|--help
Display usage message.
- v|--version
Command Version.
noderange
The nodes to be updated.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

noderefresh compute-000,compute-001

SEE ALSO

nodeimport(1)|nodeimport.1, nodechprofile(1)|nodechprofile.1, nodepurge(1)|nodepurge.1, noderange(3)|noderange.3

noderm.1

NAME

noderm -Removes the nodes in the noderange from all database table.

SYNOPSIS

noderm [-hl|--help]
noderm noderange
DESCRIPTION

The noderm command removes the nodes in the input node range.

OPTIONS

-\h|--help Display usage message.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To remove the nodes in noderange node1-node4, enter:

   noderm node1-node4

FILES

/opt/xcat/bin/noderm

SEE ALSO

nodels(1)|nodels.1, nodeadd(8)|nodeadd.8, noderange(3)|noderange.3

code:stat.1

Name

nodestat - display the running status of each node in a noderange

Synopsis

nodestat [-h | --help] [-v | --version]

Description

nodestat displays and optionally updates the database the running status of a single or range of nodes or groups. See
noderange(3)|noderange.3.

By default, it works as following:
1. gets the sshd, pbs_mom, xend port status;
2. if none of them are open, it gets the fping status;
3. for pingable nodes that are in the middle of deployment, it gets the deployment status;
4. for non-pingable nodes, it shows ‘noping’.

When -m is specified and there are settings in the monsetting table, it displays the status of the applications specified in the monsetting table. When -p is specified it shows the power status for the nodes that are not pingable. When -u is specified it saves the status info into the xCAT database. Node’s pingable status and deployment status is saved in the nodelist.status column. Node’s application status is saved in the nodelist.appstatus column.

To specify settings in the monsetting table, use ‘xcatmon’ as the name, ‘apps’ as the key and the value will be a list of comma separated list of application names. For each application, you can specify the port number that can be queried on the nodes to get the running status. Or you can specify a command that can be called to get the node status from. The command can be a command that can be run locally at the management node or the service node for hierarchical cluster, or a command that can be run remotely on the nodes.

The following is an example of the settings in the monsetting table:

<table>
<thead>
<tr>
<th>Name</th>
<th>Key</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>xcatmon</td>
<td>apps</td>
<td>ssh, ll, gpfs, someapp</td>
</tr>
<tr>
<td>xcatmon</td>
<td>gpfs</td>
<td>cmd=/tmp/mycmd, group=compute, group=service</td>
</tr>
<tr>
<td>xcarmon</td>
<td>ll</td>
<td>port=9616, group=compute</td>
</tr>
<tr>
<td>xcatmon</td>
<td>someapp</td>
<td>dcmd=/tmp/somecmd</td>
</tr>
</tbody>
</table>

Keywords to use:

- apps -- a list of comma separated application names whose status will be queried. For how to get the status of each app, look for app name in the key field in a different row.
- port -- the application daemon port number, if not specified, use internal list, then /etc/services.
- group -- the name of a node group that needs to get the application status from. If not specified, assume all the nodes in the nodelist table. To specify more than one groups, use group=a,group=b format.
- cmd -- the command that will be run locally on mn or sn.
- lcmd -- the command that will be run the mn only.
- dcmd -- the command that will be run distributed on the nodes using xdsh <nodes> ....

For commands specified by ‘cmd’ and ‘lcmd’, the input of is a list of comma separated node names, the output must be in the following format:

```
node1:string1
node2:string2
...
```

For the command specified by ‘dcmd’, no input is needed, the output can be a string.

Options

- `-f` | `--usefping`
  
  Uses fping instead of nmap even if nmap is available. If you seem to be having a problem with false negatives, fping can be more forgiving, but slower.

- `-m` | `--usemon`
  
  Uses the settings from the monsetting table to determine a list of applications that need to get status for.
-p | --powerstat

Gets the power status for the nodes that are ‘noping’.

-u | --updatedb

Updates the status and appstatus columns of the nodelist table with the returned running status from the given nodes.

-v | --version

Print version.

-h | --help

Print help.

Examples

1. `nodestat compute`

Output is similar to:

```
node1  sshd
node2  sshd
node3  ping
node4  pbs
node5  noping
```

2. `nodestat compute -p`

Output is similar to:

```
node1  sshd
node2  sshd
node3  ping
node4  pbs
node5  noping (Shutting down)
```

3. `nodestat compute -u`

Output is similar to:

```
node1  sshd
node2  sshd
node3  ping
node4  netboot
node5  noping
```

4. `nodestat compute -m`

Output is similar to:

```
node1  ping,sshd,ll,gpfs=ok
node2  ping,sshd,ll,gpfs=not ok,someapp=something is wrong
node3  netboot
node4  noping
```
packimage.1

NAME

packimage - Packs the stateless image from the chroot file system.

SYNOPSIS

packimage [-h|--help]
packimage [-v|--version]
packimage [-m|--method cpio|tar] [-c|--compress gzip|pigz|xz] [--nosyncfiles] imagename

DESCRIPTION

Packs the stateless image from the chroot file system into a file to be sent to the node for a diskless boot.

Note: For an osimage that is deployed on a cluster, running packimage will overwrite the existing rootimage file and be unavailable to the compute nodes while packimage is running.

PARAMETERS

imagename specifies the name of a OS image definition to be used. The specification for the image is stored in the osimage table and linuximage table.

OPTIONS

-h Display usage message.
-v Command Version.
-m|--method Archive Method (cpio,tar,squashfs, default is cpio)
-c|--compress Compress Method (pigz,gzip,xz, default is pigz/gzip)
--nosyncfiles Bypass of syncfiles requested, will not sync files to root image directory

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.
**EXAMPLES**

1. To pack the osimage ‘rhels7.1-x86_64-netboot-compute’:

   ```bash
   packimage rhels7.1-x86_64-netboot-compute
   ```

2. To pack the osimage ‘rhels7.1-x86_64-netboot-compute’ with “tar” to archive and “pigz” to compress:

   ```bash
   packimage -m tar -c pigz rhels7.1-x86_64-netboot-compute
   ```

3. To pack the osimage ‘rhels7.1-x86_64-netboot-compute’ without syncing files:

   ```bash
   packimage --nosyncfiles rhels7.1-x86_64-netboot-compute
   ```

**FILES**

```
/opt/xcat/sbin/packimage
```

**NOTES**

This command is part of the xCAT software product.

**SEE ALSO**

`genimage(1)`

**NAME**

`pasu` - run the ASU to many nodes in parallel

**SYNOPSIS**

```bash
pasu [-h | --help]
```

**DESCRIPTION**

The `pasu` command runs the ASU command in out-of-band mode in parallel to multiple nodes. Out-of-band mode means that ASU connects from the xCAT management node to the IMM (BMC) of each node to set or query the ASU settings. To see all of the ASU settings available on the node, use the “show all” command. To query or set multiple values, use the `-b` (batch) option. To group similar output from multiple nodes, use `xcoll(1)`.

Before running `pasu`, you must install the ASU RPM from IBM. You can download it from the IBM Fix Central site. You also must configure the IMMs properly according to xCAT documentation. Run “`rpower noderange stat`” to confirm that the IMMs are configured properly.
OPTIONS

-ll--loginname username
   The username to use to connect to the IMMs. If not specified, the row in the xCAT passwd table with key "ipmi" will be used to get the username.

-pl--passwd passwd
   The password to use to connect to the IMMs. If not specified, the row in the xCAT passwd table with key "ipmi" will be used to get the password.

-fl--fanout
   How many processes to run in parallel simultaneously. The default is 64. You can also set the XCAT-PHFNOUT environment variable.

-bl--batch -batchfile
   A simple text file that contains multiple ASU commands, each on its own line.

-dl--donotfilter
   By default, pasu filters out (i.e. does not display) the standard initial output from ASU:

```
IBM Advanced Settings Utility version 9.30.79N
Licensed Materials - Property of IBM
(C) Copyright IBM Corp. 2007-2012 All Rights Reserved
Connected to IMM at IP address node2-imm
```

If you want this output to be displayed, use this flag.

-il--interface hostname-suffix
   The hostname suffix to be appended to the node names.

-Vl--verbose
   Display verbose messages.

-hl--help
   Display usage message.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To display the Com1ActiveAfterBoot setting on 2 nodes:
   ```
   pasu node1,node2 show DevicesandIOPorts.Com1ActiveAfterBoot
   ```

   Output is similar to:
   ```
   node1: DevicesandIOPorts.Com1ActiveAfterBoot=Enable
   node2: DevicesandIOPorts.Com1ActiveAfterBoot=Enable
   ```
2. To display the Com1ActiveAfterBoot setting on all compute nodes:

```
pasu compute show DevicesandIOPorts.Com1ActiveAfterBoot | xcoll
```

Output is similar to:

```
====================================
compute
====================================
DevicesandIOPorts.Com1ActiveAfterBoot=Enable
```

3. To set several settings on all compute nodes, create a batch file called (for example) asu-settings with contents:

```
set DevicesandIOPorts.Com1ActiveAfterBoot Enable
set DevicesandIOPorts.SerialPortSharing Enable
set DevicesandIOPorts.SerialPortAccessMode Dedicated
set DevicesandIOPorts.RemoteConsole Enable
```

Then run:

```
pasu -b asu-settings compute | xcoll
```

Output is similar to:

```
====================================
compute
====================================
Batch mode start.
[set DevicesandIOPorts.Com1ActiveAfterBoot Enable]
DevicesandIOPorts.Com1ActiveAfterBoot=Enable

[set DevicesandIOPorts.SerialPortSharing Enable]
DevicesandIOPorts.SerialPortSharing=Enable

[set DevicesandIOPorts.SerialPortAccessMode Dedicated]
DevicesandIOPorts.SerialPortAccessMode=Dedicated

[set DevicesandIOPorts.RemoteConsole Enable]
DevicesandIOPorts.RemoteConsole=Enable

Beginning intermediate batch update.
Waiting for command completion status.
Command completed successfully.
Completed intermediate batch update.
Batch mode competed successfully.
```

4. To confirm that all the settings were made on all compute nodes, create a batch file called (for example) asu-show with contents:

```
show DevicesandIOPorts.Com1ActiveAfterBoot
show DevicesandIOPorts.SerialPortSharing
show DevicesandIOPorts.SerialPortAccessMode
show DevicesandIOPorts.RemoteConsole
```

Then run:

```
pasu -b asu-show compute | xcoll
```

Output is similar to:
BEGIN
# compute

Batch mode start.
[show DevicesandIOPorts.Com1ActiveAfterBoot]
DevicesandIOPorts.Com1ActiveAfterBoot=Enable

[show DevicesandIOPorts.SerialPortSharing]
DevicesandIOPorts.SerialPortSharing=Enable

[show DevicesandIOPorts.SerialPortAccessMode]
DevicesandIOPorts.SerialPortAccessMode=Dedicated

[show DevicesandIOPorts.RemoteConsole]
DevicesandIOPorts.RemoteConsole=Enable

Batch mode competed successfully.

FILES

/opt/xcat/bin/pasu

SEE ALSO

noderange(3)noderange.3, rpower(1)rpower.1, xcoll(1)xcoll.1

pcons.1

SYNOPSIS

pcons noderange command
pcons[-h|--help]
pcons[-v|--version]

DESCRIPTION

Runs the a command to the noderange using the console.

EXAMPLES

pcons 1,3 stat
pcons all,-129-256 stat

SEE ALSO

psh(1)psh.1
NAME

pgsqlsetup - Sets up the PostgreSQL database for xCAT to use.

SYNOPSIS

pgsqlsetup {-h | --help}
pgsqlsetup {-v | --version}
pgsqlsetup [-o | --setupODBC] [-V | --verbose]

DESCRIPTION

pgsqlsetup - Sets up the PostgreSQL database for xCAT to use. The pgsqlsetup script is run on the Management Node as root after the PostgreSQL code has been installed. The xcatd daemon will be stopped during migration. No xCAT commands should be run during the init process, because we will be migrating the xCAT database to PostgreSQL and restarting the xcatd daemon as well as the PostgreSQL daemon. For full information on all the steps that will be done reference One password must be supplied for the setup, a password for the xcatadm unix id and the same password for the xcatadm database id. The password will be prompted for interactively or you can set the XCATPGPW environment variable to the password and then there will be no prompt.

OPTIONS

-h|--help
Displays the usage message.

-v|--version
Displays the release version of the code.

-V|--verbose
Displays verbose messages.

-i|--init
The init option is used to setup an installed PostgreSQL database so that xCAT can use the database. This involves creating the xcat database, the xcat admin id, allowing access to the xcatdb database by the Management Node. It customizes the postgresql.conf configuration file, adds the management server to the pg_hba.conf and starts the PostgreSQL server. It also backs up the current xCAT database and restores it into the newly setup xcatdb PostgreSQL database. It creates the /etc/xcat/cfgloc file to point the xcatd daemon to the PostgreSQL database and restarts the xcatd daemon using the database. On AIX, it additionally setup the xcatadm unix id and the postgres id and group. For AIX, you should be using the PostgreSQL rpms available from the xCAT website. For Linux, you should use the PostgreSQL rpms shipped with the OS. You can chose the -o option, to run after the init. To add additional nodes to access the PostgreSQL server, setup on the Management Node, use the -a option.

For more documentation see: Setting_Up_PostgreSQL_as_the_xCAT_DB
-Ni--nostart

This option with the -i flag will create the database, but will not backup and restore xCAT tables into the
database. It will create the cfgloc file such that the next start of xcatd will try and contact the database.
This can be used to setup the xCAT PostgreSQL database during or before install.

-ll--listen address

This option is used to specify additional IP addresses on which the PostgreSQL database will listen.
Without it, only localhost (on Linux) and the management node’s main IP (on Linux and AIX) will be
configured. This option can be specified multiple times.

-al--access address

This option is used to specify additional IP addresses from which the additional nodes will connect to
the PostgreSQL database, for example, service nodes IP addresses or MN HA primary/standby nodes
physical IP addresses. Without it, only the management node will be configured for database access. This
option can be specified multiple times.

-Pl--PCM

This option sets up PostgreSQL database to be used with xCAT running with PCM.

-ol--odbc

This option sets up the ODBC /etc/odbcinst.ini, /etc/odbc.ini and the .odbc.ini file in roots home
directory will be created and initialized to run off the xcatdb PostgreSQL database.

ENVIRONMENT VARIABLES

XCATPGPW

The password to be used to setup the xCAT admin id for the database.

EXAMPLES

1. To setup PostgreSQL for xCAT to run on the PostgreSQL xcatdb database:

   psqlsetup -i

2. To setup the ODBC for PostgreSQL xcatdb database access:

   psqlsetup -o

piflash.1

SYNOPSIS

piflash noderange -****-package filename

DESCRIPTION

piflash Remotely applies firmware updates to servers.
**SYNOPSIS**

`pping [-i | --interface interfaces] [-f | --use_fping] noderange`

`pping [-h | --help]`

`pping [-v | --version]`

**DESCRIPTION**

`pping` is a utility used to ping a list of nodes in parallel. `pping` will return an unsorted list of nodes with a ping or noping status. `pping` front-ends `nmap` or `fping` if available.

This command does not support the xcatd client/server communication. It must be run on the management node.

**OPTIONS**

-`i | --interface interfaces`
  
  A comma separated list of network interface names that should be pinged instead of the interface represented by the nodename/hostname. The following name resolution convention is assumed: an interface is reachable by the hostname `<nodename>-<interface>`. For example, the ib2 interface on node3 has a hostname of node3-ib2.

  If more than one interface is specified, each interface will be combined with the nodenames as described above and will be pinged in turn.

-`f | --use_fping`
  
  Use `fping` instead of `nmap`

-`h | --help`
  
  Show usage information.

-`v | --version`
  
  Display the installed version of xCAT.

**EXAMPLES**

1. `pping all`

   Output is similar to:

   ```
   node1: ping
   node2: ping
   node3: noping
   ```

2. `pping all -i ib0,ib1`

   Output is similar to:
SEE ALSO

psh(1)|psh.1, noderange(3)|noderange.3

SYNOPSIS


DESCRIPTION

ppping is a utility used to test the connectivity between nodes in the noderange using ping. By default, pppping will return an unsorted list of the node pairs that are not able to ping each other, or a message that all nodes are pingable. More or less output can be controlled by the -V and -q options. pppping front-ends pping and xdsh.

OPTIONS

-s
   Ping serially instead of in parallel.

-i | --interface interfaces
   A comma separated list of network interface names that should be pinged instead of the interface represented by the nodename/hostname. The following name resolution convention is assumed: an interface is reachable by the hostname <nodename>-<interface>. For example, the ib2 interface on node3 has a hostname of node3-ib2.
   If more than one interface is specified, each interface will be combined with the nodenames as described above and will be pinged in turn.

-V | --verbose
   Display verbose output. The result of every ping attempt from every node will be displayed. Without this option, just a summary of the successful pings are displayed, along with all of the unsuccessful pings.

-q | --quiet
   Display minimum output: just the unsuccessful pings. This option has the effect that if all pings are successful, nothing is displayed. But it also has the performance benefit that each node does not have to send successful ping info back to the management node.

-d | --debug

1.3. Admin Guide 395
Print debug information.

-h | --help
   Show usage information.

-v | --version
   Display the installed version of xCAT.

EXAMPLES

1. pping all -q
   Output is similar to:
   
   blade7: node2: noping
   blade8: node2: noping
   blade9: node2: noping
   devmaster: node2: noping
   node2: noping

2. pping node1,node2 -i ib0,ib1,ib2,ib3
   Output is similar to:
   
   node1: pinged all nodes successfully on interface ib0
   node1: pinged all nodes successfully on interface ib1
   node1: pinged all nodes successfully on interface ib2
   node1: pinged all nodes successfully on interface ib3
   node2: pinged all nodes successfully on interface ib0
   node2: pinged all nodes successfully on interface ib1
   node2: pinged all nodes successfully on interface ib2
   node2: pinged all nodes successfully on interface ib3

SEE ALSO

psh(1)|psh.1, pping(1)|pping.1

prsync.1

Name

prsync - parallel rsync

Synopsis

prsync filename [filename ...] noderange:destinationdirectory
prsync [-o rsyncopts] [-f fanout] [filename filename ...] [directory directory ...] noderange:destinationdirectory
prsync [-h | --help | -v | --version]
Description

**prsync** is a front-end to *rsync* for a single or range of nodes and/or groups in parallel.

Note: this command does not support the *xcatd* client/server communication and therefore must be run on the management node. It does not support hierarchy, use **xdep -F** to run *rsync* from the management node to the compute node via a service node

**prsync** is NOT multicast, but is parallel unicasts.

Options

- **-o rsyncopts**
  
  *rsync* options. See **rsync(1)**.

- **-f fanout**
  
  Specifies a fanout value for the maximum number of concurrently executing remote shell processes.

- **filename**
  
  A space delimited list of files to *rsync*.

- **directory**
  
  A space delimited list of directories to *rsync*.

- **noderange:destination**
  
  A noderange(3)|noderange.3 and destination directory. The : is required.

- **-h | --help**
  
  Print help.

- **-v | --version**
  
  Print version.

**XCATPSHDFANOUT**

Specifies the fanout value. This variable is overridden by the -f flag. Default is 64.

Examples

1. `cd /install; prsync -o "crz" post stage:/install`

2. `prsync passwd group rack01:/etc`

See Also

noderange(3)noderange.3, pscp(1)|pscp.1, pping(1)|pping.1, psh(1)|psh.1
pscp.1

Name

pscp - parallel remote copy

Synopsis

pscp [-i suffix] [scp options ...] [-f fanout] filename [filename ...] noderange:destinationdirectory
pscp [-h | --help | -v | --version]

Description

cscp is a utility used to copy a single or multiple set of files and/or directories to a single or range of nodes and/or groups in parallel.
cscp is a front-end to the remote copy scp.

Note: this command does not support the xcatd client/server communication and therefore must be run on the management node. It does not support hierarchy, use xdcp to run remote copy command from the management node to the compute node via a service node.
cscp is NOT multicast, but is parallel unicasts.

Options

-f fanout
   Specifies a fanout value for the maximum number of concurrently executing remote shell processes.
-i suffix
   Interfaces to be used.
scp options
   See scp(1)
filename
   A space delimited list of files to copy. If -r is passed as an scp option, directories may be specified as well.
noderange:destination
   A noderange(3)noderange.3 and destination directory. The : is required.
-h | --help
   Print help.
-v | --version
   Print version.

XCATPSHFANOUT
   Specifies the fanout value. This variable is overridden by the -f flag. Default is 64.
Examples

1. `pscp -r /usr/local node1,node3:/usr/local`
2. `pscp passwd group rack01:/etc`

See Also

tnode_range(3)tnoderange.3, pping(1)|pping.1, prsync(1)|prsync.1, psh(1)|psh.1

psh.1

Name

psh - parallel remote shell

Synopsis

```
psh [-i interface] [-f fanout] [-l user] noderange command
psh { -h | --help | -v | --version }
```

Description

*psh* is a utility used to run a command across a list of nodes in parallel.

**Note:**

This command does not run through xcatd like most xCAT commands do. This means you must either run it on the management node, or have a network connection between your machine and the nodes. It does not support hierarchy, use *xdsh* to run remote command from the management node to the compute node via a service node.

*psh* arguments need to precede noderange, otherwise, you will get unexpected errors.

Options

- `-i interface`
  
  The NIC on the node that psh should communicate with. For example, if *interface* is *eth1*, then psh will concatenate *-eth1* to the end of every node name before ssh’ing to it. This assumes those host names have been set up to resolve to the IP address of each of the eth1 NICs.

- `-f fanout`
  
  Specifies a fanout value for the maximum number of concurrently executing remote shell processes.

- `-l user`
  
  Log into the nodes as the specified username. The default is to use the same username as you are running the psh command as.
-n|--nonodecheck

Do not send the noderange to xcatd to expand it into a list of nodes. Instead, use the noderange exactly as it is specified. In this case, the noderange must be a simple list of comma-separated hostnames of the nodes. This allows you to run psh even when xcatd is not running.

**noderange**

See noderange(3)\noderange.3.

**command**

Command to be run in parallel. If no command is given then psh enters interactive mode. In interactive mode a “>” prompt is displayed. Any command entered is executed in parallel to the nodes in the noderange. Use “exit” or “Ctrl-D” to end the interactive session.

-h | --help

Print help.

**Environment Variables**

**XCATPSHFANOUT**

Specifies the fanout value. This variable is overridden by the -f flag. Default is 64.

**Examples**

1. Run uptime on 3 nodes:

```bash
psh node4-node6 uptime
```

Output is similar to:

```
node4: Sun Aug 5 17:42:06 MDT 2001
node5: Sun Aug 5 17:42:06 MDT 2001
node6: Sun Aug 5 17:42:06 MDT 2001
```

2. Run a command on some BladeCenter management modules:

```bash
psh amm1-amm5 'info -T mm[1]'
```

3. Remove the tmp files on the nodes in the 1st frame:

```bash
psh rack01 'rm -f /tmp/*'
```

Notice the use of ‘’ to forward shell expansion. This is not necessary in interactive mode.

**See Also**

noderange(3)\noderange.3, pscp(1)pscp.1, pping(1)ppling.1, prsync(1)prsync.1
pushinitrd.1

NAME

pushinitrd - queries your SoftLayer account and gets attributes for each server.

SYNOPSIS

pushinitrd [-v | --verbose] [-w waittime] [noderange]
pushinitrd [-? | -h | --help]

DESCRIPTION

The pushinitrd command copies the initrd, kernel, params, and static IP info to nodes, so they can be net installed even across vlans (w/o setting up pxe/dhcp broadcast relay). This assumes a working OS is on the nodes. Before running this command, you must run nodeset for these nodes. All of the nodes given to one invocation of pushinitrd must be using the same osimage.

Before using this command, if will be most convenient if you exchange the ssh keys using:

```
xdsh <noderange> -K
```

OPTIONS

-w waittime

The number of seconds the initrd should wait before trying to communicate over the network. The default is 75. This translates into the netwait kernel parameter and is usually needed in a SoftLayer environment because it can take a while for a NIC to be active after changing state.

-?|--help

Display usage message.

-v|--version

Command Version.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. Configure nodes for net installing in a SoftLayer environment:

```
pushinitrd <noderange>
```
FILES

/opt/xcat/bin/pushinitrd

SEE ALSO

getslnodes(1)|getslnodes.1

rbeacon.1

SYNOPSIS

rbeacon [-h | --help | -v | --version | -V | --verbose]

BMC (using IPMI):

rbeacon noderange {on | blink | off | stat}

OpenPOWER BMC (using IPMI):

rbeacon noderange {on | blink | off | stat}

OpenPOWER OpenBMC:

rbeacon noderange {on | off | stat}

DESCRIPTION

rbeacon Turns beacon (a light on the front and/or rear of the physical server) on/off/blink or gives status of a node or noderange.

EXAMPLES

rbeacon 1,3 off
rbeacon 14-56,70-203 on
rbeacon 1,3,14-56,70-203 blink
rbeacon all,-129-256 stat

SEE ALSO

noderange(3)noderange.3, rpower(1)|rpower.1
rbootseq.1

SYNOPSIS

rbootseq [-h | --help | -v | --version]

Blade specific:

rbootseq noderate {hd0 | hd1 | hd2 | hd3 | net | iscsi | iscsicrit | cdrom | usbfash | floppy | none | list | stat},...

HP Blade specific:

rbootseq noderate {hd | net1 | net2 | net3 | net4 | cdrom | usbfash | floppy | none},...

PPC (using Direct FSP Management) specific:

rbootseq noderate [hfi|net]

DESCRIPTION

For Blade specific:

rbootseq sets the boot sequence (the order in which boot devices should be tried) for the specified blades. Up to four different medium/devices can be listed, separated by commas. The boot sequence will remain in effect for these blades until set differently.

For PPC (using Direct FSP Management) specific:

rbootseq sets the ethernet (net) or hfi device as the first boot device for the specified PPC LPARs. The rbootseq command requires that the ethernet or hfi mac address is stored in the mac table, and that the network information is correct in the networks table.

OPTIONS

hd0 | harddisk0 | hd | harddisk
    The first hard disk.

hd1 | harddisk1
    The second hard disk.

hd2 | harddisk2
    The third hard disk.

hd3 | harddisk3
    The fourth hard disk.

n | net | network
    Boot over the ethernet network, using a PXE or BOOTP broadcast.

n | net | network | net1 | nic1 (HP Blade Only)
Boot over the first ethernet network, using a PXE or BOOTP broadcast.

**net2 | nic2 (HP Blade Only)**

Boot over the second ethernet network, using a PXE or BOOTP broadcast.

**net3 | nic3 (HP Blade Only)**

Boot over the third ethernet network, using a PXE or BOOTP broadcast.

**net3 | nic3 (HP Blade Only)**

Boot over the fourth ethernet network, using a PXE or BOOTP broadcast.

**hfi**

Boot p775 nodes over the HFI network, using BOOTP broadcast.

**iscsi**

Boot to an iSCSI disk over the network.

**iscsicrit**

??

**cd | cdrom**

The CD or DVD drive.

**usbflash | usb | flash**

A USB flash drive.

**floppy**

The floppy drive.

**none**

If it gets to this part of the sequence, do not boot. Can not be specified 1st, or before any real boot devices.

**list | stat**

Display the current boot sequence.

### EXAMPLES

1. Set blades 14-56 and 70-203 to try to boot first from the CD drive, then the floppy drive, then the network, and finally from the 1st hard disk:

   ```
   rbootseq blade[14-56],blade[70-203] c,f,n,hd0
   ```

### SEE ALSO

rsetboot(1)|rsetboot.1

rcons.1

**Name**

**rcons** - remotely accesses the serial console of a node
Synopsis

rcons singlenode [conserver-host] [-f] [-s]
rcons [-h | --help | -v | --version]

Description

rcons provides access to a single remote node serial console, using the out-of-band infrastructure for the node (e.g. BMC, Management Module, HMC, KVM, etc.). It uses the conserver open source package to provide one read-write and multiple read-only instances of the console, plus console logging.

If conserver-host is specified, the conserver daemon on that host will be contacted, instead of on the local host.

To exit the console session, enter: ‘ctrl-e c .’ (3 characters: ctrl-e, ‘c’ and ‘’).

Options

-f

If another console for this node is already open in read-write mode, force that console into read-only (spy) mode, and open this console in read-write mode. If -f is not specified, this console will be put in spy mode if another console is already open in read-write mode. The -f flag can not be used with the -s flag.

-s

Open the console in read-only (spy) mode, in this mode all the escape sequences work, but all other keyboard input is discarded. The -s flag can not be used with the -f flag.

-h | --help

Print help.

-v | --version

Print version.

Files

nodehm table - xCAT node hardware management table. See nodehm(5)|nodehm.5 for further details. This is used to determine the console access method.

Examples

rcons node5

See Also

wcons(1)|wcons.1
NAME

regnotif - Registers a Perl module or a command that will get called when changes occur in the desired xCAT database tables.

SYNOPSIS

regnotif [-h | --help]
regnotif [-v | --version]
regnotif filename tablename[,tablename]... [-o | --operation actions]

DESCRIPTION

This command is used to register a Perl module or a command to the xCAT notification table. Once registered, the module or the command will get called when changes occur in the xCAT database tables indicated by tablename. The changes can be row addition, deletion and update which are specified by actions.

PARAMETERS

filename is the path name of the Perl module or command to be registered. tablename is the name of the table that the user is interested in.

OPTIONS

-h | --help Display usage message.
-v | --version Command Version.
-V | --verbose Verbose output.

-o | --operation specifies the database table actions that the user is interested in. It is a comma separated list. ‘a’ for row addition, ‘d’ for row deletion and ‘u’ for row update.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To register a Perl module that gets invoked when rows get added or deleted. in the nodelist and the nodehm tables, enter:

```
regnotif /opt/xcat/lib/perl/xCAT_monitoring/mycode.pm nodelist,nodhm -o a,d
```

2. To register a command that gets invoked when rows get updated in the switch table, enter:
regnotif /usr/bin/mycmd switch -o u

FILES

/opt/xcat/bin/regnotif

SEE ALSO

unregnotif(1)|unregnotif.1

renergy.1

NAME

renergy - remote energy management tool

SYNOPSIS

renergy [-h | --help]
renergy [-v | --version]
Power 6 server specific :
renergy noderange [-V] { all | [savingstatus] [cappingstatus] [cappingmaxmin] [cappingvalue] [cappingsoftmin] [averageAC] [averageDC] [ambienttemp] [exhausttemp] [CPUspeed] [syssbpower] [sysIPLtime]}
renergy noderange [-V] { savingstatus={on | off} | cappingstatus={on | off} | cappingwatt=watt | cappingperc=percentage}
Power 7 server specific :
renergy noderange [-V] { all | [savingstatus] [dsavingstatus] [cappingstatus] [cappingmaxmin] [cappingvalue] [cappingsoftmin] [averageAC] [averageDC] [ambienttemp] [exhausttemp] [CPUspeed] [syssbpower] [sysIPLtime] [fsavingstatus] [ffoMin] [ffoVmin] [ffoTurbo] [ffoNorm] [ffovalue]}
renergy noderange [-V] { savingstatus={on | off} | dsavingstatus={on-norm | on-maxp | off} | fsavingstatus={on | off} | ffovalue=MHZ | cappingstatus={on | off} | cappingwatt=watt | cappingperc=percentage}
Power 8 server specific :
renergy noderange [-V] { all | [savingstatus] [dsavingstatus] [averageAC] [averageAChistory] [averageAC] [averageDChistory] [ambienttemp] [ambienttemphistory] [exhausttemp] [exhausttemphistory] [fanspeed] [fanspeedhistory] [CPUspeed] [CPUspeedhistory] [syssbpower] [sysIPLtime] [fsavingstatus] [ffoMin] [ffoVmin] [ffoTurbo] [ffoNorm] [ffovalue]}
renergy noderange [-V] { savingstatus={on | off} | dsavingstatus={on-norm | on-maxp | off} | fsavingstatus={on | off} | ffovalue=MHZ }

NOTE: The setting operation for Power 8 server is only supported for the server which is running in PowerVM mode. Do NOT run the setting for the server which is running in OPAL mode.

BladeCenter specific :
For Management Modules:
DESCRIPTION

This `energy` command can be used to manage the energy consumption of IBM servers which support IBM EnergyScale technology. Through this command, user can query and set the power saving and power capping status, and also can query the average consumed energy, the ambient and exhaust temperature, the processor frequency for a server.

`energy` command supports IBM POWER6, POWER7 and POWER8 rack-mounted servers, BladeCenter management modules, blade servers, and iDataPlex servers. For POWER6 and POWER7 rack-mounted servers, the following specific hardware types are supported: 8203-E4A, 8204-E8A, 9125-F2A, 8233-E8B, 8236-E8C. For POWER8 server, there’s no hardware type restriction.

The parameter `noderange` needs to be specified for the `energy` command to get the target servers. The `noderange` should be a list of CEC node names, blade management module node names or blade server node names. Lpar name is not acceptable here.

`energy` command can accept multiple of energy attributes to query or one of energy attribute to set. If only the attribute name is specified, without the ‘=’, `energy` gets and displays the current value. Otherwise, if specifying the attribute with ‘=’ like ‘savingstatus=on’, `energy` will set the attribute savingstatus to value ‘on’.

The attributes listed in the SYNOPSIS section are which ones can be handled by `energy` command. But for each specific type of server, there are some attributes that are not supported. If user specifies an attribute which is not supported by a specific server, the return value of this attribute will be ‘na’.

For a blade server nodes:

```
renergy noderange [-V] [all | pd1all | pd2all | [pd1status] [pd2status] [pd1policy] [pd2policy]  
[pd1powermodule1] [pd1powermodule2] [pd2powermodule1] [pd2powermodule2] [pd1availablepower]  
[pd2availablepower] [pd1reservedpower] [pd2reservedpower] [pd1remainpower] [pd2remainpower]  
[pd1inusedpower] [pd2inusedpower] [availableDC] [averageAC] [thermaloutput] [ambienttemp] [mmtemp]]
```

For Flex Management Modules:

```
renergy noderange [-V] [all | [powerstatus] [powerpolicy] [powermodule] [availablepower] [reservedpower] [remainpower] [inusedpower] [availableDC] [averageAC] [thermaloutput] [ambienttemp] [mmtemp]]
```

For Flex node (power and x86):

```
renergy noderange [-V] [all | [averageDC] [capability] [cappingvalue] [CPUspeed] [maxCPUspeed] [savingstatus] [dsavingstatus]]
```

For iDataPlex specific :

```
renergy noderange [-V] [(cappingmaxmin | cappingmax | cappingmin)] [cappingstatus] [cappingvalue] [relhistogram]]
```

For OpenPOWER server specific :

```
renergy noderange [powerusage | temperature]
```
Note: the options powerusage and temperature are only supported for OpenPOWER servers.

The supported attributes for each specific system p hardware type is listed as follows:

**8203-E4A, 8204-E8A**

Supported attributes:
- **Query**: savingstatus,cappingstatus,cappingmin,cappingmax, cappingvalue,cappingsoftmin,averageAC,averageDC,ambienttemp, exhausttemp,CPUspeed,syssbpower,sysIPLtime
- **Set**: savingstatus,cappingstatus,cappingwatt,cappingperc

**9125-F2A**

Supported attributes:
- **Query**: savingstatus,averageAC,ambienttemp,exhausttemp, CPUspeed
- **Set**: savingstatus

**8233-E8B, 8236-E8C**

Supported attributes:
- **Query**: savingstatus,dsavingstatus,cappingstatus,cappingmin, cappingmax,cappingvalue,cappingsoftmin,averageAC,averageDC, ambienttemp,exhausttemp,CPUspeed,syssbpower,sysIPLtime
- **Set**: savingstatus,dsavingstatus,cappingstatus,cappingwatt, cappingperc

**9125-F2C, 9119-FHB**

Supported attributes:
- **Query**: savingstatus,dsavingstatus,cappingstatus,cappingmin, cappingmax,cappingvalue,cappingsoftmin,averageAC,averageDC, ambienttemp,exhausttemp,CPUspeed,syssbpower,sysIPLtime, fsavingstatus,fioMin,fioVmin,fioTurbo,fioNorm,fiovalue
- **Set**: savingstatus,dsavingstatus,cappingstatus,cappingwatt, cappingperc,fsavingstatus,fiovalue

**Non of Above**

For the machine type which is not in the above list, the following attributes can be tried but not guaranteed:
- **Query**: savingstatus,dsavingstatus,cappingstatus,cappingmin, cappingmax,cappingvalue,cappingsoftmin,averageAC,averageDC, ambienttemp,exhausttemp,CPUspeed,syssbpower,sysIPLtime
- **Set**: savingstatus,dsavingstatus,cappingstatus,cappingwatt, cappingperc

Note: For system P CEC nodes, each query operation for attribute CPUspeed, averageAC or averageDC needs about 30 seconds to complete. The query for others attributes will get response immediately.

**PREREQUISITES**

For the Power6 and Power7 nodes, the renergy command depends on the Energy Management Plugin xCAT-pEnergy to communicate with server. xCAT-pEnergy can be downloaded from the IBM web site: http://www.ibm.com/support/fixcentral/. (Other Software -> EM)

NOTE: Power8 nodes don’t need this specific energy management package.

For iDataPlex nodes, the renergy command depends on the Energy Management Plugin xCAT-xEnergy to communicate with server. This plugin must be requested from IBM.

(The support for BladeCenter energy management is built into base xCAT, so no additional plugins are needed for BladeCenter.)
OPTIONS

-h | --help
Display the usage message.

-v | --version
Display the version information.

-V
Verbose output.

all
Query all energy attributes which supported by the specific type of hardware.
For Power8 machines, will not display the attributes for historical records.

pd1all
Query all energy attributes of the power domain 1 for blade management module node.

pd2all
Query all energy attributes of the power domain 2 for blade management module node.

ambienttemp
Query the current ambient temperature. (Unit is centigrade)

ambienttemphistory
Query the historical records which were generated in last one hour for ambienttemp.

availableDC
Query the total DC power available for the entire blade center chassis.

averageAC
Query the average power consumed (Input). (Unit is watt)
Note: For 9125-F2A,9125-F2C server, the value of attribute averageAC is the aggregate for all of the servers in a rack.
Note: For Blade Center, the value of attribute averageAC is the total AC power being consumed by all modules in the chassis. It also includes power consumed by the Chassis Cooling Devices for BCH chassis.

averageAChistory
Query the historical records which were generated in last one hour for averageAC.

averageDC
Query the average power consumed (Output). (Unit is watt)

averageDChistory
Query the historical records which were generated in last one hour for averageDC.

capability
Query the Power Capabilities of the blade server.
staticPowerManagement: the module with the static worst case power values.
fixedPowermanagement: the module with the static power values but ability to throttle.
dynamicPowerManagement: the module with power meter capability, measurement enabled, but capping disabled.
dynamicPowerMeasurement1: the module with power meter capability, measurement enabled, phase 1 only
dynamicPowerMeasurement2: the module with power meter capability, measurement enabled, phase 2 or higher
dynamicPowerMeasurementWithPowerCapping: the module with power meter capability, both measurement and capping enabled, phase 2 or higher

cappingGmin
Query the Guaranteed Minimum power capping value in watts.
cappingmax
Query the Maximum of power capping value in watts.
cappingmaxmin
Query the Maximum and Minimum of power capping value in watts.
cappingmin
Query the Minimum of power capping value in watts.
cappingperc=percentage
Set the power capping value base on the percentage of the max-min of capping value which getting from cappingmaxmin attribute. The valid value must be from 0 to 100.
cappingsoftmin
Query the minimum value that can be assigned to power capping without guaranteed enforceability. (Unit is watt)
cappingstatus
Query the power capping status. The result should be ‘on’ or ‘off’.
cappingstatus={on | off}
Set the power capping status. The value must be ‘on’ or ‘off’. This is the switch to turn on or turn off the power capping function.
cappingvalue
Query the current power capping value. (Unit is watt)
cappingwatt=watt
Set the power capping value base on the watt unit.
If the ‘watt’ > maximum of cappingmaxmin or ‘watt’ < cappingsoftmin, the setting operation will be failed. If the ‘watt’ > cappingsoftmin and ‘watt’ < minimum of cappingmaxmin, the value can NOT be guaranteed.

CPUspeed
Query the effective processor frequency. (Unit is MHz)
CPUspeedhistory
Query the historical records which were generated in last one hour for CPUspeed
dsavingstatus
Query the dynamic power saving status. The result should be ‘on-norm’, ‘on-maxp’ or ‘off’.

If turning on the dynamic power saving, the processor frequency and voltage will be dropped dynamically based on the core utilization. It supports two modes for turn on state:

- **on-norm** - means normal, the processor frequency cannot exceed the nominal value;
- **on-maxp** - means maximum performance, the processor frequency can exceed the nominal value.

\[
\text{dsavingstatus} = \{ \text{on-norm} | \text{on-maxp} | \text{off} \}
\]

Set the dynamic power saving. The value must be ‘on-norm’, ‘on-maxp’ or ‘off’.

The dsavingstatus setting operation needs about 2 minutes to take effect. (The used time depends on the hardware type)

The dsavingstatus only can be turned on when the savingstatus is in turn off status.

**exhausttemp**

Query the current exhaust temperature. (Unit is centigrade)

**exhausttemphistory**

Query the historical records which were generated in last one hour for exhausttemp.

**fanspeed**

Query the fan speed for all the fans which installed in this node. (Unit is RPM - Rotations Per Minute)

If there are multiple fans for a node, multiple lines will be output. And a fan name in bracket will be appended after fanspeed attribute name.

**fanspeedhistory**

Query the historical records which were generated in last one hour for fanspeed.

**ffoMin**

Query the minimum cpu frequency which can be set for FFO. (Fixed Frequency Override)

**ffoNorm**

Query the maximum cpu frequency which can be set for FFO.

**ffoTurbo**

Query the advertised maximum cpu frequency (selling point).

**ffoVmin**

Query the minimum cpu frequency which can be set for dropping down the voltage to save power. That means when you drop the cpu frequency from the ffoVmin to ffoVmin, the voltage won’t change, then there’s no obvious power to be saved.

**ffoValue**

Query the current value of FFO.

**ffoValue=MHZ**

Set the current value of FFO. The valid value of ffoValue should be between the ffoMin and ffoNorm.

**Note1:** Due to the limitation of firmware, the frequency in the range 3501 MHz - 3807 MHz can NOT be set to ffoValue. This range may be changed in future.

**Note2:** The setting will take effect only when the fsavingstatus is in ‘on’ status. But you need to set the ffoValue to a valid value before enabling the fsavingstatus. (It’s a limitation of the initial firmware and will be fixed in future.)
The ffovalue setting operation needs about 1 minute to take effect.

**ffosavingstatus**

Query the status of FFO. The result should be ‘on’ or ‘off’. ‘on’ - enable; ‘off’ - disable.

`ffosavingstatus = {on | off}`

Set the status of FFO. The value must be ‘on’ or ‘off’.

‘on’ - enable. It will take effect only when the ffovalue has been set to a valid value.

‘off’ - disable. It will take effect immediately.

Note: See the Note2 of ffovalue=MHZ.

**maxCPUspeed**

Query the maximum processor frequency. (Unit is MHz)

**mmttemp**

Query the current temperature of management module. (Unit is centigrade)

**pd1status | powerstatus**

Query the status of power domain 1 for blade management module node.

Note: for the attribute without the leading ‘pd1’ which means there’s only one power domain in the chassis.

**pd1policy | powerpolicy**

Query the power management policy of power domain 1.

**pd1powermodule1 | powermodule**

Query the First Power Module capacity in power domain 1.

**pd1powermodule2 | powermodule**

Query the Second Power Module capacity in power domain 1.

**pd1availablepower | availablepower**

Query the total available power in power domain 1.

**pd1reservedpower | reservedpower**

Query the power that has been reserved for power domain 1.

**pd1remainpower | remainpower**

Query the remaining power available in power domain 1.

**pd1inusedpower | inusedpower**

Query the total power being used in power domain 1.

**pd2status**

Query the status of power domain 2 for blade management module node.

**pd2policy**

Query the power management policy of power domain 2.

**pd2powermodule1**

Query the First Power Module capacity in power domain 2.
pd2powermodule2
Query the Second Power Module capacity in power domain 2.

pd2availablepower
Query the total available power in power domain 2.

pd2reservedpower
Query the power that has been reserved for power domain 2.

pd2remainpower
Query the remaining power available in power domain 2.

pd2inusedpower
Query the total power being used in power domain 2.

relhistogram
Query histogram data for wattage information

savingstatus
Query the static power saving status. The result should be ‘on’ or ‘off’. ‘on’ - enable; ‘off’ - disable.
savingstatus={on | off}
Set the static power saving. The value must be ‘on’ or ‘off’.
If turning on the static power saving, the processor frequency and voltage will be dropped to a fixed value to save energy.
The savingstatus setting operation needs about 2 minutes to take effect. (The used time depends on the hardware type)
The savingstatus only can be turned on when the dsavingstatus is in turn off status.

sysIPLtime
Query the time used from FSP standby to OS standby. (Unit is Second)

syssbpower
Query the system power consumed prior to power on. (Unit is Watt)

thermaloutput
Query the thermal output (load) in BTUs per hour for the blade center chassis.

powerusage
Query System Power Statistics with DCMI (Data Center Manageability Interface).

temperature
Query the temperature from DCMI (Data Center Manageability Interface) Temperature sensor. Currently, only CPU temperature and baseboard temperature sensor available for OpenPOWER servers.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.
EXAMPLES

1. Query all attributes which CEC1, CEC2 supported.

   renergy CEC1,CEC2 all

   The output of the query operation:

   CEC1: savingstatus: off
   CEC1: dsavingstatus: off
   CEC1: cappingstatus: off
   CEC1: cappingmin: 1953 W
   CEC1: cappingmax: 2358 W
   CEC1: cappingvalue: 2000 W
   CEC1: cappingsoftmin: 304 W
   CEC1: averageAC: na
   CEC1: averageDC: na
   CEC1: ambienttemp: na
   CEC1: exhausttemp: na
   CEC1: CPUspeed: na
   CEC1: syssbpower: 40 W
   CEC1: sysIPLtime: 900 S
   CEC2: savingstatus: off
   CEC2: cappingstatus: off
   CEC2: cappingmin: 955 W
   CEC2: cappingmax: 1093 W
   CEC2: cappingvalue: 1000 W
   CEC2: cappingsoftmin: 226 W
   CEC2: averageAC: 627 W
   CEC2: averageDC: 531 W
   CEC2: ambienttemp: 25 C
   CEC2: exhausttemp: 40 C
   CEC2: CPUspeed: 4695 MHz

2. Query the fanspeed attribute for Power8 CEC.

   renergy CEC1 fanspeed

   The output of the query operation:

   CEC1: fanspeed (Fan U78CB.001.WZS00MA-A1 00002101): 5947 RPM
   CEC1: fanspeed (Fan U78CB.001.WZS00MA-A2 00002103): 6081 RPM
   CEC1: fanspeed (Fan U78CB.001.WZS00MA-A3 00002105): 6108 RPM
   CEC1: fanspeed (Fan U78CB.001.WZS00MA-A4 00002107): 6000 RPM
   CEC1: fanspeed (Fan U78CB.001.WZS00MA-A5 00002109): 6013 RPM
   CEC1: fanspeed (Fan U78CB.001.WZS00MA-A6 0000210B): 6013 RPM
   CEC1: fanspeed (Fan U78CB.001.WZS00MA-A7 0000210C): 4992 RPM
   CEC1: fanspeed (Fan U78CB.001.WZS00MA-AE 0000210D): 5016 RPM

3. Query the historical records for the CPUspeed attribute. (Power8 CEC)

   renergy CEC1 CPUspeedhistory

   The output of the query operation:

   CEC1: CPUspeedhistory: 2027 MHZ: 20141226042900
   CEC1: CPUspeedhistory: 2027 MHZ: 20141226042930
   CEC1: CPUspeedhistory: 2244 MHZ: 20141226043000

(continues on next page)
4 Query all the attributes for management module node MM1. (For chassis)

```
renergy MM1 all
```

The output of the query operation:

```
mm1: availableDC: 5880W
mm1: frontpaneltmp: 18.00 Centigrade
mm1: inusedAC: 2848W
mm1: mmtmp: 28.00 Centigrade
mm1: pd1avaiblepower: 2940W
mm1: pd1inusedpower: 848W
mm1: pd1policy: redundantWithoutPerformanceImpact
mm1: pd1powermodule1: Bay 1: 2940W
mm1: pd1powermodule2: Bay 2: 2940W
mm1: pd1remainpower: 1269W
mm1: pd1reservedpower: 1671W
mm1: pd1status: 1 - Power domain status is good.
mm1: pd2avaiblepower: 2940W
mm1: pd2inusedpower: 1490W
mm1: pd2policy: redundantWithoutPerformanceImpact
mm1: pd2powermodule1: Bay 3: 2940W
mm1: pd2powermodule2: Bay 4: 2940W
mm1: pd2remainpower: 51W
mm1: pd2reservedpower: 2889W
mm1: pd2status: 2 - Warning: Power redundancy does not exist in this power domain.
mm1: thermaloutput: 9717.376000 BTU/hour
```

5. Query all the attributes for blade server node blade1.

```
renergy blade1 all
```

The output of the query operation:

```
blade1: CPUspeed: 4204MHZ
blade1: averageDC: 227W
blade1: capability: dynamicPowerMeasurement2
blade1: cappingvalue: 315W
blade1: dsavingstatus: off
blade1: maxCPUspeed: 4204MHZ
blade1: savingstatus: off
```

6. Query the attributes savingstatus, cappingstatus and CPUspeed for server CEC1.

```
renergy CEC1 savingstatus cappingstatus CPUspeed
```

The output of the query operation:
7. Turn on the power saving function of CEC1.

```bash
renergy CEC1 savingstatus=on
```

The output of the setting operation:

```
CEC1: Set savingstatus succeeded.
CEC1: This setting may need some minutes to take effect.
```

8. Set the power capping value base on the percentage of the max-min capping value. Here, set it to 50%.

```bash
renergy CEC1 cappingperc=50
```

If the maximum capping value of the CEC1 is 850w, and the minimum capping value of the CEC1 is 782w, the Power Capping value will be set as \(((850-782)*50\% + 782) = 816w\).

The output of the setting operation:

```
CEC1: Set cappingperc succeeded.
CEC1: cappingvalue: 816
```

9. Query power usage and temperature for OpenPOWER servers.

```bash
renergy ops01 powerusage temperature
```

The output will be like this:

```
ops01: Current Power : 591W
ops01: Minimum Power over sampling duration : 558W
ops01: Maximum Power over sampling duration : 607W
ops01: Average Power over sampling duration : 572W
ops01: Time Stamp : 11/18/2015 - 1:4:1
ops01: Statistics reporting time period : 10000 milliseconds
ops01: Power Measurement : Active
ops01: CPU Temperature Instance 0 : +39 Centigrade
ops01: Baseboard temperature Instance 0 : +28 Centigrade
```

**REFERENCES**

1. For more information on ‘Power System Energy Management’:

2. EnergyScale white paper for Power6:
   [http://www-03.ibm.com/systems/power/hardware/whitepapers/energyscale.html](http://www-03.ibm.com/systems/power/hardware/whitepapers/energyscale.html)

3. EnergyScale white paper for Power7:
   [http://www-03.ibm.com/systems/power/hardware/whitepapers/energyscale7.html](http://www-03.ibm.com/systems/power/hardware/whitepapers/energyscale7.html)
FILES

/opt/xcat/bin/renergy

replaycons.1

NAME

replaycons - replay the console output for a node

SYNOPSIS

replaycons [node] [bps] [tail_amount]
replaycons [-h | --help | -v | --version]

DESCRIPTION

The replaycons command reads the console log stored by conserver for this node, and displays it in a way that simulates the original output of the console. Using the bps value, it will throttle the speed of the output play back. (The conserver logs are stored in /var/log/consoles.)

For now, replaycons must be run locally on the system on which the console log is stored. This is normally that management node, but in a hierarchical cluster will usually be the service node.

OPTIONS

bps

The display rate to use to play back the console output. Default is 19200.

tail_amount

The place in the console log file to start play back, specified as the # of lines from the end.

-v | --version

Command Version.

-h | --help

Display usage message.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.
EXAMPLES

1. To replay the console for node1 at the default rate, starting 2000 lines from the end:
   
   ```
   replaycons 19200 2000
   ```

FILES

```
/opt/xcat/bin/replaycons
```

SEE ALSO

rcons(1)|rcons.1

restartxcatd.1

NAME

restartxcatd - Restart the xCAT daemon (xcatd).

SYNOPSIS

```
restartxcatd [[-h | --help] | [-v | --version] | [-r | --reload] | [-V | --verbose]]
```

DESCRIPTION

The `restartxcatd` command restarts the xCAT daemon (xcatd).

Linux Specific

It will perform the xcatd fast restart. The xcatd fast restart is a specific restart which has two advantages compares to the stop and start.

1. The interval of xcatd out of service is very short.
2. The in processing request which initiated by old xcatd will not be stopped by force. The old xcatd will hand over the sockets to new xcatd, but old xcat will still be waiting for the in processing request to finish before the exit.

It does the same thing as ‘service xcatd restart’ on NON-systemd enabled Operating System like rh6.x and sles11.x. But for the systemd enabled Operating System like rh7 and sles12, the ‘service xcatd restart’ just do the stop and start instead of xcatd fast restart.

It’s recommended to use `restartxcatd` command to restart xcatd on systemd enable system like rh7 and sles12 instead of ‘service xcatd restart’ or ‘systemctl restart xcatd’.

AIX Specific

It runs ‘stopsrc -s xcatd’ to stop xcatd first if xcatd is active, then runs ‘startsrec -s xcatd’ to start xcatd.

If the xcatd subsystem was not created, `restartxcatd` will create it automatically.
OPTIONS

-h|--help  Display usage message.
-v|--version  Command Version.
-r|--reload  On a Service Node, services will not be restarted.
-V|--verbose  Display the verbose messages.

RETURN VALUE

0  The command completed successfully.
1  An error has occurred.

EXAMPLES

1. To restart the xCAT daemon, enter:

   restartxcatd

FILES

/opt/xcat/sbin/restartxcatd

restorexCATdb.1

NAME

restorexCATdb - restores the xCAT db tables.

SYNOPSIS

restorexCATdb [-a] [-V] [[-p | --path] path]
restorexCATdb [-h | --help] [-v | --version]

DESCRIPTION

If not using binary restore(-b), the restorexCATdb command restores the xCAT database tables from the *.csv files in directory given by the -p flag. The site table skiptables attribute can be set to a list of tables not to restore. It will not restore isnm_perf* tables. See man dumpxCATdb.

If using the binary restore option for DB2 or postgreSQL, the entire database is restored from the binary backup made with dumpxCATdb. The database will be restored using the database Utilities. For DB2, the timestamp of the correct DB2 backup file (-t) must be provided. All applications accessing the DB2 database must be stopped before you can use the binary restore options. See the xCAT DB2 document for more information. For PostgreSQL, you do not have
to stop the applications accessing the database and the complete path to the backup file, must be supplied on the -p flag.

OPTIONS

-\texttt{-h|--help} Display usage message.
-\texttt{-v|--version} Command Version.
-\texttt{-V|--verbose} Verbose.
-\texttt{-a} All, without this flag the eventlog and auditlog will be skipped. These tables are skipped by default because restoring will generate new indexes
-\texttt{-b} Restore from the binary image.
-\texttt{-p|--path} Path to the directory containing the database restore files. If restoring from the binary image (-b) and using postgresQL, then this is the complete path to the restore file that was created with dumpxCATdb -b.
-\texttt{-t|--timestamp} Use with the -b flag to designate the timestamp of the binary image to use to restore for DB2.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To restore the xCAT database from the /dbbackup/db directory, enter:

\begin{verbatim}
restorexCATdb -p /dbbackup/db
\end{verbatim}

2. To restore the xCAT database including auditlog and eventlog from the /dbbackup/db directory, enter:

\begin{verbatim}
restorexCATdb -a -p /dbbackup/db
\end{verbatim}

3. To restore the xCAT DB2 database from the binary image with timestamp 20111130130239 enter:

\begin{verbatim}
restorexCATdb -b -t 20111130130239 -p /dbbackup/db
\end{verbatim}

4. To restore the xCAT postgresQL database from the binary image file pgbackup.20553 created by dumpxCATdb enter:

\begin{verbatim}
restorexCATdb -b -p /dbbackup/db/pgbackup.20553
\end{verbatim}

FILES

/opt/xcat/sbin/restorexCATdb

SEE ALSO

dumpxCATdb(1) dumpxCATdb.1
reventlog.1

Name

reventlog - retrieve or clear remote hardware event logs

Synopsis

reventlog noderange [number-of-entries [-s]|all [-s] | clear]
reventlog [-h | --help | -v | --version]

OpenPOWER OpenBMC specific :

reventlog noderange [resolved=(id-list|LED)]

Description

reventlog can display any number of remote hardware event log entries or clear them for a range of nodes. Hardware event logs are stored on each servers service processor.

Options

number-of-entries
   Retrieve the specified number of entries from the nodes’ service processors.

all
   Retrieve all entries.

-s
   To sort the entries from latest (always the last entry in event DB) to oldest (always the first entry in event DB). If number-of-entries specified, the latest number-of-entries events will be output in the order of latest to oldest.

clear
   Clear event logs.

resolved=(id-list|LED)
   Mark event log entries as resolved. Use comma separated list of entry ids to specify individual entries. Use LED to mark as resolved all event log entries that contribute to LED fault.

-h | --help
   Print help.

-v | --version
   Print version.
**Examples**

1. List last 5 event log entries from node4 and node5

   ```
   reventlog node4,node5 5
   ```

   Output is similar to:

   ```
   node4: SERVPROC I 09/06/00 15:23:33 Remote Login Successful User ID = USERID[00]
   node4: SERVPROC I 09/06/00 15:23:32 System spn1 started a RS485 connection with us[00]
   node4: SERVPROC I 09/06/00 15:22:35 RS485 connection to system spn1 has ended[00]
   node4: SERVPROC I 09/06/00 15:22:32 Remote Login Successful User ID = USERID[00]
   node4: SERVPROC I 09/06/00 15:22:31 System spn1 started a RS485 connection with us[00]
   node5: SERVPROC I 09/06/00 15:22:32 Remote Login Successful User ID = USERID[00]
   node5: SERVPROC I 09/06/00 15:22:31 System spn1 started a RS485 connection with us[00]
   node5: SERVPROC I 09/06/00 15:21:34 RS485 connection to system spn1 has ended[00]
   node5: SERVPROC I 09/06/00 15:21:30 Remote Login Successful User ID = USERID[00]
   node5: SERVPROC I 09/06/00 15:21:29 System spn1 started a RS485 connection with us[00]
   ```

2. Clear all event log entries from node4 and node5

   ```
   reventlog node4,node5 clear
   ```

   Output is similar to:

   ```
   node4: clear
   node5: clear
   ```

3. Mark as resolved all event log entries from node4 that contribute to LED fault

   ```
   reventlog node4 resolved=LED
   ```

   Output is similar to:

   ```
   Attempting to resolve the following log entries: LED...
   node4: Resolved 51.
   node4: Resolved 52.
   node4: Resolved 58.
   ```

**SEE ALSO**

rpower(1) rpower.1, monstart(1) monstart.1

rflash.1
Name

**rflash** - Performs Licensed Internal Code (LIC) update or firmware update on supported xCAT managed nodes.

Synopsis

```
rflash [-h | --help] [-v | --version] [-V | --verbose]
```

**PPC (with HMC) specific:**

```
rflash nodernode -p directory [--activate {concurrent | disruptive}]
rflash nodernode [--commit | --recover]
```

**PPC (without HMC, using Direct FSP Management) specific:**

```
rflash nodernode -p directory [--activate {disruptive | deferred}] [-d data_directory]
rflash nodernode [--commit | --recover]
```

**NeXtScale FPC specific:**

```
rflash nodernode http_directory
```

**OpenPOWER BMC specific (using IPMI):**

```
rflash nodernode [hpm_file_path | -d data_directory] [-c | --check] [-r retry=count]
rflash nodernode --recover bmc_file_path
```

**OpenPOWER OpenBMC specific:**

```
rflash nodernode [--check | -l | --list]
rflash nodernode tar_file_path [-c | --check] [-a | --activate] [-u | --upload]
rflash nodernode tar_file_directory [-d | --no-host-reboot]
rflash nodernode image_id [-a | --activate] [-d | --delete]
```

Description

The **rflash** command initiates Firmware updates on supported xCAT nodes. Licensed Internal Code (also known as microcode) updates are performed on supported HMC-attached POWER5 and POWER6 pSeries nodes, and POWER7 systems using Direct FSP management.

The command scans the specified directory structure for Firmware update package files applicable to the given nodes and components. And then it will automatically select the latest version for the upgrade. The firmware update files include the Microcode update package and associated XML file. They can be downloaded from the IBM Web site: [http://www-933.ibm.com/support/fixcentral/](http://www-933.ibm.com/support/fixcentral/).
The POWER5 and POWER6 systems contain several components that use Licensed Internal Code. The `rflash` command supports two of these components: the managed system (also known as the Central Electronics Complex, or CEC) and the power subsystem (also known as the Bulk Power Assembly (BPA) or Bulk Power Controller (BPC)). Some POWER5 managed systems can be attached to a power subsystem. These power subsystems can support multiple managed systems. When the `rflash` command is invoked, xCAT will determine the managed system or power subsystem associated with that CEC and perform the update.

The `noderange` can be an CEC or CEC list, a Lpar or Lpar list and a Frame or Frame list. But CEC (or Lpar) and Frame can’t be used at the same time. When the `noderange` is an CEC or CEC list, `rflash` will upgrade the firmware of the CEC or CECs in the cec list. If `noderange` is a Lpar or Lpar list, `rflash` will update Licensed Internal Code (LIC) on HMC-attached POWER5 and POWER6 pSeries nodes, and POWER7 systems using Direct FSP management. If `noderange` is a Frame or Frame list, `rflash` will update Licensed Internal Code (LIC) of the power subsystem on HMC-attached POWER5 and POWER6 pSeries nodes. The `noderange` can also be the specified node groups. You can specify a comma or space-separated list of node group ranges. See the `noderange` man page for detailed usage information.

The command will update firmware for NeXtScale FPC when given an FPC node and the http information needed to access the firmware.

**PPC (with HMC) specific:**

The `rflash` command uses the `xdsh` command to connect to the HMC controlling the given managed system and perform the updates. Before running `rflash`, use `rspconfig` to check if the related HMC ssh is enabled. To enable a HMC ssh connection, use `rspconfig` command.

**Warning!** This command may take considerable time to complete, depending on the number of systems being updated and the workload on the target HMC. In particular, power subsystem updates may take an hour or more if there are many attached managed systems.

Depending on the Licensed Internal Code update that is installed, the affected HMC-attached POWER5 and POWER6 systems may need to be recycled. The `--activate` flag determines how the affected systems activate the new code. The concurrent option activates code updates that do not require a system recycle (known as a “concurrent update”). If this option is given with an update that requires a system recycle (known as a “disruptive update”), a message will be returned, and no activation will be performed. The disruptive option will cause any affected systems that are powered on to be powered down before installing and activating the update. Once the update is complete, the command will attempt to power on any affected systems that it powered down. Those systems that were powered down when the command was issued will remain powered down when the update is complete.

The flash chip of a POWER5 and POWER6 managed system or power subsystem stores firmware in two locations, referred to as the temporary side and the permanent side. By default, most POWER5 and POWER6 systems boot from the temporary side of the flash. When the `rflash` command updates code, the current contents of the temporary side are written to the permanent side, and the new code is written to the temporary side. The new code is then activated. Therefore, the two sides of the flash will contain different levels of code when the update has completed.

The `--commit` flag is used to write the contents of the temporary side of the flash to the permanent side. This flag should be used after updating code and verifying correct system operation. The `--recover` flag is used to write the permanent side of the flash chip back to the temporary side. This flag should be used to recover from a corrupt flash operation, so that the previously running code can be restored.

**NOTE:** When the `--commit` or `--recover` two flags is used, the `noderange` cannot be BPA. It only can be CEC or LPAR, and will take effect for both managed systems and power subsystems.

xCAT recommends that you shutdown your Operating System images and power off your managed systems before applying disruptive updates to managed systems or power subsystems.

Any previously activated code on the affected systems will be automatically accepted into permanent flash by this procedure.
IMPORTANT! If the power subsystem is recycled, all of its attached managed systems will be recycled.

If it outputs "Timeout waiting for prompt" during the upgrade, set the "ppctimeout" larger in the site table. After the upgrade, remember to change it back. If run the "rflash" command on an AIX management node, need to make sure the value of "useSSHonAIX" is "yes" in the site table.

**PPC (using Direct FSP Management) specific:**

In currently Direct FSP/BPA Management, our rflash doesn’t support concurrent value of --activate flag, and supports disruptive and deferred. The disruptive option will cause any affected systems that are powered on to be powered down before installing and activating the update. So we require that the systems should be powered off before do the firmware update.

The deferred option will load the new firmware into the T (temp) side, but will not activate it like the disruptive firmware. The customer will continue to run the Frames and CECs working with the P (perm) side and can wait for a maintenance window where they can activate and boot the Frame/CECs with new firmware levels. Refer to the doc to get more details: XCAT_Power_775_Hardware_Management

In Direct FSP/BPA Management, there is -d data_directory option. The default value is /tmp. When doing firmware update, rflash will put some related data from rpm packages in <data_directory> directory, so the execution of rflash will require available disk space in <data_directory> for the command to properly execute:

For one GFW rpm package and one power code rpm package, if the GFW rpm package size is gfw_rpmsize, and the Power code rpm package size is power_rpmsize, it requires that the available disk space should be more than: 1.5*gfw_rpmsize + 1.5*power_rpmsize

For Power 775, the rflash command takes effect on the primary and secondary FSPs or BPAs almost in parallel.

For more details about the Firmware Update using Direct FSP/BPA Management, refer to: XCAT_Power_775_Hardware_Management#Updating_the_BPA_and_FSP_firmware_using_xCAT_DFM

**NeXtScale FPC specific:**

The command will update firmware for NeXtScale FPC when given an FPC node and the http information needed to access the firmware. The http information required includes both the MN IP address as well as the directory containing the firmware. It is recommended that the firmware be downloaded and placed in the /install directory structure as the xCAT MN /install directory is configured with the correct permissions for http. Refer to the doc to get more details: XCAT_NeXtScale_Clusters

**OpenPOWER specific (using IPMI):**

The command will update firmware for OpenPOWER BMC when given an OpenPOWER node with mgt=ipmi and either the hpm formatted file path or path to a data directory.

**Note:** When using rflash in hierarchical environment, the hpm file or data directory must be accessible from Service Nodes.

**OpenPOWER specific (using OpenBMC):**

The command will update firmware for OpenPOWER BMC when given an OpenPOWER node with mgt=openbmc and either an update .tar file or an uploaded image id.

-ll--list:
The list option will list out available firmware on the BMC. It provides an interface to display the ID of the various firmware levels.

The (*) symbol indicates the active running firmware on the server.

The (+) symbol indicates the firmware that is pending and a reboot is required to set it to be the active running firmware level.

**-ul--upload:**
The upload option expects a .tar file as the input and will upload the file to the BMC. Use the list option to view the result.

**-al--activate:**
The activate option expects either a .tar file or an ID as the input. If a .tar file is provided, it will upload and activate the firmware in a single step.

To apply the firmware level, a reboot is required to BMC and HOST.

**Note:** When using rflash in hierarchical environment, the .tar file must be accessible from Service Nodes.

**-d:**
This option streamlines the update, activate, reboot BMC and reboot HOST procedure. It expects a directory containing both BMC and Host .tar files. When BMC and Host tar files are provided, the command will upload and activate firmware. After BMC becomes activate, it will reboot BMC. If BMC state is Ready, the command will reboot the HOST. If BMC state is NotReady, the command will exit.

**Note:** When using **--no-host-reboot**, it will not reboot the host after BMC is reboot.

**--delete:**
This delete option will delete update image from BMC. It expects an ID as the input.

**Options**

**-hl--help**
Writes the command’s usage statement to standard output.

**-cl--check**
Check the firmware version of BMC and an update file.

**-p directory**
Specifies the directory where the packages are located.

**-d data_directory**
PPC (without HMC, using Direct FSP Management) specific:

Specifies the directory where the raw data from rpm packages for each CEC/Frame are located. The default directory is /tmp. The option is only used in Direct FSP/BPA Management.

OpenPOWER BMC specific (using IPMI):

Used for IBM Power S822LC for Big Data systems only. Specifies the directory where the pUpdate utility and at least one of BMC or Host update files are located. The utility and update files can be downloaded from FixCentral.

**--activate {concurrent | disruptive}**
Must be specified to activate the new Licensed Internal Code. The “disruptive” option will cause the target systems to be recycled. Without this flag, LIC updates will be installed only, not activated.

--commit
Used to commit the flash image in the temporary side of the chip to the permanent side for both managed systems and power subsystems.

--recover
PPC (with HMC) and PPC (without HMC, using Direct FSP Management) specific:
Used to recover the flash image in the permanent side of the chip to the temporary side for both managed systems and power subsystems.
OpenPOWER BMC specific (using IPMI):
Used for IBM Power S822LC for Big Data systems only. Used to recover the BMC with a BMC image downloaded from FixCentral. This option will only work if BMC is in “Brick protection” state.

--retry=count
Specify number of times to retry the update if failure is detected. Default value is 2. Value of 0 can be used to indicate no retries.

-al--activate
Activate update image. Image id or update file must be specified.

-ll--list
List currently uploaded update images. “(*)” indicates currently active image.

-ul--upload
Upload update image. Specified file must be in .tar format.

--delete
Delete update image from BMC

-vl--version
Displays the command’s version.

-Vl--verbose
Verbose output.

Exit Status

0 The command completed successfully.
1 An error has occurred.

Examples

1. To update only the power subsystem attached to a single HMC-attached pSeries CEC(cec_name), and recycle the power subsystem and all attached managed systems when the update is complete, and the Microcode update package and associated XML file are in /tmp/fw, enter:

   rflash cec_name -p /tmp/fw --activate disruptive
2. To update only the power subsystem attached to a single HMC-attached pSeries node, and recycle the power subsystem and all attached managed systems when the update is complete, and the Microcode update package and associated XML file are in /tmp/fw, enter:

```
rflash bpa_name -p /tmp/fw --activate disruptive
```

3. To commit a firmware update to permanent flash for both managed system and the related power subsystems, enter:

```
rflash cec_name --commit
```

4. To update the firmware on a NeXtScale FPC specify the FPC node name and the HTTP location of the file including the xCAT MN IP address and the directory on the xCAT MN containing the firmware as follows:

```
rflash fpc01 http://10.1.147.169/install/firmware/fhet17a/ibm_fw_fpc_fhet17a-\2.02_anyos_noarch.rom
```

5. To update the firmware on OpenPOWER machine specify the node name and the file path of the HPM firmware file as follows:

```
rflash fs3 /firmware/8335_810.1543.20151021b_update.hpm
```

Print verbose message to rflash log file (/var/log/xcat/rflash/fs3.log) when updating firmware:

```
rflash fs3 /firmware/8335_810.1543.20151021b_update.hpm -V
```

6. To update the firmware on IBM Power S822LC for Big Data machine specify the node name and the file path of the data directory containing pUpdate utility, both BMC and Host update files:

```
rflash briggs01 -d /root/supermicro/OP825
```

7. To update the firmware on the OpenBMC machine, specify the firmware update file to upload and activate:

```
rflash p9euh02 -a /tmp/witherspoon.pnor.squashfs.tar
```

### Location

```
/opt/xcat/bin/rflash
```

### NOTES

This command is part of the xCAT software product.

### SEE ALSO

```
rinv(1) rinv.1, rspconfig(1) rspconfig.1
```

### rinv.1

#### Name

```
rinv - Remote hardware inventory
```

1.3. Admin Guide  429
Synopsis

rinv [-h | --help | -v | --version]

BMC/MPA specific:

rinv noderange [model | serial | asset | vpd | deviceid | guid | firm | dimm | mprom | all]

OpenPOWER (IPMI) server specific:

rinv noderange [model | serial | deviceid | uuid | guid | vpd | mprom | firm | all]

OpenPOWER (OpenBMC) server specific:

rinv noderange [model] [serial] [firm] [cpu] [dimm] [all] [-V | --verbose]

PPC (with HMC) specific:

rinv noderange { bus | config | serial | model | firm | all}

PPC (using Direct FSP Management) specific:

rinv noderange [firm]

rinv noderange {deconfig [-x]}

Blade specific:

rinv noderange {mtm | serial | mac | bios | diag | mprom | mparom | firm | all}

VMware specific:

rinv noderange [-t]

pdu specific:

rinv noderange

zVM specific:

rinv noderange [config | all]

rinv noderange [--diskpoolspace]

rinv noderange [--diskpool pool space]

rinv noderange [--fcpdevices state details]
\texttt{rinv noderange [--diskpoolnames]}
\texttt{rinv noderange [--networknames]}
\texttt{rinv noderange [--network name]}
\texttt{rinv noderange [--ssi]}
\texttt{rinv noderange [--smapilevel]}
\texttt{rinv noderange [--wwpns fcp\_channel]}
\texttt{rinv noderange [--zfcppool pool space]}
\texttt{rinv noderange [--zfcppoolnames]}

\textbf{Description}

\texttt{rinv} retrieves hardware configuration information from the on-board Service Processor for a single or range of nodes and groups.

Calling \texttt{rinv} for VMware will display the UUID/GUID, number of CPUs, amount of memory, the MAC address and a list of Hard disks. The output for each Hard disk includes the label, size and backing file location.

\textbf{Options}

\texttt{bus}

List all buses for each I/O slot.

\texttt{config}

Retrieves number of processors, speed, total memory, and DIMM locations.

\texttt{model}

Retrieves model number.

\texttt{serial}

Retrieves serial number.

\texttt{firm}

Retrieves firmware versions.

\texttt{deconfig}

Retrieves deconfigured resources. Deconfigured resources are hw components (cpus, memory, etc.) that have failed so the firmware has automatically turned those components off. This option is only capable of listing some of the deconfigured resources and should not be the only method used to check the hardware status.

\texttt{-x}

To output the raw information of deconfigured resources for CEC.

\texttt{asset}

Retrieves asset tag. Usually it’s the MAC address of eth0.

\texttt{vpd}

Same as specifying model, serial, deviceid, and mprom.
diag
  Diagnostics information of firmware.

mprom
  Retrieves mprom firmware level.

dimm
  Retrieves dual in-line memory module information.

deviceid
  Retrieves device identification. Usually device, manufacturing and product IDs.

uuid
  Retrieves the universally unique identifier.

guid
  Retrieves the global unique identifier.

all
  All of the above.

-h | --help
  Print help.

-v | --version
  Print version.

-V | --verbose
  Prints verbose output, if available.

-t
  Set the values in the vm table to what vCenter has for the indicated nodes.

zVM specific :

--diskpoolspace
  Calculates the total size of every known storage pool.

--diskpool pool space
  Lists the storage devices (ECKD and FBA) contained in a disk pool. Space can be: all, free, or used.

--fcpdevices state details
  Lists the FCP device channels that are active, free, or offline. State can be: active, free, or offline.

--diskpoolnames
  Lists the known disk pool names.

--networknames
  Lists the known network names.

--network name
  Shows the configuration of a given network device.

--ssi
Obtain the SSI and system status.

--smapilevel
Obtain the SMAPI level installed on the z/VM system.

--wwpns fcp_channel
Query a given FCP device channel on a z/VM system and return a list of WWPNs.

--zfcppool pool space
List the SCSI/FCP devices contained in a zFCP pool. Space can be: free or used.

--zfcppoolnames
List the known zFCP pool names.

Examples

1. To retrieve all information available from blade node4, enter:

   rinv node5 all

   Output is similar to:

   node5: Machine Type/Model 865431Z
   node5: Serial Number 23C5030
   node5: Asset Tag 00:06:29:1F:01:1A
   node5: PCI Information
   node5: Bus VendID DevID RevID Description Slot Pass/Fail
   node5: 0 1166 0009 06 Host Bridge 0 PASS
   node5: 0 1166 0009 06 Host Bridge 0 PASS
   node5: 0 5333 8A22 04 VGA Compatible Controller0 PASS
   node5: 0 8086 1229 08 Ethernet Controller 0 PASS
   node5: 0 8086 1229 08 Ethernet Controller 0 PASS
   node5: 0 1166 0200 50 ISA Bridge 0 PASS
   node5: 0 1166 0211 00 IDE Controller 0 PASS
   node5: 0 1166 0220 04 Universal Serial Bus 0 PASS
   node5: 1 9005 008F 02 SCSI Bus Controller 0 PASS
   node5: 1 14C1 8043 03 Unknown Device Type 2 PASS
   node5: Machine Configuration Info
   node5: Number of Processors: 3
   node5: Processor Speed: 866 MHz
   node5: Total Memory: 512 MB
   node5: Memory DIMM locations: Slot(s) 3 4

2. To output the raw information of deconfigured resources for CEC cec01, enter:

   rinv cec01 deconfig -x

   Output is similar to:

   cec01:
   <SYSTEM>
   <System_type>IH</System_type>
   <NODE>
   <Location_code>U78A9.001.0123456-P1</Location_code>
   <RID>800</RID>

(continues on next page)
3. To retrieve `config` information from the HMC-managed LPAR node3, enter:

```
rinv node3 config
```

Output is similar to:

```
node5: Machine Configuration Info
node5: Number of Processors: 1
node5: Total Memory (MB): 1024
``` 

4. To retrieve information about a VMware node vm1, enter:

```
rinv vm1
```

Output is similar to:

```
vm1: UUID/GUID: 42198f65-d579-fb26-8de7-3ae49e1790a7
vm1: CPUs: 1
vm1: Memory: 1536 MB
vm1: Network adapter 1: 36:1b:c2:6e:04:02
vm1: Hard disk 1 (d0): 9000 MB @ [nfs_192.168.68.21_vol_rclstorage_vmware]
  → vml_3/vml.vmtdk
vm1: Hard disk 2 (d4): 64000 MB @ [nfs_192.168.68.21_vol_rclstorage_vmware]
  → vml_3/vml_5.vmdk
```

**zVM specific :**

5. To list the defined network names available for a given node:

```
rinv pokdev61 --getnetworknames
```

Output is similar to:

```
pokdev61: LAN:QDIO SYSTEM GLAN1
pokdev61: LAN:HIPERS SYSTEM GLAN2
pokdev61: LAN:QDIO SYSTEM GLAN3
pokdev61: VSWITCH SYSTEM VLANTST1
pokdev61: VSWITCH SYSTEM VLANTST2
pokdev61: VSWITCH SYSTEM VSW1
pokdev61: VSWITCH SYSTEM VSW2
pokdev61: VSWITCH SYSTEM VSW3
```

6. To list the configuration for a given network:

```
rinv pokdev61 --getnetwork GLAN1
```

Output is similar to:

```
pokdev61: LAN SYSTEM GLAN1 Type: QDIO Connected: 1 Maxconn: INFINITE
pokdev61: PERSISTENT UNRESTRICTED IP Accounting: OFF
pokdev61: IPTimeout: 5 MAC Protection: Unspecified
pokdev61: Isolation Status: OFF
```
7. To list the disk pool names available:

```
 rinv pokdev61 --diskpoolnames
```

Output is similar to:

```
pokdev61: POOL1
pokdev61: POOL2
pokdev61: POOL3
```

8. List the configuration for a given disk pool:

```
 rinv pokdev61 --diskpool POOL1 free
```

Output is similar to:

```
pokdev61: #VolID DevType StartAddr Size
pokdev61: EMC2C4 3390-09 0001 10016
pokdev61: EMC2C5 3390-09 0001 10016
```

9. List the known zFCP pool names.

```
 rinv pokdev61 --zfcppoolnames
```

Output is similar to:

```
pokdev61: zfcp1
pokdev61: zfcp2
pokdev61: zfcp3
```

10. List the SCSI/FCP devices contained in a given zFCP pool:

```
 rinv pokdev61 --zfcppool zfcp1
```

Output is similar to:

```
pokdev61: #status,wwpn,lun,size,range,owner,channel,tag
pokdev61: used,500512345678c411,40144121000000000,2g,3B40-3B7F,ihost13,3b77, replace_root_device
pokdev61: used,500512345678c411,40144122000000000,8192M,3B40-3B7F,ihost13,
pokdev61: free,500512345678c411,40144123000000000,8g,3B40-3B7F,,
pokdev61: free,5005123456789411,40144124000000000,2g,3B40-3B7F,,
pokdev61: free,5005123456789411;5005123456789411,40144126000000000,2G,3B40-
```

SEE ALSO

rpower(1)|rpower.1
rmdef.1

NAME

rmdef - Use this command to remove xCAT data object definitions.
SYNOPSIS

rmdef [-h | --help] [-t object-types]

DESCRIPTION

This command is used to remove xCAT object definitions that are stored in the xCAT database.

OPTIONS

- all

Clear the whole xCAT database. A backup of the xCAT definitions should be saved before using this option as the xCAT daemons will no longer work once cleared.

To restore:

1. export XCATBYPASS=1 and run the restorexCATdb command.
   or
2. Run xcatconfig -d which initializes the database the same as when xCAT was installed.

- force

Use this with the --all option as an extra indicator that ALL definitions are to be removed.

- help

Display a usage message.

noderange

A set of comma delimited node names and/or group names. See the “noderange” man page for details on supported formats.

-o object-names

A set of comma delimited object names.

-t object-types

A set of comma delimited object types.

-C cleanup

Perform additional cleanup by running nodeset offline, makeconservercf -d and makegocons --cleanup on the objects specified in the noderange.

-V | --verbose

Verbose mode.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.
EXAMPLES

1. To remove a range of node definitions.
   
   \texttt{rmdef -t node node1-node4}

2. To remove all node definitions for the nodes contained in the group bpcnodes.
   
   \texttt{rmdef -t node -o bpcnodes}

3. To remove the group called bpcnodes.
   
   \texttt{rmdef -t group -o bpcnodes}

   (This will also update the values of the “groups” attribute of the member nodes.)

FILES

\$XCATROOT/bin/rmdef

(The XCATROOT environment variable is set when xCAT is installed. The default value is “/opt/xcat”.)

NOTES

This command is part of the xCAT software product.

SEE ALSO

mkdef(1)|mkdef.1, lsdef(1)|lsdef.1, chdef(1)|chdef.1, xcatstanzafile(5)|xcatstanzafile.5

rmdocker.1

SYNOPSIS

\texttt{rmdocker noderange [-f | --force]}
\texttt{rmdocker [-h | --help]}
\texttt{rmdocker [-v | --version]}

DESCRIPTION

\texttt{rmdocker} To remove docker instances with the specified node name

OPTIONS

-\texttt{-f | --force}
Force to removal of a running container or failed to disconnect customized network
EXAMPLES

rmdocker host01c01
host01c01: Disconnect customized network 'mynet0' done
host01c01: success

SEE ALSO

mkdocker(1)|mkdocker.1, lsdocker(1)|lsdocker.1

rmdsklsnode.1

NAME

rmdsklsnode - Use this xCAT command to remove AIX/NIM diskless machine definitions.

SYNOPSIS

rmdsklsnode [-h | --help ]


DESCRIPTION

Use this command to remove all NIM client machine definitions that were created for the specified xCAT nodes.
The xCAT node definitions will not be removed. Use the xCAT rmdef command to remove xCAT node definitions.
If you are using xCAT service nodes the rmdsklsnode command will automatically determine the correct server(s) for the node and remove the NIM definitions on that server(s).
If the node you are trying to remove is currently running the rmdsklsnode command will not remove the definitions. You can use the “-f” option to shut down the node and remove the definition.

Removing alternate NIM client definitions

If you used the “-n” option when you created the NIM client definitions with the mkdsklsnode command then the NIM client machine names would be a combination of the xCAT node name and the osimage name used to initialize the NIM machine. To remove these definitions, you must provide the name of the osimage that was used using the “-i” option.
In most cases you would most likely want to remove the old client definitions without disturbing the nodes that you just booted with the new alternate client definition. The rmdsklsnode -r option can be used to remove the old alternate client definitions without stopping the running node.
However, if you have NIM dump resources assign to your nodes be aware that when the old NIM alternate client definitions are removed it will leave the nodes unable to produce a system dump. This is a current limitation in the NIM support for alternate client definitions. For this reason, it is recommended that you wait to do this cleanup until right before you do your next upgrade.
OPTIONS

-f |--force
   Use the force option to stop and remove running nodes. This handles the situation where a NIM machine
definition indicates that a node is still running even though it is not.

-b |--backupSN
   When using backup service nodes only update the backup. The default is to update both the primary and
   backup service nodes.

-h |--help
   Display usage message.

-i image_name
   The name of an xCAT image definition.

noderange
   A set of comma delimited node names and/or group names. See the “noderange” man page for details on
   additional supported formats.

-p|--primarySN
   When using backup service nodes only update the primary. The default is to update both the primary and
   backup service nodes.

-r|--remdef
   Use this option to reset, deallocate, and remove NIM client definitions. This option will not attempt to
   shut down running nodes. This option should be used when remove alternate NIM client definitions that
   were created using mkdsklsnode -n.

-V |--verbose
   Verbose mode.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. Remove the NIM client definition for the xCAT node named “node01”. Give verbose output.
   rmdsklsnode -V node01

2. Remove the NIM client definitions for all the xCAT nodes in the group “aixnodes”. Attempt to shut down the
   nodes if they are running.
   rmdsklsnode -f aixnodes

3. Remove the NIM client machine definition for xCAT node “node02” that was created with the mkdsklsnode -n
   option and the image “AIXdskls”. (i.e. NIM client machine name “node02_AIXdskls”.)
This assume that node02 is not currently running.

4. Remove the old alternate client definition “node27_olddskls”.

Assuming the node was booted using an new alternate NIM client definition then this will leave the node running.

FILES

/opt/xcat/bin/rmdsklsnode

NOTES

This command is part of the xCAT software product.

SEE ALSO

mkdsklsnode(1)|mkdsklsnode.1

rmflexnode.1

NAME

rmflexnode - Delete a flexible node.

SYNOPSIS

rmflexnode [-h | --help]
rmflexnode [-v | --version]
rmflexnode noderange

DESCRIPTION

Delete a flexible node which created by the mkflexnode command.

The rmflexnode command will delete the Partition which the slots in id attribute assigned to.

The action of deleting flexible node will impact the hardware status. Before deleting it, the blades in the slot range should be in power off state.

After the deleting, use the lsflexnode to check the status of the node.

The noderange only can be a blade node.
OPTIONS

-h | --help
   Display the usage message.

-v | --version
   Display the version information.

EXAMPLES

1 Delete a flexible node base on the xCAT node blade1.
   The blade1 should belong to a complex, the id attribute should be set correctly and all the slots should be in power off state.
   
   rmflexnode blade1

FILES

/opt/xcat/bin/rmflexnode

SEE ALSO

lsflexnode(1)|lsflexnode.1, mkflexnode(1)|mkflexnode.1

rmhwconn.1

NAME

rmhwconn - Use this command to remove connections from CEC and Frame nodes to HMC nodes.

SYNOPSIS

rmhwconn [-h| --help]
rmwconn [-v| --version]

PPC (with HMC) specific:

rmhwconn [-V| --verbose] noderange

PPC (without HMC, using FSPAPI) specific:

rmhwconn noderange -T tooltype
**PPC (use HMC as SFP) specific:**

rmhwconn -s

**DESCRIPTION**

For PPC (with HMC) specific:

This command is used to disconnect CEC and Frame nodes from HMC nodes, according to the connection information defined in ppc table in xCAT DB.

Note: If a CEC belongs to a frame with a BPA installed, this CEC cannot be disconnected individually. Instead, the whole frame should be disconnected.

For PPC (without HMC, using FSPAPI) specific:

It’s used to disconnection CEC and Frame nodes from hardware server.

For PPC (use HMC as SFP) specific:

It is used to disconnect Frame nodes from HMC nodes.

**OPTIONS**

- **-h|--help**
  
  Display usage message.

- **-V|--verbose**
  
  Verbose output.

- **-T**
  
  The tooltype is used to communicate to the CEC/Frame. The value could be **lpar** or **fnn**. The tooltype value **lpar** is for xCAT and **fnn** is for CNM.

**RETURN VALUE**

0 The command completed successfully.

1 An error has occurred.

**EXAMPLES**

1. To disconnect all CEC nodes in node group cec from their HMC nodes:

   rmhwconn cec

2. To remove the connection for Frame node frame1:

   rmhwconn frame1

3. To disconnect all CEC nodes in node group cec from their related hardware server, using lpar tooltype:
rmhwconn cec -T lpar

FILES

$XCATROOT/bin/rmhwconn
(The XCATROOT environment variable is set when xCAT is installed. The default value is “/opt/xcat”.)

NOTES

This command is part of the xCAT software product.

SEE ALSO

lshwconn(1)|lshwconn.1, mkhwconn(1)|mkhwconn.1

rmhypervisor.1

NAME

rmhypervisor - Remove the virtualization hosts.

SYNOPSIS

RHEV specific :

rmhypervisor nodename [-f]

DESCRIPTION

The rmhypervisor command can be used to remove the virtualization host.

OPTIONS

-f

If -f is specified, the host will be deactivated to maintenance before the removing.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.
EXAMPLES

1. To remove the host ‘host1’, enter:
   
   `rmhypervisor host1`

FILES

/opt/xcat/bin/rmhypervisor

rmigrate.1

Name

rmigrate - Execute migration of a guest VM between hosts/hypervisors

Synopsis

`rmigrate noderange target_host`

For zVM:

`rmigrate noderange [destination=target_host] [action=action] [force=force] [immediate=yes_no] [max_total=total] [max_quiesce=quiesce]`

Description

`rmigrate` requests that a guest VM to be moved from the current hypervisor to another. It will request a live migration if possible. The vmstorage directory should be shared between the source and destination hypervisors.

Note: Make sure SELINUX is disabled and firewall is turned off on source and destination hypervisors.

For zVM:

`rmigrate` migrates a VM from one z/VM member to another in an SSI cluster (only in z/VM 6.2).

OPTIONS

zVM specific:

`destination=` The name of the destination z/VM system to which the specified virtual machine will be relocated.

`action=` It can be: (MOVE) initiate a VMRELOCATE MOVE of the VM, (TEST) determine if VM is eligible to be relocated, or (CANCEL) stop the relocation of VM.

`force=` It can be: (ARCHITECTURE) attempt relocation even though hardware architecture facilities or CP features are not available on destination system, (DOMAIN) attempt relocation even though VM would be moved outside of its
domain, or (STORAGE) relocation should proceed even if CP determines that there are insufficient storage resources on destination system.

**immediate**= It can be: (YES) VMRELOCATE command will do one early pass through virtual machine storage and then go directly to the quiesce stage, or (NO) specifies immediate processing.

**max_total**= The maximum wait time for relocation to complete.

**max_quiesce**= The maximum quiesce time a VM may be stopped during a relocation attempt.

**Files**

**vm** table - Table governing VM parameters. See vm(5)/vm.5 for further details. This is used to determine the current host to migrate from.

**Examples**

1. To migrate kvm guest “kvm1” from hypervisor “hyp01” to hypervisor “hyp02”, run:

```bash
r migrate kvm1 hyp02
```

2. To migrate kvm guest “kvm1” to hypervisor “hyp02”, which is already on host “hyp02”, enter:

```bash
r migrate kvm1 hyp02
```

**zVM specific:**

```bash
r migrate ihost123 destination=pokdev62
```

**rmimage.1**

**NAME**

**rmimage** - Removes the Linux stateless or statelite image from the file system.

**SYNOPSIS**

```
rimage [-h | --help]
rimage [-V | --verbose] imagename [--xcatdef]
```

**DESCRIPTION**

Removes the Linux stateless or statelite image from the file system. The install dir is setup by using “installdir” attribute set in the site table.

If *imagename* is specified, this command uses the information in the *imagename* to calculate the image root directory; otherwise, this command uses the operating system name, architecture and profile name to calculate the image root directory.
The osimage definition will not be removed from the xCAT tables by default, specifying the flag --xcatdef will remove the osimage definition, or you can use rmdef -t osimage to remove the osimage definition.

The statelite image files on the diskful service nodes will not be removed, remove the image files on the service nodes manually if necessary, for example, use command “rsync -az –delete /install <sn>:/” to remove the image files on the service nodes, where the <sn> is the hostname of the service node.

Parameters

imgname specifies the name of an os image definition to be used. The specification for the image is stored in the osimage table and linuximage table.

OPTIONS

-h | --help Display usage message.
-V | --verbose Verbose mode.
--xcatdef Remove the xCAT osimage definition

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To remove a RHEL 7.1 stateless image for a compute node architecture x86_64, enter:

```bash
rmimage rhels7.1-x86_64-netboot-compute
```

2. To remove a rhels5.5 statelite image for a compute node architecture ppc64 and the osimage definition, enter:

```bash
rmimage rhels5.5-ppc64-statelite-compute --xcatdef
```

FILES

/opt/xcat/sbin/rmimage

NOTES

This command is part of the xCAT software product.

SEE ALSO

genimage(1)|genimage.1, packimage(1)|packimage.1
NAME

rmkit - Remove Kits from xCAT

SYNOPSIS

rmkit [-? | -h | --help] [-v | --version]
rmkit [-V | --verbose] [-f | --force] [-t | --test] kitlist

DESCRIPTION

The rmkit command removes kits on the xCAT management node from kit names.
Note: The xCAT support for Kits is only available for Linux operating systems.

OPTIONS

-?|--help
   Display usage message.

-V|--verbose
   Verbose mode.

-v|--version
   Command version.

-f|--force
   Remove this kit even there is any component in this kit is listed by osimage.kitcomponents. If this option
   is not specified, this kit will not be removed if any kit components listed in an osimage.kitcomponents

-t|--test
   Test if kitcomponents in this kit are used by osimage

kitlist
   A comma delimited list of kits that are to be removed from the xCAT cluster. Each entry can be a kitname
   or kit basename. For kit basename, rmkit command will remove all the kits that have that kit basename.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.
EXAMPLES

1. To remove two kits from tarball files.

   \texttt{rmkit kit-test1,kit-test2}

   Output is similar to:

   \texttt{Kit kit-test1-1.0-Linux,kit-test2-1.0-Linux was successfully removed.}

2. To remove two kits from tarball files even the kit components in them are still being used by osimages.

   \texttt{rmkit kit-test1,kit-test2 --force}

   Output is similar to:

   \texttt{Kit kit-test1-1.0-Linux,kit-test2-1.0-Linux was successfully removed.}

3. To list kitcomponents in this kit used by osimage

   \texttt{rmkit kit-test1,kit-test2 -t}

   Output is similar to:

   \texttt{kit-test1-kitcomp-1.0-Linux is being used by osimage osimage-test}

   Following kitcomponents are in \textit{use}: kit-test1-kitcomp-1.0-Linux

SEE ALSO

\texttt{lskit(1)|lskit.1}, \texttt{addkit(1)|addkit.1}, \texttt{addkitcomp(1)|addkitcomp.1}, \texttt{rmkitcomp(1)|rmkitcomp.1}, \texttt{chkkitcomp(1)|chkkitcomp.1}

\texttt{rmkitcomp.1}

NAME

\texttt{rmkitcomp} - Remove Kit components from an xCAT osimage.

SYNOPSIS

\texttt{rmkitcomp [-? | -h | --help] [-v | --version]}

\texttt{rmkitcomp [-V | --verbose] [-u | --uninstall] [-f | --force] [--noscripts] -i osimage kitcompname_list}

DESCRIPTION

The \texttt{rmkitcomp} command removes kit components from an xCAT osimage. All the kit component attribute values that are contained in the osimage will be removed, and the kit component meta rpm and package rpm could be uninstalled by \texttt{-u|--uninstall} option.

Note: The xCAT support for Kits is only available for Linux operating systems.
OPTIONS

-ul--uninstall
   All the kit component meta rpms and package rpms in otherpkglist will be uninstalled during genimage for stateless image and updatenode for stateful nodes.

-hl--help
   Display usage message.

-Vl--verbose
   Verbose mode.

-Vl--version
   Command version.

-fl--force
   Remove this kit component from osimage no matter it is a dependency of other kit components.

--noscripts
   Do not remove kitcomponent’s postbootscripts from osimage

-i osimage
   osimage name that include this kit component.

kitcompname_list
   A comma-delimited list of valid full kit component names or kit component basenames that are to be removed from the osimage. If a basename is specified, all kitcomponents matching that basename will be removed from the osimage.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To remove a kit component from osimage

   
   |   rmkitcomp -i rhels6.2-ppc64-netboot-compute comp-test1-1.0-1-rhel6.2-ppc64
   |

   Output is similar to:

   |   kitcomponents comp-test1-1.0-1-rhel6.2-ppc64 were removed from osimage rhels6.2-ppc64-netboot-compute successfully
   |

2. To remove a kit component even it is still used as a dependency of other kit component.

   
   |   rmkitcomp -f -i rhels6.2-ppc64-netboot-compute comp-test1-1.0-1-rhel6.2-ppc64
   |

   Output is similar to:
kitcomponents comp-test1-1.0-1-rhel6.2-ppc64 were removed from osimage rhel6.2-ppc64-netboot-compute successfully

3. To remove a kit component from osimage and also remove the kit component meta RPM and package RPM. So in next genimage for stateless image and updatenode for stateful nodes, the kit component meta RPM and package RPM will be uninstalled.

rmkitcomp -u -i rhel6.2-ppc64-netboot-compute comp-test1-1.0-1-rhel6.2-ppc64

Output is similar to:

kitcomponents comp-test1-1.0-1-rhel6.2-ppc64 were removed from osimage rhel6.2-ppc64-netboot-compute successfully

SEE ALSO

lskit(1)|lskit.1, addkit(1)|addkit.1, rmkit(1)|rmkit.1, addkitcomp(1)|addkitcomp.1, chkkitcomp(1)|chkkitcomp.1

rmnimimage.1

NAME

rmnimimage - Use this xCAT command to remove NIM resources specified in an xCAT osimage definition.

SYNOPSIS

rmnimimage [-h|--help]

DESCRIPTION

Use this xCAT command to remove the AIX resources specified in an xCAT osimage definition.

To list the contents of the xCAT osimage definition use the xCAT lsdef command (“lsdef -t osimage -l -o <osimage_name>”). Before running the rmnimimage command you should be absolutely certain that you really want to remove the NIM resources specified in the xCAT osimage definition!

The default behavior of this command is to remove all the NIM resources, except the lpp_source, on the xCAT management node in addition to the resources that were replicated on any xCAT service nodes.

This command may also be used to clean up individual xCAT service nodes and remove the xCAT osimage definitions.

The “nim -o remove” operation is used to remove the NIM resource definitions. If you wish to completely remove all the files and directories (left behind by the NIM command) you must specify the “-d” option when you run rmnimimage. The “-d” option will also remove the lpp_source resource.

If you wish to remove the NIM resource from one or more xCAT service nodes without removing the resources from the management node you can use the “-s <servicenoderange>” option. In this case the NIM resources specified in the xCAT osimage definition will be removed from the service nodes ONLY. The NIM resources on the management node will not be removed.
If you wish to remove NIM resources on the management node only, you can specify the “-M” option.

If you wish to also remove the xCAT osimage definition you must specify the “-x” option.

This command will not remove NIM resources if they are currently being used in another xCAT osimage definition. To see which resources are common between osimages you can specify the “-V” option. You can override this check by specifying the “-f” option.

This command will not remove NIM resources if they are currently allocated. You must deallocate the resources before they can be removed. See the `xcat2nim` and `rmdsklsnode` commands for information on how to deallocate and remove NIM machine definitions for standalone and diskless nodes.

See the AIX NIM documentation for additional details on how to deallocate and remove unwanted NIM objects.

**OPTIONS**

- **-h | --help**
  Display usage message.

- **-d|--delete**
  Delete any files or directories that were left after the “nim -o remove” command was run. This option will also remove the lpp_source resouce and all files contained in the lpp_source directories. When this command completes all definitions and files will be completely erased so use with caution!

- **-f|--force**
  Override the check for shared resources when removing an xCAT osimage.

- **-M|--managementnode**
  Remove NIM resources from the xCAT management node only.

- **-s servicenoderange**
  Remove the NIM resources on these xCAT service nodes only. Do not remove the NIM resources from the xCAT management node.

- **osimage_name**
  The name of the xCAT osimage definition.

- **-V|--verbose**
  Verbose mode. This option will display the underlying NIM commands that are being called.

- **-x|--xcatdef**
  Remove the xCAT osimage definition.

**RETURN VALUE**

0 The command completed successfully.

1 An error has occurred.
EXAMPLES

1. Remove all NIM resources specified in the xCAT “61image” definition.

   ```bash
rmmnimimage 61image
   ```

   The “nim -o remove” operation will be used to remove the NIM resource definitions on the management node as well as any service nodes where the resource has been replicated. This NIM operation does not completely remove all files and directories associated with the NIM resources.

2. Remove all the NIM resources specified by the xCAT “61rte” osimage definition. Delete ALL files and directories associated with the NIM resources. This will also remove the lpp_source resource.

   ```bash
rmmnimimage -d 61rte
   ```

3. Remove all the NIM resources specified by the xCAT “614img” osimage definition and also remove the xCAT definition.

   ```bash
rmmnimimage -x -d 614img
   ```

   Note: When this command completes all definitions and files will be completely erased, so use with caution!

4. Remove the NIM resources specified in the “614dskls” osimage definition on the xcatsn1 and xcatsn2 service nodes. Delete all files or directories associated with the NIM resources.

   ```bash
rmmnimimage -d -s xcatsn1,xcatsn2 614dskls
   ```

5. Remove the NIM resources specified in the “614old” osimage definition on the xCAT management node only.

   ```bash
rmmnimimage -M -d 614old
   ```

FILES

```
/opt/xcat/bin/rmmnimimage
```

NOTES

This command is part of the xCAT software product.

SEE ALSO

mknimimage(1)|mknimimage.1

rmvlan.1

NAME

rmvlan - It removes the vlan from the cluster.
SYNOPSIS

rmvlan vlanid
rmvlan [-h | --help]
r vlan [-v | --version]

DESCRIPTION

The rmvlan command removes the given vlan ID from the cluster. It removes the vlan id from all the switches involved, deconfigures the nodes so that vlan adaptor (tag) will be removed, cleans up /etc/hosts, DNS and database tables for the given vlan.

For added security, the root guard and bpdu guard were enabled for the ports in this vlan by mkvlan and chvlan commands. However, the guards will not be disabled by this command. To disable them, you need to use the switch command line interface. Refer to the switch command line interface manual to see how to disable the root guard and bpdu guard for a port.

Parameters

vlanid is a unique vlan number.

OPTIONS

-h | --help Display usage message.
-v | --version The Command Version.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To remove vlan 3

   rmvlan 3

   If the nodes are KVM guest then the do the following after the vlan is removed:  
      rpower node1,node2  off
      rmvm node1,node2

FILES

/opt/xcat/bin/rmvlan
SEE ALSO

mkvlan(1)|mkvlan.1, chvlan(1)|chvlan.1, lsvlan(1)|lsvlan.1

rmvm.1

NAME

rmvm - Removes HMC-, DFM-, IVM-, KVM-, VMware- and zVM-managed partitions or virtual machines.

SYNOPSIS

rmvm [-h|--help]
rmvm [-v|--version]
rmvm [-V|--verbose]
noderange

For KVM and VMware:

rmvm [-p] [-f] noderange

PPC (using Direct FSP Management) specific:

rmvm [-p] noderange

DESCRIPTION

The rmvm command removes the partitions specified in noderange. If noderange is an CEC, all the partitions associated with that CEC will be removed. Note that removed partitions are automatically removed from the xCAT database. For IVM-managed systems, care must be taken to not remove the VIOS partition, or all the associated partitions will be removed as well.

For DFM-managed (short For Direct FSP Management mode) normal power machines, only partitions can be removed. No options is needed.

OPTIONS

-h|--help Display usage message.
-v|--version Command Version.
-V|--verbose Verbose output.
-r Retain the data object definitions of the nodes.
--service Remove the service partitions of the specified CECs.
-p KVM: Purge the existence of the VM from persistent storage. This will erase all storage related to the VM in addition to removing it from the active virtualization configuration. PPC: Remove the specified partition on normal power machine.
-f Force remove the VM, even if the VM appears to be online. This will bring down a live VM if requested.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.

**EXAMPLES**

1. To remove the HMC-managed partition lpar3, enter:

   ```bash
rmmvm lpar3
   ```

   Output is similar to:

   ```bash
   lpar3: Success
   ```

2. To remove all the HMC-managed partitions associated with CEC cec01, enter:

   ```bash
rmmvm cec01
   ```

   Output is similar to:

   ```bash
   lpar1: Success
   lpar2: Success
   lpar3: Success
   ```

3. To remove the HMC-managed service partitions of the specified CEC cec01 and cec02, enter:

   ```bash
rmmvm cec01,cec02 --service
   ```

   Output is similar to:

   ```bash
   cec01: Success
   cec02: Success
   ```

4. To remove the HMC-managed partition lpar1, but retain its definition, enter:

   ```bash
rmmvm lpar1 -r
   ```

   Output is similar to:

   ```bash
   lpar1: Success
   ```

5. To remove a zVM virtual machine:

   ```bash
rmmvm gpok4
   ```

   Output is similar to:

   ```bash
   gpok4: Deleting virtual server LNX4... Done
   ```

6. To remove a DFM-managed partition on normal power machine:
rmvm lpar1

Output is similar to:

lpar1: Done

FILES

/opt/xcat/bin/rmvm

SEE ALSO

mkvm(1)|mkvm.1, lsvm(1)|lsvm.1, chvm(1)|chvm.1

rmzone.1

NAME

rmzone - Removes a zone from the cluster.

SYNOPSIS

rmzone
zonename

\[-g\] \[-f\] 

rmzone \[-h\] \[-v\]

DESCRIPTION

The rmzone command is designed to remove a previously defined zone from the cluster. It will remove the zone entry in the zone table. It will remove the zone from the zonename attributes on the nodes that were assigned to the zone. Optionally, it will remove the zonename group from the nodes that were assigned to the zone. It will also remove the root ssh keys that were created for that zone on the Management Node. The rmzone command is only supported on Linux ( No AIX support). The nodes are not automatically updated with new root ssh keys by rmzone. You must run updatenode -k or xdsh -K to the nodes to update the root ssh keys. The nodes new ssh key will be assigned from the defaultzone in the zone table, or if no entries in the zone table, the keys will come from /root/ssh. Note: if any zones in the zone table, there must be one and only one defaultzone. Otherwise, errors will occur.

OPTIONS

\[-h\] \|--help

Displays usage information.

\[-v\] \|--version

Displays command version and build date.

\[-f\] \|--force
Used to remove a zone that is defined as current default zone. This should only be done if you are removing all zones, or you will adding a new zone or changing an existing zone to be the default zone.

-g | --assigngroup
Remove the assigned group named zonename from all nodes assigned to the zone being removed.

-V | --verbose
Verbose mode.

Examples

1. To remove zone1 from the zone table and the zonename attribute on all it's assigned nodes, enter:

   rmzone zonename

2. To remove zone2 from the zone table, the zone2 zonename attribute, and the zone2 group assigned to all nodes that were in zone2, enter:

   rmzone zone2 -g

3. To remove zone3 from the zone table, all the node zone attributes and override the fact it is the defaultzone, enter:

   rmzone zone3 -g -f

Files

/opt/xcat/bin/rmzone/
Location of the rmzone command.

SEE ALSO

mkzone(1)|mkzone.1, chzone(1)|chzone.1, xdsh(1)|xdsh.1, updatenode(1)|updatenode.1

rnetboot.1

NAME

rnetboot - Cause the range of nodes to boot to network.

SYNOPSIS

rnetboot [-V | --verbose] [-s boot_device_order] [-F] [-f] noderange [-m table.column==expectedstatus [-m table.column=~expectedstatus]] [-t timeout] [-r retrycount]
rnetboot [-h | --help] [-v | --version]

zVM specific:

rnetboot noderange [ipl= address]
DESCRIPTION

The rnetboot command will do what is necessary to make each type of node in the given noderange boot from the network. This is usually used to boot the nodes stateless or to network install system p nodes.

OPTIONS

-s
Set the boot device order. Accepted boot devices are hd and net.

-F
Force reboot the system no matter what state the node is. By default, rnetboot will not reboot the node if node is in ‘boot’ state.

-f
Force immediate shutdown of the partition.

-m
Use one or multiple -m flags to specify the node attributes and the expected status for the node installation monitoring and automatic retry mechanism. The operators ==, !=, =~ and !~ are valid. This flag must be used with -t flag.

Note: if the “val” fields includes spaces or any other characters that will be parsed by shell, the “attr<oper-ator>val” needs to be quoted. If the operator is “!~”, the “attr<operator>val” needs to be quoted using single quote.

-r
specify the number of retries that the monitoring process will perform before declaring the failure. The default value is 3. Setting the retrycount to 0 means only monitoring the os installation progress and will not re-initiate the installation if the node status has not been changed to the expected value after timeout. This flag must be used with -m flag.

-t
Specify the timeout, in minutes, to wait for the expectedstatus specified by -m flag. This is a required flag if the -m flag is specified.

-V|--verbose
Verbose output.

-h|--help
Display usage message.

-v|--version
Command Version.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.
EXAMPLES

rnetboot 1,3
rnetboot 14-56,70-203
rnetboot 1,3,14-56,70-203
rnetboot all,-129-256
rnetboot all -s hd,net
rnetboot all ipl=00c

SEE ALSO

nodeset(8)|nodeset.8
rollupdate.1

NAME

rollupdate - performs cluster rolling update

SYNOPSIS

cat stanza-file | rollupdate [-V | --verbose] [-t | --test]
rollupdate [-? | -h | --help | -v | --version]

DESCRIPTION

The rollupdate command creates and submits scheduler reservation jobs that will notify xCAT to shutdown a group of nodes, run optional out-of-band commands from the xCAT management node, and reboot the nodes. Currently, only LoadLeveler is supported as a job scheduler with rollupdate.

Input to the rollupdate command is passed in as stanza data through STDIN. Information such as the sets of nodes that will be updated, the name of the job scheduler, a template for generating job command files, and other control data are required. See /opt/xcat/share/xcat/rollupdate/rollupdate.input.sample and /opt/xcat/share/xcat/rollupdate/rollupdate_all.input.sample for stanza keywords, usage, and examples.

The rollupdate command will use the input data to determine each set of nodes that will be managed together as an update group. For each update group, a job scheduler command file is created and a reservation request is submitted. When the group of nodes becomes available and the scheduler activates the reservation, the xcatd daemon on the management node will be notified to begin the update process for all the nodes in the update group. If specified, prescripts will be run, an operating system shutdown command will be sent to each node, out-of-band operations can be run on the management node, and the nodes are powered back on.

The rollupdate command assumes that, if the update is to include rebooting stateless or statelite nodes to a new operating system image, the image has been created and tested, and that all relevant xCAT commands have been run for the nodes such that the new image will be loaded when xCAT reboots the nodes.
OPTIONS

- -v|--version
    Command Version.

- -V|--verbose
    Display additional progress and error messages. Output is also logged in /var/log/xcat/rollupdate.log.

- -t|--test
    Run the rollupdate command in test mode only to verify the output files that are created. No scheduler reservation requests will be submitted.

- -?|-h|--help
    Display usage message.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To run a cluster rolling update based on the information you have created in the file /u/admin/rolling_updates/update_all.stanza enter:

   cat /u/admin/rolling_updates/update_all.stanza | rollupdate

FILES

/opt/xcat/bin/rollupdate
/opt/xcat/share/xcat/rollupdate/rollupdate.input.sample
/opt/xcat/share/xcat/rollupdate/ll.tmpl
/opt/xcat/share/xcat/rollupdate/rollupdate_all.input.sample
/opt/xcat/share/xcat/rollupdate/llall.tmpl
/var/log/xcat/rollupdate.log

SEE ALSO

rpower.1

NAME

rpower - remote power control of nodes
SYNOPSIS

```
rpower noderange [-nodeps] [on | onstandby | off | suspend | stat | state | reset | boot] [-m table.column==expectedstatus [-m table.column=~expectedstatus]] [-t timeout] [-r retrycount]
rpower [-h | --help | -v | --version]

BMC (using IPMI):

rpower noderange [on | off | softoff | reset | boot | cycle | stat | state | status | wake | suspend [-w timeout] [-o] [-r]]
rpower noderange [pduon | pduoff | pdustat | pdureset]

OpenPOWER BMC (using IPMI):

rpower noderange [on | off | reset | boot | state | status]
rpower noderange [pduon | pduoff | pdustat | pdureset]

OpenPOWER OpenBMC:

rpower noderange [off | on | softoff | reset | boot | bmcreboot | bmcstate | stat | state | status]

PPC (with IVM or HMC) specific:

rpower noderange [--nodeps] [of]

CEC (with HMC) specific:

rpower noderange [on | off | reset | boot | onstandby]

LPAR (with HMC) specific:

rpower noderange [on | off | stat | state | reset | boot | of | sms | softoff]

CEC (using Direct FSP Management) specific:

rpower noderange [onstandby | stat | state] [-T tooltype]
rpower noderange [on | off | resetsp]

Frame (using Direct FSP Management) specific:

rpower noderange [rackstandby | exit_rackstandby | stat | state | resetsp]
```
LPAR (using Direct FSP Management) specific:

```
rpower noderange [on | off | stat | state | reset | boot | of | sms]
```

Blade (using Direct FSP Management) specific:

```
rpower noderange [on | onstandby | off | stat | state | sms]
```

Blade specific:

```
rpower noderange [cycle | softoff]
```

Lenovo High-Density Server specific:

```
rpower noderange [on | off | reset | boot | reseat]
```

zVM specific:

```
rpower noderange [on | off | reset | stat | softoff]
```

docker specific:

```
rpower noderange [start | stop | restart | pause | unpause | state]
```

pdu specific:

```
rpower noderange [stat | off | on | reset]
```

DESCRIPTION

`rpower` controls the power for a single or range of nodes, via the out-of-band path.

OPTIONS

- **on**
  
  Turn power on.

- **onstandby**
  
  Turn power on to standby state

- **-T**
  
  The value could be `lpar` or `fnm`. The tooltype value `lpar` is for xCAT and `fnm` is for CNM. The default value is “lpar”. For cold start in the large cluster, it will save a lot of time if the admins use “`rpower noderange onstandby -T fnm`” to power on all the CECs from the management node through the `fnm` connections.
rackstandby

Places the rack in the rack standby state. It requires that all CECs and DE be powered off before it will run.

exit_rackstandby

Exit Rack standby will be the default state that a rack goes into when power is initially applied to the rack. It simply moves the BPA from Rack standby to both bpa’s in standby state.

resetsp

Reboot the service processor. If there are primary and secondary FSPs/BPAs of one cec/frame, it will reboot them almost at the same time.

softoff

Attempt to request clean shutdown of OS (may not detect failures in completing command)

off

Turn power off.

suspend

Suspend the target nodes execution.

The suspend action could be run together with -w -o -r.

Refer to the following steps to enable the suspend function:

1. Add the ‘acpid’ and ‘suspend’ (the suspend package is not needed on RHEL) package to the .pkglist of your osimage so that the required package could be installed correctly to your target system.

2. Add two configuration files for the base function:

   ```
   /etc/pm/config.d/suspend
   S2RAM_OPTS="--force --vbe_save --vbe_post --vbe_mode"
   
   /etc/acpi/events/suspend_event
   event=button/sleep.*
   action=/usr/sbin/pm-suspend
   ```

3. Add the hook files for your specific applications which need specific action before or after the suspend action.

   Refer to the ‘pm-utils’ package for how to create the specific hook files.

wake

Wake up the target nodes which is in suspend state.

Don’t try to run wake against the ‘on’ state node, it would cause the node gets to ‘off’ state.

For some of xCAT hardware such as NeXtScale, it may need to enable S3 before using wake. The following steps can be used to enable S3. Reference pasu(1)/pasu.1 for “pasu” usage.

```
[root@xcatmn home]# echo "set Power.S3Enable Enable" > power-setting
[root@xcatmn home]# pasu -b power-setting node01
node01: Batch mode start.
node01: [set Power.S3Enable Enable]
node01: Power.S3Enable=Enable
node01: node01: Beginning intermediate batch update.
node01: Waiting for command completion status.
```
node01: Command completed successfully.
node01: Completed intermediate batch update.
node01: Batch mode completed successfully.

[root@xcatmn home] # pasu node01 show all | grep -i s3
node01: IMM.Community_HostIPAddress3.1=
node01: IMM.Community_HostIPAddress3.2=
node01: IMM.Community_HostIPAddress3.3=
node01: IMM.DNS_IP_Address3=0.0.0.0
node01: IMM.IPv6DNS_IP_Address3=::
node01: Power.S3Enable=Enable

stat | state
Print the current power state/status.

reset
Send a hard reset.

boot
If off, then power on. If on, then hard reset. This option is recommended over cycle.

cycle
Power off, then on.

reseat
For Lenovo high-density servers, simulates unplugging and replugging the node into the chassis.

of
Boot the node to open firmware console mode.

sms
Boot the node to open firmware SMS menu mode.

-m table.column==expectedstatus -m table.column!=expectedstatus
Use one or multiple -m flags to specify the node attributes and the expected status for the node installation monitoring and automatic retry mechanism. The operators ==, !=, = and != are valid. This flag must be used with -t flag.

Note: if the “val” fields includes spaces or any other characters that will be parsed by shell, the “attr<operator>val” needs to be quoted. If the operator is “!~”, the “attr<operator>val” needs to be quoted using single quote.

--nodeps
Do not use dependency table (default is to use dependency table). Valid only with on|off|boot|reset|cycle for blade power method and on|off|softoff for hmc/fsp power method.

-r retrycount
specify the number of retries that the monitoring process will perform before declaring the failure. The default value is 3. Setting the retrycount to 0 means only monitoring the os installation progress and will not re-initiate the installation if the node status has not been changed to the expected value after timeout. This flag must be used with -m flag.

-t timeout
Specify the timeout, in minutes, to wait for the expected status specified by -m flag. This is a required flag if the -m flag is specified.

Power off, then on.

-w timeout

To set the timeout for the suspend action to wait for the success.

-o

To specify that the target node will be power down if suspend action failed.

-r

To specify that the target node will be reset if suspend action failed.

start

To start a created docker instance.

stop

To stop a created docker instance.

restart

To restart a created docker instance.

pause

To pause all processes in the instance.

unpause

To unpause all processes in the instance.

bmcreboot

To reboot BMC.

bmcstate

To get state of the BMC.

state

To get state of the instance.

-h | --help

Prints out a brief usage message.

-v | --version

Display the version number.

EXAMPLES

1. To display power status of nodes4 and note5

   rpower node4,node5 stat

Output is similar to:

   node4: on
   node5: off
2. To power on node5

```
rpower node5 on
```

Output is similar to:

```
node5: on
```

**SEE ALSO**

noderange(3) noderange.3, rcons(1) rcons.1, rinv(1) rinv.1, rvitals(1) rvitals.1, rscan(1) rscan.1

**rscan.1**

**NAME**

`rscan` - Collects node information from one or more hardware control points.

**SYNOPSIS**

```
rscan [-h|--help]
rscan [-v|--version]
rscan [-V|--verbose]
rscan [-V|--verbose] noderange [-u][-w][-z]
```

**DESCRIPTION**

The `rscan` command lists hardware information for each node managed by the hardware control points specified in noderange.

For the management module of blade, if the blade server is a Flex system P node, the fsp belongs to the blade server also will be scanned.

For the KVM host, all the KVM guests on the specified KVM host will be scanned.

Note: The first line of the output always contains information about the hardware control point. When using the rscan command to generate output for HMC or IVM hardware control points, it provides the FSPs and BPAs as part of the output. The only exception is the rscan -u flag which provides updates made hardware control point in the xCAT database.

**OPTIONS**

- **-h|--help** Display usage message.
- **-v|--version** Command Version.
- **-V|--verbose** Verbose output.
- **-u** Updates and then prints out node definitions in the xCAT database for CEC/BPA. It updates the existing nodes that contain the same mtms and serial number for nodes managed by the specified hardware control point. This primarily works with CEC/FSP and frame/BPA nodes when the node name is not the same as the managed system name on
hardware control point (HMC). This flag will update the BPA/FSP node name definitions to be listed as the managed system name in the xCAT database.

For the Flex system manager, both the blade server and fsp object of xCAT will be updated if the mpa and slot id are matched to the object which has been defined in the xCAT database.

For KVM host, the information of the KVM guests which have been defined in xCAT database will be updated.

Note: only the matched object will be updated.

-\texttt{f} For KVM host, the information of the KVM guests, which are not defined in xCAT database yet, will be written into xCAT database.

-\texttt{w} Writes output to xCAT database.

For KVM host, updates the information of the KVM guests which have been defined in xCAT database with the same node name and KVM host, creates the definition of the KVM guests which do not exist in xCAT database, and notifies user about the conflicting KVM guests that the name exist in xCAT database but the kvm host is different.

-\texttt{x} XML format.

-\texttt{z} Stanza formated output.

Note: For KVM host, -\texttt{z} is not a valid option for rscan.

**RETURN VALUE**

0 The command completed successfully.

1 An error has occurred.

**EXAMPLES**

1. To list all nodes managed by HMC hmc01 in tabular format, enter:

   \texttt{rscan hmc01}

   Output is similar to:

<table>
<thead>
<tr>
<th>type</th>
<th>name</th>
<th>id</th>
<th>type-model</th>
<th>serial-number</th>
<th>address</th>
</tr>
</thead>
<tbody>
<tr>
<td>hmc</td>
<td>hmc01</td>
<td>7310-C05</td>
<td>10F426A</td>
<td>hmc01</td>
<td></td>
</tr>
<tr>
<td>fsp</td>
<td>Server-9117-MMA-SN10F6F3D</td>
<td>9117-MMA</td>
<td>10F6F3D</td>
<td>3.3.3.197</td>
<td></td>
</tr>
<tr>
<td>lpar</td>
<td>lpar3</td>
<td>4</td>
<td>9117-MMA</td>
<td>10F6F3D</td>
<td></td>
</tr>
<tr>
<td>lpar</td>
<td>lpar2</td>
<td>3</td>
<td>9117-MMA</td>
<td>10F6F3D</td>
<td></td>
</tr>
<tr>
<td>lpar</td>
<td>lpar1</td>
<td>2</td>
<td>9117-MMA</td>
<td>10F6F3D</td>
<td></td>
</tr>
<tr>
<td>lpar</td>
<td>p6vios</td>
<td>1</td>
<td>9117-MMA</td>
<td>10F6F3D</td>
<td></td>
</tr>
</tbody>
</table>

2. To list all nodes managed by IVM ivm02 in XML format and write the output to the xCAT database, enter:

   \texttt{rscan ivm02 -x -w}

   Output is similar to:

   (continues on next page)
3. To list all nodes managed by HMC hmc02 in stanza format and write the output to the xCAT database, enter:

   rscan hmc02 -z -w

Output is similar to:

Server-9458-100992001Y_B:
   objtype=node
   nodetype=bpa
   id=2
   model=9458-100
   serial=992001Y
   hcp=hmc02
   profile=
   parent=
   groups=bpa,all
   mgt=hmc
   cons=

(continues on next page)
4. To update definitions of nodes, which is managed by hmc03, enter:

```
rscan hmc03 -u
```

Output is similar to:

```
#Updated following nodes:
 type name id type-model serial-number address
fsp Server-9125-F2A-SN0262672-B 3 9125-F2A 0262672 192.168.200.243
```

5. To collects the node information from one or more hardware control points on zVM AND populate the database with details collected by rscan:

```
rscan gpok2 -w
```

Output is similar to:
6. To scan the Flex system cluster:

```
rscan cmm01
```

Output is similar to:

```
<table>
<thead>
<tr>
<th>type</th>
<th>name</th>
<th>id</th>
<th>type-model</th>
<th>serial-number</th>
<th>mpa</th>
<th>address</th>
</tr>
</thead>
<tbody>
<tr>
<td>cmm</td>
<td>AMM680520153</td>
<td>0</td>
<td>789392X</td>
<td>100048A</td>
<td>cmm01</td>
<td>cmm01</td>
</tr>
<tr>
<td>blade</td>
<td>SN#YL10JH184067</td>
<td>1</td>
<td>789542X</td>
<td>10F752A</td>
<td>cmm01</td>
<td>12.0.0.9</td>
</tr>
<tr>
<td>xblade</td>
<td>SN#YL10JH184068</td>
<td>2</td>
<td>789542X</td>
<td>10F652A</td>
<td>cmm01</td>
<td>12.0.0.10</td>
</tr>
<tr>
<td>blade</td>
<td>SN#YL10JH184079</td>
<td>3</td>
<td>789542X</td>
<td>10F697A</td>
<td>cmm01</td>
<td>12.0.0.11</td>
</tr>
</tbody>
</table>
```

7. To update the Flex system cluster:

```
rscan cmm01 -u
```

Output is similar to:

```
cmm [AMM680520153] Matched To =>[cmm01]
blade [SN#YL10JH184067] Matched To =>[cmm01node01]
blade [SN#YL10JH184079] Matched To =>[cmm01node03]
```

8. To scan the KVM host “hyp01”, write the KVM guest information into xCAT database:

```
rscan hyp01 -w
```

9. To update definitions of kvm guest, which is managed by hypervisor hyp01, enter:

```
rscan hyp01 -u
```

Output is similar to:

```
<table>
<thead>
<tr>
<th>type</th>
<th>name</th>
<th>hypervisor</th>
<th>id</th>
<th>cpu</th>
<th>memory</th>
<th>nic</th>
<th>disk</th>
</tr>
</thead>
<tbody>
<tr>
<td>kvm</td>
<td>kvm2</td>
<td>hyp01</td>
<td>12</td>
<td>2</td>
<td>1024</td>
<td>virbr0</td>
<td>/install/vms/kvm2.hda.qcow2</td>
</tr>
<tr>
<td>kvm</td>
<td>kvm1</td>
<td>hyp01</td>
<td>10</td>
<td>1</td>
<td>1024</td>
<td>virbr0</td>
<td>/install/vms/kvm1.hda.qcow2</td>
</tr>
</tbody>
</table>
```

**FILES**

```
/opt/xcat/bin/rscan
```

---

**CAT3 Documentation, Release 2.14.5**

```
gpok2:
  objtype=node
  arch=s390x
  os=sles10sp3
  hcp=gpok3.endicott.ibm.com
  userid=LINUX2
  nodetype=vm
  parent=POKDEV61
  groups=all
  mgt=zvm
```
SEE ALSO

lsslp(1)|lsslp.1

rsetboot.1

SYNOPSIS

rsetboot noderange [hd | net | cd | default | stat] [-u] [-p]
rsetboot [-h | --help | -v | --version | -V | --verbose]

DESCRIPTION

rsetboot sets the boot media and boot mode that should be used on the next boot of the specified nodes. After the
nodes are booted with the specified device and boot mode (e.g. via rpower(1)|rpower.1), the nodes will return to using
the default boot device specified in the BIOS.

OPTIONS

hd

Boot from the hard disk.

net

Boot over the network, using a PXE or BOOTP broadcast.

cd

Boot from the CD or DVD drive.

def | default

Boot using the default set in BIOS.

stat

Display the current boot setting.

-u

To specify the next boot mode to be “UEFI Mode”. (Not supported for OpenBMC)

-p

To make the specified boot device and boot mode settings persistent.

EXAMPLES

1. Set nodes 1 and 3 to boot from the network on the next boot:

rsetboot node1,node3 net

2. Display the next-boot value for nodes 14-56 and 70-203:
rsetboot node[14-56],node[70-203] stat

Or:

rsetboot node[14-56],node[70-203]

3. Restore the next-boot value for these nodes back to their default set in the BIOS:

rsetboot node1,node3,node[14-56],node[70-203] default

SEE ALSO

rbootseq(1)|rbootseq.1

rspconfig.1

NAME

rspconfig - Configures nodes’ service processors

SYNOPSIS

rspconfig [-h | --help | -v | --version | -V | --verbose]

BMC/MPA specific:

rspconfig noderange { alert | snmpdest | community }
rspconfig noderange alert={on | enable | off | disable}
rspconfig noderange snmpdest=snmpmanager-IP
rspconfig noderange community={public | string}

BMC specific:

rspconfig noderange { ip | netmask | gateway | backupgateway | garp | vlan}
rspconfig noderange garp=time

OpenBMC specific:

rspconfig noderange { ipsrc | ip | netmask | gateway | vlan}
rspconfig noderange admin_passwd={currentpasswd,newpasswd}
rspconfig noderange autoreboot
rspconfig noderange autoreboot={0|1}
rspconfig noderange bootmode
rspsconfig noderange bootmode={safe|regular|setup}
rspsconfig noderange dump [-l | --list] [-g | --generate] [-c | --clear {id | all}] [-d | --download {id | all}]
rspsconfig noderange gard -c|--clear
rspsconfig noderange ip=dhcp
rspsconfig noderange hostname
rspsconfig noderange hostname={* | name}
rspsconfig noderange ntpservers
rspsconfig noderange ntpservers={ntpservers}
rspsconfig noderange powerrestorepolicy
rspsconfig noderange powerrestorepolicy={always_on|restore|always_off}
rspsconfig noderange powersupplyredundancy
rspsconfig noderange powersupplyredundancy={disabled|enabled}
rspsconfig noderange sshcfg
rspsconfig noderange timesyncmethod
rspsconfig noderange timesyncmethod={manual|ntp}

**MPA specific:**

rspsconfig noderange {sshcfg | snmpcfg | pd1 | pd2 | network | swnet | ntp | textid | frame}
rspsconfig noderange USERID={newpasswd} updateBMC={y | n}
rspsconfig noderange sshcfg={enable | disable}
rspsconfig noderange snmpcfg={enable | disable}
rspsconfig noderange solcfg={enable | disable}
rspsconfig noderange pd1={nonred | redwoperf | redwperf}
rspsconfig noderange pd2={nonred | redwoperf | redwperf}
rspsconfig noderange network={[*], host, gateway, netmask}]
rspsconfig noderange initnetwork={[*], host, gateway, netmask}]
rspsconfig noderange textid={* | textid}
rspsconfig singlenode frame={frame_number}
rspsconfig noderange frame={*}
rspsconfig noderange swnet={[*], gateway, netmask}]
rspsconfig noderange ntp={[*], ntpserver, [frequency], [v3]}

**FSP/CEC specific:**

rspsconfig noderange {autopower | iocap | decfg | memdecfg | procdecfg | time | date | spdump | sysdump | network}
rspsconfig noderange autopower={enable | disable}
rsconfignoderangeiocap={enable|disable}
rsconfignoderangetime=hh:mm:ss
rsconfignoderangedate=mm:dd:yyyy
rsconfignoderangedecfg={enable|disable:policyname,...}
rsconfignoderangeprocdecfg={configure|deconfigure:processingunit:id,...}
rsconfignoderangememdecfg={configure|deconfigure:processingunit:unit|bank:id,...}
rsconfignoderangenetwork={nic,*}
rsconfignoderangenetwork={nic,[IP],[hostname],[gateway],[netmask]}
rsconfignoderangenetwork={nic,0.0.0.0}
rsconfignoderangeHMC_passwd={currentpasswd,newpasswd}
rsconfignoderangeadmin_passwd={currentpasswd,newpasswd}
rsconfignoderangegeneral_passwd={currentpasswd,newpasswd}
rsconfignoderange*_passwd={currentpasswd,newpasswd}
rsconfignoderangehostname={*|name}
rsconfignoderange--resetnet

**Flex system Specific:**

rsconfignoderangesshcfg={enable|disable}
rsconfignoderangesnmpcfg={enable|disable}
rsconfignoderangenetwork={[ip],[host],[gateway],[netmask]|*}
rsconfignoderangesolcfg={enable|disable}
rsconfignoderangextextid={*|textid}
rsconfignoderangececoff_policy={poweroff|stayon}

**BPA/Frame Specific:**

rsconfignoderange{network}
rsconfignoderangenetwork={nic,*}
rsconfignoderangenetwork={nic,[IP],[hostname],[gateway],[netmask]}
rsconfignoderangenetwork={nic,0.0.0.0}
rsconfignoderangeHMC_passwd={currentpasswd,newpasswd}
rsconfignoderangeadmin_passwd={currentpasswd,newpasswd}
rsconfignoderangegeneral_passwd={currentpasswd,newpasswd}
rsconfignoderange*_passwd={currentpasswd,newpasswd}
rsconfignoderange{hostname}
rsppconfig noderange hostname={* | name}
rsppconfig noderange --resetnet

FSP/CEC (using Direct FSP Management) Specific:

rsppconfig noderange HMC_passwd={currentpasswd,newpasswd}
rsppconfig noderange admin_passwd={currentpasswd,newpasswd}
rsppconfig noderange general_passwd={currentpasswd,newpasswd}
rsppconfig noderange *_passwd={currentpasswd,newpasswd}
rsppconfig noderange {sysname}
rsppconfig noderange sysname={* | name}
rsppconfig noderange {pending_power_on_side}
rsppconfig noderange pending_power_on_side={temp | perm}
rsppconfig noderange {cec_off_policy}
rsppconfig noderange cec_off_policy={poweroff | stayon}
rsppconfig noderange {BSR}
rsppconfig noderange {huge_page}
rsppconfig noderange huge_page={NUM}
rsppconfig noderange {setup_failover}
rsppconfig noderange setup_failover={enable | disable}
rsppconfig noderange {force_failover}
rsppconfig noderange --resetnet

BPA/Frame (using Direct FSP Management) Specific:

rsppconfig noderange HMC_passwd={currentpasswd,newpasswd}
rsppconfig noderange admin_passwd={currentpasswd,newpasswd}
rsppconfig noderange general_passwd={currentpasswd,newpasswd}
rsppconfig noderange *_passwd={currentpasswd,newpasswd}
rsppconfig noderange {frame}
rsppconfig noderange frame={* | frame_number}
rsppconfig noderange {sysname}
rsppconfig noderange sysname={* | name}
rsppconfig noderange {pending_power_on_side}
rsppconfig noderange pending_power_on_side={temp | perm}
rsppconfig noderange --resetnet
HMC Specific:

```
rspconfig nodename {sshcfg}
rspconfig nodename sshcfg={enable | disable}
rspconfig nodename --resetnet
```

DESCRIPTION

rspconfig configures various settings in the nodes’ service processors.

For options autopower | iocap | decfg | memdecfg | procdecfg | time | date | spdump | sysdump | network, user need to use `chdef -t site enableASMI=yes` to enable ASMI first.

OPTIONS

```
alert={on | enable | off | disable}
    Turn on or off SNMP alerts.

autopause={enable | disable}
    Select the policy for auto power restart. If enabled, the system will boot automatically once power is restored after a power disturbance.

backupgateway
    Get the BMC backup gateway ip address.

community={public | string}
    Get or set the SNMP community value. The default is `public`.

date=mm:dd:yyyy
    Enter the current date.

decfg={enable | disable;policyname,…}
    Enables or disables deconfiguration policies.

frame={framenumber | *}
    Set or get frame number. If no framenumber and * specified, framenumber for the nodes will be displayed and updated in xCAT database. If framenumber is specified, it only supports single node and the framenumber will be set for that frame. If * is specified, it supports nodename and all the frame numbers for the nodename will be read from xCAT database and set to frames. Setting the frame number is a disruptive command which requires all CECs to be powered off prior to issuing the command.

cec_off_policy={poweroff | stayon}
    Set or get cec off policy after lpars are powered off. If no cec_off_policy value specified, the cec_off_policy for the nodes will be displayed. The cec_off_policy has two values: `poweroff` and `stayon`. `poweroff` means Power off when last partition powers off. `stayon` means Stay running after last partition powers off. If cec_off_policy value is specified, the cec off policy will be set for that cec.

HMC_passwd={currentpasswd,newpasswd}
    Change the password of the userid HMC for CEC/Frame. If the CEC/Frame is the factory default, the currentpasswd should NOT be specified; otherwise, the currentpasswd should be specified to the current password of the userid HMC for the CEC/Frame.
admin_passwd=\{currentpasswd,newpasswd\}

Change the password of the userid admin for CEC/Frame from currentpasswd to newpasswd. If the CEC/Frame is the factory default, the currentpasswd should NOT be specified; otherwise, the currentpasswd should be specified to the current password of the userid admin for the CEC/Frame.

general_passwd=\{currentpasswd,newpasswd\}

Change the password of the userid general for CEC/Frame from currentpasswd to newpasswd. If the CEC/Frame is the factory default, the currentpasswd should NOT be specified; otherwise, the currentpasswd should be specified to the current password of the userid general for the CEC/Frame.

*_passwd=\{currentpasswd,newpasswd\}

Change the passwords of the userids HMC, admin and general for CEC/Frame from currentpasswd to newpasswd. If the CEC/Frame is the factory default, the currentpasswd should NOT be specified; otherwise, if the current passwords of the userids HMC, admin and general for CEC/Frame are the same one, the currentpasswd should be specified to the current password, and then the password will be changed to the newpasswd. If the CEC/Frame is NOT the factory default, and the current passwords of the userids HMC, admin and general for CEC/Frame are NOT the same one, this option could NOT be used, and we should change the password one by one.

frequency

The NTP update frequency (in minutes).

gard -c|--clear

Clear gard file. [OpenBMC]

garp=time

Get or set Gratuitous ARP generation interval. The unit is number of 1/2 second.

gateway

The gateway ip address.

hostname

Display the CEC/BPA system names.

BSR

Get Barrier Synchronization Register (BSR) allocation for a CEC.

huge_page

Query huge page information or request NUM of huge pages for CEC. If no value specified, it means query huge page information for the specified CECs, if a CEC is specified, the specified huge_page value NUM will be used as the requested number of huge pages for the CEC, if CECs are specified, it means to request the same NUM huge pages for all the specified CECs.

setup_failover=\{enable | disable\}

Enable or disable the service processor failover function of a CEC or display status of this function.

force_failover

Force a service processor failover from the primary service processor to the secondary service processor.

hostname=\{* | name\}

Set CEC/BPA system names to the names in xCAT DB or the input name.

iocap=\{enable | disable\}
Select the policy for I/O Adapter Enlarged Capacity. This option controls the size of PCI memory space allocated to each PCI slot.

**hostname**
Get or set hostname on the service processor.

**vlan**
Get or set vlan ID. For get vlan ID, if vlan is not enabled, ‘BMC VLAN disabled’ will be displayed. For set vlan ID, the valid value are [1-4096].

**ipsrc**
Get the IP source for OpenBMC.

**ip**
The IP address.

**memdecfg**={configure | deconfigure; processingunit:unit|bank:id; . . .}
Select whether each memory bank should be enabled or disabled. State changes take effect on the next platform boot.

**netmask**
The subnet mask.

**powerrestorepolicy**
Display or control BMC Power Restore Policy attribute setting. [OpenBMC]

**powersupplyredundancy**
Display or control BMC Power Supply Redundancy attribute setting. [OpenBMC]

**autoreboot**
Display or control BMC Auto Reboot attribute setting. [OpenBMC]

**bootmode**
Display or control BMC Boot Mode attribute setting. [OpenBMC]

**dump**
Generate/Manage BMC system dumps. If no sub-option is provided, will generate, wait, and download the dump. [OpenBMC]

- `-c` will clear a single specified dump, or use ‘all’ to clear all dumps on the BMC.
- `-l` will list all the generated dumps on the BMC.
- `-g` will generate a new dump on the BMC. Dump generation can take a few minutes.
- `-d` will download a single dump or all generated dumps from the BMC to /var/log/xcat/dump on management or service node.

**timesyncmethod**
Set the method for time synchronization on the BMC. [OpenBMC]

**network**={[ip],[host],[gateway],[netmask]*}
For MPA: get or set the MPA network parameters. If ‘*’ is specified, all parameters are read from the xCAT database.
For FSP of Flex system P node: set the network parameters. If '*' is specified, all parameters are read from the xCAT database.

\texttt{initnetwork} = \{ [ip],[host],[gateway],[netmask]]* \}

For MPA only. Connecting to the IP of MPA from the hosts.otherinterfaces to set the MPA network parameters. If '*' is specified, all parameters are read from the xCAT database.

\texttt{network} = \{nic, [ip],[host],[gateway],[netmask]]* \}

Not only for FSP/BPA but also for IMM. Get or set the FSP/BPA/IMM network parameters. If '*' is specified, all parameters are read from the xCAT database. If the value of \texttt{ip} is '0.0.0.0', this \texttt{nic} will be configured as a DHCP client. Otherwise this \texttt{nic} will be configured with a static IP.

Note that IPs of FSP/BPAs will be updated with this option, user needs to put the new IPs to /etc/hosts manually or with xCAT command makehosts. For more details, see the man page of makehosts.

\texttt{nonred}

Allows loss of redundancy.

\texttt{ntp} = \{ [ntpenable],[ntpservers],[frequency],[v.f] \}

Get or set the MPA Network Time Protocol (NTP) parameters.

\texttt{ntpenable}

Enable or disable NTP (enable|disable).

\texttt{ntpservers}

Get or set NTP servers name. [OpenBMC]

\texttt{pd1} = \{ nonred | redwoperf | redwperf \}

Power Domain 1 - determines how an MPA responds to a loss of redundant power.

\texttt{pd2} = \{ nonred | redwoperf | redwperf \}

Power Domain 2 - determines how an MPA responds to a loss of redundant power.

\texttt{procdefcfg} = \{ configure|deconfigure|processingunit:id,… } \}

Selects whether each processor should be enabled or disabled. State changes take effect on the next platform boot.

\texttt{redwoperf}

Prevents components from turning on that will cause loss of power redundancy.

\texttt{redwperf}

Power throttles components to maintain power redundancy and prevents components from turning on that will cause loss of power redundancy.

\texttt{snmpcfg} = \{ enable | disable \}

Enable or disable SNMP on MPA.

\texttt{snmpdest} = \texttt{snmpmanager-IP}

Get or set where the SNMP alerts should be sent to.

\texttt{solcfg} = \{ enable | disable \}
Enable or disable the sol on MPA (or CMM) and blade servers belongs to it.

**spdump**
Performs a service processor dump.

**sshefg={enable | disable}**
Enable or disable SSH on MPA.

**sshefg**
Copy SSH keys.

**swnet={[ip],[gateway],[netmask]}**
Set the Switch network parameters.

**sysdump**
Performs a system dump.

**sysname**
Query or set sysname for CEC or Frame. If no value specified, means to query sysname of the specified nodes. If ‘*’ specified, it means to set sysname for the specified nodes, and the sysname values would get from xCAT database. If a string is specified, it means to use the string as sysname value to set for the specified node.

**pending_power_on_side={temp|perm}**
List or set pending power on side for CEC or Frame. If no pending_power_on_side value specified, the pending power on side for the CECs or frames will be displayed. If specified, the pending_power_on_side value will be set to CEC’s FSPs or Frame’s BPAs. The value ‘temp’ means T-side or temporary side. The value ‘perm’ means P-side or permanent side.

**time=hh:mm:ss**
Enter the current time in UTC (Coordinated Universal Time) format.

**textid={textid}**
Set the blade or MPA textid. When using ‘*’, the textid used is the node name specified on the command-line. Note that when specifying an actual textid, only a single node can be specified in the noderange.

**USERID={newpasswd} updateBMC={yn}**
Change the password of the userid USERID for CMM in Flex system cluster. The option updateBMC can be used to specify whether updating the password of BMCs that connected to the specified CMM. The value is ‘y’ by default which means whenever updating the password of CMM, the password of BMCs will be also updated. Note that there will be several seconds needed before this command complete.

If value ‘*’ is specified for USERID and the object node is *Flex System X node*, the password used to access the BMC of the System X node through IPMI will be updated as the same password of the userid USERID of the CMM in the same cluster.

**--resetnet**
Reset the network interfaces of the specified nodes.

**v3**
Enable or disable v3 authentication (enable|disable).

**-h | --help**
Prints out a brief usage message.
-v | --version

Display the version number.

EXAMPLES

1. To setup new ssh keys on the Management Module mm:

   ```
   rspconfig mm snmpcfg=enable sshcfg=enable
   ```

2. To turn on SNMP alerts for node5:

   ```
   rspconfig node5 alert=on
   ```

   Output is similar to:

   ```
   node5: Alerts: enabled
   ```

3. To display the destination setting for SNMP alerts for node4:

   ```
   rspconfig node4 snmpdest
   ```

   Output is similar to:

   ```
   node4: BMC SNMP Destination 1: 9.114.47.227
   ```

4. To display the frame number for frame 9A00-10000001

   ```
   rspconfig> 9A00-10000001 frame
   ```

   Output is similar to:

   ```
   9A00-10000001: 1
   ```

5. To set the frame number for frame 9A00-10000001

   ```
   rspconfig 9A00-10000001 frame=2
   ```

   Output is similar to:

   ```
   9A00-10000001: SUCCESS
   ```

6. To set the frame numbers for frame 9A00-10000001 and 9A00-10000002

   ```
   rspconfig 9A00-10000001,9A00-10000002 frame=*
   ```

   Output is similar to:

   ```
   9A00-10000001: SUCCESS
   9A00-10000002: SUCCESS
   ```

7. To display the MPA network parameters for mm01:

   ```
   rspconfig mm01 network
   ```

   Output is similar to:
8. To change the MPA network parameters with the values in the xCAT database for mm01:

```
rspconfig mm01 network=*  
```

Output is similar to:

```
mm01: MM IP: 192.168.1.47
mm01: MM Hostname: mm01
mm01: Gateway: 192.168.1.254
mm01: Subnet Mask: 255.255.255.224
```

9. To change only the gateway parameter for the MPA network mm01:

```
rspconfig mm01 network=,,192.168.1.1,  
```

Output is similar to:

```
mm01: Gateway: 192.168.1.1
```

10. To display the FSP network parameters for fsp01:

```
rspconfig> fsp01 network  
```

Output is similar to:

```
fsp01:
  eth0:
   IP Type: Dynamic
   IP Address: 192.168.1.215
   Hostname: fsp01
   Gateway: 255.255.255.0

  eth1:
   IP Type: Dynamic
   IP Address: 192.168.200.51
   Hostname: fsp01
   Gateway:
   Netmask: 255.255.255.0
```

11. To change the FSP network parameters with the values in command line for eth0 on fsp01:

```
rspconfig fsp01 network=eth0,192.168.1.200,fsp01,,255.255.255.0  
```

Output is similar to:

```
fsp01: Success to set IP address,hostname,netmask
```

12. To change the FSP network parameters with the values in the xCAT database for eth0 on fsp01:

```
rspconfig fsp01 network=eth0,*  
```

Output is similar to:
13. To configure eth0 on fsp01 to get dynamic IP address from DHCP server:

```
fsp01: Success to set IP address, hostname, gateway, netmask
```

```
rspconfig fsp01 network=eth0,0.0.0.0
```

Output is similar to:

```
fsp01: Success to set IP type to dynamic.
```

14. To get the current power redundancy mode for power domain 1 on mm01:

```
rspconfig mm01 pd1
```

Output is similar to:

```
mm01: Redundant without performance impact
```

15. To change the current power redundancy mode for power domain 1 on mm01 to non-redundant:

```
rspconfig mm01 pd1=nonred
```

Output is similar to:

```
mm01: nonred
```

16. To enable NTP with an NTP server address of 192.168.1.1, an update frequency of 90 minutes, and with v3 authentication enabled on mm01:

```
rspconfig mm01 ntp=enable,192.168.1.1,90,enable
```

Output is similar to:

```
mm01: NTP: disabled
mm01: NTP Server: 192.168.1.1
mm01: NTP: 90 (minutes)
mm01: NTP: enabled
```

17. To disable NTP v3 authentication only on mm01:

```
rspconfig mm01 ntp=,,disable
```

Output is similar to:

```
mm01: NTP v3: disabled
```

18. To disable Predictive Failure and L2 Failure deconfiguration policies on mm01:

```
rspconfig mm01 decfg=disable:predictive,L3
```

Output is similar to:

```
mm01: Success
```

19. To deconfigure processors 4 and 5 of Processing Unit 0 on mm01:
20. To check if CEC sysname set correct on mm01:

```plaintext
rspconfig mm01 sysname
mm01: mm01
rspconfig mm01 sysname=cec01
mm01: Success
rspconfig mm01 sysname
mm01: cec01
```

21. To check and change the pending_power_on_side value of cec01’s fsps:

```plaintext
rspconfig cec01 pending_power_on_side
cec01: Pending Power On Side Primary: temp
cec01: Pending Power On Side Secondary: temp
rspconfig cec01 pending_power_on_side=perm
cec01: Success
rspconfig cec01 pending_power_on_side
cec01: Pending Power On Side Primary: perm
cec01: Pending Power On Side Secondary: perm
```

22. To show the BSR allocation for cec01:

```plaintext
rspconfig cec01 BSR
```

Output is similar to:

```plaintext
cec01: Barrier Synchronization Register (BSR)
cec01: Number of BSR arrays: 256
cec01: Bytes per BSR array : 4096
cec01: Available BSR array : 0
cec01: Partition name: BSR arrays
cec01: lpar01 : 32
cec01: lpar02 : 32
cec01: lpar03 : 32
cec01: lpar04 : 32
cec01: lpar05 : 32
cec01: lpar06 : 32
cec01: lpar07 : 32
cec01: lpar08 : 32
```

23. To query the huge page information for CEC1, enter:
24. To request 10 huge pages for CEC1, enter:

```
rspconfig CEC1 huge_page=10
```

Output is similar to:

```
CEC1: Success
```

25. To disable service processor failover for cec01, in order to complete this command, the user should power off cec01 first:

```
rspconfig cec01 setup_failover

getfailoverstatus

rpower cec01 off

rspconfig cec01 setup_failover=disable

getfailoverstatus

rspconfig cec01 setup_failover

getfailoverstatus

ceco: Failure status: Disabled
```

26. To force service processor failover for cec01:

```
lshwconn cec01

ceco1: 192.168.1.1: LINE DOWN
ceco1: 192.168.2.1: sp=primary,ipadd=192.168.2.1,alt_ipadd=unavailable, state=LINE UP
ceco1: 192.168.1.2: sp=secondary,ipadd=192.168.1.2,alt_ipadd=unavailable, state=LINE UP
ceco1: 192.168.2.2: LINE DOWN

rspconfig cec01 force_failover
```

(continues on next page)
27. To deconfigure memory bank 9 and 10 of Processing Unit 0 on mm01:

<table>
<thead>
<tr>
<th>Command:</th>
<th>Description</th>
</tr>
</thead>
</table>
   | `rspconfig mm01 memdecfg=deconfigure:bank:0:9,10` | Output is similar to:
   | `mm01: Success` |  |

28. To reset the network interface of the specified nodes:

<table>
<thead>
<tr>
<th>Command:</th>
<th>Description</th>
</tr>
</thead>
</table>
   | `rspconfig --resetnet` | Output is similar to:
   | `Start to reset network..` |  |
   | `Reset network failed nodes:` |  |
   | `Reset network succeed nodes:` |  |
   | `Reset network finished.` |  |

29. To update the existing admin password on fsp:

<table>
<thead>
<tr>
<th>Command:</th>
<th>Description</th>
</tr>
</thead>
</table>
   | `rspconfig fsp admin_passwd=admin,abc123` | Output is similar to:
   | `fsp: Success` |  |

30. To set the initial password for user HMC on fsp:

<table>
<thead>
<tr>
<th>Command:</th>
<th>Description</th>
</tr>
</thead>
</table>
   | `rspconfig fsp HMC_passwd=,abc123` | Output is similar to:
   | `fsp: Success` |  |

31. To list BMC dumps available for download:

<table>
<thead>
<tr>
<th>Command:</th>
<th>Description</th>
</tr>
</thead>
</table>
   | `rspconfig p9euh02 dump -l` | Output is similar to:
   |  |  |
32. To generate and download BMC dump:

```
rspconfig p9euh02 dump
```

Output is similar to:

```
Capturing BMC Diagnostic information, this will take some time...
p9euh02: Dump requested. Target ID is 6, waiting for BMC to generate...
p9euh02: Dump 6 generated. Downloading to /var/log/xcat/dump/20171211-0951-
˓→p9euh02_dump_6.tar.xz
```

SEE ALSO

noderange(3)|noderange.3, rpower(1)|rpower.1, rcons(1)|rcons.1, rinv(1)|rinv.1, rvitals(1)|rvitals.1, rscan(1)|rscan.1, 
rflash(1)|rflash.1

rspreset.1

Name

rspreset - resets the service processors associated with the specified nodes

Synopsis

rspreset noderange

rspreset [-h | --help | -v | --version]

Description

rspreset resets the service processors associated with the specified nodes. It searches the nodehm table and associated 
tables to find the service processors associated with the nodes specified. If the node is a BMC-based node, the node’s 
BMC will be reset. If the node is a blade, the blade’s on board service processor will be reset.

Options

-h | --help

Print help.

-v | --version

Print version.
Examples

1. Reset the service processor that controls node5:

   

   rspreset node5

SEE ALSO

rpower(1)|rpower.1, nodehm(5)|nodehm.5

rvitals.1

Name

rvitals - remote hardware vitals

Synopsis

rvitals [-h | --help | -v | --version]

FSP/LPAR (with HMC) specific:

rvitals noderange \{ temp | voltage |lcds | all \}

CEC/LPAR/Frame (using Direct FSP Management) specific:

rvitals noderange \{rackenv |lcds | all \} [-V|--verbose]

MPA specific:

rvitals noderange \{temp | voltage | wattage |fanspeed | power | leds | summary | all \}

Blade specific:

rvitals noderange \{temp | wattage | fanspeed | leds | summary | all \}

BMC specific:

rvitals noderange \{temp | voltage | wattage | fanspeed | power | leds | all \}

OpenPOWER (IPMI) specific:

rvitals noderange \{temp | voltage | wattage | fanspeed | power | leds | chassis | all \}
OpenPOWER (OpenBMC) specific:

rvitals noderange [temp | voltage | wattage | fanspeed | power | leds | altitude | all] [-V|--verbose]

Description

rvitals Retrieves hardware vital information from the on-board Service Processor for a single or range of nodes and groups.

Options

cputemp
    Retrieves CPU temperatures.
disktemp
    Retrieves HD back plane temperatures.
ambtemp
    Retrieves ambient temperatures.
temp
    Retrieves all temperatures.
voltage
    Retrieves power supply and VRM voltage readings.
fanspeed
    Retrieves fan speeds.
lcds
    Retrieves LCDs status.
rackenv
    Retrieves rack environmental.
leds
    Retrieves LEDs status.
chassis
    Retrieves chassis status.
altitude
    Retrieves altitude related attributes.
power
    Retrieves power status.
powertime
    Retrieves total power uptime. This value only increases, unless the Service Processor flash gets updated. This option is not valid for x86 architecture systems.
reboot
Retrieves total number of reboots. This value only increases, unless the Service Processor flash gets updated. This option is not valid for x86 architecture systems.

state
Retrieves the system state.

all
All of the above.

-h | --help
Print help.

-v | --version
Print version.

Examples

rvitals node5 all

Output is similar to:

node5: CPU 1 Temperature: + 29.00 C (+ 84.2 F)
node5: CPU 2 Temperature: + 19.00 C (+ 66.2 F)
node5: DASD Sensor 1 Temperature: + 32.00 C (+ 89.6 F)
node5: System Ambient Temperature Temperature: + 26.00 C (+ 78.8 F)
node5: +5V Voltage: + 5.01V
node5: +3V Voltage: + 3.29V
node5: +12V Voltage: + 11.98V
node5: +2.5V Voltage: + 2.52V
node5: VRM1 Voltage: + 1.61V
node5: VRM2 Voltage: + 1.61V
node5: Fan 1 Percent of max: 100%
node5: Fan 2 Percent of max: 100%
node5: Fan 3 Percent of max: 100%
node5: Fan 4 Percent of max: 100%
node5: Fan 5 Percent of max: 100%
node5: Fan 6 Percent of max: 100%
node5: Current Power Status On
node5: Current LCD1: SuSE Linux
node5: Power On Seconds 11855915
node5: Number of Reboots 930
node5: System State Booting OS or in unsupported OS

SEE ALSO

rpower(1)rpower.1, rinv(1)rinv.1

sinv.1

NAME

sinv - Checks the software configuration of the nodes in the cluster.
SYNOPSIS


sinv [-h | -v]

DESCRIPTION

The `sinv` command is designed to check the configuration of the nodes in a cluster. The command takes as input command line flags, and one or more templates which will be compared against the output of the `xdsh` command, designated to be run by the `-c` or `-f` flag, on the nodes in the noderange.

The nodes will then be grouped according to the template they match and a report returned to the administrator in the output file designated by the `-o` flag, or to stdout.

`sinv` supports checking the output from the `rinv` or `xdsh` command.

The `sinv` command is an xCAT Distributed Shell Utility.

COMMAND SPECIFICATION:

The `xdsh` or `rinv` command to execute on the remote targets is specified by the `-c` flag, or by the `-f` flag which is followed by the fully qualified path to a file containing the command.

Note: do not add `| xdshcoll` to the command on the command line or in the command file, it is automatically added by `sinv`.

The syntax for the `-c` parameter is as follows:

```
"command[; command]..."
```

where `command` is the command to run on the remote target. Quotation marks are required to ensure that all commands in the list are executed remotely, and that any special characters are interpreted correctly on the remote target.

The `sinv` command does not work with any interactive commands, including those that read from standard input.

REMOTE SHELL COMMAND:

For `xdsh`, support is explicitly provided for AIX Remote Shell and OpenSSH, but any secure remote command that conforms to the IETF (Internet Engineering Task Force) Secure Remote Command Protocol can be used. See man `xdsh` for more details.

OPTIONS

- **-o | --output report output file**

  Optional output file. This is the location of the file that will contain the report of the nodes that match, and do not match, the input templates. If the flag is not used, the output will go to stdout.

- **-p | --tp template path**

  This is the path to the template file. The template contains the output of `xdsh` or `rinv` command, that has been run against a “seed” node, a node that contains the configuration that you would like all nodes in your noderange to match.

  The admin can create the template by running the `xdsh` or `rinv` command on the seed node, pipe to `xdshcoll` (required) and store the output in the template path. See examples.

  **Note:** The admin can also edit the template to remove any lines that they do not want checked.
An alternative method is to use the [-s seed node] parameter, which will automatically build the template for you from the seed node named.

If a seed node is not provided, then command will automatically use the first node in the noderange as the seed node.

-t | --tc template count

This count is the number of templates that the command will use to check for nodes matches. If the template in the template path does not match a node, the sinv will check additional templates up to the template count.

For each node, it will compare the node against each template to see if there is a match. If there is no match, and we are not over the template count, then a new template will be created from the node output. This will result in having all nodes that match a given template reported in their group at the end of the run in the output file. If no template count is specified, 0 is the default, and all nodes will be compared against the first template.

-s | --seed seed node

This is the node that will be used to build the first template that is stored in template path. You can use this parameter instead of running the command yourself to build the template.

Note: If no seed node is supplied, the first node in the noderange is automatically selected as a seed node.

-i | --ignorefirst

This flag suppresses the reporting of the nodes matching the first template. In very large systems, you may not want to show the nodes that have the correct configuration, since the list could contain thousands of nodes. This allows you to only report the nodes that do not match the required configuration.

-e | --exactmatch

This requires the check of node output against template to be an exact match. If this flag is not set, sinv checks to see if the return from the xdsh or rinv command to the nodes contain a match for each line in the input template (except for xdshcoll header and comments). If not in exactmatch mode, there can be more lines in the xdsh or rinv return from the nodes.

For example, if running a “rpm -qa | grep xCAT” command, without exactmatch set, if the node contains more xCAT rpms that listed in the template, it would be considered a match, as long as all rpms listed in the template were on the node. With exactmatch set, the output must be identical to the template.

--devicetype type_of_device

Specify a user-defined device type that references the location of relevant device configuration file. The devicetype value must correspond to a valid device configuration file. xCAT ships some default configuration files for Ethernet switches and IB switches under /opt/xcat/share/xcat/devicetype directory. If you want to overwrite any of the configuration files, copy them to /var/opt/xcat/ directory and customize. For example, base/IBSwitch/Qlogic/config is the configuration file location if devicetype is specified as IB-Switch::Qlogic. xCAT will first search config file using /var/opt/xcat/ as the base. If not found, it will search for it using /opt/xcat/share/xcat/devicetype/ as the base.

-u | --user user_ID

Specifies a remote user name to use for remote command execution.

-c | --command

The xdsh or rinv command that will be run. The command should be enclosed in double quotes to insure correct shell interpretation. This parameter must only contain, the node range or the image path (Linux) or spot name for AIX. It cannot be used to set additional input flags to xdsh or rinv (for example -s,-T,-e). See examples below.
**Note:** do not add the `| xdshcoll` to the command, it is automatically added by `sinv`. `sinv` also automatically sets the `-v` flag for `xdsh`.

- **-f | --file**
  The file containing the `xdsh` or `rinv` command that will be run. This should be the fully qualified name of the file.
  **Note:** do not add the `| xdshcoll` to the command in the file, it is automatically added by `sinv`.

- **-r | --remove**
  This flag indicates that generated templates should be removed at the at the end of the `sinv` command execution.
  If the flag is specified, then all templates that are generated by the `sinv` command, will be removed. If the first template is created by the admin, it will not be removed.
  If the flag is not specified, no templates will be removed. It is up to the admin to cleanup templates.

- **-h | --help**
  Displays usage information.

- **-v | --version**
  Displays xCAT release version.

- **-V | --verbose**
  Verbose mode.

**Examples**

1. To setup `sinv.template` (name optional) for input to the `sinv` command, enter:
   ```bash
exdsh node1,node2 "rpm -qa | grep ssh " | xdshcoll > /tmp/sinv.template
   ```
   **Note:** when setting up the template the output of `xdsh` must be piped to `xdshcoll`, `sinv` processing depends on it.

2. To setup `rinv.template` for input to the `sinv` command, enter:
   ```bash
rinv node1-node2 serial | xdshcoll > /tmp/rinv.template
   ```
   **Note:** when setting up the template the output of `rinv` must be piped to `xdshcoll`, `sinv` processing depends on it.

3. To execute `sinv` using the `sinv.template` generated above on the nodegroup, `testnodes`, possibly generating up to two new templates, and removing all generated templates in the end, and writing output report to `/tmp/sinv.output`, enter:
   ```bash
sinv -c "xdsh testnodes rpm -qa | grep ssh" -p /tmp/sinv.template -t 2 -r -o →/tmp/sinv.output
   ```
   **Note:** do not add the pipe to `xdshcoll` on the `-c` flag, it is automatically added by the `sinv`.

4. To execute `sinv` on noderange, `node1-node4`, using the seed node, `node8`, to generate the first template, using the `xdsh` command (`-c`), possibly generating up to two additional templates and not removing any templates at the end, enter:
   ```bash
sinv -c "xdsh node1-node4 lslpp -l | grep bos.adt" -s node8 -p /tmp/sinv. →template -t 2 -o /tmp/sinv.output
   ```
5. To execute `sinv` on noderange, `node1-node4`, using the seed node, `node8`, to generate the first template, using the `rinv` command (`-c`), possibly generating up to two additional templates and removing any generated templates at the end, enter:

```
SINV -c "RINV NODE1-NODE4 SERIAL" -s node8 -p /tmp/sinv.template -t 2 -r -o /tmp/rinv.output
```

6. To execute `sinv` on noderange, `node1-node4`, using `node1` as the seed node, to generate the `sinv.template` from the `xdsh` command (`-c`), using the exact match option, generating no additional templates, enter:

```
SINV -c "XDSH NODE1-NODE4 LSLPP -L | GREP BOS.ADT" -s node1 -e -p /tmp/sinv.template -o /tmp/sinv.output
```

Note: the `/tmp/sinv.template` file must be empty, otherwise it will be used as an admin generated template.

7. To execute `sinv` on the Linux osimage defined for `cn1`. First build a template from the `/etc/hosts` on the node. Then run `sinv` to compare.

```
xdsh cn1 "cat /etc/hosts" | xdshcoll > /tmp/sinv2/template"
SINV -c "XDSH -I /INSTALL/NETBOOT/RHEL64/TEST_RAMDISK_STATELLE/ROOTIMG CAT /ETC/HOSTS" -e -t 1 -p /tmp/sinv.template -o /tmp/sinv.output
```

8. To execute `sinv` on the AIX NIM 611dskls spot and compare `/etc/hosts` to compute1 node, run the following:

```
xdsh compute1 "cat /etc/hosts" | xdshcoll > /tmp/sinv2/template"
SINV -c "XDSH -I 611DSKLS CAT /ETC/HOSTS" -e -t1 -p /tmp/sinv.template -o /tmp/sinv.output
```

9. To execute `sinv` on the device `mswitch2` and compare to `mswitch1`

```
SINV -c "XDSH MSWITCH ENABLE;SHOW VERSION" -s mswitch1 -p /tmp/sinv/template --devicetype IBSwitch::Mellanox -l admin -t 2
```

**Files**

`/opt/xcat/bin/sinv`

Location of the `sinv` command.

**SEE ALSO**

`xdsh(1)`|`xdsh.1`, `noderange(3)`|`noderange.3`

**snmove.1**

**NAME**

`smove` - Move xCAT compute nodes to a different xCAT service node.

**SYNOPSIS**

```
```

DESCRIPTION

The snmove command may be used to move a node or nodes from one service node to another backup service node. The use of backup service nodes in an xCAT hierarchical cluster can help improve the overall reliability, availability, and serviceability of the cluster.

Before you run the snmove command it is assumed that the backup service node has been configured properly to manage the new node or nodes. (See the xCAT document named “Using xCAT Service Nodes with AIX” for information on how to set up backup AIX service nodes.).

The snmove command can use the information stored in the xCAT database or information passed in on the command line to determine the current service node and the backup service node.

To specify the primary and backup service nodes you can set the “servicenode” attribute of the node definitions.

The servicenode attribute is the hostname of the xCAT service node as it is known by the management node. The xcatmaster attribute is the hostname of the xCAT service node as known by the node. The servicenode attribute should be set to a comma-separated list so that the primary service node is first and the backup service node is second. The xcatmaster attribute must be set to the hostname of the primary service node as it is known by the node.

When the snmove command is run it modifies the xCAT database to switch the primary server to the backup server.

It will also check the other services that are being used for the node (tftpserver, monserver, nfsserver, conserver), and if they were set to the original service node they will be changed to point to the backup service node.

By default the command will modify the nodes so that they will be able to be managed by the backup service node.

If the -i option is specified, the nodes themselves will not be modified.

You can also have postscripts executed on the nodes by using the -P option if needed.

The xCAT snmove command may also be used to synchronize statelite persistent files from the primary service node to the backup service node without actually moving the nodes to the backup servers.

If you run the command with the “-l” option it will attempt to use rsync to update the statelite persistent directory on the backup service node. This will only be done if the server specified in the “statelite” table is the primary service node.

When the snmove command is executed the new service node must be running but the original service node may be down.

Note: On a Linux cluster, for NFS statelite nodes that do not use external NFS server, if the original service node is down, the nodes it manages will be down too. You must run nodest command and then reboot the nodes after running snmove. For stateless nodes and RAMDisk statelite nodes, the nodes will be up even if the original service node is down. However, make sure to run nodest command if you decide to reboot the nodes later.

OPTIONS

-d|--dest

    Specifies the hostname of the new destination service node as known by (facing) the management node.

-D|--destn

    Specifies the hostname of the destination service node as known by (facing) the nodes.
-h|--help
Display usage message.

-il|--ignorenodes
No modifications will be made on the nodes. If not specified, several xCAT postscripts will be run on the nodes to complete the switch to the new service node.

-li|--liteonly
Use this option to ONLY synchronize any AIX statelite files from the primary server to the backup server for the nodes. It will not do the actual moving of the nodes to the backup servers.

-P|--postscripts
Specifies a list of extra postscripts to be run on the nodes after the nodes are moved over to the new service node. If all is specified, all the postscripts defined in the postscripts table will be run for the nodes. The specified postscripts must be stored under /install/postscripts directory.

-s|--source
Specifies the hostname of the current (source) service node as known by (facing) the management node.

-S|--sourcen
Specifies the hostname of the current service node adapter as known by (facing) the nodes.

-V|--verbose
Verbose mode.

-v|--version
Command Version.

EXAMPLES

1. Move the nodes contained in group “group1” to the service node named “xcatsn02”.

   snmove group1 -d xcatsn02 -D xcatsn02-eth1

2. Move all the nodes that use service node xcatsn01 to service node xcatsn02.

   snmove -s xcatsn01 -S xcatsn01-eth1 -d xcatsn02 -D xcatsn02-eth1

3. Move any nodes that have sn1 as their primary server to the backup service node set in the xCAT node definition.

   snmove -s sn1

4. Move all the nodes in the xCAT group named “nodegroup1” to their backup SNs.

   snmove nodegroup1

5. Move all the nodes in xCAT group “sngroup1” to the service node named “xcatsn2”.

   snmove sngroup1 -d xcatsn2

6. Move all the nodes in xCAT group “sngroup1” to the SN named “xcatsn2” and run extra postscripts.

   snmove sngroup1 -d xcatsn2 -P test1
7. Move all the nodes in xCAT group “sngroup1” to the SN named “xcatsn2” and do not run anything on the nodes.

\texttt{snmove sngroup1 -d xcatsn2 -i}

8. Synchronize any AIX satellite files from the primary server for compute03 to the backup server. This will not actually move the node to it’s backup service node.

\texttt{snmove compute03 -l -V}

FILES

\texttt{/opt/xcat/sbin/snmove}

SEE ALSO

noderange(3)|noderange.3

\texttt{swapnodes.1}

NAME

\texttt{swapnodes} - swap the location info in the db (all the attributes in the ppc table and the nodepos table) between 2 nodes. If swapping within a cec, it will assign the IO adapters that were assigned to the defective node to the available node.

SYNOPSIS

\texttt{swapnodes [-h|--help]}

\texttt{swapnodes -c current\_node -f fip\_node [-o]}

DESCRIPTION

This command is only for Power 775 using Direct FSP Management, and used in Power 775 Availability Plus.

The \texttt{swapnodes} command will keep the \texttt{current\_node} name in the xCAT table, and use the \texttt{fip\_node}’s hardware resource. Besides that, the IO adapters will be assigned to the new hardware resource if they are in the same CEC. So the \texttt{swapnodes} command will do 2 things:

1. Swap the location info in the db between 2 nodes:
   All the ppc table attributes (including hcp, id, parent, supernode and so on). All the nodepos table attributes (including rack, u, chassis, slot, room and so on).

2. Assign the I/O adapters from the defective node (the original \texttt{current\_node}) to the available node (the original \texttt{fip\_node}) if the nodes are in the same cec.

The \texttt{swapnodes} command shouldn’t make the decision of which 2 nodes are swapped. It will just received the 2 node names as cmd line parameters.
After running `swapnodes` command, the order of the I/O devices may be changed after IO re-assignment, so the administrator needs to run `rbootseq` to set the boot string for the `current_node`. And then boot the node with the same image and same postscripts because they have the same attributes.

Without `-o` option, it’s used to swap the location info in the db between 2 nodes. With `-o` option, it’s used to move the `current_node` definition to `fip_node` (the 2nd octant), not move the `fip_node` definition to the 1st octant. If the two nodes are in a cec, it will assign the IO adapters that were assigned to the defective node to the available node. Originally, the `current_node` is a defective non-compute node, and `fip_node` is a available compute node. After the swapping, the `current_node` will be a available node.

**OPTIONS**

**-h|--help**
Display usage message.

**-c**
`current_node` – the defective non-compute node.

**-f**
`fip_node` – a compute node which will be swapped as the non-compute node.

**-o**
one way. Only move the `current_node` definition to the `fip_node`’s hardware resource, and not move the `fip_node` definition to the `current_node`. And then the `current_node` will use the `fip_node`’s hardware resource, and the `fip_node` definition is not changed. If the two nodes are in the same CEC, the I/O adapter from the original `current_node` will be assigned to the `fip_node`.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.

**EXAMPLES**

1. To swap the service node attributes and IO assignments between sn1 and compute2 which are in the same cec, all the attributes in the ppc table and nodepos table of the two node will be swapped, and the I/O adapters from the defective node (the original sn1) will be assigned to the available node (the original compute2). After the swapping, the sn1 will use the compute2’s hardware resource and the I/O adapters from the original sn1.

```
swapnodes -c sn1 -f compute2
```

2. To swap the service node attributes and IO assignments between sn1 and compute2 which are NOT in the same cec, all the attributes in the ppc table and nodepos table of the two node will be swapped. After the swapping, the sn1 will use the compute2’s hardware resource.

```
swapnodes -c sn1 -f compute2
```

3. Only to move the service node (sn1) definition to the compute node (compute2)’s hardware resource, and not move the compute2 definition to the sn1. After the swapping, the sn1 will use the compute2’s hardware resource, and the compute2 definition is not changed.

```
`
 FILES

$XCATROOT/bin/swapnodes
(The XCATROOT environment variable is set when xCAT is installed. The default value is “/opt/xcat.”)

 NOTES

This command is part of the xCAT software product.

 SEE ALSO

lsvm(1)|lsvm.1, mkvm(1)|mkvm.1, chvm(1)|chvm.1

 switchblade.1

 SYNOPSIS

 switchblade MM {list | stat}
 switchblade node {media | mt | kvm | video | both} [slot_num]
 switchblade [-h | --help | -v | --version]

 DESCRIPTION

 switchblade assigns the BladeCenter media tray and/or KVM to the specified blade, so that they can be used with that blade. If list or stat are specified instead, switchblade will display the current assignment. You can either specify a management module or a node (blade) to switchblade. If the latter, switchblade will determine the management module of the node.

 OPTIONS

 list | stat
 Display which blade the media tray and KVM are currently assigned to.

 media | mt
 Assign the media tray to the specified blade.

 kvm | video
 Assign the KVM (video display) to the specified blade.

 both
 Assign both the media tray and the KVM to the specified blade.

 slot_num
The slot # of the blade that the resources should be assigned to. If not specified, it will use the slot # of
the node specified.

EXAMPLES

1. Switch the media tray to be assigned to the blade in slot 4 (assume it is node4):

   ```
   switchblade node4 media
   ```

   Output will be like:

   ```
   Media Tray slot: 4
   ```

SEE ALSO

rbootseq(1)|rbootseq.1

switchdiscover.1

SYNOPSIS

switchdiscover [-h|--help]

switchdiscover [-v|--version]

switchdiscover [noderange|--range ip_ranges] [-V] [-w][-r|-x|-z][-s scan_methods] [--setup] [-c community]

DESCRIPTION

The switchdiscover command scans the subnets and discovers all the switches on the subnets. The command takes a
list of subnets as input. The default subnets are the ones that the xCAT management node is on. It uses nmap command
as default to discover the switches. However, you can specify other discovery methods such as lldp or snmp with -s
flag. You can write the discovered switches into xCAT database with -w flag. This command supports may output
formats such as xml(-x), raw(-r) and stanza(-z) in addition to the default format.

--setup flag is for switch-based switch discovery. It will find all the discovered switches on the subnets, then match
them with predefined switches in the xCATDB. Next, it will set discovered switches with static ip address and host-
ame based on the predefined switch. It will also enable snmpv3 configuration. The details of the process are defined

To view all the switches defined in the xCAT database use `lsdef -w "nodetype=switch"` command.

For lldp method, make sure that lldpd package is installed and lldpd is running on the xCAT management node. lldpd
comes from xcat-dep package or you can get it from http://vincentbernat.github.io/lldpd/installation.html.

For snmp method, make sure that snmpwalk command is installed and snmp is enabled for switches. To install sn-
mpwalk, “yum install net-snmp-utils” for redhat and sles, “apt-get install snmp” for Ubuntu. The switchdiscover
command only check the switches with default community string, if user already configured switch with other comm-
unity string, need to pass in with -c option for switchdiscover command to be able to discover.
OPTIONS

noderange

The switches which the user want to discover. If the user specify the noderange, switchdiscover will just return the switches in the node range. Which means it will help to add the new switches to the xCAT database without modifying the existed definitions. But the switches’ name specified in noderange should be defined in database in advance. The ips of the switches will be defined in /etc/hosts file. This command will fill the switch attributes for the switches defined.

-h|--help

Display usage message.

--range

Specify one or more IP ranges. Each can be an ip address (10.1.2.3) or an ip range (10.1.2.0/24). If the range is huge, for example, 192.168.1.1/8, the switch discover may take a very long time to scan. So the range should be exactly specified.

For nmap and snmp scan method, it accepts multiple formats. For example: 192.168.1.1/24, 40-41.1-2.3-4.1-100.

If the range is not specified, the command scans all the subnets that the active network interfaces (eth0, eth1) are on where this command is issued.

-r

Display Raw responses.

-s

It is a comma separated list of methods for switch discovery. The possible switch scan methods are: lldp, nmap or snmp. The default is nmap.

-v|--version

Command Version.

-V

Verbose output.

-w

Writes output to xCAT database.

-x

XML formatted output.

-z

Stanza formatted output.

--setup

Process switch-based switch discovery. Update discovered switch’s ip address, hostname and enable snmpv3 configuration based on the predefined switch.

-c

User defined community string for snmp scan.
RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To discover the switches on some subnets:
   ```
   switchdiscover --range 10.2.3.0/24,192.168.3.0/24,11.5.6.7
   ```
2. To do the switch discovery and save them to the xCAT database:
   ```
   switchdiscover --range 10.2.3.4/24 -w
   ```
   It is recommended to run `makehosts` after the switches are saved in the DB.
3. To use lldp method to discover the switches:
   ```
   switchdiscover -s lldp
   ```
4. To process switch-based switch discovery, the core switch has to be configured and top-of-rack (edge) switch has to be predefine into xCAT database with attribute switch and switchport to core switch:
   ```
   switchdiscover --range 192.168.5.150-170 -s snmp --setup
   ```

FILES

/opt/xcat/bin/switchdiscover

SEE ALSO

`tabgrep.1`

NAME

`tabgrep` - list table names in which an entry for the given node appears.

SYNOPSIS

`tabgrep nodename`
`tabgrep [-? | -h | --help]`

DESCRIPTION

The tabgrep command displays the tables that contain a row for the specified node. Note that the row can either have that nodename as the key or it could have a group that contains the node as the key.
OPTIONS

-?|-h|--help
   Display usage message.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To display the tables that contain blade1:

   tabgrep blade1

   The output would be similar to:

   nodelist
   nodehm
   mp
   chain
   hosts
   mac
   noderes
   nodetype

FILES

/opt/xcat/bin/tabgrep

SEE ALSO

nodels(1)|nodels.1, tabdump(8)|tabdump.8

unregnotif.1

NAME

unregnotif - unregister a Perl module or a command that was watching for the changes of the desired xCAT database tables.

SYNOPSIS

unregnotif [-h] [--help]
unregnotif [-v] [--version]
unregnotif filename

DESCRIPTION

This command is used to unregister a Perl module or a command that was watching for the changes of the desired xCAT database tables.

PARAMETERS

filename is the path name of the Perl module or command to be registered.

OPTIONS

- \( h \) | -help Display usage message.
- \( v \) | -version Command Version.
- \( V \) | -verbose Verbose output.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To unregister a Perl module, enter:
   
   unregnotif /opt/xcat/lib/perl/xCAT_monitoring/mycode.pm

2. To register a command, enter:
   
   unregnotif /usr/bin/mymodule

FILES

/opt/xcat/bin/unregnotif

SEE ALSO

regnotif(1)|regnotif.1
updateSNimage.1

NAME

updateSNimage - Adds the needed Service Node configuration files to the install image.
SYNOPSIS

updateSNimage [-h | --help ]
updateSNimage [-v | --version]
updateSNimage [-n node] [-p path]

DESCRIPTION

This command is used to add the Service Node configuration files to the install image. It will either copy them locally or scp them to a remote host.

OPTIONS

- **-h | --help** Display usage message.
- **-v | --version** Display xCAT version.
- **-n | --node** A remote host name or ip address that contains the install image to be updated.
- **-p | --path** Path to the install image.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To update the image on the local host.
   
   `updateSNimage -p /install/netboot/fedora8/x86_64/test/rootimg`

2. To update the image on a remote host.
   
   `updateSNimage -n 9.112.45.6 -p /install/netboot/fedora8/x86_64/test/rootimg`

updatenode.1

NAME

`updatenode` - Update nodes in an xCAT cluster environment.

SYNOPSIS

DESCRIPTION

The updatenode command is run on the xCAT management node and can be used to perform the following node updates:

1. Distribute and synchronize files.
2. Install or update software on diskful nodes.
3. Run postscripts.
4. Update the ssh keys and host keys for the service nodes and compute nodes; Update the ca and credentials for the service nodes.

The default behavior when no options are input to updatenode will be to run the following options -S, -P and -F options in this order. If you wish to limit updatenode to specific actions you can use combinations of the -S, -P, and -F flags.

For example, If you just want to synchronize configuration file you could specify the -F flag. If you want to synchronize files and update software you would specify the -F and -S flags. See the descriptions of these flags and examples below.

The flag -k (--security) can NOT be used together with -S, -P, and -F flags.

The flag -f (--snsync) can NOT be used together with -S, -P, and -F flags.

Note: In a large cluster environment the updating of nodes in an ad hoc manner can quickly get out of hand, leaving the system administrator with a very confusing environment to deal with. The updatenode command is designed to encourage users to handle cluster updates in a manner that is recorded and easily repeatable.

To distribute and synchronize files

The basic process for distributing and synchronizing nodes is:

* Create a synclist file.
* Indicate the location of the synclist file.
* Run the updatenode command to update the nodes.

Files may be distributed and synchronized for both diskless and diskful nodes. Syncing files to NFS-based statelite nodes is not supported.

More information on using the synchronization file function is in the following doc: Using_Updatenode.

Create the synclist file

The synclist file contains the configuration entries that specify where the files should be synced to. In the synclist file, each line is an entry which describes the location of the source files and the destination location for the files on the target node.
For more information on creating your synclist files and where to put them, read:

Sync-ing_Config_Files_to_Nodes

Run updatenode to synchronize the files

```
updatenode <noderange> -F
```

To install or update software

updatenode can be used to install or update software on the nodes. See the following documentation for setting up otherpkgs: Install_Additional_Packages

To install/update the packages, run:

```
updatenode <noderange> -S
```

For Linux systems:

It this is equivalent to running the following command:

```
updatenode noderange -P ospkgs,otherpkgs
```

It will update all the rpms specified in the .pkglist file and .otherpkgs.pkglist file. ospkgs postscript will normally remove all the existing rpm repositories before adding server:/install/<os>/<arch> as the new repository. To preserve the existing repositories, you can run the following command instead:

```
updatenode noderange -P "ospkgs --keeprepo,otherpkgs"
```

For AIX systems:

Note: The updatenode command is used to update AIX diskful nodes only. For updating diskless AIX nodes refer to the xCAT for AIX update documentation and use the xCAT mknimimage command. For information on updating software on AIX cluster: For diskful installs, read: XCAT_AIX_RTE_Diskful_Nodes For diskless installs, read: XCAT_AIX_Diskless_Nodes

updatenode can also be used in Sysclone environment to push delta changes to target node. After capturing the delta changes from the golden client to management node, just run below command to push delta changes to target nodes.

```
updatenode <targetnoderange> -S
```

To run postscripts

The scripts must be copied to the /install/postscripts directory on the xCAT management node. (Make sure they are executable and world readable.)

To run scripts on a node you must either specify them on the command line or you must add them to the “postscripts” attribute for the node.

To set the postscripts attribute of the node (or group) definition you can use the xCAT chdef command. Set the value to be a comma separated list of the scripts that you want to be executed on the nodes. The order of the scripts in the list determines the order in which they will be run. You can use the lsdef command to check the postscript order.

Scripts can be run on both diskless and diskful nodes.
To run all the customization scripts that have been designated for the nodes, (in the “postscripts and postbootscripts” attributes), type:

```
updatenode <noderange> -P
```

To run the “syslog” script for the nodes, type:

```
updatenode <noderange> -P syslog
```

To run a list of scripts, type:

```
updatenode <noderange> -P "script1 p1 p2,script2"
```

where p1 p2 are the parameters for script1.

The flag ‘-P’ can be omitted when only scripts names are specified.

Note: script1,script2 may or may not be designated as scripts to automatically run on the node. However, if you want script1 and script2 to get invoked next time the nodes are deployed then make sure to add them to the “postscripts/postbootscripts” attribute in the database for the nodes.

**Update security**

The basic functions of update security for nodes:

* Setup the ssh keys for the target nodes. It enables the management node and service nodes to ssh to the target nodes without password.
* Redeliver the host keys to the target nodes.
* Redeliver the ca and certificates files to the service node. These files are used to authenticate the ssl connection between xcat’s of management node and service node.
* Remove the entries of target nodes from known_hosts file.

*Set up the SSH keys*

A password for the user who is running this command is needed to setup the ssh keys. This user must have the same uid and gid as the userid on the target node where the keys will be setup.

If the current user is root, roots public ssh keys will be put in the authorized_keys* files under roots .ssh directory on the node(s). If the current user is non-root, the user must be in the policy table and have credential to run the xdsh command. The non-root users public ssh keys and root’s public ssh keys will be put in the authorized_keys* files under the non-root users .ssh directory on the node(s).

*Handle the hierarchical scenario*

When update security files for the node which is served by a service node, the service node will be updated automatically first, and then the target node.

The certificates files are needed for a service node to authenticate the ssl connections between the xCAT client and xcatd on the service node, and the xcatd’s between service node and management node. The files in the directories /etc/xcat/cert/ and ~/.xcat/ will be updated.

Since the certificates have the validity time, the ntp service is recommended to be set up between management node and service node.

Simply running following command to update the security keys:

```
updatenode <noderange> -k
```
PARAMETERS

noderange

A set of comma delimited xCAT node names and/or group names. See the xCAT “noderange” man page
for details on additional supported formats.

script1,script2, . . .

A comma-separated list of script names. The scripts must be executable and copied to the /install/postscripts directory. Each script can take zero or more parameters. If parameters are specified, the whole list needs to be quoted by double quotes. For example:

"script1 p1 p2,script2"

[attr=val [attr=val. . . ]]]

Specifies one or more “attribute equals value” pairs, separated by spaces. Attr=val pairs must be spec-
ified last on the command line. The currently supported attributes are: “installp_bundle”, “otherpkgs”,
“installp_flags”, “emgr_flags” and “rpm_flags”. These attributes are only valid for AIX software mainte-
nance support.

OPTIONS

--fanout=fanout_value

Specifies a fanout value for the maximum number of concurrently executing remote shell processes. Serial
execution can be specified by indicating a fanout value of 1. If --fanout is not specified, a default fanout
value of 64 is used.

-A|--updateallsw

Install or update all software contained in the source directory. (AIX only)

-c|--cmdlineonly

Specifies that the updatenode command should only use software maintenance information provided on
the command line. This flag is only valid when using AIX software maintenance support.

-d alt_source_dir

Used to specify a source directory other than the standard lpp_source directory specified in the xCAT
osimage definition. (AIX only)

-f|--sync

Specifies that file synchronization should be performed on the nodes. rsync/scp and ssh must be installed
and configured on the nodes. The function is not supported for NFS-based statelite installations. For
NFS-based statelite installations to sync files, you should use the read-only option for files/directories
listed in litetree table with source location specified in the litetree table.

-fl|--snsync

Specifies that file synchronization should be performed to the service nodes that service the nodes in the
noderange. This updates the service nodes with the data to sync to the nodes. rsync/scp and ssh must be
installed and configured on the service nodes. For hierarchy, this optionally can be done before syncing
the files to the nodes with the -F flag. If the -f flag is not used, then the -F flag will sync the servicenodes
before the nodes automatically. When installing nodes in a hierarchical cluster, this flag should be used
to sync the service nodes before the install, since the files will be sync’d from the service node by the
syncfiles postscript during the install. The function is not supported for NFS-based statelite installations.
For satellite installations to sync files, you should use the read-only option for files/directories listed in lifetree table with source location specified in the litetree table.

\[ \text{[-r l --node-rcp \{full_path_to_remote_copy_command\}] } \]

Specifies the full path of the remote copy command used for syncing files to node targets, such as “/usr/bin/rsync” or “/usr/bin/scp”. If not specified, rsync will be used by default.

Notice: The synclist for “-r /usr/bin/scp” has some differences with “-r /usr/bin/rsync”:
1. the “EXECUTE“ clause is not supported in “-r /usr/bin/scp”
2. if the destination directory specified in synclist is an existing file on target node, “updatenode -r /usr/bin/scp” will fail with ‘’scp: <destination directory>: Not a directory’’
3. if the destination file specified in synclist is an existing directory on target node, “updatenode -r /usr/bin/scp” will fail with ‘’scp: <destination file>: Is a directory’’

\[ \text{--genmypost} \]

Will generate a new mypostscript file for the nodes in the noderange, if site precreatemypostscripts is 1 or YES.

\[ \text{--help} \]

Display usage message.

\[ \text{--security} \]

Update the ssh keys and host keys for the service nodes and compute nodes; Update the ca and credentials to the service nodes. Never run this command to the Management Node, it will take down xcatd. You must be running updatenode as root to use the -k flag.

\[ \text{--user user_ID} \]

Specifies a non-root user name to use for remote command execution. This option is only available when running postscripts (-P) for AIX and Linux and updating software (-S) for Linux only. The non-root userid must be previously defined as an xCAT user. The userid sudo setup will have to be done by the admin on the node. This is not supported in a hierarchical cluster, that is the node is serviced by a service node. See the document Granting_Users_xCAT_privileges for required xcat/sudo setup.

\[ \text{--scripts} \]

Specifies that postscripts and postbootscripts should be run on the nodes. updatenode -P syncfiles is not supported. The syncfiles postscript can only be run during install. You should use updatenode <noderange> -F instead.

\[ \text{--sw} \]

Specifies that node software should be updated. In Sysclone environment, specifies pushing the delta changes to target nodes.

\[ \text{--noverify} \]

Specifies that node network availability verification will be skipped.

\[ \text{--sn} \]

Set the server information stored on the nodes in /opt/xcat/xcatinfo on Linux.

\[ \text{timeout} \]

Specifies a timeout in seconds the command will wait for the remote targets to complete. If timeout is not specified it will wait indefinitely. updatenode -k is the exception that has a timeout of 10 seconds, unless overridden by this flag.
-vl--version
   Command Version.
-Vl--verbose
   Verbose mode.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

EXAMPLES

1. To perform all updatenode features for the Linux nodes in the group “compute”:

   ```
   updatenode compute
   ```

   The command will: run any scripts listed in the nodes “postscripts and postbootscripts” attribute, install or update any software indicated in the /install/custom/install/<ostype>/profile.therpkg.s.pkglist (refer to the To install or update software part), synchronize any files indicated by the synclist files specified in the osimage “synclists” attribute.

2. To run postscripts, postbootscripts and file synchronization only on the node “clstrn01”:

   ```
   updatenode clstrn01 -F -P
   ```

3. Running updatenode -P with the syncfiles postscript is not supported. You should use updatenode -F instead.
   Do not run:

   ```
   updatenode clstrn01 -P syncfiles
   ```

   Run:

   ```
   updatenode clstrn01 -F
   ```

4. To run the postscripts and postbootscripts indicated in the postscripts and postbootscripts attributes on the node “clstrn01”:

   ```
   updatenode clstrn01 -P
   ```

5. To run the postscripts script1 and script2 on the node “clstrn01”:

   ```
   cp script1,script2 /install/postscripts
   updatenode clstrn01 -P "script1 p1 p2,script2"
   ```

   Since flag ‘-P’ can be omitted when only script names are specified, the following command is equivalent:

   ```
   updatenode clstrn01 "script1 p1 p2,script2"
   ```

   p1 p2 are parameters for script1.
6. To synchronize the files on the node “clstrn01”: Prepare the synclist file. For AIX, set the full path of synclist in the osimage table synclists attribute. For Linux, put the synclist file into the location: /install/custom/<inst_type>/<distro>/<profile>.<os>.<arch>.synclist. Then:

```bash
updatenode clstrn01 -F
```

7. To perform the software update on the Linux node “clstrn01”: Copy the extra rpm into the /install/post/otherpkgs/<os>/<arch>/ and add the rpm names into the /install/custom/install/<ostype>/profile.otherpkgs.pkglist. Then:

```bash
updatenode clstrn01 -S
```

8. To update the AIX node named “xcn11” using the “installp_bundle” and/or “otherpkgs” attribute values stored in the xCAT database. Use the default installp, rpm and emgr flags.

```bash
updatenode xcn11 -V -S
```

Note: The xCAT “xcn11” node definition points to an xCAT osimage definition which contains the “installp_bundle” and “otherpkgs” attributes as well as the name of the NIM lpp_source resource.

9. To update the AIX node “xcn11” by installing the “bos.cpr” fileset using the “-agQXY” installp flags. Also display the output of the installp command.

```bash
updatenode xcn11 -V -S otherpkgs="I:bos.cpr" installp_flags="-agQXY"
```

Note: The ‘I:’ prefix is optional but recommended for installp packages.

10. To uninstall the “bos.cpr” fileset that was installed in the previous example.

```bash
updatenode xcn11 -V -S otherpkgs="I:bos.cpr" installp_flags="-u"
```

11. To update the AIX nodes “xcn11” and “xcn12” with the “gpfs.base” fileset and the “rsync” rpm using the installp flags “-agQXY” and the rpm flags “-i --nodeps”.

```bash
updatenode xcn11,xcn12 -V -S otherpkgs="I:gpfs.base,R:rsync-2.6.2-1.aix5.1.ppc.rpm" installp_flags="-agQXY" rpm_flags="-i --nodeps"
```

Note: Using the “-V” flag with multiple nodes may result in a large amount of output.

12. To uninstall the syncp rpm that was installed in the previous example.

```bash
updatenode xcn11 -V -S otherpkgs="R:rsync-2.6.2-1" rpm_flags="-e"
```

13. Update the AIX node “node01” using the software specified in the NIM “sslbnd” and “sshbnd” installp_bundle resources and the “-agQXY” installp flags.

```bash
updatenode node01 -V -S installp_bundle="sslbnd,sshbnd" installp_flags="-agQXY"
```

14. To get a preview of what would happen if you tried to install the “rsct.base” fileset on AIX node “node42”. (You must use the “-V” option to get the full output from the installp command.)

```bash
updatenode node42 -V -S otherpkgs="I:rsct.base" installp_flags="-apXY"
```

15. To check what rpm packages are installed on the AIX node “node09”. (You must use the “-c” flag so updatenode does not get a list of packages from the database.)
16. To install all software updates contained in the /images directory.

   updatenode node09 -V -c -S rpm_flags="-qa"

Note: Make sure the directory is exportable and that the permissions are set correctly for all the files. (Including the .toc file in the case of installp filesets.)

17. Install the interim fix package located in the /efixes directory.

   updatenode node29 -V -S -d /efixes otherpkgs=E:IZ38930TL0.120304.epkg Z

18. To uninstall the interim fix that was installed in the previous example.

   updatenode xcatsn11 -V -S -c emgr_flags="-r -L IZ38930TL0"

19. To update the security keys for the node “node01”

   updatenode node01 -k

20. To update the service nodes with the files to be synchronized to node group compute:

   updatenode compute -f

21. To run updatenode with the non-root userid “user1” that has been setup as an xCAT userid with sudo on node1 to run as root, do the following: See Granting_Users_xCAT_privileges for required sudo setup.

   updatenode node1 -l user1 -P syslog

22. In Sysclone environment, after capturing the delta changes from golden client to management node, to run updatenode to push these delta changes to target nodes.

   updatenode target-node -S

FILES

/opt/xcat/bin/updatenode

wcons.1

Name

wcons - windowed remote console

Synopsis

wcons [-t | --tile=n] [xterm-options] noderange
wcons [-h | --help | -v | --version]
Description

**wcons** provides access to the remote node serial console of a single or range of nodes or groups.  
**wcons** is a simple front-end to rcons in an xterm session for each console.

Options

- **-t | --tile=n**  
  Tile **wcons** windows from top left to bottom right. If *n* is specified then tile *n* across. If *n* is not specified then tile to edge of screen. If tiled **wcons** windows reach bottom right, then the windows start at top left overlaying existing **wcons** windows.

- **-h | --help**  
  Print help.

- **-v | --version**  
  Print version.

**xterm options**

See xterm(1). Any options other than those listed above are passed directly to xterm. **Note:** when given multiple nodes, wcons will override -title and tries to figure out optimal -geometry options for the xterms (however, -geometry can still be specified).

Files

**nodehm** table - xCAT node hardware management table. See nodehm(5)|nodehm.5 for further details. This is used to determine the console access method.

Examples

```
wcons node1-node5
wcons --tile --font=nil2 all
wcons -t 4 node1-node16
wcons -f vs -t 4 node1-node4
```

Bugs

Tile mode assumes that the width of the left window border is also the width of the right and bottom window border. Most window managers should not have a problem. If you really need support for a screwy window manager let me know.

See Also

noderange(3)|noderange.3, rcons(1)|rcons.1, xterm(1)
wkill.1

Name

wkill - kill windowed remote consoles

Synopsis

wkill [noderange]
wkill [-h | --help | -v | --version]

Description

wkill will kill the wcons windows on your $DISPLAY for a single or range or nodes or groups.
wkill was written because I’m too lazy to point and click off 64 windows.
wkill will only kill windows on your display and for only the noderange(3)noderange.3 you specify. If no noderange(3)noderange.3 is specified, then all wcons windows on your $DISPLAY will be killed.

Options

-h | --help
   Print help.
-v | --version
   Print version.

Examples

wkill node1-node5

See Also

noderange(3)noderange.3, wcons(1)wcons.1

wvid.1

Name

wvid - windowed remote video console for nodes

Synopsis

wvid noderange
Description

\texttt{wvid} provides access to the remote node video console of a single node, or range of nodes or groups. \texttt{wvid} provides a simple front-end to the hardware’s remote console capability. Currently this command is supported for: blades, BMC/IMM, KVM, and Xen.

The \texttt{nodehm.cons} attribute of the node determines the method used to open the console. See \texttt{nodehm(5)|nodehm.5} for further details.

Options

No options are supported at this time.

Examples

1. To open video consoles for the 1st 2 nodes:

\begin{verbatim}
  wvid node1,node2
\end{verbatim}

See Also

\texttt{noderange(3)|noderange.3, rcons(1)|rcons.1, wcons(1)|wcons.1}

\texttt{xCATWorld.1}

NAME

\texttt{xCATWorld} - Sample client program for xCAT.

SYNOPSIS

\texttt{xCATWorld noderange}

DESCRIPTION

The \texttt{xCATWorld} program gives you a sample client program that interfaces to the \texttt{/opt/xcat/lib/perl/xCAT_plugin/xCATWorld.pm} plugin. For debugging purposes we have an Environment Variable \texttt{XCATBYPASS}. If \texttt{export XCATBYPASS=yes}, the client will call the plugin without going through the \texttt{xcat} daemon, \texttt{xcatd}.

OPTIONS

0 The command completed successfully.
1 An error has occurred.
EXAMPLES

1. To run, enter:

```
xCATWorld nodegrp1
```

FILES

```
/opt/xcat/bin/xCATWorld
```

NOTES

This command is part of the xCAT software product.

xcat2nim.1

NAME

**xcat2nim** - Use this command to create and manage AIX NIM definitions based on xCAT node, group and network object definitions.

SYNOPSIS

```
xcat2nim [-h|--help]
```

DESCRIPTION

The **xcat2nim** command uses xCAT node, group and network object definitions to create, update, list, or remove corresponding NIM definitions.

Before you create or update NIM definitions the xCAT definitions must be created and NIM must be configured.

The **xcat2nim** command uses xCAT database information, command line input, and default values to run the appropriate NIM commands.

The xCAT node, group and network definition names will correspond to the NIM machine, machine group and network definitions.

Note: The length of a NIM object name must be no longer than 39 characters.

To create or update a NIM definition you must provide the names of the xCAT definitions to use. The default behavior is to create new NIM definitions but not apply updates to existing definitions. If you wish to update existing NIM definitions then you must use the “update” option. If you wish to completely remove the old definition and re-create it you must use the “force” option.

The xCAT code uses the appropriate NIM commands to create the NIM definitions. To create definitions the “nim -o define” operation is used. To update definitions the “nim -o change” operation is used. If you wish to specify additional information to pass to the NIM commands you can use the “attr=val” support. The attribute names must correspond to the attributes supported by the relevant NIM commands. (For example, “netboot_kernel=mp”)

1.3. Admin Guide 517
If the object type you are creating is a node then the object names can be a noderange value.

If you are using xCAT service nodes the `xcat2nim` command will automatically determine the correct server for the node and create the NIM definitions on that server.

The `xcat2nim` command support for NIM networks is limited to creating and listing.

When creating network definitions the command will check to make sure the network definition (or it’s equivalent) does not exist and then create the required NIM network, route and interface definitions. In some cases the equivalent network definition may exist using a different name. In this case a new definition WILL NOT be created.

To list the NIM definitions that were created you must specify the “list” option and the names of the xCAT objects that were used to create the NIM definitions. The `xcat2nim` command will list the corresponding NIM machine, machine group or network definitions using the “lsnim -l” command.

To remove NIM definitions you must specify the “remove” option and the names of the xCAT objects that were used to create the NIM definitions.

The remove(“-r”), force(“-f”) and update(“-u”) options are not supported for NIM network definitions.

OPTIONS

- **-a|--all** The list of objects will include all xCAT node, group and network objects.

  `attr=val [attr=val . . . ]` Specifies one or more “attribute equals value” pairs, separated by spaces. Attr=val pairs must be specified last on the command line. The attribute names must correspond to the attributes supported by the relevant NIM commands. When providing attr=val pairs on the command line you must not specify more than one object type.

- **-b|--backupSN** When using backup service nodes only update the backup. The default is to update both the primary and backup service nodes.

- **-f|--force** The force option will remove the existing NIM definition and create a new one.

- **-h|--help** Display the usage message.

- **-l|--list** List NIM definitions corresponding to xCAT definitions.

- **-o object-names** A set of comma delimited xCAT object names. Objects must be of type node, group, or network.

- **-p|--primarySN** When using backup service nodes only update the primary. The default is to update both the primary and backup service nodes.

- **-r|--remove** Remove NIM definitions corresponding to xCAT definitions.

- **-t object-types** A set of comma delimited xCAT object types. Supported types include: node, group, and network.

Note: If the object type is “group”, it means that the `xcat2nim` command will operate on a NIM machine group definition corresponding to the xCAT node group definition. Before creating a NIM machine group, all the NIM client nodes definition must have been created.

- **-u|--update** Update existing NIM definitions based on xCAT definitions.

- **-V|--verbose** Verbose mode.

RETURN VALUE

0 The command completed successfully.

1 An error has occurred.
EXAMPLES

1. To create a NIM machine definition corresponding to the xCAT node “clstrn01”.
   ```bash
cat2nim -t node -o clstrn01
   ```

2. To create NIM machine definitions for all xCAT node definitions.
   ```bash
cat2nim -t node
   ```

3. Update all the NIM machine definitions for the nodes contained in the xCAT “compute” node group and specify attribute values that will be applied to each definition.
   ```bash
cat2nim -u -t node -o compute netboot_kernel=mp cable_type="N/A"
   ```

4. To create a NIM machine group definition corresponding to the xCAT group “compute”.
   ```bash
cat2nim -t group -o compute
   ```

5. To create NIM network definitions corresponding to the xCAT “clstr_net” and “publc_net” network definitions. Also display verbose output.
   ```bash
cat2nim -V -t network -o "clstr_net,publc_net"
   ```

6. To list the NIM definition for node clstrn02.
   ```bash
cat2nim -l -t node clstrn02
   ```

7. To re-create a NIM machine definition and display verbose output.
   ```bash
cat2nim -V -t node -f clstrn05
   ```

8. To remove the NIM definition for the group “AIXnodes”.
   ```bash
cat2nim -t group -r -o AIXnodes
   ```

9. To list the NIM “clstr_net” definition.
   ```bash
cat2nim -l -t network -o clstr_net
   ```

FILES

$XCATROOT/bin/cat2nim

NOTES

This command is part of the xCAT software product.

SEE ALSO

mkdef(1)|mkdef.1
NAME

xcatchroot - Use this xCAT command to modify an xCAT AIX diskless operating system image.

SYNOPSIS

xcatchroot -h

xcatchroot [-V] -i osimage_name cmd_string

DESCRIPTION

For AIX diskless images this command will modify the AIX SPOT resource using the chroot command. You must include the name of an xCAT osimage definition and the command that you wish to have run in the spot.

WARNING:
Be very careful when using this command!!! Make sure you are very clear about exactly what you are changing so that you do not accidently corrupt the image.

As a precaution it is advisable to make a copy of the original spot in case your changes wind up corrupting the image.

When you are done updating a NIM spot resource you should always run the NIM check operation on the spot.

```nim -Fo check <spot_name>```

The xcatchroot command will take care of any of the required setup so that the command you provide will be able to run in the spot chroot environment. It will also mount the lpp_source resource listed in the osimage definition so that you can access additional software that you may wish to install.

For example, assume that the location of the spot named in the xCAT osimage definition is /install/nim/spot/614spot/usr. The associated root directory in this spot would be /install/nim/spot/614spot/usr/lpp/bos/inst_root. The chroot is automatically done to this new root directory. The spot location is mounted on /.../inst_root/usr so that when your command is run in the chroot environment it is actually running commands from the spot usr location.

Also, the location of the lpp_source resource specified in the osimage definition will be mounted to a subdirectory of the spot /.../inst_root directory. For example, if the lpp_source location is /install/nim/lpp_source/614lpp_lpp_source then that would be mounted over /install/nim/spot/614spot/usr/lpp/bos/inst_root/lpp_source.

When you provide a command string to run make sure you give the full paths of all commands and files assuming the /.../inst_root directory is you root directory.

If you wish to install software from the lpp_source location you would provide a directory location of /lpp_source (or /lpp_source/installp/ppc or /lpp_source/RPMS/ppc etc.) See the example below.

Always run the NIM check operation after you are done updating your spot. (ex. “nim -o check <spot_name>”)

OPTIONS

cmd_string
   The command you wish to have run in the chroot environment. (Use a quoted string.)

-h |--help
Display usage message.

-i osimage_name

The name of the xCAT osimage definition.

-V |--verbose

Verbose mode.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.

**EXAMPLES**

1) Set the root password to “cluster” in the spot so that when the diskless node boots it will have a root password set.

```
xcatchroot -i 614spot "/usr/bin/echo root:cluster | /usr/bin/chpasswd -c"
```

2. Install the bash rpm package.

```
xcatchroot -i 614spot "/usr/bin/rpm -Uvh /lpp_source/RPMS/ppc bash-3.2-1.aix5.2.ppc.rpm"
```

3. To enable system debug.

```
xcatchroot -i 614spot "bosdebug -D -M"
```

4. To set the “ipforwarding” system tunable.

```
xcatchroot -i 614spot "/sbin/no -r -o ipforwarding=1"
```

**FILES**

/opt/xcat/bin/xcatchroot

**NOTES**

This command is part of the xCAT software product.

*xcatperftest.1*

**NAME**

*xcatperftest* - Run xCAT command performance baseline testing on fake nodes.
**SYNOPSIS**

`xcatperftest [-?|-h] [PERF_DRYRUN=y] [PERF_NOCREATE=y] xcatperftest <total> [command-list-file]`

**DESCRIPTION**

The `xcatperftest` command runs commands defined in a command list file and get their execution response time baseline for performance purpose. The `xcatperftest` command is part of the xCAT package xCAT-test, and you can run it standalone or leverage it to build up your automation test cases.

Any commands could be defined in the command list file, however, it is recommended that the one-time initial configuration are well prepared prior to run `xcatperftest` command. For example, the network object, osdistor and osimage image objects.

Follow the below steps to run `xcatperftest` command:

1. Install xCAT-test on a xCAT management nodes.
2. Prepare a command list in which the commands are what you want to measure.
3. Prepare the initial configuration based on the command list to make sure all commands could be executed in technical.
4. Run `xcatperftest` with the total fake nodes number and the above command list file.

Node: It is suggested to run the command in background as it normally takes long time to finish all the performance testing with large amount of fake nodes.

**OPTIONS**

- `-?|-h`
  
  Display usage message.

- `<command-list-file>`
  
  Specifies the command list file with full-path. xCAT supports an example command file: 
  `/opt/xcat/share/xcat/tools/autotest/perfcmds.lst`

- `<total>`
  
  Total number of fake nodes will be defined during the testing.

**RETURN VALUE**

- 0 The command completed successfully.
- 1 An error has occurred.

**COMMAND LIST FILE**

The command list file is in flat text format, the testing framework will parse the file line by line, here is an example of the command list file:
Note: Each line defines one command, and the commands dependency should be handled by the line order. If you define a node range series line (started with #SERIES#) in this file, xcatperftest will run the command for each node range defined in series line.

#SERIES# To define a node range series, and the series should be an comma split incremental number sequence.

#STANZ# It will be replaced with real stanz file path when this command line runs.

#NODES# It will be replaced with real node range defined in #SERIES# line when this command line runs. If no series line, the node group will be used.

#PERFGRP# It will be replaced with node group when this command line runs.

ENVIRONMENT VARIABLE

The xcatperftest command supports be customized by some environment variables.

FAKE_NODE_PREFIX
Optional, the prefix of the fake compute node name. By default, the value is ‘fake’

FAKE_NODE_GROUP
# Optional, the group name of all the fake compute nodes. By default, the value is ‘perftest’

FAKE_NETWORK_PRO
Mandatory, the Provision network for all the fake compute nodes. By default, the value is ‘192.168’. It must be a string like ‘A.B’, and be matched with ‘tabdump networks’

FAKE_NETWORK_BMC
Mandatory, the BMC network for all the fake compute nodes. By default, the value is ‘192.168’. Note: It could not be the same subnet as ‘FAKE_NETWORK_PRO’ It must be a string like ‘A.B’ and no need to be defined in ‘networks’ table.

PERF_NODETEMPL
Optional, The node template name used for generating fake nodes. By default, it will be auto-detected according to the current arch.

PERF_DRYRUN
Optional, Indicate no real commands will be executed if the environment variable is set.

PERF_NOCREATE
Optional, Indicate no new fake nodes will be created if the environment variable is set.
EXEMPLARY

1. To run the performance testing for the commands defined in /tmp/cmd.lst on 5000 fake nodes:
   ```bash
   xcatperftest 5000 /tmp/cmd.lst
   ```

2. To generate an xCAT node object stanz file for 10000 nodes in subnet 10.100.0.0:
   ```bash
   FAKE_NETWORK_PRO=10.100 FAKE_NETWORK_BMC=10.200 xcatperftest 10000
   ```

3. To run the performance testing for the commands defined in /opt/xcat/share/xcat/tools/autotest/perfcmds.lst on 5000 existing fake nodes:
   ```bash
   PERF_NOCREATE=y xcatperftest 5000 /opt/xcat/share/xcat/tools/autotest/perfcmds.lst
   ```

FILES

/opt/xcat/bin/xcatperftest

/opt/xcat/share/xcat/tools/autotest/perfcmds.lst

xcattest.1

NAME

xcattest - Run automated xCAT test cases.

SYNOPSIS

xcattest [-?-h]

xcattest [-f configure file] [-b case bundle list]

xcattest [-f configure file] [-t case list]

xcattest [-f configure file] [-c cmd list]

xcattest [-b case bundle list] [-l]

xcattest [-t case list] [-l]

xcattest [-c cmd list] [-l]

xcattest [-s command]

xcattest [-s bundle]

DESCRIPTION

The xcattest command runs test cases to verify the xCAT functions, it can be used when you want to verify the xCAT functions for whatever reason, for example, to ensure the code changes you made do not break the existing commands; to run acceptance test for new build you got; to verify the xCAT snapshot build or development build before putting it onto your production system. The xcattest command is part of the xCAT package xCAT-test.
The root directory for the xCAT-test package is /opt/xcat/share/xcat/tools/autotest/. All test cases are in the sub directory testcase, indexed by the xCAT command, you can add your own test cases according to the test cases format below. The subdirectory bundle contains all the test cases bundles definition files, you can customize or create any test cases bundle file as required. The testing result information will be written into the subdirectory result, the timestamps are used as the postfixes for all the result files. xCAT-test package ships two configuration files template aix.conf.template and linux.conf.template for AIX and Linux environment, you can use the template files as the start point of making your own configuration file.

OPTIONS

-?|-h
Display usage message.

-f configure file
Specifies the configuration file with full-path. xCAT supports an example config file: /opt/xcat/share/xcat/tools/autotest/linux.conf.template

-b case bundle list
Comma separated list of test cases bundle files, each test cases bundle can contain multiple lines and each line for one test case name. The bundle files should be listed in: /opt/xcat/share/xcat/tools/autotest/bundle.

-t cases list
Comma separated list of test cases that will be run.

-c cmd list
Comma separated list of commands which will be tested, i.e., all the test cases under the command sub directory will be run.

-l
Display the test cases names specified by the flag -b, -t or -c.

-s
Display the bundle files and command with value: bundle or command.

RETURN VALUE

0 The command completed successfully.
1 An error has occurred.

TEST CASE FORMAT

The xCAT-test test cases are in flat text format, the testing framework will parse the test cases line by line, here is an example of the test case:

```
#required, case name
start:case name
#optional, description of the test case
description: what the test case is for?
#optional, environment requirements
os:AIX/Linux
```
**#optional, environment requirements**

<table>
<thead>
<tr>
<th>arch:ppc/x86</th>
</tr>
</thead>
</table>

**#optional, environment requirements**

<table>
<thead>
<tr>
<th>hcp:hmc/mm/bmc/fsp</th>
</tr>
</thead>
</table>

**#required, command need to run**

<table>
<thead>
<tr>
<th>cmd:command</th>
</tr>
</thead>
</table>

**#optional, check return code of last executed command**

<table>
<thead>
<tr>
<th>check:rc == or != return code</th>
</tr>
</thead>
</table>

**#optional, check output of last executed command**

<table>
<thead>
<tr>
<th>check:output== or != or =~ output check string</th>
</tr>
</thead>
</table>

end

**Note**: Each test case can have more than one *cmd* sections and each *cmd* section can have more than one *check:rc* sections and more than one *check:output* sections, the *output check string* can include regular expressions.

**EXAMPLES**

1. To run all test cases related command rpower:

   ```bash
   xcattest -f /tmp/config -c rpower
   ```

2. To run customized bundle with /tmp/config file:

   ```bash
   xcattest -c lsdef -l > /opt/xcat/share/xcat/tools/autotest/bundle/custom.bundle
   Modify custom.bundle
   xcattest -f /tmp/config -b custom.bundle
   ```

3. To run specified test cases with /tmp/config file:

   ```bash
   xcattest -f /tmp/config -t lsdef_t_o_l_z
   ```

4. To add a new case to test chvm. In the example, we assume that the *min_mem* should not be equal to 16 in the lpar profile of computenode. The case name is *chvm_custom*. It create a test lpar named testnode firstly, that change the *min_mem* of the lpar to 16 using chvm, then check if *min_mem* have changed correctly. At last, the testnode be remove to ensure no garbage produced in the cases.

   ```bash
   add a new test case file in /opt/xcat/share/xcat/tools/autotest/chvm
   edit filename
   start:chvm_custom
   hcp:hmc
   cmd:lsvm $$SCN > /tmp/autotest.profile
   check:rc==0
   cmd:mkdef -t node -o testnode mgt=hmc groups=all
   cmd:mkvm testnode -i $$MaxLparID -l $$SCN
   check:rc==0
   cmd:perl -pi -e 's/min_mem=\d+/min_mem=16/g' /tmp/autotest.profile
   cmd:cat /tmp/autotest.profile|chvm testnode
   check:rc==0
   cmd:lsvm testnode
   check:output=~min_mem=16
   cmd:rmvm testnode
   cmd:rm -f /tmp/autotest.profile
   end
   ```
INLINE FUNCTIONS

The xCAT-test testing framework provides some inline functions. The inline functions can be called in test cases as __FUNCTIONNAME(PARAMETERLIST)__ to get some necessary attributes defined in the configuration file. The inline functions can be used in cmd section and the check:output section.

1. GETNODEATTR(nodename, attribute) To get the value of specified node’s attribute

2. INC(digit) To get value of digit+1.

For example, to run rsan command against the hardware control point of compute node specified in the configuration file:

   rscan __GETNODEATTR($$CN, hcp)__ -z

3. GETTABLEVALUE(keyname, key, colname, table) To get the value of column where keyname == key in specified table.

FILES

/opt/xcat/bin/xcattest

xcoll.1

NAME

xcoll - Formats and consolidates the output of the psh, rinv commands.

SYNOPSIS

xcoll [-n] [-c]

DESCRIPTION

The xcoll command formats and consolidates output from the psh,rinv command. The xcoll command takes, as input, lines in the following format:

grouppname: line of output from remote command, will use group name, if defined

The xcoll command formats the lines as follows and writes them to standard output. Assume that the output from node3 and node4 is identical:

| ============================================================== |
| nodel or nodegroup name                                      |
| ============================================================== |
| . . lines from psh for nodel with hostnames stripped off     |
| . .                                                         |
| ============================================================== |

(continues on next page)
node2 or nodegroup name
====================================.

lines from psh for node2 with hostnames stripped off.

node3, node4 or nodegroup name
====================================.

lines from psh for node 3 with hostnames stripped off.

OPTIONS

-c
Display a total nodecount for each set of output.

-n
Display output as nodenames instead of groupnames.

EXAMPLES

1. To display the results of a command issued on several nodes, in the format used in the Description, enter:

   psh node1,node2,node3 cat /etc/passwd | xcoll

SEE ALSO

psh(1), xdshbak(1), xdshbak(1), xdshcoll(1), xdshcoll(1)

xdcp.1

NAME

xdcp - Concurrently copies files to or from multiple nodes. In addition, provides an option to use rsync to update the files on the nodes, or to an installation image on the local node.

SYNOPSIS


xdcp noderange [-F rsync input file]
**xdcp** computenoderange [-s -F rsync input file]

**xdcp** [-i path to install image] [-F rsync input file]

**xdcp** [-h | -V | -q]

### DESCRIPTION

The **xdcp** command concurrently copies files to or from remote target nodes. The command issues a remote copy command for each node or device specified. When files are pulled from a target, they are placed into the target_path with the name of the remote node or device appended to the copied source_file name. The /usr/bin/rcp command is the model for syntax and security. If using hierarchy, then xdcp runs on the service node that is servicing the compute node. The file will first be copied to the path defined in the site table, SNsyncfiledir attribute, or the default path /var/xcat/syncfiles on the service node, if the attribute is not defined. The -P flag will not automatically copy the files from the compute node to the Management node, hierarchically. There is a two step process, see -P flag. If the Management Node is target node, it must be defined in the xCAT database with nodetype=mn. When the **xdcp** command runs the Management Node as the target, it does not use remote commands but uses the local OS copy (**cp**) command.

**REMOTE USER:**

A user_ID can be specified for the remote copy command. Remote user specification is identical for the **xdcp** and **xdsh** commands. See the **xdsh** command for more information.

**REMOTE COMMAND COPY:**

The **xdcp** command uses a configurable remote copy command to execute remote copies on remote targets. Support is explicitly provided for Remote Shell rcp command, the OpenSSH scp command and the /usr/bin/rsync command.

For node targets, the remote copy command is determined by the following order of precedence:

1. The -r flag.
2. The /usr/bin/scp command.

**COMMAND EXECUTIONS:**

The maximum number of concurrent remote copy command processes (the fanout) can be specified with the -f flag or the DSH_FANOUT environment variable. The fanout is only restricted by the number of remote shell commands that can be run in parallel. You can experiment with the DSH_FANOUT value on your management server to see if higher values are appropriate.

A timeout value for remote copy command execution can be specified with the -t flag or DSH_TIMEOUT environment variable. If any remote target does not respond within the timeout value, the xdcp command displays an error message and exits.

The -T flag provides diagnostic trace information for dcp command execution. Default settings and the actual remote copy commands that are executed to the remote targets are displayed.

The **xdcp** command can be executed silently using the -Q flag; no target standard output or standard error is displayed.

### OPTIONS

**sourcefile...**

Specifies the complete path for the file to be copied to or from the target. Multiple files can be specified. When used with the -R flag, only a single directory can be specified. When used with the -P flag, only a single file can be specified.

**targetpath**
If one source_file file, then it specifies the file to copy the source_file file to on the target. If multiple source_file files, it specifies the directory to copy the source_file files to on the target. If the -P flag is specified, the target_path is the local host location for the copied files. The remote file directory structure is recreated under target_path and the remote target name is appended to the copied source_file name in the target_path directory. Note: the targetpath directory must exist.

-B | --bypass

Runs in bypass mode, use if the xcatd daemon is hung.

-f | --fanout fanout_value

Specifies a fanout value for the maximum number of concurrently executing remote shell processes. Serial execution can be specified by indicating a fanout value of 1. If -f is not specified, a default fanout value of 64 is used.

-F | --File rsync input file

Specifies the path to the file that will be used to build the rsync command. The format of the input file is as follows, each line contains:

```
<path to source file1> <path to source file2> ... -> < path to destination file/directory>
```

or

```
<path to source file> -> <path to destination file>
```

or

```
<path to source file> -> <path to destination directory ( must end in /)>
```

For example:

```
/etc/password /etc/hosts -> /etc
/tmp/file2 -> /tmp/file2
/tmp/file2 -> /tmp/
/tmp/filex -> /tmp/source/filey
/etc/* -> /etc/
```

Running postscripts after files are sync’d to the nodes:

After you define the files to rsync, you can add an EXECUTE: clause in the synclist file. The EXECUTE: clause will list all the postscripts that you would like to run after the files are sync’d to the node. The postscript file must be of the form filename.post, where the <filename> is the <filename> is the from <filename>, reside in the same directory as filename, and be executable. If the file filename is rsync’d to the node, then the filename.post will automatically be run on the node. If the file filename is not updated on the node, the filename.post will not be run.

Putting the filename.post in the file list to rsync to the node is required for hierarchical clusters. It is optional for non-hierarchical clusters.

Another option is the EXECUTEALWAYS: clause in the synclist file. The EXECUTEALWAYS: will list all the postscripts that you would like to run after the files are sync’d to the nodes. These scripts will run whether or not any files are sync’d to the nodes. The scripts have no special format, but must contain the fully qualified path.
The scripts must be also added to the file list to rsync to the node for hierarchical clusters. It is optional for non-hierarchical clusters.

For example, your rsynclist file may look like this:

```
/tmp/share/file2  ->  /tmp/file2
/tmp/share/file2.post  ->  /tmp/file2.post
/tmp/share/file3  ->  /tmp/file3
/tmp/share/file3.post  ->  /tmp/file3.post
/tmp/myscript  ->  /tmp/myscript
# the below are postscripts
EXECUTE:
  /tmp/share/file2.post
  /tmp/share/file3.post
EXECUTEALWAYS:
  /tmp/myscript
```

If /tmp/file2 and /tmp/file3 update /tmp/file2 and /tmp/file3 on the node, then the postscripts /tmp/file2.post and /tmp/file3.post are automatically run on the node. /tmp/myscript will always be run on the node.

Another option is the APPEND: clause in the synclist file. The APPEND: clause is used to append the contents of the input file to an existing file on the node. The file to append must already exist on the node and not be part of the synclist that contains the APPEND: clause.

For example, your rsynclist file may look like this:

```
/tmp/share/file2  ->  /tmp/file2
/tmp/share/file2.post  ->  /tmp/file2.post
/tmp/share/file3  ->  /tmp/file3
/tmp/share/file3.post  ->  /tmp/file3.post
/tmp/myscript  ->  /tmp/myscript
# the below are postscripts
EXECUTE:
  /tmp/share/file2.post
  /tmp/share/file3.post
EXECUTEALWAYS:
  /tmp/myscript
APPEND:
  /etc/myappenddir/appendfile  ->  /etc/mysetup/setup
  /etc/myappenddir/appendfile2  ->  /etc/mysetup/setup2
```

When you use the append script, the file (left) of the arrow is appended to the file right of the arrow. In this example, /etc/myappenddir/appendfile is appended to /etc/mysetup/setup file, which must already exist on the node. The /opt/xcat/share/xcat/scripts/xdcpappend.sh is used to accomplish this.

Another option is the MERGE: clause in the synclist file. The MERGE: clause is used to append the contents of the input file to /etc/passwd, /etc/group, or /etc/shadow on a Linux node. It is only supported for those files and only on Linux. You must not use both the APPEND and MERGE function for these three files. The processing could end up not creating the file you desire. The MERGE function is the preferred method, because APPEND only adds to the file. MERGE will add to the file but also insure there are no duplicate entries.

For example, your rsynclist file may look like this:

```
/tmp/share/file2  ->  /tmp/file2
/tmp/share/file2.post  ->  /tmp/file2.post
/tmp/share/file3  ->  /tmp/file3
/tmp/share/file3.post  ->  /tmp/file3.post
/tmp/myscript  ->  /tmp/myscript
# the below are postscripts EXECUTE:
  /tmp/share/file2.post
  /tmp/share/file3.post
EXECUTEALWAYS:
  /tmp/myscript APPEND:
  /custom/mypasswd  ->  /etc/passwd
  /custom/mygroups  ->  /etc/group
  /custom/myshadow  ->  /etc/shadow
```

Note: no order can be assumed by the order that the EXECUTE,EXECUTEALWAYS and APPEND
clause fall in the synclist file.

For more information on syncing files to node, read Sync-ing_Config_Files_to_Nodes

On Linux rsync always uses ssh remoteshell. On AIX, ssh or rsh is used depending on the site.useSSHonAIX attribute.

-h | --help
Displays usage information.

-i | --rootimg install image
Specifies the path to the install image on the local Linux node.

-o | --node-options node_options
Specifies options to pass to the remote shell command for node targets. The options must be specified within double quotation marks (""") to distinguish them from xdsh options.

-p | --preserve
Preserves the source file characteristics as implemented by the configured remote copy command.

-P | --pull
Pulls (copies) the files from the targets and places them in the target_path directory on the local host. The target_path must be a directory. Files pulled from remote machines have .target appended to the file name to distinguish between them. When the -P flag is used with the -R flag, .target is appended to the directory. Only one file per invocation of the xdcp pull command can be pulled from the specified targets. Hierarchy is not automatically support yet. You must first pull the file to the Service Node and then pull the file to the Management node.

-q | --show-config
Displays the current environment settings for all DSH Utilities commands. This includes the values of all environment variables and settings for all currently installed and valid contexts. Each setting is prefixed with context: to identify the source context of the setting.

-r | --node-rcp node_remote_copy
Specifies the full path of the remote copy command used for remote command execution on node targets.

-R | --recursive recursive
Recursively copies files from a local directory to the remote targets, or when specified with the -P flag, recursively pulls (copies) files from a remote directory to the local host. A single source directory can be specified using the source_file parameter.

-s synch service nodes
Will only sync the files listed in the synclist (-F), to the service nodes for the input compute node list. The files will be placed in the directory defined by the site.SNsyncfiledir attribute, or the default /var/xcat/syncfiles directory.

-t | --timeout timeout
Specifies the time, in seconds, to wait for output from any currently executing remote targets. If no output is available from any target in the specified timeout, xdsh displays an error and terminates execution for the remote targets that failed to respond. If timeout is not specified, xdsh waits indefinitely to continue processing output from all remote targets. When specified with the -i flag, the user is prompted for an additional timeout interval to wait for output.

-T | --trace
Enables trace mode. The `xdcp` command prints diagnostic messages to standard output during execution to each target.

`-v | --verify`

Verifies each target before executing any remote commands on the target. If a target is not responding, execution of remote commands for the target is canceled.

`-V | --version`

Displays the `xdcp` command version information.

**Environment Variables**

**DSH_ENVIRONMENT**

Specifies a file that contains environment variable definitions to export to the target before executing the remote command. This variable is overridden by the `-E` flag.

**DSH_FANOUT**

Specifies the fanout value. This variable is overridden by the `-f` flag.

**DSH_NODE_OPTS**

Specifies the options to use for the remote shell command with node targets only. This variable is overridden by the `-o` flag.

**DSH_NODE_RCP**

Specifies the full path of the remote copy command to use to copy local scripts and local environment configuration files to node targets.

**DSH_NODE_RSH**

Specifies the full path of the remote shell to use for remote command execution on node targets. This variable is overridden by the `-r` flag.

**DSH_NODEGROUP_PATH**

Specifies a colon-separated list of directories that contain node group files for the DSH context. When the `-a` flag is specified in the DSH context, a list of unique node names is collected from all node group files in the path.

**DSH_PATH**

Sets the command path to use on the targets. If DSH_PATH is not set, the default path defined in the profile of the remote user_ID is used.

**DSH_SYNTAX**

Specifies the shell syntax to use on remote targets; `ksh` or `csh`. If not specified, the `ksh` syntax is assumed. This variable is overridden by the `-S` flag.

**DSH_TIMEOUT**

Specifies the time, in seconds, to wait for output from each remote target. This variable is overridden by the `-t` flag.
Exit Status

Exit values for each remote copy command execution are displayed in messages from the xdcp command, if the remote copy command exit value is non-zero. A non-zero return code from a remote copy command indicates that an error was encountered during the remote copy. If a remote copy command encounters an error, execution of the remote copy on that target is bypassed.

The xdcp command exit code is 0, if the xdcp command executed without errors and all remote copy commands finished with exit codes of 0. If internal xdcp errors occur or the remote copy commands do not complete successfully, the xdcp command exit value is greater than 0.

Security

The xdcp command has no security configuration requirements. All remote command security requirements - configuration, authentication, and authorization - are imposed by the underlying remote command configured for xdsh. The command assumes that authentication and authorization is configured between the local host and the remote targets. Interactive password prompting is not supported; an error is displayed and execution is bypassed for a remote target if password prompting occurs, or if either authorization or authentication to the remote target fails. Security configurations as they pertain to the remote environment and remote shell command are userdefined.

Examples

1. To copy the /etc/hosts file from all nodes in the cluster to the /tmp/hosts.dir directory on the local host, enter:
   \[
   \text{xdcp all -P } /\text{etc/hosts } /\text{tmp/hosts.dir}
   \]
   A suffix specifying the name of the target is appended to each file name. The contents of the /tmp/hosts.dir directory are similar to:
   \[
   \begin{array}{ccc}
   \text{hosts._node1} & \text{hosts._node4} & \text{hosts._node7} \\
   \text{hosts._node2} & \text{hosts._node5} & \text{hosts._node8} \\
   \text{hosts._node3} & \text{hosts._node6} & \\
   \end{array}
   \]

2. To copy the directory /var/log/testlogdir from all targets in NodeGroup1 with a fanout of 12, and save each directory on the local host as /var/log._target, enter:
   \[
   \text{xdcp NodeGroup1 -f 12 -RP } /\text{var/log/testlogdir } /\text{var/log}
   \]

3. To copy /localnode/smallfile and /tmp/bigfile to /tmp on node1 using rsync and input -t flag to rsync, enter:
   \[
   \text{xdcp nodel } -r /\text{usr/bin/rsync -o "-t" /localnode/smallfile } /\text{tmp/bigfile } /\text{tmp}
   \]

4. To copy the /etc/hosts file from the local host to all the nodes in the cluster, enter:
   \[
   \text{xdcp all } /\text{etc/hosts } /\text{etc/hosts}
   \]

5. To copy all the files in /tmp/testdir from the local host to all the nodes in the cluster, enter:
   \[
   \text{xdcp all } /\text{tmp/testdir } /\text{tmp/testdir}
   \]

6. To copy all the files in /tmp/testdir and it’s subdirectories from the local host to node1 in the cluster, enter:
   \[
   \text{xdcp nodel } -R /\text{tmp/testdir } /\text{tmp/testdir}
   \]
7. To copy the /etc/hosts file from node1 and node2 to the /tmp/hosts.dir directory on the local host, enter:

```
xdcp node1,node2 -P /etc/hosts /tmp/hosts.dir
```

8. To rsync the /etc/hosts file to your compute nodes:

   Create a rsync file /tmp/myrsync, with this line:

   `/etc/hosts -> /etc/hosts`

   or

   `/etc/hosts -> /etc/` (last / is required)

   Run:

   ```
   xdcpc compute -F /tmp/myrsync
   ```

9. To rsync all the files in /home/mikev to the compute nodes:

   Create a rsync file /tmp/myrsync, with this line:

   `/home/mikev/* -> /home/mikev/` (last / is required)

   Run:

   ```
   xdcpc compute -F /tmp/myrsync
   ```

10. To rsync to the compute nodes, using service nodes, the command will first rsync the files to the /var/xcat/syncfiles directory on the service nodes and then rsync the files from that directory to the compute nodes. The /var/xcat/syncfiles default directory on the service nodes, can be changed by putting a directory value in the site table SNsyncfiledir attribute.

    Create a rsync file /tmp/myrsync, with this line:

    `/etc/hosts /etc/passwd -> /etc`

    or

    `/etc/hosts /etc/passwd -> /etc/`

    Run:

    ```
    xdcpc compute -F /tmp/myrsync
    ```

    to update the Compute Nodes

11. To rsync to the service nodes in preparation for rsyncing the compute nodes during an install from the service node.

    Create a rsync file /tmp/myrsync, with this line:

    `/etc/hosts /etc/passwd -> /etc`

    Run:

    ```
    xdcpc compute -s -F /tmp/myrsync
    ```

    to sync the service node for compute

12. To rsync the /etc/file1 and file2 to your compute nodes and rename to filex and filey:

    Create a rsync file /tmp/myrsync, with these line:

    `/etc/file1 -> /etc/filex`

    ```
    xdcpc compute -F /tmp/myrsync
    ```
12. To update the Compute Nodes:

Run:

```bash
xdcp compute -F /tmp/myrsync
```

to update the Compute Nodes

13. To rsync files in the Linux image at /install/netboot/fedora9/x86_64/compute/rootimg on the MN:

Create a rsync file /tmp/myrsync, with this line:

```
/etc/hosts /etc/passwd -> /etc
```

Run:

```bash
xdcp -i /install/netboot/fedora9/x86_64/compute/rootimg -F /tmp/myrsync
```

14. To define the Management Node in the database so you can use xdc

```bash
xcatconfig -m
```

**Files**

**SEE ALSO**

xdsh(1)|xdsh.1, noderange(3)|noderange.3

---

**xdsh.1**

**NAME**

*xdsh* - Concurrently runs remote commands on multiple nodes (Management Node, Service Nodes, compute nodes), or an install image.

**SYNOPSIS**

```bash
```

```bash
xdsh noderange [-K]
```

```bash
xdsh noderange [-K] [-l userID] --devicetype type_of_device
```

```bash
xdsh [-i image path | nim image name] command_list
```

```bash
xdsh noderange [-c]
```

```bash
xdsh [-h | -V | -q]
```
DESCRIPTION

The `xdsh` command runs commands in parallel on remote nodes and/or the Management Node. The `xdsh` command issues a remote shell command for each target specified, and returns the output from all targets, formatted so that command results from all nodes can be managed. If the command is to be executed on the Management Node, it does not use a remote shell command, but uses the local OS copy or shell command. The Management Node must be defined in the xCAT database. The best way to do this is to use the xcatconfig -m option. The `xdsh` command is an xCAT Distributed Shell Utility.

COMMAND SPECIFICATION:

The commands to execute on the targets are specified by the `command_list` `xdsh` parameter, or executing a local script using the `-e` flag.

The syntax for the `command_list` `xdsh` parameter is as follows:

```
command[; command]...
```

where `command` is the command to run on the remote target. Quotation marks are required to ensure that all commands in the list are executed remotely, and that any special characters are interpreted correctly on the remote target. A script file on the local host can be executed on each of the remote targets by using the `-e` flag. If `-e` is specified, `command_list` is the script name and arguments to the script. For example:

```
xdsh hostname -e script_filename [arguments]...
```

The `script_filename` file is copied to a random filename in the `/tmp` directory on each remote target and then executed on the targets.

The `xdsh` command does not work with any interactive commands, including those that read from standard input.

REMOTE SHELL COMMAND:

The `xdsh` command uses a configurable remote shell command to execute remote commands on the remote targets. Support is explicitly provided for AIX Remote Shell and OpenSSH, but any secure remote command that conforms to the IETF (Internet Engineering Task Force) Secure Remote Command Protocol can be used.

The remote shell is determined as follows, in order of precedence:

1. The `-r` flag.
2. The `DSH_NODE_RSH` environment variable.
3. The default node remote shell as defined by the target `context`.
4. The `/usr/bin/ssh` command.

The remote shell options are determined as follows, in order of precedence:

1. The `-o` flag.
2. The `DSH_NODE_OPTS` environment variable.

REMOTE SHELL ENVIRONMENT:

The shell environment used on the remote target defaults to the shell defined for the `user_ID` on the remote target. The command syntax that `xdsh` uses to form the remote commands can be specified using the `-S` flag. If `-S` is not specified, the syntax defaults to `sh` syntax.

When commands are executed on the remote target, the path used is determined by the `DSH_PATH` environment variable defined in the shell of the current user. If `DSH_PATH` is not set, the path used is the remote shell default path. For example, to set the local path for the remote targets, use:

```
DSH_PATH=$PATH
```
The **-E** flag exports a local environment definition file to each remote target. Environment variables specified in this file are defined in the remote shell environment before the *command_list* is executed. The file should be executable and contain one environment variable per line.

**COMMAND EXECUTION:**

The maximum number of concurrent remote shell command processes (the fanout) can be specified with the **-f** flag or with the **DSH_FANOUT** environment variable. The fanout is only restricted by the number of remote shell commands that can be run in parallel. You can experiment with the **DSH_FANOUT** value on your management server to see if higher values are appropriate.

A timeout value for remote command execution can be specified with the **-t** flag or with the **DSH_TIMEOUT** environment variable. If any remote target does not provide output to either standard output or standard error within the timeout value, **xdsh** displays an error message and exits.

If streaming mode is specified with the **-s** flag, output is returned as it becomes available from each target, instead of waiting for the *command_list* to complete on all targets before returning output. This can improve performance but causes the output to be unsorted.

The **-z** flag displays the exit code from the last command issued on the remote node in *command_list*. Note that OpenSSH behaves differently; it returns the exit status of the last remote command issued as its exit status. If the command issued on the remote node is run in the background, the exit status is not displayed.

The **-m** flag monitors execution of the **xdsh** command by printing status messages to standard output. Each status message is preceded by **dsh**.

The **-T** flag provides diagnostic trace information for the execution of the **xdsh** command. Default settings and the actual remote shell commands executed on the remote targets are displayed.

No error detection or recovery mechanism is provided for remote targets. The **xdsh** command output to standard error and standard output can be analyzed to determine the appropriate course of action.

**COMMAND OUTPUT:**

The **xdsh** command waits until complete output is available from each remote shell process and then displays that output before initiating new remote shell processes. This default behavior is overridden by the **-s** flag.

The **xdsh** command output consists of standard error and standard output from the remote commands. The **xdsh** standard output is the standard output from the remote shell command. The **xdsh** standard error is the standard error from the remote shell command. Each line is prefixed with the host name of the node that produced the output. The host name is followed by the : character and a command output line. A filter for displaying identical outputs grouped by node is provided separately. See the **xdshbak** command for more information.

A command can be run silently using the **-Q** flag; no output from each target’s standard output or standard error is displayed.

**SIGNALS:**

Signal 2 (INT), Signal 3 (QUIT), and Signal 15 (TERM) are propagated to the commands executing on the remote targets.

Signal 19 (CONT), Signal 17 (STOP), and Signal 18 (TSTP) default to **xdsh**; the **xdsh** command responds normally to these signals, but the signals do not have an effect on remotely executing commands. Other signals are caught by **xdsh** and have their default effects on the **xdsh** command; all current child processes, through propagation to remotely running commands, are terminated (SIGTERM).

**OPTIONS**

- **-B | --bypass**
  
  Runs in bypass mode, use if the xcatd daemon is hung.
-c | --cleanup

This flag will have xdsh remove all files from the subdirectories of the target directory on the service nodes, where xdcps the copy to the compute nodes as defined in the site table SNsyncfiledir and nodesynchfiledir attribute, when the target is a service node.

It can also be used to remove the nodesynchfiledir directory on the compute nodes, which keeps the backup copies of files for the xdcps APPEND function support, if a compute node is the target.

-e | --execute

Indicates that command_list specifies a local script filename and arguments to be executed on the remote targets. The script file is copied to the remote targets and then remotely executed with the given arguments. The DSH_NODE_RCP environment variables specify the remote copy command to use to copy the script file to node targets.

-E | --environment environment_file

Specifies that the environment_file contains environment variable definitions to export to the target before executing the command_list.

--devicetype type_of_device

Specify a user-defined device type that references the location of relevant device configuration file. The devicetype value must correspond to a valid device configuration file. xCAT ships some default configuration files for Ethernet switches and and IB switches under /opt/xcat/share/xcat/devicetype directory. If you want to override any of the configuration files, copy them to /var/opt/xcat/directory and customize. For example, base/IBSwitch/Qlogic/config is the configuration file location if devicetype is specified as IBSwitch::Qlogic. xCAT will first search config file using /var/opt/xcat/ as the base. If not found, it will search for it using /opt/xcat/share/xcat/devicetype/ as the base.

-f | --fanout fanout_value

Specifies a fanout value for the maximum number of concurrently executing remote shell processes. Serial execution can be specified by indicating a fanout value of 1. If -f is not specified, a default fanout value of 64 is used.

-h | --help

Displays usage information.

-i | --rootimg install image

For Linux, Specifies the path to the install image on the local node. For AIX, specifies the name of the osimage on the local node. Run lsnim for valid names. xdsh will chroot (xcatchroot for AIX) to this path and run the xdsh command against the install image. No other xdsh flags, environment variables apply with this input. A noderange is not accepted. Only runs on the local host, normally the Management Node. The command you run must not prompt for input, the prompt will not be returned to you, and it will appear that xdsh hangs.

-K | --ssh-setup

-1 | --rootimg install image

For Linux, Specifies the path to the install image on the local node. For AIX, specifies the name of the osimage on the local node. Run lsnim for valid names. xdsh will chroot (xcatchroot for AIX) to this path and run the xdsh command against the install image. No other xdsh flags, environment variables apply with this input. A noderange is not accepted. Only runs on the local host, normally the Management Node. The command you run must not prompt for input, the prompt will not be returned to you, and it will appear that xdsh hangs.

-K | --ssh-setup

-1 | --user user_ID --devicetype type_of_device

Set up the SSH keys for the user running the command to the specified node list. The userid must have the same uid, gid and password as the userid on the node where the keys will be setup.

If the current user is root, roots public ssh keys will be put in the authorized_keys* files under roots .ssh directory on the node(s). If the current user is non-root, the user must be in the policy table and have credential to run the xdsh command. The non-root users public ssh keys and root’s public ssh keys will be put in the authorized_keys* files under the non-root users .ssh directory on the node(s). Other device types, such as IB switch, are also supported. The device should be defined as a node and nodetype should be defined as switch before connecting. The xdsh -K command must be run from the Management Node.
-l | --user user_ID
   Specifies a remote user name to use for remote command execution.

-L | --no-locale
   Specifies to not export the locale definitions of the local host to the remote targets. Local host locale
   definitions are exported by default to each remote target.

-m | --monitor
   Monitors remote shell execution by displaying status messages during execution on each target.

-o | --node-options node_options
   Specifies options to pass to the remote shell command for node targets. The options must be specified
   within double quotation marks (""') to distinguish them from xdsh options.

-q | --show-config
   Displays the current environment settings for all DSH Utilities commands. This includes the values of all
   environment variables and settings for all currently installed and valid contexts. Each setting is prefixed
   with context: to identify the source context of the setting.

-Q | --silent
   Specifies silent mode. No target output is written to standard output or standard error. Monitoring mes-
   sages are written to standard output.

-r | --node-rsh node_remote_shell
   Specifies the path of the remote shell command used for remote command execution on node targets.

-s | --stream
   Specifies that output is returned as it becomes available from each target, instead of waiting for the com-
   mand_list to be completed on a target before returning output.

-S | --syntax {csh | ksh}
   Specifies the shell syntax to be used on the remote target. If not specified, the ksh syntax is used.

--sudo
   Adding the --sudo flag to the xdsh command will have xdsh run sudo before running the command. This
   is particular useful when using the -e option. This is required when you input -l with a non-root user id
   and want that id to be able to run as root on the node. The non-root userid will must be previously defined
   as an xCAT user, see process for defining non-root ids in xCAT and setting up for using xdsh. The userid
   sudo setup will have to be done by the admin on the node. This includes, allowing all commands that
   you would like to run with xdsh by using visudo to edit the /etc/sudoers file. You must disabl ssh tty
   requirements by commenting out or removing this line in the /etc/sudoers file “#Defaults requiretty”. See
   the document Granting_Users_xCAT_privileges for sudo setup requirements. This is not supported in a
   hierarical cluster, that is the nodes are serviced by servicenodes.

-t | --timeout timeout
   Specifies the time, in seconds, to wait for output from any currently executing remote targets. If no output
   is available from any target in the specified timeout, xdsh displays an error and terminates execution for
   the remote targets that failed to respond. If timeout is not specified, xdsh waits indefinitely to continue
   processing output from all remote targets. The exception is the -K flag which defaults to 10 seconds.

-T | --trace
   Enables trace mode. The xdsh command prints diagnostic messages to standard output during execution
   to each target.
-v | --verify

Verifies each target before executing any remote commands on the target. If a target is not responding, execution of remote commands for the target is canceled. When specified with the -i flag, the user is prompted to retry the verification request.

-V | --version

Displays the xdsh command version information.

-X env_list

Ignore xdsh environment variables. This option can take an argument which is a comma separated list of environment variable names that should NOT be ignored. If there is no argument to this option, or the argument is an empty string, all xdsh environment variables will be ignored. This option is useful when running xdsh from within other scripts when you don’t want the user’s environment affecting the behavior of xdsh.

-z | --exit-status

Displays the exit status for the last remotely executed non-asynchronous command on each target. If the command issued on the remote node is run in the background, the exit status is not displayed.

Exit values for each remote shell execution are displayed in messages from the xdsh command, if the remote shell exit values are non-zero. A non-zero return code from a remote shell indicates that an error was encountered in the remote shell. This return code is unrelated to the exit code of the remotely issued command. If a remote shell encounters an error, execution of the remote command on that target is bypassed.

The xdsh command exit code is 0 if the command executed without errors and all remote shell commands finished with exit codes of 0. If internal xdsh errors occur or the remote shell commands do not complete successfully, the xdsh command exit value is greater than 0. The exit value is increased by 1 for each successive instance of an unsuccessful remote command execution. If the remotely issued command is run in the background, the exit code of the remotely issued command is 0.

Environment Variables

DEVICETYPE

Specify a user-defined device type. See --devicetype flag.

DSH_ENVIRONMENT

Specifies a file that contains environment variable definitions to export to the target before executing the remote command. This variable is overridden by the -E flag.

DSH_FANOUT

Specifies the fanout value. This variable is overridden by the -f flag.

DSH_NODE_OPTS

Specifies the options to use for the remote shell command with node targets only. This variable is overridden by the -o flag.

DSH_NODE_RCP

Specifies the full path of the remote copy command to use to copy local scripts and local environment configuration files to node targets.

DSH_NODE_RSH
Specifies the full path of the remote shell to use for remote command execution on node targets. This variable is overridden by the -r flag.

**DSH_PATH**

Sets the command path to use on the targets. If DSH_PATH is not set, the default path defined in the profile of the remote user_ID is used.

**DSH_REMOTE_PASSWORD**

If DSH_REMOTE_PASSWORD is set to the password of the userid (usually root) that will ssh to the node, then when you use the -K flag, you will not be prompted for a password.

**DSH_SYNTAX**

Specifies the shell syntax to use on remote targets; ksh or csh. If not specified, the ksh syntax is assumed. This variable is overridden by the -S flag.

**DSH_TIMEOUT**

Specifies the time, in seconds, to wait for output from each remote target. This variable is overridden by the -t flag.

**DSH_VERIFY**

Verifies each target before executing any remote commands on the target. If a target is not responding, execution of remote commands for the target is canceled. This variable is overridden by the -v flag.

**Compatibility with AIX dsh**

To provide backward compatibility for scripts written using dsh in AIX and CSM, a tool has been provided groupfiles4dsh, which will build node group files from the xCAT database that can be used by dsh. See man groupfiles4dsh.

**SECURITY**

The xdsh command has no security configuration requirements. All remote command security requirements - configuration, authentication, and authorization - are imposed by the underlying remote command configured for xdsh. The command assumes that authentication and authorization is configured between the local host and the remote targets. Interactive password prompting is not supported; an error is displayed and execution is bypassed for a remote target if password prompting occurs, or if either authorization or authentication to the remote target fails. Security configurations as they pertain to the remote environment and remote shell command are userdefined.

**EXIT STATUS**

The xdsh command exit code is 0 if the command executed without errors and all remote shell commands finished with exit codes of 0. If internal dsh errors occur or the remote shell commands do not complete successfully, the dsh command exit value is greater than 0. The exit value is increased by 1 for each successive instance of an unsuccessful remote command execution. If the remotely issued command is run in the background, the exit code of the remotely issued command is 0.

**EXAMPLES**

1. To set up the SSH keys for root on node1, run as root:
2. To run the `ps -ef` command on node targets `node1` and `node2`, enter:
```
xdsh node1,node2 "ps -ef"
```

3. To run the `ps` command on node targets `node1` and run the remote command with the `-v` and `-t` flag, enter:
```
xdsh node1,node2 -o "-v -t" ps
```

4. To execute the commands contained in `myfile` in the XCAT context on several node targets, with a fanout of 1, enter:
```
xdsh node1,node2 -f 1 -e myfile
```

5. To run the `ps` command on node1 and ignore all the dsh environment variable except the DSH_NODE_OPTS, enter:
```
xdsh node1 -X `DSH_NODE_OPTS` ps
```

6. To run on Linux, the xdsh command “rpm -qa | grep xCAT” on the service node fedora9 diskless image, enter:
```
xdsh -i /install/netboot/fedora9/x86_64/service/rootimg "rpm -qa | grep xCAT"
```

7. To run on AIX, the xdsh command “lslpp -l | grep bos” on the NIM 611dskls spot, enter:
```
xdsh -i 611dskls "/usr/bin/lslpp -l | grep bos"
```

8. To cleanup the servicenode directory that stages the copy of files to the nodes, enter:
```
xdsh servicenoderange -c
```

9. To define the QLogic IB switch as a node and to set up the SSH keys for IB switch `qswitch` with device configuration file `/var/opt/xcat/IBSwitch/Qlogic/config` and user name `username`, enter
```
chdef -t node -o qswitch groups=all nodetype=switch
xdsh qswitch -K -l username --devicetype IBSwitch::Qlogic
```

10. To define the Management Node in the database so you can use `xdsh`, enter
```
xcatconfig -m
```

11. To define the Mellanox switch as a node and run a command to show the ssh keys. `mswitch` with and user name `username`, enter
```
chdef -t node -o mswitch groups=all nodetype=switch
xdsh mswitch -l admin --devicetype IBSwitch::Mellanox 'enable;configure
˓→terminal;show ssh server host-keys'
```

12. To define a BNT Ethernet switch as a node and run a command to create a new vlan with vlan id 3 on the switch.
```
chdef myswitch groups=all
tabch switch=myswitch switches.sshusername=admin switches.
˓→sshpassword=password switches.protocol=[ssh|telnet]
```

where `admin` and `password` are the SSH user name and password for the switch.
If it is for Telnet, add \textit{tn:} in front of the user name: \textit{tn:admin}.

\begin{verbatim}
dsh myswitch --devicetype EthSwitch::BNT 'enable;configure terminal;vlan 3; end;show vlan'
\end{verbatim}

13. To run \texttt{xdsh} with the non-root userid \texttt{"user1"} that has been setup as an xCAT userid and with sudo on node1 and node2 to run as root, do the following, see xCAT doc on Granting_Users_xCAT_privileges:

\begin{verbatim}
dsh node1,node2 --sudo -l user1 "cat /etc/passwd"
\end{verbatim}

### Files

SEE ALSO

\texttt{xdshbak(1)|xdshbak.1, noderange(3)|noderange.3, groupfiles4dsh(1)|groupfiles4dsh.1}

\texttt{xdshbak.1}

**NAME**

\texttt{xdshbak} - Formats the output of the \texttt{xdsh} command.

**SYNOPSIS**

\texttt{xdshbak [-c | -x [ -b ] | -h | -q]}

**DESCRIPTION**

The \texttt{xdshbak} command formats output from the \texttt{xdsh} command. The \texttt{xdshbak} command takes, as input, lines in the following format:

\begin{verbatim}
host_name: line of output from remote command
\end{verbatim}

The \texttt{xdshbak} command formats the lines as follows and writes them to standard output. Assume that the output from node3 and node4 is identical, and the \texttt{-c} (collapse) flag was specified:

\begin{verbatim}
HOSTS --------------------------------------------------------
node1 --------------------------------------------------------

lines from xdsh for node1 with hostnames stripped off

HOSTS --------------------------------------------------------
node2 --------------------------------------------------------

lines from xdsh for node2 with hostnames stripped off
\end{verbatim}

(continues on next page)
When output is displayed from more than one node in collapsed form, the host names are displayed alphabetically. When output is not collapsed, output is displayed sorted alphabetically by host name.

If the -q quiet flag is not set then xdshbak command writes “.” for each 1000 lines of output processed (to show progress), since it won’t display the output until it has processed all of it.

If the -x flag is specified, the extra header lines that xdshbak normally displays for each node will be omitted, and the hostname at the beginning of each line is not stripped off, but xdshbak still sorts the output by hostname for easier viewing:

```
node1: lines from xdsh for node1
      
node2: lines from xdsh for node2
```

If the -b flag is specified in addition to -x, the hostname at the beginning of each line is stripped.

### Standard Error

When the xdshbak filter is used and standard error messages are generated, all error messages on standard error appear before all standard output messages. This is true with and without the -c flag.

### OPTIONS

- **-b**
  
  Strip the host prefix from the beginning of the lines. This only works with the -x option.

- **-c**
  
  If the output from multiple nodes is identical it will be collapsed and displayed only once.

- **-x**
  
  Omit the extra header lines that xdshbak normally displays for each node. This provides more compact output, but xdshbak still sorts the output by node name for easier viewing. This option should not be used with -c.

- **-h**
  
  Displays usage information.

- **-q**
  
  Quiet mode, do not display “.” for each 1000 lines of output.
EXAMPLES

1. To display the results of a command issued on several nodes, in the format used in the Description, enter:

   xdsh node1,node2,node3 cat /etc/passwd | xdshbak

2. To display the results of a command issued on several nodes with identical output displayed only once, enter:

   xdsh host1,host2,host3 pwd | xdshbak -c

3. To display the results of a command issued on several nodes with compact output and be sorted alphabetically by host name, enter:

   xdsh host1,host2,host3 date | xdshbak -x

SEE ALSO

xdsh(1)|xdsh.1, xcoll(1)|xcoll.1

xdshcoll.1

NAME

xdshcoll - Formats and consolidates the output of the xdsh, inv commands.

SYNOPSIS

xdshcoll

DESCRIPTION

The xdshcoll command formats and consolidates output from the xdsh, inv command. The xdshcoll command takes, as input, lines in the following format:

host_name: line of output from remote command

The xdshcoll command formats the lines as follows and writes them to standard output. Assume that the output from node3 and node4 is identical:

```
====================================
node1
====================================
```

(continues on next page)
EXAMPLES

1. To display the results of a command issued on several nodes, in the format used in the Description, enter:

   xdsh node1,node2,node3 cat /etc/passwd > | B<xdshcoll

SEE ALSO

xdshbak(1)|xdshbak.1

xpbsnodes.1

NAME

xpbsnodes - PBS pbsnodes front-end for a noderange.

SYNOPSIS

xpbsnodes 

xpbsnodes [[noderange]] [[offline | clear | stat | state]]

xpbsnodes [-h | --help] [-v | --version]

DESCRIPTION

xpbsnodes is a front-end to PBS pbsnode but uses xCAT's noderange to specify nodes.

OPTIONS

-h|--help Display usage message.
-v|--version Command Version.
offline|off Take nodes offline.
clear|online|on Take nodes online.

stat|state Display PBS node state.

**RETURN VALUE**

0 The command completed successfully.
1 An error has occurred.

**EXAMPLES**

1. To display status of all PBS nodes, enter:

   xpbsnodes all stat

**FILES**

/opt/torque/x86_64/bin/xpbsnodes

**SEE ALSO**

noderange(3)noderange.3

**Name**

noderange - syntax for compactly expressing a list of node names

**Synopsis**

*Examples:*

   node1,node2,node8,node20,group1
   node14–node56,node70–node203,group1–group10
   node1,node2,node8,node20,node14–node56,node70–node203
   node[14–56]
   f[1–3]n[1–20]
   all,node129–node256,–frame01–frame03
   /node.*

(continues on next page)
^/tmp/nodes
node0+5
10-15,-13
group1@group2
table.attribute<operator>value

**Description**

`noderange` is a syntax that can be used in most xCAT commands to conveniently specify a list of nodes. The result is that the command will be applied to a range of nodes, often in parallel.

If you invoke xCAT `noderange` from a shell you may need to quote the `noderange` if the shell would otherwise treat the punctuation marks in the `noderange` as control operators. The affected punctuation marks may include Asterisk (`*`), Left Square Bracket (`[`), Right Square Bracket (`]`), Circumflex Accent (`^`), and Overline (`~`).

`noderange` is a comma-separated list. Each token (text between commas) in the list can be any of the forms listed below:

**Individual node or group:**

```
node01
group1
```

**A range of nodes or groups:**

```
node01-node10  (equivalent to: node01,node02,node03,...node10)
node[01-10]   (same as above)
node01:node10  (same as above)
node[01:10]   (same as above)
f[1-2]n[1-3]  (equivalent to: f1n1,f1n2,f1n3,f2n1,f2n2,f2n3)
group1-group3 (equivalent to: group1,group2,group3)
```

(all the permutations supported above for nodes are also supported for groups)

`nodeRange` tries to be intelligent about detecting padding, so you can specify “node001-node200” and it will add the proper number of zeroes to make all numbers 3 digits.

**An incremented range of nodes:**

```
node0+3   (equivalent to: node01,node11,node12,node13)
```

**A node shorthand range of nodes:**

```
10-20    (equivalent to: node10,node11,node12,...node20)
10+3    (equivalent to: node10,node11,node12,node13)
```

Currently, the prefix that will be prepended for the above syntax is always “node”. Eventually, the prefix and optional suffix will be settable via the environment variables XCAT_NODE_PREFIX and XCAT_NODE_SUFFIX, but currently this only works in bypass mode.

**A regular expression match of nodes or groups:**
XCAT3 Documentation, Release 2.14.5

The path of a file containing noderanges of nodes or groups:

```
^/tmp/nodelist
```

where /tmp/nodelist can contain entries like:

```
# my node list (this line ignored)
^/tmp/foo # ignored
node01   # node comment
node02
node03
node10-node20
^/tmp/[456].*  
-node50
```

Node ranges can contain any combination:

```
node01-node30,node40,^/tmp/nodes,/node[13].*,2-10,node50+5
```

Any individual noderange may be prefixed with an exclusion operator (default -) with the exception of the file operator (default ^). This will cause that individual noderange to be subtracted from the total resulting list of nodes.

The intersection operator @ calculates the intersection of the left and right sides:

```
group1@group2   (will result in the list of nodes that group1 and group2 have in common)
```

Any combination or multiple combinations of inclusive and exclusive ranges of nodes and groups is legal. There is no precedence implied in the order of the arguments. Exclusive ranges have precedence over inclusive. Parentheses can be used to explicitly specify precedence of any operators.

Nodes have precedence over groups. If a node range match is made then no group range match will be attempted.

All node and group names are validated against the nodelist table. Invalid names are ignored and return nothing.

**xCAT Node Name Format**

Throughout this man page the term **xCAT Node Name Format** is used. **xCAT Node Name Format** is defined by the following regex:

```
^([A-Za-z-]+)\([0-9]+\)\{([A-Za-z-])+([A-Za-z0-9-]+)+\}
```

In plain English, a node or group name is in **xCAT Node Name Format** if starting from the beginning there are:

* one or more alpha characters of any case and any number of “-” in any combination
* followed by one or more numbers
* then optionally followed by one alpha character of any case or “-“
* followed by any combination of case mixed alphanumerics and “-“

**noderange** supports node/group names in *any* format. **xCAT Node Name Format** is *not* required, however some node range methods used to determine range will not be used for non-conformant names.

Example of **xCAT Node Name Format** node/group names:
**Examples**

1. Generates a list of all nodes (assuming all is a group) listed in the `nodelist` table less node5 through node10:
   ```
   all,-node5-node10
   ```

2. Generates a list of nodes 1 through 10 less nodes 3,4,5. Note that node4 is listed twice, first in the range and then at the end. Because exclusion has precedence node4 will be excluded.
   ```
   node1-node10,-node3-node5,node4
   ```

3. Generates a list of nodes 1 through 10 less nodes 3 and 5.
   ```
   node1-node10,-node3,-node5
   ```

4. Generates a list of all (assuming ‘all’ is a group) nodes in the `nodelist` table less 17 through 32.
   ```
   -node17-node32,all
   ```

5. Generates a list of nodes 1 through 128, and user nodes 1 through 4.
   ```
   node1-node128,user1-user4
   ```

6. Generates a list of all nodes (assuming ‘all’ is a group), less nodes in groups rack1 through rack3 (assuming groups rack1, rack2, and rack3 are defined), less nodes 100 through 200, less nodes in the storage group. Note that node150 is listed but is excluded.
   ```
   all,-rack1-rack3,-node100-node200,node150,-storage
   ```

7. Generates a list of nodes matching the regex `node[23].*`. That is all nodes that start with node2 or node3 and end in anything or nothing. E.g. node2, node3, node20, node30, node21234 all match.
   ```
   /node[23].*
   ```

8. Generates a list of nodes which have the value hmc in the nodehm.cons attribute.
   ```
   nodehm.cons==hmc
   nodehm.cons=~hmc
   ```

9. Generate a list of nodes in the 1st two frames:
   ```
   f[1-2]n[1-42]
   ```
Bugs

The special characters used by xCAT noderange are also special characters to many shell programs. In particular, the characters '*', '[', ']', '^', and '~' may have to be escaped from the shell.

SEE ALSO

nodels(1)|nodels.1
man5
auditlog.5

NAME

auditlog - a table in the xCAT database.

SYNOPSIS

auditlog Attributes: recid, audittime, userid, clientname, clienttype, command, noderange, args, status, comments, disable

DESCRIPTION

Audit Data log.

auditlog Attributes:

recid
   The record id.
audittime
   The timestamp for the audit entry.
userid
   The user running the command.
clientname
   The client machine, where the command originated.
clienttype
   Type of command: cli, java, webui, other.
command
   Command executed. See auditskipcmds site table attribute to control which commands get logged.
noderange
The noderange on which the command was run.

**args**

The command argument list.

**status**

Allowed or Denied.

**comments**

Any user-provided notes.

**disable**

Do not use. tabprune will not work if set to yes or 1

### SEE ALSO

node(1), chtab(8), tabdump(8), tabedit(8)

### bootparams.5

#### NAME

**bootparams** - a table in the xCAT database.

#### SYNOPSIS

**bootparams Attributes:** node, kernel, initrd, kcmdline, addkcmdline, dhcpstatements, adddhcpstatements, comments, disable

#### DESCRIPTION

Current boot settings to be sent to systems attempting network boot for deployment, stateless, or other reasons. Mostly automatically manipulated by xCAT.

**bootparams Attributes:**

**node**

The node or group name

**kernel**

The kernel that network boot actions should currently acquire and use. Note this could be a chained boot loader such as memdisk or a non-linux boot loader

**initrd**

The initial ramdisk image that network boot actions should use (could be a DOS floppy or hard drive image if using memdisk as kernel)

**kcmdline**
Arguments to be passed to the kernel

addkcmdline

User specified kernel options for os provision process(no prefix) or the provisioned os(with prefix “R::”). The options should be delimited with spaces(” “)

dhcpstatements

xCAT manipulated custom dhcp statements (not intended for user manipulation)

adddhcpstatements

Custom dhcp statements for administrator use (not implemented yet)

comments

Any user-written notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

boottarget.5

NAME

boottarget - a table in the xCAT database.

SYNOPSIS

boottarget Attributes: bprofile, kernel, initrd, kcmdline, comments, disable

DESCRIPTION

Specify non-standard initrd, kernel, and parameters that should be used for a given profile.

boottarget Attributes:

bprofile

All nodes with a nodetype.profile value equal to this value and nodetype.os set to “boottarget”, will use the associated kernel, initrd, and kcmdline.

kernel

The kernel that network boot actions should currently acquire and use. Note this could be a chained boot loader such as memdisk or a non-linux boot loader

initrd
The initial ramdisk image that network boot actions should use (could be a DOS floppy or hard drive image if using memdisk as kernel)

**kcmdline**
Arguments to be passed to the kernel

**comments**
Any user-written notes.

**disable**
Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

cfgmgt.5

NAME

cfgmgt - a table in the xCAT database.

SYNOPSIS

cfgmgt Attributes: node, cfgmgr, cfgserver, roles, comments, disable

DESCRIPTION

Configuration management data for nodes used by non-xCAT osimage management services to install and configure software on a node.

cfgmgt Attributes:

node
The node being managed by the cfgmgr service

cfgmgr
The name of the configuration manager service. Currently ‘chef’ and ‘puppet’ are supported services.

cfgserver
The xCAT node name of the chef server or puppet master

roles
The roles associated with this node as recognized by the cfgmgr for the software that is to be installed and configured. These role names map to chef recipes or puppet manifest classes that should be used for this node. For example, chef OpenStack cookbooks have roles such as mysql-master,keystone, glance, nova-controller, nova-conductor, cinder-all.

comments
Any user-written notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

chain.5

NAME

chain - a table in the xCAT database.

SYNOPSIS

chain Attributes: node, currstate, currchain, chain, ondiscover, comments, disable

DESCRIPTION

Controls what operations are done (and it what order) when a node is discovered and deployed.

chain Attributes:

node

The node name or group name.

currstate

The current or next chain step to be executed on this node by xCAT-genesis. Set by xCAT during node discovery or as a result of nodeset.

currchain

The chain steps still left to do for this node. This attribute will be automatically adjusted by xCAT while xCAT-genesis is running on the node (either during node discovery or a special operation like firmware update). During node discovery, this attribute is initialized from the chain attribute and updated as the chain steps are executed.

chain

A comma-delimited chain of actions to be performed automatically when this node is discovered for the first time. (xCAT and the DHCP server do not recognize the MAC address of the node when xCAT initializes the discovery process.) The last step in this process is to run the operations listed in the chain attribute, one by one. Valid values: boot, runcmd=<cmd>, runimage=<URL>, shell, standby. For example, to have the genesis kernel pause to the shell, use chain=shell.

ondiscover

This attribute is currently not used by xCAT. The “nodediscover” operation is always done during node discovery.
comments

   Any user-written notes.

disable

   Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

deps.5

NAME

deps - a table in the xCAT database.

SYNOPSIS

deps Attributes: node, nodedep, msdelay, cmd, comments, disable

DESCRIPTION

Describes dependencies some nodes have on others. This can be used, e.g., by rpower -d to power nodes on or off in the correct order.

deps Attributes:

node

   The node name or group name.

nodedep

   Comma-separated list of nodes or node groups it is dependent on.

msdelay

   How long to wait between operating on the dependent nodes and the primary nodes.

cmd

   Comma-separated list of which operation this dependency applies to.

comments

   Any user-written notes.

disable

   Set to ‘yes’ or ‘1’ to comment out this row.
SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

discoverydata.5

NAME

discoverydata - a table in the xCAT database.

SYNOPSIS

discoverydata Attributes: uuid, node, method, discoverytime, arch, cpucount, cputype, memory, mtm, serial, nicdriver, nicipv4, nichwaddr, nicpci, nicloc, niconboard, nicfirm, switchname, switchaddr, switchdesc, switchport, otherdata, comments, disable

DESCRIPTION

Discovery data which sent from genesis.

discoverydata Attributes:

uuid

The uuid of the node which send out the discovery request.

node

The node name which assigned to the discovered node.

method

The method which handled the discovery request. The method could be one of: switch, blade, profile, sequential.

discoverytime

The last time that xCAT received the discovery message.

arch

The architecture of the discovered node. e.g. x86_64.

cpucount

The number of cores multiply by threads core supported for the discovered node. e.g. 192.

cputype

The cpu type of the discovered node. e.g. Intel(R) Xeon(R) CPU E5-2690 0 @ 2.90GHz

memory

The memory size of the discovered node. e.g. 198460852

mtm

The machine type model of the discovered node. e.g. 786310X
serial

The serial number of the discovered node. e.g. 1052EFB

nicdriver

The driver of the nic. The value should be comma separated <nic name!driver name>. e.g. eth0!be2net,eth1!be2net

nicipv4

The ipv4 address of the nic. The value should be comma separated <nic name!ipv4 address>. e.g. eth0!10.0.0.212/8

nicwaddr

The hardware address of the nic. The should will be comma separated <nic name!hardware address>. e.g. eth0!34:40:B5:BE:DB:B0,eth1!34:40:B5:BE:DB:B4

nicpci

The pic device of the nic. The value should be comma separated <nic name!pci device>. e.g. eth0!0000:0c:00.0,eth1!0000:0c:00.1

nicloc

The location of the nic. The value should be comma separated <nic name!nic location>. e.g. eth0!Onboard Ethernet 1,eth1!Onboard Ethernet 2

niconboard

The onboard info of the nic. The value should be comma separated <nic name!onboard info>. e.g. eth0!1,eth1!2

nicfirm

The firmware description of the nic. The value should be comma separated <nic name!firmware description>. e.g. eth0!ServerEngines BE3 Controller,eth1!ServerEngines BE3 Controller

switchname

The switch name which the nic connected to. The value should be comma separated <nic name!switch name>. e.g. eth0!e909f06sw01

switchaddr

The address of the switch which the nic connected to. The value should be comma separated <nic name!switch address>. e.g. eth0!192.168.70.120

switchdesc

The description of the switch which the nic connected to. The value should be comma separated <nic name!switch description>. e.g. eth0!IBM Flex System Fabric EN4093 10Gb Scalable Switch, flash image: version 7.2.6, boot image: version 7.2.6

switchport

The port of the switch that the nic connected to. The value should be comma separated <nic name!switch port>. e.g. eth0!INTA2

otherdata

The left data which is not parsed to specific attributes (The complete message comes from genesis)

comments

Any user-written notes.
disable

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

domain.5

NAME

domain - a table in the xCAT database.

SYNOPSIS

domain Attributes: node, ou, authdomain, adminuser, adminpassword, type, comments, disable

DESCRIPTION

Mapping of nodes to domain attributes

domain Attributes:

node

The node or group the entry applies to

ou

For an LDAP described machine account (i.e. Active Directory), the organizational unit to place the system. If not set, defaults to cn=Computers,dc=your,dc=domain

authdomain

If a node should participate in an AD domain or Kerberos realm distinct from domain indicated in site, this field can be used to specify that

adminuser

Allow a node specific indication of Administrative user. Most will want to just use passwd table to indicate this once rather than by node.

adminpassword

Allow a node specific indication of Administrative user password for the domain. Most will want to ignore this in favor of passwd table.

type

Type, if any, of authentication domain to manipulate. The only recognized value at the moment is activatedirectory.

comments

Any user-written notes.
disable

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

eventlog.5

NAME

eventlog - a table in the xCAT database.

SYNOPSIS

eventlog Attributes: recid, eventtime, eventtype, monitor, monnode, node, application, component, id, severity, message, rawdata, comments, disable

DESCRIPTION

Stores the events occurred.

eventlog Attributes:

recid

The record id.
eventtime

The timestamp for the event.
eventtype

The type of the event.
monitor

The name of the monitor that monitors this event.
monnode

The node that monitors this event.
node

The node where the event occurred.
application

The application that reports the event.
component

The component where the event occurred.
id
   The location or the resource name where the event occurred.

severity
   The severity of the event. Valid values are: informational, warning, critical.

message
   The full description of the event.

rawdata
   The data that associated with the event.

comments
   Any user-provided notes.

disable
   Do not use. tabprune will not work if set to yes or 1

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

firmware.5

NAME

firmware - a table in the xCAT database.

SYNOPSIS

firmware Attributes: node, cfgfile, comments, disable

DESCRIPTION

Maps node to firmware values to be used for setup at node discovery or later

firmware Attributes:

node
   The node id.

cfgfile
   The file to use.

comments
   Any user-written notes.

disable
Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

hosts.5

NAME

hosts - a table in the xCAT database.

SYNOPSIS

hosts Attributes: node, ip, hostnames, otherinterfaces, comments, disable

DESCRIPTION

IP addresses and hostnames of nodes. This info is optional and is only used to populate /etc/hosts and DNS via makehosts and makedns. Using regular expressions in this table can be a quick way to populate /etc/hosts.

hosts Attributes:
	node
	The node name or group name.

type
	The IP address of the node. This is only used in makehosts. The rest of xCAT uses system name resolution to resolve node names to IP addresses.

hostnames
	Hostname aliases added to /etc/hosts for this node. Comma or blank separated list.

otherinterfaces
	Other IP addresses to add for this node. Format: -<ext>:<ip>,<intfhostname>:<ip>,…

comments
	Any user-written notes.

disable
	Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)
hwinv.5

NAME

hwinv - a table in the xCAT database.

SYNOPSIS

hwinv Attributes: node, cputype, cpucount, memory, disksize, comments, disable

DESCRIPTION

The hardware inventory for the node.

hwinv Attributes:

node
   The node name or group name.
cputype
   The cpu model name for the node.
cpucount
   The number of cpus for the node.
memory
   The size of the memory for the node in MB.
disksize
   The size of the disks for the node in GB.
comments
   Any user-provided notes.
disable
   Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

hypervisor.5

NAME

hypervisor - a table in the xCAT database.
SYNOPSIS

hypervisor Attributes: node, type, mgr, interface, netmap, defaultnet, cluster, datacenter, preferdirect, comments, disable

DESCRIPTION

Hypervisor parameters

hypervisor Attributes:

node
The node or static group name

type
The plugin associated with hypervisor specific commands such as revacuate

mgr
The virtualization specific manager of this hypervisor when applicable

interface
The definition of interfaces for the hypervisor. The format is [network-name:interfacename:bootprotocol:IP:netmask:gateway] that split with | for each interface

netmap
Optional mapping of useful names to relevant physical ports. For example, 10ge=vmnic_16.0&vmnic_16.1,ge=vmnic1 would be requesting two virtual switches to be created, one called 10ge with vmnic_16.0 and vmnic_16.1 bonded, and another simply connected to vmnic1. Use of this allows abstracting guests from network differences amongst hypervisors

defaultnet
Optionally specify a default network entity for guests to join to if they do not specify.

cluster
Specify to the underlying virtualization infrastructure a cluster membership for the hypervisor.

datacenter
Optionally specify a datacenter for the hypervisor to exist in (only applicable to VMWare)

preferdirect
If a mgr is declared for a hypervisor, xCAT will default to using the mgr for all operations. If this is field is set to yes or 1, xCAT will prefer to directly communicate with the hypervisor if possible

comments
disable

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)
NAME

ipmi - a table in the xCAT database.

SYNOPSIS

ipmi Attributes: node, bmc, bmcport, taggedvlan, bmcid, username, password, comments, disable

DESCRIPTION

Settings for nodes that are controlled by an on-board BMC via IPMI.

ipmi Attributes:

node

The node name or group name.

bmc

The hostname of the BMC adapter.

bmcport

In systems with selectable shared/dedicated ethernet ports, this parameter can be used to specify the preferred port. 0 means use the shared port, 1 means dedicated, blank is to not assign.

The following special cases exist for IBM System x servers:

For x3755 M3 systems, 0 means use the dedicated port, 1 means shared, blank is to not assign.

For certain systems which have a mezzaine or ML2 adapter, there is a second value to include:

For x3750 M4 (Model 8722):

0 2 1st 1Gbps interface for LOM
0 0 1st 10Gbps interface for LOM
0 3 2nd 1Gbps interface for LOM
0 1 2nd 10Gbps interface for LOM

For x3750 M4 (Model 8752), x3850/3950 X6, dx360 M4, x3550 M4, and x3650 M4:
**1.3. Admin Guide**

---

```
0  Shared (1st onboard interface)
1  Dedicated
2 0  First interface on ML2 or mezzanine adapter
2 1  Second interface on ML2 or mezzanine adapter
2 2  Third interface on ML2 or mezzanine adapter
2 3  Fourth interface on ML2 or mezzanine adapter
```

**taggedvlan**

bmcsetup script will configure the network interface of the BMC to be tagged to the VLAN specified.

**bmcid**

Unique identified data used by discovery processes to distinguish known BMCs from unrecognized BMCs

**username**

The BMC userid. If not specified, the key=ipmi row in the passwd table is used as the default.

**password**

The BMC password. If not specified, the key=ipmi row in the passwd table is used as the default.

**comments**

Any user-written notes.

**disable**

Set to ‘yes’ or ‘1’ to comment out this row.

**SEE ALSO**

`nodels(1)`, `chtab(8)`, `tabdump(8)`, `tabedit(8)`

**iscsi.5**

**NAME**

**iscsi** - a table in the xCAT database.

**SYNOPSIS**

**iscsi Attributes:** `node`, `server`, `target`, `lun`, `iname`, `file`, `userid`, `passwd`, `kernel`, `kcmdline`, `initrd`, `comments`, `disable`

**DESCRIPTION**

Contains settings that control how to boot a node from an iSCSI target
iscsi Attributes:

node
   The node name or group name.
server
   The server containing the iscsi boot device for this node.
target
   The iscsi disk used for the boot device for this node. Filled in by xCAT.
lun
   LUN of boot device. Per RFC-4173, this is presumed to be 0 if unset. tgt often requires this to be 1
iname
   Initiator name. Currently unused.
file
   The path on the server of the OS image the node should boot from.
userid
   The userid of the iscsi server containing the boot device for this node.
passwd
   The password for the iscsi server containing the boot device for this node.
kernel
   The path of the linux kernel to boot from.
kcmdline
   The kernel command line to use with iSCSI for this node.
initrd
   The initial ramdisk to use when network booting this node.
comments
   Any user-written notes.
disable
   Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

kit.5

NAME

kit - a table in the xCAT database.
SYNOPSIS

kit Attributes:  kitname, basename, description, version, release, ostype, isinternal, kitdeployparams, kitdir, comments, disable

DESCRIPTION

This table stores all kits added to the xCAT cluster.

kit Attributes:

kitname
  The unique generated kit name, when kit is added to the cluster.
basename
  The kit base name
description
  The Kit description.
version
  The kit version
release
  The kit release
ostype
  The kit OS type. Linux or AIX.
isinternal
  A flag to indicated if the Kit is internally used. When set to 1, the Kit is internal. If 0 or undefined, the kit is not internal.
kitdeployparams
  The file containing the default deployment parameters for this Kit. These parameters are added to the OS Image definition's list of deployment parameters when one or more Kit Components from this Kit are added to the OS Image.
kitdir
  The path to Kit Installation directory on the Mgt Node.
comments
  Any user-written notes.
disable
  Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)
**NAME**

kitcomponent - a table in the xCAT database.

**SYNOPSIS**

**kitcomponent Attributes:** kitcompname, description, kitname, kitreponame, basename, version, release, serverroles, kitpkgdeps, prerequisite, driverpacks, kitcompdeps, postbootscripts, genimage_postinstall, exlist, comments, disable

**DESCRIPTION**

This table stores all kit components added to the xCAT cluster.

**kitcomponent Attributes:**

**kitcompname**

The unique Kit Component name. It is auto-generated when the parent Kit is added to the cluster.

**description**

The Kit component description.

**kitname**

The Kit name which this Kit Component belongs to.

**kitreponame**

The Kit Package Repository name which this Kit Component belongs to.

**basename**

Kit Component basename.

**version**

Kit Component version.

**release**

Kit Component release.

**serverroles**

The types of servers that this Kit Component can install on. Valid types are: mgtnode, servicenode, compute

**kitpkgdeps**

Comma-separated list of packages that this kit component depends on.

**prerequisite**

Prerequisite for this kit component, the prerequisite includes ospkgdeps,preinstall,preupgrade,preuninstall scripts

**driverpacks**
Comma-separated List of driver package names. These must be full names like: pkg1-1.0-1.x86_64.rpm.

**kitcompdeps**
Comma-separated list of kit components that this kit component depends on.

**postbootscripts**
Comma-separated list of postbootscripts that will run during the node boot.

**genimage_postinstall**
Comma-separated list of postinstall scripts that will run during the genimage.

**exlist**
Exclude list file containing the files/directories to exclude when building a diskless image.

**comments**
Any user-written notes.

**disable**
Set to ‘yes’ or ‘1’ to comment out this row.

**SEE ALSO**

nodels(1), chtab(8), tabdump(8), tabedit(8)

**kitrepo.5**

**NAME**

**kitrepo** - a table in the xCAT database.

**SYNOPSIS**

**kitrepo Attributes:** kitreponame, kitname, osbasename, osmajorversion, osminorversion, osarch, compat_osbasenames, kitrepodir, comments, disable

**DESCRIPTION**

This table stores all kits added to the xCAT cluster.

**kitrepo Attributes:**

**kitreponame**

The unique generated kit repo package name, when kit is added to the cluster.

**kitname**

The Kit name which this Kit Package Repository belongs to.

**osbasename**
The OS distro name which this repository is based on.

**osmajorversion**

The OS distro major version which this repository is based on.

**osminorversion**

The OS distro minor version which this repository is based on. If this attribute is not set, it means that this repo applies to all minor versions.

**osarch**

The OS distro arch which this repository is based on.

**compat_osbasenames**

List of compatible OS base names.

**kitrepodir**

The path to Kit Repository directory on the Mgt Node.

**comments**

Any user-written notes.

**disable**

Set to ‘yes’ or ‘1’ to comment out this row.

### SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

**kvm_masterdata.5**

### NAME

**kvm_masterdata** - a table in the xCAT database.

### SYNOPSIS

**kvm_masterdata Attributes:** name, xml, comments, disable

### DESCRIPTION

Persistent store for KVM plugin for masters

**kvm_masterdata Attributes:**

**name**

The name of the relevant master

**xml**
The XML description to be customized for clones of this master

**comments**

**disable**

Set to ‘yes’ or ‘1’ to comment out this row.

**SEE ALSO**

nodels(1), chtab(8), tabdump(8), tabedit(8)

**kvm_nodedata.5**

**NAME**

**kvm_nodedata** - a table in the xCAT database.

**SYNOPSIS**

**kvm_nodedata Attributes:** node, xml, comments, disable

**DESCRIPTION**

Persistent store for KVM plugin, not intended for manual modification.

**kvm_nodedata Attributes:**

**node**

The node corresponding to the virtual machine

**xml**

The XML description generated by xCAT, fleshed out by libvirt, and stored for reuse

**comments**

Any user-written notes.

**disable**

Set to ‘yes’ or ‘1’ to comment out this row.

**SEE ALSO**

nodels(1), chtab(8), tabdump(8), tabedit(8)
**linuximage.5**

**NAME**

**linuximage** - a table in the xCAT database.

**SYNOPSIS**

**linuximage Attributes:** `imagename`, `template`, `boottarget`, `addkcmdline`, `pkglist`, `pkgdir`, `otherpkglist`, `otherpkgdir`, `exlist`, `postinstall`, `rootimgdir`, `kerneldir`, `nodebootif`, `nodeifce`, `netdrivers`, `kernelver`, `krpmver`, `permission`, `dump`, `crashkernelsize`, `partitionfile`, `driverupdatesrc`, `comments`, `disable`

**DESCRIPTION**

Information about a Linux operating system image that can be used to deploy cluster nodes.

**linuximage Attributes:**

**imagename**

The name of this xCAT OS image definition.

**template**

The fully qualified name of the template file that will be used to create the OS installer configuration file for stateful installations (e.g. kickstart for RedHat, autoyast for SLES).

**boottarget**

The name of the boottarget definition. When this attribute is set, xCAT will use the kernel, initrd and kernel params defined in the boottarget definition instead of the default.

**addkcmdline**

User specified kernel options for os provision process(no prefix) or the provisioned os(with prefix “R:”). The options should be delimited with spaces(“ “). This attribute is ignored if `linuximage.boottarget` is set.

**pkglist**

The fully qualified name of the file that stores the distro packages list that will be included in the image. Make sure that if the pkgs in the pkglist have dependency pkgs, the dependency pkgs should be found in one of the pkgdir.

**pkgdir**

The name of the directory where the distro packages are stored. It could be set to multiple paths. The multiple paths must be separated by “,”. The first path in the value of osimage.pkgdir must be the OS base pkg dir path, such as `pkgdir=/install/rhel6.2/x86_64/install/updates`. In the os base pkg path, there are default repository data. And in the other pkg path(s), the users should make sure there are repository data. If not, use “createrepo” command to create them. For ubuntu, multiple mirrors can be specified in the pkgdir attribute, the mirrors must be prefixed by the protocol(http/ssh) and delimited with “,” between each other.

**otherpkglist**

The fully qualified name of the file that stores non-distro package lists that will be included in the image. It could be set to multiple paths. The multiple paths must be separated by “,”.
otherpkgdir

The base directory and urls of internet repos from which the non-distro packages are retrieved. Only 1 local directory is supported at present. The entries should be delimited with comma “,”. Currently, the internet repos are only supported on Ubuntu and Redhat.

exlist

The fully qualified name of the file that stores the file names and directory names that will be excluded from the image during packimage command. It is used for diskless image only.

postinstall

Supported in diskless image only. The fully qualified name of the scripts and the user-specified arguments running in non-chroot mode after the package installation but before initrd generation during genimage. If multiple scripts are specified, they should be seperated with comma “,”. The arguments passed to each postinstall script include 4 implicit arguments(<rootimage path>,<os version>,<os arch>,<profile>) and the user-specified arguments. A set of osimage attributes are exported as the environment variables to be used in the postinstall scripts:

```
IMG_ARCH(The architecture of the osimage, such as "ppc64le","x86_64"),
IMG_NAME(The name of the osimage, such as "rhels7.3-ppc64le-netboot-compute"),
IMG_OSVER(The os release of the osimage, such as "rhels7.3","sles11.4"),
IMG_PROFILE(the profile of the osimage, such as "service","compute"),
IMG_PKGLIST(the "pkglist" attribute of the osimage),
IMG_PKGDIR(the "pkgdir" attribute of the osimage),
IMG_OTHERPKGLIST(the "otherpkglist" attribute of the osimage),
IMG_ROOTIMGDIR(the "rootimgdir" attribute of the osimage)
```

rootimgdir

The directory name where the image is stored. It is generally used for diskless image. It also can be used in sysclone environment to specify where the image captured from golden client is stored. In sysclone environment, rootimgdir is generally assigned to some default value by xcat, but you can specify your own store directory. Just one thing need to be noticed, wherever you save the image, the name of last level directory must be the name of image. For example, if your image name is testimage and you want to save this image under home directory, rootimgdir should be assigned to value /home/testimage/

cerneldir

The directory name where the 3rd-party kernel is stored. It is used for diskless image only.

nodebootif

The network interface the stateless/statelite node will boot over (e.g. eth0)

otherfice

Other network interfaces (e.g. eth1) in the image that should be configured via DHCP

netdrivers

The ethernet device drivers of the nodes which will use this linux image, at least the device driver for the nodes’ installnic should be included

kernelver

The version of linux kernel used in the linux image. If the kernel version is not set, the default kernel in rootimgdir will be used

krpmver
The rpm version of kernel packages (for SLES only). If it is not set, the default rpm version of kernel packages will be used.

**permission**

The mount permission of \./statelite directory is used, its default value is 755

**dump**

The NFS directory to hold the Linux kernel dump file (vmcore) when the node with this image crashes, its format is “nfs://<nfs_server_ip>/<kdump_path>”. If you want to use the node’s “xcatmaster” (its SN or MN), <nfs_server_ip> can be left blank. For example, “nfs:///<kdump_path>” means the NFS directory to hold the kernel dump file is on the node’s SN, or MN if there’s no SN.

**crashkernelsize**

the size that assigned to the kdump file. If the kernel size is not set, 256M will be the default value.

**partitionfile**

Only available for diskful osimages and statelite osimages(localdisk enabled). The full path of the partition file or the script to generate the partition file. The valid value includes:

- `<the absolute path of the partition file>`: For diskful osimages, the partition file contains the partition definition that will be inserted directly into the template file for os installation. The syntax and format of the partition file should confirm to the corresponding OS installer of the Linux distributions(e.g. kickstart for RedHat, autoyast for SLES, pressed for Ubuntu). For statelite osimages, when the localdisk is enabled, the partition file with specific syntax and format includes the partition scheme of the local disk, please refer to the statelite documentation for details.

- `<the absolute path of the partition script>`: a shell script to generate the partition file “/tmp/partitionfile” inside the installer before the installation start.

- `<the absolute path of the disk name file>`: only available for ubuntu osimages, includes the name(s) of the disks to partition in traditional, non-devfs format(e.g. /dev/sdx, not e.g. /dev/discs/disc0/disc), and be delimited with space. All the disks involved in the partition file should be specified. "d:<the absolute path of the disk name file>";

- `<the absolute path of the partition script>`: only available for ubuntu osimages, a script to generate the disk name file “/tmp/xcat.install_disk” inside the debian installer. This script is run in the “pressed/early_command” section.

- `<the absolute path of the additional pressed config file>`: only available for ubuntu osimages, contains the additional pressed entries in “d-i . . .” form. This can be used to specify some additional preseed options to support RAID or LVM in Ubuntu.

- `<the absolute path of the additional pressed config scripts>`: only available for ubuntu osimages, runs in pressed/early_command and set the preseed values with “debconf-set”. The multiple values should be delimited with comma “,”

**driverupdatesrc**

The source of the drivers which need to be loaded during the boot. Two types of driver update source are supported: Driver update disk and Driver rpm package. The value for this attribute should be comma separated sources. Each source should be the format `tab:full_path_of_source_file`. The tab keyword can be: dud (for Driver update disk) and rpm (for driver rpm). If missing the tab, the rpm format is the default. e.g. dud:/install/dud/dd.img,rpm:/install/rpm/d.rpm

**comments**

Any user-written notes.

**disable**

Set to ‘yes’ or ‘1’ to comment out this row.

**SEE ALSO**

nodels(1), chtab(8), tabdump(8), tabedit(8)
NAME

litefile - a table in the xCAT database.

SYNOPSIS

litefile Attributes: image, file, options, comments, disable

DESCRIPTION

The litefile table specifies the directories and files on the statelite nodes that should be readwrite, persistent, or readonly overlay. All other files in the statelite nodes come from the readonly statelite image.

litefile Attributes:

image

The name of the image (as specified in the osimage table) that will use these options on this dir/file. You can also specify an image group name that is listed in the osimage.groups attribute of some osimages. ‘ALL’ means use this row for all images.

file

The full pathname of the file. e.g: /etc/hosts. If the path is a directory, then it should be terminated with a ‘/’.

options

Options for the file:

```
tmpfs - It is the default option if you leave the options column blank. It provides a file or directory for the node to use when booting, its permission will be the same as the original version on the server. In most cases, it is read-write; however, on the next statelite boot, the original version of the file or directory on the server will be used, it means it is non-persistent. This option can be performed on files and directories.

rw - Same as above. Its name "rw" does NOT mean it always be read-write, even in most cases it is read-write. Do not confuse it with the "rw" permission in the file system.

persistent - It provides a mounted file or directory that is copied to the xCAT persistent location and then over-mounted on the local file or directory. Anything written to that file or directory is preserved. It means, if the file/directory does not exist at first, it will be copied to the persistent location. Next time the file/directory in the persistent location will be used. The file/directory will be persistent across reboots. Its permission will be the same as the original one in the statelite location. It requires the statelite table to be filled out with a spot for persistent statelite. This option can be performed on files and directories.
```
(continues on next page)
con - The contents of the pathname are concatenated to the contents of the
existing file. For this directive the searching in the litetree hierarchy
does not stop when the first match is found. All files found in the
hierarchy will be concatenated to the file when found. The permission of
the file will be "-rw-r-r--", which means it is read-write for the root
user, but readonly for the others. It is non-persistent, when the node
reboots, all changes to the file will be lost. It can only be performed on
files. Do not use it for one directory.

ro - The file/directory will be overmounted read-only on the local file/
directory. It will be located in the directory hierarchy specified in the
litetree table. Changes made to this file or directory on the server will
be immediately seen in this file/directory on the node. This option
requires that the file/directory to be mounted must be available in one of
the entries in the litetree table. This option can be performed on files
and directories.

link - It provides one file/directory for the node to use when booting, it
is copied from the server, and will be placed in tmpfs on the booted node.
In the local file system of the booted node, it is one symbolic link to
one file/directory in tmpfs. And the permission of the symbolic link is
"lrwxrwxrwx", which is not the real permission of the file/directory on
the node. So for some application sensitive to file permissions, it will
be one issue to use "link" as its option, for example, "/root/.ssh/",
which is used for SSH, should NOT use "link" as its option. It is non-
persistent, when the node is rebooted, all changes to the file/directory
will be lost. This option can be performed on files and directories.

link,con - It works similar to the "con" option. All the files found in the
litetree hierarchy will be concatenated to the file when found. The final
file will be put to the tmpfs on the booted node. In the local file system
of the booted node, it is one symbolic link to the file/directory in tmpfs.
It is non-persistent, when the node is rebooted, all changes to the file
will be lost. The option can only be performed on files.

link,persistent - It provides a mounted file or directory that is copied to
the xCAT persistent location and then over-mounted to the tmpfs on the
booted node, and finally the symbolic link in the local file system will
be linked to the over-mounted tmpfs file/directory on the booted node. The
file/directory will be persistent across reboots. The permission of the
file/directory where the symbolic link points to will be the same as the
original one in the statelite location. It requires the statelite table to
be filled out with a spot for persistent statelite. The option can be
performed on files and directories.

link,ro - The file is readonly, and will be placed in tmpfs on the booted
node. In the local file system of the booted node, it is one symbolic link
to the tmpfs. It is non-persistent, when the node is rebooted, all changes
to the file/directory will be lost. This option requires that the file/
directory to be mounted must be available in one of the entries in the
litetree table. The option can be performed on files and directories.

comments
Any user-written notes.

disable
Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

litetree.5

NAME

litetree - a table in the xCAT database.

SYNOPSIS

litetree Attributes: priority, image, directory, mntopts, comments, disable

DESCRIPTION

Directory hierarchy to traverse to get the initial contents of node files. The files that are specified in the litefile table are searched for in the directories specified in this table.

litetree Attributes:

priority

This number controls what order the directories are searched. Directories are searched from smallest priority number to largest.

image

The name of the image (as specified in the osimage table) that will use this directory. You can also specify an image group name that is listed in the osimage.groups attribute of some osimages. ‘ALL’ means use this row for all images.

directory

The location (hostname:path) of a directory that contains files specified in the litefile table. Variables are allowed. E.g: $noderes.nfsserver://xcatmasternode/install/$node/#CMD=uname-r#/ 

mntopts

A comma-separated list of options to use when mounting the litetree directory. (Ex. ‘soft’) The default is to do a ‘hard’ mount.

comments

Any user-written notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.
SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

mac.5

NAME

mac - a table in the xCAT database.

SYNOPSIS

mac Attributes: node, interface, mac, comments, disable

DESCRIPTION

The MAC address of the node’s install adapter. Normally this table is populated by getmacs or node discovery, but you can also add entries to it manually.

mac Attributes:

node

The node name or group name.

interface

The adapter interface name that will be used to install and manage the node. E.g. eth0 (for linux) or en0 (for AIX).)

mac

The mac address or addresses for which xCAT will manage static bindings for this node. This may be simply a mac address, which would be bound to the node name (such as “01:02:03:04:05:0E”). This may also be a “|” delimited string of “mac address!hostname” format (such as “01:02:03:04:05:0E!node5|02:03:04:05:0F!node6-eth1”). If there are multiple nics connected to Management Network (usually for bond), in order to make sure the OS deployment finished successfully, the macs of those nics must be able to resolve to same IP address. First, users have to create alias of the node for each mac in the Management Network through either: 1. adding the alias into /etc/hosts for the node directly or: 2. setting the alias to the “hostnames” attribute and then run “makehost” against the node. Then, configure the “mac” attribute of the node like “mac1!nodemac2!node-alias”. For the first mac address (mac1 in the example) set in “mac” attribute, do not need to set a “node name” string for it since the nodename of the node will be used for it by default.

comments

Any user-written notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.
SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

mic.5

NAME

mic - a table in the xCAT database.

SYNOPSIS

mic Attributes: node, host, id, nodetype, bridge, onboot, vlog, powermgt, comments, disable

DESCRIPTION

The host, slot id and configuration of the mic (Many Integrated Core).

mic Attributes:

node
    The node name or group name.
host
    The host node which the mic card installed on.
id
    The device id of the mic node.
nodetype
    The hardware type of the mic node. Generally, it is mic.
bridge
    The virtual bridge on the host node which the mic connected to.
onboot
    Set mic to autboot when mpss start. Valid values: yes|no. Default is yes.
vlog
    Set the Verbose Log to console. Valid values: yes|no. Default is no.
powermgt
    Set the Power Management for mic node. This attribute is used to set the power management state that
can be set: cpufreq, corec6, pc3 and pc6. The valid value for powermgt attribute should be
    cpufreq=on|off!corec6=on|off!pc3=on|off!pc6=on|off. Refer to the doc of mic to get more information for power
    management.
comments

1.3. Admin Guide
Any user-provided notes.

disable
   Do not use. tabprune will not work if set to yes or 1

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

NAME

monitoring - a table in the xCAT database.

SYNOPSIS

monitoring Attributes: name, nodestatmon, comments, disable

DESCRIPTION

Controls what external monitoring tools xCAT sets up and uses. Entries should be added and removed from this table using the provided xCAT commands monstart and monstop.

monitoring Attributes:

name
   The name of the monitoring plug-in module. The plug-in must be put in /lib/perl/xCAT_monitoring/. See the man page for monstart for details.

nodestatmon
   Specifies if the monitoring plug-in is used to feed the node status to the xCAT cluster. Any one of the following values indicates “yes”: y, Y, yes, Yes, YES, 1. Any other value or blank (default), indicates “no”.

comments
   Any user-written notes.

disable
   Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)
monsetting.5

NAME

monsetting - a table in the xCAT database.

SYNOPSIS

monsetting Attributes: name, key, value, comments, disable

DESCRIPTION

Specifies the monitoring plug-in specific settings. These settings will be used by the monitoring plug-in to customize the behavior such as event filter, sample interval, responses etc. Entries should be added, removed or modified by chtab command. Entries can also be added or modified by the monstart command when a monitoring plug-in is brought up.

monsetting Attributes:

name
  The name of the monitoring plug-in module. The plug-in must be put in /lib/perl/xCAT_monitoring/. See the man page for monstart for details.

key
  Specifies the name of the attribute. The valid values are specified by each monitoring plug-in. Use “monls name -d” to get a list of valid keys.

value
  Specifies the value of the attribute.

comments
  Any user-written notes.

disable
  Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

mp.5

NAME

mp - a table in the xCAT database.
SYNOPSIS

**mp Attributes:** node, mpa, id, nodetype, comments, disable

DESCRIPTION

Contains the hardware control info specific to blades. This table also refers to the mpa table, which contains info about each Management Module.

**mp Attributes:**

- **node**
  The blade node name or group name.

- **mpa**
  The management module used to control this blade.

- **id**
  The slot number of this blade in the BladeCenter chassis.

- **nodetype**
  The hardware type for mp node. Valid values: mm, cmm, blade.

- **comments**
  Any user-written notes.

- **disable**
  Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

mpa.5

NAME

**mpa** - a table in the xCAT database.

SYNOPSIS

**mpa Attributes:** mpa, username, password, displayname, slots, urlpath, comments, disable

DESCRIPTION

Contains info about each Management Module and how to access it.
mpa Attributes:

mpa
   Hostname of the management module.
username
   Userid to use to access the management module.
password
   Password to use to access the management module. If not specified, the key=blade row in the passwd table is used as the default.
displayname
   Alternative name for BladeCenter chassis. Only used by PCM.
slots
   The number of available slots in the chassis. For PCM, this attribute is used to store the number of slots in the following format: <slot rows>,<slot columns>,<slot orientation> Where:

   | <slot rows> | number of rows of slots in chassis |
   | <slot columns> | number of columns of slots in chassis |
   | <slot orientation> | set to 0 if slots are vertical, and set to 1 if slots of horizontal |

urlpath
   URL path for the Chassis web interface. The full URL is built as follows: <hostname>/<urlpath>
comments
   Any user-written notes.
disable
   Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

cmodels(1), chtab(8), tabdump(8), tabedit(8)

networks.5

NAME

networks - a table in the xCAT database.

SYNOPSIS

networks Attributes: netname, net, mask, mgtifname, gateway, dhcpserver, tftpserver, nameservers, ntpservers, logservers, dynamicrange, staticrange, staticrangeincrement, nodehostname, ddnsdomain, vlanid, domain, mtu, comments, disable
DESCRIPTION

Describes the networks in the cluster and info necessary to set up nodes on that network.

networks Attributes:

netname
Name used to identify this network definition.

net
The network address.

mask
The network mask.

mgtifname
The interface name of the management/service node facing this network. !remote!<nicname> indicates a non-local network on a specific nic for relay DHCP.

gateway
The network gateway. It can be set to an ip address or the keyword <xcatmaster>, the keyword <xcatmaster> indicates the cluster-facing ip address configured on this management node or service node. Leaving this field blank means that there is no gateway for this network.

dhcpsserver
The DHCP server that is servicing this network. Required to be explicitly set for pooled service node operation.

tftpserver
The TFTP server that is servicing this network. If not set, the DHCP server is assumed.

nameservers
A comma delimited list of DNS servers that each node in this network should use. This value will end up in the nameserver settings of the /etc/resolv.conf on each node in this network. If this attribute value is set to the IP address of an xCAT node, make sure DNS is running on it. In a hierarchical cluster, you can also set this attribute to "<xcatmaster>" to mean the DNS server for each node in this network should be the node that is managing it (either its service node or the management node). Used in creating the DHCP network definition, and DNS configuration.

ntpservers
The ntp servers for this network. Used in creating the DHCP network definition. Assumed to be the DHCP server if not set.

logservers
The log servers for this network. Used in creating the DHCP network definition. Assumed to be the DHCP server if not set.

dynamicrange
The IP address range used by DHCP to assign dynamic IP addresses for requests on this network. This should not overlap with entities expected to be configured with static host declarations, i.e. anything ever expected to be a node with an address registered in the mac table.

staticrange
The IP address range used to dynamically assign static IPs to newly discovered nodes. This should not overlap with the dynamic range nor overlap with entities that were manually assigned static IPs. The format for the attribute value is: <startip>-<endip>.

**staticrangeincrement**

**nodehostname**

A regular expression used to specify node name to network-specific hostname. i.e. “/z/-secondary/” would mean that the hostname of “n1” would be n1-secondary on this network. By default, the nodename is assumed to equal the hostname, followed by nodename-interfacename.

**ddnsdomain**

A domain to be combined with nodename to construct FQDN for DDNS updates induced by DHCP. This is not passed down to the client as “domain”

**vlanid**

The vlan ID if this network is within a vlan.

**domain**

The DNS domain name (ex. cluster.com).

**mtu**

The default MTU for the network. If multiple networks are applied to the same nic on the SN and/or CN, the MTU shall be the same for those networks.

**comments**

Any user-written notes.

**disable**

Set to ’yes’ or ‘1’ to comment out this row.

**SEE ALSO**

nodels(1), chtab(8), tabdump(8), tabedit(8)

dvis.5

**NAME**

**nics** - a table in the xCAT database.

**SYNOPSIS**

**nics Attributes:** node, nicips, niconstameprefixes, niconstameprefixes, nictypes, nicustomscripts, nicnetworks, nicaliases, nicextraparams, nicdevices, nicsadapter, comments, disable

**DESCRIPTION**

Stores NIC details.
nics Attributes:

node
The node or group name.

nicips
Comma-separated list of IP addresses per NIC.

  To specify one ip address per NIC: <nic1>!<ip1>,<nic2>!<ip2>,..., for example, eth0!10.0.0.100,ib0!11.0.0.100

  To specify multiple ip addresses per NIC: <nic1>!<ip1>,<nic2>!<ip2>..., for example, eth0!10.0.0.100|fd55::214:5eff:fe15:849b,ib0!11.0.0.100|2001::214:5eff:fe15:849a.

  The xCAT object definition commands support to use nicips.<nicname> as the sub attributes.

Note: The primary IP address must also be stored in the hosts.ip attribute. The nichostnamesuffixes should specify one hostname suffix for each ip address.

nichostnamesuffixes
Comma-separated list of hostname suffixes per NIC.

If only one ip address is associated with each NIC: <nic1>!<ext1>,<nic2>!<ext2>,..., for example, eth0|-eth0,ib0|-ib0

If multiple ip addresses are associated with each NIC: <nic1>!<ext1>|<ext2>,<nic2>!<ext1>|<ext2>,..., for example, eth0!eth0-eth0-ipv6,ib0!ib0-ib0-ipv6.

The xCAT object definition commands support to use nichostnamesuffixes.<nicname> as the sub attributes.

Note: According to DNS rules a hostname must be a text string up to 24 characters drawn from the alphabet (A-Z), digits (0-9) and minus sign (-). When you are specifying "nichostnamesuffixes" or "nicaliases" make sure the resulting hostnames will conform to this naming convention

nichostnameprefixes
Comma-separated list of hostname prefixes per NIC.

If only one ip address is associated with each NIC: <nic1>!<ext1>,<nic2>!<ext2>,..., for example, eth0!eth0-,ib0!ib-

If multiple ip addresses are associated with each NIC: <nic1>!<ext1>|<ext2>,<nic2>!<ext1>|<ext2>,..., for example, eth0!eth0-eth0-ipv6i-,ib0!ib-ib-ipv6-.

The xCAT object definition commands support to use nichostnameprefixes.<nicname> as the sub attributes. Note: According to DNS rules a hostname must be a text string up to 24 characters drawn from the alphabet (A-Z), digits (0-9) and minus sign (-). When you are specifying “nichostnameprefixes” or “nicaliases” make sure the resulting hostnames will conform to this naming convention

nictypes
Comma-separated list of NIC types per NIC. <nic1>!<type1>,<nic2>!<type2>, e.g. eth0!Ethernet,ib0!Infiniband. The xCAT object definition commands support to use nictypes.<nicname> as the sub attributes.

niccustomscripts
Comma-separated list of custom scripts per NIC. <nic1>!<script1>,<nic2>!<script2>, e.g. eth0!configeth eth0, ib0!configib ib0. The xCAT object definition commands support to use niccustomscripts.<nicname> as the sub attribute.
nicnetworks

Comma-separated list of networks connected to each NIC.

- If only one ip address is associated with each NIC: `<nic1>!<network1>,<nic2>!<network2>`, for example, eth0!10_0_0_0-255_255_0_0, ib0!11_0_0_0-255_255_0_0
- If multiple ip addresses are associated with each NIC: `<nic1>!<network1>|<network2>,<nic2>!<network1>|<network2>`, for example, eth0!10_0_0_0-255_255_0_0|fd55:faaf:e1ab:336::/64, ib0!11_0_0_0-255_255_0_0|2001:db8:1:0::/64. The xCAT object definition commands support to use nicnetworks.<nicname> as the sub attributes.

nicaliases

Comma-separated list of hostname aliases for each NIC.

- Format: `eth0!<alias list>,eth1!<alias1 list>|<alias2 list>` For multiple aliases per nic use a space-separated list.
  - For example: eth0!moe larry curly,eth1!tom|jerry

nicextraparams

Comma-separated list of extra parameters that will be used for each NIC configuration.

- If only one ip address is associated with each NIC: `<nic1>!<param1=value1 param2=value2>,<nic2>!<param3=value3>`, for example, eth0!MTU=1500, ib0!MTU=65520 CONNECTED_MODE=yes.
- If multiple ip addresses are associated with each NIC: `<nic1>!<param1=value1 param2=value2|<param3=value3>,<nic2>!<param4=value4 param5=value5|<param6=value6>`, for example, eth0!MTU=1500|MTU=1460, ib0!MTU=65520 CONNECTED_MODE=yes.
  - The xCAT object definition commands support to use nicextraparams.<nicname> as the sub attributes.

nicdevices

Comma-separated list of NIC device per NIC, multiple ethernet devices can be bonded as bond device, these ethernet devices are separated by |. `<nic1>!<dev1>|<dev3>,<nic2>!<dev2>`, e.g. bond0!eth0|eth2, br0!bond0. The xCAT object definition commands support to use nicdevices.<nicname> as the sub attributes.

nicsadapter

Comma-separated list of NIC information collected by getadapter. `<nic1>!<param1=value1 param2=value2>,<nic2>!<param4=value4 param5=value5>`, for example, enP3p3s0f1!mac=98:be:94:59:fa:cd linkstate=DOWN, enP3p3s0f2!mac=98:be:94:59:fa:ce candidate=name=enP3p3s0f2/enx98be9459face

comments

Any user-written notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

dnodes(1), chtab(8), tabdump(8), tabedit(8)
nimimage.5

NAME

nimimage - a table in the xCAT database.

SYNOPSIS

nimimage Attributes: imagename, nimtype, lpp_source, spot, root, dump, paging, resolv_conf, tmp, home, shared_home, res_group, nimmethod, script, bosinst_data, installp_bundle, mksysb, fb_script, shared_root, otherpkgs, image_data, configdump, comments, disable

DESCRIPTION

All the info that specifies a particular AIX operating system image that can be used to deploy AIX nodes.

nimimage Attributes:

imagename

User provided name of this xCAT OS image definition.

nimtype

The NIM client type- standalone, diskless, or dataless.

lpp_source

The name of the NIM lpp_source resource.

spot

The name of the NIM SPOT resource.

root

The name of the NIM root resource.

dump

The name of the NIM dump resource.

paging

The name of the NIM paging resource.

resolv_conf

The name of the NIM resolv_conf resource.

tmp

The name of the NIM tmp resource.

home

The name of the NIM home resource.

shared_home

The name of the NIM shared_home resource.
res_group
   The name of a NIM resource group.

nimmethod
   The NIM install method to use, (ex. rte, mksysb).

script
   The name of a NIM script resource.

bosinst_data
   The name of a NIM bosinst_data resource.

installp_bundle
   One or more comma separated NIM installp_bundle resources.

mksysb
   The name of a NIM mksysb resource.

fb_script
   The name of a NIM fb_script resource.

shared_root
   A shared_root resource represents a directory that can be used as a / (root) directory by one or more
diskless clients.

otherpkgs
   One or more comma separated installp or rpm packages. The rpm packages must have a prefix of ‘R:’,
   (ex. R:foo.rpm)

image_data
   The name of a NIM image_data resource.

configdump
   Specifies the type of system dump to be collected. The values are selective, full, and none. The default is
   selective.

comments
   Any user-provided notes.

disable
   Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

nodegroup.5

NAME

nodegroup - a table in the xCAT database.
SYNOPSIS

nodegroup Attributes: groupname, grouptype, members, membergroups, wherevals, comments, disable

DESCRIPTION

Contains group definitions, whose membership is dynamic depending on characteristics of the node.

nodegroup Attributes:

groupname
  Name of the group.

grouptype
  Static or Dynamic. A static group is defined to contain a specific set of cluster nodes. A dynamic node group is one that has its members determined by specifying a selection criteria for node attributes.

members
  The value of the attribute is not used, but the attribute is necessary as a place holder for the object def commands. (The membership for static groups is stored in the nodelist table.)

membergroups
  This attribute stores a comma-separated list of nodegroups that this nodegroup refers to. This attribute is only used by PCM.

wherevals
  A list of “attr*val” pairs that can be used to determine the members of a dynamic group, the delimiter is “::” and the operator * can be ==, =~, != or !~.

comments
  Any user-written notes.

disable
  Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

nodehm.5

NAME

nodehm - a table in the xCAT database.
SYNOPSIS

nodehm Attributes: node, power, mgt, cons, termserver, termport, conserver, serialport, serialspeed, serialflow, getmac, cmdmapping, consoleondemand, consoleenabled, comments, disable

DESCRIPTION

Settings that control how each node’s hardware is managed. Typically, an additional table that is specific to the hardware type of the node contains additional info. E.g. the ipmi, mp, and ppc tables.

nodehm Attributes:

node
The node name or group name.

power
The method to use to control the power of the node. If not set, the mgt attribute will be used. Valid values: ipmi, blade, hmc, ivm, fsp, kvm, esx, rhevm. If “ipmi”, xCAT will search for this node in the ipmi table for more info. If “blade”, xCAT will search for this node in the mp table. If “hmc”, “ivm”, or “fsp”, xCAT will search for this node in the ppc table.

mgt
The method to use to do general hardware management of the node. This attribute is used as the default if power or getmac is not set. Valid values: openbmc, ipmi, blade, hmc, ivm, fsp, bpa, kvm, esx, rhevm. See the power attribute for more details.

cons
The console method. If nodehm.serialport is set, this will default to the nodehm.mgt setting, otherwise it defaults to unused. Valid values: cyclades, mrv, or the values valid for the mgt attribute.

termserver
The hostname of the terminal server.

termport
The port number on the terminal server that this node is connected to.

conserver
The hostname of the machine where the conserver daemon is running. If not set, the default is the xCAT management node.

serialport
The serial port for this node, in the linux numbering style (0=COM1/ttyS0, 1=COM2/ttyS1). For SOL on IBM blades, this is typically 1. For rackmount IBM servers, this is typically 0.

serialspeed
The speed of the serial port for this node. For SOL this is typically 19200.

serialflow
The flow control value of the serial port for this node. For SOL this is typically ‘hard’.

getmac
The method to use to get MAC address of the node with the getmac command. If not set, the mgt attribute will be used. Valid values: same as values for mgmt attribute.

**cmdmapping**

The fully qualified name of the file that stores the mapping between PCM hardware management commands and xCAT/third-party hardware management commands for a particular type of hardware device. Only used by PCM.

**consoleondemand**

This overrides the value from site.consoleondemand. Set to ‘yes’, ‘no’, ‘1’ (equivalent to ‘yes’), or ‘0’ (equivalent to ‘no’). If not set, the default is the value from site.consoleondemand.

**consoleenabled**

A flag field to indicate whether the node is registered in the console server. If ‘1’, console is enabled, if not set, console is not enabled.

**comments**

Any user-written notes.

**disable**

Set to ‘yes’ or ‘1’ to comment out this row.

**SEE ALSO**

nodels(1), chtab(8), tabdump(8), tabedit(8)

**nodelist.5**

**NAME**

**nodelist** - a table in the xCAT database.

**SYNOPSIS**

**nodelist Attributes:** node, groups, status, statustime, appstatus, appstatustime, primariesn, hidden, updatestatus, updatestatustime, zonename, comments, disable

**DESCRIPTION**

The list of all the nodes in the cluster, including each node’s current status and what groups it is in.

**nodelist Attributes:**

**node**

The hostname of a node in the cluster.

**groups**
A comma-delimited list of groups this node is a member of. Group names are arbitrary, except all nodes should be part of the ‘all’ group. Internal group names are designated by using __<groupname>. For example, __Unmanaged, could be the internal name for a group of nodes that is not managed by xCAT. Admins should avoid using the __ characters when defining their groups.

status
The current status of this node. This attribute will be set by xCAT software. Valid values: defined, booting, netbooting, booted, discovering, configuring, installing, alive, standingby, powering-off, unreachable. If blank, defined is assumed. The possible status change sequences are: For installation: defined-[discovering]->[configuring]->[standingby]->installing-[postbooting]->booted-[alive], For diskless deployment: defined-[discovering]->[configuring]->[standingby]->netbooting-[postbooting]->booted-[alive]. For booting: [alive/unreachable]->booting-[postbooting]->booted-[alive], For powering off: [alive]->powering-off->[unreachable], For monitoring: alive-unreachable. Discovering and configuring are for x Series discovery process. Alive and unreachable are set only when there is a monitoring plug-in start monitor the node status for xCAT. Note that the status values will not reflect the real node status if you change the state of the node from outside of xCAT (i.e. power off the node using HMC GUI).

statustime
The data and time when the status was updated.

appstatus
A comma-delimited list of application status. For example: ‘sshd=up,ftp=down,ll=down’

appstatustime
The date and time when appstatus was updated.

primarysn
Not used currently. The primary servicenode, used by this node.

hidden
Used to hide fsp and bpa definitions, 1 means not show them when running lsdef and nodels

updatestatus
The current node update status. Valid states are synced, out-of-sync, syncing, failed.

updatestatustime
The date and time when the updatestatus was updated.

zonename
The name of the zone to which the node is currently assigned. If undefined, then it is not assigned to any zone.

comments
Any user-written notes.

disable
Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)
nodepos.5

NAME

nodepos - a table in the xCAT database.

SYNOPSIS

nodepos Attributes: node, rack, u, chassis, slot, room, height, comments, disable

DESCRIPTION

Contains info about the physical location of each node. Currently, this info is not used by xCAT, and therefore can be in whatever format you want. It will likely be used in xCAT in the future.

nodepos Attributes:

node
   The node name or group name.
rack
   The frame the node is in.
u
   The vertical position of the node in the frame
chassis
   The BladeCenter chassis the blade is in.
slot
   The slot number of the blade in the chassis. For PCM, a comma-separated list of slot numbers is stored
room
   The room where the node is located.
height
   The server height in U(s).
comments
   Any user-written notes.
disable
   Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)
noderes.5

NAME

noderes - a table in the xCAT database.

SYNOPSIS

noderes Attributes: node, servicenode, netboot, tftpserver, tftpdir, nfsserver, monserver, nfssdir, installnic, primarynic, discoverynics, cmdinterface, xcatmaster, current_osimage, next_osimage, nimserver, routenames, nameservers, proxydhcp, syslog, comments, disable

DESCRIPTION

Resources and settings to use when installing nodes.

noderes Attributes:

node

The node name or group name.

servicenode

A comma separated list of node names (as known by the management node) that provides most services for this node. The first service node on the list that is accessible will be used. The 2nd node on the list is generally considered to be the backup service node for this node when running commands like snmove.

netboot

The type of network booting to use for this node. Valid values:

<table>
<thead>
<tr>
<th>Arch</th>
<th>OS</th>
<th>valid netboot options</th>
</tr>
</thead>
<tbody>
<tr>
<td>x86, x86_64</td>
<td>ALL</td>
<td>pxe, xnba</td>
</tr>
<tr>
<td>ppc64</td>
<td>&lt;=rhe16, &lt;=sles11.3</td>
<td>yaboot</td>
</tr>
<tr>
<td>ppc64</td>
<td>&gt;=rhe1s7, &gt;=sles11.4</td>
<td>grub2, grub2-http, grub2-</td>
</tr>
<tr>
<td>tftp</td>
<td></td>
<td>petitboot</td>
</tr>
<tr>
<td>ppc64le</td>
<td>ALL</td>
<td>grub2, grub2-http, grub2-</td>
</tr>
<tr>
<td>PowerKVM Guest</td>
<td>ALL</td>
<td>grub2, grub2-http, grub2-</td>
</tr>
</tbody>
</table>

The TFTP server for this node (as known by this node). If not set, it defaults to networks.tftpserver.

tftpdir

The directory that roots this nodes contents from a tftp and related perspective. Used for NAS offload by using different mountpoints.

nfsserver

The NFS or HTTP server for this node (as known by this node). 

monserver
The monitoring aggregation point for this node. The format is “x,y” where x is the ip address as known by the management node and y is the ip address as known by the node.

**nfsdir**

The path that should be mounted from the NFS server.

**installnic**

The network adapter on the node that will be used for OS deployment, the installnic can be set to the network adapter name or the mac address or the keyword “mac” which means that the network interface specified by the mac address in the mac table will be used. If not set, primarynic will be used. If primarynic is not set too, the keyword “mac” will be used as default.

**primarynic**

This attribute will be deprecated. All the used network interface will be determined by installnic. The network adapter on the node that will be used for xCAT management, the primarynic can be set to the network adapter name or the mac address or the keyword “mac” which means that the network interface specified by the mac address in the mac table will be used. Default is eth0.

**discoverynics**

If specified, force discovery to occur on specific network adapters only, regardless of detected connectivity. Syntax can be simply “eth2,eth3” to restrict discovery to whatever happens to come up as eth2 and eth3, or by driver name such as “bnx2:0,bnx2:1” to specify the first two adapters managed by the bnx2 driver

**cmdinterface**

Not currently used.

**xcatmaster**

The hostname of the xCAT service node (as known by this node). This acts as the default value for nfsserver and tftpserver, if they are not set. If xcatmaster is not set, the node will use whoever responds to its boot request as its master. For the directed bootp case for POWER, it will use the management node if xcatmaster is not set.

**current_osimage**

Not currently used. The name of the osimage data object that represents the OS image currently deployed on this node.

**next_osimage**

Not currently used. The name of the osimage data object that represents the OS image that will be installed on the node the next time it is deployed.

**nimserver**

Not used for now. The NIM server for this node (as known by this node).

**routenames**

A comma separated list of route names that refer to rows in the routes table. These are the routes that should be defined on this node when it is deployed.

**nameservers**

An optional node/group specific override for name server list. Most people want to stick to site or network defined nameserver configuration.

**proxydhcp**
To specify whether the node supports proxydhcp protocol. Valid values: yes or 1, no or 0. Default value is yes.

syslog

To configure how to configure syslog for compute node. Valid values: blank (not set), ignore. blank - run postscript syslog; ignore - do NOT run postscript syslog

comments

Any user-written notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

nodetype.5

NAME

nodetype - a table in the xCAT database.

SYNOPSIS

nodetype Attributes: node, os, arch, profile, provmethod, supportedarchs, nodetype, comments, disable

DESCRIPTION

A few hardware and software characteristics of the nodes.

nodetype Attributes:

node

The node name or group name.

os

The operating system deployed on this node. Valid values: AIX, rhels*, rhelc*, rhas*, centos*, SL*, fedora*, sles* (where * is the version #). As a special case, if this is set to “boottarget”, then it will use the initrd/kernel/parameters specified in the row in the boottarget table in which boottarget.bprofile equals nodetype.profile.

arch

The hardware architecture of this node. Valid values: x86_64, ppc64, x86, ia64.

profile
The string to use to locate a kickstart or autoyast template to use for OS deployment of this node. If the provmethod attribute is set to an osimage name, that takes precedence, and profile need not be defined. Otherwise, the os, profile, and arch are used to search for the files in /install/custom first, and then in /opt/xcat/share/xcat.

provmethod

The provisioning method for node deployment. The valid values are install, netboot, statelite or an os image name from the osimage table. If an image name is specified, the osimage definition stored in the osimage table and the linuximage table (for Linux) or nimimage table (for AIX) are used to locate the files for templates, pkglists, syncfiles, etc. On Linux, if install, netboot or statelite is specified, the os, profile, and arch are used to search for the files in /install/custom first, and then in /opt/xcat/share/xcat.

supportedarchs

Comma delimited list of architectures this node can execute.

donetype

A comma-delimited list of characteristics of this node. Valid values: ppc, blade, vm (virtual machine), osi (OS image), mm, mn, rsa, switch.

comments

Any user-written notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

notification.5

NAME

notification - a table in the xCAT database.

SYNOPSIS

notification Attributes: filename, tables, tableops, comments, disable

DESCRIPTION

Contains registrations to be notified when a table in the xCAT database changes. Users can add entries to have additional software notified of changes. Add and remove entries using the provided xCAT commands regnotif and unregnotif.
notification Attributes:

filename
   The path name of a file that implements the callback routine when the monitored table changes. Can be a perl module or a command. See the regnotif man page for details.

tables
   Comma-separated list of xCAT database tables to monitor.

tableops
   Specifies the table operation to monitor for. Valid values: “d” (rows deleted), “a” (rows added), “u” (rows updated).

comments
   Any user-written notes.

disable
   Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

openbmc.5

NAME

openbmc - a table in the xCAT database.

SYNOPSIS

openbmc Attributes: node, bmc, consport, taggedvlan, username, password, comments, disable

DESCRIPTION

Setting for nodes that are controlled by an on-board OpenBMC.

openbmc Attributes:

node
   The node name or group name.

bmc
   The hostname of the BMC adapter.

consport
   The console port for OpenBMC.
taggedvlan

   bmcsetup script will configure the network interface of the BMC to be tagged to the VLAN specified.

username

   The BMC userid.

password

   The BMC password.

comments

   Any user-written notes.

disable

   Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

osdistro.5

NAME

osdistro - a table in the xCAT database.

SYNOPSIS

osdistro Attributes: osdistroname, basename, majorversion, minorversion, arch, type, dirpaths, comments, disable

DESCRIPTION

Information about all the OS distros in the xCAT cluster

osdistro Attributes:

osdistroname

   Unique name (e.g. rhels6.2-x86_64)

basename

   The OS base name (e.g. rhels)

majorversion

   The OS distro major version.(e.g. 6)

minorversion

   The OS distro minor version. (e.g. 2)

arch
The OS distro arch (e.g. x86_64)

type
    Linux or AIX
dirpaths
    Directory paths where OS distro is store. There could be multiple paths if OS distro has more than one
    ISO image. (e.g. /install/rhels6.2/x86_64,...)

comments
    Any user-written notes.
disable
    Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)
osdistroupdate.5

NAME

osdistroupdate - a table in the xCAT database.

SYNOPSIS

osdistroupdate Attributes: osupdatename, osdistroname, dirpath, downloadtime, comments, disable

DESCRIPTION

Information about the OS distro updates in the xCAT cluster

osdistroupdate Attributes:

osupdatename
    Name of OS update. (e.g. rhn-update1)
osdistroname
    The OS distro name to update. (e.g. rhels)
dirpath
    Path to where OS distro update is stored. (e.g. /install/osdistroupdates/rhels6.2-x86_64-20120716-update)
downloadtime
    The timestamp when OS distro update was downloaded.

comments
NAME

osimage - a table in the xCAT database.

SYNOPSIS

osimage Attributes: imagename, groups, profile, imagetype, description, provmethod, rootfstype, osdistroname, os-updatename, cfmdir, osname, osvers, osarch, synclists, postscripts, postbootscripts, serverrole, isdeletable, kitcomponents, environvar, comments, disable

DESCRIPTION

Basic information about an operating system image that can be used to deploy cluster nodes.

osimage Attributes:

imagename

The name of this xCAT OS image definition.

groups

A comma-delimited list of image groups of which this image is a member. Image groups can be used in the litefile and litetree table instead of a single image name. Group names are arbitrary.

profile

The node usage category. For example compute, service.

imagetype

The type of operating system image this definition represents (linux,AIX).

description

OS Image Description

provmethod

The provisioning method for node deployment. The valid values are install, netboot, statelite, boottarget, dualboot, sysclone. If boottarget is set, you must set linuximage.boottarget to the name of the boottarget definition. It is not used by AIX.

rootfstype
The filesystem type for the rootfs is used when the provmethod is statelite. The valid values are nfs or ramdisk. The default value is nfs.

**osdistroname**

The name of the OS distro definition. This attribute can be used to specify which OS distro to use, instead of using the osname, osvers, and osarch attributes. For *kit commands, the attribute will be used to read the osdistro table for the osname, osvers, and osarch attributes. If defined, the osname, osvers, and osarch attributes defined in the osimage table will be ignored.

**osupdatename**

A comma-separated list of OS distro updates to apply to this osimage.

**cfmdir**

CFM directory name for PCM. Set to /install/osimages/<osimage name>/cfmdir by PCM.

**osname**

Operating system name - AIX or Linux.

**osvers**

The Linux operating system deployed on this node. Valid values: rhels*, rhelc*, rhas*, centos*, SL*, fedora*, sles* (where * is the version #).

**osarch**

The hardware architecture of this node. Valid values: x86_64, ppc64, x86, ia64.

**synclists**

The fully qualified name of a file containing a list of files to synchronize on the nodes. Can be a comma separated list of multiple synclist files. The synclist generated by PCM named /install/osimages/<imagename>/synclist.cfm is reserved for use only by PCM and should not be edited by the admin.

**postscripts**

Comma separated list of scripts that should be run on this image after diskful installation or diskless boot. For installation of RedHat, CentOS, Fedora, the scripts will be run before the reboot. For installation of SLES, the scripts will be run after the reboot but before the init.d process. For diskless deployment, the scripts will be run at the init.d time, and xCAT will automatically add the list of scripts from the postbootscripts attribute to run after postscripts list. For installation of AIX, the scripts will run after the reboot and acts the same as the postbootscripts attribute. For AIX, use the postbootscripts attribute. See the site table runbootscripts attribute.

**postbootscripts**

Comma separated list of scripts that should be run on this after diskful installation or diskless boot. On AIX these scripts are run during the processing of /etc/inittab. On Linux they are run at the init.d time. xCAT automatically adds the scripts in the xcatdefaults.postbootscripts attribute to run first in the list. See the site table runbootscripts attribute.

**serverrole**

The role of the server created by this osimage. Default roles: mgtnode, servicenode, compute, login, storage, utility.

**isdeletable**

A flag to indicate whether this image profile can be deleted. This attribute is only used by PCM.

**kitcomponents**
List of Kit Component IDs assigned to this OS Image definition.

environvar

Comma delimited environment variables for the osimage

comments

Any user-written notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

passwd.5

NAME

passwd - a table in the xCAT database.

SYNOPSIS

passwd Attributes: key, username, password, cryptmethod, authdomain, comments, disable

DESCRIPTION

Contains default userids and passwords for xCAT to access cluster components. In most cases, xCAT will also actually set the userid/password in the relevant component when it is being configured or installed. Userids/passwords for specific cluster components can be overridden in other tables, e.g. mpa, ipmi, ppchcp, etc.

passwd Attributes:

key

The type of component this user/pw is for. Valid values: blade (management module), ipmi (BMC), system (nodes), omapi (DHCP), hmc, ivm, cec, frame, switch.

username

The default userid for this type of component

password

The default password for this type of component. On Linux, a crypted form could be provided. Hashes starting with $1$, $5$ and $6$ (md5, sha256 and sha512 respectively) are supported.

cryptmethod
Indicates the method to use to encrypt the password attribute. On AIX systems, if a value is provided for this attribute it indicates that the password attribute is encrypted. If the cryptmethod value is not set it indicates the password is a simple string value. On Linux systems, the cryptmethod can be set to md5, sha256 or sha512. If not set, sha256 will be used as default to encrypt plain-text passwords.

authdomain
The domain in which this entry has meaning, e.g. specifying different domain administrators per active directory domain

comments
Any user-written notes.

disable
Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

NAME

pdu - a table in the xCAT database.

SYNOPSIS

pdu Attributes: node, nodetype, pdutype, outlet, username, password, snmpversion, community, snmpuser, authtype, authkey, privtype, privkey, seclevel, comments, disable

DESCRIPTION

Parameters to use when interrogating pdus

pdu Attributes:

node
The hostname/address of the pdu to which the settings apply

nodetype
The node type should be pdu

pdutype
The type of pdu

outlet
The pdu outlet count

username
The remote login user name

**password**
The remote login password

**snmpversion**
The version to use to communicate with switch. SNMPv1 is assumed by default.

**community**
The community string to use for SNMPv1/v2

**snmpuser**
The username to use for SNMPv3 communication, ignored for SNMPv1

**authtype**
The authentication protocol(MD5|SHA) to use for SNMPv3.

**authkey**
The authentication passphrase for SNMPv3

**privtype**
The privacy protocol(AES|DES) to use for SNMPv3.

**privkey**
The privacy passphrase to use for SNMPv3.

**seclevel**
The Security Level(noAuthNoPriv|authNoPriv|authPriv) to use for SNMPv3.

**comments**
Any user-written notes.

**disable**
Set to ‘yes’ or ‘1’ to comment out this row.

**SEE ALSO**

`nodels(1), chtab(8), tabdump(8), tabedit(8)`

**pduoutlet.5**

**NAME**

**pduoutlet** - a table in the xCAT database.

**SYNOPSIS**

**pduoutlet Attributes:** node, pdu, comments, disable
DESCRIPTION

Contains list of outlet numbers on the pdu each node is connected to.

**pduoutlet Attributes:**

- **node**
  - The node name or group name.
- **pdu**
  - a comma-separated list of outlet number for each PDU, ex: pdu1:outlet1,pdu2:outlet1
- **comments**
  - Any user-written notes.
- **disable**
  - Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

performance.5

NAME

**performance** - a table in the xCAT database.

SYNOPSIS

**performance Attributes:** timestamp, node, attrname, attrvalue, comments, disable

DESCRIPTION

Describes the system performance every interval unit of time.

**performance Attributes:**

- **timestamp**
  - The time at which the metric was captured.
- **node**
  - The node name.
- **attrname**
  - The metric name.
**attrvalue**

The metric value.

**comments**

Any user-provided notes.

**disable**

Set to ‘yes’ or ‘1’ to comment out this row.

**SEE ALSO**

nodes(1), ctab(8), tabdump(8), tabedit(8)

**policy.5**

**NAME**

**policy** - a table in the xCAT database.

**SYNOPSIS**

**policy Attributes:** priority, name, host, commands, noderange, parameters, time, rule, comments, disable

**DESCRIPTION**

The policy table in the xCAT database controls who has authority to run specific xCAT operations. It is basically the Access Control List (ACL) for xCAT. It is sorted on the priority field before evaluating.

**policy Attributes:**

**priority**

The priority value for this rule. This value is used to identify this policy data object (i.e. this rule) The table is sorted on this field with the lower the number the higher the priority. For example 1.0 is higher priority than 4.1 is higher than 4.9.

**name**

The username that is allowed to perform the commands specified by this rule. Default is “*” (all users).

**host**

The host from which users may issue the commands specified by this rule. Default is “*” (all hosts). Only all or one host is supported

**commands**

The list of commands that this rule applies to. Default is “*” (all commands).

**noderange**

The Noderange that this rule applies to. Default is “*” (all nodes). Not supported with the *def commands.
parameters

A regular expression that matches the command parameters (everything except the noderange) that this rule applies to. Default is “*” (all parameters). Not supported with the *def commands.

time

Time ranges that this command may be executed in. This is not supported.

rule

Specifies how this rule should be applied. Valid values are: allow, trusted. Allow will allow the user to run the commands. Any other value will deny the user access to the commands. Trusted means that once this client has been authenticated via the certificate, all other information that is sent (e.g. the username) is believed without question. This authorization should only be given to the xcatd on the management node at this time.

comments

Any user-written notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

postscripts.5

NAME

postscripts - a table in the xCAT database.

SYNOPSIS

postscripts Attributes: node, postscripts, postbootscripts, comments, disable

DESCRIPTION

The scripts that should be run on each node after installation or diskless boot.

postscripts Attributes:

node

The node name or group name.

postscripts

Comma separated list of scripts that should be run on this node after diskful installation or diskless boot. Each script can take zero or more parameters. For example: “script1 p1 p2,script2,...”. xCAT automatically adds the postscripts from the xcatdefaults.postscripts attribute of the table to run first on the nodes after install or diskless boot. For installation of RedHat, CentOS, Fedora, the scripts will be run before
the reboot. For installation of SLES, the scripts will be run after the reboot but before the init.d process. For diskless deployment, the scripts will be run at the init.d time, and xCAT will automatically add the list of scripts from the postbootscripts attribute to run after postscripts list. For installation of AIX, the scripts will run after the reboot and acts the same as the postbootscripts attribute. For AIX, use the postbootscripts attribute. Please note that the postscripts specified for “xcatdefaults” will be assigned to node automatically, they can not be removed from “postscripts” attribute of a node with “chdef -m” command

**postbootscripts**

Comma separated list of scripts that should be run on this node after diskful installation or diskless boot. Each script can take zero or more parameters. For example: “script1 p1 p2,script2,…”. On AIX these scripts are run during the processing of /etc/inittab. On Linux they are run at the init.d time. xCAT automatically adds the scripts in the xcatdefaults.postbootscripts attribute to run first in the list. Please note that the postbootscripts specified for “xcatdefaults” will be assigned to node automatically, they can not be removed from “postbootscripts” attribute of a node with “chdef -m” command

**comments**

Any user-written notes.

**disable**

Set to ‘yes’ or ‘1’ to comment out this row.

**SEE ALSO**

nodels(1), chtab(8), tabdump(8), tabedit(8)

**ppc.5**

**NAME**

ppc - a table in the xCAT database.

**SYNOPSIS**

**ppc Attributes:** node, hcp, id, pprofile, parent, nodetype, supernode, sfp, comments, disable

**DESCRIPTION**

List of system p hardware: HMCs, IVMs, FSPs, BPCs, CECs, Frames.

**ppc Attributes:**

**node**

The node name or group name.

**hcp**

The hardware control point for this node (HMC, IVM, Frame or CEC). Do not need to set for BPAs and FSPs.

**id**
For LPARs: the LPAR numeric id; for CECs: the cage number; for Frames: the frame number.

**pprofile**

The LPAR profile that will be used the next time the LPAR is powered on with rpower. For DFM, the pprofile attribute should be set to blank.

**parent**

For LPARs: the CEC; for FSPs: the CEC; for CEC: the frame (if one exists); for BPA: the frame; for frame: the building block number (which consists 1 or more service nodes and compute/storage nodes that are serviced by them - optional).

**nodetype**

The hardware type of the node. Only can be one of fsp, bpa, cec, frame, ivm, hmc and lpar

**supernode**

Indicates the connectivity of this CEC in the HFI network. A comma separated list of 2 ids. The first one is the supernode number the CEC is part of. The second one is the logical location number (0-3) of this CEC within the supernode.

**sfp**

The Service Focal Point of this Frame. This is the name of the HMC that is responsible for collecting hardware service events for this frame and all of the CECs within this frame.

**comments**

Any user-written notes.

**disable**

Set to ‘yes’ or ‘1’ to comment out this row.

**SEE ALSO**

nodels(1), chtab(8), tabdump(8), tabedit(8)

**ppcdirect.5**

**NAME**

**ppcdirect** - a table in the xCAT database.

**SYNOPSIS**

**ppcdirect Attributes:** hcp, username, password, comments, disable

**DESCRIPTION**

Info necessary to use FSPs/BPAs to control system p CECs/Frames.
ppcdirect Attributes:

hcp

Hostname of the FSPs/BPAs(for ASMI) and CECs/Frames(for DFM).

username

Userid of the FSP/BPA(for ASMI) and CEC/Frame(for DFM). If not filled in, xCAT will look in the passwd table for key=fsp. If not in the passwd table, the default used is admin.

password

Password of the FSP/BPA(for ASMI) and CEC/Frame(for DFM). If not filled in, xCAT will look in the passwd table for key=fsp. If not in the passwd table, the default used is admin.

comments

Any user-written notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

ppchcp.5

NAME

ppchcp - a table in the xCAT database.

SYNOPSIS

ppchcp Attributes: hcp, username, password, comments, disable

DESCRIPTION

Info necessary to use HMCs and IVMs as hardware control points for LPARs.

ppchcp Attributes:

hcp

Hostname of the HMC or IVM.

username

Userid of the HMC or IVM. If not filled in, xCAT will look in the passwd table for key=hmc or key=ivm. If not in the passwd table, the default used is hscroot for HMCs and padmin for IVMs.

password
Password of the HMC or IVM. If not filled in, xCAT will look in the passwd table for key=hmc or key=ivm. If not in the passwd table, the default used is abc123 for HMCs and padmin for IVMs.

comments

Any user-written notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

prescripts.5

NAME

prescripts - a table in the xCAT database.

SYNOPSIS

prescripts Attributes: node, begin, end, comments, disable

DESCRIPTION

The scripts that will be run at the beginning and the end of the nodeset(Linux), nimnodeset(AIX) or mkdsklsnode(AIX) command.

prescripts Attributes:

node

The node name or group name.

begin

The scripts to be run at the beginning of the nodeset(Linux), nimnodeset(AIX) or mkdsklsnode(AIX) command.

The format is: [action1:]s1,s2…[| action2:s3,s4,s5…]

where:

• action1 and action2 for Linux are the nodeset actions specified in the command. For AIX, action1 and action1 can be ‘diskless’ for mkdsklsnode command and ‘standalone’ for nimnodeset command.

• s1 and s2 are the scripts to run for action1 in order.

• s3, s4, and s5 are the scripts to run for actions2.

If actions are omitted, the scripts apply to all actions. Examples:
myscript1,myscript2 (all actions) diskless:myscript1,myscript2 (AIX) install:myscript1,myscript2|netboot:myscript3 (Linux)

All the scripts should be copied to /install/prescripts directory. The following two environment variables will be passed to each script:

NODES a coma separated list of node names that need to run the script for ACTION current nodeset action.

If ‘#xCAT setting:MAX_INSTANCE=number’ is specified in the script, the script will get invoked for each node in parallel, but no more than number of instances will be invoked at at a time. If it is not specified, the script will be invoked once for all the nodes.

end

The scripts to be run at the end of the nodeset(Linux), nimnodeset(AIX), or mkdsklnode(AIX) command. The format is the same as the ‘begin’ column.

comments

Any user-written notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodes(1), chtab(8), tabdump(8), tabedit(8)

prodkey.5

NAME

prodkey - a table in the xCAT database.

SYNOPSIS

prodkey Attributes: node, product, key, comments, disable

DESCRIPTION

Specify product keys for products that require them

prodkey Attributes:

node

The node name or group name.

product

A string to identify the product (for OSes, the osname would be used, i.e. wink28

key
The product key relevant to the aforementioned node/group and product combination

**comments**

Any user-written notes.

**disable**

Set to ‘yes’ or ‘1’ to comment out this row.

**SEE ALSO**

nodels(1), chtab(8), tabdump(8), tabedit(8)

rack.5

**NAME**

rack - a table in the xCAT database.

**SYNOPSIS**

rack Attributes: rackname, displayname, num, height, room, comments, disable

**DESCRIPTION**

Rack information.

rack Attributes:

**rackname**

The rack name.

**displayname**

Alternative name for rack. Only used by PCM.

**num**

The rack number.

**height**

Number of units which can be stored in the rack.

**room**

The room in which the rack is located.

**comments**

Any user-written notes.

**disable**

Set to ‘yes’ or ‘1’ to comment out this row.
SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

routes.5

NAME

routes - a table in the xCAT database.

SYNOPSIS

routes Attributes: routename, net, mask, gateway, ifname, comments, disable

DESCRIPTION

Describes the additional routes needed to be setup in the os routing table. These routes usually are used to connect the management node to the compute node using the service node as gateway.

routes Attributes:

routename
    Name used to identify this route.

net
    The network address.

mask
    The network mask.

gateway
    The gateway that routes the ip traffic from the mn to the nodes. It is usually a service node.

ifname
    The interface name that facing the gateway. It is optional for IPv4 routes, but it is required for IPv6 routes.

comments
    Any user-written notes.

disable
    Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)
servicenode.5

NAME

servicenode - a table in the xCAT database.

SYNOPSIS

servicenode Attributes: node, nameserver, dhcpserver, tftpserver, nfsserver, conserver, monserver, ldapserver, ntpserver, ftpserver, nimserver, ipforward, dhcpinterfaces, proxydhcp, comments, disable

DESCRIPTION

List of all Service Nodes and services that will be set up on the Service Node.

servicenode Attributes:
	node

The hostname of the service node as known by the Management Node.

nameserver

Do we set up DNS on this service node? Valid values: 2, 1, or 0. If 2, creates named.conf as dns slave, using the management node as dns master, and starts named. If 1, creates named.conf file with forwarding to the management node and starts named. If 0, it does not change the current state of the service.

dhcpserver

Do we set up DHCP on this service node? Not supported on AIX. Valid values: 1 or 0. If 1, runs makedhcp -n. If 0, it does not change the current state of the service.

tftpserver

Do we set up TFTP on this service node? Not supported on AIX. Valid values: 1 or 0. If 1, configures and starts atftp. If 0, it does not change the current state of the service.

nfsserver

Do we set up file services (HTTP, FTP, or NFS) on this service node? For AIX will only setup NFS, not HTTP or FTP. Valid values: 1 or 0. If 0, it does not change the current state of the service.

conserver

Do we set up console service on this service node? Valid values: 0, 1, or 2. If 0, it does not change the current state of the service. If 1, configures and starts conserver daemon. If 2, configures and starts goconserver daemon.

monserver

Is this a monitoring event collection point? Valid values: 1 or 0. If 0, it does not change the current state of the service.

ldapserver

Do we set up ldap caching proxy on this service node? Not supported on AIX. Valid values: 1 or 0. If 0, it does not change the current state of the service.
ntpserver

Not used. Use `setupntp` postscript to setup a ntp server on this service node? Valid values: 1 or 0. If 0, it does not change the current state of the service.

ftpserver

Do we set up a ftp server on this service node? Not supported on AIX Valid values: 1 or 0. If 1, configure and start vsftpd. (You must manually install vsftpd on the service nodes before this.) If 0, it does not change the current state of the service. xCAT is not using ftp for compute nodes provisioning or any other xCAT features, so this attribute can be set to 0 if the ftp service will not be used for other purposes.

nimserver

Not used. Do we set up a NIM server on this service node? Valid values: 1 or 0. If 0, it does not change the current state of the service.

ipforward

Do we set up ip forwarding on this service node? Valid values: 1 or 0. If 0, it does not change the current state of the service.

dhcinterfaces

The network interfaces DHCP server should listen on for the target node. This attribute can be used for management node and service nodes. If defined, it will override the values defined in `site.dhcinterfaces`. This is a comma separated list of device names. !remote! indicates a non-local network for relay DHCP. For example: !remote!, eth0, eth1.

proxydhcp

Do we set up proxydhcp service on this node? valid values: 1 or 0. If 1, the proxydhcp daemon will be enabled on this node.

comments

Any user-written notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

`nodels(1), chtab(8), tabdump(8), tabedit(8)`

`site.5`

NAME

site - a table in the xCAT database.

SYNOPSIS

site Attributes: key, value, comments, disable
DESCRIPTION

Global settings for the whole cluster. This table is different from the other tables in that each attribute is just named in the key column, rather than having a separate column for each attribute. The following is a list of attributes currently used by xCAT organized into categories.

**site Attributes:**

<table>
<thead>
<tr>
<th>key</th>
<th>Attribute Name: Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>--------------</td>
<td>---------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>AIX ATTRIBUTES</td>
<td></td>
</tr>
<tr>
<td>nimprime</td>
<td>The name of NIM server, if not set default is the AIX MN. If Linux MN, then must be set for support of mixed cluster</td>
</tr>
<tr>
<td>useSSHonAIX</td>
<td>(yes/1 or no/0). Default is yes. The support for rsh/rcp is deprecated.</td>
</tr>
<tr>
<td>useNFSv4onAIX</td>
<td>(yes/1 or no/0). If yes, NFSv4 will be used with NIM. If no, NFSv3 will be used with NIM. Default is no.</td>
</tr>
<tr>
<td>--------------</td>
<td>---------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>DATABASE ATTRIBUTES</td>
<td></td>
</tr>
<tr>
<td>auditnosyslog</td>
<td>If set to 1, then commands will only be written to the auditlog table.</td>
</tr>
<tr>
<td>auditskipcmds</td>
<td>List of commands and/or client types that will not be written to the auditlog table and syslog. See auditnosyslog.</td>
</tr>
<tr>
<td>databaseloc</td>
<td>Directory where we create the db instance directory.</td>
</tr>
<tr>
<td>excludenodes</td>
<td>A set of comma separated nodes and/or groups that would be subtracted from any noderange, it can be used for excluding some failed nodes for any xCAT commands. See the 'noderange' manpage for details on supported formats.</td>
</tr>
<tr>
<td>nodestatus</td>
<td>If set to 'n', the nodelist.status column will not be updated during</td>
</tr>
</tbody>
</table>
the node deployment, node discovery and power operations. The default is to update.
skiptables: Comma separated list of tables to be skipped by dumpxCATdb
skipvalidatelog: If set to 1, then getcredentials and getpostscripts calls will not be logged in syslog.

------------
DHCP ATTRIBUTES
------------
dhcpinterfaces: The network interfaces DHCP should listen on. If it is the same for all nodes, use a comma-separated list of the NICs. To specify different NICs for different nodes, use the format: "xcatmn|eth1,eth2;service|bond0", where xcatmn is the name of the management node, DHCP should listen on the eth1 and eth2 interfaces. All the nodes in group 'service' should listen on the 'bond0' interface.

To disable the genesis kernel from being sent to specific interfaces, a ':noboot' option can be appended to the interface name. For example, if the management node has two interfaces, eth1 and eth2, disable genesis from being sent to eth1 using: "eth1:noboot,eth2".
dhcpsetup: If set to 'n', it will skip the dhcp setup process in the nodeset cmd.
dhcplease: The lease time for the dhcp client. The default value is 43200.
disjointdhcps: If set to '1', the .leases file on a service node only contains the nodes it manages. And when 'sharedtftp' is disabled, nodeset handles boot loader configuration on a service node only for the nodes it manages. The default value is '0'. It means include all the nodes in the subnet.
pruneservices: Whether to enable service pruning when noderm is run (i.e. removing DHCP entries when noderm is executed)
managedaddressmode: The mode of networking configuration during node provision.
configured on MN.
--dhcp protocol.
The default is 'dhcp'.

DNS ATTRIBUTES

dnshandler: Name of plugin that handles DNS setup for makedns.
domain: The DNS domain name used for the cluster.
forwarders: The DNS servers at your site that can provide names outside of
the cluster.
node to forward requests it does not know to these servers. Note that the DNS
servers on the service nodes will ignore this value and always be configured
to forward to the management node.
emptyzonesenable: (yes or no). This is to set empty-zones-enable value in
named.conf options section.
master: The hostname of the xCAT management node, as known by the nodes.
nameservers: A comma delimited list of DNS servers that each node in the
cluster should use. This value will end up in the nameserver settings of the
/etc/resolv.conf on each node. It is common (but not
required) to set this attribute value to the IP addr of the xCAT management
node, if you have set up the DNS on the management node by running
makedns. In a hierarchical cluster, you can also set this attribute to
"<xcatmaster>" to mean the DNS server for each node should be
the node that is managing it (either its service node or the
management node).
externaldns: To specify that external dns is used. If externaldns is set
to any value then, makedns command will not start the local nameserver on
xCAT MN. Default is to start the local nameserver.
dnsupdaters: The value are ',' separated string which will be added to the
zone config section. This is an interface for user to add configuration entries to
the zone sections in named.conf.
dnsinterfaces: The network interfaces DNS should listen on. If it is the
same for all nodes, use a simple comma-separated list of NICs. To
specify different NICs for different nodes, use the format: "xcatmn|eth1,eth2;
service|bond0", "
where xcatmn is the name of the management node, and DNS should listen on the eth1 and eth2 interfaces. All the nodes in group 'service' should listen on the 'bond0' interface.

NOTE: If using this attribute to block certain interfaces, make sure the IP maps to your hostname of xCAT MN is not blocked since xCAT needs to use this IP to communicate with the local NDS server on MN.

-------------------------
HARDWARE CONTROL ATTRIBUTES
-------------------------
blademaxp: The maximum number of concurrent processes for blade hardware control.
ea_primary_hmc: The hostname of the HMC that the Integrated Switch Network Management Event Analysis should send hardware serviceable events to for processing and potentially sending to IBM.
ea_backup_hmc: The hostname of the HMC that the Integrated Switch Network Management Event Analysis should send hardware serviceable events to if the primary HMC is down.
enableASMI: (yes/1 or no/0). If yes, ASMI method will be used after fsp-api. If no, when fsp-api is used, ASMI method will not be used. Default is no.
fsptimeout: The timeout, in milliseconds, to use when communicating with FSPs.
hwctrldispatch: Whether or not to send hw control operations to the service node of the target nodes. Default is 'y'. (At present, this attribute is only used for IBM Flex System)
ipmidispatch: Whether or not to send ipmi hw control operations to the service node of the target compute nodes. Default is 'y'.
ipmapmaxp: The max # of processes for ipmi hw ctrl. The default is 64. Currently, this is only used for HP hw control.
ipmiretries: The # of retries to use when communicating with BMCs. Default is 3.
ipmisdr_cache: If set to 'no', then the xCAT IPMI support will not cache locally the target node's SDR cache to improve performance.
ipmitimeout: The timeout to use when communicating with BMCs. Default is 2. This attribute is currently not used.
**maxssh:** The max # of SSH connections at any one time to the hw ctrl point for PPC

This parameter doesn't take effect on the rpower command. It takes effects on other PPC hardware control command getmacs/rnetboot/rbootseq and so on. Default is 8.

**syspowerinterval:** For SystemP CECs, this is the number of seconds the rpower command will wait between performing the action for each CEC.

For SystemX IPMI servers, this is the number of seconds the rpower command will wait between powering on <syspowermaxnodes> nodes at a time. This value is used to control the power on speed in large clusters. Default is 0.

**syspowermaxnodes:** The number of servers to power on at one time before waiting 'syspowerinterval' seconds to continue on to the next set of nodes. If the noderange given to rpower includes nodes served by different service nodes, it will try to spread each set of nodes across the service nodes evenly. Currently only used for IPMI servers and must be set if 'syspowerinterval' is set.

**powerinterval:** The number of seconds the rpower command to LPARs will wait between performing the action for each LPAR. LPARs of different HCPs (HMCs or FSPs) are done in parallel. This is used to limit the cluster boot up speed in large clusters. Default is 0. This is currently only used for system p hardware.

**ppcmaxp:** The max # of processes for PPC hw ctrl. If there are more than ppcmaxp hcps, this parameter will take effect. It will control the max number of processes for PPC hardware control commands. Default is 64.

**ppcretry:** The max # of PPC hw connection attempts to HMC before failing. It only takes effect on the hardware control commands through HMC. Default is 3.

**ppctimeout:** The timeout, in milliseconds, to use when communicating with PPC hw through HMC. It only takes effect on the hardware control commands through HMC. Default is 0.
### INSTALL/DEPLOYMENT ATTRIBUTES

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>snmpc</td>
<td>The snmp community string that xcat should use when communicating with the switches.</td>
</tr>
<tr>
<td>cleanupxcatpost</td>
<td>(yes/1 or no/0). Set to 'yes' or '1' to clean up the /xcatpost directory on the stateless and stateelite nodes after the postscripts are run. Default is no.</td>
</tr>
<tr>
<td>db2installloc</td>
<td>The location which the service nodes should mount for the db2 code to install. Format is hostname:/path. If hostname is omitted, it defaults to the management node. Default is /mntdb2.</td>
</tr>
<tr>
<td>defserialflow</td>
<td>The default serial flow - currently only used by the mknb command.</td>
</tr>
<tr>
<td>defserialport</td>
<td>The default serial port - currently only used by mknb.</td>
</tr>
<tr>
<td>defserialspeed</td>
<td>The default serial speed - currently only used by mknb.</td>
</tr>
<tr>
<td>disablenodesetwarning</td>
<td>Allow the legacy xCAT non-osimage style nodeset to execute.</td>
</tr>
<tr>
<td>genmacprefix</td>
<td>When generating mac addresses automatically, use this manufacturing prefix (e.g. 00:11:aa)</td>
</tr>
<tr>
<td>genpasswords</td>
<td>Automatically generate random passwords for BMCs when configuring them.</td>
</tr>
<tr>
<td>installdir</td>
<td>The local directory name used to hold the node deployment packages.</td>
</tr>
<tr>
<td>installoc</td>
<td>The location from which the service nodes should mount the deployment packages in the format hostname:/path. If hostname is omitted, it defaults to the management node. The path must match the path in the installdir attribute.</td>
</tr>
<tr>
<td>iscsidir</td>
<td>The path to put the iscsi disks in on the mgmt node.</td>
</tr>
<tr>
<td>mnroutenames</td>
<td>The name of the routes to be setup on the management node. It is a comma separated list of route names that are defined in the routes table.</td>
</tr>
<tr>
<td>runbootscripts</td>
<td>If set to 'yes' the scripts listed in the postbootscripts attribute in the osimage and postscripts tables will be run during each reboot of stateful (diskful) nodes. This attribute has no default.</td>
</tr>
</tbody>
</table>
effect on stateless and statelite nodes. Run the following command after you change the value of this attribute:
'updatenode <nodes> -P setuppostbootscripts'

precreatemypostscripts: (yes/1 or no/0). Default is no. If yes, it will instruct xCAT at nodeset and update node time to query the db once for all of the nodes passed into the cmd and create the mypostscript file for each node, and put them in a directory of tftpdir (such as: /tftpboot). If no, it will not generate the mypostscript file in the tftpdir.

secureroot: If set to 1, xCAT will use secure mode to transfer root password hash during the installation. Default is 0.

setinstallnic: Set the network configuration for installnic to be static.

sharedtftp: Set to 0 or no, xCAT should not assume the directory in tftpdir is mounted on all on Service Nodes. Default is 1/yes. If value is set to a hostname, the directory in tftpdir will be mounted from that hostname on the SN

sharedinstall: Indicates if a shared file system will be used for installation resources. Possible values are: 'no', 'sns', or 'all'. 'no' means a shared file system is not being used. 'sns' means a shared filesystem is being used across all service nodes. 'all' means that the management as well as the service nodes are all using a common shared filesystem. The default is 'no'.

xcatconfdir: Where xCAT config data is (default /etc/xcat).

xcatdebugmode: the xCAT debug level. xCAT provides a batch of techniques to help user debug problems while using xCAT, especially on OS provision, and accessing the installing system via ssh, etc. These techniques will be enabled according to different xCAT debug levels specified by 'xcatdebugmode', currently supported values: '0': disable debug mode '1': enable basic debug mode '2': enable expert debug mode For the details on 'basic debug mode' and 'expert debug mode', refer to xCAT documentation.

-------------------

REMTESHELL ATTRIBUTES
-------------------
nodesyncfiledir: The directory on the node, where xdcp will rsync the files

SNsyncfiledir: The directory on the Service Node, where xdcp will rsync the files from the MN that will eventually be rsync'd to the compute nodes.

sshbetweennodes: Comma separated list of groups of compute nodes to enable passwordless root ssh to the nodes during install or running 'xdsh -K'. The default is ALLGROUPS. Set to NOGROUPS to disable.

are always configured with passwordless root access. Service Nodes are not affected by this attribute as they are always configured with passwordless root access.

continue installing. If using the zone table, this attribute in not used.

-----------------
SERVICES ATTRIBUTES
-----------------

consolondemand: When set to 'yes', conserver connects and creates the console output only when the user opens the console. Default is 'no' on Linux, 'yes' on AIX.

httpport: The port number that the booting/installing nodes should contact the http server on the MN/SN on. It is your responsibility to configure the http server to listen on that port - xCAT will not do that.

nmapoptions: Additional options for the nmap command. nmap is used in pping, nodestat, xdsh -v and updatenode commands. Sometimes additional performance tuning may be needed for nmap due to network traffic.

may not give stable output. You can increase the timeout value by specifying '--min-rtt-timeout 1s'. xCAT will append the options defined here to the nmap command.

ntpservers: A comma delimited list of NTP servers for the service node and the compute node to sync with. The keyword <xcatmaster> means the node's NTP server is the node that is managing it (either its service node or the management node).

extntpservers: A comma delimited list of external NTP servers for the xCAT management node to sync with. If it is empty, the NTP server will use the management node's own hardware clock to calculate the system date and time.
svloglocal: If set to 1, syslog on the service node will not get forwarded to the management node.

timezone: (e.g. America/New_York)

tftpdir: The tftp directory path. Default is /tftpboot
	tftpflags: The flags that used to start tftpd. Default is '-v -l -s /tftpboot -m /etc/tftpmapfile4xcat.conf' if tftpflags is not set

useNmapfromMN: When set to yes, nodestat command should obtain the node status using nmap (if available) from the management node instead of the service node. This will improve the performance in a flat network.

vsftp: Default is 'n'. If set to 'y', xcatd on the management node will automatically start vsftpd. (vsftpd must be installed by the admin). This setting does not apply to service nodes. For service nodes, set servicenode ftpserver=1.

FQDNfirst: Fully Qualified Domain Name first. If set to 1/yes/enable, the /etc/hosts entries generated by 'makehosts' will put the FQDN before the PQDN(Partially Qualified Domain Name). Otherwise, the original behavior will be performed.

hierarchicalattrs: A comma delimited list of table attributes(e.g. postscripts, postbootscripts) that will be included hierarchically. Attribute values for all the node's groups will be applied to the node in the groups' order except the repeat one.

By default, comma is used to combine the values. But some columns use different delimiter, to specify delimiter for those columns as format of 'column:delimiter'.

dbtracelevel: The trace level for the database access log. To activate this setting, please restart xcatd or send HUP signal to the 'xcatd: DB Access' process, Like: 

```
ps -ef | grep 'xcatd: DB Access' | grep -v grep | awk '{print $2}' | xargs kill -HUP
```

Current support values:
0: disable the trace log for db
1: trace the calls of database subroutines
2: Besides the log from level 1, trace the event to build the cache for the table
3: Besides the log from level 2, trace the event with cache hit

(continues on next page)
4: Besides the log from level 3, trace the SQL statement for db access.
   With this configuration, xcat will send the log to syslog very frequently, some of the log may be lost if imjournal is enabled by rsyslog. Please see https://github.com/xcat2/xcat-core/issues/3910 for the detail.

-----------------------
VIRTUALIZATION ATTRIBUTES
-----------------------
usexhrm: Have xCAT execute the xHRM script when booting up KVM guests to configure the virtual network bridge.

vcenterautojoin: When set to no, the VMWare plugin will not attempt to auto remove and add hypervisors while trying to perform operations. If users or tasks outside of xCAT perform the joining this assures xCAT will not interfere.

vmwarereconfigonpower: When set to no, the VMWare plugin will make no effort to push vm.cpus/vm.memory updates from xCAT to VMWare.

persistkvmguests: Keep the kvm definition on the kvm hypervisor when you power off the kvm guest node. This is useful for you to manually change the kvm xml definition file in virsh for debugging. Set anything means enable.

----------------------
XCAT DAEMON ATTRIBUTES
----------------------
tokenexpiredays: Number of days before REST API token will expire. The default is 1. use 'never' if you want your token to never expire.

useflowcontrol: (yes/1 or no/0). If yes, the postscript processing on each node contacts xcatd on the MN/SN using a lightweight UDP packet to wait until xcatd is ready to handle the requests associated with postscripts. This prevents deploying nodes from flooding xcatd and locking out admin interactive use. This value works with the xcatmaxconnections and xcatmaxbatch attributes. Is not supported on AIX. If the value is no, nodes sleep for a random time before contacting xcatd, and retry. The default is no. See the following document for details: Hints_and_Tips_for_Large_Scale_Clusters
xCATmaxconnections: Number of concurrent xCAT protocol requests before requests begin queueing. This applies to both client command requests and node requests, e.g. to get postscripts. Default is 64.

xCATmaxbatchconnections: Number of concurrent xCAT connections allowed from the nodes. Value must be less than xCATmaxconnections. Default is 50.

xCATdport: The port used by the xCAT daemon for client/server communication.

xCATiport: The port used by xCAT to receive install status updates from nodes.

xCATlport: The port used by xCAT command log writer process to collect command output.

xCATsslversion: The ssl version by xCAT. Default is TLSv1.

xCATsslciphers: The ssl cipher by xCAT. Default is 3DES.

value

The value of the attribute specified in the “key” column.

comments

Any user-written notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

statelite.5

NAME

statelite - a table in the xCAT database.

SYNOPSIS

statelite Attributes: node, image, statemnt, mntopts, comments, disable
DESCRIPTION

The location on an NFS server where a node’s persistent files are stored. Any file marked persistent in the litefile table will be stored in the location specified in this table for that node.

statellite Attributes:

node
The name of the node or group that will use this location.

image
Reserved for future development, not used.

statemnt
The persistent read/write area where a node’s persistent files will be written to, e.g: 10.0.0.1/state/. The node name will be automatically added to the pathname, so 10.0.0.1:/state, will become 10.0.0.1:/state/<nodename>.

mntopts
A comma-separated list of options to use when mounting the persistent directory. (Ex. ‘soft’) The default is to do a ‘hard’ mount.

comments
Any user-written notes.

disable
Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

storage.5

NAME

storage - a table in the xCAT database.

SYNOPSIS

storage Attributes: node, osvolume, size, state, storagepool, hypervisor, fcrange, volumetag, type, controller, comments, disable

DESCRIPTION

storage Attributes:

node
The node name

**osvolume**

Specification of what storage to place the node OS image onto. Examples include:

<table>
<thead>
<tr>
<th>Example</th>
</tr>
</thead>
<tbody>
<tr>
<td>localdisk (Install to first non-FC attached disk)</td>
</tr>
<tr>
<td>usbdisk (Install to first USB mass storage device seen)</td>
</tr>
<tr>
<td>wwn=0x50000393c813840c (Install to storage device with given WWN)</td>
</tr>
</tbody>
</table>

**size**

Size of the volume. Examples include: 10G, 1024M.

**state**

State of the volume. The valid values are: free, used, and allocated

**storagepool**

Name of storage pool where the volume is assigned.

**hypervisor**

Name of the hypervisor where the volume is configured.

**fcrange**

A range of acceptable fibre channels that the volume can use. Examples include: 3B00-3C00;4B00-4C00.

**volumetag**

A specific tag used to identify the volume in the autoyast or kickstart template.

**type**

The plugin used to drive storage configuration (e.g. svc)

**controller**

The management address to attach/detach new volumes. In the scenario involving multiple controllers, this data must be passed as argument rather than by table value.

**comments**

Any user-written notes.

**disable**

Set to ‘yes’ or ‘1’ to comment out this row.

### SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

switch.5

### NAME

switch - a table in the xCAT database.
SYNOPSIS

switch Attributes: node, switch, port, vlan, interface, comments, disable

DESCRIPTION

Contains what switch port numbers each node is connected to.

switch Attributes:

node
The node name or group name.

switch
The switch hostname.

port
The port number in the switch that this node is connected to. On a simple 1U switch, an administrator can generally enter the number as printed next to the ports, and xCAT will understand switch representation differences. On stacked switches or switches with line cards, administrators should usually use the CLI representation (i.e. 2/0/1 or 5/8). One notable exception is stacked SMC 8848M switches, in which you must add 56 for the proceeding switch, then the port number. For example, port 3 on the second switch in an SMC8848M stack would be 59

vlan
The ID for the tagged vlan that is created on this port using mkvlan and chvlan commands.

interface
The interface name from the node perspective. For example, eth0. For the primary nic, it can be empty, the word “primary” or “primary:ethx” where ethx is the interface name.

comments
Any user-written notes.

disable
Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

switches.5

NAME

switches - a table in the xCAT database.
SYNOPSIS

switches Attributes: switch, snmpversion, username, password, privacy, auth, linkports, sshusername, sshpassword, protocol, switchtype, comments, disable

DESCRIPTION

Parameters to use when interrogating switches

switches Attributes:

switch
The hostname/address of the switch to which the settings apply

snmpversion
The version to use to communicate with switch. SNMPv1 is assumed by default.

username
The username to use for SNMPv3 communication, ignored for SNMPv1

password
The password string for SNMPv3 or community string for SNMPv1/SNMPv2. Falls back to passwd table, and site snmpc value if using SNMPv1/SNMPv2.

privacy
The privacy protocol to use for v3. xCAT will use authNoPriv if this is unspecified. DES is recommended to use if v3 enabled, as it is the most readily available.

auth
The authentication protocol to use for SNMPv3. SHA is assumed if v3 enabled and this is unspecified

linkports
The ports that connect to other switches. Currently, this column is only used by vlan configuration. The format is: “port_number:switch,port_number:switch…” Refer to the switch table for details on how to specify the port numbers.

sshusername
The remote login user name. It can be for ssh or telnet. If it is for telnet, set protocol to “telnet”. If the sshusername is blank, the username, password and protocol will be retrieved from the passwd table with “switch” as the key.

sshpassword
The remote login password. It can be for ssh or telnet. If it is for telnet, set protocol to “telnet”. If the sshusername is blank, the username, password and protocol will be retrieved from the passwd table with “switch” as the key.

protocol
Protocol for running remote commands for the switch. The valid values are: ssh, telnet. ssh is the default. If the sshusername is blank, the username, password and protocol will be retrieved from the passwd table with “switch” as the key. The passwd.comments attribute is used for protocol.

switchtype
The type of switch. It is used to identify the file name that implements the functions for this switch. The valid values are: Mellanox, Cisco, BNT and Juniper.

**SEE ALSO**

nodels(1), chtab(8), tabdump(8), tabedit(8)

taskstate.5

**NAME**

taskstate - a table in the xCAT database.

**SYNOPSIS**

taskstate Attributes: node, command, state, pid, reserve, disable

**DESCRIPTION**

The task state for the node.

**taskstate Attributes:**

**node**

The node name.

**command**

Current command is running

**state**

The task state(callback, running) for the node.

**pid**

The process id of the request process.

**reserve**

used to lock the node

**disable**

Set to ‘yes’ or ‘1’ to comment out this row.

**SEE ALSO**

nodels(1), chtab(8), tabdump(8), tabedit(8)
**token.5**

**NAME**

token - a table in the xCAT database.

**SYNOPSIS**

token Attributes: tokenid, username, expire, created, access, comments, disable

**DESCRIPTION**

The token of users for authentication.

token Attributes:

tokenid

It is a UUID as an unified identify for the user.

username

The user name.

expire

The expire time for this token.

created

Creation time for this token.

access

Last access time for this token.

comments

Any user-provided notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.

**SEE ALSO**

nodels(1), chtab(8), tabdump(8), tabedit(8)

**virtsd.5**

**NAME**

virtsd - a table in the xCAT database.
SYNOPSIS

virtsd Attributes: node, sdtype, stype, location, host, cluster, datacenter, comments, disable

DESCRIPTION

The parameters which used to create the Storage Domain

virtsd Attributes:

node
   The name of the storage domain
sdtype
   The type of storage domain. Valid values: data, iso, export
stype
   The type of storage. Valid values: nfs, fcp, iscsi, localfs
location
   The path of the storage
host
   For rhev, a hypervisor host needs to be specified to manage the storage domain as SPM (Storage Pool Manager). But the SPM role will be failed over to another host when this host down.
cluster
   A cluster of hosts
datacenter
   A collection for all host, vm that will shared the same storages, networks.
comments
disable

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

vm.5

NAME

vm - a table in the xCAT database.
SYNOPSIS

vm Attributes: node, mgr, host, migrationdest, storage, storagemodel, storagecache, storageformat, cfgstore, memory, cpus, nics, nicmodel, bootorder, clockoffset, virtflags, master, vncport, textconsole, powerstate, beacon, datacenter, cluster, guestostype, othersettings, physlots, vidmodel, vidproto, vidpassword, comments, disable

DESCRIPTION

Virtualization parameters

vm Attributes:
	node
	The node or static group name

tmgr
	The function manager for the virtual machine

thost
	The system that currently hosts the VM

tmigrationdest
	A noderange representing candidate destinations for migration (i.e. similar systems, same SAN, or other criteria that xCAT can use

storage
	A list of storage files or devices to be used. i.e. dir://cluster/vm/<nodename> or nfs://<server>/path/to/folder/

storagemodel
	Model of storage devices to provide to guest

storagecache
	Select caching scheme to employ. E.g. KVM understands ‘none’, ‘writethrough’ and ‘writeback’

storageformat
	Select disk format to use by default (e.g. raw versus qcow2)

cfgstore
	Optional location for persistent storage separate of emulated hard drives for virtualization solutions that require persistent store to place configuration data

memory
	Megabytes of memory the VM currently should be set to.

cpus
	Number of CPUs the node should see.
nics
Network configuration parameters. Of the general form [physnet:]interface,. Generally, interface describes the vlan entity (default for native, tagged for tagged, vl[number] for a specific vlan. physnet is a virtual switch name or port description that is used for some virtualization technologies to construct virtual switches. hypervisor.netmap can map names to hypervisor specific layouts, or the descriptions described there may be used directly here where possible.

nicmodel

Model of NICs that will be provided to VMs (i.e. e1000, rtl8139, virtio, etc)

bootorder

Boot sequence (i.e. net,hd)

clockoffset

Whether to have guest RTC synced to “localtime” or “utc” If not populated, xCAT will guess based on the nodetype.os contents.

virtflags

General flags used by the virtualization method.

For example, in Xen it could, among other things, specify paravirtualized setup, or direct kernel boot. For a hypervisor:

imageformat=[raw|fullraw|qcow2] raw is a generic sparse file that allocates storage on demand fullraw is a generic, non-sparse file that preallocates all space qcow2 is a sparse, copy-on-write capable format implemented at the virtualization layer rather than the filesystem level

clonemethod=[qemu-img|reflink] qemu-img allows use of qcow2 to generate virtualization layer copy-on-write reflink uses a generic filesystem facility to clone the files on your behalf, but requires filesystem support such as btrfs

placement_affinity=[migratable|user_migratable|pinned]

master

The name of a master image, if any, this virtual machine is linked to. This is generally set by clonevm and indicates the deletion of a master that would invalidate the storage of this virtual machine

vncport

Tracks the current VNC display port (currently not meant to be set

textconsole

Tracks the Psuedo-TTY that maps to the serial port or console of a VM

powerstate

This flag is used by xCAT to track the last known power state of the VM.

beacon

This flag is used by xCAT to track the state of the identify LED with respect to the VM.

datacenter

Optionally specify a datacenter for the VM to exist in (only applicable to VMWare)

cluster

Specify to the underlying virtualization infrastructure a cluster membership for the hypervisor.

guestostype
This allows administrator to specify an identifier for OS to pass through to virtualization stack. Normally this should be ignored as xCAT will translate from nodetype.os rather than requiring this field be used

### othersettings

This allows specifying a semicolon delimited list of key->value pairs to include in a vmx file of VMware or KVM. For partitioning on normal power machines, this option is used to specify the hugepage and/or bsr information, the value is like: `hugepage:1,bsr=2`. For KVM cpu pinning, this option is used to specify the physical cpu set on the host, the value is like: `vcpupin:'0-15,^8'`. Its syntax is a comma separated list and a special markup using `-` and `^` (ex. `0-4`, `0-3,^2`) can also be allowed, the `-` denotes the range and the `^` denotes exclusive. For KVM memory binding, the value is like: `membind:0`, restrict a guest to allocate memory from the specified set of NUMA nodes. For PCI passthrough, the value is like: `devpassthrough:pci_0001_01_00_0,pci_0000_03_00_0`, the value for PCI device format also can be like: `devpassthrough:0001:01:00.1`, the PCI devices are assigned to a virtual machine, and the virtual machine can use this I/O exclusively, the devices list are a list of PCI device names delimited with comma, the PCI device names can be obtained by running `virsh nodedev-list` on the host.

### physlots

Specify the physical slots drc index that will assigned to the partition, the delimiter is ``, and the drc index must started with `0x`. For more details, reference manpage for `lsvm`.

### vidmodel

Model of video adapter to provide to guest. For example, qxl in KVM

### vidproto

Request a specific protocol for remote video access be set up. For example, spice in KVM.

### vidpassword

Password to use instead of temporary random tokens for VNC and SPICE access

### comments

### disable

**SEE ALSO**

`nodels(1)`, `chtab(8)`, `tabdump(8)`, `tabedit(8)`

vmmaster.5

**NAME**

vmmaster - a table in the xCAT database.

**SYNOPSIS**

vmmaster Attributes: name, os, arch, profile, storage, storagemodel, nics, vintage, originator, virttype, specializeparameters, comments, disable

**DESCRIPTION**

Inventory of virtualization images for use with clonevm. Manual intervention in this table is not intended.
vm master Attributes:

name
   The name of a master

os
   The value of nodetype.os at the time the master was captured

arch
   The value of nodetype.arch at the time of capture

profile
   The value of nodetype.profile at time of capture

storage
   The storage location of bulk master information

storagemodel
   The default storage style to use when modifying a vm cloned from this master

nics
   The nic configuration and relationship to vlans/bonds/etc

vintage
   When this image was created

originator
   The user who created the image

virttype
   The type of virtualization this image pertains to (e.g. vmware, kvm, etc)

specializeparameters
   Implementation specific arguments, currently only “autoLogonCount=<number” for ESXi clonevme

comments

disable

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

vpd.5

NAME

vpd - a table in the xCAT database.
SYNOPSIS

**vpd Attributes:** node, serial, mtm, side, asset, uuid, comments, disable

DESCRIPTION

The Machine type, Model, and Serial numbers of each node.

**vpd Attributes:**

- **node**
  The node name or group name.

- **serial**
  The serial number of the node.

- **mtm**
  The machine type and model number of the node. E.g. 7984-6BU

- **side**
  <BPA>-<port> or <FSP>-<port>. The side information for the BPA/FSP. The side attribute refers to which BPA/FSP, A or B, which is determined by the slot value returned from lsslp command. It also lists the physical port within each BPA/FSP which is determined by the IP address order from the lsslp response. This information is used internally when communicating with the BPAs/FSPs

- **asset**
  A field for administrators to use to correlate inventory numbers they may have to accommodate

- **uuid**
  The UUID applicable to the node

- **comments**
  Any user-written notes.

- **disable**
  Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

websrv.5

NAME

websrv - a table in the xCAT database.
SYNOPSIS

websrv Attributes: node, port, username, password, comments, disable

DESCRIPTION

Web service parameters

websrv Attributes:

node
   The web service hostname.

port
   The port of the web service.

username
   Userid to use to access the web service.

password
   Password to use to access the web service.

comments
   Any user-written notes.

disable
   Set to 'yes' or '1' to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

winimage.5

NAME

winimage - a table in the xCAT database.

SYNOPSIS

winimage Attributes: imagename, template, installto, partitionfile, winpepath, comments, disable

DESCRIPTION

Information about a Windows operating system image that can be used to deploy cluster nodes.
winimage Attributes:

imagename

The name of this xCAT OS image definition.

template

The fully qualified name of the template file that is used to create the windows unattend.xml file for diskful installation.

installto

The disk and partition that the Windows will be deployed to. The valid format is <disk>:<partition>. If not set, default value is 0:1 for bios boot mode(legacy) and 0:3 for uefi boot mode; If setting to 1, it means 1:1 for bios boot and 1:3 for uefi boot

partitionfile

The path of partition configuration file. Since the partition configuration for bios boot mode and uefi boot mode are different, this configuration file can include both configurations if you need to support both bios and uefi mode. Either way, you must specify the boot mode in the configuration. Example of partition configuration file: [BIOS]xxxxxxx[UEFI]yyyyyy. To simplify the setting, you also can set installto in partitionfile with section like [INSTALLTO]:0:1

winpepath

The path of winpe which will be used to boot this image. If the real path is /tftpboot/winboot/winpe1/, the value for winpepath should be set to winboot/winpe1

comments

Any user-written notes.

disable

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

xcatdb.5

NAME

An overview of the xCAT database.

DESCRIPTION

The xCAT database contains user settings for the cluster and information gathered from the cluster. It consists of a series of tables, which are described below. To get more information about a particular table, run man for that table name. The tables can be manipulated directly using the tabedit or chtab commands. They can be viewed using nodels or tabdump.
Alternatively, the xCAT database can be viewed and edited as logical objects, instead of flat tables. In this mode, xCAT takes care of which table each attribute should go in. To treat the database as logical object definitions, use the commands: `lsdef`, `mkdef`, `chdef`, `rmdef`. See Object Definitions below.

xCAT allows the use of different database applications, depending on the needs of your cluster. The default database is SQLite, which is a daemonless, zero-config database. But you could instead choose to use something like postgresql for greater scalability and remote access in the hierarchical/service node case. To use a different database or a different location, create the file `/etc/xcat/cfgloc`. See the appropriate xCAT documentation for the format of the file for the database you choose. The following example `/etc/xcat/cfgloc` file is for PostgreSQL:

```
Pg:dbname=xcat;host=<mgmtnode>|<pgadminuserid>|<pgadminpasswd>
```

where mgmtnode is the hostname of the management node adapter on the cluster side, and the pgadminuserid and pgadminpasswd are the database admin and password.

### GROUPS AND REGULAR EXPRESSIONS IN TABLES

The xCAT database has a number of tables, some with rows that are keyed by node name (such as noderes and nodehm) and others that are not keyed by node name (for example, the policy table). The tables that are keyed by node name have some extra features that enable a more template-based style to be used:

Any group name can be used in lieu of a node name in the node field, and that row will then provide “default” attribute values for any node in that group. A row with a specific node name can then override one or more attribute values for that specific node. For example, if the nodehm table contains:

```
#node,power,mgt,cons,termserver,termport,conserver,serialport,serialspeed,serialflow,
    →getmac,cmdmapping,comments,disable
"mygroup",,"ipmi",,,,,,,"19200",,,,,
"node1",,,,,,,"115200",,,,,
```

In the above example, the node group called mygroup sets mgt=ipmi and serialspeed=19200. Any nodes that are in this group will have those attribute values, unless overridden. For example, if node2 is a member of mygroup, it will automatically inherit these attribute values (even though it is not explicitly listed in this table). In the case of node1 above, it inherits mgt=ipmi, but overrides the serialspeed to be 115200, instead of 19200. A useful, typical way to use this capability is to create a node group for your nodes and for all the attribute values that are the same for every node, set them at the group level. Then you only have to set attributes for each node that vary from node to node.

xCAT extends the group capability so that it can also be used for attribute values that vary from node to node in a very regular pattern. For example, if in the ipmi table you want the bmc attribute to be set to whatever the nodename is with “-bmc” appended to the end of it, then use this in the ipmi table:

```
#node,bmc,bmcport,taggedvlan,bmcid,username,password,comments,disable
"compute","/\(-bmc\)/",,,,,
```

In this example, “compute” is a node group that contains all of the compute nodes. The 2nd attribute (bmc) is a regular expression that is similar to a substitution pattern. The 1st part “z” matches the end of the node name and substitutes “-bmc”, effectively appending it to the node name.

Another example is if node1 is to have IP address 10.0.0.1, node2 is to have IP address 10.0.0.2, etc., then this could be represented in the hosts table with the single row:

```
#node,ip,hostnames,otherinterfaces,comments,disable
"compute","|node\((d+)\)\|10.0.0.\((\$1+0)\)|",,,,,
```

In this example, the regular expression in the ip attribute uses “|” to separate the 1st and 2nd part. This means that xCAT will allow arithmetic operations in the 2nd part. In the 1st part, “(d+)”, will match the number part of the node
name and put that in a variable called $1. The 2nd part is what value to give the ip attribute. In this case it will set it to the string “10.0.0.” and the number that is in $1. (Zero is added to $1 just to remove any leading zeroes.)

A more involved example is with the mp table. If your blades have node names node01, node02, etc., and your chassis node names are cmm01, cmm02, etc., then you might have an mp table like:

```
#node,mpa,id,nodetype,comments,disable
"blade","\D+(\d+)|cmm(sprintf('%02d',($1-1)/14+1))|","\D+(\d+)|(($1-1)%14+1)|",,"
```

Before you panic, let me explain each column:

**blade**

This is a group name. In this example, we are assuming that all of your blades belong to this group. Each time the xCAT software accesses the mp table to get the management module and slot number of a specific blade (e.g. **node20**), this row will match (because **node20** is in the **blade** group). Once this row is matched for **node20**, then the processing described in the following items will take place.

|D+(d+)|cmm(sprintf(‘%02d’,($1-1)/14+1))|

This is a perl substitution pattern that will produce the value for the second column of the table (the management module hostname). The text `D+(d+)` between the 1st two vertical bars is a regular expression that matches the node name that was searched for in this table (in this example **node20**). The text that matches within the 1st set of parentheses is set to $1. (If there was a 2nd set of parentheses, it would be set to $2, and so on.) In our case, the D+ matches the non-numeric part of the name (**node**) and the d+ matches the numeric part (**20**). So $1 is set to **20**. The text `cmm(sprintf(‘%02d’,($1-1)/14+1))` between the 2nd and 3rd vertical bars produces the string that should be used as the value for the mpa attribute for node20. Since $1 is set to 20, the expression `($1-1)/14+1` equals 19/14 + 1, which equals 2. (The division is integer division, so 19/14 equals 1. Fourteen is used as the divisor, because there are 14 blades in each chassis.) The value of 2 is then passed into sprintf() with a format string to add a leading zero, if necessary, to always make the number two digits. Lastly the string `cmm` is added to the beginning, making the resulting string `cmm02`, which will be used as the hostname of the management module.

|D+(d+)|(($1-1)%14+1)|

This item is similar to the one above. This substitution pattern will produce the value for the 3rd column (the chassis slot number for this blade). Because this row was the match for **node20**, the parentheses within the 1st set of vertical bars will set $1 to 20. Since % means modulo division, the expression `($1-1)%14+1` will evaluate to **6**.


**Easy Regular Expressions**

As of xCAT 2.8.1, you can use a modified version of the regular expression support described in the previous section. You do not need to enter the node information (1st part of the expression), it will be derived from the input nodename. You only need to supply the 2nd part of the expression to determine the value to give the attribute. For examples, see [http://xcat-docs.readthedocs.org/en/latest/guides/admin-guides/basic_concepts/xcat_db/reg exp_db.html#easy-regular-expressions](http://xcat-docs.readthedocs.org/en/latest/guides/admin-guides/basic_concepts/xcat_db/regexp_db.html#easy-regular-expressions)

**Regular Expression Helper Functions**

xCAT provides several functions that can simplify regular expressions.

**a2idx**

ASCII Character to Index
a2zidx
ASCII Character to 0-Index

dim2idx
Dimensions to Index

skip
Skip indices

ipadd
Add to an IP address

http://xcat-docs.readthedocs.org/en/latest/guides/admin-guides/basic_concepts/xcat_db/regexp_db.html#regular-expression-helper-functions

OBJECT DEFINITIONS

Because it can get confusing what attributes need to go in what tables, the xCAT database can also be viewed and edited as logical objects, instead of flat tables. Use mkdef, chdef, lsdef, and rmdef to create, change, list, and delete objects. When using these commands, the object attributes will be stored in the same tables, as if you edited the tables by hand. The only difference is that the object commands take care of knowing which tables all of the information should go in.

xCAT Object Name Format:

xCAT Object Name Format is defined by the following regex:

```
^([A-Za-z-]+)([0-9]+)(([A-Za-z-][A-Za-z0-9-]*)*)
```

In plain English, an object name is in xCAT Object Name Format if starting from the begining there are:

* one or more alpha characters of any case and any number of “-” in any combination

* followed by one or more numbers

* then optionally followed by one alpha character of any case or “-“

* followed by any combination of case mixed alphanumerics and “-“

Object Types

To run man for any of the object definitions below, use section 7. For example: man 7 node

The object types are:

auditlog(7) auditlog.7
boottarget(7) boottarget.7
eventlog(7)|eventlog.7
firmware(7)|firmware.7
group(7)|group.7
kit(7)|kit.7
kitcomponent(7)|kitcomponent.7
kitrepo(7)|kitrepo.7
monitoring(7)|monitoring.7
network(7)|network.7
node(7)|node.7
notification(7)|notification.7
osdistro(7)|osdistro.7
osdistroupdate(7)|osdistroupdate.7
osimage(7)|osimage.7
pdu(7)|pdu.7
policy(7)|policy.7
rack(7)|rack.7
route(7)|route.7
site(7)|site.7
taskstate(7)|taskstate.7
zone(7)|zone.7
zvmivp(7)|zvmivp.7

TABLES

To manipulate the tables directly, use nodels(1), chtab(8), tabdump(8), tabedit(8), nodeadd(8), nodech(1).

To run man for any of the table descriptions below, use section 5. For example: man 5 nodehm

The tables are:
auditlog(5)|auditlog.5
    Audit Data log.

boottarget(5)|boottarget.5
    Specify non-standard initrd, kernel, and parameters that should be used for a given profile.

bootparams(5)|bootparams.5
    Current boot settings to be sent to systems attempting network boot for deployment, stateless, or other reasons. Mostly automatically manipulated by xCAT.

bootstate(5)|bootstate.5
    Configuration management data for nodes used by non-xCAT osimage management services to install and configure software on a node.
chain(5)|chain.5
  Controls what operations are done (and it what order) when a node is discovered and deployed.

deps(5)|deps.5
  Describes dependencies some nodes have on others. This can be used, e.g., by rpower -d to power nodes
  on or off in the correct order.

discoverydata(5)|discoverydata.5
  Discovery data which sent from genesis.

domain(5)|domain.5
  Mapping of nodes to domain attributes

eventlog(5)|eventlog.5
  Stores the events occurred.

firmware(5)|firmware.5
  Maps node to firmware values to be used for setup at node discovery or later

hosts(5)|hosts.5
  IP addresses and hostnames of nodes. This info is optional and is only used to populate /etc/hosts and
  DNS via makehosts and makedns. Using regular expressions in this table can be a quick way to populate
  /etc/hosts.

hwinv(5)|hwinv.5
  The hareware inventory for the node.

hypervisor(5)|hypervisor.5
  Hypervisor parameters

ipmi(5)|ipmi.5
  Settings for nodes that are controlled by an on-board BMC via IPMI.

iscsi(5)|iscsi.5
  Contains settings that control how to boot a node from an iSCSI target

kit(5)|kit.5
  This table stores all kits added to the xCAT cluster.

kitcomponent(5)|kitcomponent.5
  This table stores all kit components added to the xCAT cluster.

kitrepo(5)|kitrepo.5
  This table stores all kits added to the xCAT cluster.

kvm_masterdata(5)|kvm_masterdata.5
  Persistent store for KVM plugin for masters

kvm_nodedata(5)|kvm_nodedata.5
  Persistent store for KVM plugin, not intended for manual modification.

linuximage(5)|linuximage.5
  Information about a Linux operating system image that can be used to deploy cluster nodes.
The litefile table specifies the directories and files on the statelite nodes that should be readwrite, persistent, or readonly overlay. All other files in the statelite nodes come from thereadonly statelite image.

Directory hierarchy to traverse to get the initial contents of node files. The files that are specified in the litefile table are searched for in the directories specified in this table.

The MAC address of the node’s install adapter. Normally this table is populated by getmacs or node discovery, but you can also add entries to it manually.

The host, slot id and configuration of the mic (Many Integrated Core).

Controls what external monitoring tools xCAT sets up and uses. Entries should be added and removed from this table using the provided xCAT commands monstart and monstop.

Specifies the monitoring plug-in specific settings. These settings will be used by the monitoring plug-in to customize the behavior such as event filter, sample interval, responses etc. Entries should be added, removed or modified by chtab command. Entries can also be added or modified by the monstart command when a monitoring plug-in is brought up.

Contains the hardware control info specific to blades. This table also refers to the mpa table, which contains info about each Management Module.

Contains info about each Management Module and how to access it.

Describes the networks in the cluster and info necessary to set up nodes on that network.

Stores NIC details.

All the info that specifies a particular AIX operating system image that can be used to deploy AIX nodes.

Contains group definitions, whose membership is dynamic depending on characteristics of the node.

Settings that control how each node’s hardware is managed. Typically, an additional table that is specific to the hardware type of the node contains additional info. E.g. the ipmi, mp, and ppc tables.

The list of all the nodes in the cluster, including each node’s current status and what groups it is in.
Contains info about the physical location of each node. Currently, this info is not used by xCAT, and therefore can be in whatever format you want. It will likely be used in xCAT in the future.

noderes(5)|noderes.5
Resources and settings to use when installing nodes.

nodetype(5)|nodetype.5
A few hardware and software characteristics of the nodes.

notification(5)|notification.5
Contains registrations to be notified when a table in the xCAT database changes. Users can add entries to have additional software notified of changes. Add and remove entries using the provided xCAT commands regnotif and unregnotif.

openbmc(5)|openbmc.5
Setting for nodes that are controlled by an on-board OpenBMC.

osdistro(5)|osdistro.5
Information about all the OS distros in the xCAT cluster

osdistroupdate(5)|osdistroupdate.5
Information about the OS distro updates in the xCAT cluster

osimage(5)|osimage.5
Basic information about an operating system image that can be used to deploy cluster nodes.

passwd(5)|passwd.5
Contains default userids and passwords for xCAT to access cluster components. In most cases, xCAT will also actually set the userid/password in the relevant component when it is being configured or installed. Userids/passwords for specific cluster components can be overridden in other tables, e.g. mpa, ipmi, ppchcp, etc.

pdu(5)|pdu.5
Parameters to use when interrogating pdus

pduitlet(5)|pduitlet.5
Contains list of outlet numbers on the pdu each node is connected to.

performance(5)|performance.5
Describes the system performance every interval unit of time.

policy(5)|policy.5
The policy table in the xCAT database controls who has authority to run specific xCAT operations. It is basically the Access Control List (ACL) for xCAT. It is sorted on the priority field before evaluating.

postscripts(5)|postscripts.5
The scripts that should be run on each node after installation or diskless boot.

ppc(5)|ppc.5
List of system p hardware: HMCs, IVMs, FSPs, BPCs, CECs, Frames.

ppcdirect(5)|ppcdirect.5
Info necessary to use FSPs/BPAs to control system p CECs/Frames.
ppchcp(5)|ppchcp.5
Info necessary to use HMCs and IVMs as hardware control points for LPARs.

prescripts(5)|prescripts.5
The scripts that will be run at the beginning and the end of the nodeset(Linux), nimnodeset(AIX) or mkdsklsnode(AIX) command.

prodkey(5)|prodkey.5
Specify product keys for products that require them

rack(5)|rack.5
Rack information.

routes(5)|routes.5
Describes the additional routes needed to be setup in the os routing table. These routes usually are used to connect the management node to the compute node using the service node as gateway.

servicenode(5)|servicenode.5
List of all Service Nodes and services that will be set up on the Service Node.

site(5)|site.5
Global settings for the whole cluster. This table is different from the other tables in that each attribute is just named in the key column, rather than having a separate column for each attribute. The following is a list of attributes currently used by xCAT organized into categories.

statelite(5)|statelite.5
The location on an NFS server where a nodes persistent files are stored. Any file marked persistent in the litefile table will be stored in the location specified in this table for that node.

storage(5)|storage.5

switch(5)|switch.5
Contains what switch port numbers each node is connected to.

switches(5)|switches.5
Parameters to use when interrogating switches

taskstate(5)|taskstate.5
The task state for the node.

token(5)|token.5
The token of users for authentication.

virtsd(5)|virtsd.5
The parameters which used to create the Storage Domain

vm(5)|vm.5
Virtualization parameters

vmmaster(5)|vmmaster.5
Inventory of virtualization images for use with clonevm. Manual intervention in this table is not intended.

vpd(5)|vpd.5
The Machine type, Model, and Serial numbers of each node.
websrv(5) | websrv.5
Web service parameters

winimage(5) | winimage.5
Information about a Windows operating system image that can be used to deploy cluster nodes.

zone(5) | zone.5
Defines a cluster zone for nodes that share root ssh key access to each other.

zvm(5) | zvm.5
List of z/VM virtual servers.

zvmivp(5) | zvmivp.5
List of z/VM Installation Verification Procedures (IVPs) to be periodically run.

SEE ALSO

node(1), chtab(8), tabdump(8), tabedit(8), lsdef(1), mkdef(1), chdef(1), rmdef(1)

xcatstanzafile.5

NAME

xcatstanzafile - Format of a stanza file that can be used with xCAT data object definition commands.

DESCRIPTION

A stanza file contains information that can be used to create xCAT data object definitions. A stanza file can be used as input to several xCAT commands. The stanza file contains one or more individual stanzas that provide information for individual object definitions. The following rules must be followed when creating a stanza file:

* An object stanza header consists of the object name followed by a colon, ("\:").
* Attribute lines must take the form of Attribute=Value.
* Attribute name might include the character dot ("\."), like passwd.HMC and nicips.eth0.
* Only one stanza can exist for each object name.
* All stanzas except for default stanzas must have a value set for “objtype”.
* Comments beginning with the “#” pound sign may be added to the file. A comment must be on a separate line.
When parsing the file, tab characters and spaces are ignored.

* Each line of the file can have no more than one header or attribute definition.

* If the header name is “default-<object type>:” the attribute values in the stanza are considered default values for subsequent definitions in the file that are the same object type.

* Default stanzas can be specified multiple times and at any point in a stanza file. The values apply to all definitions following the default stanzas in a file. The default values are cumulative; a default attribute value will remain set until it is explicitly unset or changed.

* To turn off a default value, use another default stanza to set the attribute to have no value using a blank space.

* When a specific value for an attribute is provided in the stanza, it takes priority over any default value that had been set.

The format of a stanza file should look similar to the following.

```
default-<object type>:
   attr=val
   attr=val
   . . .

<object name>:
   objtype=<object type>
   attr=val
   attr=val
   . . .

<object name>:
   objtype=<object type>
   attr=val
   attr=val
   . . .
```

**EXAMPLES**

1. Sample stanza file:

```
mysite:
   objtype=site
   rsh=/bin/rsh
   rcp=/bin/rcp
   installdir=/xcatinstall
   domain=ppd.pok.ibm.com

MSnet01:
   objtype=network
   gateway=1.2.3.4
```

(continues on next page)
```
netmask=255.255.255.0
nameserver=5.6.7.8

default-node:
    next_osimage=aix61
    network=MSnet01
    groups=all,compute

node01:
    objtype=node
    MAC=A2E26002C003
    xcatmaster=MS02.ppd.pok.com
    nfsserver=IS227.ppd.pok.com

node02:
    objtype=node
    MAC=A2E26002B004
    xcatmaster=MS01.ppd.pok.com
    nfsserver=IS127.ppd.pok.com

grp01:
    objtype=group
    members=node1,node2,node3
```

NOTES

This file is part of xCAT software product.

SEE ALSO

mkdef(1)|mkdef.1, lsdef(1)|lsdef.1, rmdef(1)|rmdef.1, chdef(1)|chdef.1

zone.5

NAME

zone - a table in the xCAT database.

SYNOPSIS

zone Attributes: zonename, sshkeydir, sshbetweennodes, defaultzone, comments, disable

DESCRIPTION

Defines a cluster zone for nodes that share root ssh key access to each other.
zone Attributes:

zonename
    The name of the zone.

sshkeydir
    Directory containing the shared root ssh RSA keys.

sshbetweennodes
    Indicates whether passwordless ssh will be setup between the nodes of this zone. Values are yes/1 or no/0. Default is yes.

defaultzone
    If nodes are not assigned to any other zone, they will default to this zone. If value is set to yes or 1.

comments
    Any user-provided notes.

disable
    Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

nodels(1), chtab(8), tabdump(8), tabedit(8)

zvm.5

NAME

zvm - a table in the xCAT database.

SYNOPSIS

zvm Attributes: node, hcp, userid, nodetype, parent, comments, disable, discovered, status

DESCRIPTION

List of z/VM virtual servers.

zvm Attributes:

node
    The node name.

hcp
    The hardware control point for this node.

userid
The z/VM user ID of this node.

**nodetype**

The node type. Valid values: cec (Central Electronic Complex), lpar (logical partition), zvm (z/VM host operating system), and vm (virtual machine).

**parent**

The parent node. For LPAR, this specifies the CEC. For z/VM, this specifies the LPAR. For VM, this specifies the z/VM host operating system.

**comments**

Any user provided notes.

**disable**

Set to ‘yes’ or ‘1’ to comment out this row.

**discovered**

Set to ‘1’ to indicate this node was discovered.

**status**

The processing status. Key value pairs (key=value) indicating status of the node. Multiple pairs are separated by semi-colons. Keys include: CLONING, CLONE_ONLY.

**SEE ALSO**

nodels(1), chtab(8), tabdump(8), tabedit(8)

zvmivp.5

**NAME**

zvmivp - a table in the xCAT database.

**SYNOPSIS**

zvmivp Attributes: id, ip, schedule, last_run, type_of_run, access_user, orch_parms, prep_parms, main_ivp_parms, comments, disable

**DESCRIPTION**

List of z/VM Installation Verification Procedures (IVPs) to be periodically run.

**zvmivp Attributes:**

**id**

Unique identifier associated with the IVP run, e.g. 1.

**ip**
IP address of the target system, either the IP of the OpenStack compute node or the xCAT management node.

**schedule**

The hours (0-24) that the IVP should be run. Multiple hours are separated by a blank.

**last_run**

The last time the IVP was run specified as a set of 3 blank delimited words: year, Julian date, and hour (in 24 hour format).

**type_of_run**

The type of run requested, ‘fullivp’ or ‘basicivp’.

**access_user**

User on the OpenStack node that is used to: push the IVP preparation script to the OpenStack system, drive the preparation script to validate the OpenStack configuration files, and return the created driver script to the xCAT MN system for the next part of the IVP. This user should be able to access the OpenStack configuration files that are scanned by the IVP.

**orch_parms**

Parameters to pass to the IVP orchestrator script, verifynode.

**prep_parms**

Parameters to pass to the phase 1 IVP preparation script.

**main_ivp_parms**

Parameters to pass to the main IVP script.

**comments**

Any user provided notes or description of the run.

**disable**

Set to ‘yes’ or ‘1’ to disable this IVP run.

**SEE ALSO**

nodels(1), chtab(8), tabdump(8), tabedit(8)

**NAME**

auditlog - a logical object definition in the xCAT database.

**SYNOPSIS**

**auditlog Attributes:** args, audittime, clientname, clienttype, command, comments, disable, noderange, recid, status, userid
DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: `mkdef`, `chdef`, `lsdef`, and `rmdef`. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

**auditlog Attributes:**

- **args** (auditlog.args)
  - The command argument list.
- **audittime** (auditlog.audittime)
  - The timestamp for the audit entry.
- **clientname** (auditlog.clientname)
  - The client machine, where the command originated.
- **clienttype** (auditlog.clienttype)
  - Type of command: cli, java, webui, other.
- **command** (auditlog.command)
  - Command executed. See auditskipcmds site table attribute to control which commands get logged.
- **comments** (auditlog.comments)
  - Any user-provided notes.
- **disable** (auditlog.disable)
  - Do not use. tabprune will not work if set to yes or 1
- **noderange** (auditlog.noderange)
  - The noderange on which the command was run.
- **recid** (auditlog.recid)
  - The record id.
- **status** (auditlog.status)
  - Allowed or Denied.
- **userid** (auditlog.userid)
  - The user running the command.

SEE ALSO

- `mkdef(1)`, `chdef(1)`, `lsdef(1)`, `rmdef(1)`
boottarget.7

NAME

boottarget - a logical object definition in the xCAT database.

SYNOPSIS

boottarget Attributes: bprofile, comments, initrd, kcmdline, kernel

DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: mkdef, chdef, lsdef, and rmdef. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

boottarget Attributes:

bprofile (boottarget.bprofile)
  All nodes with a nodetype.profile value equal to this value and nodetype.os set to "boottarget", will use the associated kernel, initrd, and kcmdline.

comments (boottarget.comments)
  Any user-written notes.

initrd (boottarget.initrd)
  The initial ramdisk image that network boot actions should use (could be a DOS floppy or hard drive image if using memdisk as kernel)

kcmdline (boottarget.kcmdline)
  Arguments to be passed to the kernel

kernel (boottarget.kernel)
  The kernel that network boot actions should currently acquire and use. Note this could be a chained boot loader such as memdisk or a non-linux boot loader

SEE ALSO

mkdef(1), chdef(1), lsdef(1), rmdef(1)

eventlog.7

NAME

eventlog - a logical object definition in the xCAT database.
SYNOPSIS

eventlog Attributes: application, comments, component, disable, eventtime, eventtype, id, message, monitor, monnode, node, rawdata, recid, severity

DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: mkdef, chdef, lsdef, and rmdef. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

eventlog Attributes:

application (eventlog.application)
    The application that reports the event.
comments (eventlog.comments)
    Any user-provided notes.
component (eventlog.component)
    The component where the event occurred.
disable (eventlog.disable)
    Do not use. tabprune will not work if set to yes or 1
eventtime (eventlog.eventtime)
    The timestamp for the event.
eventtype (eventlog.eventtype)
    The type of the event.
id (eventlog.id)
    The location or the resource name where the event occurred.
message (eventlog.message)
    The full description of the event.
monitor (eventlog.monitor)
    The name of the monitor that monitors this event.
monnode (eventlog.monnode)
    The node that monitors this event.
node (eventlog.node)
    The node where the event occurred.
rawdata (eventlog.rawdata)
    The data that associated with the event.
recid (eventlog.recid)
The record id.

severity (eventlog.severity)

The severity of the event. Valid values are: informational, warning, critical.

SEE ALSO

mkdef(1), chdef(1), lsdef(1), rmdef(1)

**firmware.7**

**NAME**

definition - a logical object definition in the xCAT database.

**SYNOPSIS**

**firmware Attributes:** `cfgfile, comments, disable`

**DESCRIPTION**

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: `mkdef`, `chdef`, `lsdef`, and `rmdef`. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

**firmware Attributes:**

cfgfile (firmware.cfgfile)

The file to use.

comments (firmware.comments)

Any user-written notes.

disable (firmware.disable)

Set to ‘yes’ or ‘1’ to comment out this row.

SEE ALSO

mkdef(1), chdef(1), lsdef(1), rmdef(1)

**group.7**

**NAME**

group - a logical object definition in the xCAT database.
SYNOPSIS

**group Attributes:** addkcmdline, arch, authdomain, authkey, authtype, bmc, bmcpassword, bmcport, bmcusername, bmcvlantag, cfgmgr, cfgmgtroles, cfgserver, chain, chassis, cmdmapping, community, cons, conserver, consoleenabled, consoleondemand, consport, cpucount, cputype, currcmrn, currsrte, dhcpinterfaces, disksize, displayname, dockercpus, dockerflag, dockerhost, dockermemory, dockernics, domainadminpassword, domainadminusername, domaintree, getmac, groupname, grouptype, hcp, height, hostcluster, hostinterface, hostmanager, hostnames, hosttype, hwtype, id, initrd, installnic, interface, ip, iscsipassword, iscsiserver, iscsitarget, iscsiuserrid, kcmdline, kernel, linkports, mac, membersgroups, members, memory, mgt, micbridge, michost, micid, miconboot, micpowermgmt, micvlog, migrationondest, monserver, mpa, mtm, nameservers, nethost, nfsdir, nfsserver, nicaliases, niccustomscripts, nicdevices, nicextraparams, nichostnameprefixes, nichostnamesuffixes, nicips, nicnetworks, nicsadapter, nictypes, nimservers, nodetype, ondiscovery, os, osvolume, otherinterfaces, ou, outlet, parent, passwd.HMC, passwd.admin, passwd.celogin, passwd.general, passwd.hscroot, password, pdu, pductype, postbootscripts, postscripts, power, pprofile, prescripts-begin, prescripts-end, primarynic, privkey, privtype, productkey, profile, protocol, provmethod, rack, room, routenames, secelvel, serial, serialflow, serialport, serialspeed, servicenode, setupconserver, setupdhcp, setupftp, setupip-forward, setupldap, setupnameserver, setupnfs, setupnim, setupnt, setupproxydhcp, setupproxysplitftps, splitftps, sftp, side, slot, slotid, slots, snmpauth, snmppassword, snmpprivacy, snmpuser, snmpusername, snmpversion, storagcontroller, storagetype, supernode, supportedarchs, supportedproxysplitftps, switch, switchinterface, switchport, switchtype, switchvlan, syslog, termport, termserver, tftpdir, tftpserver, unit, urlpath, usercomment, userid, username, vmbeacon, vmbootorder, vmcfgstore, vncluster, vnmcus, vnmhost, vmmanager, vmmaster, vmmemory, vmnicnicmodel, vnics, vmothersetting, vmphyists, vmstorage, vmstoragecache, vmstorageformat, vmstoragemodel, vminetconsole, vmvifflags, vmvneport, webport, wherevals, xcatmaster

DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: **mkdef, chdef, lsdef**, and **rmdef**. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

**group Attributes:**

**addkcmdline** (bootparams.addkcmdline)

User specified kernel options for os provision process(no prefix) or the provisioned os(with prefix “R::”).

The options should be delimited with spaces (“” “”)

**arch** (nodetype.arch)

The hardware architecture of this node. Valid values: x86_64, ppc64, x86, ia64.

**authdomain** (domain.authdomain)

If a node should participate in an AD domain or Kerberos realm distinct from domain indicated in site, this field can be used to specify that

**authkey** (pdu.authkey)

The authentication passphrase for SNMPv3

**authtype** (pdu.authtype)

The authentication protocol(MD5|SHA) to use for SNMPv3.

**bmc** (ipmi.bmc, openbmc.bmc)
The hostname of the BMC adapter.

or

The hostname of the BMC adapter.

bmcpassword (ipmi.password, openbmc.password)

The BMC password. If not specified, the key=ipmi row in the passwd table is used as the default.

or

The BMC password.

bmcport (ipmi.bmcport)

In systems with selectable shared/dedicated ethernet ports, this parameter can be used to specify the preferred port. 0 means use the shared port, 1 means dedicated, blank is to not assign.

The following special cases exist for IBM System x servers:

For x3755 M3 systems, 0 means use the dedicated port, 1 means shared, blank is to not assign.

For certain systems which have a mezzanine or ML2 adapter, there is a second value to include:

For x3750 M4 (Model 8722):

0 2 1st 1Gbps interface for LOM
0 0 1st 10Gbps interface for LOM
0 3 2nd 1Gbps interface for LOM
0 1 2nd 10Gbps interface for LOM

For x3750 M4 (Model 8752), x3850/3950 X6, dx360 M4, x3550 M4, and x3650 M4:

0 Shared (1st onboard interface)
1 Dedicated
2 0 First interface on ML2 or mezzanine adapter
2 1 Second interface on ML2 or mezzanine adapter
2 2 Third interface on ML2 or mezzanine adapter
2 3 Fourth interface on ML2 or mezzanine adapter

bmcusername (ipmi.username, openbmc.username)

The BMC userid. If not specified, the key=ipmi row in the passwd table is used as the default.

or

The BMC userid.
**bmcvlnntag** (ipmi.taggedvlan, openbmc.taggedvlan)

bmcsetup script will configure the network interface of the BMC to be tagged to the VLAN specified.

or

bmcsetup script will configure the network interface of the BMC to be tagged to the VLAN specified.

**cfgmgr** (cfgmgt.cfgmgr)

The name of the configuration manager service. Currently ‘chef’ and ‘puppet’ are supported services.

**cfgmgtroles** (cfgmgt.roles)

The roles associated with this node as recognized by the cfgmgr for the software that is to be installed and configured. These role names map to chef recipes or puppet manifest classes that should be used for this node. For example, chef OpenStack cookbooks have roles such as mysql-master, keystone, glance, nova-controller, nova-conductor, cinder-all.

**cfgserver** (cfgmgt.cfgserver)

The xCAT node name of the chef server or puppet master

**chain** (chain.chain)

A comma-delimited chain of actions to be performed automatically when this node is discovered for the first time. (xCAT and the DHCP server do not recognize the MAC address of the node when xCAT initializes the discovery process.) The last step in this process is to run the operations listed in the chain attribute, one by one. Valid values: boot, runcmd=<cmd>, runimage=<URL>, shell, standby. For example, to have the genesis kernel pause to the shell, use chain=shell.

**chassis** (nodepos.chassis)

The BladeCenter chassis the blade is in.

**cmdmapping** (nodehm.cmdmapping)

The fully qualified name of the file that stores the mapping between PCM hardware management commands and xCAT/third-party hardware management commands for a particular type of hardware device. Only used by PCM.

**community** (pdu.community)

The community string to use for SNMPv1/v2

**cons** (nodehm.cons)

The console method. If nodehm.serialport is set, this will default to the nodehm.mgt setting, otherwise it defaults to unused. Valid values: cyclades, mrv, or the values valid for the mgt attribute.

**conserver** (nodehm.conserver)

The hostname of the machine where the conserver daemon is running. If not set, the default is the xCAT management node.

**consoleenabled** (nodehm.consoleenabled)

A flag field to indicate whether the node is registered in the console server. If ‘1’, console is enabled, if not set, console is not enabled.

**consoleondemand** (nodehm.consoleondemand)

This overrides the value from site.consoleondemand. Set to ‘yes’, ‘no’, ‘1’ (equivalent to ‘yes’), or ‘0’ (equivalent to ‘no’). If not set, the default is the value from site.consoleondemand.

**consport** (openbmc.consport)
The console port for OpenBMC.

**cpucount (hwinv.cpucount)**

The number of cpus for the node.

**cputype (hwinv.cputype)**

The cpu model name for the node.

**currchain (chain.currchain)**

The chain steps still left to do for this node. This attribute will be automatically adjusted by xCAT while xCAT-genesis is running on the node (either during node discovery or a special operation like firmware update). During node discovery, this attribute is initialized from the chain attribute and updated as the chain steps are executed.

**currstate (chain.currstate)**

The current or next chain step to be executed on this node by xCAT-genesis. Set by xCAT during node discovery or as a result of nodeset.

**dhcpinterfaces (servicenode.dhcpinterfaces)**

The network interfaces DHCP server should listen on for the target node. This attribute can be used for management node and service nodes. If defined, it will override the values defined in site.dhcpinterfaces. This is a comma separated list of device names. !remote! indicates a non-local network for relay DHCP. For example: !remote!,eth0,eth1

**disksize (hwinv.disksize)**

The size of the disks for the node in GB.

**displayname (mpa.displayname)**

Alternative name for BladeCenter chassis. Only used by PCM.

**dockercpus (vm.cpus)**

Number of CPUs the node should see.

**dockerflag (vm.othersettings)**

This allows specifying a semicolon delimited list of key->value pairs to include in a vmx file of VMware or KVM. For partitioning on normal power machines, this option is used to specify the hugepage and/or bsr information, the value is like:`hugepage:1,bsr=2`. For KVM cpu pinning, this option is used to specify the physical cpu set on the host, the value is like:`"vcpupin:'0-15,^8'"`. Its syntax is a comma separated list and a special markup using `^` and `^` (ex. ‘0-4’, ‘0-3.^2’) can also be allowed, the `^` denotes the range and the `^` denotes exclusive. For KVM memory binding, the value is like:`membind:0`, restrict a guest to allocate memory from the specified set of NUMA nodes. For PCI passthrough, the value is like:`devpasssthrough:pci_0001_01_00_0,pci_0000_03_00_0`, the value for PCI device format also can be like:`devpasssthrough:0001:01:00.1`, the PCI devices are assigned to a virtual machine, and the virtual machine can use this I/O exclusively, the devices list are a list of PCI device names delimited with comma, the PCI device names can be obtained by running `virsh nodedev-list` on the host.

**dockerhost (vm.host)**

The system that currently hosts the VM

**dockermemory (vm.memory)**

Megabytes of memory the VM currently should be set to.

**dockernics (vm.nics)**
Network configuration parameters. Of the general form [physnet:]interface,.. Generally, interface describes the vlan entity (default for native, tagged for tagged, vl[number] for a specific vlan. physnet is a virtual switch name or port description that is used for some virtualization technologies to construct virtual switches. hypervisor.netmap can map names to hypervisor specific layouts, or the descriptions described there may be used directly here where possible.

domainadminpassword (domain.adminpassword)

Allow a node specific indication of Administrative user password for the domain. Most will want to ignore this in favor of passwd table.

domainadminuser (domain.adminuser)

Allow a node specific indication of Administrative user. Most will want to just use passwd table to indicate this once rather than by node.

domaintype (domain.type)

Type, if any, of authentication domain to manipulate. The only recognized value at the moment is activedirectory.

getmac (nodehm.getmac)

The method to use to get MAC address of the node with the getmac command. If not set, the mgt attribute will be used. Valid values: same as values for mgmt attribute.

grouptype (nodegroup.grouptype)

Static or Dynamic. A static group is defined to contain a specific set of cluster nodes. A dynamic node group is one that has its members determined by specifying a selection criteria for node attributes.

hcp (ppc.hcp, zvm.hcp)

The hardware control point for this node (HMC, IVM, Frame or CEC). Do not need to set for BPAs and FSPs.

or

The hardware control point for this node.

height (nodepos.height)

The server height in U(s).

hostcluster (hypervisor.cluster)

Specify to the underlying virtualization infrastructure a cluster membership for the hypervisor.

hostinterface (hypervisor.interface)

The definition of interfaces for the hypervisor. The format is [network-name:interfacename:bootprotocol:IP:netmask:gateway] that split with | for each interface

hostmanager (hypervisor.mgr)

The virtualization specific manager of this hypervisor when applicable

hostnames (hosts.hostnames)

Hostname aliases added to /etc/hosts for this node. Comma or blank separated list.

hosttype (hypervisor.type)

The plugin associated with hypervisor specific commands such as revacuate
**hwtype** (ppc.nodetype, zvm.nodetype, mp.nodetype, mic.nodetype)

The hardware type of the node. Only can be one of fsp, bpa, cec, frame, ivm, hmc and lpar

or

The node type. Valid values: cec (Central Electronic Complex), lpar (logical partition), zvm (z/VM host operating system), and vm (virtual machine).

or

The hardware type for mp node. Valid values: mm, cmm, blade.

or

The hardware type of the mic node. Generally, it is mic.

**id** (ppc.id, mp.id)

For LPARs: the LPAR numeric id; for CECs: the cage number; for Frames: the frame number.

or

The slot number of this blade in the BladeCenter chassis.

**initrd** (bootparams.initrd)

The initial ramdisk image that network boot actions should use (could be a DOS floppy or hard drive image if using memdisk as kernel)

**installnic** (noderes.installnic)

The network adapter on the node that will be used for OS deployment, the installnic can be set to the network adapter name or the mac address or the keyword “mac” which means that the network interface specified by the mac address in the mac table will be used. If not set, primarynic will be used. If primarynic is not set too, the keyword “mac” will be used as default.

**interface** (mac.interface)

The adapter interface name that will be used to install and manage the node. E.g. eth0 (for linux) or en0 (for AIX).)

**ip** (hosts.ip)

The IP address of the node. This is only used in makehosts. The rest of xCAT uses system name resolution to resolve node names to IP addresses.

**iscsipassword** (iscsi.passwd)

The password for the iscsi server containing the boot device for this node.

**isciserver** (iscsi.server)

The server containing the iscsi boot device for this node.

**iscsitarget** (iscsi.target)

The iscsi disk used for the boot device for this node. Filled in by xCAT.

**iscsiuserid** (iscsi.userid)

The userid of the iscsi server containing the boot device for this node.

**kcmdline** (bootparams.kcmdline)

Arguments to be passed to the kernel

**kernel** (bootparams.kernel)
The kernel that network boot actions should currently acquire and use. Note this could be a chained boot loader such as memdisk or a non-linux boot loader.

**linkports** (switches.linkports)

The ports that connect to other switches. Currently, this column is only used by vlan configuration. The format is: "port_number:switch,port_number:switch...". Refer to the switch table for details on how to specify the port numbers.

**mac** (mac.mac)

The mac address or addresses for which xCAT will manage static bindings for this node. This may be simply a mac address, which would be bound to the node name (such as "01:02:03:04:05:0E"). This may also be a "|" delimited string of "mac address!hostname" format (such as "01:02:03:04:05:0E!node501:02:03:04:05:0F!node6-eth1"). If there are multiple nics connected to Management Network (usually for bond), in order to make sure the OS deployment finished successfully, the macs of those nics must be able to resolve to same IP address. First, users have to create alias of the node for each mac in the Management Network through either: 1. adding the alias into /etc/hosts for the node directly or: 2. setting the alias to the “hostnames” attribute and then run “makehost” against the node. Then, configure the “mac” attribute of the node like “mac1!node1mac2!node-alias”. For the first mac address (mac1 in the example) set in “mac” attribute, do not need to set a “node name” string for it since the nodename of the node will be used for it by default.

**membergroups** (nodegroup.membergroups)

This attribute stores a comma-separated list of nodegroups that this nodegroup refers to. This attribute is only used by PCM.

**members** (nodegroup.members)

The value of the attribute is not used, but the attribute is necessary as a place holder for the object def commands. (The membership for static groups is stored in the nodelist table.)

**memory** (hwinv.memory)

The size of the memory for the node in MB.

**mgt** (nodehm.mgt)

The method to use to do general hardware management of the node. This attribute is used as the default if power or getmac is not set. Valid values: openbmc, ipmi, blade, hmc, ivm, fsp, bpa, kvm, esx, rhevm. See the power attribute for more details.

**micbridge** (mic.bridge)

The virtual bridge on the host node which the mic connected to.

**michost** (mic.host)

The host node which the mic card installed on.

**micid** (mic.id)

The device id of the mic node.

**miconboot** (mic.onboot)

Set mic to autoboot when mpss start. Valid values: yes|no. Default is yes.

**micpowermgmt** (mic.powermgmt)

Set the Power Management for mic node. This attribute is used to set the power management state that mic may get into when it is idle. Four states can be set: cpufreq, corec6, pc3 and pc6. The valid value for powermgmt attribute should be [cpufreq=[on|off]]|corec6=[on|off]]|pc3=[on|off]]|pc6=[on|off]].
e.g. cpufreq=on!corec6=off!pc3=on!pc6=off. Refer to the doc of mic to get more information for power management.

**micvlog (mic.vlog)**

Set the Verbose Log to console. Valid values: yes|no. Default is no.

**migrationdest (vm.migrationdest)**

A noderange representing candidate destinations for migration (i.e. similar systems, same SAN, or other criteria that xCAT can use

**monserver (noderes.monserver)**

The monitoring aggregation point for this node. The format is “x,y” where x is the ip address as known by the management node and y is the ip address as known by the node.

**mpa (mp.mpa)**

The management module used to control this blade.

**mtm (vpd.mtm)**

The machine type and model number of the node. E.g. 7984-6BU

**nameservers (noderes.nameservers)**

An optional node/group specific override for name server list. Most people want to stick to site or network defined nameserver configuration.

**netboot (noderes.netboot)**

The type of network booting to use for this node. Valid values:

```
<table>
<thead>
<tr>
<th>Arch</th>
<th>OS</th>
<th>valid netboot options</th>
</tr>
</thead>
<tbody>
<tr>
<td>x86, x86_64</td>
<td>ALL</td>
<td>pxe, xnba</td>
</tr>
<tr>
<td>ppc64</td>
<td>&lt;=rhe16, &lt;=sles11.3</td>
<td>yaboot</td>
</tr>
<tr>
<td>ppc64</td>
<td>&gt;=rhe1s7, &gt;=sles11.4</td>
<td>grub2,grub2-http,grub2-tftp</td>
</tr>
<tr>
<td>ppc64le</td>
<td>NonVirtualize</td>
<td>ALL</td>
</tr>
<tr>
<td>ppc64le PowerKVM Guest</td>
<td>ALL</td>
<td>petitboot</td>
</tr>
<tr>
<td></td>
<td>&lt;=tftp</td>
<td>grub2,grub2-http,grub2-tftp</td>
</tr>
</tbody>
</table>
```

**nfsdir (noderes.nfsdir)**

The path that should be mounted from the NFS server.

**nfsserver (noderes.nfsserver)**

The NFS or HTTP server for this node (as known by this node).

**nicaliases (nics.nicaliases)**

**Comma-separated list of hostname aliases for each NIC.**

*Format: eth0!<alias list>,eth1!<alias1 list>|<alias2 list>* For multiple aliases per nic use a space-separated list.

For example: eth0!moe larry curly,eth1!tom|jerry

**niccustomscripts (nics.niccustomscripts)**

Comma-separated list of custom scripts per NIC. <nic1>!<script1>,<nic2>!<script2>, e.g. eth0!configeth eth0, ib0!configib ib0. The xCAT object definition commands support to use niccustomscripts.<nicname> as the sub attribute.

**nicdevices (nics.nicdevices)**

1.3. Admin Guide  671
Comma-separated list of NIC device per NIC, multiple ethernet devices can be bonded as bond device, these ethernet devices are separated by \(|\). \(<\text{nic1}>!<\text{dev1}>!<\text{dev3}>, <\text{nic2}>!<\text{dev2}>, \text{e.g. bond0!eth0eth2,br0!bond0}\). The xCAT object definition commands support to use nicdevices.<nicname> as the sub attributes.

nicextraparams (nics.nicextraparams)

Comma-separated list of extra parameters that will be used for each NIC configuration.

- **If only one ip address is associated with each NIC:** \(<\text{nic1}>!<\text{param1}=\text{value1}\>
  
  \(<\text{param2}=\text{value2}>, <\text{nic2}>!<\text{param3}=\text{value3}>, \ldots\), for example, eth0!MTU=1500, ib0!MTU=65520 CONNECTED_MODE=yes.

- **If multiple ip addresses are associated with each NIC:** \(<\text{nic1}>!<\text{param1}=\text{value1}\>
  
  \(<\text{param2}=\text{value2}>, <\text{param3}=\text{value3}>, <\text{nic2}>!<\text{param4}=\text{value4}\>
  
  \(<\text{param5}=\text{value5}>, <\text{param6}=\text{value6}>, \ldots\), for example, eth0!MTU=1500/MTU=1460, ib0!MTU=65520 CONNECTED_MODE=yes.

The xCAT object definition commands support to use nicextraparams.<nicname> as the sub attributes.

nichostnameprefixes (nics.nichostnameprefixes)

Comma-separated list of hostname prefixes per NIC.

- **If only one ip address is associated with each NIC:** \(<\text{nic1}>!<\text{ext1}>, <\text{nic2}>!<\text{ext2}>, \ldots\), for example, eth0/eth0-, ib0/ib-

- **If multiple ip addresses are associated with each NIC:** \(<\text{nic1}>!<\text{ext1}>!<\text{ext2}>, <\text{nic2}>!<\text{ext1}>!<\text{ext2}>, \ldots\)

The xCAT object definition commands support to use nichostnameprefixes.<nicname> as the sub attributes. Note: According to DNS rules a hostname must be a text string up to 24 characters drawn from the alphabet (A-Z), digits (0-9) and minus sign (-). When you are specifying “nichostnameprefixes” or “nicaliases” make sure the resulting hostnames will conform to this naming convention.

nichostnamesuffixes (nics.nichostnamesuffixes)

Comma-separated list of hostname suffixes per NIC.

- **If only one ip address is associated with each NIC:** \(<\text{nic1}>!<\text{ext1}>, <\text{nic2}>!<\text{ext2}>, \ldots\), for example, eth0!/eth0-, ib0!/ib-

- **If multiple ip addresses are associated with each NIC:** \(<\text{nic1}>!<\text{ext1}>!<\text{ext2}>, <\text{nic2}>!<\text{ext1}>!<\text{ext2}>, \ldots\), for example, eth0!/eth0!/eth0-ipv6, ib0!/ib-ipv6.

The xCAT object definition commands support to use nichostnamesuffixes.<nicname> as the sub attributes.

nicips (nics.nicips)

Comma-separated list of IP addresses per NIC.

- **To specify one ip address per NIC:** \(<\text{nic1}>!<\text{ip1}>, <\text{nic2}>!<\text{ip2}>, \ldots\), for example, eth0!10.0.0.100, ib0!11.0.0.100

Note: According to DNS rules a hostname must be a text string up to 24 characters drawn from the alphabet (A-Z), digits (0-9) and minus sign (-). When you are specifying **"nichostnamesuffixes"** or **"nicaliases"** make sure the resulting hostnames will conform to this naming convention.
To specify multiple ip addresses per NIC: `<nic1>!<ip1>!<ip2>,<nic2>!<ip1>!<ip2>`, for example, `eth0!10.0.0.100|fd55:faaf:e1ab:336::/64,ib0!11.0.0.0-255.255.0.0|2001:db8:1:0::/64`.

The xCAT object definition commands support to use nicips.<nicname> as the sub attributes.

Note: The primary IP address must also be stored in the hosts.ip attribute. The nichostnamesuffixes should specify one hostname suffix for each ip address.

**nicnetworks** *(nics.nicnetworks)*

Comma-separated list of networks connected to each NIC.

**If only one ip address is associated with each NIC:** `<nic1>!<network1>,<nic2>!<network2>`, for example, `eth0!10.0.0.0-255.255.0.0, ib0!11.0.0.0-255.255.0.0`.

**If multiple ip addresses are associated with each NIC:** `<nic1>!<network1>|<network2>,<nic2>!<network1>|<network2>`, for example, `eth0!10.0.0.0-255.255.0.0|fd55:faaf:e1ab:336::/64, ib0!11.0.0.0-255.255.0.0|2001:db8:1:0::/64`. The xCAT object definition commands support to use nicnetworks.<nicname> as the sub attributes.

**nicsadapter** *(nics.nicsadapter)*

Comma-separated list of NIC information collected by getadapter. `<nic1>!<param1=value1 param2=value2>,<nic2>!<param4=value4 param5=value5>`, for example, `enP3p3s0f1!mac=98:be:94:59:fa:cd linkstate=DOWN,enP3p3s0f2!mac=98:be:94:59:fa:ce candidatename=enP3p3s0f2/enx98be9459face`.

**nictypes** *(nics.nictypes)*

Comma-separated list of NIC types per NIC. `<nic1>!<type1>,<nic2>!<type2>`, e.g. `eth0!Ethernet,ib0!Infiniband`. The xCAT object definition commands support to use nictypes.<nicname> as the sub attributes.

**nimserver** *(noderes.nimserver)*

Not used for now. The NIM server for this node (as known by this node).

**nodetype** *(nodetype.nodetype, pdu.nodetype)*

A comma-delimited list of characteristics of this node. Valid values: ppc, blade, vm (virtual machine), osi (OS image), mm, mn, rsa, switch.

or

The node type should be pdu.

**ondiscover** *(chain.ondiscover)*

This attribute is currently not used by xCAT. The “ondiscover” operation is always done during node discovery.

**os** *(nodetype.os)*

The operating system deployed on this node. Valid values: AIX, rhel*,rhele*, rhas*,centos*,SL*, fedora*, sles* (where * is the version #). As a special case, if this is set to “boottarget”, then it will use the initrd/kernel/parameters specified in the row in the boottarget table in which boottarget.bprofile equals nodetype.profile.

**osvolume** *(storage.osvolume)*

Specification of what storage to place the node OS image onto. Examples include:

```
localdisk (Install to first non-FC attached disk)
usbdisk (Install to first USB mass storage device seen)
wwn=0x50000393c813840c (Install to storage device with given WNN)
```

1.3. Admin Guide 673
otherinterfaces (hosts.otherinterfaces)

Other IP addresses to add for this node. Format: -<ext>:<ip>,<intfhostname>:<ip>,...

ou (domain.ou)

For an LDAP described machine account (i.e. Active Directory), the organizational unit to place the system. If not set, defaults to cn=Computers,dc=your,dc=domain

outlet (pdu.outlet)

The pdu outlet count

parent (ppc.parent)

For LPARs: the CEC; for FSPs: the CEC; for CEC: the frame (if one exists); for BPA: the frame; for frame: the building block number (which consists 1 or more service nodes and compute/storage nodes that are serviced by them - optional).

passwd.HMC (ppcdirect.password)

Password of the FSP/BPA(for ASMI) and CEC/Frame(for DFM). If not filled in, xCAT will look in the passwd table for key=fsp. If not in the passwd table, the default used is admin.

passwd.admin (ppcdirect.password)

Password of the FSP/BPA(for ASMI) and CEC/Frame(for DFM). If not filled in, xCAT will look in the passwd table for key=fsp. If not in the passwd table, the default used is admin.

passwd.celogin (ppcdirect.password)

Password of the FSP/BPA(for ASMI) and CEC/Frame(for DFM). If not filled in, xCAT will look in the passwd table for key=fsp. If not in the passwd table, the default used is admin.

passwd.general (ppcdirect.password)

Password of the FSP/BPA(for ASMI) and CEC/Frame(for DFM). If not filled in, xCAT will look in the passwd table for key=fsp. If not in the passwd table, the default used is admin.

passwd.hscroot (ppcdirect.password)

Password of the FSP/BPA(for ASMI) and CEC/Frame(for DFM). If not filled in, xCAT will look in the passwd table for key=fsp. If not in the passwd table, the default used is admin.

password (ppchcp.password, mpa.password, webserv.password, pdu.password, switches.sshpassword)

Password of the HMC or IVM. If not filled in, xCAT will look in the passwd table for key=hmc or key=ivm. If not in the passwd table, the default used is abc123 for HMCs and padmin for IVMs.

or

Password to use to access the management module. If not specified, the key=blade row in the passwd table is used as the default.

or

Password to use to access the web service.

or

The remote login password

or

The remote login password. It can be for ssh or telnet. If it is for telnet, set protocol to “telnet”. If the sshusername is blank, the username, password and protocol will be retrieved from the passwd table with “switch” as the key.
**pdu** (pduoutlet.pdu)

A comma-separated list of outlet number for each PDU, ex: pdu1:outlet1,pdu2:outlet1

**pdutype** (pdu.pdutype)

The type of pdu

**postbootscripts** (postscripts.postbootscripts)

Comma separated list of scripts that should be run on this node after diskful installation or diskless boot. Each script can take zero or more parameters. For example: “script1 p1 p2,script2,…”. On AIX these scripts are run during the processing of /etc/inittab. On Linux they are run at the init.d time. xCAT automatically adds the scripts in the xcatdefaults.postbootscripts attribute to run first in the list. Please note that the postbootscripts specified for “xcatdefaults” will be assigned to node automatically, they can not be removed from “postbootscripts” attribute of a node with “chdef -m” command

**postscripts** (postscripts.postscripts)

Comma separated list of scripts that should be run on this node after diskful installation or diskless boot. Each script can take zero or more parameters. For example: “script1 p1 p2,script2,…”. xCAT automatically adds the postscripts from the xcatdefaults.postscripts attribute of the table to run first on the nodes after install or diskless boot. For installation of RedHat, CentOS, Fedora, the scripts will be run before the reboot. For installation of SLES, the scripts will be run after the reboot but before the init.d process. For diskless deployment, the scripts will be run at the init.d time, and xCAT will automatically add the list of scripts from the postbootscripts attribute to run after postscripts list. For installation of AIX, the scripts will be run after the reboot and acts the same as the postbootscripts attribute. For AIX, use the postbootscripts attribute. Please note that the postscripts specified for “xcatdefaults” will be assigned to node automatically, they can not be removed from “postscripts” attribute of a node with “chdef -m” command

**power** (nodehm.power)

The method to use to control the power of the node. If not set, the mgt attribute will be used. Valid values: ipmi, blade, hmc, ivm, fsp, kvm, esx, rhevm. If “ipmi”, xCAT will search for this node in the ipmi table for more info. If “blade”, xCAT will search for this node in the mp table. If “hmc”, “ivm”, or “fsp”, xCAT will search for this node in the ppc table.

**pprofile** (ppc.pprofile)

The LPAR profile that will be used the next time the LPAR is powered on with rpower. For DFM, the pprofile attribute should be set to blank

**prescripts-begin** (prescripts.begin)

The scripts to be run at the beginning of the nodeset(Linux), nimnodeset(AIX) or mkdsklsnode(AIX) command.

**The format is:** [action1:s1,s2,…][| action2:s3,s4,s5,…]

**where:**

- action1 and action2 for Linux are the nodeset actions specified in the command. For AIX, action1 and action1 can be ‘diskless’ for mkdsklsnode command’ and ‘standalone for nimnodeset command.
- s1 and s2 are the scripts to run for action1 in order.
- s3, s4, and s5 are the scripts to run for actions2.

If actions are omitted, the scripts apply to all actions. Examples:

```bash
myscript1.myscript2 (all actions) diskless:myscript1.myscript2 (AIX) install:myscript1.myscript2|netboot:myscript3 (Linux)
```
All the scripts should be copied to /install/prescripts directory. The following two environment variables will be passed to each script:

- **NODES** a comma separated list of node names that need to run the script for ACTION current nodeset action.

If ‘#xCAT setting:MAX_INSTANCE=number’ is specified in the script, the script will get invoked for each node in parallel, but no more than number of instances will be invoked at a time. If it is not specified, the script will be invoked once for all the nodes.

**prescripts-end** (prescripts.end)

The scripts to be run at the end of the nodeset(Linux), nimnodeset(AIX), or mkdsklsnode(AIX) command. The format is the same as the ‘begin’ column.

**primarynic** (noderes.primarynic)

This attribute will be deprecated. All the used network interface will be determined by installnic. The network adapter on the node that will be used for xCAT management, the primarynic can be set to the network adapter name or the mac address or the keyword “mac” which means that the network interface specified by the mac address in the mac table will be used. Default is eth0.

**privkey** (pdu.privkey)

The privacy passphrase to use for SNMPv3.

**privtype** (pdu.privtype)

The privacy protocol (AES|DES) to use for SNMPv3.

**productkey** (prodkey.key)

The product key relevant to the aforementioned node/group and product combination.

**profile** (nodetype.profile)

The string to use to locate a kickstart or autoyast template to use for OS deployment of this node. If the provmethod attribute is set to an osimage name, that takes precedence, and profile need not be defined. Otherwise, the os, profile, and arch are used to search for the files in /install/custom first, and then in /opt/xcat/share/xcat.

**protocol** (switches.protocol)

Protocol for running remote commands for the switch. The valid values are: ssh, telnet. ssh is the default. If the sshusername is blank, the username, password and protocol will be retrieved from the passwd table with “switch” as the key. The passwd.comments attribute is used for protocol.

**provmethod** (nodetype.provmethod)

The provisioning method for node deployment. The valid values are install, netboot, statelite or an os image name from the osimage table. If an image name is specified, the osimage definition stored in the osimage table and the linuximage table (for Linux) or nimimage table (for AIX) are used to locate the files for templates, pkglists, syncfiles, etc. On Linux, if install, netboot or statelite is specified, the os, profile, and arch are used to search for the files in /install/custom first, and then in /opt/xcat/share/xcat.

**rack** (nodepos.rack)

The frame the node is in.

**room** (nodepos.room)

The room where the node is located.

**routenames** (noderes.routenames)
A comma separated list of route names that refer to rows in the routes table. These are the routes that should be defined on this node when it is deployed.

**seclevel** (pdu.secelve)

The Security Level(noAuthNoPriv|authNoPriv|authPriv) to use for SNMPv3.

**serial** (vpd.serial)

The serial number of the node.

**serialflow** (nodehm.serialflow)

The flow control value of the serial port for this node. For SOL this is typically ’hard’.

**serialport** (nodehm.serialport)

The serial port for this node, in the linux numbering style (0=COM1/ttyS0, 1=COM2/ttyS1). For SOL on IBM blades, this is typically 1. For rackmount IBM servers, this is typically 0.

**serialspeed** (nodehm.serialspeed)

The speed of the serial port for this node. For SOL this is typically 19200.

**servicenode** (noderes.servicenode)

A comma separated list of node names (as known by the management node) that provides most services for this node. The first service node on the list that is accessible will be used. The 2nd node on the list is generally considered to be the backup service node for this node when running commands like snmove.

**setupconserver** (servicenode.conserver)

Do we set up console service on this service node? Valid values: 0, 1, or 2. If 0, it does not change the current state of the service. If 1, configures and starts conserver daemon. If 2, configures and starts goconserver daemon.

**setupdhcp** (servicenode.dhcpserver)

Do we set up DHCP on this service node? Not supported on AIX. Valid values: 1 or 0. If 1, runs makedhcp -n. If 0, it does not change the current state of the service.

**setupftp** (servicenode.ftpserver)

Do we set up a ftp server on this service node? Not supported on AIX Valid values: 1 or 0. If 1, configure and start vsftpd. (You must manually install vsftpd on the service nodes before this.) If 0, it does not change the current state of the service. xCAT is not using ftp for compute nodes provisioning or any other xCAT features, so this attribute can be set to 0 if the ftp service will not be used for other purposes.

**setupipforward** (servicenode.ipforward)

Do we set up ip forwarding on this service node? Valid values: 1 or 0. If 0, it does not change the current state of the service.

**setupldap** (servicenode.ldapserver)

Do we set up ldap caching proxy on this service node? Not supported on AIX. Valid values: 1 or 0. If 0, it does not change the current state of the service.

**setupnameserver** (servicenode.nameserver)

Do we set up DNS on this service node? Valid values: 2, 1, or 0. If 2, creates named.conf as dns slave, using the management node as dns master, and starts named. If 1, creates named.conf file with forwarding to the management node and starts named. If 0, it does not change the current state of the service.

**setupnfs** (servicenode.nfsserver)
Do we set up file services (HTTP, FTP, or NFS) on this service node? For AIX will only setup NFS, not HTTP or FTP. Valid values: 1 or 0. If 0, it does not change the current state of the service.

setupnim (servicenode.nimserver)

Not used. Do we set up a NIM server on this service node? Valid values: 1 or 0. If 0, it does not change the current state of the service.

setupntp (servicenode.ntpserver)

Not used. Use setupntp postscript to setup a ntp server on this service node? Valid values: 1 or 0. If 0, it does not change the current state of the service.

setupproxydhcp (servicenode.proxydhcp)

Do we set up proxydhcp service on this node? valid values: 1 or 0. If 1, the proxydhcp daemon will be enabled on this node.

setuptftp (servicenode.tftpserver)

Do we set up TFTP on this service node? Not supported on AIX. Valid values: 1 or 0. If 1, configures and starts atftp. If 0, it does not change the current state of the service.

sfp (ppc.sfp)

The Service Focal Point of this Frame. This is the name of the HMC that is responsible for collecting hardware service events for this frame and all of the CECs within this frame.

side (vpd.side)

<BPA>-<port> or <FSP>-<port>. The side information for the BPA/FSP. The side attribute refers to which BPA/FSP, A or B, which is determined by the slot value returned from lsslp command. It also lists the physical port within each BPA/FSP which is determined by the IP address order from the lsslp response. This information is used internally when communicating with the BPAs/FSPs

slot (nodepos.slot)

The slot number of the blade in the chassis. For PCM, a comma-separated list of slot numbers is stored

slotid (mp.id)

The slot number of this blade in the BladeCenter chassis.

slots (mpa.slots)

The number of available slots in the chassis. For PCM, this attribute is used to store the number of slots in the following format: <slot rows>,<slot columns>,<slot orientation> Where:

<slot rows> = number of rows of slots in chassis
<slot columns> = number of columns of slots in chassis
<slot orientation> = set to 0 if slots are vertical, and set to 1 if slots are horizontal

snmpauth (switches.auth)

The authentication protocol to use for SNMPv3. SHA is assumed if v3 enabled and this is unspecified

snmppassword (switches.password)

The password string for SNMPv3 or community string for SNMPv1/SNMPv2. Falls back to passwd table, and site snmpc value if using SNMPv1/SNMPv2.

snmpprivacy (switches.privacy)

The privacy protocol to use for v3. xCAT will use authNoPriv if this is unspecified. DES is recommended to use if v3 enabled, as it is the most readily available.
**snmpuser** *(pdu.snmpuser)*

The username to use for SNMPv3 communication, ignored for SNMPv1.

**snmpusername** *(switches.username)*

The username to use for SNMPv3 communication, ignored for SNMPv1.

**snmpversion** *(pdu.snmpversion, switches.snmpversion)*

The version to use to communicate with switch. SNMPv1 is assumed by default.

or

The version to use to communicate with switch. SNMPv1 is assumed by default.

**storagcontroller** *(storage.controller)*

The management address to attach/detach new volumes. In the scenario involving multiple controllers, this data must be passed as argument rather than by table value.

**storagetype** *(storage.type)*

The plugin used to drive storage configuration (e.g. svc).

**supernode** *(ppc.supernode)*

Indicates the connectivity of this CEC in the HFI network. A comma separated list of 2 ids. The first one is the supernode number the CEC is part of. The second one is the logical location number (0-3) of this CEC within the supernode.

**supportedarchs** *(nodetype.supportedarchs)*

Comma delimited list of architectures this node can execute.

**supportproxydhcp** *(noderes.proxydhcp)*

To specify whether the node supports proxydhcp protocol. Valid values: yes or 1, no or 0. Default value is yes.

**switch** *(switch.switch)*

The switch hostname.

**switchinterface** *(switch.interface)*

The interface name from the node perspective. For example, eth0. For the primary nic, it can be empty, the word “primary” or “primary:ethx” where ethx is the interface name.

**switchport** *(switch.port)*

The port number in the switch that this node is connected to. On a simple 1U switch, an administrator can generally enter the number as printed next to the ports, and xCAT will understand switch representation differences. On stacked switches or switches with line cards, administrators should usually use the CLI representation (i.e. 2/0/1 or 5/8). One notable exception is stacked SMC 8848M switches, in which you must add 56 for the proceeding switch, then the port number. For example, port 3 on the second switch in an SMC8848M stack would be 59.

**switchtype** *(switches.switchtype)*

The type of switch. It is used to identify the file name that implements the functions for this switch. The valid values are: Mellanox, Cisco, BNT and Juniper.

**switchvlan** *(switch.vlan)*

The ID for the tagged vlan that is created on this port using mkvlan and chvlan commands.

**syslog** *(noderes.syslog)*
To configure how to configure syslog for compute node. Valid values: blank (not set), ignore. blank - run postscript syslog; ignore - do NOT run postscript syslog

termport (nodehm.termport)

The port number on the terminal server that this node is connected to.

termserver (nodehm.termserver)

The hostname of the terminal server.

tftpdir (noderes.tftpdir)

The directory that roots this nodes contents from a tftp and related perspective. Used for NAS offload by using different mountpoints.

tftpserver (noderes.tftpserver)

The TFTP server for this node (as known by this node). If not set, it defaults to networks.tftpserver.

unit (nodepos.u)

The vertical position of the node in the frame

urlpath (mpa.urlpath)

URL path for the Chassis web interface. The full URL is built as follows: <hostname>/<urlpath>

usercomment (nodegroup.comments)

Any user-written notes.

userid (zvm.userid)

The z/VM userID of this node.

username (ppchcp.username, mpa.username, websrv.username, pdu.username, switches.sshusername)

Userid of the HMC or IVM. If not filled in, xCAT will look in the passwd table for key=hmc or key=ivm. If not in the passwd table, the default used is hscroot for HMCs and padmin for IVMs.

or

Userid to use to access the management module.

or

Userid to use to access the web service.

or

The remote login user name

or

The remote login user name. It can be for ssh or telnet. If it is for telnet, set protocol to “telnet”. If the sshusername is blank, the username, password and protocol will be retrieved from the passwd table with “switch” as the key.

vmbeacon (vm.beacon)

This flag is used by xCAT to track the state of the identify LED with respect to the VM.

vmbootorder (vm.bootorder)

Boot sequence (i.e. net,hd)

vmcfgstore (vm.cfgstore)
Optional location for persistent storage separate of emulated hard drives for virtualization solutions that require persistent store to place configuration data

**vmcluster** (vm.cluster)

Specify to the underlying virtualization infrastructure a cluster membership for the hypervisor.

**vmcpus** (vm.cp)

Number of CPUs the node should see.

**vmhost** (vm.host)

The system that currently hosts the VM.

**vmmanager** (vm.mgr)

The function manager for the virtual machine.

**vmmaster** (vm.master)

The name of a master image, if any, this virtual machine is linked to. This is generally set by `clonevm` and indicates the deletion of a master that would invalidate the storage of this virtual machine.

**vmmemory** (vm.memory)

Megabytes of memory the VM currently should be set to.

**vmnicnicmodel** (vm.nicmodel)

Model of NICs that will be provided to VMs (i.e. e1000, rtl8139, virtio, etc).

**vmnics** (vm.nics)

Network configuration parameters. Of the general form [physnet:]interface... Generally, interface describes the vlan entity (default for native, tagged for tagged, vl[number] for a specific vlan. physnet is a virtual switch name or port description that is used for some virtualization technologies to construct virtual switches. hypervisor.netmap can map names to hypervisor specific layouts, or the descriptions described there may be used directly here where possible.

**vmothersetting** (vm.othersettings)

This allows specifying a semicolon delimited list of key->value pairs to include in a vmx file of VMware or KVM. For partitioning on normal power machines, this option is used to specify the hugepage and/or bsr information, the value is like:‘hugepage:1,bsr=2’. For KVM cpu pinning, this option is used to specify the physical cpu set on the host, the value is like:”vcpupin:’0-15,^8’”,Its syntax is a comma separated list and a special markup using ‘-’ and ‘^’ (ex. ‘0-4’, ‘0-3,^2’) can also be allowed, the ‘-’ denotes the range and the ‘^’ denotes exclusive. For KVM memory binding, the value is like:’membind:0’, restrict a guest to allocate memory from the specified set of NUMA nodes. For PCI passthrough, the value is like:’devpasssthrough:pci_0001_01_00_0,pci_0000_03_00_0’, the value for PCI device format also can be like:’devpasssthrough:0001:01:00.1’, the PCI devices are assigned to a virtual machine, and the virtual machine can use this I/O exclusively, the devices list are a list of PCI device names delimited with comma, the PCI device names can be obtained by running `virsh nodename-list` on the host.

**vmphyslots** (vm.physlots)

Specify the physical slots drc index that will assigned to the partition, the delimiter is ‘,‘, and the drc index must started with ‘0x‘. For more details, reference manpage for ‘lsvm‘.

**vmstorage** (vm.storage)

A list of storage files or devices to be used. i.e. dir://cluster/vm/<nodename> or nfs://<server>/path/to/folder/

**vmstoragecache** (vm.storagecache)
Select caching scheme to employ. E.g. KVM understands ‘none’, ‘writethrough’ and ‘writeback’

`vmstorageformat` (vm.storageformat)

Select disk format to use by default (e.g. raw versus qcow2)

`vmstoragemodel` (vm.storagemodel)

Model of storage devices to provide to guest

`vmtextrconsole` (vm.textconsole)

Tracks the Psuedo-TTY that maps to the serial port or console of a VM

`vnmvirtflags` (vm.virtflags)

General flags used by the virtualization method.

  For example, in Xen it could, among other things, specify paravirtualized setup, or direct kernel boot. For a hypervisor/dom0 entry, it is the virtualization method (i.e. “xen”). For KVM, the following flag=value pairs are recognized:

  - `imageformat=[raw|fullraw|qcow2]` raw is a generic sparse file that allocates storage on demand
    fullraw is a generic, non-sparse file that preallocates all space
    qcow2 is a sparse, copy-on-write capable format implemented at the virtualization layer rather than the filesystem level

  - `clonemethod=[qemu-img|reflink]` qemu-img allows use of qcow2 to generate virtualization layer copy-on-write
    reflink uses a generic filesystem facility to clone the files on your behalf, but requires filesystem support such as btrfs

  - `placement_affinity=[migratable|user_migratable|pinned]`

`vmvncport` (vm.vncport)

Tracks the current VNC display port (currently not meant to be set)

`webport` (websrv.port)

The port of the web service.

`wherevals` (nodegroup.wherevals)

A list of “attr*val” pairs that can be used to determine the members of a dynamic group, the delimiter is “::” and the operator * can be ==, =~, != or !~.

`xcatmaster` (noderes.xcatmaster)

The hostname of the xCAT service node (as known by this node). This acts as the default value for nfsserver and tftpserver, if they are not set. If xcatmaster is not set, the node will use whoever responds to its boot request as its master. For the directed bootp case for POWER, it will use the management node if xcatmaster is not set.

SEE ALSO

mkdef(1), chdef(1), lsdef(1), rmdef(1)

kit.7

NAME

kit - a logical object definition in the xCAT database.
SYNOPSIS

kit Attributes: basename, description, isinternal, kitdeployparams, kitdir, kitname, ostype, release, version

DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: mkdef, chdef, lsdef, and rmdef. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

kit Attributes:

basename (kit.basename)
   The kit base name

description (kit.description)
   The Kit description.

isinternal (kit.isinternal)
   A flag to indicated if the Kit is internally used. When set to 1, the Kit is internal. If 0 or undefined, the kit is not internal.

kitdeployparams (kit.kitdeployparams)
   The file containing the default deployment parameters for this Kit. These parameters are added to the OS Image definition's list of deployment parameters when one or more Kit Components from this Kit are added to the OS Image.

kitdir (kit.kitdir)
   The path to Kit Installation directory on the Mgt Node.

kitname (kit.kitname)
   The unique generated kit name, when kit is added to the cluster.

ostype (kit.ostype)
   The kit OS type. Linux or AIX.

release (kit.release)
   The kit release

version (kit.version)
   The kit version

SEE ALSO

mkdef(1), chdef(1), lsdef(1), rmdef(1)
kitcomponent.7

NAME

kitcomponent - a logical object definition in the xCAT database.

SYNOPSIS

kitcomponent Attributes: basename, description, driverpacks, exlist, genimage_postinstall, kitcompdeps, kitcompname, kitname, kitpkgdeps, kitreponame, postbootscripts, prerequisite, release, serverroles, version

DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: mkdef, chdef, lsdef, and rmdef. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

kitcomponent Attributes:

basename (kitcomponent.basename)
    Kit Component basename.
description (kitcomponent.description)
    The Kit component description.
driverpacks (kitcomponent.driverpacks)
    Comma-separated List of driver package names. These must be full names like: pkg1-1.0-1.x86_64.rpm.
exlist (kitcomponent.exlist)
    Exclude list file containing the files/directories to exclude when building a diskless image.
genimage_postinstall (kitcomponent.genimage_postinstall)
    Comma-separated list of postinstall scripts that will run during the genimage.
kitcompdeps (kitcomponent.kitcompdeps)
    Comma-separated list of kit components that this kit component depends on.
kitcompname (kitcomponent.kitcompname)
    The unique Kit Component name. It is auto-generated when the parent Kit is added to the cluster.
kitname (kitcomponent.kitname)
    The Kit name which this Kit Component belongs to.
kitpkgdeps (kitcomponent.kitpkgdeps)
    Comma-separated list of packages that this kit component depends on.
kitreponame (kitcomponent.kitreponame)
    The Kit Package Repository name which this Kit Component belongs to.
postbootscripts (kitcomponent.postbootscripts)

Comma-separated list of postbootscripts that will run during the node boot.

prerequisite (kitcomponent.prerequisite)

Prerequisite for this kit component, the prerequisite includes ospkgdeps, preinstall, preupgrade, preuninstall scripts

release (kitcomponent.release)

Kit Component release.

serverroles (kitcomponent.serverroles)

The types of servers that this Kit Component can install on. Valid types are: mgtnode, servicenode, compute

version (kitcomponent.version)

Kit Component version.

SEE ALSO

mkdef(1), chdef(1), lsdef(1), rmdef(1)

kitrepo.7

NAME

kitrepo - a logical object definition in the xCAT database.

SYNOPSIS

kitrepo Attributes: compat_osbasenames, kitname, kitrepodir, kitreponame, osarch, osbasename, osmajorversion, osminorversion

DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: mkdef, chdef, lsdef, and rmdef. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

kitrepo Attributes:

compat_osbasenames (kitrepo.compat_osbasenames)

List of compatible OS base names.

kitname (kitrepo.kitname)

The Kit name which this Kit Package Repository belongs to.

kitrepodir (kitrepo.kitrepodir)
The path to Kit Repository directory on the Mgt Node.

**kitreponame** (kitrepo.kitreponame)

The unique generated kit repo package name, when kit is added to the cluster.

**osarch** (kitrepo.osarch)

The OS distro arch which this repository is based on.

**osbasename** (kitrepo.osbasename)

The OS distro name which this repository is based on.

**osmajorversion** (kitrepo.osmajorversion)

The OS distro major version which this repository is based on.

**osminorversion** (kitrepo.osminorversion)

The OS distro minor version which this repository is based on. If this attribute is not set, it means that this repo applies to all minor versions.

SEE ALSO

mkdef(1), chdef(1), lsdef(1), rmdef(1)

monitoring.7

NAME

monitoring - a logical object definition in the xCAT database.

SYNOPSIS

monitoring Attributes: comments, disable, name, nodestatmon

DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: **mkdef**, **chdef**, **lsdef**, and **rmdef**. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

**monitoring Attributes:**

**comments** (monitoring.comments)

Any user-written notes.

**disable** (monitoring.disable)

Set to ‘yes’ or ‘1’ to comment out this row.

**name** (monitoring.name)
The name of the monitoring plug-in module. The plug-in must be put in /lib/perl/xCAT_monitoring/. See the man page for monstart for details.

**nodestatmon** *(monitoring.nodestatmon)*

Specifies if the monitoring plug-in is used to feed the node status to the xCAT cluster. Any one of the following values indicates “yes”: y, Y, yes, Yes, YES, 1. Any other value or blank (default), indicates “no”.

**SEE ALSO**

mkdef(1), chdef(1), lsdef(1), rmdef(1)

network.7

**NAME**

**network** - a logical object definition in the xCAT database.

**SYNOPSIS**

**network Attributes**: ddnsdomain, dhcpserver, domain, dynamicrange, gateway, logservers, mask, mgtifname, mtu, nameservers, net, netname, nodehostname, ntpservers, staticrange, staticrangeincrement, tftpserver, usercomment, vlanid

**DESCRIPTION**

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: mkdef, chdef, lsdef, and rmdef. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

**network Attributes:**

**ddnsdomain** *(networks.ddnsdomain)*

A domain to be combined with nodename to construct FQDN for DDNS updates induced by DHCP. This is not passed down to the client as “domain”

**dhcpserver** *(networks.dhcpserver)*

The DHCP server that is servicing this network. Required to be explicitly set for pooled service node operation.

**domain** *(networks.domain)*

The DNS domain name (ex. cluster.com).

**dynamicrange** *(networks.dynamicrange)*

The IP address range used by DHCP to assign dynamic IP addresses for requests on this network. This should not overlap with entities expected to be configured with static host declarations, i.e. anything ever expected to be a node with an address registered in the mac table.
**gateway** (networks.gateway)

The network gateway. It can be set to an ip address or the keyword `<xcatmaster>`, the keyword `<xcatmaster>` indicates the cluster-facing ip address configured on this management node or service node. Leaving this field blank means that there is no gateway for this network.

**logservers** (networks.logservers)

The log servers for this network. Used in creating the DHCP network definition. Assumed to be the DHCP server if not set.

**mask** (networks.mask)

The network mask.

**mgtifname** (networks.mgtifname)

The interface name of the management/service node facing this network. `!remote!<nicname>` indicates a non-local network on a specific nic for relay DHCP.

**mtu** (networks.mtu)

The default MTU for the network. If multiple networks are applied to the same nic on the SN and/or CN, the MTU shall be the same for those networks.

**nameservers** (networks.nameservers)

A comma delimited list of DNS servers that each node in this network should use. This value will end up in the nameserver settings of the `/etc/resolv.conf` on each node in this network. If this attribute value is set to the IP address of an xCAT node, make sure DNS is running on it. In a hierarchical cluster, you can also set this attribute to `"<xcatmaster>"` to mean the DNS server for each node in this network should be the node that is managing it (either its service node or the management node). Used in creating the DHCP network definition, and DNS configuration.

**net** (networks.net)

The network address.

**netname** (networks.netname)

Name used to identify this network definition.

**nodehostname** (networks.nodehostname)

A regular expression used to specify node name to network-specific hostname. i.e. “/z/-secondary/" would mean that the hostname of “n1” would be n1-secondary on this network. By default, the nodename is assumed to equal the hostname, followed by nodename-interfacename.

**ntpservers** (networks.ntpservers)

The ntp servers for this network. Used in creating the DHCP network definition. Assumed to be the DHCP server if not set.

**staticrange** (networks.staticrange)

The IP address range used to dynamically assign static IPs to newly discovered nodes. This should not overlap with the dynamicrange nor overlap with entities that were manually assigned static IPs. The format for the attribute value is: `<startip>-<endip>`.

**staticrangeincrement** (networks.staticrangeincrement)

**tftpserver** (networks.tftpserver)

The TFTP server that is servicing this network. If not set, the DHCP server is assumed.

**usercomment** (networks.comments)
Any user-written notes.

**vlanid** (networks.vlanid)

The vlan ID if this network is within a vlan.

SEE ALSO

mkdef(1), chdef(1), lsdef(1), rmdef(1)

node.7

NAME

node - a logical object definition in the xCAT database.

SYNOPSIS

node Attributes: addkcmdline, appstatus, appstatustime, arch, authdomain, authkey, authtype, bmc, bmcpassword, bmcport, bmcusername, bmcvlanlag, cfgrngr, cfgrngtroles, cfgrngserver, chain, chassis, cmdmapping, community, cons, conserver, consoleenabled, consoleondemand, consport, cpucount, cputype, currchain, currstate, dhcpinterfaces, disksize, displayname, dockercpus, dockercfg, dockerhost, dockermemory, dockernics, domaimadminpassword, domainadminuser, domaintype, getmac, groups, hcp, height, hidden, hostcluster, hostinterface, hostmanager, hostnames, hosttype, hwtypes, id, initrd, installnic, interface, ip, iscsipassword, isccserver, iscstarget, iscsiuserid, kmddline, kernel, linksports, mac, memory, mgt, mibbridge, michost, micid, miconboot, micpowermgmt, micvlog, migrationdest, monserver, mpa, mtm, nameservers, netboot, nfsdir, nfsserver, nicalias, niccustomscripts, nicdev, nicdevparam, nicherownamesprefixes, nicherownamesuffixes, nicips, nicnetworks, nicadapter, nicproto, nimserver, node, nodetype, ondiscover, os, osvolume, otherinterfaces, ou, outlet, parent, passwd.HMC, passwd.admin, passwd.celogin, passwd generalized, passwd.hscroot, password, pdu, pdu.adapters, postbootscripts, postscripts, power, pprofile, prescriptsbegin, prescripts-end, primarynic, primaryswitch, privkey, privtype, productkey, profile, protocol, provmethod, rack, room, routenames, seclevel, serial, serialflow, serialport, serialspeed, servicenode, setupconserver, setupdhcp, setupif, setupifforward, setupldap, setupnameserver, setupnfs, setupnmp, setapproxydhcp, setupifip, sfp, side, slot, slotid, slots, snmpauth, snmppassword, snmpprivacy, snmpusername, snmpversion, status, status-time, storagetype, supernode, supportedarchs, supportproxydhcp, switch, switchinterface, switchport, switchtype, switchvlan, syslog, termport, termserver, tfpdir, tfpserver, unit, updatestatus, updatestatustime, urlpath, usercommand, userid, username, vmbeacon, vmbootorder, vmcfgstore, vmcluster, vmcpus, vmhost, vmhost, vmmemory, vmnicnicmodel, vmnics, vmothersetting, vmphyslots, vmstorage, vmstoragecache, vmstorageformat, vmstoragemodel, vmtextconsole, vnvinf-light, vminport, webport, xcatmaster, zonename

DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: mkdef, chdef, lsdef, and rmdef. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

node Attributes:

addkcmdline (bootparams.addkcmdline)
User specified kernel options for os provision process (no prefix) or the provisioned os (with prefix “R::”). The options should be delimited with spaces (" ")

**appstatus** (nodelist.appstatus)

A comma-delimited list of application status. For example: ‘sshd=up,ftp=down,ll=down’

**appstatustime** (nodelist.appstatustime)

The date and time when appstatus was updated.

**arch** (nodetype.arch)

The hardware architecture of this node. Valid values: x86_64, ppc64, x86, ia64.

**authdomain** (domain.authdomain)

If a node should participate in an AD domain or Kerberos realm distinct from domain indicated in site, this field can be used to specify that

**authkey** (pdu.authkey)

The authentication passphrase for SNMPv3

**authtype** (pdu.authtype)

The authentication protocol (MD5|SHA) to use for SNMPv3.

**bmc** (ipmi.bmc, openbmc.bmc)

The hostname of the BMC adapter.

or

The hostname of the BMC adapter.

**bmcpassword** (ipmi.password, openbmc.password)

The BMC password. If not specified, the key=ipmi row in the passwd table is used as the default.

or

The BMC password.

**bmcport** (ipmi.bmcport)

In systems with selectable shared/dedicated ethernet ports, this parameter can be used to specify the preferred port. 0 means use the shared port, 1 means dedicated, blank is to not assign.

The following special cases exist for IBM System x servers:

For x3755 M3 systems, 0 means use the dedicated port, 1 means shared, blank is to not assign.

For certain systems which have a mezzanine or ML2 adapter, there is a second value to include:

For x3750 M4 (Model 8722):

<table>
<thead>
<tr>
<th>Value</th>
<th>Interface</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 2</td>
<td>1st 1Gbps</td>
<td>for LOM</td>
</tr>
<tr>
<td>0 0</td>
<td>1st 10Gbps</td>
<td>for LOM</td>
</tr>
<tr>
<td>0 3</td>
<td>2nd 1Gbps</td>
<td>for LOM</td>
</tr>
</tbody>
</table>

(continues on next page)
0 1 2nd 10Gbps interface for LOM

For x3750 M4 (Model 8752), x3850/3950 X6, dx360 M4, x3550 M4, and x3650 M4:

0 Shared (1st onboard interface)
1 Dedicated
2 0 First interface on ML2 or mezzanine adapter
2 1 Second interface on ML2 or mezzanine adapter
2 2 Third interface on ML2 or mezzanine adapter
2 3 Fourth interface on ML2 or mezzanine adapter

**bmcusername** (ipmi.username, openbmc.username)

The BMC userid. If not specified, the key=ipmi row in the passwd table is used as the default.

or

The BMC userid.

**bmcvlantag** (ipmi.taggedvlan, openbmc.taggedvlan)

bmcsetup script will configure the network interface of the BMC to be tagged to the VLAN specified.

or

bmcsetup script will configure the network interface of the BMC to be tagged to the VLAN specified.

**cfgmgr** (cfgmgt.cfgmgr)

The name of the configuration manager service. Currently ‘chef’ and ‘puppet’ are supported services.

**cfgmgtroles** (cfgmgt.roles)

The roles associated with this node as recognized by the cfgmgr for the software that is to be installed and configured. These role names map to chef recipes or puppet manifest classes that should be used for this node. For example, chef OpenStack cookbooks have roles such as mysql-master,keystone, glance, nova-controller, nova-conductor, cinder-all.

**cfgserver** (cfgmgt.cfgserver)

The xCAT node name of the chef server or puppet master

**chain** (chain.chain)

A comma-delimited chain of actions to be performed automatically when this node is discovered for the first time. (xCAT and the DHCP server do not recognize the MAC address of the node when xCAT initializes the discovery process.) The last step in this process is to run the operations listed in the chain attribute, one by one. Valid values: boot, runcmd=<cmd>, runimage=<URL>, shell, standby. For example, to have the genesis kernel pause to the shell, use chain=shell.

**chassis** (nodepos.chassis)

The BladeCenter chassis the blade is in.
cmdmapping (nodehm.cmdmapping)

The fully qualified name of the file that stores the mapping between PCM hardware management commands and xCAT/third-party hardware management commands for a particular type of hardware device. Only used by PCM.

community (pdu.community)

The community string to use for SNMPv1/v2

cons (nodehm.cons)

The console method. If nodehm.serialport is set, this will default to the nodehm.mgt setting, otherwise it defaults to unused. Valid values: cyclades, mrv, or the values valid for the mgt attribute.

conserver (nodehm.conserver)

The hostname of the machine where the conserver daemon is running. If not set, the default is the xCAT management node.

consoleenabled (nodehm.consoleenabled)

A flag field to indicate whether the node is registered in the console server. If ‘1’, console is enabled, if not set, console is not enabled.

consoleondemand (nodehm.consoleondemand)

This overrides the value from site.consoleondemand. Set to ‘yes’, ‘no’, ‘1’ (equivalent to ‘yes’), or ‘0’ (equivalent to ‘no’). If not set, the default is the value from site.consoleondemand.

conspor (openbmc.conspor)

The console port for OpenBMC.

cputype (hwinv.cputype)

The cpu model name for the node.

currchain (chain.currchain)

The chain steps still left to do for this node. This attribute will be automatically adjusted by xCAT while xCAT-genesis is running on the node (either during node discovery or a special operation like firmware update). During node discovery, this attribute is initialized from the chain attribute and updated as the chain steps are executed.

currstate (chain.currstate)

The current or next chain step to be executed on this node by xCAT-genesis. Set by xCAT during node discovery or as a result of nodeset.

dhcpinterfaces (servicenode.dhcpinterfaces)

The network interfaces DHCP server should listen on for the target node. This attribute can be used for management node and service nodes. If defined, it will override the values defined in site.dhcpinterfaces. This is a comma separated list of device names. !remote! indicates a non-local network for relay DHCP. For example: !remote!,eth0,eth1

disksize (hwinv.disksize)

The size of the disks for the node in GB.

displayname (mpa.displayname)
Alternative name for BladeCenter chassis. Only used by PCM.

**dockercpus (vm.cpus)**

Number of CPUs the node should see.

**dockerflag (vm.othersettings)**

This allows specifying a semicolon delimited list of key->value pairs to include in a vmx file of VMware or KVM. For partitioning on normal power machines, this option is used to specify the hugepage and/or bsr information, the value is like: `hugepage:1,bss=2` for KVM cpu pinning, this option is used to specify the physical cpu set on the host, the value is like: `vcpupin:`.`0-15,`^8``. Its syntax is a comma separated list and a special markup using `-` and `^` (ex. `0-4`, `0-3,^2`) can also be allowed, the `-` denotes the range and the `^` denotes exclusive. For KVM memory binding, the value is like: `membind:`.`0` , restrict a guest to allocate memory from the specified set of NUMA nodes. For PCI passthrough, the value is like: `devpassthrough:pci_0001_01_00_0,pci_0000_03_00_0`, the value for PCI device format also can be like: `devpassthrough:0001:01:00.1`, the PCI devices are assigned to a virtual machine, and the virtual machine can use this I/O exclusively, the devices list are a list of PCI device names delimited with comma, the PCI device names can be obtained by running `virsh nodedev-list` on the host.

**dockerhost (vm.host)**

The system that currently hosts the VM

**dockermemory (vm.memory)**

Megabytes of memory the VM currently should be set to.

**dockernics (vm.nics)**

Network configuration parameters. Of the general form [physnet:]interface... Generally, interface describes the vlan entity (default for native, tagged for tagged, vl[number] for a specific vlan. physnet is a virtual switch name or port description that is used for some virtualization technologies to construct virtual switches. hypervisor.netmap can map names to hypervisor specific layouts, or the descriptions described there may be used directly here where possible.

**domainadminpassword (domain.adminpassword)**

Allow a node specific indication of Administrative user password for the domain. Most will want to ignore this in favor of passwd table.

**domainadminuser (domain.adminuser)**

Allow a node specific indication of Administrative user. Most will want to just use passwd table to indicate this once rather than by node.

**domaintype (domain.type)**

Type, if any, of authentication domain to manipulate. The only recognized value at the moment is active directory.

**getmac (nodehm.getmac)**

The method to use to get MAC address of the node with the getmac command. If not set, the mgt attribute will be used. Valid values: same as values for mgmt attribute.

**groups (nodelist.groups)**

A comma-delimited list of groups this node is a member of. Group names are arbitrary, except all nodes should be part of the `all` group. Internal group names are designated by using `<groupname>`. For example: __Unmanaged, could be the internal name for a group of nodes that is not managed by xCAT. Admins should avoid using the __ characters when defining their groups.

**hcp (ppc.hcp, zvm.hcp)**

1.3. Admin Guide 693
The hardware control point for this node (HMC, IVM, Frame or CEC). Do not need to set for BPAs and FSPs.

or

The hardware control point for this node.

**height** (nodepos.height)

The server height in U(s).

**hidden** (nodelist.hidden)

Used to hide fsp and bpa definitions, 1 means not show them when running lsdef and nodels

**hostcluster** (hypervisor.cluster)

Specify to the underlying virtualization infrastructure a cluster membership for the hypervisor.

**hostinterface** (hypervisor.interface)

The definition of interfaces for the hypervisor. The format is [network-name:interfacename:bootprotocol:IP:netmask:gateway] that split with | for each interface

**hostmanager** (hypervisor.mgr)

The virtualization specific manager of this hypervisor when applicable

**hostnames** (hosts.hostnames)

Hostname aliases added to /etc/hosts for this node. Comma or blank separated list.

**hosttype** (hypervisor.type)

The plugin associated with hypervisor specific commands such as revacuate

**hwtype** (ppc.nodetype, zvm.nodetype, mp.nodetype, mic.nodetype)

The hardware type of the node. Only can be one of fsp, bpa, cec, frame, ivm, hmc and lpar

or

The node type. Valid values: cec (Central Electronic Complex), lpar (logical partition), zvm (z/VM host operating system), and vm (virtual machine).

or

The hardware type for mp node. Valid values: mm,cmm, blade.

or

The hardware type of the mic node. Generally, it is mic.

**id** (ppc.id, mp.id)

For LPARs: the LPAR numeric id; for CECs: the cage number; for Frames: the frame number.

or

The slot number of this blade in the BladeCenter chassis.

**initrd** (bootparams.initrd)

The initial ramdisk image that network boot actions should use (could be a DOS floppy or hard drive image if using memdisk as kernel)

**installnic** (noderes.installnic)
The network adapter on the node that will be used for OS deployment, the installnic can be set to the network adapter name or the mac address or the keyword “mac” which means that the network interface specified by the mac address in the mac table will be used. If not set, primarynic will be used. If primarynic is not set too, the keyword “mac” will be used as default.

**interface** (mac.interface)

The adapter interface name that will be used to install and manage the node. E.g. eth0 (for linux) or en0 (for AIX).

**ip** (hosts.ip)

The IP address of the node. This is only used in makehosts. The rest of xCAT uses system name resolution to resolve node names to IP addresses.

**iscsipassword** (iscsipasswd)

The password for the iscsi server containing the boot device for this node.

**iscsiserver** (iscsi.server)

The server containing the iscsi boot device for this node.

**iscsitarget** (iscsi.target)

The iscsi disk used for the boot device for this node. Filled in by xCAT.

**iscsiuserid** (iscsi.userid)

The userid of the iscsi server containing the boot device for this node.

**kcmdline** (bootparams.kcmdline)

Arguments to be passed to the kernel.

**kernel** (bootparams.kernel)

The kernel that network boot actions should currently acquire and use. Note this could be a chained boot loader such as memdisk or a non-linux boot loader.

**linkports** (switches.linkports)

The ports that connect to other switches. Currently, this column is only used by vlan configuration. The format is: “port_number:switch,port_number:switch…” Refer to the switch table for details on how to specify the port numbers.

**mac** (mac.mac)

The mac address or addresses for which xCAT will manage static bindings for this node. This may be simply a mac address, which would be bound to the node name (such as “01:02:03:04:05:0E”). This may also be a “|” delimited string of “mac address!hostname” format (such as “01:02:03:04:05:0E!node5|01:02:03:04:05:0F!node6-eth1”). If there are multiple nics connected to Management Network (usually for bond), in order to make sure the OS deployment finished successfully, the macs of those nics must be able to resolve to same IP address. First, users have to create alias of the node for each mac in the Management Network through either: 1. adding the alias into /etc/hosts for the node directly or 2. setting the alias to the “hostnames” attribute and then run “makehost” against the node. Then, configure the “mac” attribute of the node like “mac1!node1_mac1|node-alias”. For the first mac address (mac1 in the example) set in “mac” attribute, do not need to set a “node name” string for it since the nodename of the node will be used for it by default.

**memory** (hwinv.memory)

The size of the memory for the node in MB.

**mgt** (nodehm.mgt)
The method to use to do general hardware management of the node. This attribute is used as the default if power or getmac is not set. Valid values: openbmc, ipmi, blade, hmc, ivm, fsp, bpa, kvm, esx, rhevm. See the power attribute for more details.

**micbridge (mic.bridge)**

The virtual bridge on the host node which the mic connected to.

**michost (mic.host)**

The host node which the mic card installed on.

**micid (mic.id)**

The device id of the mic node.

**miconboot (mic.onboot)**

Set mic to autoboot when mpss start. Valid values: yes/no. Default is yes.

**micpowermgt (mic.powermgt)**

Set the Power Management for mic node. This attribute is used to set the power management state that mic may get into when it is idle. Four states can be set: cpufreq, corec6, pc3 and pc6. The valid value for powermgt attribute should be [cpufreq<onloff>][corec6<onloff>][pc3<onloff>][pc6<onloff>]. e.g. cpufreq=on!corec6=off!pc3=on!pc6=off. Refer to the doc of mic to get more information for power management.

**micvlog (mic.vlog)**

Set the Verbose Log to console. Valid values: yes/no. Default is no.

**migrationdest (vm.migrationdest)**

A noderange representing candidate destinations for migration (i.e. similar systems, same SAN, or other criteria that xCAT can use)

**monserver (noderes.monserver)**

The monitoring aggregation point for this node. The format is “x,y” where x is the ip address as known by the management node and y is the ip address as known by the node.

**mpa (mp.mpa)**

The management module used to control this blade.

**mtm (vpd.mtm)**

The machine type and model number of the node. E.g. 7984-6BU

**nameservers (noderes.nameservers)**

An optional node/group specific override for name server list. Most people want to stick to site or network defined nameserver configuration.

**netboot (noderes.netboot)**

The type of network booting to use for this node. Valid values:

<table>
<thead>
<tr>
<th>Arch</th>
<th>OS</th>
<th>Valid netboot options</th>
</tr>
</thead>
<tbody>
<tr>
<td>x86, x86_64</td>
<td>ALL</td>
<td>pxe, xnba</td>
</tr>
<tr>
<td>ppc64</td>
<td>&lt;=rhel6, &lt;=sles11.3</td>
<td>yaboot</td>
</tr>
<tr>
<td>ppc64</td>
<td>&gt;=rhel7, &gt;=sles11.4</td>
<td>grub2,grub2-http,grub2-</td>
</tr>
<tr>
<td></td>
<td>tftp</td>
<td></td>
</tr>
<tr>
<td>ppc64le</td>
<td>ALL</td>
<td>petitboot</td>
</tr>
<tr>
<td>ppc64le</td>
<td>PowerKVM Guest</td>
<td>grub2,grub2-http,grub2-</td>
</tr>
<tr>
<td></td>
<td>tftp</td>
<td></td>
</tr>
</tbody>
</table>

(continues on next page)
nfsdir (noderes.nfsdir)
The path that should be mounted from the NFS server.
nfsserver (noderes.nfsserver)
The NFS or HTTP server for this node (as known by this node).
nicaliases (nics.nicaliases)
Comma-separated list of hostname aliases for each NIC.
Format: eth0!<alias list>,eth1!<alias1 list>|<alias2 list>  For multiple aliases per nic use a space-separated list.
For example: eth0!moe larry curly,eth1!tomjerry

niccustomscripts (nics.niccustomscripts)
Comma-separated list of custom scripts per NIC. <nic1>!<script1>,<nic2>!<script2>, e.g. eth0!configeth
eth0, ib0!configib ib0. The xCAT object definition commands support to use niccustomscripts.<nicname>
as the sub attribute.
nicdevices (nics.nicdevices)
Comma-separated list of NIC device per NIC, multiple ethernet devices can be bonded as bond
device, these ethernet devices are separated by |.  <nic1>!<dev1>|<dev3>,<nic2>!<dev2>, e.g.
bond0!eth0|eth2,br0!bond0. The xCAT object definition commands support to use nicdevices.<nicname>
as the sub attributes.
nicextraparams (nics.nicextraparams)
Comma-separated list of extra parameters that will be used for each NIC configuration.
If only one ip address is associated with each NIC: <nic1>!<param1=value1
param2=value2>,<nic2>!<param3=value3>, for example, eth0!MTU=1500,ib0!MTU=65520 CONNECTED_MODE=yes.
If multiple ip addresses are associated with each NIC: <nic1>!<param1=value1
param2=value2>,<nic2>!<param3=value3>,<nic2>!<param4=value4
param5=value5>,<param6=value6>, for example, eth0!MTU=1500MTU=1460,ib0!MTU=65520 CONNECTED_MODE=yes.
The xCAT object definition commands support to use nicextraparams.<nicname> as the sub attributes.
nichostnameprefixes (nics.nichostnameprefixes)
Comma-separated list of hostname prefixes per NIC.
If only one ip address is associated with each NIC: <nic1>!<ext1>,<nic2>!<ext2>..., for ex-
ample, eth0|eth0-ib0|ib-
If multiple ip addresses are associated with each NIC: <nic1>!<ext1>,<ext2>,<nic2>!<ext1>,<ext2>..., for example, eth0|eth0-ipv6|ib-ipv6-.
The xCAT object definition commands support to use nichostnameprefixes.<nicname> as the sub attributes. Note: According to DNS rules a hostname must be a text string up to 24 characters drawn
from the alphabet (A-Z), digits (0-9) and minus sign (-). When you are specifying “nichostnamepre-
fixes” or “nicaliases” make sure the resulting hostnames will conform to this naming convention.
nichostnamesuffixes (nics.nichostnamesuffixes)
Comma-separated list of hostname suffixes per NIC.

If only one IP address is associated with each NIC: `<nic1>!<ext1>,<nic2>!<ext2>,..., for example, eth0!-eth0,ib0!-ib0`

If multiple IP addresses are associated with each NIC: `<nic1>!<ext1>!<ext2>,<nic2>!<ext1>!<ext2>,..., for example, eth0!-eth0-ipv6,ib0!-ib0-ipv6.`

The xCAT object definition commands support to use `nichostnamesuffixes.<nicname>` as the sub attributes.

Note: According to DNS rules a hostname must be a text string up to 24 characters drawn from the alphabet (A-Z), digits (0-9) and minus sign (-).

When you are specifying "nichostnamesuffixes" or "nicaliases" make sure the resulting hostnames will conform to this naming convention.

nicips (nics.nicips)

Comma-separated list of IP addresses per NIC.

To specify one IP address per NIC: `<nic1>!<ip1>,<nic2>!<ip2>,..., for example, eth0!10.0.0.100,ib0!11.0.0.100`

To specify multiple IP addresses per NIC: `<nic1>!<ip1>!<ip2>,<nic2>!<ip1>!<ip2>,..., for example, eth0!10.0.0.100::5eff:fe15:849b,ib0!11.0.0.100::5eff:fe15:849a.`

The xCAT object definition commands support to use `nicips.<nicname>` as the sub attributes.

Note: The primary IP address must also be stored in the `hosts.ip` attribute. The `nichostnamesuffixes` should specify one hostname suffix for each IP address.

nicnetworks (nics.nicnetworks)

Comma-separated list of networks connected to each NIC.

If only one IP address is associated with each NIC: `<nic1>!<network1>,<nic2>!<network2>, for example, eth0!10_0_0_0-255_255_0_0, ib0!11_0_0_0-255_255_0_0`

If multiple IP addresses are associated with each NIC: `<nic1>!<network1>!<network2>,<nic2>!<network1>!<network2>, for example, eth0!10_0_0_0-255_255_0_0::5eff:fe15:849b,ib0!11_0_0_0-255_255_0_0::5eff:fe15:849a.`

The xCAT object definition commands support to use `nicnetworks.<nicname>` as the sub attributes.

nicsadapter (nics.nicsadapter)

Comma-separated list of NIC information collected by `getadapter`. `<nic1>!<param1=value1 param2=value2>,<nic2>!<param4=value4 param5=value5>, for example, enP3p3s0f1!mac=98:be:94:59:fa:cd linkstate=DOWN,enP3p3s0f2!mac=98:be:94:59:fa:ce candidatename=enP3p3s0f2/enx98be9459face`

nictypes (nics.nictypes)

Comma-separated list of NIC types per NIC. `<nic1>!<type1>,<nic2>!<type2>, e.g. eth0!Ethernet,ib0!Infiniband.`

The xCAT object definition commands support to use `nictypes.<nicname>` as the sub attributes.

nimserver (noderes.nimserver)

Not used for now. The NIM server for this node (as known by this node).

node (nodelist.node)

The hostname of a node in the cluster.

nodetype (nodetype.nodetype, pdu.nodetype)

Chapter 1. Table of Contents
A comma-delimited list of characteristics of this node. Valid values: ppc, blade, vm (virtual machine), osi (OS image), mm, mn, rsa, switch.

or

The node type should be pdu

ondiscover (chain.ondiscover)

This attribute is currently not used by xCAT. The “ondiscover” operation is always done during node discovery.

os (nodetype.os)

The operating system deployed on this node. Valid values: AIX, rhels*, rhelc*, rhas*, centos*, SL*, fedora*, sles* (where * is the version #). As a special case, if this is set to “boottarget”, then it will use the initrd/kernel/parameters specified in the row in the boottarget table in which boottarget.bprofile equals nodetype.profile.

osvolume (storage.osvolume)

Specification of what storage to place the node OS image onto. Examples include:

- localdisk (Install to first non-FC attached disk)
- usbdisk (Install to first USB mass storage device seen)
- wwn=0x50000393c813840c (Install to storage device with given WWN)

otherinterfaces (hosts.otherinterfaces)

Other IP addresses to add for this node. Format: -<ext>:<ip>,<intfhostname>:<ip>,... 

ou (domain.ou)

For an LDAP described machine account (i.e. Active Directory), the organizational unit to place the system. If not set, defaults to cn=Computers,dc=your,dc=domain

outlet (pdu.outlet)

The pdu outlet count

parent (ppc.parent)

For LPARs: the CEC; for FSPs: the CEC; for CEC: the frame (if one exists); for BPA: the frame; for frame: the building block number (which consists 1 or more service nodes and compute/storage nodes that are serviced by them - optional).

passwd.HMC (ppcdirect.password)

Password of the FSP/BPA(for ASMI) and CEC/Frame(for DFM). If not filled in, xCAT will look in the passwd table for key=fsp. If not in the passwd table, the default used is admin.

passwd.admin (ppcdirect.password)

Password of the FSP/BPA(for ASMI) and CEC/Frame(for DFM). If not filled in, xCAT will look in the passwd table for key=fsp. If not in the passwd table, the default used is admin.

passwd.celogin (ppcdirect.password)

Password of the FSP/BPA(for ASMI) and CEC/Frame(for DFM). If not filled in, xCAT will look in the passwd table for key=fsp. If not in the passwd table, the default used is admin.

passwd.general (ppcdirect.password)

Password of the FSP/BPA(for ASMI) and CEC/Frame(for DFM). If not filled in, xCAT will look in the passwd table for key=fsp. If not in the passwd table, the default used is admin.
passwd.hscroot (ppcdirect.password)

Password of the FSP/BPA (for ASMI) and CEC/Frame (for DFM). If not filled in, xCAT will look in the passwd table for key=fsp. If not in the passwd table, the default used is admin.

password (pphcp.password, mpa.password, webserv.password, pdu.password, switches.sshpassword)

Password of the HMC or IVM. If not filled in, xCAT will look in the passwd table for key=hmc or key=ivm. If not in the passwd table, the default used is abc123 for HMCs and padmin for IVMs.

or
Password to use to access the management module. If not specified, the key=blade row in the passwd table is used as the default.

or
Password to use to access the web service.

or
The remote login password

or
The remote login password. It can be for ssh or telnet. If it is for telnet, set protocol to “telnet”. If the sshusername is blank, the username, password and protocol will be retrieved from the passwd table with “switch” as the key.

pdu (pduoutlet.pdu)

a comma-separated list of outlet number for each PDU, ex: pdu1:outlet1,pdu2:outlet1

pdutype (pdu.pdutype)

The type of pdu

postbootscripts (postscripts.postbootscripts)

Comma separated list of scripts that should be run on this node after diskful installation or diskless boot. Each script can take zero or more parameters. For example: “script1 p1 p2,script2,...”. On AIX these scripts are run during the processing of /etc/inittab. On Linux they are run at the init.d time. xCAT automatically adds the scripts in the xcatdefaults.postbootscripts attribute to run first in the list. Please note that the postbootscripts specified for “xcatdefaults” will be assigned to node automatically, they can not be removed from “postbootscripts” attribute of a node with “chdef -m” command

postscripts (postscripts.postscripts)

Comma separated list of scripts that should be run on this node after diskful installation or diskless boot. Each script can take zero or more parameters. For example: “script1 p1 p2,script2,...”. xCAT automatically adds the postscripts from the xcatdefaults.postscripts attribute of the table to run first on the nodes after install or diskless boot. For installation of RedHat, CentOS, Fedora, the scripts will be run before the reboot. For installation of SLES, the scripts will be run after the reboot but before the init.d process. For diskless deployment, the scripts will be run at the init.d time, and xCAT will automatically add the list of scripts from the postbootscripts attribute to run after postscripts list. For installation of AIX, the scripts will run after the reboot and acts the same as the postbootscripts attribute. For AIX, use the postbootscripts attribute. Please note that the postscripts specified for “xcatdefaults” will be assigned to node automatically, they can not be removed from “postscripts” attribute of a node with “chdef -m” command

power (nodehm.power)

The method to use to control the power of the node. If not set, the mgt attribute will be used. Valid values: ipmi, blade, hmc, ivm, fsp, kvm, esx, rhevm. If “ipmi”, xCAT will search for this node in the ipmi table
for more info. If “blade”, xCAT will search for this node in the mp table. If “hmc”, “ivm”, or “fsp”, xCAT will search for this node in the ppc table.

**pprofile (ppc.pprofile)**

The LPAR profile that will be used the next time the LPAR is powered on with rpower. For DFM, the pprofile attribute should be set to blank

**prescripts-begin (prescripts.begin)**

The scripts to be run at the beginning of the nodeset(Linux), nimnodeset(AIX) or mkdsklsnode(AIX) command.

The format is: [action1:][s1,s2…][| action2:s3,s4,s5…]

where:

- action1 and action2 for Linux are the nodeset actions specified in the command. For AIX, action1 and action1 can be ‘diskless’ for mkdsklsnode command’ and ‘standalone for nimnodeset command.
- s1 and s2 are the scripts to run for action1 in order.
- s3, s4, and s5 are the scripts to run for actions2.

If actions are omitted, the scripts apply to all actions. Examples:

```
myscript1,myscript2 (all actions) diskless:myscript1,myscript2 (AIX) in-
stall:myscript1,myscript2|netboot:myscript3 (Linux)
```

All the scripts should be copied to /install/prescripts directory. The following two environment variables will be passed to each script:

- NODES a coma separated list of node names that need to run the script for ACTION current nodeset action.

If ‘#xCAT setting:MAX_INSTANCE=number’ is specified in the script, the script will get invoked for each node in parallel, but no more than number of instances will be invoked at at a time. If it is not specified, the script will be invoked once for all the nodes.

**prescripts-end (prescripts.end)**

The scripts to be run at the end of the nodeset(Linux), nimnodeset(AIX),or mkdsklsnode(AIX) command. The format is the same as the ‘begin’ column.

**primarynic (noderes.primarynic)**

This attribute will be deprecated. All the used network interface will be determined by installnic. The network adapter on the node that will be used for xCAT management, the primarynic can be set to the network adapter name or the mac address or the keyword “mac” which means that the network interface specified by the mac address in the mac table will be used. Default is eth0.

**primarysn (nodelist.primarysn)**

Not used currently. The primary servicenode, used by this node.

**privkey (pdu.privkey)**

The privacy passphrase to use for SNMPv3.

**privtype (pdu.privtype)**

The privacy protocol(AESIDES) to use for SNMPv3.

**productkey (prodkey.key)**

The product key relevant to the aforementioned node/group and product combination
**profile (nodetype.profile)**

The string to use to locate a kickstart or autoyast template to use for OS deployment of this node. If the provmethod attribute is set to an osimage name, that takes precedence, and profile need not be defined. Otherwise, the os, profile, and arch are used to search for the files in /install/custom first, and then in /opt/xcat/share/xcat.

**protocol (switches.protocol)**

Protocol for running remote commands for the switch. The valid values are: ssh, telnet. ssh is the default. If the sshusername is blank, the username, password and protocol will be retrieved from the passwd table with “switch” as the key. The passwd.comments attribute is used for protocol.

**provmethod (nodetype.provmethod)**

The provisioning method for node deployment. The valid values are install, netboot, statelite or an os image name from the osimage table. If an image name is specified, the osimage definition stored in the osimage table and the linuximage table (for Linux) or nimimage table (for AIX) are used to locate the files for templates, pkglists, syncfiles, etc. On Linux, if install, netboot or statelite is specified, the os, profile, and arch are used to search for the files in /install/custom first, and then in /opt/xcat/share/xcat.

**rack (nodepos.rack)**

The frame the node is in.

**room (nodepos.room)**

The room where the node is located.

**routenames (noderes.routenames)**

A comma separated list of route names that refer to rows in the routes table. These are the routes that should be defined on this node when it is deployed.

**seclevel (pdu.seclevel)**

The Security Level(noAuthNoPriv|authNoPriv|authPriv) to use for SNMPv3.

**serial (vpd.serial)**

The serial number of the node.

**serialflow (nodehm.serialflow)**

The flow control value of the serial port for this node. For SOL this is typically ‘hard’. 

**serialport (nodehm.serialport)**

The serial port for this node, in the linux numbering style (0=COM1/ttyS0, 1=COM2/ttyS1). For SOL on IBM blades, this is typically 1. For rackmount IBM servers, this is typically 0.

**serialspeed (nodehm.serialspeed)**

The speed of the serial port for this node. For SOL this is typically 19200.

**servicenode (noderes.servicenode)**

A comma separated list of node names (as known by the management node) that provides most services for this node. The first service node on the list that is accessible will be used. The 2nd node on the list is generally considered to be the backup service node for this node when running commands like snmove.

**setupconserver (servicenode.conserver)**

Do we set up console service on this service node? Valid values: 0, 1, or 2. If 0, it does not change the current state of the service. If 1, configures and starts conserver daemon. If 2, configures and starts goconserver daemon.
**setupdhcp** (servicenode.dhcpserver)

Do we set up DHCP on this service node? Not supported on AIX. Valid values: 1 or 0. If 1, runs makedhcp -n. If 0, it does not change the current state of the service.

**setupftp** (servicenode.ftpsserver)

Do we set up a ftp server on this service node? Not supported on AIX. Valid values: 1 or 0. If 1, configure and start vsftpd. (You must manually install vsftpd on the service nodes before this.) If 0, it does not change the current state of the service. xCAT is not using ftp for compute nodes provisioning or any other xCAT features, so this attribute can be set to 0 if the ftp service will not be used for other purposes.

**setupipforward** (servicenode.ipforward)

Do we set up ip forwarding on this service node? Valid values: 1 or 0. If 0, it does not change the current state of the service.

**setupldap** (servicenode.ldapserver)

Do we set up ldap caching proxy on this service node? Not supported on AIX. Valid values: 1 or 0. If 0, it does not change the current state of the service.

**setupnameserver** (servicenode.nameserver)

Do we set up DNS on this service node? Valid values: 2, 1, or 0. If 2, creates named.conf as dns slave, using the management node as dns master, and starts named. If 1, creates named.conf file with forwarding to the management node and starts named. If 0, it does not change the current state of the service.

**setupnfs** (servicenode.nfsserver)

Do we set up file services (HTTP, FTP, or NFS) on this service node? For AIX will only setup NFS, not HTTP or FTP. Valid values: 1 or 0. If 0, it does not change the current state of the service.

**setupnim** (servicenode.nimserver)

Not used. Do we set up a NIM server on this service node? Valid values: 1 or 0. If 0, it does not change the current state of the service.

**setupntp** (servicenode.ntpserver)

Not used. Use setupntp postscript to setup a ntp server on this service node? Valid values: 1 or 0. If 0, it does not change the current state of the service.

**setupproxydhcp** (servicenode.proxydhcp)

Do we set up proxydhcp service on this node? valid values: 1 or 0. If 1, the proxydhcp daemon will be enabled on this node.

**setupftp** (servicenode.tftpsserver)

Do we set up TFTP on this service node? Not supported on AIX. Valid values: 1 or 0. If 1, configures and starts atftp. If 0, it does not change the current state of the service.

**sfp** (ppc.sfp)

The Service Focal Point of this Frame. This is the name of the HMC that is responsible for collecting hardware service events for this frame and all of the CECs within this frame.

**side** (vpd.side)


\(<\text{BPA}>\text{-}<\text{port}>\) or \(<\text{FSP}>\text{-}<\text{port}>\). The side information for the BPA/FSP. The side attribute refers to which BPA/FSP, A or B, which is determined by the slot value returned from lsslp command. It also lists the physical port within each BPA/FSP which is determined by the IP address order from the lsslp response. This information is used internally when communicating with the BPAs/FSPs.

**slot** (nodepos.slot)
The slot number of the blade in the chassis. For PCM, a comma-separated list of slot numbers is stored

**slotid** (mp.id)

The slot number of this blade in the BladeCenter chassis.

**slots** (mpa.slots)

The number of available slots in the chassis. For PCM, this attribute is used to store the number of slots in the following format: `<slot rows>,<slot columns>,<slot orientation>` Where:

| `<slot rows>` | = number of rows of slots in chassis |
| `<slot columns>` | = number of columns of slots in chassis |
| `<slot orientation>` | = set to 0 if slots are vertical, and set to 1 if slots of horizontal |

**snmpauth** (switches.auth)

The authentication protocol to use for SNMPv3. SHA is assumed if v3 enabled and this is unspecified

**snmppassword** (switches.password)

The password string for SNMPv3 or community string for SNMPv1/SNMPv2. Falls back to passwd table, and site snmpc value if using SNMPv1/SNMPv2.

**snmpprivacy** (switches.privacy)

The privacy protocol to use for v3. xCAT will use authNoPriv if this is unspecified. DES is recommended to use if v3 enabled, as it is the most readily available.

**snmpuser** (pdu.snmpuser)

The username to use for SNMPv3 communication, ignored for SNMPv1

**snmpusername** (switches.username)

The username to use for SNMPv3 communication, ignored for SNMPv1

**snmpversion** (pdu.snmpversion, switches.snmpversion)

The version to use to communicate with switch. SNMPv1 is assumed by default. or

The version to use to communicate with switch. SNMPv1 is assumed by default.

**status** (nodelist.status)

The current status of this node. This attribute will be set by xCAT software. Valid values: defined, booting, netbooting, booted, discovering, configuring, installing, alive, standingby, powering-off, unreachable. If blank, defined is assumed. The possible status change sequences are: For installation: defined->[discovering]->[configuring]->[standingby]->installing->booting->[postbooting]->booted->[alive]. For diskless deployment: defined->[discovering]->[configuring]->[standingby]->netbooting->[postbooting]->booted->[alive]. For booting: [alive/unreachable]->booting->[postbooting]->booted->[alive]. For powering off: [alive]->powering-off->[unreachable]. For monitoring: alive->unreachable. Discovering and configuring are for x Series discovery process. Alive and unreachable are set only when there is a monitoring plug-in start monitor the node status for xCAT. Note that the status values will not reflect the real node status if you change the state of the node from outside of xCAT (i.e. power off the node using HMC GUI).

**statustime** (nodelist.statustime)

The data and time when the status was updated.

**storagcontroller** (storage.controller)
The management address to attach/detach new volumes. In the scenario involving multiple controllers, this data must be passed as argument rather than by table value.

**storage_type** *(storage.type)*

The plugin used to drive storage configuration (e.g. svc)

**supernode** *(ppc.supernode)*

Indicates the connectivity of this CEC in the HFI network. A comma separated list of 2 ids. The first one is the supernode number the CEC is part of. The second one is the logical location number (0-3) of this CEC within the supernode.

**supported_archs** *(nodetype.supportedarchs)*

Comma delimited list of architectures this node can execute.

**support_proxy_dhcp** *(noderes.proxydhcp)*

To specify whether the node supports proxydhcp protocol. Valid values: yes or 1, no or 0. Default value is yes.

**switch** *(switch.switch)*

The switch hostname.

**switch_interface** *(switch.interface)*

The interface name from the node perspective. For example, eth0. For the primary nic, it can be empty, the word “primary” or “primary:ethx” where ethx is the interface name.

**switch_port** *(switch.port)*

The port number in the switch that this node is connected to. On a simple 1U switch, an administrator can generally enter the number as printed next to the ports, and xCAT will understand switch representation differences. On stacked switches or switches with line cards, administrators should usually use the CLI representation (i.e. 2/0/1 or 5/8). One notable exception is stacked SMC 8848M switches, in which you must add 56 for the proceeding switch, then the port number. For example, port 3 on the second switch in an SMC8848M stack would be 59.

**switch_type** *(switches.switchtype)*

The type of switch. It is used to identify the file name that implements the functions for this switch. The valid values are: Mellanox, Cisco, BNT and Juniper.

**switch_vlan** *(switch.vlan)*

The ID for the tagged vlan that is created on this port using mkvlan and chvlan commands.

**syslog** *(noderes.syslog)*

To configure how to configure syslog for compute node. Valid values: blank(not set), ignore. blank - run postscript syslog; ignore - do NOT run postscript syslog

**term_port** *(nodehm.termport)*

The port number on the terminal server that this node is connected to.

**term_server** *(nodehm.termserver)*

The hostname of the terminal server.

**tftp_dir** *(noderes.tftpdir)*

The directory that roots this nodes contents from a tftp and related perspective. Used for NAS offload by using different mountpoints.
tftpserver (noderes.tftpserver)

The TFTP server for this node (as known by this node). If not set, it defaults to networks.tftpserver.

unit (nodepos.u)

The vertical position of the node in the frame

updatestatus (nodelist.updatestatus)

The current node update status. Valid states are synced, out-of-sync, syncing, failed.

updatestatustime (nodelist.updatestatustime)

The date and time when the updatestatus was updated.

urlpath (mpa.urlpath)

URL path for the Chassis web interface. The full URL is built as follows: <hostname>/<urlpath>

usercomment (nodelist.comments)

Any user-written notes.

userid (zvm.userid)

The z/VM userID of this node.

username (ppchcp.username, mpa.username, websrv.username, pdu.username, switches.sshusername)

Userid of the HMC or IVM. If not filled in, xCAT will look in the passwd table for key=hmc or key=ivm. If not in the passwd table, the default used is hscroot for HMCs and padmin for IVMs.

or

Userid to use to access the management module.

or

Userid to use to access the web service.

or

The remote login user name

or

The remote login user name. It can be for ssh or telnet. If it is for telnet, set protocol to “telnet”. If the sshusername is blank, the username, password and protocol will be retrieved from the passwd table with “switch” as the key.

vmbeacon (vm.beacon)

This flag is used by xCAT to track the state of the identify LED with respect to the VM.

vmbootorder (vm.bootorder)

Boot sequence (i.e. net,hd)

vmcfgstore (vm.cfgstore)

Optional location for persistent storage separate of emulated hard drives for virtualization solutions that require persistent store to place configuration data

vmcluster (vm.cluster)

Specify to the underlying virtualization infrastructure a cluster membership for the hypervisor.

vmcpus (vm(cpus)
Number of CPUs the node should see.

**vmhost** (vm.host)

The system that currently hosts the VM

**vmmanager** (vm.mgr)

The function manager for the virtual machine

**vmmaster** (vm.master)

The name of a master image, if any, this virtual machine is linked to. This is generally set by clonevm and indicates the deletion of a master that would invalidate the storage of this virtual machine

**vmmemory** (vm.memory)

Megabytes of memory the VM currently should be set to.

**vmnicnicmodel** (vm.nicmodel)

Model of NICs that will be provided to VMs (i.e. e1000, rtl8139, virtio, etc)

**vmnics** (vm.nics)

Network configuration parameters. Of the general form [physnet:]interface,... Generally, interface describes the vlan entity (default for native, tagged for tagged, vl[number] for a specific vlan. phsysnet is a virtual switch name or port description that is used for some virtualization technologies to construct virtual switches. hypervisor.netmap can map names to hypervisor specific layouts, or the descriptions described there may be used directly here where possible.

**vmothersetting** (vm.othersettings)

This allows specifying a semicolon delimited list of key->value pairs to include in a vmx file of VMware or KVM. For partitioning on normal power machines, this option is used to specify the hugepage and/or bsr information, the value is like:'hugepage:1,bsr=2'. For KVM cpu pinning, this option is used to specify the physical cpu set on the host, the value is like:'vcputin:0-15,^8'. Its syntax is a comma separated list and a special markup using ‘-’ and ‘^’ (ex. ‘0-4’, ‘0-3,^2’) can also be allowed, the ‘-‘ denotes the range and the ‘^’ denotes exclusive. For KVM memory binding, the value is like:'membind:0', restrict a guest to allocate memory from the specified set of NUMA nodes. For PCI passthrough, the value is like:'devpassthrough:pci_0001_01_00_0,pci_0000_03_00_0', the value for PCI device format also can be like:'devpassthrough:0001:01:00.1', the PCI devices are assigned to a virtual machine, and the virtual machine can use this I/O exclusively, the devices list are a list of PCI device names delimited with comma, the PCI device names can be obtained by running `virsh nodedev-list` on the host.

**vmphyslots** (vm.physlots)

Specify the physical slots drc index that will assigned to the partition, the delimiter is ‘,’ and the drc index must started with ‘0x’. For more details, reference manpage for ‘lsvm’.

**vmstorage** (vm.storage)

A list of storage files or devices to be used. i.e. dir://cluster/vm/<nodename> or nfs://<server>/path/to/folder/

**vmstoragecache** (vm.storagecache)

Select caching scheme to employ. E.g. KVM understands ‘none’, ‘writethrough’ and ‘writeback’

**vmstorageformat** (vm.storageformat)

Select disk format to use by default (e.g. raw versus qcow2)

**vmstoragemodel** (vm.storagemodel)

Model of storage devices to provide to guest
vmtextconsole (vm.textconsole)

Tracks the Psuedo-TTY that maps to the serial port or console of a VM

vmvirtflags (vm.virtflags)

General flags used by the virtualization method.

For example, in Xen it could, among other things, specify paravirtualized setup, or direct kernel boot. For a hypervisor/dom0 entry, it is the virtualization method (i.e. "xen"). For KVM, the following flag=value pairs are recognized:

- **imageformat**=[raw|fullraw|qcow2] raw is a generic sparse file that allocates storage on demand. fullraw is a generic, non-sparse file that preallocates all space. qcow2 is a sparse, copy-on-write capable format implemented at the virtualization layer rather than the filesystem level.

- **clonemethod**=[qemu-img|reflink] qemu-img allows use of qcow2 to generate virtualization layer copy-on-write. reflink uses a generic filesystem facility to clone the files on your behalf, but requires filesystem support such as btrfs.

- placement_affinity=[migratable|user_migratable|pinned]

vmvncport (vm.vncport)

Tracks the current VNC display port (currently not meant to be set)

webport (websrv.port)

The port of the web service.

xcatmaster (noderes.xcatmaster)

The hostname of the xCAT service node (as known by this node). This acts as the default value for nfsserver and tftpserver, if they are not set. If xcatmaster is not set, the node will use whoever responds to its boot request as its master. For the directed bootp case for POWER, it will use the management node if xcatmaster is not set.

zonename (nodelist.zonename)

The name of the zone to which the node is currently assigned. If undefined, then it is not assigned to any zone.

SEE ALSO

mkdef(1), chdef(1), lsdef(1), rmdef(1)

notification.7

NAME

notification - a logical object definition in the xCAT database.

SYNOPSIS

notification Attributes: comments, filename, tableops, tables
DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: **mkdef**, **chdef**, **lsdef**, and **rmdef**. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

**notification Attributes:**

- **comments** (notification.comments)
  Any user-written notes.
- **filename** (notification.filename)
  The path name of a file that implements the callback routine when the monitored table changes. Can be a perl module or a command. See the regnotif man page for details.
- **tableops** (notification.tableops)
  Specifies the table operation to monitor for. Valid values: “d” (rows deleted), “a” (rows added), “u” (rows updated).
- **tables** (notification.tables)
  Comma-separated list of xCAT database tables to monitor.

SEE ALSO

**mkdef(1)**, **chdef(1)**, **lsdef(1)**, **rmdef(1)**

osdistro.7

NAME

osdistro - a logical object definition in the xCAT database.

SYNOPSIS

osdistro Attributes: arch, basename, dirpaths, majorversion, minorversion, osdistriname, type

DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: **mkdef**, **chdef**, **lsdef**, and **rmdef**. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.
osdistro Attributes:

arch (osdistro.arch)
   The OS distro arch (e.g. x86_64)
basename (osdistro.basename)
   The OS base name (e.g. rhels)
dirpaths (osdistro.dirpaths)
   Directory paths where OS distro is store. There could be multiple paths if OS distro has more than one
   ISO image. (e.g. /install/rhels6.2/x86_64, . . . )
majorversion (osdistro.majorversion)
   The OS distro major version. (e.g. 6)
minorversion (osdistro.minorversion)
   The OS distro minor version. (e.g. 2)
osdistroname (osdistro.osdistroname)
   Unique name (e.g. rhels6.2-x86_64)
type (osdistro.type)
   Linux or AIX

SEE ALSO

mkdef(1), chdef(1), lsdef(1), rmdef(1)

osdistrouupdate.7

NAME

osdistrouupdate - a logical object definition in the xCAT database.

SYNOPSIS

osdistrouupdate Attributes: dirpath, downloadtime, osdistroname, osupdatename, usercomment

DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to
manipulate the objects: mkdef, chdef, lsdef, and rmdef. These commands will take care of knowing which tables the
object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.
**osdistroupdate Attributes:**

**dirpath** (osdistroupdate.dirpath)
Path to where OS distro update is stored. (e.g. /install/osdistroupdates/rhels6.2-x86_64-20120716-update)

**downloadtime** (osdistroupdate.downloadtime)
The timestamp when OS distro update was downloaded..

**osdistroname** (osdistroupdate.osdistroname)
The OS distro name to update. (e.g. rhels)

**osupdatename** (osdistroupdate.osupdatename)
Name of OS update. (e.g. rhn-update1)

**usercomment** (osdistroupdate.comments)
Any user-written notes.

**SEE ALSO**

mkdef(1), chdef(1), lsdef(1), rmdef(1)

osimage.7

**NAME**

osimage - a logical object definition in the xCAT database.

**SYNOPSIS**

**osimage Attributes:** addkcmdline, boottarget, bosinst_data, cfmdir, configdump, crashkernelsize, description, drivereupdatesrc, dump, environvar, elist, fb_script, groups, home, image_data, imagename, imagetype, installp_bundle, installto, isdeletable, kerneldir, kernelver, kitcomponents, krpmver, lpp_source, mksysb, netdrivers, nimmethod, nintype, nodebootif, osarch, osdistroname, osname, osupdatename, osvers, otherifce, otherpkgdir, otherpkglist, otherpkgsgs, paging, partitionfile, permission, pkgdir, pkglist, postbootscripts, postinstall, postscripts, profile, provmethod, resolv_conf, root, rootfsftype, rootimgdir, script, serverrole, shared_home, shared_root, spot, synclists, template, tmp, usercomment, winpepath

**DESCRIPTION**

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: mkdef, chdef, lsdef, and rmdef. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.
osimage Attributes:

**addkcmdline** (linuximage.addkcmdline)
User specified kernel options for os provision process(no prefix) or the provisioned os(with prefix “R::”).
The options should be delimited with spaces(“ ”). This attribute is ignored if linuximage.boottarget is set.

**boottarget** (linuximage.boottarget)
The name of the boottarget definition. When this attribute is set, xCAT will use the kernel, initrd and
kernel params defined in the boottarget definition instead of the default.

**bosinst_data** (nimimage.bosinst_data)
The name of a NIM bosinst_data resource.

**cfmdir** (osimage.cfmdir)
CFM directory name for PCM. Set to /install/osimages/<osimage name>/cfmdir by PCM.

**configdump** (nimimage.configdump)
Specifies the type of system dump to be collected. The values are selective, full, and none. The default is
selective.

**crashkernelsize** (linuximage.crashkernelsize)
the size that assigned to the kdump kernel. If the kernel size is not set, 256M will be the default value.

**description** (osimage.description)
OS Image Description

**driverupdatesrc** (linuximage.driverupdatesrc)
The source of the drivers which need to be loaded during the boot. Two types of driver update source
are supported: Driver update disk and Driver rpm package. The value for this attribute should be comma
separated sources. Each source should be the format tab:full_path_of_source_file. The tab keyword can
be: dud (for Driver update disk) and rpm (for driver rpm). If missing the tab, the rpm format is the default.
e.g. dud:/install/dud/dd.img,rpm:/install/rpm/d.rpm

**dump** (linuximage.dump, nimimage.dump)
The NFS directory to hold the Linux kernel dump file (vmcore) when the node with this image crashes, its
format is “nfs://<nfs_server_ip>/<kdump_path>”. If you want to use the node’s “xcatmaster” (its SN or
MN), <nfs_server_ip> can be left blank. For example, “nfs://<kdump_path>” means the NFS directory
to hold the kernel dump file is on the node’s SN, or MN if there’s no SN.

or

The name of the NIM dump resource.

**environvar** (osimage.environvar)
Comma delimited environment variables for the osimage

**exlist** (linuximage.exlist)
The fully qualified name of the file that stores the file names and directory names that will be excluded
from the image during packimage command. It is used for diskless image only.

**fb_script** (nimimage.fb_script)
The name of a NIM fb_script resource.

**groups** (osimage.groups)
A comma-delimited list of image groups of which this image is a member. Image groups can be used in the litefile and litetree table instead of a single image name. Group names are arbitrary.

**home** (nimimage.home)

The name of the NIM home resource.

**image_data** (nimimage.image_data)

The name of a NIM image_data resource.

**imagename** (osimage.imagename)

The name of this xCAT OS image definition.

**imagetype** (osimage.imagetype)

The type of operating system image this definition represents (linux,AIX).

**installp_bundle** (nimimage.installp_bundle)

One or more comma separated NIM installp_bundle resources.

**installto** (winimage.installto)

The disk and partition that the Windows will be deployed to. The valid format is <disk>:<partition>. If not set, default value is 0:1 for bios boot mode(legacy) and 0:3 for uefi boot mode; If setting to 1, it means 1:1 for bios boot and 1:3 for uefi boot

**isdeletable** (osimage.isdeletable)

A flag to indicate whether this image profile can be deleted. This attribute is only used by PCM.

**kerneldir** (linuximage.kerneldir)

The directory name where the 3rd-party kernel is stored. It is used for diskless image only.

**kernelver** (linuximage.kernelver)

The version of linux kernel used in the linux image. If the kernel version is not set, the default kernel in rootimgdir will be used

**kitcomponents** (osimage.kitcomponents)

List of Kit Component IDs assigned to this OS Image definition.

**krpmver** (linuximage.krpmver)

The rpm version of kernel packages (for SLES only). If it is not set, the default rpm version of kernel packages will be used.

**lpp_source** (nimimage.lpp_source)

The name of the NIM lpp_source resource.

**mksysb** (nimimage.mksysb)

The name of a NIM mksysb resource.

**netdrivers** (linuximage.netdrivers)

The ethernet device drivers of the nodes which will use this linux image, at least the device driver for the nodes’ installnic should be included

**nimmethod** (nimimage.nimmethod)

The NIM install method to use, (ex. rte, mksysb).

**nimtype** (nimimage.nimtype)
The NIM client type- standalone, diskless, or dataless.

nodebootif (linuximage.nodebootif)

The network interface the stateless/statelite node will boot over (e.g. eth0)

osarch (osimage.osarch)

The hardware architecture of this node. Valid values: x86_64, ppc64, x86, ia64.

osdistroname (osimage.osdistroname)

The name of the OS distro definition. This attribute can be used to specify which OS distro to use, instead of using the osname,osvers, and osarch attributes. For *kit commands, the attribute will be used to read the osdistro table for the osname, osvers, and osarch attributes. If defined, the osname, osvers, and osarch attributes defined in the osimage table will be ignored.

osname (osimage.osname)

Operating system name- AIX or Linux.

osupdatename (osimage.osupdatename)

A comma-separated list of OS distro updates to apply to this osimage.

osvers (osimage.osvers)

The Linux operating system deployed on this node. Valid values: rhels*,rhelc*, rhas*,centos*,SL*, fedora*, sles* (where * is the version #).

otherifce (linuximage.otherifce)

Other network interfaces (e.g. eth1) in the image that should be configured via DHCP

otherpkgdir (linuximage.otherpkgdir)

The base directory and urls of internet repos from which the non-distro packages are retrieved. Only 1 local directory is supported at present. The entries should be delimited with comma “,”. Currently, the internet repos are only supported on Ubuntu and Redhat.

otherpkglist (linuximage.otherpkglist)

The fully qualified name of the file that stores non-distro package lists that will be included in the image. It could be set to multiple paths. The multiple paths must be separated by “,”.

otherpkgs (nimimage.otherpkgs)

One or more comma separated installp or rpm packages. The rpm packages must have a prefix of ‘R:’, (ex. R:foo.rpm)

paging (nimimage.paging)

The name of the NIM paging resource.

partitionfile (linuximage.partitionfile, winimage.partitionfile)

Only available for diskful osimages and statelite osimages(localdisk enabled). The full path of the partition file or the script:

"<the absolute path of the partition file>": For diskful osimages, the partition file contains the partition definition that will be inserted directly into the template file for os installation. The syntax and format of the partition file should confirm to the corresponding OS installer of the Linux distributions(e.g. kickstart for RedHat, autoyast for SLES, pressed for Ubuntu). For statelite osimages, when the localdisk is enabled, the partition file with specific syntax and format includes the partition scheme of the local disk, please refer to the statelite documentation for details. "s:<the absolute path of the partition script>": a shell script to generate the partition file ""/tmp/partitionfile" inside the installer before the installation start. “d:<the absolute path of the disk name files>”: only available for ubuntu osimages, includes the name(s) of the disks to partition in traditional,
The path of partition configuration file. Since the partition configuration for bios boot mode and uefi boot mode are different, this configuration file can include both configurations if you need to support both bios and uefi mode. Either way, you must specify the boot mode in the configuration. Example of partition configuration file: [BIOS]xxxxxxx[UEFI]yyyyyyy. To simplify the setting, you also can set installto in partitionfile with section like [INSTALLTO]0:1

### permission (linuximage.permission)

The mount permission of /.statelite directory is used, its default value is 755

### pkgdir (linuximage.pkgdir)

The name of the directory where the distro packages are stored. It could be set to multiple paths. The multiple paths must be separated by “,”. The first path in the value of osimage.pkgdir must be the OS base pkg dir path, such as pkgdir=/install/rhels6.2/x86_64,/install/updates . In the os base pkg path, there are default repository data. And in the other pkg path(s), the users should make sure there are repository data. If not, use “createrepo” command to create them. For ubuntu, multiple mirrors can be specified in the pkgdir attribute, the mirrors must be prefixed by the protocol(http/ssh) and delimited with “,” between each other.

### pkglist (linuximage.pkglist)

The fully qualified name of the file that stores the distro packages list that will be included in the image. Make sure that if the pkgs in the pkglist have dependency pkgs, the dependency pkgs should be found in one of the pkgdir

### postbootscripts (osimage.postbootscripts)

Comma separated list of scripts that should be run on this after diskful installation or diskless boot. On AIX these scripts are run during the processing of /etc/inittab. On Linux they are run at the init.d time. xCAT automatically adds the scripts in the xcatdefaults.postbootscripts attribute to run first in the list. See the site table runbootscripts attribute.

### postinstall (linuximage.postinstall)

Supported in diskless image only. The fully qualified name of the scripts and the user-specified arguments running in non-chroot mode after the package installation but before initrd generation during genimage. If multiple scripts are specified, they should be sepearated with comma “,”. The arguments passed to each postinstall script include 4 implicit arguments(<rootimage path>,<os version>,<os arch>,<profile>) and the user-specified arguments. A set of osimage attributes are exported as the environment variables to be used in the postinstall scripts:

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>IMG_ARCH</td>
<td>The architecture of the osimage, such as &quot;ppc64le&quot;,&quot;x86_64&quot;</td>
</tr>
<tr>
<td>IMG_NAME</td>
<td>The name of the osimage, such as &quot;rhels7.3-ppc64le-netboot-compute&quot;</td>
</tr>
<tr>
<td>IMG_OSVER</td>
<td>The os release of the osimage, such as &quot;rhels7.3&quot;,&quot;sles11.4&quot;</td>
</tr>
<tr>
<td>IMG_KERNELVERSION</td>
<td>The &quot;kernelver&quot; attribute of the osimage</td>
</tr>
<tr>
<td>IMG_PROFILE</td>
<td>The profile of the osimage, such as &quot;service&quot;,&quot;compute&quot;</td>
</tr>
</tbody>
</table>

(continues on next page)
**postscripts** (osimage.postscripts)

Comma separated list of scripts that should be run on this image after diskful installation or diskless boot. For installation of RedHat, CentOS, Fedora, the scripts will be run before the reboot. For installation of SLES, the scripts will be run after the reboot but before the init.d process. For diskless deployment, the scripts will be run at the init.d time, and xCAT will automatically add the list of scripts from the postbootscripts attribute to run after postscripts list. For installation of AIX, the scripts will run after the reboot and acts the same as the postbootscripts attribute. See the site table runbootscripts attribute.

**profile** (osimage.profile)

The node usage category. For example compute, service.

**provmethod** (osimage.provmethod)

The provisioning method for node deployment. The valid values are install, netboot, statelite, boottarget, dualboot, sysclone. If boottarget is set, you must set linuximage.boottarget to the name of the boottarget definition. It is not used by AIX.

**resolv_conf** (nimimage.resolv_conf)

The name of the NIM resolv_conf resource.

**root** (nimimage.root)

The name of the NIM root resource.

**rootfstype** (osimage.rootfstype)

The filesystem type for the rootfs is used when the provmethod is statelite. The valid values are nfs or ramdisk. The default value is nfs.

**rootimgdir** (linuximage.rootimgdir)

The directory name where the image is stored. It is generally used for diskless image. It also can be used in sysclone environment to specify where the image captured from golden client is stored. In sysclone environment, rootimgdir is generally assigned to some default value by xcat, but you can specify your own store directory. Just one thing need to be noticed, wherever you save the image, the name of last level directory must be the name of image. For example, if your image name is testimage and you want to save this image under home directoy, rootimgdir should be assigned to value /home/testimage/

**script** (nimimage.script)

The name of a NIM script resource.

**serverrole** (osimage.serverrole)

The role of the server created by this osimage. Default roles: mgtnode, servicenode, compute, login, storage, utility.

**shared_home** (nimimage.shared_home)

The name of the NIM shared_home resource.

**shared_root** (nimimage.shared_root)
A shared_root resource represents a directory that can be used as a / (root) directory by one or more diskless clients.

**spot** (nimimage.spot)

The name of the NIM SPOT resource.

**synclists** (osimage.synclists)

The fully qualified name of a file containing a list of files to synchronize on the nodes. Can be a comma separated list of multiple synclist files. The synclist generated by PCM named /install/osimages/<imagename>/synclist.cfm is reserved for use only by PCM and should not be edited by the admin.

**template** (linuximage.template, winimage.template)

The fully qualified name of the template file that will be used to create the OS installer configuration file for stateful installations (e.g. kickstart for RedHat, autoyast for SLES).

or

The fully qualified name of the template file that is used to create the windows unattend.xml file for diskful installation.

**tmp** (nimimage.tmp)

The name of the NIM tmp resource.

**usercomment** (linuximage.comments, nimimage.comments)

Any user-written notes.

or

Any user-provided notes.

**winpepath** (winimage.winpepath)

The path of winpe which will be used to boot this image. If the real path is /tftpboot/winboot/winpe1/, the value for winpepath should be set to winboot/winpe1

**SEE ALSO**

mkdef(1), chdef(1), lsdef(1), rmdef(1)

**NAME**

**pdu** - a logical object definition in the xCAT database.

**SYNOPSIS**

**pdu Attributes:** node, nodetype, outlet
DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: mkdef, chdef, lsdef, and rmdef. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

pdu Attributes:

node (pdu.node)
   The hostname/address of the pdu to which the settings apply

nodetype (pdu.nodetype)
   The node type should be pdu

outlet (pdu.outlet)
   The pdu outlet count

SEE ALSO

mkdef(1), chdef(1), lsdef(1), rmdef(1)

policy.7

NAME

policy - a logical object definition in the xCAT database.

SYNOPSIS

policy Attributes: commands, host, name, noderange, parameters, priority, rule, time, usercomment

DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: mkdef, chdef, lsdef, and rmdef. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

policy Attributes:

commands (policy.commands)
   The list of commands that this rule applies to. Default is "*" (all commands).

host (policy.host)
The host from which users may issue the commands specified by this rule. Default is “*” (all hosts). Only all or one host is supported.

**name** (policy.name)

The username that is allowed to perform the commands specified by this rule. Default is “*” (all users).

**noderange** (policy.noderange)

The Noderange that this rule applies to. Default is “*” (all nodes). Not supported with the *def commands.

**parameters** (policy.parameters)

A regular expression that matches the command parameters (everything except the noderange) that this rule applies to. Default is “*” (all parameters). Not supported with the *def commands.

**priority** (policy.priority)

The priority value for this rule. This value is used to identify this policy data object (i.e. this rule) The table is sorted on this field with the lower the number the higher the priority. For example 1.0 is higher priority than 4.1 is higher than 4.9.

**rule** (policy.rule)

Specifies how this rule should be applied. Valid values are: allow, trusted. Allow will allow the user to run the commands. Any other value will deny the user access to the commands. Trusted means that once this client has been authenticated via the certificate, all other information that is sent (e.g. the username) is believed without question. This authorization should only be given to the xcatd on the management node at this time.

**time** (policy.time)

Time ranges that this command may be executed in. This is not supported.

**usercomment** (policy.comments)

Any user-written notes.

**SEE ALSO**

mkdef(1), chdef(1), lsdef(1), rmdef(1)

rack.7

**NAME**

rack - a logical object definition in the xCAT database.

**SYNOPSIS**

rack **Attributes:** displayname, height, num, rackname, room, usercomment

**DESCRIPTION**

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: **mkdef**, **chdef**, **lsdef**, and **rmdef**. These commands will take care of knowing which tables the
object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

**rack Attributes:**

- **displayname** (rack.displayname)
  Alternative name for rack. Only used by PCM.
- **height** (rack.height)
  Number of units which can be stored in the rack.
- **num** (rack.num)
  The rack number.
- **rackname** (rack.rackname)
  The rack name.
- **room** (rack.room)
  The room in which the rack is located.
- **usercomment** (rack.comments)
  Any user-written notes.

**SEE ALSO**

mkdef(1), chdef(1), lsdef(1), rmdef(1)

route.7

**NAME**

route - a logical object definition in the xCAT database.

**SYNOPSIS**

**route Attributes:** gateway, ifname, mask, net, routename, usercomment

**DESCRIPTION**

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: mkdef, chdef, lsdef, and rmdef. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.
route Attributes:

gateway (routes.gateway)
   The gateway that routes the ip traffic from the mn to the nodes. It is usually a service node.

ifname (routes.ifname)
   The interface name that facing the gateway. It is optional for IPv4 routes, but it is required for IPv6 routes.

mask (routes.mask)
   The network mask.

net (routes.net)
   The network address.

routename (routes.routename)
   Name used to identify this route.

usercomment (routes.comments)
   Any user-written notes.

SEE ALSO

mkdef(1), chdef(1), lsdef(1), rmdef(1)

site.7

NAME

site - a logical object definition in the xCAT database.

SYNOPSIS

site Attributes: installdir, master, xcatdport

DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: mkdef, chdef, lsdef, and rmdef. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

site Attributes:

installdir (site.value)
   The installation directory

master (site.value)
The management node

\textbf{xcatdport} \texttt{(site.value)}

Port used by xcatd daemon on master

\textbf{SEE ALSO}

\texttt{mkdef(1), chdef(1), lsdef(1), rmdef(1)}

\textbf{taskstate.7}

\textbf{NAME}

\texttt{taskstate} - a logical object definition in the xCAT database.

\textbf{SYNOPSIS}

\texttt{taskstate Attributes: command, disable, node, pid, reserve, state}

\textbf{DESCRIPTION}

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: \texttt{mkdef, chdef, lsdef, and rmdef}. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

\texttt{taskstate Attributes:}

\texttt{command (taskstate.command)}

Current command is running

\texttt{disable (taskstate.disable)}

Set to ‘yes’ or ‘1’ to comment out this row.

\texttt{node (taskstate.node)}

The node name.

\texttt{pid (taskstate.pid)}

The process id of the request process.

\texttt{reserve (taskstate.reserve)}

used to lock the node

\texttt{state (taskstate.state)}

The task state(callback, running) for the node.
SEE ALSO

mkdef(1), chdef(1), lsdef(1), rmdef(1)

zone.7

NAME

zone - a logical object definition in the xCAT database.

SYNOPSIS

zone Attributes: defaultzone, sshbetweennodes, sshkeydir, usercomment, zonename

DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: mkdef, chdef, lsdef, and rmdef. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

zone Attributes:

defaultzone (zone.defaultzone)

If nodes are not assigned to any other zone, they will default to this zone. If value is set to yes or 1.

sshbetweennodes (zone.sshbetweennodes)

Indicates whether passwordless ssh will be setup between the nodes of this zone. Values are yes/1 or no/0. Default is yes.

sshkeydir (zone.sshkeydir)

Directory containing the shared root ssh RSA keys.

usercomment (zone.comments)

Any user-provided notes.

zonename (zone.zonename)

The name of the zone.

SEE ALSO

mkdef(1), chdef(1), lsdef(1), rmdef(1)
NAME

zvmivp - a logical object definition in the xCAT database.

SYNOPSIS

zvmivp Attributes: **

DESCRIPTION

Logical objects of this type are stored in the xCAT database in one or more tables. Use the following commands to manipulate the objects: mkdef, chdef, lsdef, and rmdef. These commands will take care of knowing which tables the object attributes should be stored in. The attribute list below shows, in parentheses, what tables each attribute is stored in.

zvmivp Attributes:

SEE ALSO

mkdef(1), chdef(1), lsdef(1), rmdef(1)

man8

ctab.8

NAME

ctab - Add, delete or update rows in the database tables.

SYNOPSIS

ctab [-h | --help]

ctab [-v | --version]

ctab keycolname=keyvalue[keycolname=keyvalue, ...] tablename.colname=newvalue [tablename.colname=newvalue ...]

ctab keycolname=keyvalue[keycolname=keyvalue, ...] tablename.colname+=newvalue [tablename.colname+=newvalue ...]

ctab -d keycolname=keyvalue[keycolname=keyvalue, ...] tablename [tabname ...]
DESCRIPTION

The `chtab` command adds, deletes or updates the attribute values in the specified table.column for the specified key-value. Normally, the given value will completely replace the current attribute value. But if “+=” is used instead of “=”, the specified value will be appended to the comma separated list of attributes, if it is not already there.

The `chtab` does not pass through xcatd, so it is not controlled by the policy mechanism.

OPTIONS

- `-h` Display usage message.
- `-v` Command Version.
- `-d` Delete option.

RETURN VALUE

0. The command completed successfully.
1. An error has occurred.

EXAMPLES

1. To add a node=node1 to the nodelist table with groups=all:

```
chtab node=node1 nodelist.groups=all
```

2. To add a keyword (tftpdir) and value (/tftpboot) to the site table:

```
chtab key=tftpdir site.value=/tftpboot
```

3. To add node1 to the nodetype table with os=rhel5:

```
chtab node=node1 nodetype.os=rhel5
```

4. To change node1 in nodetype table setting os=sles:

```
chtab node=node1 nodetype.os=sles
```

5. To change node1 by appending otherpkgs to the postbootscripts field in the postscripts table:

```
chtab node=node1 postscripts.postbootscripts+=otherpkgs
```

6. To delete node1 from nodetype table:

```
chtab -d node=node1 nodetype
```

FILES

```
/opt/xcat/bin/chtab
```
SEE ALSO

tabdump(8)|tabdump.8, tabedit(8)|tabedit.8

copycds-cdrom.8

SYNOPSIS

copycds-cdrom [copycds options] [drive]

DESCRIPTION

copycds-cdrom is a wrapper script for copycds to copy from physical CD/DVD-ROM drives located on the management server.

[copycds options] are passed unchanged to copycds.

If [drive] is not specified, /dev/cdrom is assumed.

The copycds command copies all contents of Distribution CDs or Service Pack CDs to the install directory as designated in the site table attribute: installdir.

SEE ALSO

copycds(8)|copycds.8

AUTHOR

Isaac Freeman <ifreeman@us.ibm.com>

copycds.8

NAME

copycds - Copies Linux distributions and service levels from DVDs/ISOs to the xCAT /install directory.

SYNOPSIS

copycds [-i|--inspection] [iso | device-path]
copycds [-h|--help]
DESCRIPTION

The `copycds` command copies all contents of Distribution DVDs/ISOs or Service Pack DVDs/ISOs to a destination directory. The destination directory can be specified by the `-p` option. If no path is specified, the default destination directory will be formed from the `installdir` site table attribute, distro name and architecture, for example: `/install/rhel6.3/x86_64`. The `copycds` command can copy from one or more ISO files, or the CD/DVD device path.

You can specify `-i` or `--inspection` option to check whether the DVDs/ISOs can be recognized by xCAT. If recognized, the distribution name, architecture and the disc no (the disc sequence number of DVDs/ISOs in multi-disk distribution) of the DVD/ISO is displayed. If xCAT doesn’t recognize the DVD/ISO, you must manually specify the distro name and architecture using the `-n` and `-a` options. This is sometimes the case for distros that have very recently been released, and the xCAT code hasn’t been updated for it yet.

You can get xCAT to recognize new DVDs/ISOs by adding them to `/opt/xcat/lib/perl/xCAT/data/discinfo.pm` (the key of the hash is the first line of `.discinfo`) and reloading xcatd (`service xcatd reload`).

OPTIONS

- `-n|--name|--osver` = `distroname`
  The linux distro name and version that the ISO/DVD contains. Examples: rhels6.3, sles11.2, fedora9. Note the 's' in rhels6.3 which denotes the Server version of RHEL, which is typically used.

- `-a|--arch` = `architecture`
  The architecture of the linux distro on the ISO/DVD. Examples: x86, x86_64, ppc64, s390x.

- `-p|--path` = `ospkgpath`
  The destination directory to which the contents of ISO/DVD will be copied. When this option is not specified, the default destination directory will be formed from the `installdir` site table attribute and the distro name and architecture, for example: `/install/rhel6.3/x86_64`. This option is only supported for distributions of sles, redhat and windows.

- `-i|--inspection`
  Check whether xCAT can recognize the DVDs/ISOs in the argument list, but do not copy the disc. Displays the os distribution name, architecture and disc no of each recognized DVD/ISO. This option is only supported for distributions of sles, redhat and windows.

- `-o|--noosimage`
  Do not create the default osimages based on the osdistro copied in. By default, `copycds` will create a set of osimages based on the osdistro.

- `-w|--nonoverwrite`
  Complain and exit if the os disc has already been copied in. By default, `copycds` will overwrite the os disc already copied in.

RETURN VALUE

0: The command completed successfully. For the `--inspection` option, the ISO/DVD have been recognized successfully.

Nonzero: An Error has occurred. For the `--inspection` option, the ISO/DVD cannot be recognized.
### EXAMPLES

1. To copy the RPMs from a set of ISOs that represent the DVDs of a distro:

   ```bash
   copycds dvd1.iso dvd2.iso
   ```

2. To copy the RPMs from a physical DVD to /depot/kits/3 directory:

   ```bash
   copycds -p /depot/kits/3 /dev/dvd
   ```

3. To copy the RPMs from a DVD ISO of a very recently released distro:

   ```bash
   copycds -n rhels6.4 -a x86_64 dvd.iso
   ```

4. To check whether a DVD ISO can be recognized by xCAT and display the recognized disc info:

   ```bash
   copycds -i /media/RHEL/6.2/RHEL6.2-20111117.0-Server-ppc64-DVD1.iso
   ```

   Output will be similar to:

   ```plaintext
   OS Image:/media/RHEL/6.2/RHEL6.2-20111117.0-Server-ppc64-DVD1.iso
   DISTNAME:rhels6.2
   ARCH:ppc64
   DISCNO:1
   ```

   For the attributes that are not recognized, the value will be blank.

5. To copy the packages from a supplemental DVD ISO file:

   ```bash
   copycds /isodir/RHEL6.5/RHEL6.5-Supplementary-20131114.2-Server-ppc64-DVD1.iso
   ```

   Also, remember to add the new directory to your osimage definition:

   ```bash
   chdef -t osimage myosimage -p pkgdir=/install/rhels6.5-supp/ppc64
   ```

### SEE ALSO

- nodeset(8), nodeset.8, site(5), site.5, nodetype(5), nodetyp.5

- makeconservercf.8

### NAME

**makeconservercf** - creates the conserver configuration file from info in the xCAT database

### SYNOPSIS

```bash
makeconservercf [-V|--verbose] [-d|--delete] [noderange]
makeconservercf [-V|--verbose] [-C|--cleanup]
makeconservercf [-V|--verbose] [-l|--local] [noderange]
```
makeconservercf [-V|--verbose] [-c|--conserver] [noderange]
makeconservercf [-V|--verbose] noderange [-t|--trust] hosts
makeconservercf [-hl|--help|-v|--version]

DESCRIPTION

The **makeconservercf** command will write out the `/etc/conserver.cf`, using information from the nodehm table and related tables (e.g. mp, ipmi, ppc). Normally, **makeconservercf** will write all nodes to the `/etc/conserver.cf` file. If a **noderange** is specified, it will write only those nodes to the file. In either case, if a node does not have nodehm.cons set, it will not be written to the file.

If **-d** is specified, **makeconservercf** will remove specified nodes from `/etc/conserver.cf` file. If **noderange** is not specified, all xCAT nodes will be removed from `/etc/conserver.cf` file.

If **-C|--cleanup** is specified, **makeconservercf** will remove console configuration entries from `/etc/conserver.cf` for the nodes whose definitions have been removed from xCATdb. **Don't** specify any noderange.

In the case of a hierarchical cluster (i.e. one with service nodes) **makeconservercf** will determine which nodes will have their consoles accessed from the management node and which from a service node (based on the nodehm.conserver attribute). The `/etc/conserver.cf` file will be created accordingly on all relevant management/service nodes. If **-l** is specified, it will only create the local file.

OPTIONS

- **-dl|--delete**
  Delete rather than add or refresh the nodes specified as a noderange.

- **-Cl|--cleanup**
  Remove the entries for the nodes whose definitions have been removed from xCAT db.

- **-cl|--conserver**
  Only set up the conserver on the conserver host. If no conserver host is set for nodes, the conserver gets set up only on the management node.

- **-ll|--local**
  Only run **makeconservercf** locally and create the local `/etc/conserver.cf`. The default is to also run it on all service nodes, if there are any.

- **-tl|--trust** **hosts**
  Add additional trusted hosts into `/etc/conserver.cf`. The **hosts** are comma separated list of ip addresses or host names.

- **-vl|--version**
  Display version.

- **-Vl|--verbose**
  Verbose mode.

- **-hl|--help**
  Display usage message.
RETURN VALUE

0. The command completed successfully.
1. An error has occurred.

EXAMPLES

1. To create conserver configuration for all the nodes.

   makeconservercf

2. To create conserver configuration for nodes node01-node10.

   makeconservercf node01-node10

3. To remove conserver configuration for node01.

   makeconservercf -d node01

SEE ALSO

rcons(1)|rcons.1
makedhcp.8

NAME

makedhcp - Creates and updates DHCP configuration files.

SYNOPSIS

makedhcp -n [-l|--localonly]
makedhcp -a [-l|--localonly]
makedhcp -a -d [-l|--localonly]
makedhcp -d noderange [-l|--localonly]
makedhcp noderange [-s statements] [-l|--localonly]
makedhcp -q noderange
makedhcp [-hl--help]

DESCRIPTION

The makedhcp command creates and updates the DHCP configuration on the management node and service nodes. The makedhcp command is supported for both Linux and AIX clusters.

1. Start by filling out the networks(5)|networks.5 table properly.
2. Then use the `makedhcp -n` option to create a new dhcp configuration file. You can set the site table, dhcplease attribute to the lease time for the dhcp client. The default value is 43200.

3. Next, get the node IP addresses and MACs defined in the xCAT database. Also, get the hostnames and IP addresses pushed to /etc/hosts (using makehosts(8)|makehosts.8) and to DNS (using makedns(8)|makedns.8).

4. Then run `makedhcp` with a noderange or the `-a` option. This will inject into dhcpd configuration data pertinent to the specified nodes. On linux, the configuration information immediately takes effect without a restart of DHCP.

If you need to delete node entries from the DHCP configuration, use the `-d` flag.

**OPTIONS**

-`n`

Create a new dhcp configuration file with a network statement for each network the dhcp daemon should listen on. (Which networks dhcpd should listen on can be controlled by the dhcpinterfaces attribute in the site(5)|site.5 table.) The `makedhcp` command will automatically restart the dhcp daemon after this operation. This option will replace any existing configuration file (making a backup of it first). For Linux systems the file will include network entries as well as certain general parameters such as a dynamic range and omapi configuration. For AIX systems the file will include network entries. On AIX systems, if there are any non-xCAT entries in the existing configuration file they will be preserved and added to the end of the new configuration file.

-`a`

Define all nodes to the DHCP server. (Will only add nodes that can be reached, network-wise, by this DHCP server.) The dhcp daemon does not have to be restarted after this. On AIX systems `makedhcp` will not add entries for cluster nodes that will be installed using NIM. The entries for these nodes will be managed by NIM.

`noderange`

Add the specified nodes to the DHCP server configuration.

-`s` `statements`

For the input noderange, the argument will be interpreted like dhcp configuration file text.

-`d` `noderange`

Delete node entries from the DHCP server configuration. On AIX, any entries created by NIM will not be removed.

-`a -d`

Delete all node entries, that were added by xCAT, from the DHCP server configuration.

-`l` | --localonly

Configure dhcpd on the local machine only. Without this option, makedhcp will also send this operation to any service nodes that service the nodes in the noderange.

-`q` `noderange`

Query the node entries from the DHCP server configuration. On AIX, any entries created by NIM will not be listed.

-`h|--help`

Display usage message.
RETURN VALUE

0. The command completed successfully.
1. An error has occurred.

EXAMPLES

1. Create a new DHCP configuration file and add the network definitions:

   makedhcp -n

2. Define all nodes to the dhcp server:

   makedhcp -a

   Note: This does not add nodes that will be installed with AIX/NIM.

3. Will cause dhcp on the next request to set root-path appropriately for only node5. Note some characters (e.g. “”) must be doubly escaped (once for the shell, and once for the OMAPI layer).

   makedhcp node5 -s 'option root-path "$172.16.0.1:/install/freebsd6.2/x86_64\n   \"\"';'

4. Query a node from the DHCP server.

   # makedhcp -q node01
   node01: ip-address = 91.214.34.156, hardware-address = 00:00:0c:00:04:0c

FILES

DHCP configuration files:
[AIX] /etc/dhcpsd.cnf
[SLES] /etc/dhcpd.conf
[RH] /etc/dhcp/dhcpd.conf

SEE ALSO

noderange(3)noderange.3

makedns.8

NAME

makedns - sets up domain name services (DNS).
SYNOPSIS

makedns [-h | --help]
makedns [-V | --verbose] [-e | --external] [-n | --new] [noderange]
makedns [-V | --verbose] [-e | --external] [-d | --delete noderange]

DESCRIPTION

makedns configures a DNS server on the system you run it on, which is typically the xCAT management node.

The list of nodes to include comes from either the noderange provided on the command line or the entries in the local /etc/hosts files.

There are several bits of information that must be included in the xCAT database before running this command.

You must set the forwarders attributes in the xCAT site definition.

The forwarders value should be set to the IP address of one or more nameservers at your site that can resolve names outside of your cluster. With this set up, all nodes ask the local nameserver to resolve names, and if it is a name that the MN DNS does not know about, it will try the forwarder names.

An xCAT network definition must be defined for each network used in the cluster. The net and mask attributes will be used by the makedns command.

A network domain and nameservers values must be provided either in the network definition corresponding to the node or in the site definition.

Only entries in /etc/hosts or the hosts specified by noderange that have a corresponding xCAT network definition will be added to DNS.

By default, makedns sets up the named service and updates the DNS records on the local system (management node). If the -e flag is specified, it will also update the DNS records on any external DNS server that is listed in the /etc/resolv.conf on the management node. (Assuming the external DNS server can recognize the xCAT key as authentication.)

For more information on Cluster Name Resolution: Cluster_Name_Resolution

OPTIONS

-V | --verbose
    Verbose mode.

-n | --new
    Use this flag to create new named configuration and db files.

-d | --delete
    Remove the DNS records.

-e | --external
    Update DNS records to the external DNS server listed in /etc/resolv.conf.

    Enabling the site attribute externaldns means use ‘external’ DNS by default. If setting externaldns to 1, you need NOT use -e flag in every makedns call.

noderange
A set of comma delimited node names and/or group names. See the “noderange” man page for details on additional supported formats.

**Examples**

1. To set up DNS for all the hosts in `/etc/hosts` file.
   
   ```
makedns
   ```

2. To set up DNS for `node1`.
   
   ```
makedns node1
   ```

3. To create a new named configuration and db files for all hosts in `/etc/hosts`.
   
   ```
makedns -n
   ```

4. To delete the DNS records for `node1`.
   
   ```
makedns -d node1
   ```

**SEE ALSO**

makehosts(8)|makehosts.8

makegocons.8

**NAME**

**makegocons** - Register or unregister the node in the goconserver service

**SYNOPSIS**

```
makegocons [-V|--verbose] [-d|--delete] [-q|--query] [noderange]
makegocons [-V|--verbose] [-C|--cleanup]
```

**DESCRIPTION**


The **makegocons** command will start the goconserver service if it is not started, then send the REST request to create or delete the session resource in the goconserver service. The session information including the session command or ssh connection parameters (for openbmc) is generated by xcat based on the records in the related tables (e.g. nodehm, ipmi, ppc, openbmc).

By default **makegocons** will register the session for all of the nodes in xcat.

If a `noderange` is specified, only the session in the specified scope will be affected, goconserver service will not be restarted and the other session will not be disconnected. This is the advantage of goconserver over the conserver service with **makeconservercf**.
If **-d** is specified, **makegocons** will remove the session in the goconserver service.

In the case of a hierarchical cluster (i.e. one with service nodes) **makegocons** will determine which nodes will have their consoles accessed from the management node and which from a service node (based on the nodehm.conserver attribute).

To start goconserver on the specified service node, setup goconserver package on that service node, then set the **console** column of **servicenode** table to **2**.

To support diskless service node, a new column **consoleenabled** has been added in **nodehm** table, it is used by **makegocons** command to save the current console state for the node. After reinstalling the service node, the console storage file which maintain the console nodes by goconserver is lost, xCAT would register the console nodes into goconserver based on **consoleenabled** attribute when restarting xcatd service.

For openbmc which uses ssh as the terminal session connection method, goconserver can help save the system resources as goconserver could handle the ssh connection within goroutine which is more light-weighted than the command process.

**Note**: goconserver only support the systemd based systems. It has been integrated with xCAT as a recommended package.

**OPTIONS**

- **dl--delete**
  
  Delete rather than add or refresh the nodes specified as a noderange.

- **Cl--cleanup**
  
  Remove the entries for the nodes whose definitions have been removed from xCAT db.

- **ql--query**
  
  List the console connection of the nodes. If noderange is not specified, all of the console nodes will be displayed.

- **vl--version**
  
  Display version.

- **Vl--verbose**
  
  Verbose mode.

- **hl--help**
  
  Display usage message.

**RETURN VALUE**

0. The command completed successfully.

1. An error has occurred.

**EXAMPLES**

1. To create goconserver configuration for all the nodes.

   ```bash
   makegocons
   ```

1.3. Admin Guide 735
2. To create goconserver configuration for nodes node01-node10.

   makegocons node01-node10

3. To remove goconserver configuration for node01.

   makegocons -d node01

4. To list console connection for node01.

   makegocons -q node01

SEE ALSO

rcons(1) rcons.1

makehosts.8

NAME

makehosts - sets up /etc/hosts from the xCAT hosts table.

SYNOPSIS

makehosts [-n] [noderange] [-l | --longnamefirst] [-d] [-m | --mactolinklocal]

makehosts {-h | --help}

DESCRIPTION

makehosts updates the /etc/hosts file based on information stored in the xCAT database object definitions.

The main three bits of information needed are: node hostname, node ip and network domain name.

The hostname and ip address are specified as part of the node definition.

The domain value is taken either from the xCAT network definition associated with the node or from the cluster site definition. If you are using multiple domains in the cluster you should add the domain names to the appropriate xCAT network definition.

Note: If your node hostnames and IP addresses follow a regular pattern, you can use just a few regular expressions to generate /etc/hosts using makehosts. For details on using regular expressions see the “xcatdb” man page.

If you specify additional network interfaces in your xCAT node definitions they will also be added to the /etc/hosts file. You can specify additional network interface information (NICs) using the following node attributes: nicip, nichostnamesuffixes, nictypes, niccustomscripts, nicnetworks. You can get a description of these attributes by running “lsdef -t node -h | more” or “man nics”.

OPTIONS

- n
Completely replace the /etc/hosts file, losing any previous content. If this option is not specified, it will only replace the lines in the file that correspond to the nodes in the specified noderange.

-\l  | --longnamefirst

The FQDN (Fully Qualified Domain Name) of the host will appear before the PQDN (Partially Qualified Domain Name) for each host in the /etc/hosts file. The default is PQDN first. After xCAT is installed, the attribute name “FQDNfirst” can be added into “site” table manually. If the value is set as “1”, “yes” or “enable”, the /etc/hosts entries generated by “makehosts” will put the FQDN before the PQDN. Otherwise, the original behavior will be performed.

-\m  | --mactolinklocal

Updates /etc/hosts file with IPv6 link local addresses, the link local address is generated from the mac address stored in mac table.

-d

Delete rather than create records. This will also delete any additional network interfaces (NICs) included in the node definitions.

EXAMPLES

1. Add entries to /etc/hosts for all nodes included in the xCAT node group called “compute”.

   makehosts compute

2. If the xCAT hosts table contains:

   "compute","|node(\d+)|1.2.3.($1+0)|","|(.*)|($1).cluster.net|","

   Assuming the group “compute” contains node01, node02, etc., then in /etc/hosts they will be given IP addresses of 1.2.3.1, 1.2.3.2, etc.

SEE ALSO

hosts(5)|hosts.5, makedns(8)|makedns.8

makeknownhosts.8

NAME

makeknownhosts - Make a known_hosts file under $ROOTHOME/.ssh for input noderange.

SYNOPSIS

makeknownhosts noderange [-r | --remove | -d | --delete] [-V | --verbose]
makeknownhosts [-h | --help]
DESCRIPTION

makeknownhosts Replaces or removes entries for the nodes in the known_hosts file in the $ROOTHOME/.ssh directory. The known_hosts file entry is built from the shared ssh host key that xCAT distributes to the installed nodes.

HMCs, AMM, switches, etc., where xCAT does not distribute the shared ssh host key, should not be put in the noderange.

To build the known_hosts entry for a node, you are only required to have the node in the database, and name resolution working for the node. You do not have to be able to access the node.

Having this file with correct entries, will avoid the ssh warning when nodes are automatically added to the known_hosts file. The file should be distributed using xdcpx to all the nodes, if you want node to node communication not to display the warning.

OPTIONS

noderange

A set of comma delimited node names and/or group names. See the noderange man page for details on supported formats.

-d|--delete

Only removes the entries for the nodes from the known_hosts file.

-r|--remove

Synonymous to -d|--delete.

-V|--verbose

Verbose mode.

EXAMPLES

1. To build the known_hosts entry for the nodes in the compute group

   makeknownhosts compute

2. To build the known_hosts entry for the nodes in the lpars and service groups

   makeknownhosts lpars,service

3. To remove the known_hosts entry for node02

   makeknownhosts node02 -d


makenetworks.8

NAME

makenetworks - Gather cluster network information and add it to the xCAT database.
SYNOPSIS

makenetworks [-h | --help]
makenetworks [-v | --version]
makenetworks [-V | --verbose] [-d | --display]

DESCRIPTION

The **makenetworks** command can be used to gather network information from an xCAT cluster environment and create corresponding network definitions in the xCAT database.

Every network that will be used to install a cluster node must be defined in the xCAT database.

The default behavior is to gather network information from the management node, and any configured xCAT service nodes, and automatically save this information in the xCAT database.

You can use the “-d” option to display the network information without writing it to the database.

You can also redirect the output to a file that can be used with the xCAT **mkdef** command to define the networks.

For example:

```
makenetworks -d > mynetstanzas
```

```
cat mynetstanzas | mkdef -z
```

This features allows you to verify and modify the network information before writing it to the database.

When the network information is gathered a default value is created for the “netname” attribute. This is done to make it possible to use the mkdef, chdef, lsdef, and rmdef commands to manage this data.

The default naming convention is to use a hyphen separated “net” and “mask” value with the “.” replace by “_”. (ex. “8_124_47_64-255_255_255_0”)

You can also modify the xCAT “networks” database table directly using the xCAT **tabedit** command.

```
tabedit networks
```

Note: The **makenetworks** command is run automatically when xCAT is installed on a Linux management node.

OPTIONS

- **-dl--display** Display the network definitions but do not write to the definitions to the xCAT database. The output will be in stanza file format and can be redirected to a stanza file that can be used with **mkdef** or **chdef** commands to create or modify the network definitions.
- **-h | --help** Display usage message.
- **-v | --version** Command Version.
- **-V | --verbose** Verbose mode.

RETURN VALUE

- **0.** The command completed successfully.
- **1.** An error has occurred.
EXAMPLES

1. Gather cluster network information and create xCAT network definitions.
   
   makenetworks

2. Display cluster network information but do not write the network definitions to the xCAT database.
   
   makenetworks -d

   The output would be one or more stanzas of information similar to the following. The line that ends with a colon is the value of the “netname” attribute and is the name of the network object to use with the lsdef, mkdef, chdef and rmdef commands.

   9_114_37_0-255_255_255_0:  objtype=network  gateway=9.114.37.254  mask=255.255.255.0
   net=9.114.37.0

FILES

/opt/xcat/sbin/makenetworks

SEE ALSO

makedhcp(8) | makedhcp.8
makeroutes.8

NAME

makeroutes - add or delete routes to/from the os route table on nodes.

SYNOPSIS

makeroutes [-r | --routename \(r1,[r2,\ldots]\)]
makeroutes [-d | --delete] [-r | --routenames \(r1,[r2,\ldots]\)]
makeroutes noderange [-r | --routename \(r1,[r2,\ldots]\)]
makeroutes noderange [-d | --delete] [-r | --routenames \(r1,[r2,\ldots]\)]
makeroutes [-h | --help | -v | --version]

DESCRIPTION

The makeroutes command adds or deletes routes on the management node or any given nodes. The noderange specifies the nodes where the routes are to be added or removed. When the noderange is omitted, the action will be done on the management node. The -r option specifies the name of routes. The details of the routes are defined in the routes table which contains the route name, subnet, net mask and gateway. If -r option is omitted, the names of the routes found on noderes.routenames for the nodes or on site.mnroutenames for the management node will be used.
If you want the routes be automatically setup during node deployment, first put a list of route names to `noderes.routenames` and then add `setroute` script name to the `postscripts.postbootscripts` for the nodes.

**Parameters**

`noderange` specifies the nodes where the routes are to be added or removed. If omitted, the operation will be done on the management node.

**OPTIONS**

- `-dl|--delete`
  
  Specifies to delete the given routes. If not specified, the action is to add routes.

- `-rl|--routename`
  
  Specifies a list of comma separated route names defined in the `routes` table. If omitted, all routes defined in `noderes.routenames` for nodes or `site.mnroutenames` for the management node will be used.

- `-hl|--help`
  
  Display usage message.

- `-vl|--version`
  
  Command Version.

**EXAMPLES**

1. To add all routes from the `site.mnroutenames` to the os route table for the management node.

   ```
   makeroutes
   ```

2. To add all the routes from `noderes.routenames` to the os route table for node1.

   ```
   makeroutes node1
   ```

3. To add route rr1 and rr2 to the os route table for the management node.

   ```
   makeroutes -r rrl,rr2
   ```

4. To delete route rr1 and rr2 from the os route table on node1 and node1.

   ```
   makeroutes node1,node2 -d -r rrl,rr2
   ```

**FILES**

```
/opt/xcat/sbin/makeroutes
```
SEE ALSO

mknb.8

NAME

mknb - creates a network boot root image for node discovery and flashing

SYNOPSIS

mknb

DESCRIPTION

The mknb command is run by xCAT automatically when xCAT is installed on the management node. It creates a network boot root image (used for node discovery, BMC programming, and flashing) for the same architecture that the management node is. So you normally do not need to run the mknb command yourself.

If you make custom changes to the network boot root image, you will need to run mknb again to regenerate the diskless image to include your changes. If you have an xCAT Hierarchical Cluster with Service Nodes having local /tftpboot directories (site.sharedtftp=0), you will need to copy the generated root image to each Service Node.

Presently, the architectures x86_64 and ppc64 are supported. For ppc64le, use the ppc64 architecture.

OPTIONS

arch

The hardware architecture for which to build the boot image.

RETURN VALUE

0. The command completed successfully.
1. An error has occurred.

SEE ALSO

makedhcp(8)|makedhcp.8

nodeadd.8

NAME

nodeadd - Adds nodes to the xCAT cluster database.
SYNOPSIS

```bash
nodeadd noderange groups=groupnames [table.column=value] [ ]
nodeadd [-v | --version]
nodeadd [-? | -h | --help]
```

DESCRIPTION

The nodeadd command adds the nodes specified in noderange to the xCAT database. It also stores the any additional attributes specified for these nodes. At least one groupname must be supplied. You should also consider specifying attributes in at least the following tables: `nodehm`, `noderes`, `nodetype`. See the man page for each of these for details. Also see the `xcatdb` man page for an overview of each table.

The nodeadd command also supports some short cut names as aliases to common attributes. See the `nodels` man page for details.

OPTIONS

-`-v|--version`
  Command Version.
-`-?|--help`
  Display usage message.

RETURN VALUE

- 0. The command completed successfully.
- 1. An error has occurred.

EXAMPLES

1. To add nodes in noderange node1-node4 with group all:
   ```bash
   nodeadd node1-node4 groups=all
   ```

2. To add nodes in noderange node1-node4 to the nodetype table with os=rhel5:
   ```bash
   nodeadd node1-node4 groups=all,rhel5 nodetype.os=rhel5
   ```

FILES

``/opt/xcat/bin/nodeadd``

SEE ALSO

nodels(1)|nodels.1, nodech(1)|nodech.1, noderange(3)|noderange.3
nodeset.8

Name

nodeset - set the boot state for a noderange

Synopsis

nodeset noderange osimage=[imagename] [--noupdateinitrd] | [--ignorekernelchk]
nodeset noderange runimage=task
nodeset [-h | --help | -v | --version]

Description

nodeset sets the next boot state for a single or range of nodes or groups. It tells xCAT what you want to happen the next time the nodes are booted up. See noderange(3)noderange.3. nodeset accomplishes this by changing the network boot files. Each xCAT node always boots from the network and downloads a boot file with instructions on what action to take next.

nodeset will manipulate the boot configuration files of xnba, grub2, petitboot, yaboot and pxelinux.0.

Assume that /tftpboot is the root for tftpd (set in site(5)site.5).

nodeset for petitboot makes changes to /tftpboot/petitboot/{node name}
nodeset for xnba makes changes to /tftpboot/xcat/xnba/nodes/{node name}
nodeset for grub2 makes changes to /tftpboot/boot/grub2/{node name}
nodeset for pxe makes changes to /tftpboot/pxelinux.cfg/{node hex ip}
nodeset for yaboot makes changes to /tftpboot/etc/{node hex ip}

nodeset only sets the next boot state, but does not reboot.

nodeset is called by rinstall and wininstall and is also called by the installation process remotely to set the boot state back to “boot”.

In a hierarchical cluster managed by service nodes, nodeset command is used to make sure compute node states are consistent on service and management nodes. When errors are reported, run the command with verbose mode. And the command will display additional service node information, which might be useful in identifying the problem.

A user can supply their own scripts to be run on the mn or on the service node (if a hierarchical cluster) for a node when the nodeset command is run. Such scripts are called prescripts. They should be copied to /install/prescripts directory. A table called prescripts is used to specify the scripts and their associated actions. The scripts to be run at the beginning of the nodeset command are stored in the ‘begin’ column of prescripts table. The scripts to be run at the end of the nodeset command are stored in the ‘end’ column of prescripts table. You can run ‘tabdump -d prescripts’ command for details. The following two environment variables will be passed to each script: NODES contains all the names of the nodes that need to run the script for and ACTION contains the current nodeset action. If #xCAT setting:MAX_INSTANCE=number is specified in the script, the script will get invoked for each node in parallel, but no more than number of instances will be invoked at a time. If it is not specified, the script will be invoked once for all the nodes.
Options

boot

Instruct network boot loader to be skipped, generally meaning boot to hard disk

offline

Cleanup the current pxe/tftp boot configuration files for the nodes requested

\texttt{osimage | osimage=imagename}

Prepare server for installing a node using the specified os image. The os image is defined in the \texttt{osimage}\ table and \texttt{linuximage}\ table. If the \texttt{<imagename>} is omitted, the os image name will be obtained from \texttt{nodetype.provmethod}\ for the node.

\texttt{--noupdateinitrd}

Skip the rebuilding of initrd when the ‘netdrivers’, ‘driverupdatesrc’ or ‘osupdatename’ were set for injecting new drivers to initrd. But, the \texttt{geninitrd}\ command should be run to rebuild the initrd for new drivers injecting. This is used to improve the performance of \texttt{nodeset}\ command.

\texttt{--ignorekernelchk}

Skip the kernel version checking when injecting drivers from osimage.driverupdatesrc. That means all drivers from osimage.driverupdatesrc will be injected to initrd for the specific target kernel.

runimage=task

If you would like to run a task after deployment, you can define that task with this attribute.

\texttt{stat}

Display the current boot loader config file description for the nodes requested. When \texttt{disjointdhcps}\ is set, using \texttt{-a}\ to display them on all available service nodes.

\texttt{runcmd=command}

This instructs the node to boot to the xCAT genesis environment and specified command to be executed.

\texttt{shell}

This instructs the node to boot to the xCAT genesis environment, and present a shell prompt on console. The node will also be able to be sshed into and have utilities such as wget, tftp, scp, nfs, and cifs. It will have storage drivers available for many common systems.

\texttt{shutdown}

To make the node to get into power off status. This status only can be used after \texttt{runcmd}\ and \texttt{runimage}\ to power off the node after the performing of operations.

\texttt{-V | --verbose}

Verbose mode.

\texttt{-h | --help}

Print help.

\texttt{-v | --version}

Print version.
Files

**noderes** table - xCAT node resources file. See noderes(5)noderes.5 for further details.

**nodetype** table - xCAT node installation type file. See nodetype(5)nodetype.5 for further details. This is used to determine the node installation image type.

**site** table - xCAT main configuration file. See site(5)site.5 for further details. This is used to determine the location of the TFTP root directory and the TFTP xCAT subdirectory. /tftpboot and /tftpboot/xcat is the default.

Examples

1. To setup to install mycomputeimage on the compute node group.
   ```
   nodeset compute osimage=mycomputeimage
   ```

2. To run file://T/Master/image.tgz after deployment:
   ```
   nodeset $node runimage=file://$MASTER/image.tgz
   ```

3. Boot node1 into xCAT genesis environment and execute bmcsetup script. This causes the IP, netmask, gateway, username, and password to be programmed according to the configuration in node object definition.
   ```
   rinstall node1 runcmd=bmcsetup
   ```

See Also

noderange(3)noderange.3, nodels(1)nodels.1, nodestat(1)nodestat.1, rinstall(8)rinstall.8, makedhcp(8)makedhcp.8,
osimage(7)osimage.7

rescanplugins.8

NAME

**rescanplugins** - Notifies xcatd to rescan the plugin directory

SYNOPSIS

rescanplugins
rescanplugins [-h | --help]
rescanplugins [-v | --version]
rescanplugins [-s | --servicenodes]

DESCRIPTION

rescanplugins notifies the xcatd daemon to rescan the plugin directory and update its internal command handlers hash. This command should be used when plugins have been added or removed from the xCAT plugin directory.
(~/opt/xcat/lib/perl/xCAT_plugin) or if the contents of the handled.commands subroutine in an existing plugin has changed.

If rescanplugins is called as a subrequest from another command, the xcatd command handlers hash changes will not be available to that command’s process. Only subsequent command calls will see the updates.

OPTIONS

-hl--help
  Displays the usage message.

-v|--version
  Displays the release version of the code.

-sl--servicenodes
  Process the rescanplugins on the management node and on all service nodes. The rescanplugins command will be sent to the xcatd daemon on all nodes defined in the servicenode table. The default is to only run on the management node.

EXAMPLES

1. To rescan the plugins only on the xCAT Management Node:

   rescanplugins

2. To rescan the plugins on the xCAT Management Node and on all service nodes:

   rescanplugins -s

rinstall.8

Name

rinstall - Begin OS provision on a noderange

Synopsis

rinstall noderange [boot | shell | runcmd=command] [-c | --console] [-V | --verbose]
rinstall noderange runimage=task
rinstall [-h | --help] [-v | --version]
Description

rinstall is a convenience command to begin OS provision on a noderange.

If osimage=imagename is specified or osimage is specified and nodetype.provmethod=osimage is set, provision the noderange with the osimage specified/configured. If no task specified, default is osimage.

If -c is specified, rinstall will run rcons on the node. This is allowed only if one node is in the noderange. If consoles are needed on multiple nodes, see winstall(8)|winstall.8.

Options

boot

Instruct network boot loader to be skipped, generally meaning boot to hard disk

osimage[=imagename]

Prepare server for installing a node using the specified OS image. The OS image is defined in the osimage table and linuximage table. If the imagename is omitted, the OS image name will be obtained from nodetype.provmethod for the node.

--noupdateinitrd

Skip the rebuilding of initrd when the ‘netdrivers’, ‘driverupdatesrc’ or ‘osupdatename’ were set for injecting new drivers to initrd. But, the geninitrd command should be run to rebuild the initrd for new drivers injecting. This is used to improve the performance of rinstall command.

--ignorekernelchk

Skip the kernel version checking when injecting drivers from osimage.driverupdatesrc. That means all drivers from osimage.driverupdatesrc will be injected to initrd for the specific target kernel.

runimage=task

If you would like to run a task after deployment, you can define that task with this attribute.

runcmd=command

This instructs the node to boot to the xCAT genesis environment and specified command to be executed.

shell

This instructs the node to boot to the xCAT genesis environment, and present a shell prompt on console. The node will also be able to be sshed into and have utilities such as wget, tftp, scp, nfs, and cifs. It will have storage drivers available for many common systems.

-h | --help

Display usage message.

-v | --version

Display version.

-u | --uefimode

For BMC-based servers, to specify the next boot mode to be “UEFI Mode”.

-V | --verbose

Verbose output.

-c | --console
Requests that **rinstall** runs **rcons** once the provision starts. This will only work if there is only one node in the noderange. See **winstall(8)**/winstall.8 for starting consoles on multiple nodes.

**Examples**

1. Provision nodes 1 through 20, using their current configuration.

   ```
   rinstall node1-node20
   ```

2. Provision nodes 1 through 20 with the osimage rhels6.4-ppc64-netboot-compute.

   ```
   rinstall node1-node20 osimage=rhels6.4-ppc64-netboot-compute
   ```

3. Provision node1 and start a console to monitor the process.

   ```
   rinstall node1 -c
   ```

4. Boot node1 into xCAT genesis environment and execute bmcsetup script. This causes the IP, netmask, gateway, username, and password to be programmed according to the configuration in node object definition.

   ```
   rinstall node1 runcmd=bmcsetup
   ```

**See Also**

noderange(3)/noderange.3, wininstall(8)/winstall.8, rcons(1)/rcons.1

**rmosdistro.8**

**SYNOPSIS**

```
rmosdistro [-a | --all] [-f | --force] osdistroname [osdistroname2 ...]
rmosdistro [-h | --help]
```

**DESCRIPTION**

The **rmosdistro** command removes the specified OS Distro that was created by **copycds**. To delete all OS Distro entries, please specify [-a | --all]. If the specified OS Distro is referenced by some osimage, [-f | --force] can be used to remove it.

**ARGUMENTS**

The OS Distro names to delete, delimited by blank space.

**OPTIONS**

- **-a | --all**
  
  If specified, try to delete all the OS Distros.
CAT3 Documentation, Release 2.14.5

-f | --force

Remove referenced OS Distros, never prompt.

-h | --help

Show info of rmosdistro usage.

RETURN VALUE

Zero: The command completed successfully.

Nonzero: An Error has occurred.

EXAMPLES

1. To remove OS Distro “rhels6.2-ppc64” and “sles11.2-ppc64”:
   
   rmosdistro rhels6.2-ppc64 sles11.2-ppc64

2. To remove OS Distro “rhels6.2-ppc64”, regardless of whether is referenced by any osimage:
   
   rmosdistro -f rhels6.2-ppc64

3. To remove all OS Distros:
   
   rmosdistro -a

runsqlcmd.8

NAME

runsqlcmd - Runs sql command files against the current xCAT database.

SYNOPSIS

runsqlcmd
runsqlcmd [-h | --help]
runsqlcmd [-v | --version]
runsqlcmd [-d | --dir directory_path] [-V | --verbose]
runsqlcmd [-f | --files list of files] [-V | --verbose]
runsqlcmd [-V | --verbose] [sql statement]

DESCRIPTION

The runsqlcmd routine, runs the sql statements contained in the *.sql files as input to the command against the current running xCAT database. Only DB2, MySQL and PostgreSQL databases are supported. SQLite is not supported. If no directory or filelist is provided, the default /opt/xcat/lib/perl/xCAT_schema directory is used. If the directory is input
with the -d flag, that directory will be used. If a comma separated list of files is input with the -f flag, those files will be used.

**OPTIONS**

- **-h|--help**
  
  Displays the usage message.

- **-v|--version**
  
  Displays current code version.

- **-V|--verbose**
  
  Displays extra debug information.

- **-d|--dir**
  
  To use a directory other than the default directory, enter the directory path here.

- **-f|--files**
  
  Comma separated list of files (full path), wildcard (*) can be used.

**File format**

The files must be of the form `<name>.sql` or `<name>_<database>.sql` where `<database>` is mysql, pgsql, or db2. Files must have permission 0755.

**sql statement**

Quoted sql statement syntax appropriate for the current database.

**EXAMPLES**

1. To run the database appropriate *.sql files in `/opt/xcat/lib/perl/xCAT_schema`:

   ```bash
   runsqlcmd
   ```

2. To run the database appropriate *.sql files in `/tmp/mysql`:

   ```bash
   runsqlcmd -d /tmp/mysql
   ```

3. To run the database appropriate *.sql files in the input list:

   ```bash
   runsqlcmd -f "/tmp/mysql/test*,/tmp/mysql/test1*"
   ```

4. To checkout one DB2 sql file:

   ```bash
   runsqlcmd -f /tmp/db2/test_db2.sql
   ```

5. To run the following command to the database:

   ```bash
   runsqlcmd "Select * from site;"
   ```
setupiscsidev.8

NAME

setupiscsidev - creates a LUN for a node to boot up with, using iSCSI

SYNOPSIS

setupiscsidev [-sl--size] noderange
setupiscsidev [-hl--help|-vl--version]

DESCRIPTION

The setupiscsidev command will create a LUN on the management node (or service node) for each node specified. The LUN device can then be used by the node as an iSCSI device so the node can boot diskless, stateful.

OPTIONS

-sl--size
  The size of the LUN that should be created. Default is 4096.
-vl--version
  Display version.
-hl--help
  Display usage message.

RETURN VALUE

  0. The command completed successfully.
  1. An error has occurred.

SEE ALSO

nodeset(8) nodeset.8
tabch.8

NAME

tabch - Add, delete or update rows in the database tables.
SYNOPSIS

```
tabch [-h | --help]  
tabch [-v | --version]  
tabcch  keycolname=keyvalue[,keycolname=keyvalue,..]  
                tablename.colname=newvalue  [tablename.colname=newvalue]  
tabcch  keycolname=keyvalue[,keycolname=keyvalue,..]  
                tablename.colname+=newvalue  [tablename.colname+=newvalue]  
tabcch  -d  keycolname=keyvalue[,keycolname=keyvalue,..]  
                tablename [tablename,..]  
```

DESCRIPTION

The `tabch` command adds, deletes or updates the attribute values in the specified table.column for the specified key-value. The difference between `tabch` and `chtab` is `tabch` runs as a plugin under the xcatd daemon. This gives the additional security of being authorized by the daemon. Normally, the given value will completely replace the current attribute value. But if “+=” is used instead of “=”, the specified value will be appended to the comma separated list of attributes, if it is not already there.

OPTIONS

- **-h | --help** Display usage message.
- **-v | --version** Command Version.
- **-d** Delete option.

RETURN VALUE

0. The command completed successfully.
1. An error has occurred.

EXAMPLES

1. To add a node=node1 to the nodelist table with groups=all:

   ```
tabcch  node=node1 nodelist.groups=all  
   ```

2. To add a keyword (tftpdir) and value (/tftpboot) to the site table:

   ```
tabcch  key=tftpdir site.value=/tftpboot  
   ```

3. To add node1 to the nodetype table with os=rhel5:

   ```
tabcch  node=node1 nodetype.os=rhel5  
   ```

4. To change node1 in nodetype table setting os=sles:

   ```
tabcch  node=node1 nodetype.os=sles  
   ```
5. To change node1 by appending otherpkgs to the postbootscripts field in the postscripts table:

```
tabch node=node1 postscripts.postbootscripts+=otherpkgs
```

6. To delete node1 from nodetype table:

```
tabch -d node=node1 nodetype
```

**FILES**

```
/opt/xcat/sbin/tabch
```

**SEE ALSO**

```
tabdump(8)|tabdump.8, tabedit(8)|tabedit.8
```

**tabdump.8**

**NAME**

```
tabdump - display an xCAT database table in CSV format.
```

**SYNOPSIS**

```
tabdump

```

**DESCRIPTION**

The tabdump command displays the header and all the rows of the specified table in CSV (comma separated values) format. Only one table can be specified. If no table is specified, the list of existing tables will be displayed.
OPTIONS

-?|-h|--help
    Display usage message.

-d
    Show descriptions of the tables, instead of the contents of the tables. If a table name is also specified, descriptions of the columns (attributes) of the table will be displayed. Otherwise, a summary of each table will be displayed.

-n
    Shows the most recent number of entries as supplied on the -n flag from the auditlog or eventlog table.

-f
    File name or path to file in which to dump the table. Without this the table is dumped to stdout. Using the -f flag allows the table to be dumped one record at a time. If tables are very large, dumping to stdout can cause problems such as running out of memory.

-w 'attr==val' -w 'attr=~val'...
    Use one or multiple -w flags to specify the selection string that can be used to select particular rows of the table. See examples.

    Operator descriptions:

    ==  Select nodes where the attribute value is exactly this value.
    !=  Select nodes where the attribute value is not this specific value.
    >  Select nodes where the attribute value is greater than this specific value.
    >= Select nodes where the attribute value is greater than or equal to this specific value.
    <  Select nodes where the attribute value is less than this specific value.
    <= Select nodes where the attribute value is less than or equal to this specific value.
    =~ Select nodes where the attribute value matches the SQL LIKE value.
    !~ Select nodes where the attribute value matches the SQL NOT LIKE value.

RETURN VALUE

    0. The command completed successfully.
    1. An error has occurred.

EXAMPLES

    1. To display the contents of the site table:

        tabdump site

    2. To display the contents of the nodelist table where the groups attribute is compute:
tabdump -w 'groups==compute' nodelist

3. To display the contents of the nodelist table where the groups attribute is comput% where % is a wildcard and can represent any string and the status attribute is booted:

```
$ tabdump -w 'groups=~comput%' -w 'status==booted' nodelist
```

4. To display the records of the auditlog on date 2011-04-18 11:30:00:

```
$ tabdump -w 'audittime==2011-04-18 11:30:00' auditlog
```

5. To display the records of the auditlog starting on 2011-04-18:

```
$ tabdump -w 'audittime>2011-04-18 11:30:00' auditlog
```

6. To display the 10 most recent entries in the auditlog:

```
$ tabdump -n 10 auditlog
```

7. To see what tables exist in the xCAT database:

```
$ tabdump
```

8. To back up all the xCAT database tables, instead of running `tabdump` multiple times, you can use the `dumpxCATdb` command as follows:

```
$ dumpxCATdb -p /tmp/xcatbak
```

See the `dumpxCATdb` man page for details.

9. To display a summary description of each table:

```
$ tabdump -d
```

10. To display a description of each column in the nodehm table:

```
$ tabdump -d nodehm
```

**FILES**

```
/opt/xcat/sbin/tabdump
```

**SEE ALSO**

`tabrestore(8)` `tabrestore.8`, `tabedit(8)` `tabedit.8`, `dumpxCATdb(1)` `dumpxCATdb.1`

**tabedit.8**

**NAME**

`tabedit` - view an xCAT database table in an editor and make changes.
SYNOPSIS

```
tabedit table
```

DESCRIPTION

The `tabedit` command opens the specified table in the user's editor, allows them to edit any text, and then writes changes back to the database table. The table is flattened into a CSV (comma separated values) format file before giving it to the editor. After the editor is exited, the CSV file will be translated back into the database format. You may not `tabedit` the auditlog or eventlog because indexes will be regenerated. Use `tabprune` command to edit auditlog and eventlog.

OPTIONS

```
-?|-h|--help
```

Display usage message.

ENVIRONMENT VARIABLES

TABEDITOR

The editor that should be used to edit the table, for example: vi, vim, emacs, oocalc, pico, gnumeric, nano. If `TABEDITOR` is not set, the value from `EDITOR` will be used. If `EDITOR` is not set, it will default to `vi`.

RETURN VALUE

0. The command completed successfully.
1. An error has occurred.

EXAMPLES

1. To edit the site table:

```
tabedit site
```

FILES

```
/opt/xcat/sbin/tabedit
```

SEE ALSO

`tabrestore(8)` | `tabrestore.8`, `tabdump(8)` | `tabdump.8`, `chtab(8)` | `chtab.8`
tabprune.8

NAME

tabprune - Deletes records from the eventlog, auditlog, isnm_perf, isnm_perf_sum tables.

SYNOPSIS

tabprune [eventlog | auditlog] [-V] [-i recid | -n number of records | -p percentage | -d number of days | -a]
tabprune tablename -a
tabprune [-h | --help] [-v | --version]

DESCRIPTION

The tabprune command is used to delete records from the auditlog, eventlog, isnm_perf, isnm_perf_sum tables. As an option, the table header and all the rows pruned from the specified table will be displayed in CSV (comma separated values) format. The all records options (-a) can be used on any xCAT table.

OPTIONS

- -h | --help

Display usage message.

- -V

Verbose mode. This will cause tabprune to display the records that are being deleted from the table, in case you want to redirect them to a file to archive them.

- -a

Remove all records from the input table name. This option can be used on any xCAT table.

- -i recid number

Remove the records whose recid is less than the input recid number.

- -n number

Remove the number of records input.

- -p percent

Remove the number of records input.

- -d number of days

Remove all records that occurred >= than number of days ago.

RETURN VALUE

 0. The command completed successfully.

 1. An error has occurred.
EXAMPLES

1. To remove all the records in the eventlog table:
   ```bash
tabprune eventlog -a
   ```

2. To remove all the records in the eventlog table saving the deleted records in eventlog.csv:
   ```bash
tabprune eventlog -V -a > eventlog.csv
   ```

3. To remove all the records before recid=200 in the auditlog table:
   ```bash
tabprune auditlog -i 200
   ```

4. To remove 400 records from the auditlog table and display the remove records:
   ```bash
tabprune auditlog -V -n 400
   ```

5. To remove 50% of the eventlog table:
   ```bash
tabprune eventlog -p 50
   ```

6. To remove all records that occurred >= 5 days ago in the eventlog:
   ```bash
tabprune eventlog -d 5
   ```

FILES

`/opt/xcat/sbin/tabprune`

SEE ALSO

`tabrestore(8)`| `tabrestore.8`, `tabedit(8)`| `tabedit.8`, `tabdump(8)`| `tabdump.8`

`tabrestore.8`

NAME

`tabrestore` - replaces with or adds to a xCAT database table the contents in a csv file.

SYNOPSIS

```
tabrestore [-a] table.csv
tabrestore [-? | -h | --help]
tabrestore [-v | --version]
```
DESCRIPTION

The tabrestore command reads the contents of the specified file and puts its data in the corresponding table in the xCAT database. Any existing rows in that table are replaced unless the (-a) flag is used and then the rows in the file are added to the table. The file must be in csv format. It could be created by tabdump. Only one table can be specified.

This command can be used to copy the example table entries in /opt/xcat/share/xcat/templates/e1350 into the xCAT database.

OPTIONS

-?|--help
   Display usage message.

-|tl|--version
   Display version.

-al|--addrows
   Add rows from the CSV file to the table instead of replacing the table with the CSV file.

RETURN VALUE

0. The command completed successfully.
1. An error has occurred.

EXAMPLES

1. To replace the rows in the mp table with the rows in the mp.csv file:

   tabrestore mp.csv

   The file mp.csv could contain something like:

   #node,mpa,id,comments,disable
   "blade","|\D+(\d+)|amm\{((\$1-1)/14+1)\}|","|D+(\d+)\{((\$1-1)\%14+1)\}|",,

2. To add the rows in the mp.csv file to the rows in the mp table:

   tabrestore -a mp.csv

3. To restore database tables from restore_directory that we dumped with dumpxCATdb:

   restoresxCATdb -p restore_directory

FILES

/opt/xcat/sbin/tabrestore
**SEE ALSO**

tabdump(8)|tabdump.8, tabedit(8)|tabedit.8, dumpxCATdb(1)|dumpxCATdb.1

**winstall.8**

**Name**

`winstall` - Begin OS provision on a noderange

**Synopsis**

```
winstall noderange [boot | shell | runcmd=bmcsetup] [runimage=task] [-V | --verbose]
winstall noderange [osimage=imagename | imagename] [--ignorekernelchk] [-u | --uefimode] [-V | --verbose]
winstall [-h | --help | -v | --version]
```

**Description**

`winstall` is a convenience command to begin OS provision on a noderange.

If `osimage=imagename | imagename` is specified or `nodetype.provmethod=osimage` is set, provision the noderange with the osimage specified/configured.

It will then run `wcons` on the noderange.

**Options**

- **boot**
  
  Instruct network boot loader to be skipped, generally meaning boot to hard disk

- **imagename | osimage=imagename**
  
  Prepare server for installing a node using the specified os image. The os image is defined in the `osimage` table and `linuximage` table. If the `imagename` is omitted, the os image name will be obtained from `nodetype.provmethod` for the node.

- **--ignorekernelchk**
  
  Skip the kernel version checking when injecting drivers from osimage.driverupdatesrc. That means all drivers from osimage.driverupdatesrc will be injected to initrd for the specific target kernel.

- **runimage=task**
  
  If you would like to run a task after deployment, you can define that task with this attribute.

- **runcmd=bmcsetup**
  
  This instructs the node to boot to the xCAT nbfs environment and proceed to configure BMC for basic remote access. This causes the IP, netmask, gateway, username, and password to be programmed according to the configuration table.

- **shell**
This instructs the node to boot to the xCAT genesis environment, and present a shell prompt on console. The node will also be able to be sshed into and have utilities such as wget, tftp, scp, nfs, and cifs. It will have storage drivers available for many common systems.

-h | --help
Display usage message.

-v | --version
Display version.

-u | --uefimode
For BMC-based servers, to specify the next boot mode to be “UEFI Mode”.

-V | --verbose
Verbose output.

Examples

1. Provision nodes 1 through 20, using their current configuration.

   ```
   wininstall node1-node20
   ```

2. Provision nodes 1 through 20 with the osimage rhels6.4-ppc64-netboot-compute.

   ```
   wininstall node1-node20 osimage=rhel6.4-ppc64-netboot-compute
   ```

See Also
noderange(3) | noderange.3, rinstall(8) | rinstall.8, wcons(1) | wcons.1

xcatconfig.8

NAME

xcatconfig - Sets up the Management Node during the xCAT install.

SYNOPSIS

xcatconfig [-h | --help]
xcatconfig [-v | --version]
xcatconfig [-i | --initinstall] [-V | --verbose]
xcatconfig [-u | --updateinstall] [-V | --verbose]
xcatconfig [-f | --force] [-V | --verbose]
DESCRIPTION

**xcatconfig** Performs basic xCAT setup operations on an xCAT management node. This command should not be run on an xCAT Service Node, unless you are making it a Management Node. See flag description below for more details.

OPTIONS

- **-h|--help**
  Displays the usage message.

- **-v|--version**
  Displays the release version of the code.

- **-V|--verbose**
  Displays verbose messages.

- **-i|--initialinstall**
  The install option is normally run as a post operation from the rpm xCAT.spec file during the initial install of xCAT on the Management Node. It will setup the root ssh keys, ssh node keys, xCAT credentials, initialize the database, export directories, start syslog and other daemons as needed after the initial install of xCAT.

- **-u|--updateinstall**
  The update install option is normally run as a post operation from the rpm xCAT.spec file during an update install of xCAT on the Management Node. It will check the setup the root ssh keys, ssh node keys, xCAT credentials, database, exported directories, syslog and the state of daemons needed by xCAT, after the updateinstall of xCAT. If setup is required, it will perform the operation. It will restart the necessary daemons.

- **-k|--sshkeys**
  This option will remove and regenerate the root id_rsa keys. It should only be used, if the keys are deleted or corrupted. The keys must then be distributed to the nodes by installing, running updatenode -k, or using xdsh -K option, for root to be able to ssh to the nodes without being prompted for a password. rsconfig will need to be run to distribute the key to the MM and HMCs. Any device, we need to ssh from the MN to the device will also have to be updated with the new ssh keys.

- **-s|--sshnodehostkeys**
  This option will remove and regenerate the node host ssh keys. It should only be used, if the keys are deleted or are corrupted. The keys must then be redistribute to the nodes by installing, running updatenode -k or using xdcp or pcp to copy the keys from /etc/xcat/hostkeys directory to the /etc/ssh directory on the nodes.

- **-c|--credentials**
  This option will remove all xcat credentials for root and any userids where credentials have been created. It will regenerate roots credentials, but the admin will have to add back all the userid credentials needed with the /opt/xcat/share/xcat/scripts/setup-local-client.sh <username> command. It should only be used, if they are deleted or become corrupted. The root credentials must be redistributed to the service nodes by installing the service node or using updatenode -k. makeconservercf must be rerun to pick up the new credentials, and conserver must be stopped and started.

- **-d|--database**
This option will reinitialize the basic xCAT database table setup. It will not remove any new database entries that have been added, but it is strongly suggested that you backup your database (dumpxCATdb) before using it.

**-f|--force**

The force option may be used after the install to reinitialize the Management Node. This option will regenerate keys, credential and reinitialize the site table. This option should be used, if keys or credentials become corrupt or lost. Additional action must be taken after using the force options. ssh keys must be redistributed to the nodes, site table attributes might need to be restored, makeconservercf needs to be rerun to pick up the new credentials and conserver stopped and started, rspconfig needs to be rerun to distribute the new keys to the MM and the HMCs. A new set of common ssh host keys will have been generated for the nodes. If you wish your nodes to be able to ssh to each other with out password intervention, then you should redistribute these new keys to the nodes. If the nodes hostkeys are updated then you will need to remove their entries from the known_hosts files on the management node before using ssh, xdsh, xdcp. Redistribute credentials and ssh keys to the service nodes and ssh keys to the nodes by using the updatenode -k command.

**-m|--mgtnode**

This option will add the Management Node to the database with the correct attributes set to be recognized by xCAT. This should be run after the hostname of the Management Node is set to the name that will resolve to the cluster-facing NIC.

**-t|--tunables**

This option will set tunable parameters on the Management and Service nodes recommended for your Linux cluster. It will only set them during initial install, if you run xcatconfig -f or xcatconfig -t.

**EXAMPLES**

1. To force regeneration of keys and credentials and reinitialize the site table:

   ```bash
   xcatconfig -f
   ```

2. To regenerate root’s ssh keys:

   ```bash
   xcatconfig -k
   ```

3. To regenerate node host ssh keys:

   ```bash
   xcatconfig -s
   ```

4. To regenerate node host ssh keys and credentials:

   ```bash
   xcatconfig -s -c
   ```

5. To add the Management Node to the DB:

   ```bash
   xcatconfig -m
   ```

**xcatd.8**

**NAME**

**xcatd** - The xCAT daemon
SYNOPSIS

xcatd

DESCRIPTION

The heart of the xCAT architecture is the xCAT daemon xcatd on the management node. This receives requests from the client, validates the requests, and then invokes the operation. The xcatd daemon also receives status and inventory info from the nodes as they are being discovered and installed/booted.

Errors and information are reported through syslog to the /var/log/messages file. You can search for xCAT in those messages.


EXAMPLES

1. To start/stop/restart xcatd on Linux, enter:

   ```
   service xcatd start
   service xcatd stop
   service xcatd restart
   ```

2. To start/stop/restart xcatd on AIX, enter:

   ```
   restartxcatd
   or
   startsrc -s xcatd
   stopsrc -s xcatd
   ```

FILES

/opt/xcat/sbin/xcatd

SEE ALSO

xcatdebug.8

NAME

xcatdebug - Enable or disable the trace facilities for xCAT. (Only supports Linux Operating System)

SYNOPSIS

xcatdebug [ [-f enable | disable [-c {configuration file | subroutine}]] | [-d enable | disable]]
DESCRIPTION

xCAT offers two trace facilities to debug the xCAT:

Subroutine calling trace

Display the calling trace for subroutine when it is called.

The trace message includes: The name of the called subroutine; The arguments which passed to the called subroutine; The calling stack of the subroutine. By default, the trace will be enabled to all the subroutines in the xcatd and plugin modules. The target subroutine can be configured by configuration file or through xcatdebug command line.

The flag -c is used to specify the subroutine list for subroutine calling trace, it can only work with -f. The value of -c can be a configuration file.

configuration file: a file contains multiple lines of SUBROUTINE_DEFINITION subroutine list: SUBROUTINE_DEFINITION | SUBROUTINE_DEFINITION | ...

SUBROUTINE_DEFINITION: is the element for the -c to specify the subroutine list.

The format of SUBROUTINE_DEFINITION: [plugin](subroutine1,subroutine2,...)

If ignoring the [plugin], the subroutines in the () should be defined in the xcatd. e.g. (daemonize,do_installm_service,do_udp_service)

Otherwise, the package name of the plugin should be specified. e.g. xCAT::Utils(isMN,Version) e.g. xCAT_plugin::DBobjectdef(defls,process_request)

The trace log will be written to /var/log/xcat/subcallingtrace. The log file subcallingtrace will be backed up for each running of the xcatdebug -f enable.

Commented trace log

The trace log code is presented as comments in the code of xCAT. In general mode, it will be kept as comments. But in debug mode, it will be commented back as common code to display the trace log.

NOTE: This facility can be enabled by pass the ENABLE_TRACE_CODE=1 global variable when running the xcatd. e.g. ENABLE_TRACE_CODE=1 xcatd -f

This facility offers two formats for the trace log code:

Trace section  ## TRACE_BEGIN # print "In the debugn"; ## TRACE_END

Trace in a single line  ## TRACE_LINE print "In the trace linen";

The commented trace log can be added in xcatd and plugin modules. But following section has been added into the BEGIN {} section of the target plugin module to enable the facility.

```plaintext
if (defined $ENV{ENABLE_TRACE_CODE}) {
    use xCAT::Enabletrace qw(loadtrace filter);
    loadtrace();
}
```

OPTIONS

-f

Enable or disable the subroutine calling trace.

For enable, if ignoring the -c flag, all the subroutines in the xcatd and plugin modules will be enabled.

For disable, all the subroutines which has been enabled by -f enable will be disabled. -c will be ignored.

-c
Specify the configuration file or subroutine list.

**configuration file** [a file contains multiple lines of `\SUBROUTINE_DEFINITION`]

- e.g. `(plugin_command) xCAT_plugin::DBobjectdefs(defls,process_request)
  xCAT::DBobjUtils(getobjdefs)`

**subroutine list** [a string like `\SUBROUTINE_DEFINITION | SUBROUTINE_DEFINITION|. . .`]

- e.g. `"(plugin_command)|xCAT_plugin::DBobjectdefs(defls,process_request)|xCAT::DBobjUtils(getobjdefs)"

-d

Enable or disable the commented trace log.

Note: The xcatd will be restarted for the performing of `-d`

**EXAMPLES**

1. Enable the **subroutine calling trace** for all the subroutines in the xcatd and plugin modules.

   ```
   xcatdebug -f enable
   ```

2. Enable the **subroutine calling trace** for the subroutines configured in the `/opt/xcat/share/xcat/samples/tracelevel0`

   ```
   xcatdebug -f enable -c /opt/xcat/share/xcat/samples/tracelevel0
   ```

3. Enable the **subroutine calling trace** for the plugin_command in xcatd and defls,process_request in the xCAT_plugin::DBobjectdefs module.

   ```
   xcatdebug -f enable -c "xCAT_plugin::DBobjectdefs(defls,process_request)|(plugin_command)"
   ```

4. Disable the **subroutine calling trace** for all the subroutines which have been enabled by `xcatdebug -f enable`.

   ```
   xcatdebug -f disable
   ```

5. Enable the **commented trace log**

   ```
   xcatdebug -d enable
   ```

6. Enable both the **subroutine calling trace** and **commented trace log**

   ```
   xcatdebug -f enable -c /opt/xcat/share/xcat/samples/tracelevel0 -d enable
   ```

**xcatsetup.8**

**NAME**

**xcatsetup** - Prime the xCAT database using naming conventions specified in a config file.
SYNOPSIS

\texttt{xcatsetup \[-s|--stanzas stanza-list\] \[-yesreallydeletenodes\] cluster-config-file}

\texttt{xcatsetup \[-? | -h | --help \] \[-v | --version\]}

DESCRIPTION

The \texttt{xcatsetup} command reads the specified config file that contains general information about the cluster being set up, and naming conventions and IP addresses that you want to use. It then defines the basic objects in the xCAT database representing this cluster configuration. The \texttt{xcatsetup} command prepares the database for the step of discovering the hardware that is connected to the service and cluster networks. The typical steps of setting up a system p cluster are:

1. Install the xCAT software on the management node
2. Create the cluster config file and run xcatsetup
3. Put hardware control passwords in the ppchcp or ppcdirect database table
4. Run makenetworks and makedhcp
5. Run the discovery commands (lsslp, mkhwconn, rspconfig) as described in the System P Hardware Management cookbook.
6. Configure and start services using makehosts, makedns, mkconserver.cf, etc.
7. Create the images that should be installed or booted on the nodes
8. Run nodeset and rpower/rnetboot to boot up the nodes.

The \texttt{xcatsetup} command is intended as a quick way to fill out the database for a cluster that has very regular naming patterns. The only thing it does is fill in database attributes. If your cluster does not follow consistent naming patterns, or has some other special configuration, you should define attribute values manually using mkdef(1)/mkdef.1, instead of using \texttt{xcatsetup}. The cluster config file is meant to be an easy way to prime the database; it is not meant to be a long living file that you update as the cluster changes. If you do want to run xcatsetup again at a later time, because, for example, you added a lot of nodes, you should put the total list of nodes in the config file, not just the new ones. This is because xcatsetup uses some regular expressions for groups (e.g. frame, cec, compute) that would be calculated incorrectly if the config file told xcatsetup about only the new nodes.

Speaking of regular expressions, xcatsetup creates some pretty complicated regular expressions in the database. These are useful because they keep most of the tables small, even for large clusters. But if you want to tweak them, they may be hard to understand. If after running xcatsetup, you want to convert your database to use individual rows for every node, you can do the following:

\begin{verbatim}
lsdef -z all > tmp.stanza
cat tmp.stanza | chdef -z
\end{verbatim}

Many of the sections and attributes in the configuration file can be omitted, if you have a simple cluster, or if you want to create just 1 or 2 of the object types at this time. See the section \texttt{A Simpler Configuration File} for an example of this.

If you want to delete all of the nodes that xcatsetup created, and start over, use the \texttt{--yesreallydeletenodes} option.

Restrictions

1. The \texttt{xcatsetup} command has only been implemented and tested for system p servers so far.
The **config file** is organized in stanza format and supports the keywords in the sample file below. Comment lines begin with “#”. Stanzas can be omitted if you do not want to define that type of object. The only hostname formats supported are those shown in this sample file, although you can change the base text and the numbers. For example, hmc1-hmc3 could be changed to hwmgmt01-hwmgmt12. The hostnames specified must sort correctly. I.e. use node01-node80, instead of node1-node80. This sample configuration file is for a 2 building block cluster.

```
xcat-site:
    domain = cluster.com
    # currently only direct fsp control is supported
    use-direct-fsp-control = 1
    # ISR network topology. For example, one of the following: 128D, 64D, 32D, 16D, 8D, ...
    topology = 32D
    # The nameservers in site table will be set with the value of master automatically.
xcat-service-lan:
    # IP range used for DHCP. If you set the entry, the networks table will be filled
    # automatically with this range and the dhcp interface will be set in the site table.
    dhcp-dynamic-range = 50.0.0.0-50.0.0.200
xcat-hmcs:
    hostname-range = hmc1-hmc2
    starting-ip = 10.200.1.1
xcat-frames:
    # these are the connections to the frames
    hostname-range = frame[1-6]
    num-frames-per-hmc = 3
    # this lists which serial numbers go with which frame numbers
    vpd-file = vpd2bb.stanza
    # There are two rules of defining FSP/BPAs. The first defining the node's host name
    # by increasing the last bit
    # of IP address, while the second defining the node's name by varying the second bit
    # and the third bit of IP.
    # This assumes you have 2 service LANs: a primary service LAN 10.230.0.0/255.255.0.
    # that all of the port 0's
    # are connected to, and a backup service LAN 10.231.0.0/255.255.0.0 that all of the
    # port 1's are connected to.
    # bpa-a-0-starting-ip = 10.230.1.1
    # bpa-b-0-starting-ip = 10.230.2.1
    # bpa-a-1-starting-ip = 10.231.1.1
    # bpa-b-1-starting-ip = 10.231.2.1
    # This assumes you have 2 service LANs: a primary service LAN 40.x.y.z/255.0.0.0
    # that all of the port 0's
    # are connected to, and a backup service LAN 41.x.y.z/255.0.0.0 that all of the port
    # 1's are connected to.
    # "x" is the frame number and "z" is the bpa/fsp id (1 for the first BPA/FSP in the
    # Frame/CEC, 2 for the
    # second BPA/FSP in the Frame/CEC). For BPAs "y" is always 0 and for FSPs "y" is
    # the cec id.
    vlan-1 = 40
    vlan-2 = 41
```
xCAT3 Documentation, Release 2.14.5

(continued from previous page)

xCAT3 Documentation, Release 2.14.5

(continued from previous page)

```plaintext
xCAT3 Documentation, Release 2.14.5

(continued from previous page)

```
VPD File for Frames

The vpd-file specifies the following vpd table attributes for the frames: node, serial, mtm, side. Use the same stanza format that accepted by the chdef(1)/chdef.1 command, as documented in xcatstanzafile(5)/xcatstanzafile.5. The purpose of this file is to enable xCAT to match up frames found through lsslp(1)/lsslp.1 discovery with the database objects created by xcatsetup. All of the frames in the cluster must be specified.

Here is a sample file:

```
frame1:
  objtype=node
  serial=99200G1
  mtm=9A00-100
frame2:
  objtype=node
  serial=99200D1
  mtm=9A00-100
frame3:
  objtype=node
  serial=99200G1
  mtm=9A00-100
frame4:
  objtype=node
  serial=99200D1
  mtm=9A00-100
frame5:
  objtype=node
  serial=99200G1
  mtm=9A00-100
frame6:
  objtype=node
  serial=99200D1
  mtm=9A00-100
```

Supernode Numbers for CECs

The supernode-list file lists what supernode numbers should be given to each CEC in each frame. Here is a sample file:

```
frame1: 0, 1, 16
frame2: 17, 32
frame3: 33, 48, 49
frame4: 64, 65, 80
frame5: 81, 96
frame6: 97(1), 112(1), 113(1), 37(1), 55, 71
```
The name before the colon is the node name of the frame. The numbers after the colon are the supernode numbers to assign to the groups of CECs in that frame from bottom to top. Each supernode contains 4 CECs, unless it is immediately followed by “(#),” in which case the number in parenthesis indicates how many CECs are in this supernode.

A Simpler Configuration File

This is an example of a simple cluster config file that just defines the frames and CECs for 2 frames, without specifying VPD data or supernode numbers at this time.

```
xcat-site:
   use-direct-fsp-control = 1

xcat-frames:
   hostname-range = frame[1-2]

xcat-cecs:
   #hostname-range = cec[01-24]
   hostname-range = f[1-2]c[01-12]
   num-cecs-per-frame = 12

xcat-lpars:
   hostname-range = f[1-2]c[01-12]p[01,05,09,13,17,21,25,29]
```

Database Attributes Written

The following lists which database attributes are filled in as a result of each stanza. Note that depending on the values in the stanza, some attributes might not be filled in.

xcat-site
   site table: domain, nameservers, topology

xcat-hmcs
   site table: ea_primary_hmc, ea_backup_hmc
   nodelist table: node, groups (all HMCs (hmc) ), hidden
   hosts table: node, ip
   ppc table: node, comments
   nodetype table: node, nodetype

xcat-frames
   nodelist table: node, groups (all frames (frame) ), hidden
   ppc table: node, id, hcp, nodetype, sfp
   nodetype table: node, nodetype
   nodehm table: node, mgt
   vpd table: node, serial, mtm, side

xcat-bpas
nodelist table: node, groups (bpa,all), hidden
ppc table: node, id, hcp, nodetype, parent
nodetype table: node, nodetype
nodehm table: node, mgt
vpd table: node, serial, mtm, side

xcat-cecs

nodelist table: node, groups (all CECs (cec), all CECs in a frame (<frame>cec), hidden
ppc table: node, supernode, hcp, id, parent
nodetype table: node, nodetype
nodehm table: node, mgt
nodegroup table: groupname, grouptype, members, wherevals (all nodes in a CEC (<cec>nodes)
nodepos: rack, u

xcat-fsps

nodelist table: node, groups (fsp,all), hidden
ppc table: node, id, hcp, nodetype, parent
nodetype table: node, nodetype
nodehm table: node, mgt
vpd table: node, serial, mtm, side

xcat-building-blocks

site table: sharedtftp, sshbetweennodes(service)
ppc table: node, parent (for frame)

xcat-service-nodes

nodelist table: node, groups (all service nodes (service), all service nodes in a BB (bb<num>service)
hosts table: node, ip, hostnames, otherinterfaces
ppc table: node, id, hcp, parent
nodetype table: node, nodetype, arch
nodehm table: node, mgt, cons
noderes table: netboot
servicenode table: node, nameserver, dhcpserver, tftpserver, nfsserver, conserver, monserver, ftpserver, nimserver, ipforward
nodegroup table: groupname, grouptype, members, wherevals (all nodes under a service node (<servicenode>nodes)
nodepos: rack, u

xcat-storage-nodes

nodelist table: node, groups (all storage nodes (storage), all storage nodes in a BB (bb<num>storage)
hosts table: node, ip, hostnames, otherinterfaces
ppc table: node, id, hcp, parent
nodetype table: node, nodetype, arch
nodehm table: node, mgt, cons
noderes table: netboot, xcatmaster, servicenode
nodepos: rack, u

xcat-compute-nodes

nodelist table: node, groups (all compute nodes (compute) )
hosts table: node, ip, hostnames, otherinterfaces
ppc table: node, id, hcp, parent
nodetype table: node, nodetype, arch
nodehm table: node, mgt, cons
noderes table: netboot, xcatmaster, servicenode
nodepos: rack, u

ll-config

postscripts: postscripts

OPTIONS

-sl|--stanzas stanza-list
A comma-separated list of stanza names that xcatsetup should process in the configuration file. If not specified, it will process all the stanzas that start with ‘xcat’ and some other stanzas that give xCAT hints about how to set up the HPC products.

This option should only be specified if you have already run xcatsetup earlier with the stanzas that occur before this in the configuration file. Otherwise, objects will be created that refer back to other objects that do not exist in the database.

-v|--version
Command Version.

-?|--help
Display usage message.

--yesreallydeletenodes

Delete the nodes represented in the cluster config file, instead of creating them. This is useful if your first attempt with the cluster config file wasn’t quite right and you want to start over. But use this option with extreme caution, because it will potentially delete a lot of nodes. If the only thing you have done so far in your database is add nodes by running xcatsetup, then it is safe to use this option to start over. If you have made other changes to your database, you should first back it up using dumpxCATdb(1) before using this option.

RETURN VALUE

0. The command completed successfully.
1. An error has occurred.
**EXAMPLES**

1. Use the sample config.txt file at the beginning of this man page to create all the objects/nodes for a 2 building block cluster.

   ```
   xcatsetup config.txt
   ```

   The output:

   ### Defining site attributes...
   ### Defining HMCs...
   ### Defining frames...
   ### Defining CECs...
   ### Defining building blocks...
   ### Defining LPAR nodes...

2. Use the simpler config file shown earlier in this man page to create just the frame and cec objects:

   ```
   xcatsetup config-simple.txt
   ```

   The output:

   ### Defining frames...
   ### Defining CECs...

**FILES**

```
/opt/xcat/sbin/xcatsetup
```

**SEE ALSO**

mkdef(1) | mkdef.1, chdef(1) | chdef.1, lsdef(1) | lsdef.1, xcatstanzafile(5) | xcatstanzafile.5, noderange(3) | noderange.3, nodeadd(8) | nodeadd.8

xcatsnap.8

**NAME**

**xcatsnap** - Gathers information for service about the current running xCAT environment.

**SYNOPSIS**

xcatsnap

xcatsnap [-h | --help]

xcatsnap [-v | --version]

xcatsnap [-B | --bypass]

xcatsnap [-d | --dir]
DESCRIPTION

xcatsnap - The xcatsnap command gathers configuration, log and trace information about the xCAT components that are installed. This command only collects the data on the local node on which this command is run. This command is typically executed when a problem is encountered with any of these components in order to provide service information to the IBM Support Center.

This command should only be executed at the instruction of the IBM Support Center.

OPTIONS

-\h|--help
  Displays the usage message.

-\v|--version
  Displays the release version of the code.

-\B|--bypass
  Runs in bypass mode, use if the xcatd daemon is hung.

-\d|--dir
  The directory to put the snap information. Default is /tmp/xcatsnap.

ENVIRONMENT VARIABLES

EXAMPLES

1. Run the xcatsnap routine in bypass mode and put info in /tmp/mydir:
   
   \xcatsnap -B -d /tmp/mydir

2. To run the xcatsnap routine and use default directory /tmp/xcatsnap:
   
   \xcatsnap

xCAT Tools

Disclaimer: Use at your own risk

The following tools are shipped with xCAT and have been contributed by various xCAT community users. The tools are located under /opt/xcat/share/xcat/tools/.

detect_dhcpd

Usage: detect_dhcpd -i interface [-m macaddress] [-t timeout] [-V]

This command can be used to detect the dhcp server in a network for a specific mac address.

(continues on next page)
Options:
- i interface: The interface which facing the target network.
- m macaddress: The mac that will be used to detect dhcp server. Recommend to use the real mac of the node that will be netboot. If no specified, the mac of interface which specified by -i will be used.
- t timeout: The time to wait to detect the dhcp messages. The default value is 10s.

Author: Wang, Xiao Peng

mac2linklocal

Usage: mac2linklocal -m

Determines the IPv6 link local address that is appropriate for a NIC, based on its MAC.

Author: Li, Guang Cheng

mktoolscenter

Usage: mktoolscenter
- ph
- pp
- puser
- ppw
- l
- s
- nfsserver
- nfspath
- profilename
- help

Updates IBM system x server hardware using IBM Bootable Media Creator.

Author: Jim Turner

nodesw

nodesw changes the vlan of a node to a specified vlan
requires xCAT 2.0, Switch configured with SNMP sets, and only tested on SMC8648T

nodesw -h|--help
nodesw [-v] vlan
nodesw [-v] show

Author: Vallard Benincosa

1.3. Admin Guide 777
reorgtbls

DB2 Table Reorganization utility.
This script can be set as a cron job or run on the command line to reorg the xcatdb
→DB2 database tables. It automatically added as a cron job, if you use the
→db2sqlsetup command to create your DB2 database setup for xCAT.
Usage:
  --V - Verbose mode
  --h - usage
  --t - comma delimited list of tables.
Without this flag it reorgs all tables in the xcatdb database .

Author: Lissa Valletta

rmblade

Usage: rmblade [-h|--help]

Response to SNMP for monsetting to remove blade from xCAT when trap is received.
Pipe the MM IP address and blade slot number into this cmd.

Example:
1. user removes a blade from the chassis
2. snmp trap setup to point here
3. this script removes the blade configuration from xCAT
4. so if blade is placed in new slot or back in then xCAT goes
   through rediscover process again.

Author: Jarrod Johnson

rmnodecfg

Usage: rmnodecfg [-h|--help]

Removes the configuration of a node so that the next time you reboot
it, it forces it to go through the discovery process.
This does not remove it completely from xCAT. You may want to do this
command before running noderm to completely purge the system of the node

Author: Vallard Benincosa

test_hca_state

test_hca_state (part of the BEF_Scripts for xCAT) v3.2.27

Usage: test_hca_state NODERANGE [FILTER] | xcoll

  --help Display this help output.
  NODERANGE
    An xCAT noderange on which to operate.
FILTER
A string to match in the output, filtering out everything else. This
is passed to "egrep" and can be a simple string or a regular
expression.

Purpose:
This tool provides a quick and easily repeatable method of
validating key InfiniBand adapter (HCA) and node based InfiniBand
settings across an entire cluster.

Having consistent OFED settings, and even HCA firmware, can be very
important for a properly functioning InfiniBand fabric. This tool
can help you confirm that your nodes are using the settings you
want, and if any nodes have settings discrepancies.

Example output:

```
# This example shows that all of rack 14 has the same settings.
#
root@mgt1:~ # test_hca_state rack14 | xcoll
====================================
rack14
====================================
OFED Version: MLNX_OFED_LINUX-2.0-3.0.0.3 (OFED-2.0-3.0.0):
mlx4_0
  PCI: Gen3
  Firmware installed: 2.30.3200
  Firmware active: 2.30.3200
  log_num_mtt: 20
  log_mtt_per_seg: 3
  Port 1: InfiniBand  phys_state: 5: LinkUp
    state: 4: ACTIVE
    rate: 40 Gb/sec (4X FDR10)
    symbol_error: 0
    port_rcv_errors: 0
  Port 2: InfiniBand  phys_state: 3: Disabled
    state: 1: DOWN
    rate: 10 Gb/sec (4X)
    symbol_error: 0
    port_rcv_errors: 0

IPoIB
  recv_queue_size: 8192
  send_queue_size: 8192
  ib0:
    Mode: datagram
    MTU: 4092
    Mode: up
  ib1:
    Mode: datagram
    MTU: 4092
    Mode: up
```

# This example uses a FILTER on the word 'firmware'. In this case, we've upgraded the firmware across rack11 and rack12.
# - On rack11, we've also restarted the IB stack (/etc/init.d/openibd restart) to activate the new firmware.
# - Rack 12 has also been updated, as we can see from the 'Firmware installed' line, but it's nodes are still running with their prior level of firmware and must reload the IB stack to have it take effect.

root@mgt1:~ # test_hca_state rack11,rack12 firmware | xcoll
====================================
rack11
====================================
Firmware installed: 2.30.3200
Firmware active: 2.30.3200

rack12
====================================
Firmware installed: 2.30.3200
Firmware active: 2.11.1260

Author: Brian Finley
If you encounter any problems with the tools, post a message to the xCAT mailing list for help.

1.4 Advanced Topics

1.4.1 Chain

The chain mechanism is created to allow the administrator to define a series of tasks or operations that will be executed in series on the target node.

The chain mechanism is implemented in xCAT genesis system. The genesis is a customized Linux system, if can be used to do discovery and configuration after booted on the specified node.

Understanding chain table

The chain table (tabdump chain) is an xCAT database table that holds the chain configuration. The following attributes can be defined to perform the chain function:

- currstate
- currchain
- chain

To know how are those three attributes used, reference the picture:
Task Type

xCAT supports following types of task which could be set in the chain:

- **runcmd**

  ```
  runcmd=<cmd>
  ```

Currently only the **bmcsetup** command is officially supplied by xCAT to run to configure the BMC of the compute node. You can find the **bmcsetup** in `/opt/xcat/share/xcat/netboot/genesis/<arch>/fs/bin/`. You also could create your
command in this directory and adding it to be run by `runcmd=<you cmd>`.

```plaintext
runcmd=bmcsetup
```

**Note:** The command `mknb <arch>` is needed before reboot the node.

- **runimage**

  ```plaintext
  runimage=<URL>
  ```

**URL** is a string which can be run by `wget` to download the image from the URL. The example could be:

```plaintext
runimage=http://<IP of xCAT Management Node>/<dir>/image.tgz
```

The **image.tgz** must have the following properties:

- Created using the `tar zcvf` command
- The tarball must include a `runme.sh` script to initiate the execution of the runimage

To create your own image, reference creating image for runimage.

**Tip:** You could try to run `wget http://<IP of xCAT Management Node>/<dir>/image.tgz` manually to make sure the path has been set correctly.

- **osimage**

  ```plaintext
  osimage=<image name>
  ```

This task is used to specify the image that should be deployed onto the compute node.

- **shell**

Causes the genesis kernel to create a shell for the administrator to log in and execute commands.

- **standby**

Causes the genesis kernel to go into standby and wait for tasks from the chain.

### Run Task List During Discovery

To run a list of tasks during the discovery, set the tasks in the chain table by using the `chdef` command to change the chain attribute, before powering on the nodes. For example:

```plaintext
chdef <noderange> chain='runcmd=bmcsetup,osimage=<osimage name>'
```

These tasks will be run after the discovery.

### Run Task List to Configure a Node

Run the `nodeset` command to set the tasks for the compute node and `rpower <noderange> reset` to initiate the running of tasks.

```plaintext
nodeset <noderange> runimage=http://<IP of xCAT Management Node>/image.tgz,osimage=<image name>
rpower <noderange> reset
```

In this example, the `runimage` will be run first, and then the image `<image_name>` will be deployed to the node.
1.4.2 Cluster Maintenance

Compute Node

Changing the Hostname/IP address

Background

If the hostname or IP address has already been modified on compute nodes, follow the steps to change the configuration in xcat.

Remove Old Provision Environment

1. Remove the nodes from DNS configuration
   makedns -d <noderange>

2. Remove the nodes from the DHCP configuration
   makedhcp -d <noderange>

3. Remove the nodes from the goconserver configuration
   makegocons -d <noderange>

Change Definition

1. Change networks table definitions
   lsdef -t network -l

   The output may be like
   
   10_0_0_0-255_0_0_0 (network)
   192_168_122_0-255_255_255_0 (network)

   Change the networks table definitions. For example 192_168_122_0-255_255_255_0 is a original network configuration which should be modified to 192_168_123_0-255_255_255_0:

   rmdef -t network 192_168_122_0-255_255_255_0
   mkdef -t network 192_168_123_0-255_255_255_0 net=192.168.123.0 mask=255.255.255.0

2. Change the hostname in the xCAT database (This command only supports one node at a time). For many nodes you will have to write a script.

   # changes node1 to node2 in the database
   chdef -t node -o node1 -n node2

3. Change the hostname and IP address in the /etc/hosts file
   - If you do not use the hosts table in xCAT to create the /etc/hosts file, edit the /etc/hosts file and change your hostname and IP address entries directly.
• If you use the xCAT hosts table, and your nodes are defined by name in the hosts table, the hosts table must be updated with the new names when we changed the node name using chdef command. If the hosts tables contains regular expression, you have to rewrite the regular expression to match your new hostname and IP address.

• If these is no regular expression in the hosts table, you can run

```
nodech <newnodename> hosts.ip="x.xx.xx.xx"
```

Update The Provision Environment

1. Configure the new names in DNS
   ```
makedns -n
   ```

2. Configure the new names in DHCP
   ```
makedhcp -a
   ```

3. Configure the new names in goconserver
   ```
makegocons
   ```

Replacing Nodes

OpenPOWER Nodes

When compute nodes are physically replaced in the frame, leverage xCAT to re-discover the compute nodes. The following guide can be used for:

• IBM OpenPOWER S822LC for HPC

1. Identify the machine(s) to be replaced: frame10cn02.

2. [Optional] It’s recommended to set the BMC IP address back to DHCP, if it was set to STATIC.
   ```
   rspconfig frame10cn02 ip=dhcp
   ```

3. Set the outgoing machine to offline and remove attributes of the machine:
   ```
   nodeset frame10cn02 offline
   chdef frame10cn02 mac=""
   ```

4. If using MTMS-based discovery, fill in the Model-Type and Serial Number for the machine:
   ```
   chdef frame10cn02 mtn=8335-GTB serial=<<NEW SERIAL NUMBER>>
   ```

5. If using SWITCH-based discovery, go on to the next step. The switch and switch-port should already be set in the compute node definition.
   Node attributes will be replaced during the discovery process (mtn, serial, mac, etc.)
6. Search for the new BMC in the open range:

```
bmcdiscover --range <IP open range> -w -z
```

7. When the BMC is found, start the discovery with the following commands:

```
rsetboot /node-8335.* net
rpower /node-8335.* boot
```

Management Node

Changing the hostname/IP address

Overview

This document is intended to describe the steps that must be taken if you need to change your Linux Management Node’s hostname and/or IP address after the cluster is installed and configured by xCAT. This documentation will only cover the changes by xCAT and will not try to cover any other changes by any other tools.

Backup your xCAT data

Clean up the database by running `tabprune` command:

```
tabprune -a auditlog
tabprune -a eventlog
```

Now take a snapshot of the Management Node. This will also create a database backup. You can use this data as reference if needed.

```
xcatsnap -d
```

Stop xCAT

You need to stop the xcat daemon and any other applications that are using the xCAT database on the Management Node and the Service Nodes. To determine your database, run

```
lsxcatd -a | grep dbengine
```

To stop xCAT:

```
service xcatd stop
```

Stop The Database

For all databases except SQLite, you should stop the database. For example

```
service postgresql stop
service mysqld stop
```
Change the Management Hostname

- hostname command

  ```
  hostname <new_MN_name>
  ```

- Update the hostname configuration files:

  Add hostname in `/etc/hostname`
  Add HOSTNAME attribute in `/etc/sysconfig/network` (only for [RHEL])

Update Database Files

You need to update the new MN hostname or IP address in several database configuration files.

SQLite

Nothing to do.

PostgreSQL

- Edit `/etc/xcat/cfgloc` file...

  ```
  Replace Pg:dbname=xcatdb;host=<old_MN_ip>|xcatadm|xcat20 with Pg:dbname=xcatdb;host=<new_MN_ip>|xcatadm|xcat20.
  ```

- Edit config database config file `/var/lib/pgsql/data/pg_hba.conf`...

  ```
  Replace host all all <old_MN_ip>/32 md5 with host all all <new_MN_ip>/32 md5
  ```

MySQL

- Edit `/etc/xcat/cfgloc`...

  ```
  Replace mysql:dbname=xcatdb;host=<old_MN_ip>|xcatadmin|xcat20 with mysql:dbname=xcatdb;host=<new_MN_ip|xcatadmin|xcat20
  ```

Start the database

```
service postgresql start
service mysqld start
```

Start xCAT

```
service xcatd start
```

Verify your new database setup

```
lscatd -a | grep dbengine
tabdump site # if output exists
```
Change The Definition In xCAT Database

Change the site table master attribute

```
chdef -t site master=<new_MN_ip>
```

Change all IP address attribute relevant to the MN IP address

For example, the old IP address was “10.6.0.1”

- Query all the attributes with old address

  ```
  lsdef -t node -l | grep "10.6.0.1"
  ...
  conserver=10.6.0.1
  conserver=10.6.0.1
  conserver=10.6.0.1
  conserver=10.6.0.1
  nfsserver=10.6.0.1
  servicenode=10.6.0.1
  xcatmaster=10.6.0.1
  →install/autoinst
  nfsserver=10.6.0.1
  servicenode=10.6.0.1
  tftpserver=10.6.0.1
  xcatmaster=10.6.0.1
  servicenode=10.6.0.1
  xcatmaster=10.6.0.1
  ...
  ```

- Looking at the list above, taking `conserver` as an example, query the nodes with `conserver=10.6.0.1`:

  ```
  lsdef -t node -w conserver="10.6.0.1"
  ...
  cn1 (node)
  cn2 (node)
  cn3 (node)
  cn4 (node)
  ```

- Change the `conserver` address for nodes `cn1,cn2,cn3,cn4`

  ```
  chdef -t node cn1-cn4 conserver=<new_ip_address>
  ```

- Repeat the same process for the other attributes containing the old IP address.

Change networks table

Check your networks table to see if the network definitions are still correct, if not edit accordingly

```
lsdef -t network -l
chdef -t network <key=value>
```
Check Result

You can check whether all the old address has been changed using

```bash
dumpxCATdb -P <new database backup path>
cd <new database backup path>
fgrep "10.6.0.1" *.csv
```

If the old address still exists in the *.csv file, you can edit this file, then use the following command to restore the records

```bash
tabrestore <xxx.csv>
```

Generate SSL credentials(optional)

Use the following command to generate new SSL credentials: `xcatconfig -c`.

Then update the following in xCAT:

- Update the policy table with new management node name and replace:

  ```
  "1.4","old_MN_name",,",","trusted",,
  ```

  with:

  ```
  "1.4","new_MN_name",,",","trusted",`
  ```

- Setup up goconserver with new credentials

  ```bash
  makegocons
  ```

External DNS Server Changed

- Update nameserver entries in `/etc/resolv.conf`

- Update nameserver attribute in site table

  ```bash
  chdef -t site -o clustersite nameservers="new_ip_address1,new_ip_address2"
  ```

- Update site forwarders in DB

  ```bash
  chdef -t site -o clustersite forwarders="new_ip_address1,new_ip_address2"
  ```

- Run command `makedns -n`

Domain Name Changed

Change the entries in `/etc/hosts`.
Change the `/etc/resolv.conf`, forwarders attribute in site table.

```bash
lsdef -t site -o clustersite -i forwarders
chdef -t site -o clustersite forwarders <new list>
```
Change the domain name in the xCAT database site table.

```bash
chdef -t site -o clustersite domain=<new_domainname>
```

From xCAT 2.8, multiple domains is supported in the cluster. Update the networks table definition.

```bash
lsdef -t network -l
chdef -t network -o <network_name> ddnsdomain=<new_domainname1,new_domainname2>
```

**Update the Provision Environment**

Determine if the Management node is defined in the database, assuming it was done correctly using xcatconfig -m, by running:

```bash
lsdef __mgmtnode
```

If it exists, then use the return name and do the following:

- Remove the MN from DNS configuration
  ```bash
  makedns -d <old_MN_name>
  ```
- Remove the MN from the DHCP configuration
  ```bash
  makedns -d <old_MN_name>
  ```
- Remove the MN from the conserver configuration
  ```bash
  makedns -d <old_MN_name>
  ```
- Change the MN name in the xCAT database
  ```bash
  chdef -t node -o <old_MN_name> -n <new_MN_name>
  ```
- Add the new MN to DNS
  ```bash
  makedns -n
  ```
- Add the MN to dhcp
  ```bash
  makedhcp -a
  ```
- Add the MN to goconserver
  ```bash
  makegocons
  ```

**Update the genesis packages**

Run `mknb <arch>` after changing the ip of MN.

**Service Node**

**Changing the Hostname/IP address**
Change compute node definition relevant to the service node

Change the settings in database. Below shows a method to find out where the old IP address settings (take 10.6.0.1 as an example) are used in Hierarchy environment.

- Query the old attribute

```bash
lsdef -t node -l | grep "10.6.0.1"
# below is output of the above command. We can find out that nfsserver and servicenode are using the old IP address setting.
nfsserver=10.6.0.1
servicenode=10.6.0.1
```

- Query the nodes whose nfsserver is 10.6.0.1

```bash
lsdef -w nfsserver==10.6.0.1
# below is output of the above command
 cn1 (node)
 cn2 (node)
 cn3 (node)
 cn4 (node)
```

- Change the nfsserver address for cn1,cn2,cn3,cn4 by running the following command:

```bash
chdef -t node cn1-cn4 nfsserver=<new service node IP address>
```

Database Connection Changes

Granting or revoking access privilege in the database for the service node.

- For MySQL, refer to *Granting/Revoking access to the database for Service Node Clients*.

Update Provision Environment on Service Node

If you are using service nodes to install the nodes and using `/etc/hosts` for hostname resolution, you need to copy the new `/etc/hosts` from the management node to the service nodes, then run `makedns -n` on the service nodes.

For example:

```bash
xdcp <servicenodes> /etc/hosts /etc/hosts
xdsh <servicenodes> makedns -n
```

Reinstall the nodes to pick up all changes

```bash
nodeset <noderange> osimage=<osimagename>
```

Then use your normal command to install the nodes like rinstall, rnetboot, etc.

Software and Firmware Inventory

xCAT provides a command `sinv` that checks the software and firmware inventory in this cluster.

The command creates an inventory of the input software/firmware check, comparing to other machines in the cluster and produces an output of node that are installed the same and those that are not.
This command uses the xdsh parallel command, so it is in itself a parallel command, and thus can be run on multiple cluster nodes at one time and is hierarchical.

The sinv command is designed to check the configuration of the nodes in a cluster. The command takes as input command line flags, and one or more templates which will be compared against the output of the xdsh command, designated to be run on the nodes in the noderange.

The nodes will then be grouped according to the template they match and a report returned to the administrator in the output file designated or to stdout.

sinv supports checking the output from the rinv or xdsh command.

For example, if you wanted to check the ssh level on all the nodes and make sure they were the same as on the service node, you would first generate a template from the “good” service node (sn1) by running the following:

```
xdsh sn1 "rpm -qa | grep ssh " | xdshcoll > /tmp/sinv/sinv.template
```

To execute sinv using the sinv.template generated above on the nodegroup, testnodes ,writing output report to /tmp/sinv.output, enter:

```
sinv -c "xdsh testnodes rpm -qa | grep ssh" -p /tmp/sinv/sinv.template -o /tmp/sinv.output
```

The report will look something like this, if every node matches:

```
Command started with following input:

xdsh cmd:xdsh testnodes rpm -qa | grep ssh.
Template path:/tmp/sinv/sinv.template.
Template cnt:0.
Remove template:NO.
Output file:/tmp/sinv/sinv.output.
Exactmatch:NO.
Ignorefirst:NO.
Seed node:None.
file:None.
The following nodes match /tmp/lissav/sinv.template:
testnodes
```

There are many options for matching and reporting supported by the sinv command, including support to run rinv and generate reports on firmware inventory.

### 1.4.3 Migrate xCat Management node

**xCAT Management Node Migration**

This document describes how to migrate xCAT Management node to a new node. The following example describes a typical scenario, this example is verified on redhat7.3.

1. Initially, the first xcat management node is active, and the second node is passive.
2. Backup all useful xCAT data from xCAT Management node to back-up server at regular intervals.
3. When the first xCAT management node is broken, use backup to restore original xCAT data to the second node with the same host name and ip.
Backup Old xCAT Management Node

Backup xCAT management node data to backup server:

1.1 Backup xCAT important files and directories:

1. Get `installdir` from `site` table, backup `installdir` directory, in this case, back up `install` directory:

```
lsdef -t site clustersite -i installdir
Object name: clustersite
installdir=/install
```

2. Backup these two xCAT directories:

```
~/.xcat
/etc/xcat
```

Note: Backing up `~/.xcat` is for all users who have xCAT client certs.

3. If there are customized files and directories for `otherpkgdir`, `pkgdir`, `pkglist` or `template` in some `osimage` definitions, backup these files and directories. For example:

```
lsdef -t osimage customized_rhels7.4-x86_64-install-compute -i otherpkgdir,pkgdir, pkglist,template
Object name: customized_rhels7.4-x86_64-install-compute
otherpkgdir=/<customized_dir>/post/otherpkgs/rhels7.4/x86_64
pkgdir=/<customized_pkgdir>/rhels7.4/x86_64
pkglist=/<customized_pkglist_dir>/compute.rhels7.pkglist
template=/<customized_temp_dir>/compute.rhels7tmpl
```

1.2 Backup ssh related files:

```
/etc/ssh
~/.ssh
```

1.3 Backup host files:

```
/etc/resolv.conf
/etc/hosts
/etc/passwd
/etc/group
```

1.4 Backup yum resource files:

```
/etc/yum.repos.d
```

1.5 Backup conserver conf files:

```
/etc/conserver.cf
```

1.6 Backup DNS related files:

```
/etc/named
/etc/named.conf
/etc/named.iscdlv.key
```

(continues on next page)
1.7 Backup dhcp files:

/etc/dhcp
/var/lib/dhcpd
/etc/sysconfig/dhcpd
/etc/sysconfig/dhcpd6

1.8 Backup apache:

/etc/httpd
/var/www

1.9 Backup tftp files:

/tftpboot

1.10 Backup NTP configure file:

/etc/ntp.conf

1.11 Backup database configure files (optional):

• [PostgreSQL]

/var/lib/pgsql/data/pg_hba.conf
/var/lib/pgsql/data/postgresql.conf

1.12 Backup NFS (optional):

/etc/exports
/var/lib/nfs
/etc/sysconfig/nfs

1.13 (optional)

Besides the files mentioned above, there may be some additional customization files and production files that need to be backup, depending on your local unique requirements. Here are some example files that can be considered:

/.profile
/.rhosts
/etc/auto_master
/etc/auto/maps/auto.u
/etc/motd
/etc/security/limits
/etc/netsvc.conf
/etc/inetd.conf
/etc/security/passwd
/etc/security/group
/etc/services
/etc/inittab (andmore)

1.14 Backup the xCAT database tables for the current configuration, using command:
dumpxCATdb -p <your_backup_dir>

1.15 Save all installed xCAT RPM names into a file:

rpm -qa|grep -i xCAT > xcat_rpm_names

1.16 (Optional) Find customization made to files installed from packages, backup these files. For example

rpm -q --verify -a conserver-xcat
rpm -q --verify -a xCAT-server
rpm -q --verify -a syslinux-xcat
rpm -q --verify -a xCAT-client
rpm -q --verify -a xCAT

**Restore xCAT management node**

2.1 Power off old xCAT management server before configuring new xCAT management server

2.2 Configure new xCAT management server using the same ip and hostname as old xCAT management server. Configure the same additional network for hardware management network if needed, for example, bmc network or hmc network. xCAT management server setup refer to Prepare the Management Node

2.3 Overwrite files/directories mentioned in above 1.2, 1.3, 1.4 from backup server to new xCAT management server

2.4 Download xcat-core and xcat-dep tar ball, then install xCAT in new xCAT management server, refer to install xCAT

2.5 Use rpm -qa|grep -i xCAT to list all xCAT RPMs in new xCAT management node, compare these RPMs base name with those in xcat_rpm_names from above 1.15. If some RPMs are missing, use yum install <rpm_package_basename> to install missing RPMs.

2.6 If use MySQL/MariaDB/PostgreSQL, migrate xCAT to use MySQL/MariaDB/PostgreSQL refer to Configure a Database

2.7 To restore the xCAT database

1. Restore xCAT database from the /dbbackup/db directory without auditlog and eventlog, enter:

   ```
   restorexCATdb -p /dbbackup/db
   ```

2. Restore the xCAT database including auditlog and eventlog from the /dbbackup/db directory, enter:

   ```
   restorexCATdb -a -p /dbbackup/db
   ```

3. (optional) Overwrite files in above 1.11, restart PostgreSQL:

   ```
   service postgresql restart
   ```

2.8 Overwrite remaining files/directories mentioned in above 1.1, 1.5, 1.6, 1.7, 1.8, 1.9, 1.10, 1.12; If needed, check if files exist based on above 1.13 and 1.16.

2.9 Verify xCAT:

   ```
   tabdump site
   ```

2.10 Restart named, use nslookup to check DNS:
2.11 Restart conserver, use rcons to check console:

```
service conserver restart
rcons <cn1>
```

2.12 Configure DHCP:

```
makedhcp -n
makedhcp -a
```

2.13 Restart httpd for REST API, for more information refer to Rest API:

```
service httpd restart
```

### 1.4.4 Confluent

Confluent is a new codebase with a few goals in mind:

- Augment xCAT 2.X series
- Potentially serve in place of xCAT-server for the next generation of xCAT

**Disclaimer:** *Confluent code in conjunction with xCAT 2.X is currently BETA, use at your own risk*

**confluent-server**

**Getting Started**

Confluent is intended to be used in conjunction with xCAT. The following documentation assumes that xCAT is already installed and configured on the management node.

**Download confluent**

To build from source, ensure your machine has the correct development packages to build rpms, then execute the following:

- Clone the git repo:

  ```
git clone https://github.com/xcat2/confluent.git
  ```

- Build the **confluent-server** and **confluent-client** packages:

  ```
cd confluent/confluent_server ; ./buildrpm ; cd -
cd confluent/confluent_client ; ./buildrpm ; cd -
  ```

**Install**
dependency

The following example describes the steps for **rhels7.5** on **ppc64le**:

```bash
yum install libffi-devel.ppc64le
yum install openssl-devel
pip install crypto pyasn1 pycrypto eventlet pyparsing netifaces scrapy pysnmp
→paramiko pyghmi pyte
```

confluent

**Installing xCAT-confluent via rpm:**

```bash
rpm -ivh /root/rpmbuild/RPMS/noarch/confluent_server-*.noarch.rpm --nodeps
rpm -ivh /root/rpmbuild/RPMS/noarch/confluent_client-*.noarch.rpm --nodeps
```

You may find it helpful to add the confluent paths into your system path:

```bash
CONFLUENTROOT=/opt/confluent
export PATH=$CONFLUENTROOT/bin:$PATH
export MANPATH=$CONFLUENTROOT/share/man:$MANPATH
```

**Configuration**

**Starting/Stopping confluent**

To start confluent:

```bash
service confluent start
```

To stop confluent:

```bash
service confluent stop
```

If you want confluent daemon to start automatically at bootup, add confluent service to **chkconfig**:

```bash
chkconfig confluent on
```

**Replacing conserver with confluent**

A new keyword, **consoleservice**, has been added to the xCAT site table to allow the system administrator to control between **conserver** and **confluent**. If consoleservice is not set, default behavior is to use **conserver**.

Set the consoleservice to confluent:

```bash
chdef -t site consoleservice='confluent'
```

Run **makeconfluentcfg** to create the confluent configuration files:

```bash
makeconfluentcfg
```

Use **rcons** as before to start the console session.:
Web Browser access

Confluent-api and confluent-consoles are able to be accessed from the browser. It is **highly** recommended that you create a non-root user to access the sessions:

```
Create the non-root user on the management node
# useradd -m xcat

Create a non-root user in confetty
# /opt/confluent/bin/confetty create users/xcat

Set the password for the non-root user
# /opt/confluent/bin/confetty set users/xcat password="mynewpassword" password="********"
```

Rest Explorer

Configure the httpd configuration for confluent-api by creating a `confluent.conf` file under `/etc/httpd/conf.d/` directory:

```
The example uses server ip: 10.2.5.3 and port 4005

# cat /etc/httpd/conf.d/confluent.conf
LoadModule proxy_http_module modules/mod_proxy_http.so
<Location /confluent-api>
  ProxyPass http://10.2.5.3:4005
</Location>
#
# restart httpd
service httpd restart
```

Now point your browser to: `http://<server ip>:<port>` and log in with the non-root user and password created above.

Confluent consoles

confluent-web is provided in a subdirectory under the confluent project confluent_web

Download the content of that directory to `/var/www/html/confluent` and point your browser to:

```
http://<server ip>/confluent/consoles.html
```

confluent-client

Starting the confetty client

As the root user, running `/opt/confluent/bin/confetty` will open the confetty prompt
Creating a non root user

It’s recommended to create a non root user to use to connect to confetty

1. Create a non-root user on the management node:

   ```bash
   useradd -m xcat
   ```

2. As root, create a non-root user in confetty:

   ```bash
   /opt/confluent/bin/confetty create users/xcat
   ```

3. Set the password for the non-root user:

   ```bash
   /opt/confluent/bin/confetty set users/xcat password="mynewpassword"
   password="********"
   ```

Connecting to a remote server

In order to do remote sessions, keys must first be added to /etc/confluent

- /etc/confluent/privkey.pem - private key
- /etc/confluent/srvcert.pem - server cert

If you want to use the xCAT Keys, you can simply copy them into /etc/confluent

```bash
cp /etc/xcat/cert/server-key.pem /etc/confluent/privkey.pem
cp /etc/xcat/cert/server-cert.pem /etc/confluent/srvcert.pem
```

The user and password may alternatively be provided via environment variables:

```bash
CONFLUENT_USER=xcat
CONFLUENT_PASSPHRASE="mynewpassword"
export CONFLUENT_USER CONFLUENT_PASSPHRASE
```

Start confetty, specify the server IP address:

```bash
confetty -s <remote_ip>
```

If you want to run a confluent command against another host, could set the CONFLUENT_HOST variable:

```bash
CONFLUENT_HOST=<remote_ip>
export CONFLUENT_HOST
```

1.4.5 Go Conserver

goconserver is a conserver replacement written in Go programming language. For more information, see https://github.com/xcat2/goconserver/
Quickstart

1. For refresh xCAT installation, run the command below to start and configure goconserver
   makegocons
   
   The new console logs will start logging to /var/log/consoles/<node>.log

1. For xCAT updating, and use conserver before, following the step below to enable goconserver
   (a) stop conserver on management node
   systemctl stop conserver.service

   (b) For hierarchical cluster, shall also stop conserver on service nodes, and config goconserver as
   console server:
   xdsh service 'systemctl stop conserver.service'
   chdef -t group -o service setupconserver=2

   (c) start and configure goconserver
   makegocons
   
   The new console logs will start logging to /var/log/consoles/<node>.log

2. To check the console status of nodes, use:
   makegocons -q

Configuration

Location

The configuration file for goconserver is located at /etc/goconserver/server.conf. When the configuration is changed, reload using: systemctl restart goconserver.service. An example for the configuration could be found from Example Conf.

Tag For xCAT

xCAT generates a configuration file that includes a identifier on the first line. For example:

```
# generated by xcat Version 2.13.10 (git commit 7fcd37ff8b7ce37c021a9497d4baec151af547ac0, built Thu Jan 25 07:15:36 EST 2018)
```

makegocons checks for this token and will not make changes to the configuration file if it exists. This gives the user the ability to customize the configuration based on their specific site configuration.

Multiple Output Plugins

goconserver support console redirection to multiple targets with file, tcp and udp logger plugins. The entry could be found like below:
console:

    # the console session port for client(congo) to connect.
    port: 12430

logger:
    # for file logger
    file:
        # multiple file loggers could be specified
        # valid fields: name, logdir
        - name: default
            logdir: /var/log/goconserver/nodes/
        - name: xCAT
            logdir: /var/log/consoles

tcp:
    - name: logstash
      host: briggs01
      port: 9653
      ssl_key_file: /etc/xcat/cert/server-cred.pem
      ssl_cert_file: /etc/xcat/cert/server-cred.pem
      ssl_ca_cert_file: /etc/xcat/cert/ca.pem

    - name: rsyslog
      host: sn02
      port: 9653

udp:
    - name: filebeat
      host: 192.168.1.5
      port: 512

With the configuration above, the console log files for each node would be written in both /var/log/goconserver/nodes/<node>.log and /var/log/consoles/<node>.log. In addition, console log content will be redirected into remote services specified in the tcp and udp sections.

Verification

To check if goconserver works correctly, see the log file /var/log/goconserver/server.log.

1. Check if TCP logger has been activated.

    When starting goconserver, if the log message is like below, it means the TCP configuration has been activated.

    ```json
    {"file": "github.com/xcat2/goconserver/console/logger/tcp.go (122)"}, "level": "info", →"msg": "Starting TCP publisher: logstash", "time": "2018-03-02T21:15:35-05:00"
    {"file": "github.com/xcat2/goconserver/console/logger/tcp.go (122)"}, "level": "info", →"msg": "Starting TCP publisher: sn02", "time": "2018-03-02T21:15:35-05:00"
    ```

2. Debug when encounter error about TCP logger

    If the remote service is not started or the network is unreachable, the log message would be like below.

    ```json
    ```
Check the service status and the network configuration including the selinux and iptable rules. When the remote service works correctly, TCP or UDP logger of goconserver would recover automatically.

Reconnect Interval

If console node is defined with ondemand=false, when the console connection could not be established, goconserver would reconnect automatically. The interval time could be specified at

```console
console:
  # retry interval in second if console could not be connected.
  reconnect_interval: 10
```

Performance Tuning

Adjust the worker numbers to leverage multi-core processor performance based on the site configuration.

```global:
  # the max cpu cores for workload
  worker: 4
```

Debug

The log level for goconserver is defined in /etc/goconserver/server.conf

```global:
  # debug, info, warn, error, fatal, panic
  log_level: info
```

REST API

goconserver provides REST API interface to manage the node sessions. For detail, see REST.

1.4.6 Docker

Dockerized xCAT

Overview

Docker is a popular containment environment making it easier to create, deploy, and run applications/services. With Docker, applications/services are shipped as Docker images and run in Docker containers. Docker containers include the application/services and all of its running environment, which have isolated namespace and network stack but share the kernel on the host operating system. The server on which Docker containers run is called Docker host. Docker image can only run on Docker host with the same architecture.
Compose is a native tool shipped by Docker to define and run applications in Docker containers. You use a Compose file to configure your applications/services. Then, using a single command, you create and start all the services from your configuration.

By pulling xCAT Docker image and running xCAT Docker image in a container, you get a well-configured xCAT Management Node to start cluster management work, without worrying about the xCAT installation and configuration on different OS and various hardware platforms.

**xCAT Docker images**

xCAT ships 2 Docker images for Docker host with different architecture:

- “xcat/xcat-ubuntu-x86_64”: run on x86_64 Docker host
- “xcat/xcat-ubuntu-ppc64le”: run on ppc64le Docker host

Each of the xCAT Docker images above has 3 tags corresponding to different xCAT release inside Docker image:

- “latest”: the latest xCAT release
- “2.11”: xCAT 2.11 release
- “dev”: the latest xCAT development snapshot build

A Docker image with specified tag should be denoted in format “[docker image name]:[tag]”, for example, “xcat/xcat-ubuntu-x86_64:2.11”. If not specified, default tag is “latest”.

**Run xCAT in Docker**

Each container with xCAT Docker image running inside is a xCAT management node, the container connects to the compute nodes and hardware control points in the cluster via “bridge” network on the Docker host. Generally, a xCAT container should connect to 2 types of networks (the 2 types of networks might be one network in some cluster):

- “mgtnet”: Management network, the network used by the Management Node to install operating systems and manage the nodes. The Management Node and in-band Network Interface Card (NIC) of the nodes are connected to this network. A bridge “mgtbr” will be created and attached to the network interface facing the compute nodes on Docker host
- “svcnet”: Service network, the network used by the Management Node to control the nodes using out-of-band management using the Service Processor. A bridge “svcbr” will be created and attached to the network interface facing the hardware control points
You are required to determine and specify some necessary information, so that xCAT is well configured and running when the container is started. This includes:

- Docker container: xCAT Docker image with specified xCAT release; the data volumes with directories on Docker host including xCAT DB tables, the osimage resources and xCAT logs, which can be used to save and restore the data of xCAT service
- network information: the network configuration of the xCAT container
- cluster information: the domain of the cluster

The information can be specified in 2 ways to run xCAT container:

- in options and arguments of docker commands such as `docker network create` or `docker run`
- in the “docker-compose.yml”, which contains all the configuration to start xCAT containers with Compose. This is the recommended way to start xCAT container.

The 2 ways are described step-by-step in the following sections of this documentation. We recommend you start xCAT container with Compose.

When xCAT Docker container is started, you can access it with `sudo docker attach`, however, we recommend you to access it via “ssh”.

### Setup Docker host

#### Install Docker Engine

The Docker host to run xCAT Docker image should be a baremental or virtual server with Docker v1.10 or above installed. For the details on system requirements and Docker installation, refer to Docker Installation Docs.

**Note:** Docker images can only run on Docker hosts with the same architecture. Since xCAT only ships x86_64 and ppc64le Docker images, running xCAT in Docker requires x86_64 or ppc64 Docker Hosts.

### Shutdown the SELinux/Apparmor on Docker host

If the SELinux or Apparmor on Docker host is enabled, the services/applications inside Docker Container might be confined. To run xCAT in Docker container, SELinux and Apparmor on the Docker host must be disabled.

SELinux can be disabled with:

```
echo 0 > /selinux/enforce
sed -i 's/^SELINUX=.*$/SELINUX=disabled/' /etc/selinux/config
```

AppArmor can be disabled with:

```
/etc/init.d/apparmor teardown
```

### Run xCAT in Docker with Compose (Recommended)

#### An example configuration in the documentation

To demonstrate the steps to run xCAT in a Docker container, take a cluster with the following configuration as an example
The name of the docker container running xCAT: xcatmn
The hostname of container xcatmn: xcatmn
The dns domain of the cluster: clusters.com

The management network object: mgtnet
The network bridge of management network on Docker host: mgtbr
The management network interface on the Docker host facing the compute nodes: enol
The IP address of enol on Docker host: 10.5.107.1/8
The IP address of xCAT container in management network: 10.5.107.101

The service network object: svcnet
The network bridge of service network on Docker host: svcbr
The service network interface on the Docker host facing the hardware control points: eno2
The IP address of eno2 on Docker host: 192.168.0.1/8
The IP address of xCAT container in service network: 192.168.0.101

Install Compose on Docker host

Compose v1.7.0 or above should be installed on Docker host:
curl -L https://github.com/docker/compose/releases/download/1.7.0-rc1/docker-compose-
`uname -s`-`uname -m` > /usr/local/bin/docker-compose
chmod +x /usr/local/bin/docker-compose

Customize docker-compose file

xCAT ships a docker-compose template docker-compose.yml, which is a self-description file including all the configurations to run xCAT in container. You can make up your compose file based on it if you are familiar with Compose file, otherwise, you can simply customize it with the following steps:

1. Specify the xCAT Docker image

image: [xCAT Docker image name]:[tag]
specify the name and tag of xCAT Docker image, for example “xcat/xcat-ubuntu-x86_64:2.11”

2. Specify the cluster domain name

extra_hosts:
  - "xcatmn.[cluster domain name] xcatmn:[Container's IP address in management_network]"
specify the cluster domain name, i.e, “site.domain” on xCAT Management Node, for example “clusters.com”, and the IP address of xCAT Docker container in the management network, such as “10.5.107.101”

3. Specify the IP address of xCAT container in service network and management network

networks:
  svcnet:
    ipv4_address : [Container's IP address in service network]
  mgtnet:
    ipv4_address : [Container's IP address in management network]
specify the IP address of Docker container in service network and management network. If the “svcnet” is the same as “mgtnet”, the 2 “svcnet” lines should be commented out.

4. Specify the Docker network objects for management network and service network

```
networks:
  mgtnet:
    driver: "bridge"
    driver_opts:
      com.docker.network.bridge.name: "mgtbr"
    ipam:
      config:
        - subnet: [subnet of mgtbr in CIDR]
          gateway: [IP address of mgtbr]

  svcnet:
    driver: "bridge"
    driver_opts:
      com.docker.network.bridge.name: "svcbr"
    ipam:
      config:
        - subnet: [subnet of svcbr in CIDR]
          gateway: [IP address of svcbr]
```

specify the network configuration of bridge networks “mgtnet” and “svcnet”, the network configuration of the bridge networks should be same as the network interfaces attached to the bridges. The “mgtnet” and “svcnet” might the same network in some cluster, in this case, you can ignore the lines for “svcnet”.

5. Specify the Data Volumes for xCAT Docker container

```
volumes:
  #the "/install" volume is used to keep user data in xCAT, 
  #such as osimage resources
  #the user data can be accessible if specified
  - [The directory on Docker host mounted to "/install" inside container]:/install
  #the "/.dbbackup" volume is used to backup and restore xCAT DB tables 
  #Dockerized xCAT will restore xCAT DB tables if specified
  #"dumpxCATdb -p ./dbbackup" should be run manually to save xCAT DB inside container
  - [The directory on Docker host mounted to save xCAT DB inside container]:./dbbackup
  #the "/.logs" value is used to keep xCAT logs 
  #the xCAT logs will be kept if specified
  - [The directory on Docker host to save xCAT logs inside container]:/var/log/xcat/
```

specify the volumes of the xCAT container used to save and restore xCAT data

**Start xCAT Docker container with Compose**

After the “docker-compose.yml” is ready, the xCAT Docker container can be started with

1
This command starts up the Docker container and attaches the network interface “eno1” of Docker host to the bridge network “mgtbr”. It is a little complex due to a Compose bug #1003. The commands should be run successively in one line to avoid breaking the network connection of the network interface of Docker host.

To remove the container, you can run

```
docker-compose -f "docker-compose.yml" down; \
ifdown eno1; \ 
ifup eno1
```

To update the xCAT Docker image, you can run

```
docker-compose -f "docker-compose.yml" pull
```

### Known Issues

When you start up xCAT Docker container, you might see an error message at the end of the output like

```
Could't connect to Docker daemon at http+unix://var/run/docker.sock - is it running?.
→ If it's at a non-standard location, specify the URL with the DOCKER_HOST environment variable.
```

You can ignore it, the container has already been running. It is a Docker bug #1214

### Run xCAT in Docker with Docker native commands

#### Pull the xCAT Docker image from DockerHub

Now xCAT ships xCAT Docker images(x86_64 and ppc64le) on the DockerHub:

To pull the latest xCAT Docker image for x86_64, run

```
sudo docker pull xcat/xcat-ubuntu-x86_64
```

On success, you will see the pulled Docker image on Docker host

```
[root@dockerhost1 ~]# sudo docker images
REPOSITORY TAG IMAGE ID CREATED VIRTUAL SIZE
xcat/xcat-ubuntu-x86_64 latest 3a3631463e83 2 days ago 643 MB
```

### An example configuration in the documentation

To demonstrate the steps to run xCAT in a Docker container, take a cluster with the following configuration as an example
Docker host: dockerhost1
The name of the docker container running xCAT: xcatmn
The hostname of container xcatmn: xcatmn

The management network object: mgtnet
The network bridge of management network on Docker host: mgtbr
The management network interface on the Docker host facing the compute nodes: eno1
The IP address of eno1 on Docker host: 10.5.107.1/8
The IP address of xCAT container in management network: 10.5.107.101
The dns domain of the cluster: clusters.com

Create a customized Docker network on the Docker host

Docker Networks provide complete isolation for containers, which gives you control over the networks your containers run on. To run xCAT in Docker, you should create a customized bridge network according to the cluster network plan, instead of using the default bridge network created on Docker installation.

As an example, we create a customized bridge network “mgtbr” which is attached to the network interface “eno1” facing the compute nodes and inherits the network configuration of “eno1”. Since the commands to create the network will break the network connection on “eno1”, you’d better run the commands in one line instead of running them separately

```
sudo docker network create --driver=bridge --gateway=10.5.107.1 --subnet=10.5.107.0/8, --o "com.docker.network.bridge.name"="mgtbr" mgtnet; 
ifconfig eno1 0.0.0.0; 
brctl addif mgtbr eno1; 
ip link set mgtbr up
```

- `--driver=bridge` specify the network driver to be “bridge”
- `--gateway=10.5.107.1` specify the network gateway to be the IP address of “eno1” on Docker host. which will also be the IP address of network bridge “mgtbr”
- `--subnet=10.5.107.0/8` specify the subnet in CIDR format to be the subnet of “eno1”
- `com.docker.network.bridge.name"="mgtbr"` specify the bridge name of management network
- `ifconfig eno1 0.0.0.0` delete the IP address of “eno1”
- `brctl addif mgtbr eno1` attach the bridge “br0” to network interface “eno1”
- `ip link set mgtbr up` change the state of “br0” to UP

When the network is created, you can list it with `sudo docker network ls` and get the information of it with `sudo docker inspect mgtnet`.

Run xCAT in Docker container

Now run the xCAT Docker container with the Docker image “xcat/xcat-ubuntu-x86_64” and connect it to the newly created customized Docker network “mgtnet”

```
sudo docker run -it --privileged=true --hostname=xcatmn --name=xcatmn --add-host="xcatmn.clusers.com xcatmn:10.5.107.101" --volume /docker/xcatdata:/install --net=mgtnet --ip=10.5.107.101 xcat/xcat-ubuntu-x86_64
```

- use `--privileged=true` to give extended privileges to this container
• use **--hostname** to specify the hostname of the container, which is available inside the container

• use **--name** to assign a name to the container, this name can be used to manipulate the container on Docker host

• use **--add-host="xcatmn.clusers.com xcatmn:10.5.107.101"** to write the /etc/hosts entries of Docker container inside container. Since xCAT use the FQDN(Fully Qualified Domain Name) to determine the cluster domain on startup, make sure the format to be “<FQDN> <hostname>: <IP Address>”, otherwise, you need to set the cluster domain with `chdef -t site -o clustersite domain="clusters.com"` inside the container manually

• use **--volume /docker/xcatdata/:/install** to mount a pre-created “/docker/xcatdata” directory on Docker host to “/install” directory inside container as a data volume. This is optional, it is mandatory if you want to backup and restore xCAT data.

• use **--net=mgtnet** to connect the container to the Docker network “mgtnet”

• use **--ip=10.5.107.101** to specify the IP address of the xCAT Docker container

**Work with xCAT**

Once xCAT Docker container is running, you can use xCAT with the shell inside the container. Since the ssh service has been enabled on the Docker container startup, you can connect to the container via ssh. The default root password is “cluster”.

Once you attach or ssh to the container, you will find that xCAT is running and configured, you can play with xCAT and manage your cluster now.

Currently, since xCAT can only generate the diskless osimages of Linux distributions with the same OS version and architecture with xCAT MN. If you need to provision diskless osimages besides ubuntu x86_64 with xCAT running in the Docker, you can use `imgexport` and `imgimport` to import the diskless osimages generated before.

If you start up the xCAT Docker container by following the steps described in sections above strictly, without specifying “--dns=IP_ADDRESS…”, “--dns-search=DOMAIN…”, or “--dns-opt=OPTION…” options, Docker uses the /etc/resolv.conf of the host machine (where the docker daemon runs). Any DNS problem inside container, make sure the DNS server on the Docker host works well.

**Save and Restore xCAT data**

According to the policy of Docker, Docker image should only be the service deployment unit, it is not recommended to save data in Docker image. Docker uses “Data Volume” to save persistent data inside container, which can be simply taken as a shared directory between Docker host and Docker container.

For dockerized xCAT, there are 3 volumes recommended to save and restore xCAT user data.

• “/install”: save the osimage resources under “/install” directory

• “/var/log/xcat/”: save xCAT logs

• “/.dbbackup”: save and restore xCAT DB tables. You can save the xCAT DB tables with `dumpxCATdb -p /./dbbackup/` inside container and xCAT will restore the tables on the container start up.

**Docker life-cycle management in xCAT**

The Docker linux container technology is currently very popular. xCAT can help managing Docker containers. xCAT, as a system management tool has the natural advantage for supporting multiple operating systems, multiple architectures and large scale clusters.
This document describes how to use xCAT for docker management, from Docker Host setup to docker container operations.

Note:

This document was verified with:

- Docker Version 1.10, 1.11
- Docker API version 1.22

Docker Host has been verified on the following OS/ARCH combinations:

- Ubuntu 14.04.3,x86_64
- Ubuntu 15.10,x86_64
- Ubuntu 16.04,x86_64
- Ubuntu 16.04,ppc64el

Setting up Docker Host

The Docker Host is the bare metal server or virtual machine where Docker containers can run. It will be called dockerhost in the following sections.

The dockerhost at a minimum must provide the following:

- An Operating System for running docker daemon
- The certification related files to be used by Docker service for trusted connection.

Preparing osimage for docker host

The osimage represents the image of the Operating System which will be deployed on the dockerhost.

Copy files out from DVDs/ISOs and generate

[ubuntu x86_64]

```bash
copycds ubuntu-xxx-server-amd64.iso
```

[ubuntu16.04 ppc64el]

```bash
copycds ubuntu-16.04-server-ppc64el.iso
```

Create pkglist and otherpkglist of osimage for dockerhost

The pkglist file should contain the following:

```bash
# cat /install/custom/ubuntu/ubuntu.pkglist
openssh-server
ntp
gawk
```

(continues on next page)
nfs-common
snmpd
bridge-utils

The otherpkglist file should contain the following:

[ubuntu x86_64]

```bash
# cat /install/custom/ubuntu/ubuntu_docker.pkglist
docker-engine
```

[ubuntu16.04 ppc64el]

At the time of this writing (February 2016), docker package is not available for ppc64el architecture from docker.org. You can follow instructions below on how to manually download and install it.

- Download docker engine for ppc64el:

```bash
wget http://launchpadlibrarian.net/251622081/docker.io_1.10.3-0ubuntu4_ppc64el.deb -O /install/docker_ppc64el/docker.io_1.10.3-0ubuntu4_ppc64el.deb
```

- Configure otherpkgdir like this:

```bash
otherpkgdir=/install/docker_ppc64el
```

- The otherpkglist file should be:

```bash
# cat /install/custom/ubuntu/ubuntu_docker.pkglist
docker.io
```

Create the osimage for dockerhost

The osimage for dockerhost will be like this:

[ubuntu x86_64]

```bash
# lsdef -t osimage ub14.04.03-x86_64-dockerhost
Object name: ub14.04.03-x86_64-dockerhost
  imagetype=linux
  osarch=x86_64
  osname=Linux
  osvers=ubuntu14.04.3
  otherpkglist=/install/custom/ubuntu/ubuntu_docker.pkglist
  pkgdir=/install/ubuntu14.04.3/x86_64
  pkglist=/install/custom/ubuntu/ubuntu.pkglist
  profile=compute
  provmethod=install
  template=/opt/xcat/share/xcat/install/ubuntu/compute.tmpl
```

[ubuntu16.04 ppc64el]

```bash
# lsdef -t osimage ub16.04-ppc64el-dockerhost
Object name: ub16.04-ppc64el-dockerhost
  imagetype=linux
```

(continues on next page)
Preparing setup trust connection for docker service and create docker network object

Currently, a customer defined network object is needed when create a docker container with static IP address, it can be done with the command:

```
chdef host01 -p postbootscripts="setupdockerhost <netobj_name>=<subnet>/<netmask>@<gateway>:nicname"
```

- `netobj_name`: the network object to be created, it will be used in `dockernics` when creating docker container
- `subnet/netmask@gateway`: the network which the IP address of docker container running on the docker host must be located in. If `nicname` is specified, the `subnet/netmask` must be the subnet of the nic `nicname` located in. And `gateway` shall be the IP address of the nic `nicname`.
- `nicname`: the physical nic name which will be attached to the network object

For example, a network object `mynet0` with subnet `10.0.0.0/16` and gateway `10.0.101.1` on nic `eth0` can be created with the command:

```
chdef host01 -p postbootscripts="setupdockerhost mynet0=10.0.0.0/16@10.0.101.1:eth0"
```

Start OS provisioning for dockerhost

Reference *Initialize the Compute for Deployment* for how to finish an OS deployment.

Docker instance management

After the dockerhost is ready, a docker instance can be managed through xCAT commands. In xCAT, a docker instance is represented by a node whose definition can be like this:

```
# lsdef host01c01
Object name: host01c01
  dockerhost=host01:2375
  dockernics=mynet0
  groups=docker,all
  ip=10.0.120.1
  mac=02:42:0a:00:78:01
  mgt=docker
  postbootscripts=otherpkgs
  postscripts=syslog,remoteshell,syncfiles
```
The command `mkdef` or `chdef` can be used to create a new docker instance node or change the node attributes. Specify any available unused ip address for `ip` attribute. `mac` attribute is optional and if left unset, will be filled in by `mkdocker` command.

After docker instance node is defined, use command `makehosts host01c01` to add node `host01c01` and its IP address 10.0.120.1 into /etc/hosts.

### Create docker instance

```
mkdocker <node> [image=<image_name>] [command=<command>] [dockerflag=<docker_flags>]
```

- `node` - The node object which represents the docker instance
- `image` - The image name that the docker instance will use
- `command` - The command that the docker will run
- `dockerflag` - A JSON string which will be used as parameters to create a docker. Reference docker API v1.22 for more information about which parameters can be specified for “dockerflag”.

To create the docker instance `host01c01` with image `ubuntu` and command `/bin/bash`, use:

```
mkdocker host01c01 image=ubuntu command=/bin/bash dockerflag="\"AttachStdin\":true,\\n-"AttachStdout\":true,\"AttachStderr\":true,\"OpenStdin\":true}"
```

### Remove docker instance

```
rmdocker <node>
```

The command `rmdocker host01c01` can be used to remove the docker instance `host01c01`.

### List docker information

```
lsdocker <dockerhost|node> [-l|--logs]
```

To list all the running docker instances on the dockerhost `host01`, use `lsdocker host01`.
To list the info of docker instance `host01c01`, use `lsdocker host01c01`.
To get log info of docker instance `host01c01`, use `lsdocker host01c01 --logs`.

### Start docker instance

```
rpower <node> start
```

### Stop docker instance

```
rpower <node> stop
```
Restart docker instance

\texttt{rpower <node> restart}

Pause all processes within a docker instance

\texttt{rpower <node> pause}

Unpause all processes within a docker instance

\texttt{rpower <node> unpause}

Check docker instance status

\texttt{rpower <node> state}

Troubleshooting

If things go wrong:

- After dockerhost node boots, check contents of /var/log/xcat/xcat.log file on the dockerhost for errors.
- Verify nicname specified in \texttt{Preparing setup trust connection for docker service and create docker network object} section exists on the docker host. Depending on the version of Ubuntu OS and host architecture, it could be \texttt{eth0}, \texttt{em1}, \texttt{eno1}, or \texttt{enp0s1}. Verify by running on the dockerhost:

  \texttt{ip addr show dev <nicname>}

- Run \texttt{ps -ef | grep docker} to verify docker engine is running with configured options. It should look something like

  \texttt{root 3703 1 0 Apr15 ? 00:12:28 /usr/bin/docker da\textendash ename -H unix://\textendash run/docker.sock -H tcp://host01:2375 \textendash tls \textendash tlsacert=/root/.docker/ca-cert.pem \textendash tlscert=/root/.docker/dockerhost-cert.pem \textendash tlskey=/root/.docker/dockerhost-cert.pem \textendash tlsverify=true \textendash raw-logs}

  If the output is missing some options, verify that file /lib/systemd/system/docker.service contains the following lines

  \texttt{EnvironmentFile=-/etc/default/docker}
  \texttt{ExecStart=/usr/bin/docker da\textendash ename $DOCKER_OPTS -H fd://}

Docker Registry in xCAT

Docker Registry is a stateless, highly scalable server side application that stores and lets you distribute Docker images. This document describes how to set up a local private docker registry on Ubuntu 15.04 on x86_64.
Note: Ensure that docker registry is not already set up on this docker host.

Setting Up Docker Host

Install Docker version 1.6.0 or newer.

Setting Up Docker Registry Manually

Docker registry needed to be set up on xCAT’s MN.

This section describes two methods of setting up docker registry manually.

First, create some folders where files for this tutorial will live.

```bash
mkdir /docker-registry && cd $_
mkdir certs
```

Copy xCAT server certificate and key to certs folder.

```bash
cp /etc/xcat/cert/server-cert.pem certs/domain.crt
cp /etc/xcat/cert/server-key.pem certs/domain.key
```

Method 1: Start Docker Registry Directly

Create Configuration File

Define configuration file `docker-registry` under `/docker-registry/` folder as below.

```bash
#!/bin/bash

docker_command=$1
if [ $docker_command = "start" ]; then
docker_ps_result=$(docker ps -a | grep "registry")
if [ -z $docker_ps_result ]; then
docker run -d -p 5000:5000 --restart=always --name registry \
  -v ‘pwd’/data:/data \
  -e REGISTRY_STORAGE_FILESYSTEM_ROOTDIRECTORY=/data \
  -v ‘pwd’/certs:/certs \
  -e REGISTRY_HTTP_TLS_CERTIFICATE=/certs/domain.crt \
  -e REGISTRY_HTTP_TLS_KEY=/certs/domain.key \
  registry:2
else
docker start registry
fi
elif [ $docker_command = "stop" ]; then
docker stop registry
else
echo "The parameter is wrong."
fi
```
Starting Docker Registry as a Service

Create `docker-registry.service` file in `/etc/systemd/system/`, add the following contents to it.

```ini
[Unit]
Description=Docker Registry

[Service]
Type=oneshot
RemainAfterExit=yes
WorkingDirectory=/docker-registry
ExecStart=/bin/bash docker-registry start
ExecStop=/bin/bash docker-registry stop

[Install]
WantedBy=default.target
```

Start registry service:

```
service docker-registry start
```

Method 2: Managing Docker Registry with Compose

Docker Compose is a tool for defining and running Docker applications. It could help setting up registry.

Install Docker Compose

Compose can also be run inside a container, from a small bash script wrapper. To install compose as a container run:

```
curl -L https://github.com/docker/compose/releases/download/1.5.2/docker-compose-`uname -s`-`uname -m` > /usr/local/bin/docker-compose
chmod +x /usr/local/bin/docker-compose
```

Create Configuration File

Define configuration file `docker-compose.yml` under `/docker-registry/` folder as below.

```yaml
registry:
  restart: always
  image: registry:2
  ports:
    - 5000:5000
  environment:
    - REGISTRY_STORAGE_FILESYSTEM_ROOTDIRECTORY: /data
    - REGISTRY_HTTP_TLS_CERTIFICATE: /certs/domain.crt
    - REGISTRY_HTTP_TLS_KEY: /certs/domain.key
  volumes:
    - ./data:/data
    - ./certs:/certs
```

The environment section sets environment variables in the Docker registry container. The Docker registry app knows to check this environment variable when it starts up and to start saving its data to the `/data` folder as a result.
Starting Docker Registry as a Service

Create `docker-registry.service` file in `/etc/systemd/system/`, add the following contents to it.

```ini
[Unit]
Description=Docker Registry

[Service]
Type=simple
Restart=on-failure
RestartSec=30s
WorkingDirectory=/docker-registry
ExecStart=/usr/local/bin/docker-compose up

[Install]
WantedBy=default.target
```

Start registry service:

```
service docker-registry start
```

Accessing Docker Registry from other docker host

Copy ca.crt file from xCAT MN to a client machine. Client machine must be a docker host.

```bash
scp username@xCAT_MN_ip:/etc/xcat/cert/ca.pem /etc/docker/certs.d/domainname:5000/ca.crt
```

List Available Images in Registry

```
curl -k https://domainname:5000/v2/_catalog
```

Pull Images from Registry

Just use the “tag” image name, which includes the domain name, port, and image name.

```bash
docker pull domainname:5000/imagename
```

Push Images to Registry

Before the image can be pushed to the registry, it must be tagged with the location of the private registry.

```bash
docker tag imagename domainname:5000/imagename
```

Now we can push that image to our registry.

```bash
docker push domainname:5000/imagename
```

**note:** If there is a problem with the CA certificate, edit the file `/etc/default/docker` so that there is a line that reads: `DOCKER_OPTS="--insecure-registry domianname:5000"`. Then restart Docker daemon

```bash
service docker restart
```

```bash
```
1.4.7 Domain Name Resolution

Cluster Name Resolution

Setting up name resolution and having the nodes be resolved to IP addresses are required in xCAT clusters.

There are many different ways to configure name resolution in your cluster. Four of the common choices will be described in this section (look for Option #: headings):

1. In a basic (non-hierarchical) cluster, point all nodes to a DNS server running on the management node. This is the most common setup.
2. In a basic (non-hierarchical) cluster, point all nodes to an external DNS running at your site. This requires that all of your nodes have network connectivity to your site.
3. In a hierarchical cluster, point all compute nodes to their service node. Make service node as the compute nodes’ DNS server.
4. Don’t use DNS, just distribute the /etc/hosts file to every node. If you choose this you will have to distribute new versions of the /etc/hosts file to all the cluster nodes whenever you add new nodes to the cluster, and you will have to specify site.master and all other server attributes in the database as IP addresses.

But before any of those options are chosen, there are some things that must be done for all of the options.

Set the site domain Attribute

First set the domain attribute in the xCAT site table to the hostname domain you want to use for your cluster nodes:

```
chdef -t site domain=mycluster.com
```

Create xCAT Network Definitions

When you installed xCAT, it ran `makenetworks` to create network definitions for the networks that the management node is connected to (i.e. has NICs configured for). If the cluster-facing NICs were not configured when xCAT was installed, or if there are more networks in the cluster that are only available via the service nodes or compute nodes, create the new network definitions now.

Use the `mkdef` command to add additional networks to the xCAT database. (See the network for information about each attribute.) For example:

```
mkdef -t network clusternet net=11.0.0.0 mask=255.255.0.0 gateway=11.0.0.254 domain=app.cluster.com
```

Note: The `makedns` command (mentioned below) will only add nodes into the DNS configuration if the network for the node is defined.

If you want to use a different hostname domain or a different set of nameservers for nodes that are on a particular network, set those attributes in the corresponding network object:

```
mkdef -t network clusternet domain=app.cluster.com nameservers=1.2.3.4
```
Populate the /etc/hosts File

All of the management node interfaces and all of the nodes need to be added to the /etc/hosts file on the xCAT management node (whether you are using the DNS option or not). You can either edit the /etc/hosts file by hand, or use makehosts.

If you edit the file by hand, it should look similar to:

```
127.0.0.1 localhost localhost.localdomain
50.1.2.3 mgmtnode-public mgmtnode-public.cluster.com
10.0.0.100 mgmtnode mgmtnode.cluster.com
10.0.0.1 node1 node1.cluster.com
10.0.0.2 node2 node2.cluster.com
```

Verify that your /etc/hosts file contains entries for all of your management node interfaces. Manually add any that are missing.

If your node names and IP addresses follow a regular pattern, you can easily populate /etc/hosts by putting a regular expression in the xCAT hosts table and then running makehosts. To do this, you need to first create an initial definition of the nodes in the database, if you haven’t done that already:

```
mkdef node[01-80] groups=compute,all
```

Next, put a regular expression in the hosts table. The following example will associate IP address 10.0.0.1 with node1, 10.0.0.2 with node2, etc:

```
chdef -t group compute ip='|node(\d+)|10.0.0.($1+0)|'
```

(For an explanation of the regular expressions, see the man xcatdb.) Then run:

```
makehosts compute
```

and the following entries will be added to /etc/hosts:

```
10.0.0.1 node01 node01.cluster.com
10.0.0.2 node02 node02.cluster.com
10.0.0.3 node03 node03.cluster.com
```

This information is used by the makehosts command to add the additional interface hostnames etc. to the /etc/hosts file. It is also used by xCAT adapter configuration postscripts to automatically configure the additional network interfaces on the node. See the section (refer to Specifying additional network interfaces for cluster nodes).

**Note:** It is a convention of xCAT that for Linux systems the short hostname is the primary hostname for the node, and the long hostname is an alias. To have the long hostname be the primary hostname, you can use the -l option on the makehosts command.

Preparing for Using a DNS

If you are choosing any of the options for using DNS, follow these steps:

**NOTE:** This documentation only applies to the xCAT makedns command using the ddns.pm plugin. The ddns.pm plugin is based on named9/bind9, and can not support named8/bind8 due to syntax difference.

- Set the nameservers and forwarders attributes in the xCAT site table. The nameservers attribute identifies the DNS server hostname/ip that the nodes point to in their /etc/resolv.conf files. The forwarders attribute are the
DNS server’s ip that can resolve external hostnames. If you are running a DNS on the xCAT MN, it will use the forwards DNS server to resolve any hostnames it can’t.

For example:

```
chdef -t site nameservers=10.0.0.100 forwards=9.14.8.1,9.14.8.2
```

Create an /etc/resolv.conf file on the management node

Edit /etc/resolv.conf to contain the cluster domain value you set in the site table’s domain attribute above, and to point to the same DNS server you will be using for your nodes (if you are using DNS).

### Option #1: Running DNS on Your Management Node

This is the most common set up. In this configuration, a DNS running on the management node handles all name resolution requests for cluster node names. A separate DNS in your site handles requests for non-cluster hostnames.

There are several bits of information that must be included in the xCAT database before running the makedns command.

You must set the forwards attribute in the xCAT cluster site definition. The forwards value should be set to the IP address of one or more nameservers at your site that can resolve names outside of your cluster. With this set up, all nodes ask the local nameserver to resolve names, and if it is a name that the management node DNS does not know about, it will try the forwarder names.

An xCAT network definition must be defined for each management network used in the cluster. The net and mask attributes will be used by the makedns command.

A network domain and nameservers value must be provided either in the network definition corresponding to the nodes or in the site definition.

For example, if the cluster domain is mycluster.com, the IP address of the management node, (as known by the cluster nodes), is 100.0.0.41 and the site DNS servers are 50.1.2.254,50.1.3.254 then you would run the following command.

```
chdef -t site domain=mycluster.com nameservers=100.0.0.41 forwards=50.1.2.254,50.1.3.254
```

Once /etc/hosts is populated with all of the nodes’ hostnames and IP addresses, configure DNS on the management node and start it:

```
makedns -n
```

The resolv.conf files for the compute nodes will be created automatically using the domain and nameservers values set in the xCAT network or site definition.

If you add nodes or change node names or IP addresses later on, rerun makedns which will automatically restart named.

To verify the DNS service on management node is working or not:

```
nslookup <host> <mn's ip>
```

For example:

```
nslookup node1 100.0.0.41
```
Option #2: Use a DNS That is Outside of the Cluster

If you already have a DNS on your site network and you want to use it to solve the node name in your cluster, follow the steps in this section to configure your external dns (against your local dns on xCAT MN/SN).

- Set the site nameservers value to the IP address of the external name server.
  
  chdef -t site nameservers=<external dns IP>

- Set the correct information of external dns into the /etc/resolv.conf on your xCAT MN.

  The domain and nameservers values must be set correctly in /etc/resolv.conf. Which should have the same values with the ones your set in the site table.

  - Manually set up your external dns server with correct named.conf and correct zone files
  - Add the TSIG to the named.conf of your external dns for makedns command to update external dns

  ```
  tabdump -w key==omapi passwd
  get the key like "omapi","xcat_key",
  →"MFRCeHJybMxveVBNaE1YT1BFTFJzN2JuREFMeEMwU0U=",,,
  Add it to your named.conf
  key xcat_key {
    algorithm hmac-md5;
    secret "MFRCeHJybMxveVBNaE1YT1BFTFJzN2JuREFMeEMwU0U=";
  }
  
  Then change each zone to make your zones to allow this key to update.

  ```

  ```
  zone "1.168.192.IN-ADDR.ARPA." in {
    type master;
    allow-update {
      key xcat_key;
    };
    file "db.192.168.1";
  }
  ```

  - To update the name resolution entries from /etc/hosts or hosts table of xCAT MN to external DNS, run makedns -e

    Alternatively, you can set site.externaldns=1 and run makedns

Option #3: Run DNS on Management Node and Service Nodes

When you have service nodes, the recommended configuration is to run DNS on the management node and all of the service nodes. Two choices are available:

Option #3.1: Using the management node as DNS server, the service nodes as forwarding/caching servers.

This means the DNS server on the management node is the only one configured with all of the node hostname/IP address pairs. The DNS servers on the service nodes are simply forwarding/caching the DNS requests to the management node.
Option #3.2: Using the management node as DNS master, the service nodes as DNS slaves.

This means the DNS server on the management node is configured with all of the node hostname/IP address pairs, and allowed to transfer DNS zones to the service nodes. The DNS servers on the service nodes are DNS slaves, so that if the management node goes down for some reason, then you still have the service nodes to be able to do name resolution.

The configurations are described below for the two options, note the differences marked as Option #3.x.

Note: for Option #3.1, only the DNS on the management node will use the forwards setting. The DNS servers on the service nodes will always forward requests to the management node.

Note: for Option #3.2, make sure servicenode.nameserver=2 before you run makedns -n.

Once /etc/hosts is populated with all of the nodes’ hostnames and IP addresses, configure DNS on the management node and start it:

```
makedns -n
```

When the /etc/resolv.conf files for the compute nodes are created the value of the nameserver in /etc/resolv.conf is gotten from site.nameservers or networks.nameservers if it’s specified.

For example:

```
chdef -t site nameservers="<xcatmaster>" # for Option #3.1
OR
chdef -t network <my_network> nameservers="<xcatmaster>" # for Option #3.1
chdef -t site nameservers="<xcatmaster>, MN_IP" # for Option #3.2
OR
chdef -t network <my_network> nameservers="<xcatmaster>, MN_IP" # for Option #3.2
```

The <xcatmaster> keyword will be interpreted as the value of the <xcatmaster> attribute of the node definition. The <xcatmaster> value for a node is the name of it’s server as known by the node. This would be either the cluster-facing name of the service node or the cluster-facing name of the management node.

Note: The site nameservers value must be set to <xcatmaster> before you run makedhcp.

Make sure that the DNS service on the service nodes will be set up by xCAT.

Assuming you have all of your service nodes in a group called “service” you could run a command similar to the following.

```
chdef -t group service setupnameserver=1 # for Option #3.1
chdef -t group service setupnameserver=2 # for Option #3.2
```

For Linux systems, make sure DHCP is set up on the service nodes.

```
chdef -t group service setupdhcp=1
```

If you have not yet installed or diskless booted your service nodes, xCAT will take care of configuring and starting DNS on the service nodes at that time. If the service nodes are already running, restarting xcatd on them will cause xCAT to recognize the above setting and configure/start DNS:

```
xdsh service 'service xcatd restart' # linux
```

If you add nodes or change node names or IP addresses later on, rerun makedns. The DNS on the service nodes will automatically pick up the new information.
Specifying additional network interfaces for cluster nodes

You can specify additional interface information as part of an xCAT node definition. This information is used by xCAT to populate the /etc/hosts file with the extra interfaces (using the makehosts command) and providing xCAT adapter configuration scripts with the information required to automatically configure the additional interfaces on the nodes.

To use this support you must set one or more of the following node definition attributes.

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>nicips</td>
<td>IP addresses for additional interfaces (NIC). (Required)</td>
</tr>
<tr>
<td>nichostnamesuffixes</td>
<td>Hostname suffixes per NIC. This is a suffix to add to the node name to use for the hostname of the additional interface. (Optional)</td>
</tr>
<tr>
<td>nictypes</td>
<td>NIC types per NIC. The valid &quot;nictypes&quot; values are: &quot;ethernet&quot;, &quot;infiniband&quot;, and &quot;bmc&quot;. (Optional)</td>
</tr>
<tr>
<td>niccustomscripts</td>
<td>The name of an adapter configuration postscript to be used to configure the interface. (Optional)</td>
</tr>
<tr>
<td>nicnetworks</td>
<td>xCAT network definition names corresponding to each NIC. (ie. the network that the nic ip resides on.) (Optional)</td>
</tr>
<tr>
<td>nicaliases</td>
<td>Additional aliases to set for each additional NIC. (These are added to the /etc/hosts file when using makehosts). (Optional)</td>
</tr>
</tbody>
</table>

The additional NIC information may be set by directly editing the xCAT nics table or by using the xCAT *defs commands to modify the node definitions.

The details for how to add the additional information is described below. As you will see, entering this information manually can be tedious and error prone. This support is primarily targeted to be used in conjunction with other IBM products that have tools to fill in this information in an automated way.

Managing additional interface information using the xCAT *defs commands

The xCAT *defs commands (mkdef, chdef, and lsdef) may be used to manage the additional NIC information in the xCAT database.

When using the these commands the expanded nic* attribute format will always be used.

Expanded format for nic* attributes

The expanded format will be the nics attribute name and the nic name, separated by a “.” (dot).(ie. <nic attr="" name="">.<nic name=""> )

For example, the expanded format for the nicips and nichostnamesuffixes attributes for a nic named eth1 might be:

```
nicips.eth1=10.1.1.6
nichostnamesuffixes.eth1=-eth1
```

If we assume that your xCAT node name is compute02 then this would mean that you have an additional interface (“eth1”) and that the hostname and IP address are compute02-eth1 and 10.1.1.6.

A “|” delimiter is used to specify multiple values for an interface. For example:

```
nicips.eth2=60.0.0.7|70.0.0.7
nichostnamesuffixes.eth2=’-eth2|-eth2-lab’
```

This indicates that eth2 gets two hostnames and two IP addresses. (compute02-eth2 gets 60.0.0.7 and compute02-eth2-lab” gets “70.0.0.7”.)

For the nicaliases attribute a list of additional aliases may be provided.
This indicates that the **compute02-eth1** hostname would get the additional two aliases, alias1 alias2, included in the `/etc/hosts` file, (when using the `makehosts` command).

The second line indicates that **compute02-eth2** would get the additional alias alias3 and that **compute02-eth-lab** would get alias4

**Setting individual nic attribute values**

The nic attribute values may be set using the `chdef` or `mkdef` commands. You can specify the nic* values when creating an xCAT node definition with `mkdef` or you can update an existing node definition using `chdef`.

**Note:** `chdef` does not support using the “-m” and “-p” options to modify the nic* attributes.

**nicips example:**

```
chdef -t node -o compute02 nicips.eth1=11.10.1.2 nicips.eth2='80.0.0.2|70.0.0.2'
```

**Warning:** According to DNS rules a hostname must be a text string up to 24 characters drawn from the alphabet (A-Z), digits (0-9), minus sign (-), and period (.). When you are specifying “nichostnamesuffixes” or “nicaliases” make sure the resulting hostnames will conform to this naming convention.

```
chdef -t node -o compute02 nichostnamesuffixes.eth1=-eth1 nichostnamesuffixes.eth2='eth2|-eth2-lab'
```

This value indicates that the hostname for **eth1** should be “compute02-eth1”. For **eth2** we had two IP addresses so now we need two suffixes. The hostnames for **eth2** will be “compute02-eth2” and “compute02-eth2-lab”. The IP for “compute02-eth2” will be “80.0.0.2” and the IP for “compute02-eth2-lab” will be “70.0.0.2”.

```
chdef -t node -o compute02 nictypes.eth1=ethernet nictypes.eth2='ethernet|ethernet'
```

This value indicates that all the nics are ethernet. The valid “nictypes” values are: “ethernet”, “infiniband”, and “bmc”.

```
chdef -t node -o compute02 niccustomscripts.eth1=cfgeth niccustomscripts.eth2='cfgeth|cfgeth'
```

**Warning:** According to DNS rules a hostname must be a text string up to 24 characters drawn from the alphabet (A-Z), digits (0-9), minus sign (-), and period (.). When you are specifying “nichostnamesuffixes” or “nicaliases” make sure the resulting hostnames will conform to this naming convention.
In this example “cfgeth” is the name of an adapter configuration postscript to be used to configure the interface.

nicnetworks example:

```
chdef -t node -o compute02 nicnetworks.eth1=clstrnet11 nicnetworks.eth2="clstrnet80|clstrnet-lab"
```

In this example we are saying that the IP address of “eth0” (ie. compute02-eth1 -> 11.10.1.2) is part of the xCAT network named “clstrnet11”. “compute02-eth2” is in network “clstrnet80” and “compute02-eth2-lab” is in “clstrnet-lab”.

By default the xCAT code will attempt to match the interface IP to one of the xCAT network definitions.

An xCAT network definition must be created for all networks being used in the xCAT cluster environment.

nicaliases example:

```
chdef -t node -o compute02 nicaliases.eth1="moe larry"
```

In this example it specifies that, (when running makehosts), the “compute02-eth1” entry in the /etc/hosts file should get the additional aliases “moe” and “larry”.

**Add additional NIC information for a single cluster node**

In this example we assume that we have already designated that node “compute01” get IP address “60.0.0.1” which will be configured on interface “eth0”. This will be the xCAT management interface for the node. In addition to the management interface we also wish to include information for the “eth1” interface on node “compute01”. To do this we must set the additional nic information for this node. For example:

```
chdef -t node -o compute01 nicips.eth1='80.0.0.1' nictypes.eth1='ethernet' nicnetworks.eth1='clstrnet80'
```

This information will be used to configure the “eth1” interface, (in addition to the management interface (eth0)), during the boot of the node.

Also, if you were to run “makehosts compute01” at this point you would see something like the following entries added to the /etc/hosts file.

```
60.0.0.1 compute01 compute01.cluster60.com
80.0.0.1 compute01-eth1 compute01-eth1.cluster80.com
```

The domain names are found by checking the xCAT network definitions to see which one would include the IP address. The domain for the matching network is then used for the long name in the /etc/hosts file.

NOTE: If you specify the same IP address for a nic as you did for the management interface then the nic hostname will be considered an alias of the xCAT node hostname. For example, if you specified “60.0.0.1” for the eth1 “nicips” value then the /etc/hosts entry would be:

```
60.0.0.1 compute01 compute01.cluster60.com compute01-eth1
```

**Add additional NIC information for a group of nodes**

In this example we’d like to configure additional “eth1” interfaces for a group of cluster nodes.

The basic approach will be to create an xCAT node group containing all the nodes and then use a regular expression to determine the actual “nicips” to use for each node.
For this technique to work you must set up the hostnames and IP address to have a regular pattern. For more information on using regular expressions in the xCAT database see the xcatdb man page.

In the following example, the xCAT node group “compute” was defined to include all the computational nodes: compute01, compute02, compute03 etc. (These hostnames/IPs will be mapped to the “eth0” interfaces.)

For the “eth1” interfaces on these nodes we’d like to have “compute01-eth1” map to “80.0.0.1”, and “compute02-eth1” to map to “80.0.0.2” etc.

To do this we could define the “compute” group attributes as follows:

```
chdef -t group -o compute nicips='\D+(\d+)|eth1!80.0.0.($1+0)|' nichostnamesuffixes='eth1!-eth1' nictypes='eth1!ethernet'
```

These values will be applied to each node in the “compute” group. So, for example, if I list the attributes of “compute08” I’d see the following nic* attribute values set.

```
lsdef compute08
Object name: compute08
    . . .
    nicips.eth1=80.0.0.8
    nichostnamesuffixes.eth1=-eth1
    nictypes.eth1=ethernet
    . . .
```

Here is a second example of using regular expressions to define multiple nodes:

```
chdef -t group -o nictest nicips='\D+(\d+)|ib0!10.4.102.($1*1)|' nichostnamesuffixes='ib0!-ib' nictypes='ib0!Infiniband' nicnetworks='ib0!barcoo_infiniband'
```

```
lsdef nictest
Object name: node01
groups=nictest
    nichostnamesuffixes.ib0=-ib
    nicips.ib0=10.4.102.1
    nicnetworks.ib0=barcoo_infiniband
    nictypes.ib0=Infiniband
    postbootscripts=otherpkgs
    postscripts=syslog,remoteshell
```

NOTE: Make sure you haven’t already set nic* values in the individual node definitions since they would take precedence over the group value.

**Using expanded stanza file format**

The xCAT stanza file supports the expanded nic* attribute format.

It will contain the nic* attributes as described above.

Example:

```
compute01:
    objtype=node
    arch=x86_64
    mgt=ipmi
    cons=ipmi
    bmc=10.1.0.12
```

(continues on next page)
The `lsdef` command may be used to create a stanza file in this format and the `chdef/mkdef` commands will read a stanza file in this format.

### Using `lsdef` to display nic* attributes

If a node has any nic attributes set they will be displayed along with the node definition. The nic attribute values are displayed in the expanded format.

```
lsdef compute02
```

If you would only like to see the `nic*` attributes for the node you can specify the `--nics` option on the command line.

```
lsdef compute02 --nics
```

If you would like to display individual `nic*` attribute values you can use the `--i` option.

You can either specify the base `nic*` attribute name or the expanded name for a specific NIC.

```
lsdef compute05 --i nicips,nichostnamesuffixes
```

```
Object name: compute05
    nicips.eth1=11.1.89.7
    nicips.eth2=12.1.89.7
    nichostnamesuffixes.eth1=-lab
    nichostnamesuffixes.eth2=-app
```

```
lsdef compute05 --i nicips.eth1,nichostnamesuffixes.eth1
```

```
Object name: compute05
    nicips.eth1=11.1.89.7
    nichostnamesuffixes.eth1=-lab
```

### Setting addition interface information using the xCAT tabedit command

Another option for setting the nic attribute values is to use the `tabedit` command. All the nic attributes for a node or group are stored in the xCAT database table named “nics”. You can edit the table directly using the xCAT `tabedit` command.

Example:

```
tabedit nics
```

For a description of the nic* table attributes see the nics table man page.

Sample table contents:
Limited support for user application networks

In some cases you may have additional user application networks in your site that are not specifically used for cluster management. If desired you can create xCAT network definitions for these networks. This not only provides a convenient way to keep track of the network details but the information can also be used to help set up name resolution for these networks on the cluster nodes. When you add a network definition that includes a “domain” value then that domain is automatically included the xCAT name resolution set up. This will enable the nodes to be able to resolve hostnames from the other domains.

For example, when you run `makedhcp -n` it will list all domains defined in the xCAT “site” definition and xCAT “network” definitions in the “option domain-search” entry of the shared-network stanza in the dhcp configuration file. This will cause dhcp to put these domains in the compute nodes’ `/etc/resolv.conf` file every time it gets a dhcp lease.

1.4.8 GPUs

NVIDIA CUDA

CUDA (Compute Unified Device Architecture) is a parallel computing platform and programming model created by NVIDIA. It can be used to increase computing performance by leveraging the Graphics Processing Units (GPUs).

For more information, see NVIDIA’s website: https://developer.nvidia.com/cuda-zone

xCAT supports CUDA installation for Ubuntu 14.04.3 and RHEL 7.5 on PowerNV (Non-Virtualized) for both diskful and diskless nodes.

Within the NVIDIA CUDA Toolkit, installing the `cuda` package will install both the `cuda-runtime` and the `cuda-toolkit`. The `cuda-toolkit` is intended for developing CUDA programs and monitoring CUDA jobs. If your particular installation requires only running GPU jobs, it’s recommended to install only the `cuda-runtime` package.

Create CUDA software repository

The NVIDIA CUDA Toolkit is available to download at http://developer.nvidia.com/cuda-downloads.

Download the toolkit and prepare the software repository on the xCAT Management Node to server the NVIDIA CUDA files.

RHEL 7.5

1. Create a repository on the MN node installing the CUDA Toolkit:
# For cuda toolkit name: /path/to/cuda-repo-rhel7-9-2-local-9.2.64-1.ppc64le.rpm
# extract the contents from the rpm
mkdir -p /tmp/cuda
cd /tmp/cuda
rpm2cpio /path/to/cuda-repo-rhel7-9-2-local-9.2.64-1.ppc64le.rpm | cpio -i -d

# Create the repo directory under xCAT /install dir for cuda 9.2
mkdir -p /install/cuda-9.2/ppc64le/cuda-core
cp /tmp/cuda/var/cuda-repo-9-2-local/*.rpm /install/cuda-9.2/ppc64le/cuda-core

# Create the yum repo files
createrepo /install/cuda-9.2/ppc64le/cuda-core

2. The NVIDIA CUDA Toolkit contains rpms that have dependencies on other external packages (such as DKMS). These are provided by EPEL. It’s up to the system administrator to obtain the dependency packages and add those to the cuda-deps directory:

mkdir -p /install/cuda-9.2/ppc64le/cuda-deps

# Copy the DKMS rpm to this directory
cp /path/to/dkms-2.4.0-1.20170926git959bd74.el7.noarch.rpm /install/cuda-9.2/ppc64le/cuda-deps

# Execute createrepo in this directory
createrepo /install/cuda-9.2/ppc64le/cuda-deps

---

**Ubuntu 14.04.3**

NVIDIA supports two types of debian repositories that can be used to install Cuda Toolkit: local and network. You can download the installers from https://developer.nvidia.com/cuda-downloads.

**Local**

A local package repo will contain all of the CUDA packages. Extract the CUDA packages into /install/cuda-repo/ppc64le:

# For CUDA toolkit: /root/cuda-repo-ubuntu1404-7-5-local_7.5-18_ppc64el.deb

# Create the repo directory under xCAT /install dir
mkdir -p /install/cuda-repo/ppc64el

# extract the package
dpkg -x /root/cuda-repo-ubuntu1404-7-5-local_7.5-18_ppc64el.deb /install/cuda-repo/

**Network**

The online package repo provides a source list entry pointing to a URL containing the CUDA packages. This can be used directly on the Compute Nodes.

The sources.list entry may look similar to:
Authorize the CUDA repo

In order to access the CUDA repository, you must import the CUDA GPGKEY into the apt_key trust list. xCAT provides a sample postscript /install/postscripts/addcudakey to help with this task:

```
chdef -t node -o <noderange> -p postscripts=addcudakey
```

Create osimage definitions

Generate osimage definitions to provision the compute nodes with the NVIDIA CUDA toolkit installed.

RHEL 7.5

xCAT provides a sample package list (pkglist) files for CUDA. You can find them:

- **Diskful**: /opt/xcat/share/xcat/install/rh/cuda*
- **Diskless**: /opt/xcat/share/xcat/netboot/rh/cuda*

### Diskful images

The following examples will create diskful images for cudafull and cudaruntime. The osimage definitions will be created from the base rhels7.5-ppc64le-install-compute osimage.

**[Note]**: There is a requirement to reboot the machine after the CUDA drivers are installed. To satisfy this requirement, the CUDA software is installed in the pkglist attribute of the osimage definition where a reboot will happen after the Operating System is installed.

**cudafull**

1. Create a copy of the install-compute image and label it cudafull:

   ```bash
   lsdef -t osimage -z rhels7.5-ppc64le-install-compute \
   | sed '/s/install-compute:/install-cudafull:/' \
   | mkdef -z
   ```

2. Add the CUDA repo created in the previous step to the pkgdir attribute:

   ```bash
   chdef -t osimage -o rhels7.5-ppc64le-install-cudafull -p \
   pkgdir=/install/cuda-9.2/ppc64le/cuda-core,/install/cuda-9.2/ppc64le/cuda-deps
   ```

3. Use the provided cudafull pkglist to install the CUDA packages:

   ```bash
   chdef -t osimage -o rhels7.5-ppc64le-install-cudafull \
   pkglist=/opt/xcat/share/xcat/install/rh/cudafull.rhels7.ppc64le.pkglist
   ```

1.4. Advanced Topics
**cudaruntime**

1. Create a copy of the `install-compute` image and label it `cudaruntime`:

   ```bash
   lsdef -t osimage -z rhels7.5-ppc64le-install-compute \
   | sed 's/install-compute:/install-cudaruntime:/' \
   | mkdef -z
   ```

2. Add the CUDA repo created in the previous step to the `pkgdir` attribute:

   ```bash
   chdef -t osimage -o rhels7.5-ppc64le-install-cudaruntime -p \
   pkgdir=/install/cuda-9.2/ppc64le/cuda-core,/install/cuda-9.2/ppc64le/cuda-deps
   ```

3. Use the provided `cudaruntime` `pkglist` to install the CUDA packages:

   ```bash
   chdef -t osimage -o rhels7.5-ppc64le-install-cudaruntime \
   pkglist=/opt/xcat/share/xcat/instal/rh/cudaruntime.rhels7.ppc64le.pkglist
   ```

**Diskless images**

The following examples will create diskless images for `cudafull` and `cudaruntime`. The osimage definitions will be created from the base `rhels7.5-ppc64le-netboot-compute` osimage.

*Note*: For diskless, the install of the CUDA packages MUST be done in the `otherpkglist` and NOT the `pkglist` as with diskful. The requirement for rebooting the machine is not applicable in diskless nodes because the image is loaded on each reboot.

**cudafull**

1. Create a copy of the `netboot-compute` image and label it `cudafull`:

   ```bash
   lsdef -t osimage -z rhels7.5-ppc64le-netboot-compute \
   | sed 's/netboot-compute:/netboot-cudafull:/' \
   | mkdef -z
   ```

2. Verify that the CUDA repo created in the previous step is available in the directory specified by the `otherpkgdir` attribute.

   The `otherpkgdir` directory can be obtained by running `lsdef` on the osimage:

   ```bash
   # lsdef -t osimage rhels7.5-ppc64le-netboot-cudafull -i otherpkgdir
   Object name: rhels7.5-ppc64le-netboot-cudafull
   otherpkgdir=/install/post/otherpkgs/rhels7.5/ppc64le
   ```

   Create a symbolic link of the CUDA repository in the directory specified by `otherpkgdir`

   ```bash
   ln -s /install/cuda-9.2 /install/post/otherpkgs/rhels7.5/ppc64le/cuda-9.2
   ```

3. Change the `rootimgdir` for the `cudafull` osimage:

   ```bash
   chdef -t osimage -o rhels7.5-ppc64le-netboot-cudafull \
   rootimgdir=/install/netboot/rhels7.5/ppc64le/cudafull
   ```

4. Create a custom `pkglist` file to install additional operating system packages for your CUDA node.
(a) Copy the default compute pkglist file as a starting point:

```
mkdir -p /install/custom/netboot/rh/
cp /opt/xcat/share/xcat/netboot/rh/compute.rhels7.ppc64le.pkglist \
   /install/custom/netboot/rh/cudafull.rhels7.ppc64le.pkglist
```

(b) Edit the pkglist file and append any packages you desire to be installed. For example:

```
vi /install/custom/netboot/rh/cudafull.rhels7.ppc64le.pkglist
...
# Additional packages for CUDA
pciutils
```

(c) Set the new file as the pkglist attribute for the cudafull osimage:

```
chdef -t osimage -o rhels7.5-ppc64le-netboot-cudafull \
   pkglist=/install/custom/netboot/rh/cudafull.rhels7.ppc64le.pkglist
```

5. Create the otherpkg.pkglist file to do the install of the CUDA full packages:

(a) Create the otherpkg.pkglist file for cudafull:

```
vi /install/custom/netboot/rh/cudafull.rhels7.ppc64le.otherpkgs.pkglist
# add the following packages
cuda-9.2/ppc64le/cuda-deps/dkms
cuda-9.2/ppc64le/cuda-core/cuda
```

(b) Set the otherpkg.pkglist attribute for the cudafull osimage:

```
chdef -t osimage -o rhels7.5-ppc64le-netboot-cudafull \
   otherpkglist=/install/custom/netboot/rh/cudafull.rhels7.ppc64le.otherpkgs.pkglist
```

6. Generate the image:

```
genimage rhels7.5-ppc64le-netboot-cudafull
```

7. Package the image:

```
packimage rhels7.5-ppc64le-netboot-cudafull
```

### cudaruntime

1. Create a copy of the netboot-compute image and label it cudaruntime:

```
lsdef -t osimage -z rhels7.5-ppc64le-netboot-compute \
   | sed 's/netboot-compute:/netboot-cudaruntime:/' \
   | mkdef -z
```

2. Verify that the CUDA repo created previously is available in the directory specified by the otherpkgdir attribute.

   (a) Obtain the otherpkgdir directory using the lsdef command:
# lsdef -t osimage rhels7.5-ppc64le-netboot-cudaruntime -i otherpkgdir
Object name: rhels7.5-ppc64le-netboot-cudaruntime
    otherpkgdir=/install/post/otherpkgs/rhels7.5/ppc64le

(b) Create a symbolic link to the CUDA repository in the directory specified by otherpkgdir

```
ln -s /install/cuda-9.2 /install/post/otherpkgs/rhels7.5/ppc64le/cuda-9.2
```

3. Change the rootimgdir for the cudaruntime osimage:

```
chdef -t osimage -o rhels7.5-ppc64le-netboot-cudaruntime \ 
    rootimgdir=/install/netboot/rhels7.5/ppc64le/cudaruntime
```

4. Create the otherpkg.pkglist file to do the install of the CUDA runtime packages:

(a) Create the otherpkg.pkglist file for cudaruntime:

```
vi /install/custom/netboot/rh/cudaruntime.rhels7.ppc64le.\ 
otherpkg.pkglist
```

# Add the following packages:

cuda-9.2/ppc64le/cuda-deps/dkms
cuda-9.2/ppc64le/cuda-core/cuda-runtime-9-2

(b) Set the otherpkg.pkglist attribute for the cudaruntime osimage:

```
chdef -t osimage -o rhels7.5-ppc64le-netboot-cudaruntime \ 
    otherpkglist=/install/custom/netboot/rh/cudaruntime.rhels7.ppc64le.\ 
    otherpkg.pkglist
```

5. Generate the image:

```
genimage rhels7.5-ppc64le-netboot-cudaruntime
```

6. Package the image:

```
packimage rhels7.5-ppc64le-netboot-cudaruntime
```

**POWER9 Setup**

NVIDIA POWER9 CUDA driver need some additional setup. Refer the URL below for details.

xCAT includes a script, `cuda_power9_setup` as example, to help user handle this situation.

**Diskful osimage**

For diskful deployment, there is no need to change the osimage definition. Instead, add this postscript to your compute node postbootscripts list.

```
chdef p9compute -p postscripts=cuda_power9_setup
```
**Diskless osimage**

For diskless deployment, the script need to add to the postinstall script of the osimage. And it should be run in the chroot environment. Please refer the following commands as an example.

```
mkdir -p /install/custom/netboot/rh
cp /opt/xcat/share/xcat/netboot/rh/compute.rhels7.ppc64le.postinstall /install/custom/
   → -netboot/rh/compute.rhels7.ppc64le.postinstall

cat >>/install/custom/netboot/rh/cudafull.rhels7.ppc64le.postinstall <<<EOF
/install/postscripts/cuda_power9_setup
EOF
chdef -t osimage rhels7.5-ppc64le-netboot-cudafull postinstall=/install/custom/
   → -netboot/rh/cudafull.rhels7.ppc64le.postinstall
```

**Ubuntu 14.04.3**

**Diskful images**

The following examples will create diskful images for cudafull and cudaruntime. The osimage definitions will be created from the base ubuntu14.04.3-ppc64el-install-compute osimage.

xCAT provides a sample package list files for CUDA. You can find them at:

- `/opt/xcat/share/xcat/install/ubuntu/cudafull.ubuntu14.04.3.ppc64el.pkglist`
- `/opt/xcat/share/xcat/install/ubuntu/cudaruntime.ubuntu14.04.3.ppc64el.pkglist`

[**diskful note**]: There is a requirement to reboot the machine after the CUDA drivers are installed. To satisfy this requirement, the CUDA software is installed in the pkglist attribute of the osimage definition where the reboot happens after the Operating System is installed.

**cudafull**

1. Create a copy of the install-compute image and label it cudafull:

```
lsdef -t osimage -z ubuntu14.04.3-ppc64el-install-compute \
| sed 's/install-compute:/install-cudafull:/' \
| mkdef -z
```

2. Add the CUDA repo created in the previous step to the pkgdir attribute.

   If your Management Node IP is 10.0.0.1, the URL for the repo would be `http://10.0.0.1/install/cuda-repo/ppc64el/var/cuda-repo-7-5-local`, add it to the pkgdir:

```
chdef -t osimage -o ubuntu14.04.3-ppc64el-install-cudafull \
   -p pkgdir=http://10.0.0.1/install/cuda-repo/ppc64el/var/cuda-repo-7-5-local
```


3. Use the provided cudafull pkglist to install the CUDA packages:
**cudaruntime**

1. Create a copy of the install-compute image and label it cudaruntime:
   ```bash
   lsdef -t osimage -z ubuntu14.04.3-ppc64el-install-compute \ 
   | sed 's/install-compute:/install-cudaruntime:/' \ 
   | mkdef -z
   ```

2. Add the CUDA repo created in the previous step to the pkgdir attribute:
   If your Management Node IP is 10.0.0.1, the URL for the repo would be `http://10.0.0.1/install/cuda-repo/ppc64el/var/cuda-repo-7-5-local`, add it to the pkgdir:
   ```bash
   chdef -t osimage -o ubuntu14.04.3-ppc64el-install-cudaruntime \ 
   -p pkgdir=http://10.0.0.1/install/cuda-repo/ppc64el/var/cuda-repo-7-5-local
   ```


3. Use the provided cudaruntime pkglist to install the CUDA packages:
   ```bash
   chdef -t osimage -o ubuntu14.04.3-ppc64el-install-cudaruntime \  
   pkglist=/opt/xcat/share/xcat/install/ubuntu/cudaruntime.ubuntu14.04.3.ppc64el.pkglist
   ```

**Diskless images**

The following examples will create diskless images for cudafull and cudaruntime. The osimage definitions will be created from the base `ubuntu14.04.3-ppc64el-netboot-compute osimage`.

xCAT provides a sample package list files for CUDA. You can find them at:

- `/opt/xcat/share/xcat/netboot/ubuntu/cudafull.ubuntu14.04.3.ppc64el.pkglist`
- `/opt/xcat/share/xcat/netboot/ubuntu/cudaruntime.ubuntu14.04.3.ppc64el.pkglist`

[**diskless note**]: For diskless images, the requirement for rebooting the machine is not applicable because the images is loaded on each reboot. The install of the CUDA packages is required to be done in the otherpkglist **NOT** the pkglist.

**cudafull**

1. Create a copy of the netboot-compute image and label it cudafull:
   ```bash
   lsdef -t osimage -z ubuntu14.04.3-ppc64el-netboot-compute \ 
   | sed 's/netboot-compute:/netboot-cudafull:' \ 
   | mkdef -z
   ```
2. Add the CUDA repo created in the previous step to the `otherpkgdir` attribute.

   If your Management Node IP is 10.0.0.1, the URL for the repo would be `http://10.0.0.1/install/cuda-repo/ppc64el/var/cuda-repo-7-5-local`, add it to the `otherpkgdir`:

```
chdef -t osimage -o ubuntu14.04.3-ppc64el-netboot-cudafull \
  otherpkgdir=http://10.0.0.1/install/cuda-repo/ppc64el/var/cuda-repo-7-5-local
```

3. Add the provided `cudafull` `otherpkg.pkglist` file to install the CUDA packages:

```
chdef -t osimage -o ubuntu14.04.3-ppc64el-netboot-cudafull \
  otherpkglist=/opt/xcat/share/xcat/netboot/ubuntu/cudafull.otherpkg.pkglist
```


4. Verify that `acpid` is installed on the Management Node or on the Ubuntu host where you are generating the diskless image:

```
apt-get install -y acpid
```

5. Generate the image:

```
genimage ubuntu14.04.3-ppc64el-netboot-cudafull
```

6. Package the image:

```
packimage ubuntu14.04.3-ppc64el-netboot-cudafull
```

**cudaruntime**

1. Create a copy of the `netboot-compute` image and label it `cudaruntime`:

```
lsdef -t osimage -z ubuntu14.04.3-ppc64el-netboot-compute \ 
  | sed 's/netboot-compute:/netboot-cudaruntime:'/\ 
  | mkdef -z
```

2. Add the CUDA repo created in the previous step to the `otherpkgdir` attribute.

   If your Management Node IP is 10.0.0.1, the URL for the repo would be `http://10.0.0.1/install/cuda-repo/ppc64el/var/cuda-repo-7-5-local`, add it to the `otherpkgdir`:

```
chdef -t osimage -o ubuntu14.04.3-ppc64el-netboot-cudaruntime \ 
  otherpkgdir=http://10.0.0.1/install/cuda-repo/ppc64el/var/cuda-repo-7-5-local
```

3. Add the provided `cudaruntime` `otherpkg.pkglist` file to install the CUDA packages:

```
chdef -t osimage -o ubuntu14.04.3-ppc64el-netboot-cudaruntime \ 
  otherpkglist=/opt/xcat/share/xcat/netboot/ubuntu/cudaruntime.otherpkg.pkglist
```


4. Verify that `acpid` is installed on the Management Node or on the Ubuntu host where you are generating the diskless image:
5. Generate the image:

   `genimage ubuntu14.04.3-ppc64el-netboot-cudaruntime`

6. Package the image:

   `packimage ubuntu14.04.3-ppc64el-netboot-cudaruntime`

Postscripts

The following sections demonstrates how to use xCAT to configure post-installation steps

Setting PATH and LD_LIBRARY_PATH

NVIDIA recommends various post-installation actions that should be performed to properly configure the nodes. A sample script is provided by xCAT for this purpose `config_cuda` and can be modified to fit your specific installation.

Add this script to your node object using the `chdef` command:

```
chdef -t node -o <noderange> -p postscripts=config_cuda
```

Setting GPU Configurations

NVIDIA allows for changing GPU attributes using the `nvidia-smi` commands. These settings do not persist when a compute node is rebooted. One way set these attributes is to use an xCAT postscript to set the values every time the node is rebooted.

- Set the power limit to 175W:

  ```
  # set the power limit to 175W
  nvidia-smi -pl 175
  ```

- Set the GPUs to persistence mode to increase performance:

  ```
  # nvidia-smi -pm 1
  Enabled persistence mode for GPU 0000:03:00.0.
  Enabled persistence mode for GPU 0000:04:00.0.
  Enabled persistence mode for GPU 0002:03:00.0.
  Enabled persistence mode for GPU 0002:04:00.0.
  All done.
  ```

Deploy CUDA nodes

Diskful

- To provision diskful nodes using osimage `rhels7.5-ppc64le-install-cudafull`:  

```
Diskless

- To provision diskless nodes using osimage rhels7.5-ppc64le-netboot-cudafull:

```
nodeset <noderange> osimage=rhels7.5-ppc64le-netboot-cudafull
rsetboot <noderange> net
rpower <noderange> boot
```

Verify CUDA Installation

The following verification steps only apply to the “cudafull“ installations.

1. Verify driver version by looking at: /proc/driver/nvidia/version:

```
# cat /proc/driver/nvidia/version
NVRM version: NVIDIA UNIX ppc64le Kernel Module 352.39 Fri Aug 14 17:10:41 PDT→2015
GCC version: gcc version 4.8.5 20150623 (Red Hat 4.8.5-4) (GCC)
```

2. Verify the CUDA Toolkit version

```
# nvcc --V
nvcc: NVIDIA (R) Cuda compiler driver
Copyright (c) 2005-2015 NVIDIA Corporation
Built on Tue_Aug_11_14:31:50_CDT_2015
Cuda compilation tools, release 7.5, V7.5.17
```

3. Verify running CUDA GPU jobs by compiling the samples and executing the deviceQuery or bandwidthTest programs.

- Compile the samples:
  
  **[RHEL]:**

  ```
  cd ~/
  cuda-install-samples-7.5.sh .
  cd NVIDIA_CUDA-7.5_Samples
  make
  ```

  **[Ubuntu]:**

  ```
  cd ~/
  apt-get install cuda-samples-7-0 -y
  cd /usr/local/cuda-7.0/samples
  make
  ```

- Run the deviceQuery sample:

  ```
  # ./bin/ppc64le/linux/release/deviceQuery
  ./deviceQuery Starting...
  ```
CUDA Device Query (Runtime API) version (CUDART static linking)
Detected 4 CUDA Capable device(s)
Device 0: "Tesla K80"
  CUDA Driver Version / Runtime Version: 7.5 / 7.5
  CUDA Capability Major/Minor version number: 3.7
  Total amount of global memory: 11520 MBytes (12079136768 bytes)
  (13) Multiprocessors, (192) CUDA Cores/MP: 2496 CUDA Cores
  GPU Max Clock rate: 824 MHz (0.82 GHz)
  Memory Clock rate: 2505 Mhz
  Memory Bus Width: 384-bit
  L2 Cache Size: 1572864 bytes

deviceQuery, CUDA Driver = CUDART, CUDA Driver Version = 7.5, CUDA
  Runtime Version = 7.5, NumDevs = 4, Device0 = Tesla K80, Device1 = Tesla
  K80, Device2 = Tesla K80, Device3 = Tesla K80
Result = PASS

• Run the `bandwidthTest` sample:

```
# ./bin/ppc64le/linux/release/bandwidthTest
[CUDA Bandwidth Test] - Starting...
Running on...
Device 0: Tesla K80
Quick Mode
Host to Device Bandwidth, 1 Device(s)
PINNED Memory Transfers
  Transfer Size (Bytes)  Bandwidth(MB/s)
  33554432              7765.1
Device to Host Bandwidth, 1 Device(s)
PINNED Memory Transfers
  Transfer Size (Bytes)  Bandwidth(MB/s)
  33554432              7759.6
Device to Device Bandwidth, 1 Device(s)
PINNED Memory Transfers
  Transfer Size (Bytes)  Bandwidth(MB/s)
  33554432              141485.3
Result = PASS
```

NOTE: The CUDA Samples are not meant for performance measurements. Results may vary when GPU Boost is enabled.

**GPU Management and Monitoring**

The `nvidia-smi` command provided by NVIDIA can be used to manage and monitor GPUs enabled Compute Nodes. In conjunction with the xCAT``xdsh`` command, you can easily manage and monitor the entire set of GPU enabled Compute Nodes remotely from the Management Node.

Example:

```
# xdsh <noderange> "nvidia-smi -i 0 --query-gpu=name,serial,uuid --format=csv,noheader...
```
node01: Tesla K80, 0322415075970, GPU-b4f79b83-c282-4409-a0e8-0da3e06a13c3
...
**Warning:** The following commands are provided as convenience. Always consult the `nvidia-smi` manpage for the latest supported functions.

### Management

Some useful `nvidia-smi` example commands for management.

- Set persistence mode. When persistence mode is enabled the NVIDIA driver remains loaded even when no active clients, DISABLED by default:
  
  ```
  nvidia-smi -i 0 -pm 1
  ```

- Disabled ECC support for GPU. Toggle ECC support. A flag that indicates whether ECC support is enabled, need to use `--query-gpu=ecc.mode.pending` to check [Reboot required]:
  
  ```
  nvidia-smi -i 0 -e 0
  ```

- Reset the ECC volatile/aggregate error counters for the target GPUs:
  
  ```
  nvidia-smi -i 0 -p 0/1
  ```

- Set MODE for compute applications, query with `--query-gpu=compute_mode`:
  
  ```
  nvidia-smi -i 0 -c 0/1/2/3
  ```

- Trigger reset of the GPU
  
  ```
  nvidia-smi -i 0 -r
  ```

- Enable or disable Accounting Mode, statistics can be calculated for each compute process running on the GPU, query with `--query-gpu=accounting.mode`:
  
  ```
  nvidia-smi -i 0 -am 0/1
  ```

- Specifies maximum power management limit in watts, query with `--query-gpu=power.limit`
  
  ```
  nvidia-smi -i 0 -pl 200
  ```

### Monitoring

Some useful `nvidia-smi` example commands for monitoring.

- The number of NVIDIA GPUs in the system
  
  ```
  nvidia-smi --query-gpu=count --format=csv,noheader
  ```

- The version of the installed NVIDIA display driver
  
  ```
  nvidia-smi -i 0 --query-gpu=driver_version --format=csv,noheader
  ```

- The BIOS of the GPU board
  
  ```
  nvidia-smi -i 0 --query-gpu=vbios_version --format=csv,noheader
  ```

1.4. Advanced Topics
• Product name, serial number and UUID of the GPU:

```
nvidia-smi -i 0 --query-gpu=name,serial,uuid --format=csv,noheader
```

• Fan speed:

```
nvidia-smi -i 0 --query-gpu=fan.speed --format=csv,noheader
```

• The compute mode flag indicates whether individual or multiple compute applications may run on the GPU. (known as exclusivity modes)

```
nvidia-smi -i 0 --query-gpu=compute_mode --format=csv,noheader
```

• Percent of time over the past sample period during which one or more kernels was executing on the GPU:

```
nvidia-smi -i 0 --query-gpu=utilization.gpu --format=csv,noheader
```

• Total errors detected across entire chip. Sum of device_memory, register_file, l1_cache, l2_cache and texture_memory

```
nvidia-smi -i 0 --query-gpu=ecc.errors.corrected.aggregate.total --format=csv,noheader
```

• Core GPU temperature, in degrees C:

```
nvidia-smi -i 0 --query-gpu=temperature.gpu --format=csv,noheader
```

• The ECC mode that the GPU is currently operating under:

```
nvidia-smi -i 0 --query-gpu=ecc.mode.current --format=csv,noheader
```

• The power management status:

```
nvidia-smi -i 0 --query-gpu=power.management --format=csv,noheader
```

• The last measured power draw for the entire board, in watts:

```
nvidia-smi -i 0 --query-gpu=power.draw --format=csv,noheader
```

• The minimum and maximum value in watts that power limit can be set to

```
nvidia-smi -i 0 --query-gpu=power.min_limit,power.max_limit --format=csv
```

Update NVIDIA Driver

If the user wants to update the newer NVIDIA driver on the system, follow the Create CUDA software repository document to create another repository for the new driver.

The following example assumes the new driver is in /install/cuda-9.2/ppc64le/nvidia_new.

Diskful

1. Change pkgdir for the cuda image:
2. Use `xdsh` command to remove all the NVIDIA rpms:

```
xdsh <noderange> "yum remove *nvidia* -y"
```

3. Run `updatenode` command to update NVIDIA driver on the compute node:

```
updatenode <noderange> -S
```

4. Reboot compute node:

```
rpower <noderange> off
rpower <noderange> on
```

5. Verify the newer driver level:

```
nvidia-smi | grep Driver
```

**Diskless**

To update a new NVIDIA driver on diskless compute nodes, re-generate the osimage pointing to the new NVIDIA driver repository and reboot the node to load the diskless image.

Refer to *Create osimage definitions* for specific instructions.

### 1.4.9 High Availability

The xCAT management node plays an important role in the cluster, if the management node is down for whatever reason, the administrators will lose the management capability for the whole cluster, until the management node is back up and running. In some configurations, like the Linux NFSROOT-based statelite in a non-hierarchy cluster, the compute nodes may not be able to run at all without the management node. So, it is important to consider the high availability for the management node.

The goal of the HAMN (High Availability Management Node) configuration is, when the primary xCAT management node fails, the standby management node can take over the role of the management node, either through automatic failover or through manual procedure performed by the administrator, and thus avoid long periods of time during which your cluster does not have active cluster management function available.

The following pages describes ways to configure the xCAT Management Node for High Availability.

**Configuration considerations**

xCAT provides several configuration options for the HAMN, you can select one of the option based on your failover requirements and hardware configuration, the following configuration considerations should be able to help you to make the decision.

**Data synchronization mechanism**

The data synchronization is important for any high availability configuration. When the xCAT management node failover occurs, the xCAT data needs to be exactly the same before failover, and some of the operating system config-
uration should also be synchronized between the two management nodes. To be specific, the following data should be synchronized between the two management nodes to make the xCAT HAMN work:

- **xCAT database**
- **xCAT configuration files**, like `/etc/xcat`, `~/.xcat`, `/opt/xcat`
- The configuration files for the services that are required by xCAT, like named, DHCP, apache, nfs, ssh, etc.
- The operating systems images repository and users customization data repository, the `/install` directory contains these repositories in most cases.

There are a lot of ways for data synchronization, but considering the specific xCAT HAMN requirements, only several of the data synchronization options are practical for xCAT HAMN.

1. **Move physical disks between the two management nodes**: if we could physically move the hard disks from the failed management node to the backup management node, and bring up the backup management node, then both the operating system and xCAT data will be identical between the new management node and the failed management node. RAID1 or disk mirroring could be used to avoid the disk be a single point of failure.

2. **Shared data**: the two management nodes use the single copy of xCAT data, no matter which management node is the primary MN, the cluster management capability is running on top of the single data copy. The access to the data could be done through various ways like shared storage, NAS, NFS, samba etc. Based on the protocol being used, the data might be accessible only on one management node at a time or be accessible on both management nodes in parallel. If the data could only be accessed from one management node, the failover process need to take care of the data access transition; if the data could be accessed on both management nodes, the failover does not need to consider the data access transition, it usually means the failover process could be faster.

Warning: Running database through network file system has a lot of potential problems and is not practical, however, most of the database system provides database replication feature that can be used to synchronize the database between the two management nodes.

3. **Mirroring**: each of the management node has its own copy of the xCAT data, and the two copies of data are synchronized through mirroring mechanism. DRBD is used widely in the high availability configuration scenarios, to provide data replication by mirroring a whole block device via network. If we put all the important data for xCAT onto the DRBD devices, then it could assure the data is synchronized between the two management nodes. Some parallel file system also provides capability to mirror data through network.

**Manual vs. Automatic Failover**

When the primary management node fails, the backup management node could automatically take over, or the administrator has to perform some manual procedure to finish the failover. In general, the automatic failover takes less time to detect the failure and perform and failover, comparing with the manual failover, but the automatic failover requires more complex configuration. We could not say the automatic failover is better than the manual failover in all cases, the following factors should be considered when deciding the manual failover or automatic failover:

1. **How long the cluster could survive if the management node is down?**

If the cluster could not survive for more than several minutes, then the automatic failover might be the only option; if the compute nodes could run without the management node, at least for a while, then the manual failover could be an option.

From xCAT perspective, if the management node needs to provide network services like DHCP, named, ntp or nfs to the compute nodes, then the cluster probably could not survive too long if the management node is down; if the management node only performs hardware control and some other management capabilities, then the failed management node may not cause too much trouble for the cluster. xCAT provides various options for configuring if the compute nodes rely on the network services on the management node.

2. **Configuration complexity**
The configuration for the high availability applications is usually complex, it may take a long time to configure, debug and stabilize the high availability configuration.

3. Maintenance effort

The automatic failover brings in several high availability applications, after the initial configuration is done, additional maintenance effort will be needed. For example, taking care of the high availability applications during cluster update, the updates for the high availability applications themselves, troubleshooting any problems with the high availability applications. A simple question may be able to help you to decide: could you get technical support if some of the high availability applications run into problems? All software has bugs.

Configuration Options

The combinations of data synchronization mechanism and manual/automatic failover indicates different HAMN configuration options, the table below list all the combinations (the bold numbers are the combinations xCAT has documented and tested):

<table>
<thead>
<tr>
<th>#</th>
<th>Move physical disks</th>
<th>Shared data</th>
<th>Mirroring</th>
</tr>
</thead>
<tbody>
<tr>
<td>Manual Failover</td>
<td>1</td>
<td>2</td>
<td>3</td>
</tr>
<tr>
<td>Automatic Failover</td>
<td>4</td>
<td>5</td>
<td>6</td>
</tr>
</tbody>
</table>

Option 1, setup_ha_mgmt_node_with_raid1_and_disks_move
Option 2, setup_ha_mgmt_node_with_shared_data
Option 3, it is doable but not currently supported.
Option 4, it is not practical.
Option 5, setup_xcat_high_available_management_node_with_nfs
Option 6, setup_ha_mgmt_node_with_drbd_pacemaker_corosync

1.4.10 Hierarchical Clusters / Large Cluster Support

xCAT supports management of very large sized cluster by creating a Hierarchical Cluster and the concept of xCAT Service Nodes.

When dealing with large clusters, to balance the load, it is recommended to have more than one node (Management Node, “MN”) handling the installation and management of the Compute Nodes (“CN”). These additional helper nodes are referred to as Service Nodes (“SN”). The Management Node can delegate all management operational needs to the Service Node responsible for a set of compute node.

The following configurations are supported:

- Each service node installs/manages a specific set of compute nodes
- Having a pool of service nodes, any of which can respond to an installation request from a compute node (Requires service nodes to be aligned with networks broadcast domains, compute node chooses service nodes based on who responds to DHCP request first.)
- A hybrid of the above, where each specific set of compute nodes have 2 or more service nodes in a pool

The following documentation assumes an xCAT cluster has already been configured and covers the additional steps needed to support xCAT Hierarchy via Service Nodes.
Service Nodes

Service Nodes are similar to the xCAT Management Node in that each service Nodes runs an instance of the xCAT daemon: xcatd. xcatd's communicate with each other using the same XML/SSL protocol that the xCAT client uses to communicate with xcatd on the Management Node.

The Service Nodes need to communicate with the xCAT database running on the Management Node. This is done using the remote client capabilities of the database. This is why the default SQLite database cannot be used.

The xCAT Service Nodes are installed with a special xCAT package xCATsn which tells xcatd running on the node to behave as a Service Node and not the Management Node.

Configure a Database

xCAT uses the SQLite database (https://www.sqlite.org/) as the default database and it is initialized during xCAT installation of the Management Node. If using Service Nodes, SQLite cannot be used because Service Nodes require remote access to the xCAT database. One of the following databases should be used:

- MySQL/MariaDB
- PostgreSQL

MySQL/MariaDB

Install MySQL/MariaDB

The MySQL database is supported by xCAT since xCAT 2.1. MariaDB is a fork of the MySQL project which was released around 2009 and is a drop-in replacement for MySQL. MariaDB support within xCAT started in version 2.8.5 and is currently fully supported moving forward.

<table>
<thead>
<tr>
<th>Database</th>
<th>MySQL</th>
<th>MariaDB</th>
</tr>
</thead>
<tbody>
<tr>
<td>xCAT 2.1+</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>xCAT 2.8.5</td>
<td>Yes</td>
<td>RHEL 7</td>
</tr>
<tr>
<td>xCAT 2.9</td>
<td>Yes</td>
<td>SLES 12</td>
</tr>
<tr>
<td>xCAT 2.10+</td>
<td>Yes</td>
<td>Yes</td>
</tr>
</tbody>
</table>

MySQL/MariaDB packages are shipped as part of most Linux Distributions.

Red Hat Enterprise Linux

- MySQL - Using yum, ensure that the following packages are installed on the management node:
  
  perl-DBD-MySQL*
  mysql-server-5.*
  mysql-5.*
  mysql-connector-odbc-*

- MariaDB - Using yum, ensure that the following packages are installed on the management node:

  mariadb-server-5.*
  mariadb-5.*
  perl-DBD-Maria*
  mysql-connector-odbc-**
Suse Linux Enterprise Server

- MySQL - Using `zypper`, ensure that the following packages are installed on the management node:

```
mysql-client-5*
mymysqlclient_r15*
libqt4-sql-mysql-4*
libmysqlclient15-5*
perl-DBD-mysql-4*
mysql-5*
```

- MariaDB - Using `zypper`, ensure that the following packages are installed on the management node:

```
mariadb-client-10.*
mariadb-10.*
mariadb-errormessages-10.*
libqt4-sql-mysql-*
libmysqlclient18-*
perl-DBD-mysql-*
```

Debian/Ubuntu

- MySQL - Using `apt-get`, ensure that the following packages are installed on the management node:

```
mysql-server
mysql-common
libdbd-mysql-perl
libmysqlclient18
mysql-client-5*
mysql-client-core-5*
mysql-server-5*
mysql-server-core-5*
```

- MariaDB - Using `apt-get`, ensure that the following packages are installed on the management node. `apt-get install mariadb-server` will pull in all required packages. For Ubuntu 16.04, it no longer required `libmariadbclient18`.

```
libmariadbclient18
mariadb-client
mariadb-common
mariadb-server
```

Configure MySQL/MariaDB

Migrate xCAT to use MySQL/MariaDB

The following utility is provided to migrate an existing xCAT database from SQLite to MySQL/MariaDB.

```
mysqlsetup -i
```

If you need to update the database at a later time to give access to your service nodes, you can use the `mysqlsetup -u -f` command. A file needs to be provided with all the hostnames and/or IP addresses of the servers that need to access the database on the Management node. Wildcards can be used.
mysqlsetup -u -f /tmp/servicenodes

where the /tmp/servicenodes contains a host per line:

cat /tmp/servicenodes
node1
  1.115.85.2
  10.%.%.%
node2.cluster.net

While not recommended, if you wish to manually migrate your xCAT database, see the following documentation:
Manually set up MySQL

Granting/Revoking access to the database for Service Node Clients

- Log into the MySQL interactive program.
  
  /usr/bin/mysql -u root -p

- Granting access to the xCAT database. Service Nodes are required for xCAT hierarchical support. Compute nodes may also need access that depends on which application is going to run. (xcat201 is xcatadmin’s password for following examples)

  MariaDB > GRANT ALL on xcatdb.* TO xcatadmin@<servicenode(s)> IDENTIFIED BY 'xcat201';

  Use the wildcards to do a GRANT ALL to every ipaddress or nodename that need to access the database.

  MariaDB > GRANT ALL on xcatdb.* TO xcatadmin@'%.cluster.net' IDENTIFIED BY 'xcat201';
  MariaDB > GRANT ALL on xcatdb.* TO xcatadmin@'8.113.33.%' IDENTIFIED BY 'xcat201';

- To revoke access, run the following:

  MariaDB > REVOKE ALL on xcatdb.* FROM xcatadmin@'8.113.33.%';

- To Verify the user table was populated.

  MariaDB > SELECT host, user FROM mysql.user;

Using MySQL/MariaDB

Start/Stop MySQL/MariaDB service

[RHEL] for MariaDB:

  service mariadb start
  service mariadb stop

[RHEL] for MySQL:

  service mysqld start
  service mysqld stop
Basic MySQL/MariaDB commands

Refer to https://www.mariadb.org/ for the latest documentation.

- Using `mysql`, connect to the `xcat` database:
  ```
  mysql -u root -p
  ```

- List the hosts and users which managed by this `xcat` MN:
  ```
  MariaDB> SELECT host, user FROM mysql.user;
  ```

- List the databases:
  ```
  MariaDB> SHOW DATABASES;
  ```

- Use the `xcatdb`:
  ```
  MariaDB> use xcatdb;
  ```

- List all the tables:
  ```
  MariaDB [xcatdb]> SHOW TABLES;
  ```

- Show the entries in the `nodelist` table:
  ```
  MariaDB [xcatdb]> select * from nodelist;
  ```

- Quit `mysql`:
  ```
  MariaDB [xcatdb]> quit;
  ```

Removing `xcatdb` from MySQL/MariaDB

If you no longer want to use MySQL/MariaDB to maintain `xcatdb`, and like to switch to PostgreSQL or just default SQLite (Note: SQLite does not support xCAT Hierarchy (has service nodes)), use the following documentation as guide to remove `xcatdb`.

- Run a backup of the database to save any information that is needed (optional):
  ```
  mkdir -p ~/xcat-dbback
  dumpxCATdb -p ~/xcat-dbback
  ```

  If you want to restore this database later:
  ```
  XCATBYPASS=1 restorexCATdb -p ~/xcat-dbback
  ```

- Change to PostgreSQL, following documentation: *Install PostgreSQL*

- Change back to default xCAT database, SQLite (Note: xCAT Hierarchy cluster will no longer work)
1. Stop the xcatd daemon on the management node.

   service xcatd stop

2. Remove the xatdb from MySQL/MariaDB (optional):

   /usr/bin/mysql -u root -p

   drop the xcatdb:

   mysql> drop database xcatdb;

   remove the xcatadm database owner:

   mysql> drop user xcatadm;

3. Move, or remove, the /etc/xcat/cfglog file as it points xCAT to MySQL/MariaDB. (without this file, xCAT defaults to SQLite):

   rm /etc/xcat/cfglog

4. Restart xcatd:

   service xcatd start

PostgreSQL

Install PostgreSQL

PostgreSQL packages are shipped as part of most Linux Distributions.

Red Hat Enterprise Linux

Using yum, install the following rpms:

   yum install postgresql*
   yum install perl-DBD-Pg

Suse Linux Enterprise Server

Note: On SLES, perl-DBD packages are provided on the SDK iso images.

Using zypper, install the following rpms:

   zypper install postgresql*
   zypper install perl-DBD-Pg

Debian/Ubuntu

Using apt, install the following packages:
apt install postgresql libdbd-pg-perl

Configure PostgreSQL

Migrate xCAT to use PostgreSQL

A utility is provided to migrate an existing xCAT database from SQLite to PostgreSQL.

pgsqlsetup -i -V

While not recommended, if you wish to manually migrate your xCAT database, see the following documentation:
Manually set up PostgreSQL

Setting up the Service Nodes

For service nodes, add the IP address of each service nodes to the postgres configuration file: /var/lib/pgsql/data/pg_hba.conf

If you had the following two service nodes:

| sn10, ip: 192.168.1.10 with netmask 255.255.255.0 |
| sn11, ip: 192.168.1.11 with netmask 255.255.255.0 |

You would add the following to /var/lib/pgsql/data/pg_hba.conf

| host | all | all | 192.168.1.10/24 | md5 |
| host | all | all | 192.168.1.11/24 | md5 |

Restart PostgreSQL after editing the file:

```
service postgresql restart
```

For more information about changing the pg_hab.conf file and postgresql.conf files, see the following documentation: Setup the PostgreSQL Configuration Files

Modify PostgreSQL database directory

1. Check the xcatdb have been switched to pgsql:

```
lsxcatd -a
Version 2.13.6 (git commit f8c0d11ff2c7c97d6e62389c0aafcdfa06ce6f6, built Mon, Aug 7 07:15:47 EDT 2017)
This is a Management Node
cfgloc=Pg;dbname=xcatdb;host=10.3.5.100|xcatadm
dbengine=Pg
dbname=xcatdb
dbhost=10.3.5.100
dbadmin=xcatadm
```

2. Check the current working directory:
Using PostgresQL

Refer to http://www.postgresql.org/ for the latest documentation.

Using `psql`, connect to the xcat database:

```
su - postgres
psql -h <hostname> -U xcatadm -d xcatdb (default pw: cluster)
```

List the xCAT tables:

```
xcatdb=> \dt
```

Show the entries in the nodelist table:

```
xcatdb=>
```
Useful Commands

Show the SQL create statement for a table:

```
/usr/bin/pg_dump_xcatdb -U xcatadm -t <table_name>
```

# example, for prescripts table:
```
/usr/bin/pg_dump xcatdb -U xcatadm -t prescripts
```

List all databases in postgres:

```
su - postgres
psql -l
```

Removing xcatdb from PostgreSQL

To remove xcatdb completely from the PostgreSQL database:

1. Run a backup of the database to save any information that is needed:

```
mkdir -p ~/xcat-dbback
dumpxCATdb -p ~/xcat-dbback
```

2. Stop the xcatd daemon on the management node. **Note:** If you are using xCAT Hierarchy (service nodes) and removing xcatdb from postgres, hierarchy will no longer work. You will need to configure another database which supports remote database access to continue using the hierarchy feature.

```
service xcatd stop
```

3. Remove the xcatdb from PostgreSQL:

```
su - postgres
```

```
dropdb xcatdb
```

```
dropuser xcatadm
```

```
cd /var/lib/pgsql/data
rm -rf *
```

4. Move, or remove, the /etc/xcat/cfglog file as it points xCAT to PostgreSQL. (without this file, xCAT defaults to SQLite):
5. Restore the PostgreSQL database into SQLite:

```
/home/xcat/restorexCATdb -p ~/xcat-dbback
```

6. Restart xcatd:

```
/service xcatd start
```

### Define Service Nodes

This next part shows how to configure a xCAT Hierarchy and provision xCAT service nodes from an existing xCAT cluster.

The document assumes that the compute nodes that are part of your cluster have already been defined into the xCAT database and you have successfully provisioned the compute nodes using xCAT.

The following table illustrates the cluster being used in this example:

<table>
<thead>
<tr>
<th>Operating System</th>
<th>rhels7.1</th>
</tr>
</thead>
<tbody>
<tr>
<td>Architecture</td>
<td>ppc64le</td>
</tr>
<tr>
<td>xCAT Management Node</td>
<td>xcat01</td>
</tr>
<tr>
<td>Compute Nodes (group=rack1)</td>
<td>r1n01 r1n02 r1n03 ... r1n10</td>
</tr>
<tr>
<td>Compute Nodes (group=rack2)</td>
<td>r2n01 r2n02 r2n03 ... r2n10</td>
</tr>
</tbody>
</table>

1. Modify site table attribute to include service group’s postscripts in compute node definition:

```
chdef -t site hierarchicalattrs="postscripts"
```

2. Select the compute nodes that will become service nodes

   The first node in each rack, r1n01 and r2n01, is selected to become the xCAT service nodes and manage the compute nodes in that rack.

3. Change the attributes for the compute node to make them part of the service group:

```
chdef -t node -o r1n01,r2n01 -p groups=service
```

4. When copycds was run against the ISO image, several osimages are created into the osimage table. The ones named *-service are provided by easily help provision xCAT service nodes.

```
# lsdef -t osimage | grep rhels7.1
rhels7.1-ppc64le-install-compute (osimage)
rhels7.1-ppc64le-install-service (osimage) <======
rhels7.1-ppc64le-netboot-compute (osimage)
```

5. Add some common service node attributes to the service nodegroup:

```
chdef -t group -o service setupnfs=1 \       
    setupdhcp=1 \                  
    setuptftp=1 \                  
    setupnameserver=1 \           
    setupconserver=2
```

**Tips/Hint**
• Even if you do not want xCAT to configure any services, you must define the service nodes in the servicenode table with at least one attribute, set to 0, otherwise xCAT will not recognize the node as a service node.

• See the setup* attributes in the node definition man page for the list of available services: man node

• For clusters with subnetted management networks, you might want to set setupupforward=1

• For the setupconserver attribute, if conserver is used, set to 1, if goconserver is used, set to 2

6. Add additional postscripts for Service Nodes (optional)

By default, xCAT will execute the servicenode postscript when installed or diskless booted. This postscript will set up the necessary credentials and installs the xCAT software on the Service Nodes. If you have additional postscripts that you want to execute on the service nodes, copy to /install/postscripts and run the following:

```
chdef -t group -o service -p postscripts=<mypostscript>
```

7. Assigning Compute Nodes to their Service Nodes

The node attributes servicenode and xcatmaster, define which Service node will serve the particular compute node.

• servicenode - defines which Service Node the Management Node should send commands to (e.g xdsh) and should be set to the hostname or IP address of the service node that the management node can contact it by.

• xcatmaster - defines which Service Node the Compute Node should boot from and should be set to the hostname or IP address of the service node that the compute node can contact it by.

You must set both servicenode and xcatmaster regardless of whether or not you are using service node pools, for most scenarios, the value will be identical.

```
chdef -t group -o rack1 servicenode=r1n01 xcatmaster=r1n01
chdef -t group -o rack2 servicenode=r2n01 xcatmaster=r2n01
```

8. Set the conserver and monserver attributes

Set which service node should run the conserver (console) and monserver (monitoring) daemon for the nodes in the group. The most typical setup is to have the service node also ad as it’s conserver and monserver.

```
chdef -t group -o rack1 conserver=r1n01 monserver=r1n01
chdef -t group -o rack2 conserver=r2n01 monserver=r2n01
```

9. Choose location of /install and /tftpboot directories (optional).

The site table attributes installloc and sharedtftp control mounting of /install and /tftpboot directories from Management Node to Service node.

To mount /install and /tftpboot directories from Management node to each Service Node:

```
chdef -t site clustersite sharedtftp=1
chdef -t site clustersite installloc="/install"
```

To make /install and /tftpboot directories local on each Service Node, set site table attributes and “sync” /install and /tftpboot directory contents from Management Node to Service Nodes:
chdef -t site clustersite sharedtftp=0
chdef -t site clustersite installloc=
rsync -auv --exclude 'autoinst' /install r1n01:/
rsync -auv --exclude 'autoinst' /install r2n01:
rsync -auv --exclude 'autoinst' /tftpboot r1n01:/
rsync -auv --exclude 'autoinst' /tftpboot r2n01:

Configure DHCP

Add the relevant networks into the DHCP configuration, refer to: Configure xCAT

Add the defined nodes into the DHCP configuration, refer to: XCAT_pLinux_Clusters/#configure-dhcp

In the large cluster, the size of dhcp lease file "/var/lib/dhcpd/dhcpd.leases" on the DHCP server will grow over time.

At around 100MB in size, the DHCP server will take a long time to respond to DHCP requests from clients and cause DHCP timeouts:

```
...  
Mar 2 01:59:10 c656ems2 dhcpd: DHCPDISCOVER from 00:0a:f7:73:7d:d0 via eth0  
Mar 2 01:59:10 c656ems2 dhcpd: DHCPOFFER on 9.114.39.101 to 00:0a:f7:73:7d:d0 via  
    __eth0  
    __00:0a:f7:73:7d:d0 via eth0  
Mar 2 01:59:10 c656ems2 dhcpd: DHCPACK on 9.114.39.101 to 00:0a:f7:73:7d:d0 via eth0  
    __via eth0: not found  
Mar 2 01:59:10 c656ems2 dhcpd: DHCPDISCOVER from 00:0a:f7:73:7d:d0 via eth0  
Mar 2 01:59:10 c656ems2 dhcpd: DHCPOFFER on 9.114.39.101 to 00:0a:f7:73:7d:d0 via  
    __eth0  
    __00:0a:f7:73:7d:d0 via eth0  
Mar 2 01:59:10 c656ems2 dhcpd: DHCPACK on 9.114.39.101 to 00:0a:f7:73:7d:d0 via eth0  
    __via eth0: not found  
Mar 2 01:59:10 c656ems2 dhcpd: DHCPDISCOVER from 00:0a:f7:73:7d:d0 via eth0  
Mar 2 01:59:10 c656ems2 dhcpd: DHCPOFFER on 9.114.39.101 to 00:0a:f7:73:7d:d0 via  
    __eth0  
    __00:0a:f7:73:7d:d0 via eth0  
Mar 2 01:59:10 c656ems2 dhcpd: DHCPACK on 9.114.39.101 to 00:0a:f7:73:7d:d0 via eth0  
    __via eth0: not found  
...  
```

The solution is simply to restart the dhcpd service or run makedhcp -n.

Provision Service Nodes

Diskful (Stateful) Installation

Any cluster using statelite compute nodes must use a stateful (diskful) Service Nodes.

Note: All xCAT Service Nodes must be at the exact same xCAT version as the xCAT Management Node.
Configure `otherpkgdir` and `otherpkglist` for service node osimage

- Create a subdirectory `xcat` under a path specified by `otherpkgdir` attribute of the service node os image, selected during the Define Service Nodes step.

  For example, for osimage `rhels7-x86_64-install-service`

```
[root@fs4 xcat]# lsdef -t osimage rhels7-x86_64-install-service -i otherpkgdir
   Object name: rhels7-x86_64-install-service
   otherpkgdir=/install/post/otherpkggs/rhels7/x86_64
[root@fs4 xcat]# mkdir -p /install/post/otherpkggs/rhels7/x86_64/xcat
```

- Download or copy `xcat-core` and `xcat-dep.bz2` files into that `xcat` directory

```
```

- Untar the `xcat-core` and `xcat-dep.bz2` files

```
cd /install/post/otherpkggs/<os>/<arch>/xcat
tar jxvf core-rpms-snap.tar.bz2
tar jxvf xcat-dep-*.tar.bz2
```

- Verify the following entries are included in the package file specified by the `otherpkglist` attribute of the service node osimage.

```
xcat/xcat-core/xCATsn
xcat/xcat-dep/<os>/<arch>/conserver-xcat
xcat/xcat-dep/<os>/<arch>/perl-Net-Telnet
xcat/xcat-dep/<os>/<arch>/perl-Expect
```

For example, for the osimage `rhels7-x86_64-install-service`

```
lsef -t osimage rhels7-x86_64-install-service -i otherpkglist
   Object name: rhels7-x86_64-install-service
   otherpkglist=/opt/xcat/share/xcat/install/rh/service.rhels7.x86_64.otherpkggs.pkglist
   otherpkglist=/opt/xcat/share/xcat/install/rh/service.rhels7.x86_64.otherpkggs.pkglist
   otherpkglist=/opt/xcat/share/xcat/install/rh/service.rhels7.x86_64.otherpkggs.pkglist
   otherpkglist=/opt/xcat/share/xcat/install/rh/service.rhels7.x86_64.otherpkggs.pkglist
   otherpkglist=/opt/xcat/share/xcat/install/rh/service.rhels7.x86_64.otherpkggs.pkglist
   otherpkglist=/opt/xcat/share/xcat/install/rh/service.rhels7.x86_64.otherpkggs.pkglist
   otherpkglist=/opt/xcat/share/xcat/install/rh/service.rhels7.x86_64.otherpkggs.pkglist
```

**Note:** You will be installing the xCAT Service Node RPM `xCATsn` on the Service Node, not the xCAT Management Node RPM. Do not install both.

**Update the rhels6 RPM repository (rhels6 only)**

- This section could be removed after the `powerpc-utils-1.2.2-18.el6.ppc64.rpm` is built in the base rhels6 ISO.

- The direct rpm download link is:  
  ftp://linuxpatch.ncsa.uiuc.edu/PERCS/powerpc-utils-1.2.2-18.el6.ppc64.rpm
The update steps are as following: - put the new rpm in the base OS packages

```
cd /install/rhels6/ppc64/Server/Packages
mv powerpc-utils-1.2.2-17.el6.ppc64.rpm /tmp
cp /tmp/powerpc-utils-1.2.2-18.el6.ppc64.rpm .
# make sure that the rpm is be readable by other users
chmod +r powerpc-utils-1.2.2-18.el6.ppc64.rpm
```

- create the repodata

```
cd /install/rhels6/ppc64/Server
ls -al repodata/
total 14316
dr-xr-xr-x 2 root root 4096 Jul 20 09:34 .
dr-xr-xr-x 3 root root 4096 Jul 20 09:34 ..
-r--r--r-- 1 root root 1305862 Sep 22 2010 → 20dfb74c144014854d3b16313907ebcf30c9ef63346d632369a19a4add8388e7-other.sqlite.
    bz2
-r--r--r-- 1 root root 1521372 Sep 22 2010 → 57b3c81512224bb5ceb8fcb6c7fd1f7eb99ca746c66a76fb64c64f47de102-primary.xml.gz
-r--r--r-- 1 root root 2823613 Sep 22 2010 → 5f664ea798d1714d67f6610a6c92777ecb80bf35b8d3026e690cc664653e4-primary.sqlite.
    bz2
-r--r--r-- 1 root root 1418180 Sep 22 2010 → 7cec82d895b8b60b3e1254f14ee8e0a479df002f98bb557c6ccad5724ae2c8-other.xml.gz
-r--r--r-- 1 root root 194113 Sep 22 2010 → 90cbb67096e81821a2150d3b0a4f3776aba1a061b54072a0bd33d5cadd1c234a-comps-rhel6-Server.xml.gz
-r--r--r-- 1 root root 1054944 Sep 22 2010 → 346d05248098ef1724edd2c0a127954aae64d4bb7d4e693cffe32able463c-comps-rhel6-Server.xml.gz
-r--r--r-- 1 root root 3341671 Sep 22 2010 → bb3456b3482596ec3aa345d7affc42545e2db3f4f2856c0827d88477073aa45-filelists.sqlite.bz2
-r--r--r-- 1 root root 2965960 Sep 22 2010 → eb991fd2bb9af16a24a066d840ce7e6356d396b364d3cd815774e603a15ae-filelists.xml.gz
-r--r--r-- 1 root root 3829 Sep 22 2010 repomd.xml
-r--r--r-- 1 root root 2581 Sep 22 2010 TRANS.TBL
createrrepo \n  -g repodata /98462d05248098ef1724edd2c0a127954aae64d4bb7d4e693cffe32able463c-\n    comps-rhel6-Server.xml
```

Note: You should use `comps-rhel6-Server.xml` with its key as the group file.

Install Service Nodes

```
rinstall <service_node> osimage="<osimagename>"
```

For example

```
rinstall <service_node> osimage="rhels7-x86_64-install-service"
```
Monitor the Installation

Watch the installation progress using either wcons or rcons:

```bash
wcons service  # make sure DISPLAY is set to your X server/VNC or
rcons <node_name>
tail -f /var/log/messages
```

**Note:** We have experienced one problem while trying to install RHEL6 diskful Service Node working with SAS disks. The Service Node cannot reboot from SAS disk after the RHEL6 operating system has been installed. We are waiting for the build with fixes from RHEL6 team, once meet this problem, you need to manually select the SAS disk to be the first boot device and boots from the SAS disk.

Update Service Node Diskful Image

To update the xCAT software on the Service Node:

1. Remove previous xcat-core, xcat-dep, and tar files in the NFS mounted /install/post/otherpkgs/ directory:

   ```bash
   rm /install/post/otherpkgs/<os>/<arch>/xcat/xcat-core
   rm /install/post/otherpkgs/<os>/<arch>/xcat/xcat-dep
   rm /install/post/otherpkgs/<os>/<arch>/xcat/<xcat-core.tar>
   rm /install/post/otherpkgs/<os>/<arch>/xcat/<xcat-dep.tar>
   ```

2. Download the desired tar files from xcat.org on the Management Node, and untar them in the same NFS mounted /install/post/otherpkgs/ directory:

   ```bash
   cd /install/post/otherpkgs/<os>/<arch>/xcat/
   tar jxvf <new-xcat-core.tar>
   tar jxvf <new-xcat-dep.tar>
   ```

3. On the Service Node, run the package manager commands relative to the OS to update xCAT. For example, on RHEL, use the following yum commands:

   ```bash
   yum clean metadata  # or yum clean all
   yum update '*xCAT*'  # run the update
   ```

Diskless (Stateless) Installation

**Note:** The stateless Service Node is not supported in Ubuntu hierarchy cluster. For Ubuntu, skip this section.

If you want, your Service Nodes can be stateless (diskless). The Service Node must contain not only the OS, but also the xCAT software and its dependencies. In addition, a number of files are added to the Service Node to support the PostgreSQL, or MySQL database access from the Service Node to the Management node, and ssh access to the nodes that the Service Nodes services. The following sections explain how to accomplish this.
Build the Service Node Diskless Image

This section assumes you can build the stateless image on the management node because the Service Nodes are the same OS and architecture as the management node. If this is not the case, you need to build the image on a machine that matches the Service Node’s OS architecture.

- Create an osimage definition.

When you run copycds, xCAT will only create a Service Node stateful osimage definitions for that distribution. For a stateless Service Node osimage, you may create it from a stateless Compute Node osimage definition.

```
lsdef -t osimage | grep -i netboot
rhels7.3-ppc64le-netboot-compute (osimage)

mkdef -t osimage -o rhels7.3-ppc64le-netboot-service \
    --template rhels7.3-ppc64le-netboot-compute \
    profile=service provmethod=netboot postscripts=servicenode
```

```
lsdef -t osimage rhels7.3-ppc64le-netboot-service
Object name: rhels7.3-ppc64le-netboot-service
    exlist=/opt/xcat/share/xcat/netboot/rh/compute.rhels7.ppc64le.exlist
    imagetype=linux
    osarch=ppc64le
    osdistroname=rhels7.3-ppc64le
    osname=Linux
    osvers=rhels7.3
    otherpkgdir=/install/post/otherpkgs/rhels7.3/ppc64le
    pkgdir=/install/rhels7.3/ppc64le
    pkglist=/opt/xcat/share/xcat/netboot/rh/compute.rhels7.ppc64le.pkglist
    postinstall=/opt/xcat/share/xcat/netboot/rh/compute.rhels7.ppc64le.postinstall
    profile=service
    provmethod=netboot
    rootimgdir=/install/netboot/rhels7.3/ppc64le/compute
```

- Configure mandatory attributes for Service Node osimage definition.

The following attributes must be modified to suitable value:

```
exlist
otherpkglist
pkglist
postinstall
rootimgdir
```

1. Create the exlist, pkglist and otherpkglist file.

xCAT ships a basic requirements lists that will create a fully functional Service Node. However, you may want to customize your service node by adding additional operating system packages or modifying the files excluded by the exclude list. Check the below files to see if it meets your needs.

```
cd /opt/xcat/share/xcat/netboot/rh/
view service.rhels7.ppc64le.pkglist
view service.rhels7.ppc64le.otherpkgs.pkglist
view service.rhels7.ppc64le.exlist
```

If you would like to change any of these files, copy them to a custom directory. This can be any directory you choose, but we recommend that you keep it /install somewhere. A good location is something like /install/custom/netboot/<osimage>.
export OSIMAGE_DIR=/install/custom/netboot/rhels7.3-ppc64le-netboot-service
mkdir -p $OSIMAGE_DIR
cp /opt/xcat/share/xcat/netboot/rh/service.rhels7.ppc64le.pkglist $OSIMAGE_DIR
cp /opt/xcat/share/xcat/netboot/rh/service.rhels7.ppc64le.otherpkgs.pkglist $OSIMAGE_DIR
cp /opt/xcat/share/xcat/netboot/rh/service.rhels7.ppc64le.exlist $OSIMAGE_DIR

And make sure that your otherpkgs.pkglist file has the following entries:

xcat/xcat-core/xCATsn
xcat/xcat-dep/<os>/<arch>/conserver-xcat
xcat/xcat-dep/<os>/<arch>/perl-Net-Telnet
xcat/xcat-dep/<os>/<arch>/perl-Expect

For example, for the osimage rhels7.3-ppc64le-netboot-service:

xcat/xcat-core/xCATsn
xcat/xcat-dep/rh7/ppc64le/conserver-xcat
xcat/xcat-dep/rh7/ppc64le/perl-Net-Telnet
xcat/xcat-dep/rh7/ppc64le/perl-Expect

Note: You will be installing the xCAT Service Node RPM xCATsn on the Service Node, not the xCAT Management Node RPM. Do not install both.

1. Create the postinstall script.

xCAT ships a default postinstall script for stateless Service Node. You may also choose to create an appropriate /etc/fstab file in your Service Node image:

export OSIMAGE_DIR=/install/custom/netboot/rhels7.3-ppc64le-netboot-service
cp /opt/xcat/share/xcat/netboot/rh/service.rhels7.ppc64le.postinstall $OSIMAGE_DIR
vi $OSIMAGE_DIR/service.rhels7.ppc64le.postinstall

# uncomment the sample fstab lines and change as needed:
proc /proc proc rw 0 0
sysfs /sys sysfs rw 0 0
devpts /dev/pts devpts rw,gid=5,mode=620 0 0
service_ppc64le / tmpfs rw 0 1
none /tmp tmpfs defaults,size=10m 0 2
none /var/tmp tmpfs defaults,size=10m 0 2

1. Modify the Service Node osimage definition with given attributes.

export OSIMAGE_DIR=/install/custom/netboot/rhels7.3-ppc64le-netboot-service
chdef -t osimage -o rhels7.3-ppc64le-netboot-service \
exlist=$OSIMAGE_DIR/service.rhels7.ppc64le.exlist \
otherpkglist=$OSIMAGE_DIR/service.rhels7.ppc64le.otherpkgs. \
pkglist=$OSIMAGE_DIR/service.rhels7.ppc64le.pkglist \
postinstall=$OSIMAGE_DIR/service.rhels7.ppc64le.postinstall \
rootimgdir=$OSIMAGE_DIR/service
While you are here, if you’d like, you can do the same for your Service Node images, creating custom files and new custom osimage definitions as you need to.

- Make your xCAT software available for `otherpkg` processing

Option 1:

If you downloaded xCAT to your management node for installation, place a copy of your `xcat-core` and `xcat-dep` in your `otherpkgdir` directory

```bash
lsdef -t osimage -o rhels7.3-ppc64le-netboot-service -i otherpkgdir
Object name: rhels7.3-ppc64le-netboot-service
   otherpkgdir=/install/post/otherpkgs/rhels7.3/ppc64le
   cd /install/post/otherpkgs/rhels7.3/ppc64le
   mkdir xcat
   cd xcat
   cp -Rp <current location of xcat-core>/xcat-core
   cp -Rp <current location of xcat-dep>/xcat-dep
```

Option 2:

If you installed your management node directly from the online repository, you will need to download the `xcat-core` and `xcat-dep` tarballs

- From [http://xcat.org/download.html](http://xcat.org/download.html), download the `xcat-core` and `xcat-dep` tarball files. Copy these into a subdirectory in the `otherpkgdir` directory.

```bash
lsdef -t osimage -o rhels7.3-ppc64le-netboot-service -i otherpkgdir
Object name: rhels7.3-ppc64le-netboot-service
   otherpkgdir=/install/post/otherpkgs/rhels7.3/ppc64le
   cd /install/post/otherpkgs/rhels7.3/ppc64le
   mkdir xcat
   cd xcat
```
### Install Service Nodes

```
reinstall service osimage=rhel7.3-ppc64le-netboot-service
```

Watch the installation progress using either wcons or rcons:

```
wcons service  # make sure DISPLAY is set to your X server/VNC or
rcons <node_name>
tail -f /var/log/messages
```

### Enable localdisk for stateless Service Node (Optional)

If you want, your can leverage local disk to contain some directories during the stateless nodes running. And you can customize the osimage definition to achieve it. For Service Node, it is recommended to put below directories on local disk.

```
#/install (Not required when using shared /install directory)
#/tftpboot (Not required when using shared /tftpboot directory)
/var/log
/tmp
```

The following section explains how to accomplish this:

- Change the Service Node osimage definition to enable `localdisk`
#create a partition file to partition and mount the disk
export OSIMAGE=rhels7.3-ppc64le-netboot-service
cat<<EOF > /install/custom/netboot/$OSIMAGE/partitionfile
enable=yes
enablepart=yes

[disk]
dev=/dev/sda
clear=yes
parts=10,50

[localspace]
dev=/dev/sda2
fstype=ext4

[swap-space]
dev=/dev/sda1
EOF

#add the partition file to Service Node osimage definition and configure `policy`
chdef -t osimage -o $OSIMAGE partitionfile=/install/custom/netboot/$OSIMAGE/partitionfile
chtab priority=7.1 policy.commands=getpartition policy.rule=allow

#define files or directories which are required to be put on local disk
chtab litefile.image=$OSIMAGE litefile.file=/install/ litefile.options=localdisk
chtab litefile.image=$OSIMAGE litefile.file=/tftpboot/ litefile.options=localdisk
chtab litefile.image=$OSIMAGE litefile.file=/var/log/ litefile.options=localdisk
chtab litefile.image=$OSIMAGE litefile.file=/tmp/ litefile.options=localdisk

• Run image generation and repacking for your osimage definition:
  
  genimage rhels7.3-ppc64le-netboot-service
  packimage rhels7.3-ppc64le-netboot-service

Note: enablepart=yes in partition file will partition the local disk at every boot. If you want to preserve the contents on local disk at next boot, change to enablepart=no after the initial provision.

For more information on localdisk option, refer to Enabling the localdisk option

Update Service Node Stateless Image

To update the xCAT software in the image at a later time:

• Download the updated xcat-core and xcat-dep tarballs and place them in your osimage’s otherpkgdir xcat directory as you did above.

• Generate and repack the image and reboot your Service Node.

• Run image generation for your osimage definition.

  genimage "<osimagename>"
  packimage "<osimagename>"
  rinstall service osimage="<osimagename>"
Note: The Service Nodes are set up as NFS-root servers for the compute nodes. Any time changes are made to any compute image on the mgmt node it will be necessary to sync all changes to all Service Nodes. In our case the /install directory is mounted on the servicenodes, so the update to the compute node image is automatically available.

Verify Service Node Installation

- ssh to the service nodes. You should not be prompted for a password.
- Check to see that the xcat daemon xcatd is running.
- Run some database command on the service node, e.g tabdump site, or nodels, and see that the database can be accessed from the service node.
- Check that /install and /tftpboot are mounted on the service node from the Management Node, if appropriate.
- Make sure that the Service Node has name resolution for all nodes it will service.
- Run updatenode <compute node> -V -s on management node and verify output contains Running command on <service node> that indicates the command from management node is sent to service node to run against compute node target.

See Appendix B for possible solutions.

Appendix

Appendix A: Setup backup Service Nodes

For reliability, availability, and serviceability purposes you may wish to designate backup Service Nodes in your hierarchical cluster. The backup Service Node will be another active Service Node that is set up to easily take over from the original Service Node if a problem occurs. This is not an automatic failover feature. You will have to initiate the switch from the primary Service Node to the backup manually. The xCAT support will handle most of the setup and transfer of the nodes to the new Service Node. This procedure can also be used to simply switch some compute nodes to a new Service Node, for example, for planned maintenance.

Initial deployment

Integrate the following steps into the hierarchical deployment process described above.

1. Make sure both the primary and backup service nodes are installed, configured, and can access the MN database.
2. When defining the CNs add the necessary service node values to the “servicenode” and “xcatmaster” attributes of the node definitions.
3. (Optional) Create an xCAT group for the nodes that are assigned to each SN. This will be useful when setting node attributes as well as providing an easy way to switch a set of nodes back to their original server.

To specify a backup service node you must specify a comma-separated list of two service nodes for the servicenode value of the compute node. The first one is the primary and the second is the backup (or new SN) for that node. Use the hostnames of the SNs as known by the MN.

For the xcatmaster value you should only include the primary SN, as known by the compute node.
In most hierarchical clusters, the networking is such that the name of the SN as known by the MN is different than the name as known by the CN. (If they are on different networks.)

The following example assume the SN interface to the MN is on the “a” network and the interface to the CN is on the “b” network. To set the attributes you would run a command similar to the following.

```
chdef <noderange> servicenode="xcatsn1a,xcatsn2a" xcatmaster="xcatsn1b"
```

The process can be simplified by creating xCAT node groups to use as the <noderange> in the chdef command to create a xCAT node group containing all the nodes that belong to service node “SN27”. For example:

```
mkdef -t group sn1group members=node[01-20]
```

Note: Normally backup service nodes are the primary SNs for other compute nodes. So, for example, if you have 2 SNs, configure half of the CNs to use the 1st SN as their primary SN, and the other half of CNs to use the 2nd SN as their primary SN. Then each SN would be configured to be the backup SN for the other half of CNs.

When you run makedhcp command, it will configure dhcp and tftp on both the primary and backup SNs, assuming they both have network access to the CNs. This will make it possible to do a quick SN takeover without having to wait for replication when you need to switch.

**xdcp Behaviour with backup servicenodes**

The xdcp command in a hierarchical environment must first copy (scp) the files to the service nodes for them to be available to scp to the node from the service node that is it’s master. The files are placed in /var/xcat/syncfiles directory by default, or what is set in site table SNsyncfiledir attribute. If the node has multiple service nodes assigned, then xdcp will copy the file to each of the service nodes assigned to the node. For example, here the files will be copied (scp) to both service1 and rhsn. lsdef cn4 | grep servicenode.

```
servicenode=service1,rhsn
```

If a service node is offline (e.g. service1), then you will see errors on your xdcp command, and yet if rhsn is online then the xdcp will actually work. This may be a little confusing. For example, here service1 is offline, but we are able to use rhsn to complete the xdcp.

```
xdcp cn4 /tmp/lissa/file1 /tmp/file1
```

```
service1: Permission denied (publickey,password,keyboard-interactive).
service1: Permission denied (publickey,password,keyboard-interactive).
service1: lost connection
The following servicenodes: service1, have errors and cannot be updated
Until the error is fixed, xdcp will not work to nodes serviced by these service nodes.
```

```
xdsh cn4 ls /tmp/file1
```

```
cn4: /tmp/file1
```

**Switch to the backup SN**

When an SN fails, or you want to bring it down for maintenance, use this procedure to move its CNs over to the backup SN.
Move the nodes to the new service nodes

Use the `snmove` command to make the database changes necessary to move a set of compute nodes from one Service Node to another.

To switch all the compute nodes from Service Node `sn1` to the backup Service Node `sn2`, run:

```
snmove -s sn1
```

Modified database attributes

The `snmove` command will check and set several node attribute values.

- **servicenode**: This will be set to either the second server name in the servicenode attribute list or the value provided on the command line.
- **xcatmaster**: Set with either the value provided on the command line or it will be automatically determined from the servicenode attribute.
- **nfsserver**: If the value is set with the source service node then it will be set to the destination service node.
- **tftpserver**: If the value is set with the source service node then it will be reset to the destination service node.
- **monserver**: If set to the source service node then reset it to the destination servicenode and xcatmaster values.
- **conserver**: If set to the source service node then reset it to the destination servicenode and run `makeconservercf`

Run postscripts on the nodes

If the CNs are up at the time the `snmove` command is run then `snmove` will run postscripts on the CNs to reconfigure them for the new SN. The “syslog” postscript is always run. The `mkresolvconf` and `setupntp` scripts will be run if they were included in the nodes postscript list.

You can also specify an additional list of postscripts to run.

Modify system configuration on the nodes

If the CNs are up the `snmove` command will also perform some configuration on the nodes such as setting the default gateway and modifying some configuration files used by xCAT.

Switching back

The process for switching nodes back will depend on what must be done to recover the original service node. If the SN needed to be reinstalled, you need to set it up as an SN again and make sure the CN images are replicated to it. Once you’ve done this, or if the SN’s configuration was not lost, then follow these steps to move the CNs back to their original SN:

- Use `snmove`:

  ```
  snmove snlgroup -d sn1
  ```
Appendix B: Diagnostics

- **root ssh keys not setup** – If you are prompted for a password when ssh to the service node, then check to see if 
  `/root/.ssh` directory on MN has `authorized_keys` file. If the directory does not exist or no keys, run 
  `xdsh service -K`, to exchange the ssh keys for root. You will be prompted for the root password, which 
  should be the password you set for the `key=system` in the `passwd` table.

- **xCAT rpms not on SN** – On the SN, run `rpm -qa | grep xCAT` and make sure the appropriate xCAT 
  rpms are installed on the servicenode. See the list of xCAT rpms in `Diskful (Stateful) Installation`. If rpms are 
  missing, check your install setup as outlined in `Diskless (Stateless) Installation` for diskless or 
  `Diskful (Stateful)` Installation for diskful installs.

- **otherpkgs(including xCAT rpms) installation failed on the SN** – The OS repository is not created on the SN. 
  When the “yum” command is processing the dependency, the rpm packages (including expect, nmap, and httpd, 
  etc) required by xCATsn can’t be found. In this case, check whether the `/install/postscripts/repos/<osver>/<arch>/` 
  directory exists on the MN. If it is not on the MN, you need to re-run the copycds com- 
  mand, and there will be files created under the `/install/postscripts/repos/<osver>/<arch>/` directory on the MN. Then, you need to re-install the SN.

- **Error finding the database/starting xcatd** – If on the Service node when you run tabdump site, you get 
  “Connection failure: IO::Socket::SSL: connect: Connection refused at `/opt/xcat/lib/perl/xCAT/ 
  Client.pm`”. Then restart the xcatd daemon and see if it passes by running the command xcatd restart. 
  If it fails with the same error, then check to see if `/etc/xcat/cfgloc` file exists. It should exist 
  and be the same as `/etc/xcat/cfgloc` on the MN. If it is not there, copy it from the MN to the SN. The run 
  `service xcatd restart`. This indicates the servicenode postscripts did not complete successfully. Run 
  `lsdef <service node> -i postscripts -c` and verify servicenode postscript appears on the 
  list.

- **Error accessing database/starting xcatd credential failure**– If you run tabdump site on the service 
  node and get “Connection failure: IO::Socket::SSL: connect: Connection refused at `/opt/xcat/lib/perl/xCAT/ 
  Client.pm`. Then restart the xcatd daemon and see if it passes by running the command xcatd restart. 
  If it fails with the same error, then check to see if `/etc/xcat/cfgloc` file exists. It should exist 
  and be the same as `/etc/xcat/cfgloc` on the MN. If it is not there, copy it from the MN to the SN. The run 
  service xcatd restart. This indicates the the servicenode postscripts did not complete successfully. Run 
  `lsdef <service node> -i postscripts -c` and verify servicenode postscript appears on the list. Run service xcatd 
  restart again and try the tabdump site again.

- **Missing ssh hostkeys** – Check to see if `/etc/xcat/hostkeys` on the SN, has the same files as `/etc/ 
  xcat/hostkeys` on the MN. These are the ssh keys that will be installed on the compute nodes, so root can 
  ssh between compute nodes without password prompting. If they are not there copy them from the MN to the 
  SN. Again, these should have been setup by the servicenode postscripts.

- **Errors running hierarchical commands such as xdsh** – xCAT has a number of commands that run hier- 
  archically. That is, the commands are sent from xcatd on the management node to the correct service node 
  xcatd, which in turn processes the command and sends the results back to xcatd on the management node. If 
  a hierarchical command such as xcatd fails with something like “Error: Permission denied for request”, check 
  `/var/log/messages` on the management node for errors. One error might be “Request matched no policy 
  rule”. This may mean you will need to add policy table entries for your xCAT management node and service 
  node.

- **/install is not mounted on service node from management mode** – If service node does not have `/install` 
  directory mounted from management node, run `lsdef -t site clustersite -i installloc` and 
  verify `installloc="/install"`. 
Appendix C: Migrating a Management Node to a Service Node

Directly converting an existing Management Node to a Service Node may have some issues and is not recommended. Do the following steps to convert the xCAT Management Node into a Service node:

1. backup your xCAT database on the Management Node
2. Install a new xCAT Management node
3. Restore your xCAT database into the new Management Node
4. Re-provision the old xCAT Management Node as a new Service Node

Appendix D: Set up Hierarchical Conserver

To allow you to open the rcons from the Management Node using the conserver daemon on the Service Nodes, do the following:

- Set nodehm.conserver to be the service node (using the ip that faces the management node)

```
chdef -t <noderange> conserver=<servicenodeasknownbytheMN>
makeconservercf
service conserver stop
service conserver start
```

### 1.4.11 Software Kits

xCAT supports a unique software bundling concept called **software kits**. Software kit combines all of the required product components (packages, license, configuration, scripts, etc) to assist the administrator in the installation of software onto machines managed by xCAT. Software kits are made up of a collection of “kit components”, each of which is tailored to one specific environment for that particular version of the software product.

Prebuilt software kits are available as a tar file which can be downloaded and then added to the xCAT installation. After the kits are added to xCAT, kit components are then added to specific xCAT osimages to automatically install the software bundled with the kit during OS deployment. In some instances, software kits may be provided as partial kits. Partial kits need additional effort to complete the kit before it can be used by xCAT.

Software kits are supported for both diskful and diskless image provisioning.

#### Prebuilt Kits - IBM High Performance Computing

The IBM High Performance Computing (HPC) software can be installed by xCAT using Software Kits. Most products ship the complete Software Kit on the distribution media and can be consumed “as is”.

**Quick Start Guide**

This quick start is provided to guide users through the steps required to install the IBM High Performance Computing (HPC) software stack on a cluster managed by xCAT. *(NOTE: xCAT provides XLC and XLF partial kits, but all other HPC kits are provided by the HPC products teams, xCAT may not have any knowledges of their dependencies and requirements)*

The following software kits will be used to install the IBM HPC software stack on to a RedHat Enterprise Linux 7.2 operating system running on ppc64le architecture.
• xlc-13.1.3-0-ppc64le.tar.bz2
• xlf-15.1.3-0-ppc64le.tar.bz2
• pperte-2.3.0.0-1547a-ppc64le.tar.bz2
• pperte-2.3.0.2-s002a-ppc64le.tar.bz2
• essl-5.4.0-0-ppc64le.tar.bz2
• pessl-5.2.0-0-ppc64le.tar.bz2
• ppedev-2.2.0-0.tar.bz2

1. Using the addkit command, add each software kit package into xCAT:

```
addkit xlc-13.1.3-0-ppc64le.tar.bz2,xlf-15.1.3-0-ppc64le.tar.bz2
addkit pperte-2.3.0.0-1547a-ppc64le.tar.bz2,pperte-2.3.0.2-s002a-ppc64le.tar.bz2
addkit pessl-5.2.0-0-ppc64le.tar.bz2,essl-5.4.0-0-ppc64le.tar.bz2
addkit ppedev-2.2.0-0.tar.bz2
```

The lskit command can be used to view the kits after adding to xCAT.

2. Using the addkitcomp command, add the kitcomponent to the target osimage.

The order that the kit components are added to the osimage is important due to dependencies that kits may have with one another, a feature to help catch potential issues ahead of time. There are a few different types of dependencies:

- **Internal kit dependencies** - kit components within the software kit have dependencies. For example, the software has a dependency on its license component. The `-a` option will automatically resolve internal kit dependencies.

- **External kit dependencies** - a software kit depends on another software provided in a separate kit. The dependency kit must be added first. addkitcomp will complain if it cannot resolve the dependency.

- **Runtime dependencies** - the software provided in the kit has rpm requirements for external 3rd party RPMs not shipped with the kit. The administrator needs to configure these before deploying the osimage and addkitcomp cannot detect these dependencies.

In the following examples, the rhels7.2-ppc64le-install-compute osimage is used and the `-a` option is specified to resolve internal dependencies.

1. Add the XLC kit components to the osimage:

```
addkitcomp -a -i rhels7.2-ppc64le-install-compute \ 
  xlc.compiler-compute-13.1.3-0-rhels-7.2-ppc64le
```

2. Add the XLF kit components to the osimage:

```
addkitcomp -a -i rhels7.2-ppc64le-install-compute \ 
  xlf.compiler-compute-15.1.3-0-rhels-7.2-ppc64le
```

3. Add the PE RTE GA, pperte-1547a, kit components to the osimage:

```
addkitcomp -a -i rhels7.2-ppc64le-install-compute \ 
  pperte-login-2.3.0.0-1547a-rhels-7.2-ppc64le
addkitcomp -a -i rhels7.2-ppc64le-install-compute \ 
  pperte-compute-2.3.0.0-1547a-rhels-7.2-ppc64le
```
4. Add the PE RTE PTF2, `pperte-s002a`, kitcomponents to the osimage.

The PTF2 update requires the `pperte-license` component, which is provided by the GA software kit. The `addkitcomp -n` option allows for multiple versions of the same kit component to be installed into the osimage. If only the PTF2 version is intended to be installed, you can skip the previous step for adding the GA ppetre kit component, but the GA software kit must have been added to xCAT with the `addkit` command in order to resolve the license dependency.

```
addkitcomp -a -n -i rhels7.2-ppc64le-install-compute \
  pperte-login-2.3.0.2-s002a-rhels-7.2-ppc64le
addkitcomp -a -n -i rhels7.2-ppc64le-install-compute \
  pperte-compute-2.3.0.2-s002a-rhels-7.2-ppc64le
addkitcomp -a -n -i rhels7.2-ppc64le-install-compute \
  min-pperte-compute-2.3.0.2-s002a-rhels-7.2-ppc64le
```

5. Add the ESSL kitcomponents to the osimage.

The ESSL software kit has an external dependency to the `libxlf` which is provided in the XLF software kit. Since it’s already added in the above step, there is no action needed here.

If CUDA toolkit is being used, ESSL has a runtime dependency on the CUDA rpms. The administrator needs to create the repository for the CUDA 7.5 toolkit or a runtime error will occur when provisioning the node. See the Create CUDA software repository section for more details about setting up the CUDA repository on the xCAT management node.

```
# Assuming that the cuda repo has been configured at:
# /install/cuda-7.5/ppc64le/cuda-core
#
chdef -t osimage rhels7.2-ppc64le-install-compute \
  pkgdir=/install/rhels7.2/ppc64le,/install/cuda-7.5/ppc64le
addkitcomp -a -i rhels7.2-ppc64le-install-compute \
  essl-computenode-6464rte-5.4.0-0-rhels-7.2-ppc64le
addkitcomp -a -i rhels7.2-ppc64le-install-compute \
  essl-computenode-3264rte-5.4.0-0-rhels-7.2-ppc64le
addkitcomp -a -i rhels7.2-ppc64le-install-compute \
  essl-computenode-5.4.0-0-rhels-7.2-ppc64le
addkitcomp -a -i rhels7.2-ppc64le-install-compute \
  essl-loginnode-5.4.0-0-rhels-7.2-ppc64le
addkitcomp -a -i rhels7.2-ppc64le-install-compute \
  essl-computenode-3264rtecuda-5.4.0-0-rhels-7.2-ppc64le
```

If the system doesn’t have GPU and the CUDA toolkit is not needed, the administrator should not add the following kit components that requires the
CUDA packages: essl-loginnode-5.4.0-0-rhel5-7.2-ppc64le, essl-computenode-3264rte-5.4.0-0-rhel5-7.2-ppc64le and essl-computenode-3264rtecuda-5.4.0-0-rhel5-7.2-ppc64le.

Check the ESSL installation guide: http://www.ibm.com/support/knowledgecenter/SSFYH8_5.4.0/com.ibm.cluster.essl.v5r4.essl300.doc/am5il_xcatinstall.htm

1. Add the Parallel ESSL kitcomponents to osimage.

   Note: ESSL kitcomponents are required for the PESSL.

   \[
   \text{addkitcomp} -a -i \text{rhel5-2ppc64le-install-compute} \\
   \text{pessl-loginnode-5.2.0-0-rhel5-7.2-ppc64le}
   \]

   \[
   \text{addkitcomp} -a -i \text{rhel5-2ppc64le-install-compute} \\
   \text{pessl-computenode-5.2.0-0-rhel5-7.2-ppc64le}
   \]

   \[
   \text{addkitcomp} -a -i \text{rhel5-2ppc64le-install-compute} \\
   \text{pessl-computenode-3264rtempich-5.2.0-0-rhel5-7.2-ppc64le}
   \]

2. Add the PE DE kitcomponents to osimage:

   \[
   \text{addkitcomp} -a -i \text{rhel5-2ppc64le-install-compute} \\
   \text{ppedev.login-2.2.0-0-rhel5-7.2-ppc64le}
   \]

   \[
   \text{addkitcomp} -a -i \text{rhel5-2ppc64le-install-compute} \\
   \text{ppedev.compute-2.2.0-0-rhel5-7.2-ppc64le}
   \]

3. The updated osimage now contains the configuration to install using xCAT software kits:

\[
\text{lsdef} -t \text{osimage rhel5-2ppc64le-install-compute} \\
\text{Object name: rhel5-2ppc64le-install-compute} \\
\text{exlist=/install/osimages/rhel5-2ppc64le-install-compute-kits/kits/KIT_} \\
\text{COMPONENTS.exlist} \\
\text{imagetype=linux} \\
\text{kitcomponents=xlc.license-compute-13.1.3-0-rhel5-7.2-ppc64le,xlc.rte-compute-13.1.3-0-rhel5-7.2-ppc64le,xlc.compiler-compute-13.1.3-0-rhel5-7.2-ppc64le,xlf.license-compute-15.1.3-0-rhel5-7.2-ppc64le,xlf.rte-compute-15.1.3-0-rhel5-7.2-ppc64le,xlf.compiler-compute-15.1.3-0-rhel5-7.2-ppc64le,pperte-license-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,essl-loginnode-5.4.0-0-rhel5-7.2-ppc64le,essl-computenode-3264rte-5.4.0-0-rhel5-7.2-ppc64le,pperte-license-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-login-2.3.0.0-1547a-rhel5-7.2-ppc64le,pperte-compute-2.3.0.0-1547a-rhel5-7.2-ppc64le
\]

(continues on next page)
4. The osimage is now ready to deploy to the compute nodes.

Product Specific Details

Refer to the following pages for product specific details and known issues.

IBM XL Compilers


Partial Kits

The IBM XL compilers are dependencies for some of the HPC software products and is not available in xCAT Software Kit format.

To assist customers in creating a software kit for the IBM XL compilers, xCAT provides partial kits at: https://xcat.org/files/kits/hpckits/

Creating Compiler Complete Kit

To use software kits that require compiler kit components, a compiler software kit must be available. The following example will outline the steps required to create the xlc-12.1.0.8-151013-ppc64.tar.bz2 compiler software kit. Repeat the steps for each compiler kit required.

1. xCAT `buildkit` command requires `createrepo` is available on the machine:

   ```bash
   which createrepo
   ```

   If not available, use the default OS package manager to install. (yum, zypper, apt-get)

2. Obtain the IBM XL compilers rpms from the IBM Download site.

   `xlc-12.1.0.8` is downloaded to `/tmp/kits/xlc-12.1.0.8`

   ```bash
   # ls -l /tmp/kits/xlc-12.1.0.8/
   vac.cmp-12.1.0.8-151013.ppc64.rpm
   vac.lib-12.1.0.8-151013.ppc64.rpm
   vac.lic-12.1.0.8-120323.ppc64.rpm
   vaccpp.cmp-12.1.0.8-151013.ppc64.rpm
   ```
3. Obtain the corresponding compiler partial kit from https://xcat.org/files/kits/hpckits/.

xlc-12.1.0.8-151013-ppc64.NEED_PRODUCT_PKGS.tar.bz2 is downloaded to /tmp/kits:

4. Complete the partial kit by running the `buildkit addpkgs` command:

Sample output:

```
Extracting tar file /tmp/kits/xlc-12.1.0.8-151013-ppc64.NEED_PRODUCT_PKGS.tar.bz2. → Please wait.
Spawning worker 0 with 5 pkgs
Spawning worker 1 with 5 pkgs
Spawning worker 2 with 4 pkgs
Spawning worker 3 with 4 pkgs
Workers Finished
Saving Primary metadata
Saving file lists metadata
Saving other metadata
Generating sqlite DBs
Sqlite DBs complete
Creating tar file /tmp/kits/xlc-12.1.0.8-151013-ppc64.tar.bz2.
Kit tar file /tmp/kits/xlc-12.1.0.8-151013-ppc64.tar.bz2 successfully built.
```

5. The complete kit, /tmp/kits/xlc-12.1.0.8-151013-ppc64.tar.bz2 is ready to be used.

**Parallel Environment Runtime Edition (PE RTE)**

xCAT software kits for PE RTE for Linux is available on:

- PE RTE 1.3 1 and newer

---

1 If the partial kit for the version needed does not exist on the download site, open an issue to the xcat development team.
2 If using older releases of PE RTE, refer to IBM HPC Stack in an xCAT Cluster
PE RTE and mlnxofed_ib_install Conflict

PPE requires the 32-bit version of libibverbs. The default behavior of the mlnxofed_ib_install postscript used to install the Mellanox OFED Infiniband (IB) driver is to remove any of the old IB related packages when installing. To bypass this behavior, set the variable mlnxofed_options=--force when running the mlnxofed_ib_install script.

Install Multiple Versions

Beginning with PE RTE 1.2.0.10, the packages are designed to allow for multiple versions of PE RTE to coexist on the same machine.

The default behavior of xCAT software kits is to only allow one version of a kitcomponent to be associated with an xCAT osimage. When using addkitcomp to add a newer version of a kit component, xCAT will first remove the old version of the kit component before adding the new one.

To add multiple versions of PE RTE kit components to the same osimage, use the -n | --noupgrade option. For example, to add PE RTE 1.3.0.1 and PE RTE 1.3.0.2 to the compute osimage:

```bash
addkitcomp -i compute pperte_compute-1.3.0.1-0-rhels-6-x86_64
addkitcomp -i compute -n pperte_compute-1.3.0.2-0-rhels-6-x86_64
```

POE hostlist

When running parallel jobs, POE requires the user pass it a host list file. xCAT can help to create this hostlist file by running the nodels command against the desired node range and redirecting to a file.

```bash
nodels compute > /tmp/hostlist
```

Known Issues

- **[PE RTE 1.3.0.7]** - For developers creating the complete software kit. The src rpm is no longer required. It is recommended to create the new software kit for PE RTE 1.3.0.7 from scratch and not to use the older kits as a starting point.
- **[PE RTE 1.3.0.7]** - When upgrading ppe_rte_man in a diskless image, there may be errors reported during the genimage process. The new packages are actually upgraded, so the errors can be ignored with low risk.
- **[PE RTE 1.3.0.1 to 1.3.0.6]** - When uninstalling or upgrading ppe_rte_man in an diskless image, genimage <osimage> may fail and stop an an error. To workaround, simply rerun genimage <osimage> to finish the creation of the diskless image

Parallel Environment Developer Edition (PE DE)

xCAT software kits for PE DE for Linux is available on:¹

- PE DE 1.2.0.1 and newer (SystemX)
- PE DE 1.2.0.3 and newer (SystemP)

¹ If using an older release, refer to IBM HPC Stack in an xCAT Cluster
Engineering and Scientific Subroutine Library (ESSL)

xCAT software kits for ESSL for Linux is available on:

- ESSL 5.2.0.1 and newer

**Dependencies**

- ESSL has a dependency on the XLC/XLF compilers

When adding the ESSL kit component to the osimage, ensure that the compiler kit component is already added to the osimage, or, use the \(--adddeps\) option on addkitcomp to automatically assign the kit dependencies to the osimage.

To add the `essl-computenode kit component` to osimage `rhels7.2-ppc64le-install-compute`:

```
addkitcomp -a -i rhels7.2-ppc64le-install-compute \
  essl-computenode-3264rte-5.4.0-0-rhels-7.2-ppc64le
```

**Reference**

Refer to ESSL installation guide for more information: [http://www.ibm.com/support/knowledgecenter/SSFHY8_5.4.0/com.ibm.cluster.essl.v5r4.essl300.doc/am5il_xcatinstall.htm](http://www.ibm.com/support/knowledgecenter/SSFHY8_5.4.0/com.ibm.cluster.essl.v5r4.essl300.doc/am5il_xcatinstall.htm)

Parallel Engineering and Scientific Subroutine Library (PESSL)

xCAT software kits for PESSL for Linux is available on:

- PESSL 4.2.0.0 and newer

**Dependencies**

- PESSL has a dependency on the ESSL kit component

When adding PESSL kit component and want ESSL installed, ensure that the ESSL kit component is already added to the osimage, or, use the \(--adddeps\) option on addkitcomp to automatically assign the kit dependencies to the osimage.

To add the `pessl-computenode kit component` to osimage `rhels7.2-ppc64le-install-compute`:

```
addkitcomp -a -i rhels7.2-ppc64le-install-compute \
  pessl-computenode-5.2.0-0-rhels-7.2-ppc64le
```

Custom Kits - Creating Software Kits

**Introduction**

1. If using an older release, refer to IBM HPC Stack in an xCAT Cluster
2. If using an older release, refer to IBM HPC Stack in an xCAT Cluster
A Software Kit is a tar file that contains the following:

**Kit Configuration File** — A file describing the contents of this kit and contains following information

- Kit name, version, description, supported OS distributions, license information, and deployment parameters
- Kit repository information including name, supported OS distributions, and supported architectures
- Kit component information including name, version, description, server roles, scripts, and other data

**Kit Repositories** — A directory for each operating system version this kit is supported in. Each directory contains all of the product software packages required for that environment along with repository metadata.

**Kit Components** — A product “meta package” built to require all of the product software dependencies and to automatically run installation and configuration scripts.

**Kit and Kit Component Files** — Scripts, deployment parameters, exclusion lists, and other files used to install and configure the kit components and product packages.

**Docs [PCM only]**¹ — Product documentation shipped as HTML files that can be displayed through the PCM GUI

**Plugins [PCM only]** — xCAT plugins that can be used for additional product configuration and customization during PCM image management and node management

**Kit Components**

Software Kits are deployed to xCAT managed nodes through the xCAT osimage deployment mechanism. The kit components are inserted into the attributes of the Linux osimage definition. The attributes that are modified are the following:

- kitcomponents - A list of the kitcomponents assigned to the OS image
- serverrole - The role of this OS image that must match one of the supported serverroles of a kitcomponent
- otherpkglist - Includes kitcomponent meta package names
- postinstall - Includes kitcomponent scripts to run during genimage
- postbootscripts - Includes kitcomponent scripts
- exlist - Exclude lists for diskless images
- otherpkgdir - Kit repositories are linked as subdirectories to this directory

Once the kit components are added to xCAT osimage definitions, administrators can use:

1. standard node deployment for installing the kit components during diskful OS provisioning
2. genimage command to create a diskless OS image installing the kit components for diskless OS provisioning
3. updatenode command to install the kit components on existing deployed nodes

The kitcomponent metadata defines the kit packages as dependency packages and the OS package manager (yum, zypper, apt-get) automatically installles the required packages during the xCAT otherpkgs install process.

¹ PCM is IBM Platform Cluster Manager
**Kit Framework**

With time, the implementation of the xCAT Software Kit support may change.

In order to process a kit successfully, the kit must be compatible with the level of xCAT code that was used to build the kit. The xCAT kit commands and software kits contain the framework version and compatible supported versions.

To view the framework version, use the `-v` | `--version` option on `addkit`

```
# addkit -v
addkit - xCAT Version 2.11 (git commit 9ea36ca6163392bf9ab684830217f017193815be, →
built Mon Nov 30 05:43:11 EST 2015)
  kitframework = 2
  compatible_frameworks = 0,1,2
```

If the commands in the xCAT installation is not compatible with the Software Kit obtained, update xCAT to a more recent release.

**Building Kits**

**Requirements**

The `xCAT-buildkit` rpm is required to create xCAT Software Kits. This rpm should be installed along with the rest of xCAT.

If the xCAT management node is not intended to be used to build the Software Kit, refer to the *Install Guide* to configure the xCAT repository on the target node and install `xCAT-buildkit` using one of the following commands:

- **[RHEL]**
  
  ```
yum clean metadata
  yum install xCAT-buildkit
  ```

- **[SLES]**
  
  ```
zypper clean
zypper install xCAT-buildkit
``` 

- **[UBUNTU]**
  
  ```
apt-get clean
apt-get install xcat-buildkit
``` 

**Creating a New Kit**

Use the `buildkit` command to create a kit template directory structure

```
buildkit create <kitbasename> [-l|--kitloc <kit location>]
```

**Kit Directory**

The Kit directory location will be automatically populated with additional subdirectories and samples:

- `buildkit.conf` - The sample Kit build configuration file.
source_packages - This directory stores the source packages for Kit Packages and Non-Native Packages. The `buildkit` command will search these directories for source packages when building packages. This directory stores:

- RPM spec and tarballs. (A sample spec file is provided.)
- Source RPMs.
- Pre-built RPMs (contained in a subdirectory of source_packages)
- Non-Native Packages

scripts - This directory stores the Kit Deployment Scripts. Samples are provided for each type of script.

plugins - This directory stores the Kit Plugins. Samples are provided for each type of plugin.

docs - This directory stores the Kit documentation files.

other_files

- `kitdeployparams.lst`: Kit Deployment parameters file
- `exclude.lst`: File containing files/dirs to exclude in stateless image.

build - This directory stores files when the Kit is built.

- `kit_repodir` - This directory stores the fully built Kit Package Repositories
- `<kitbasename>` - This directory stores the contents of the Kit tarfile before it is tar’red up.

<kitname> - The Kit tar file, partial kit name or complete kit tar file name (ex. kitname.tar.bz2)

Kit Configuration File

The `buildkit.conf` file is a sample file that contains a description of all the supported attributes and indicates required or optional fields. The user needs to modify this file for the software kit to be built.¹

kit — This stanza defines general information for the Kit. There must be exactly one kit stanza in a kit build file.

```
kit:
    basename=pperte
    description=Parallel Environment Runtime Edition
    version=1.3.0.6
    release=0
    ostype=Linux
    osarch=x86_64
    kitlicense=ILAN  # the default kit license string is "EPL"
    kitdeployparams=pe.env  # pe.env has to define in the other_files dir.
```

kitrepo — This stanza defines a Kit Package Repository. There must be at least one kitrepo stanza in a kit build file. If this kit need to support multiple OSes, user should create a separate repository for each OS. Also, no two repositories can be defined with the same OS name, major version, and arch.

```
kirepo:
    kitrepoid=rhels6_x86_64
    osbasename=rhels
    osmajorversion=6
    osarch=x86_64

    kitrepoid=sles11_x86_64
```

¹ The latest version of the `buildkit.conf` file is located in the `/opt/xcat/share/xcat/kits/kit_template` directory.

1.4. Advanced Topics
minor version can be support following format:

- osminorversion=2  \(<=\) minor version has to be exactly matched to 2
- osminorversion=>=2  \(>=\) minor version can be 2 or greater than 2
- osminorversion=>2  \(>\) minor version can be 2 or less than 2
- osminorversion=<2  \(<\) minor version has to be less than 2

**kitcomponent** — This stanza defines one Kit Component. A kitcomponent definition is a way of specifying a subset of the product Kit that may be installed into an xCAT osimage. A kitcomponent may or may not be dependent on other kitcomponents. If user want to build a component which supports multiple OSes, need to create one kitcomponent stanza for each OS.

```
kitcomponent:
  basename=pperte_license
  description=PE RTE
  serverroles=compute
  # These packages must be shipped with the OS distro
  ospkgdeps=at,rsh,rsh-server,xinetd,sudo,libibverbs(x86-32),libibverbs(x86-64),
  →redhat-lsb
  kitrepoid=rhels6_x86_64
  kitpkgdeps=ppe_rte_license
kitcomponent:
  basename=pperte_compute
  description=PE RTE
  serverroles=compute
  kitrepoid=rhels6_x86_64
  kitcomdeps=pperte_license
  kitpkgdeps=pperte,pperteman,ppertesamples,src
  exlist=pe.exlist  \(<=\) the file needs to define in the other_files dir
  # All those post script need to define in the scripts dir
  postinstall=pperte_postinstall
  postupgrade=pperte_postinstall
  postbootscripts=pperte_postboot
kitcomponent:
  basename=pperte_license
  description=PE RTE
  serverroles=compute
  ospkgdeps=at,rsh-server,xinetd,sudo,libibverbs-32bit,libibverbs,innser
  kitrepoid=sles11_x86_64
  kitpkgdeps=ppe_rte_license
```

**kitpackage** — This stanza defines Kit Package (ie. RPM). There can be zero or more kitpackage stanzas. For multiple package supports, need to

1. Define one kitpackage section per supported OS. or
2. Define one kitpackage stanza which contains multiple kitrepoid lines. For the RPM packages, users need to responsible for creating an RPM spec file that can run on multiple OSes.

```
kitpackage:
  filename=pperte-*.x86_64.rpm
  kitrepoid=rhels6_x86_64,sles11_x86_64
```

(continues on next page)
Partial vs. Complete Kits

A complete software kit includes all the product software and is ready to be consumed as is. A partial software kit is one that does not include all the product packages and requires the consumer to download the product software and complete the kit before it can be consumed.

To build partial kits, the `isexternalpkg=yes` needs to be set in the `kitpackage` stanza in the `buildkit.conf` file:

```
kitpackage:
    filename=foobar_runtime-*.x86_64.rpm
    kitrepoid=rhel6_x86_64
    isexternalpkg=yes
```

Validating Kits

After modifying the `buildkit.conf` file and copying all the necessary files to the kit directories, use the `chkconfig` option on `buildkit` to validate the configuration file:

```
buildkit chkconfig
```

This command will verify all required fields defined in the `buildkit.conf`. If errors are found, fix the specified error and rerun the command until all fields are validated.

Build Kit Repositories

After the `buildkit` configuration file is validated, run the `buildrepo` subcommand to build the Kit Package Repositories. The build server has to have same OS distributions, versions, or architectures with build kit repositories. User can
copy the kit template directory to an appropriate server to build the repository then copy the results back the current system.

IBM HPC Products are using pre-built rpms. There are no OS/arch specific in the kitcomponent meta-package rpm and should be able to build all repositories on the same server.

To list the repos defined in the buildkit.conf:

```
buildkit listrepo
```

To build the repositories, specify a particular repository:

```
buildkit buildrepo <kit repo name>
```

or build all the repositories for this kit:

```
buildkit buildrep all
```

The repository would be built in `<Kit directory location>/build/kit_repodir/` subdirectory. If the Kit Package Repository is already fully built, then this command performs no operation. If the Kit Package Repository is not fully built, the command builds it as follows:

1. Create the Kit Package Repository directory `<Kit directory location>/build/kit_repodir/`. 
2. Build the Component Meta-Packages associated with this Kit Package Repository. Create the packages under the Kit Package Repository directory
3. Build the Kit Packages associated with this Kit Package Repository. Create the packages under the Kit Package Repository directory
4. Build the repository meta-data for the Kit Package Repository. The repository meta-data is based on the OS native package format. For example, for RHEL, we build the YUM repository meta-data with the createrepo command.

**Build Tar File**

After the Kit package repositories are built, run the `buildtar` subcommand in the Kit directory to build the final kit tarfile.

```
buildkit buildtar
```

The tar file will be built in the kit directory location. A complete kit will be named:

```
ex: kitname-1.0.0-x86_64.tar.bz2
```

A partial kit will have “NEED_PRODUCT_PKGS” string in its name:

```
ex: kitname-1.0.0-x86_64.NEED_PRODUCT_PKGS.tar.bz2
```

**Using Partial Kits with newer Software Versions**

If the product packages are for a newer version or release than what specified in the partial kit tar file name, user may still be able to build a complete kit with the packages, assuming that the partial kit is compatible with those packages.

Note: Basically, the latest partial kit available online will work until there is a newer version available.
To build a complete kit with the new software, user can provide the new version and/or release of the software on the buildkit command line.

```
buildkit addpkgs <kitname.NEED_PRODUCT_PKGS.tar.bz2> --pkgdir <product package directories> \
--kitversion <new version> --kitrelease <new release>
```

For example, if the partial kit was created for a product version of 1.3.0.2 but wish to complete a new kit for product version 1.3.0.4 then can add “-k 1.3.0.4” to the buildkit command line.

### Completing a partial kit

Follow these steps to complete the kit build process for a partial kit.

1. copy the partial kit to a working directory
2. copy the product software packages to a convenient location or locations
3. cd to the working directory
4. Build the complete kit tarfile

```
buildkit addpkgs <kit.NEED_PRODUCT_PKGS.tar.bz2> --pkgdir <product package directories>
```

The complete kit tar file will be created in the working directory

### Using Kits

#### Adding a Kit to xCAT

#### Adding a complete Kit to xCAT

A complete kit must be added to the xCAT management node and defined in the xCAT database before its kit components can be added to xCAT osimages or used to update diskful cluster nodes.

To add a kit run the following command:

```
addkit <complete kit tarfile>
```

The addkit command will expand the kit tarfile. The default location will be <site.installdir>/kits directory but an alternate location may be specified. (Where site.installdir is the value of the installdir attribute in the xCAT site definition.)

It will also add the kit to the xCAT database by creating xCAT object definitions for the kit as well as any kitrepo or kitcomponent definitions included in the kit.

Kits are added to the kit table in the xCAT database keyed by a combination of kit basename and version values. Therefore, user can add multiple kit definitions for the same product. For example, user could have one definition for release 1.2.0.0 and one for 1.3.0.0 of the product. This means that user will be able to add different versions of the kit components to different osimage definitions if desired.

#### Listing a kit

The xCAT kit object definition may be listed using the xCAT lsdef command.
The contents of the kit may be listed by using the lskit command.

```
lskit <kit name>
```

## Adding Kit Components

### Adding Kit Components to an OS Image Definition

In order to add a kitcomponent to an OS image definition, the kitcomponent must support the OS distro, version, architecture, serverrole for that OS image.

Some kitcomponents have dependencies on other kitcomponents. For example, a kit component may have a dependency on the product kit license component. Any kit components they may be required must also be defined in the xCAT database.

Note: A kit component in the latest product kit may have a dependency on a license kit component from an earlier kit version.

To check if a kitcomponent is valid for an existing OS image definition run the chkkitcomp command:

```
chkkitcomp -i <osimage> <kitcompname>
```

If the kit component is compatible then add the kitcomponent to the OS image definition using the addkitcomp command.

```
addkitcomp -a -i <osimage> <kitcompname>
```

When a kitcomponent is added to an OS image definition, the addkitcomp command will update several attributes in the xCAT database.

### Listing kit components

The xCAT kitcomponent object definition may be listed using the xCAT lsdef command.

```
lsdef -t kitcomponent -l <kit component name>
```

The contents of the kit component may be listed by using the lskitcomponent command.

```
lskitcomp <kit component name>
```

### Adding Multiple Versions of the Same Kit Component to an OS Image Definition

xCAT allows to have multiple versions/releases of a product software kit available in the cluster. Typically, different OS image definitions corresponding to the different versions/releases of a product software stack. However, in some instances, may need multiple versions/releases of the same product available within a single OS image. This is only feasible if the software product supports the install of multiple versions or releases of its product within an OS image.

Currently, it is not possible to install multiple versions of a product into an OS image using xCAT commands. xCAT uses yum on RedHat and zypper on SLES to install product rpms. These package managers do not provide an interface to install different versions of the same package, and will always force an upgrade of the package. We are investigating different ways to accomplish this function for future xCAT releases.
Some software products have designed their packaging to leave previous versions of the software installed in an OS image even when the product is upgraded. This is done by using different package names for each version/release, so that the package manager does not see the new version as an upgrade, but rather as a new package install. In this case, it is possible to use xCAT to install multiple versions of the product into the same image.

By default, when a newer version/release of a kitcomponent is added to an existing OS image definition, addkitcomp will automatically upgrade the kitcomponent by removing the old version first and then adding the new one. However, user can force both versions of the kitcomponent to be included in the OS image definition by specifying the full kitcomponent name and using the addkitcomp -n (--noupgrade) flag with two separate command calls. For example, to include both myprod_compute.1-0.1 and myprod_compute.1-0.2 into an the compute osimage, you would run in this order:

```
addkitcomp -i compute myprod_compute.1-0.1
addkitcomp -i compute -n myprod_compute.1-0.2
```

When building a diskless image for the first time, or when deploying a diskful node, xCAT will first install version 1-0.1 of myprod, and then in a separate yum or zypper call, xCAT will install version 1-0.2. The second install will either upgrade the product rpms or install the new versions of the rpms depending on how the product named the packages.

### Modifying Kit Deployment Parameters for an OS Image Definition

Some product software kits include kit deployment parameter files to set environment variables when the product packages are being installed in order to control some aspects of the install process. To determine if a kit includes such a file:

```
lsdef -t kit -o <kitname> -i kitdeployparams
```

If the kit does contain a deployment parameter file, the contents of the file will be included in the OS image definition when user add one of the kitcomponents to the image. User can view or change these values if need to change the install processing that they control for the software product:

```
addkitcomp -i <image> <kitcomponent name>
vi /install/osimages/<image>/kits/KIT_DEPLOY_PARAMS.otherpkgs.pkglist
```

NOTE: Be sure to know how changing any kit deployment parameters will impact the install of the product into the OS image. Many parameters include settings for automatic license acceptance and other controls to ensure proper unattended installs into a diskless image or remote installs into a diskful node. Changing these values will cause problems with genimage, updatenode, and other xCAT deployment commands.

### Completing the software update

#### updating diskless images

For diskless OS images, run the genimage command to update the image with the new software. Example:

```
genimage <osimage>
```

Once the osimage has been updated you may follow the normal xCAT procedures for packing and deploying the image to your diskless nodes.
installing diskful nodes

For new stateful deployments, the kitcomponent will be installed during the otherpkgs processing. Follow the xCAT procedures for your hardware type. Generally, it will be something like:

```
chdef <nodelist> provmethod=<osimage>
nodeset <nodelist> osimage
rpower <nodelist> reset
```

updating diskful nodes

For existing active nodes, use the updatenode command to update the OS on those nodes. The updatenode command will use the osimage assigned to the node to determine the software to be updated. Once the osimage has been updated, make sure the correct image is assigned to the node and then run updatenode:

```
chdef <nodelist> provmethod=<osimage>
updatenode <nodelist>
```

Removing Kit

Removing Kit Components from an OS Image Definition

To remove a kit component from an OS image definition, first list the existing kitcomponents to get the name to remove:

```
lsdef -t osimage -o <image> -i kitcomponents
```

Then, use that name to remove it from the image definition:

```
rmkitcomp -i <image> <kitcomponent name>
```

Or, if know the basename of the kitcomponent, simply:

```
rmkitcomp -i <image> <kitcompent basename>
```

Note that this ONLY removes the kitcomponent from the image definition in the xCAT database, and it will NOT remove any product packages from the actual OS image. To set up for an uninstall of the kitcomponent from the diskless image or the stateful node, specify the uninstall option:

```
rmkitcomp -u -i <image> <kitcomponent>
```

The next time when run genimage for the diskless image, or updatenode to the fulldisk nodes, the software product will be un-installed.

Removing a Kit from the xCAT Management Node

To remove a kit from xCAT, first make sure that no OS images are assigned any of the kitcomponents. To do this, run the following database queries:

```
lsdef -t kitcomponent -w 'kitname==<kitname>'
```

For each kitcomponent returned:
lsdef -t osimage -i kitcomponents -c | grep <kitcomponent>

If no osimages have been assigned any of the kitcomponents from this kit, can safely remove the kit by running:

rmmkit <kitname>

### 1.4.12 Mixed Cluster

The concept of mixed cluster support in xCAT is managing cluster which contain different hardware architectures. Most commonly, this is usually a cluster consisting of both Power and x86 systems.

#### Support Matrix

<table>
<thead>
<tr>
<th></th>
<th>RHEL ppc64 CN</th>
<th>SLES ppc64 CN</th>
<th>RHEL x86_64 CN</th>
<th>SLES x86_64 CN</th>
<th>Ubuntu x86_64 CN</th>
<th>RHEL ppc64le CN</th>
<th>SLES ppc64le CN</th>
<th>Ubuntu ppc64el CN</th>
<th>AIX CN</th>
</tr>
</thead>
<tbody>
<tr>
<td>RHEL ppc64 MN/SN</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>no</td>
</tr>
<tr>
<td>SLES ppc64 MN/SN</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>no</td>
</tr>
<tr>
<td>RHEL x86_64 MN/SN</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>no</td>
</tr>
<tr>
<td>SLES x86_64 MN/SN</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>no</td>
</tr>
<tr>
<td>Ubuntu x86_64 MN/SN</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>no</td>
</tr>
<tr>
<td>RHEL ppc64le MN/SN</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>no</td>
</tr>
<tr>
<td>SLES ppc64le MN/SN</td>
<td>no</td>
<td>no</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>no</td>
</tr>
<tr>
<td>Ubuntu ppc64el MN/SN</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>yes</td>
<td>no</td>
</tr>
<tr>
<td>AIX MN/SN</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>no</td>
<td>yes</td>
</tr>
</tbody>
</table>

Notes:

1. To manage x86_64 servers from ppc64/ppc64le nodes, will need to install the packages `xnba-undl elilo-xcat` and `syslinux-xcat` manually on the management node. And manually run command “cp /opt/xcat/share/xcat/nethot/syslinux/pxelinux.0 /tftpboot/”

2. If the compute nodes are DFM managed systems, will need xCAT 2.9.1 or higher versions and the ppc64le DFM and ppc64le hardware server on the management node.

3. If the compute nodes are DFM managed systems, will need xCAT 2.10 or higher versions and the ppc64le DFM and ppc64le hardware server on the management node.

4. If the compute nodes are DFM managed systems, will need the ppc64le DFM and ppc64le hardware server on the management node.

5. Does not support DFM managed compute nodes, hardware control does not work.
The support statements refers to hardware control, operating system (os) provisioning, and general purpose system management where we do not see any obvious problems with the indicated combination.

For diskless mixed cluster support, the initial diskless image must be created on a node running the target operating system version and architecture. see Building Stateless/Diskless Images for more details.

Power Management Node

Provision x86 Diskful

In order to provision x86_64 ipmi-based machines from Power-based xCAT management node, there are a few required xCAT dependency RPMs that must be installed:

- elilo-xcat
- xnba-undi
- syslinux-xcat

Install these RPMs using the following command:

```
yum install elilo-xcat xnba-undi syslinux-xcat
```

On the Power-based management node, obtain an x86_64 operating system ISO and add it into the xCAT osimage table by using the `copycds` command:

```
copycds /tmp/RHEL-6.6-20140926.0-Server-x86_64-dvd1.iso
```

Create a node definition for the x86_64 compute node, here is a sample:

```
lsdef -z c910f04x42
# <xCAT data object stanza file>

c910f04x42:
  objtype=node
  arch=x86_64
  bmc=10.4.42.254
  bmcpassword=PASSWORD
  bmusername=USERID
  cons=ipmi
  groups=all
  initrd=xcat/osimage/rhels6.6-x86_64-install-compute/initrd.img
  installnic=mac
  kcmdline=quiet repo=http://!myipfn!:80/install/rhels6.6/x86_64 ks=http://!myipfn!:80/install/autoinst/c910f04x42 ksdevice=34:40:b5:b9:c0:18 cmdline console=tt0, console=ttyS0,115200n8r
  kernel=xcat/osimage/rhels6.6-x86_64-install-compute/vmlinuz
  mac=34:40:b5:b9:c0:18
  mgt=ipmi
  netboot=xnba
  nodetype=osi
  os=rhel6s.6
  profile=compute
  provmethod=rhel6s.6-x86_64-install-compute
  serialflow=hard
  serialport=0
  serialspeed=115200
```
Verify the genesis packages:

- **[RHEL/SLES]**: `rpm -qa | grep -i genesis`
- **[Ubuntu]**: `dpkg -l | grep -i genesis`

If missing, install the packages `xCAT-genesis-base` and `xCAT-genesis-scripts` from `xcat-deps` repository and run `mknb <arch>` to create the genesis network boot root image.

Provision the node using the following commands:

```bash
# The following prepares the boot files in /install and /tftpboot
nodeset c910f04x42 osimage=rhels6.6-x86_64-install-compute

# Tells the BIOS to network boot on the next power on
rsetboot c910f04x42 net

# Reboots the node
rpower c910f04x42 boot
```

### Provision x86 Diskless

### Troubleshooting

**Error:** The following Error message comes out when running nodeset:

```
Error: Unable to find pxelinux.0 at /opt/xcat/share/xcat/netboot/syslinux/pxelinux.0
```

**Resolution:**

The syslinux network booting files are missing. Install the syslinux-xcat package provided in the xcat-deps repository:

```
yum -y install syslinux-xcat
```

### x86 Management Node

### Building Stateless/Diskless Images

A **stateless**, or **diskless**, provisioned nodes is one where the operating system image is deployed and loaded into memory. The Operating System (OS) does not store its files directly onto persistent storage (i.e. hard disk drive, shared drive, usb, etc) and so subsequent rebooting of the machine results in loss of any state changes that happened while the machine was running.

To deploy stateless compute nodes, you must first create a stateless image. The “netboot” osimages created from `copycds` in the `osimage` table are sample osimage definitions that can be used for deploying stateless nodes.

In a homogeneous cluster, the management node is the same hardware architecture and running the same Operating System (OS) as the compute nodes, so `genimage` can directly be executed from the management node.

The issues arises in a heterogeneous cluster, where the management node is running a different level operating system or hardware architecture as the compute nodes in which to deploy the image. The `genimage` command that builds stateless images depends on various utilities provided by the base operating system and needs to be run on a node with the same hardware architecture and major Operating System release as the nodes that will be booted from the image.
Same Operating System, Different Architecture

The following describes creating stateless images of the same Operating System, but different hardware architecture. The example will use the following nodes:

<table>
<thead>
<tr>
<th>Management Node: xcatmn (ppc64)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Target node: n01 (x86_64)</td>
</tr>
</tbody>
</table>

1. On xCAT management node, xcatmn, select the osimage you want to create from the list of osimage definitions. To list out the osimage definitions:

   ```
   lsdef -t osimage
   ```

2. **optional:** Create a copy of the osimage definition that you want to modify.

   To take the sample `rhels6.3-x86_64-netboot-compute` osimage definition and create a copy called `mycomputeimage`, run the following command:

   ```
   lsdef -t osimage -z rhels6.3-x86_64-netboot-compute | sed 's/\^[^ ]*:/'→mycomputeimage:/' | mkdef -z
   ```

3. To obtain the `genimage` command to execute on n01, execute the `genimage` command with the `--dryrun` option:

   ```
   genimage --dryrun mycomputeimage
   ```

   The result output will look similar to the following:

   ```
   Generating image:
   cd /opt/xcat/share/xcat/netboot/rh;
   ```

4. Go to the target node, n01 and run the following:

   (a) mount the `/install` directory from the xCAT Management Node:

   ```
   mkdir /install
   mount -o soft xcatmn:/install /install
   ```

   (b) Copy the executable files from the `/opt/xcat/share/xcat/netboot` from the xCAT Management node to the target node:

   ```
   mkdir -p /opt/xcat/share/xcat/
   scp -r xcatmn:/opt/xcat/share/xcat/netboot /opt/xcat/share/xcat/
   ```

5. Execute the `genimage` command obtained from the `--dryrun`:

   ```
   cd /opt/xcat/share/xcat/netboot/rh;
   ```
If problems creating the stateless image, provide a local directory for \textit{--rootimgdir}:

\texttt{mkdir -p /tmp/compute}

\textit{Rerun} \texttt{genimage}, replacing \texttt{--rootimgdir /tmp/compute}:

\texttt{cd /opt/xcat/share/xcat/netboot/rh; .\ genimage -a x86\_64 -o rhels6.3 -p compute --permission 755 --srcdir /install/ rhels6.3/x86\_64 --pkglist \ 
/install/post/otherpkgs/rhels6.3/x86\_64 --postinstall \ 
/tmp/compute /tmp/compute mycomputeimage}

Then copy the contents from \texttt{/tmp/compute} to \texttt{/install/netboot/rhels6.3/compute}

6. Now return to the management node and execute \texttt{packimage} on the osimage and continue provisioning the node

\texttt{packimage mycomputeimage}

\section*{1.4.13 Networking}

\textbf{Ethernet Switches}

\textbf{Configure Ethernet Switches}

It is recommended that spanning tree be set in the switches to portfast or edge-port for faster boot performance. See the relevant switch documentation as to how to configure this item.

It is recommended that lldp protocol in the switches is enabled to collect the switch and port information for compute node during discovery process.

\textbf{Note}: this step is necessary if you want to use xCAT’s automatic switch-based discovery described in \textit{switch-based discovery} for IPMI-controlled rack-mounted servers (Includes OpenPOWER server and x86\_64 server) and Flex chassis.

If you have a small cluster and prefer to use the sequential discover method described in \textit{Sequential-based discovery} or manually enter the MACs for the hardware, you can skip this section. Although you may want to still set up your switches for management so you can use xCAT tools to manage them, as described in \textit{Switch Management}.

xCAT will use the ethernet switches during node discovery to find out which switch port a particular MAC address is communicating over. This allows xCAT to match a random booting node with the proper node name in the database. To set up a switch, give it an IP address on its management port and enable basic SNMP functionality. (Typically, the SNMP agent in the switches is disabled by default.) The easiest method is to configure the switches to give the SNMP version 1 community string called “public” read access. This will allow xCAT to communicate to the switches without further customization. (xCAT will get the list of switches from the switch table.) If you want to use SNMP version 3 (e.g. for better security), see the example below. With SNMP V3 you also have to set the user/password and AuthProto (default is md5) in the switches table.

If for some reason you can’t configure SNMP on your switches, you can use sequential discovery or the more manual method of entering the nodes’ MACs into the database.

\textbf{SNMP V3 Configuration example}:
xCAT supports many switch types, such as BNT and Cisco. Here is an example of configuring SNMP V3 on the Cisco switch 3750/3650:

1. First, user should switch to the configure mode by the following commands:

```
[root@x346n01 ~]# telnet xcat3750
Trying 192.168.0.234...
Connected to xcat3750.
Escape character is '^]'.
User Access Verification
Password:
xcat3750-1>enable
Password:
xcat3750-1#configure terminal
Enter configuration commands, one per line. End with CNTL/Z.
xcat3750-1(config)#
```

2. Configure the **snmp-server** on the switch:

```
Switch(config)# access-list 10 permit 192.168.0.20  # 192.168.0.20 is the IP of MN
Switch(config)# snmp-server group xcatadmin v3 auth write v1default
Switch(config)# snmp-server community public RO 10
Switch(config)# snmp-server community private RW 10
Switch(config)# snmp-server enable traps
```

3. Configure the **snmp** user id (assuming a user/pw of xcat/passw0rd):

```
Switch(config)# snmp-server user xcat xcatadmin v3 auth SHA passw0rd access 10
```

4. Check the **snmp** communication to the switch:

```
On the MN: make sure the snmp rpms have been installed. If not, install them:
yum install net-snmp net-snmp-utils
Run the following command to check that the snmp communication has been setup successfully (assuming the IP of the switch is 192.168.0.234):

```
   snmpwalk -v 3 -u xcat -a SHA -A passw0rd -X cluster -l authnoPriv 192.168.0.234 .1.3.6.1.2.1.2.1.2.1.2
```
```
```
```

Later on in this document, it will explain how to make sure the switch and switches tables are setup correctly.

**Switch Management**

When managing Ethernet switches, the admin often logs into the switches one by one using SSH or Telnet and runs the switch commands. However, it becomes time consuming when there are a lot of switches in a cluster. In a very large cluster, the switches are often identical and the configurations are identical. It helps to configure and monitor them in parallel from a single command.

For managing Mellanox IB switches and Qlogic IB switches, see [Mellanox IB switches and Qlogic IB switches](#).

xCAT will not do a lot of switch management functions. Instead, it will configure the switch so that the admin can run remote command such as `xdsh` for it. Thus, the admin can use the `xdsh` to run proprietary switch commands remotely from the xCAT mn to enable VLAN, bonding, SNMP and others.
Running Remote Commands in Parallel

You can use xdsh to run parallel commands on Ethernet switches. The following shows how to configure xCAT to run xdsh on the switches:

**Note:** For this to work, configure the switch to allow `ssh` or `telnet`. The procedure varies from switch to switch, consult the reference guides for your switch to find out how to do this.

Add the switch in xCAT DB. Refer to the “Discovering Switches” section if you want xCAT to discover and define the switches for you.

```
mkdef bntc125 groups=switch mgt=switch ip=10.4.25.1 nodetype=switch switchtype=BNT
```

Set the ssh or telnet username and password.

```
chdef bntc125 username=admin 
  password=password 
  protocol=ssh

or

chdef bntc125 username=admin 
  password=password 
  protocol=telnet
```

If there are a lot of switches and they have the same user name and password for `ssh` or `telnet` connection, you can put them in the passwd table keyed by **switch**. You can use the comments attribute to describe it is for ssh to telnet. The blank means ssh.

```
#key,username,password,cryptmethod,authdomain,comments,disable
"system","root","cluster",,,, 
"switch","admin","password",,,
```

Run xdsh command

```
xsh bntc125 --devicetype EthSwitch::BNT "enable;configure terminal;vlan 3;end;show vlan"
```

**Note:** You can run multiple switch commands, each command is comma separated.

Also note that --devicetype is used here. xCAT supports the following switch types out of the box:

- BNT
- Cisco
- Juniper
- Mellanox (for IB and Ethernet switches)

If you have different type of switches, you can either use the general flag “--devicetype EthSwitch” or add your own switch types. (See the following section).

Here is what result will look like:

```
bntc125: start SSH session...
bntc125: RS G8000&gt;enable
```

(continues on next page)
You can run `xdsh` against more than one switches at a time just like running `xdsh` against nodes.

Use `xcoll` to summarize the result. For example:
```
xsh bntc1,bntc2 --devicetype EthSwitch::BNT "show access-control" |xcoll
```

The output looks like this:
```
start Telnet session...
terminal-length 0
show access-control
Current access control configuration:
  No ACLs configured.
  No IPv6 ACL configured.
  No ACL group configured.
  No VMAP configured.
```

Add New Switch Types

For any new switch types that’s not supported by xCAT yet, you can use the general `--device EthSwitch` flag with `xdsh` command.
```
xsh <switch_names> --devicetype EthSwitch "cmd1;cmd2..."
```

The only problem is that the page break is not handled well when the command output is long. To remove the page break, you can add a switch command that sets the terminal length to 0 before all other commands.
```
xsh <switch_names> --devicetype EthSwitch "command-to-set-term-length-to-0;cmd1;cmd2..."
```

where `command-to-set-term-length-to-0` is the command to set the terminal length to 0, so that the output does not have page breaks.

You can add this command to the configuration file to avoid specifying it for each `xdsh` by creating a new switch type. Here is what you do:
```
cp /opt/xcat/share/xcat/devicetype/EthSwitch/Cisco/config 
/var/opt/xcat/EthSwitch/XXX/config
```
where XXX is the name of the new switch type. You can give it any name. Then add the command for set terminal length to 0 to the “pre-command” line. The new configuration file will look like this:

```bash
# cat /var/opt/xcat/EthSwitch/XXX/config
[main]
ssh-setup-command=
[xdsh]
pre-command=command-to-set-term-length-to-0;
pst-command=NULL
```

For BNT switches, the `command-to-set-term-length-to-0` is `terminal-length 0`.

Make sure to add a semi-colon at the end of the “pre-command” line.

Then you can run the xdsh like this:

```bash
xdsh <switch_names> --devicetype EthSwitch::XXX "cmd1;cmd2;...
```

### Open Network Install Environment Switches

The Open Network Install Environment, or “ONIE”, is an open source project defining an install environment for bare metal switches. This environment allows choice for the end users when selecting a network operating system to install onto these bare metal switches.

### Cumulus Linux OS

This documentation will focus on installing the Cumulus Network Operating System (https://www.cumulusnetworks.com/) onto a “white-box” Edgecore switch but the same concepts should apply to other ONIE enabled switches using other network operating systems.

### Preparation

Prepare the Cumulus Linux files on the xCAT Management Node.

1. Obtain a valid Cumulus Linux License and download the Cumulus Linux OS installer.
2. Copy the above files into a location under the xCAT /install directory.

```bash
# Create a directory to hold the cumulus linux files
mkdir -p /install/custom/sw_os/cumulus/

# copy the license file
cp licensefile.txt /install/custom/sw_os/cumulus/

# copy the installer
cp cumulus-linux-3.1.0-bcm-armel.bin /install/custom/sw_os/cumulus/
```

1 Open Network Install Environment: Created by Cumulus Networks, Inc. in 2012, the Open Network Install Environment (ONIE) Project is a small operating system, pre-installed as firmware on bare metal network switches, that provides an environment for automated operating system provisioning.
Cumulus osimage

xCAT can able to create a cumulus osimage definition via `copycds` command. `copycds` will copy cumulus installer to a destination directory, and create several relevant osimage definitions. `cumulus<release>-<arch>` is the default osimage name.

```bash
#run copycds command
# copycds cumulus-linux-3.5.2-bcm-armel.bin
```

The `pkgdir` attribute will contain full path of cumulus installer as `/install/cumulus<release>/<arch>/<installer>`.

```bash
# lsdef -t osimage cumulus3.5.2-armel
Object name: cumulus3.5.2-armel
   description=Cumulus Linux
   imagetype=linux
   osarch=armel
   osname=cumulus
   osvers=cumulus3.5.2
   pkgdir=/install/cumulus3.5.2/armel/cumulus-linux-3.5.2-bcm-armel.bin
   provmethod=install
```

Installation and Configuration

Cumulus OS Installtion

**Important:** The following assumes that the physical switches have power and have obtained a DHCP IP address from the xCAT open range.

xCAT provides support for detecting and installing the Cumulus Linux OS into ONIE enabled switches by utilizing DHCP to detect “`onie_vendor`” from the `vendor-class-identifier` string and then send it the Cumulus Linux OS installer.

1. Create a pre-defined switch definition for the ONIE switch using the `onieswitch` template.

   The mac address of the switch management port is required for xCAT to configure the DHCP information and send over the OS to install on the switch.

   **Small Clusters**

   If you know the mac address of the management port on the switch, create the pre-defined switch definition providing the mac address.

   ```bash
   mkdef frame01sw1 --template onieswitch arch=armv71 \
   ip=192.168.1.1 mac="aa:bb:cc:dd:ee:ff"
   ```

   **Large Clusters**

   xCAT’s `switchdiscover` command can be used to discover the mac address and fill in the predefined switch definitions based on the switch/switchport mapping.

   (a) Define all the switch objects providing the switch/switchport mapping:

   ```bash
   mkdef frame01sw1 --template onieswitch arch=armv71 \
   ip=192.168.1.1 switch=coresw1 switchport=1
   mkdef frame02sw1 --template onieswitch arch=armv71 \
   (continues on next page)```
(continued from previous page)

```bash
ip=192.168.2.1 switch=coreswl switchport=2
mkdef frame03sw1 --template onieswitch arch=armv71 \
  ip=192.168.3.1 switch=coreswl switchport=3
mkdef frame04sw1 --template onieswitch arch=armv71 \
  ip=192.168.4.1 switch=coreswl switchport=4
```

(b) Leverage `switchdiscover` over the DHCP range to automatically detect the MAC address and write them into the predefined switches above.

```bash
switchdiscover --range <IP range>
```

2. Run the `nodeset` command to set the `provmethod` attribute of the target switch(es) to the Cumulus Linux install image and prepare the DHCP/BOOTP lease information for the switch:

```bash
# nodeset frame01sw1 osimage=cumulus3.5.2-arme1
# lsdef frame01sw1
Object name: frame01sw1
arch=armv7l
groups=switch,edge_switch
ip=172.21.208.03
mac=8C:EA:1B:E8:78:C0
mgt=switch
netboot=onie
nodetype=switch
postbootscripts=otherpkgs
postscripts=syslog,remoteshell
provmethod=cumulus3.5.2-arme1
switch=mid08
switchport=3
switchtype=onie
usercomment=Edgecore Networks Switch
```

`nodeset` will executing the `makedhcp` command and kick off the network install of the ONIE enabled switch. If there is no OS pre-loaded on the switch, the switch continues to send a DHCPREQUEST out to the network. After `makedhcp` is run against the switch, an entry is added to the leases file that will respond to the request with the Cumulus Linux installer file.

```bash
host frame1sw1 {
  dynamic;
  hardware ethernet 8c:ea:1b:12:ca:40;
  fixed-address 192.168.3.200;
  supersede server.ddns-hostname = "frame1sw1";
  supersede host-name = "frame1sw1";
  if substring (option vendor-class-identifier, 0, 11) = "onie_vendor" {
    supersede www-server = "http://192.168.27.1/install/cumulus3.5.2/arme1/\n→cumulus-linux-3.5.2-bcm-arme1.bin";
  }
}
```

*Typical installation time is around 1 hour*
Configure xCAT Remote Commands

After Cumulus Linux OS is installed, a default user `cumulus` will be created with default password: `CumulusLinux!`.

To ease in the management of the switch, xCAT provides a script to help configure password-less ssh as the `root` user. This script sends over the xCAT ssh keys so that the xCAT remote commands (xdsh, xdcp, etc) can be run against the ONIE switches.

Execute the following to sync the xCAT keys to the switch:

```
rspconfig frame01sw1 sshcfg
```

Validate the ssh keys are correctly configured by running a `xdsh` command:

```
xdsh frame01sw1 uptime
```

Activate the License

After Cumulus Linux OS is installed onto the ONIE switch, only the serial port console and the management ethernet port is enabled. To activate the rest of the switch ports, the license file needs to be installed onto the switch.

1. Copy the license file to the switch:

   ```
   xdcps frame01sw1 /install/custom/sw_os/cumulus/licensefile.txt /root/
   ```

2. Activate the license:

   ```
   xds frame01sw1 "/usr/cumulus/bin/cl-license -i /root/licensefile.txt"
   ```

3. Verify that the license file is successfully installed:

   ```
   xdsh frame01sw1 /usr/cumulus/bin/cl-license
   ```

   Output should be similar to: `frame01sw1 xxx@xx.com|xxxxxxxxxxxxxxxxxx`

4. Reboot the switch to apply the license file:

   ```
   xdsh frame01sw1 reboot
   ```

Enable SNMP

In order to utilize `xcatprobe switch_macmap`, `snmp` needs to be enabled. To enable, run the `enablesnmp` postscript on the switch:

```
updatenode frame01sw1 -P enablesnmp
```

To configuring SNMPv3 after enable snmp, set user, authentication and/or encryption for the switches:

```
chdef frame01sw1 snmpauth=sha snmppassword=xcatpassw0rd snmpprivacy=DES
   --snmpusername=xcatadmin
```

then execute the `configonie` command to add the snmp user for the switch:
To verify the SNMPv3 configuration, run `xcatprobe switch_macmap` command, will show following results:

```
xcatprobe switch_macmap frame01sw1 -V
<INFO>frame01sw1: Attempting to refresh switch information...
<INFO>frame01sw1: Generate SNMP session with parameter:
  'UseNumeric' => '1'
  'SecName' => 'xcatadmin'
  'AuthPass' => 'xcatpassw0rd'
  'Version' => '3'
  'PrivProto' => 'DES'
  'DestHost' => '172.21.253.102'
  'SecLevel' => 'authPriv'
  'AuthProto' => 'SHA'
  'PrivPass' => 'xcatpassw0rd'
<INFO>frame01sw1: SNMP Session query OID: ".1.3.6.1.2.1.31.1.1.1.1"
<INFO>frame01sw1: SNMP Session get data for OID: ".1.3.6.1.2.1.31.1.1.1.1":
  '1' => 'lo'
  '2' => 'eth0'
  '3' => 'swp1'
  '4' => 'swp2'
  '5' => 'swp3'
```

Switch Management

Sync File support

xCAT supports synchronize of configuration files for cumulus switches.

1. Use instructions in doc: The synclist file to set up syncfile.
2. Add synclist to cumulus osimage.

```
# chdef -t osimage cumulus3.5.2-armel synclists=/tmp/synclists
1 object definitions have been created or modified.
```
3. run `updatenode` to sync the files to cumulus switches.

```
# updatenode mid08tor03 -F
File synchronization has completed for nodes: "mid08tor03"
```

Switch Port and VLAN Configuration

xCAT places the front-panel port configuration in `/etc/network/interfaces.d/xCAT.intf`

The configinterface postscript can be used to pull switch interface configuration from the xCAT Management Node (MN) to the switch. Place the switch specific configuration files in the following directory on the MN: `/install/custom/sw_os/cumulus/interface/`

xCAT will look for files in the above directory in the following order:

1. file name that matches the switch hostname
2. file name that matches the switch group name
3. file name that has the word 'default'

Note: If the postscript cannot find a configuration file on the MN, it will set all ports on the switch to be part of VLAN 1.

Execute the script using the following command:
```
updatenode <switch> -P configinterface
```

Re-install OS

There may be occasions where a re-install of the Cumulus Linux OS is required. The following commands can be used to invoke the install:

Important: This assumes that the Cumulus Linux files are on the xCAT MN in the correct place.

- Using xCAT, `xdsh` can invoke the reinstall of the OS:

```
# to clear out all the previous configuration, use the -k option (optional)
xsh <switch> "/usr/cumulus/bin/onie-select -k

# to invoke the reinstall of the OS
xdsh <switch> "/usr/cumulus/bin/onie-select -i -f;reboot"
```

- Manually, log into the switch and run the following commands:

```
sudo onie-select -i
sudo reboot
```

Cumulus OS Upgrade

The Cumulus OS on the ONIE switches can be upgraded using one of the following methods:

Full Install

Perform a full install from the `.bin` file of the new Cumulus Linux OS version, using ONIE.

Important: Make sure you back up all your data and configuration files as the binary install will erase all previous configuration.

1. Place the binary image under `/install` on the xCAT MN node.
   
   In this example, IP=172.21.253.37 is the IP on the Management Node.

```
mkdir -p /install/onie/
cp cumulus-linux-3.4.1.bin /install/onie/
```

2. Invoke the upgrade on the switches using `xdsh`:
xdsh switch1 "/usr/cumulus/bin/onie-install -a -f -i http://172.21.253.37/install/onie/cumulus-linux-3.4.1.bin && reboot"

**Attention:** The full upgrade process may run 30 minutes or longer.

3. After upgrading, the license should be installed, see *Activate the License* for details.
4. Restore your data and configuration files on the switch.

**Update Changed Packages**

This is the preferred method for upgrading the switch OS for incremental OS updates.

**Create Local Mirror**

If the switches do not have access to the public Internet, you can create a local mirror of the Cumulus Linux repo.

1. Create a local mirror on the Management Node:

   ```bash
   mkdir -p /install/mirror/cumulus
   cd /install/mirror/cumulus
   wget -m --no-parent http://repo3.cumulusnetworks.com/repo/
   ```

2. Create a `sources.list` file to point to the local repo on the Management node. In this example, IP=172.21.253.37 is the IP on the Management Node.

   ```bash
   # cat /tmp/sources.list
   → repo CumulusLinux-3 cumulus upstream
   → repo CumulusLinux-3 cumulus upstream
   → repo CumulusLinux-3-security-updates cumulus upstream
   → repo CumulusLinux-3-security-updates cumulus upstream
   → repo CumulusLinux-3-updates cumulus upstream
   → repo CumulusLinux-3-updates cumulus upstream
   
   xdcpcp switch1 /tmp/sources.list /etc/apt/sources.list
   ```

**Invoke the Update**

1. Use xCAT `xdsh` to invoke the update:
# A reboot may be needed after the upgrade

```
xdsh switch1 'apt-get update && apt-get upgrade && reboot'
```

2. Check in `/etc/os-release` file to verify that the OS has been upgraded.

## Setup ONIE switches with ZTP in large cluster

Zero Touch Provisioning (ZTP) is a feature shipped in many network devices to enable them to be quickly deployed in large-scale environments. In Cumulus OS on ONIE switches with ZTP enabled, the URL of an user provided script can be specified in the DHCP response for the DHCP request triggered by one of the following events:

- Booting the switch
- Plugging a cable into or unplugging it from the eth0 port
- Disconnecting then reconnecting the switch’s power cord.

The script will be then downloaded and executed on the network device.

Leveraging the ZTP mechanism, xCAT provides the capability to setup ONIE switches from white-box without touching anything, including Cumulus OS installation, discovery and configuration. Please follow the steps below to setup ONIE switches in the cluster:

1. Ensure that xCAT is configured with a DHCP open range to detect when new switches request DHCP IPs
   
   (1). Make sure the network in which the management interface of the ONIE switches are connected has been defined in `networks` table

   ```
   # tabdump networks
   #netname,net,mask,mgtifname,gateway,dhcpserver,tftpserver,nameservers,ntpservers,
   →logserver,dynamicrange,staticrange,staticrangeincrement,nodehostname,
   →ddnsdomain,vlanid,domain,mtu,comments,disable
   "172.21.0-0-255.255.0.0","172.21.0.0","255.255.0.0","enP3p3s0d1","<xcatmaster>",
   
   (2). Prepare the DHCP configuration for ONIE switches setup
   
   Add the management node’s NIC facing the ONIE switches’ management interface to the `site`. `dhcpinterfaces`

   ```
   chdef -t site -p dhcpinterfaces=enP3p3s0d1
   
   Add dynamic range for the temporary IP addresses used in the OS provision and discovery of ONIE switches

   ```
   chdef -t network 172.21.0-0-255.255.0.0 dynamicrange="172.21.253.100-172.21.253.200"
   
   Update DHCP configuration file

   ```
   makedhcp -n
   ```
   
   2. Predefine ONIE switches according to the network plan

   ```
   mkdef mid05tor10 --template onieswitch ip=172.21.205.10 switch=mgmtaw01
   →switchport=10
   ```
ip is the IP address of the management interface of the ONIE switch

switch is the core switch to which the management interface of ONIE switch is connected.

switchport is the port on the core switch to which the management interface of ONIE switch is connected.

3. Add the predefined switches into /etc/hosts

```bash
makehosts mid05tor10
```

4. [If the Cumulus OS have been installed on the ONIE switches, please skip this step] Prepare the Cumulus installation image, /install/onie/onie-installer is the hard-coded path of the Cumulus installation image, or the link to the Cumulus installation image on the management node

```bash
mkdir -p /install/onie/
cp /install/custom/sw_os/cumulus/cumulus-linux-3.1.0-bcm-armel.bin /install/onie/
ln -s /install/onie/cumulus-linux-3.1.0-bcm-armel.bin /install/onie/onie-installer
```

5. Plug the ONIE switches into the cluster according to the network plan and power on them.

   For the white-box ONIE switches, the Cumulus OS will be installed, then the switches will be discovered and configured automatically, the whole process will take about 1 hour.

   For the ONIE switches already with Cumulus OS installed, please make sure the ZTP have been enabled and none of the following manual configuration have been made:

   • Password changes
   • Users and groups changes
   • Packages changes
   • Interfaces changes
   • The presence of an installed license

   Otherwise, please run `ztp -R` on the switches to reset the ZTP state before switch boot up for setup. The whole setup process will take about 1-2 minutes.

6. The switch definition in xCAT will be updated when the switch is configured

```bash
# lsdef mid05tor10
Object name: mid05tor10
  arch=armv7l
groups=switch
  ip=172.21.205.10
mgt=switch
  netboot=onie
  nodetype=switch
postbootscripts=otherpkgs
postscripts=syslog,remoteshell,syncfiles
serial=11S01FT690YA50YD73EACH
status=configured
statustime=06-22-2017 23:14:14
supportedarchs=armv7l
switch=mgmtsw01
switchport=10
switchtype=Edgecore Networks Switch

status=configured indicates that the switch has been discovered and configured.
```
Switch Discover

Discovering Switches

Use switchdiscover command to discover the switches that are attached to the neighboring subnets on xCAT management node.

```
switchdiscover [noderange|--range ip_ranges] [-s scan_methods] [-r|x|-z][-w]
```

where the scan_methods can be nmap, snmp”, or **lldp . The default is nmap. (nmap comes from most os distribution.)

To discover switches over the IP range 10.4.25.0/24 and 192.168.0.0/24, use the following command:

```
# switchdiscover --range 10.4.25.0/24,192.168.0.0/24
Discovering switches using nmap...

<table>
<thead>
<tr>
<th>ip</th>
<th>name</th>
<th>vendor</th>
<th>mac</th>
</tr>
</thead>
<tbody>
<tr>
<td>192.168.0.131</td>
<td>switch_192_168_0_131</td>
<td>Mellanox Technologie</td>
<td>00:02:C9:AA:00:53</td>
</tr>
<tr>
<td>10.4.25.1</td>
<td>switch_10_4_25_1</td>
<td>Juniper networks</td>
<td>2C:6B:F5:00:11:22</td>
</tr>
</tbody>
</table>
```

If -w flag is specified, the command will write the discovered switches into xCAT databases. If the command above was executed with -w the following switch objects would be created:

```
# lsdef switch_name
Object name: switch_name
groups=switch
ip=switch_ip
mgt=switch
nodetype=switch
switchtype=switch_vendor
```

The Ip address is stored in the hosts table. You can run the following command to add the IP addresses in the /etc/hosts

```
makehosts
```

The discovery process works with the following four kind of switches:

```
Mellanox (IB and Ethernet switches)
Cisco
BNT
Juniper
```

The switchdiscover command can display the output in xml format, stanza forma and normal list format. See the man pages for this command for details.

Switch-based Switch Discovery

Currently, xCAT supports switch based hardware discovery, the servers are identified through the switches and switch ports they are directly connected to. A similar method can be used to discover switches using switch-based discovery within the user defined dynamic IP range.

Pre-requisite

In order to do switch-based switch discovery, the admin
1. Needs to manually setup and configure core-switch. SNMP v3 needs to be enabled in order for xCAT access to it. **username** and **userpassword** attributes are for the remote login. It can be for ssh or telnet. If it is for telnet, set protocol to “telnet”. If the **username** is blank, the **username** and **password** will be retrieved from the passwd table with “switch” as the key. SNMP attributes will used for SNMPv3 communication. **nodetype** has to be set to “switch” to differentiate between switch-based node discovery or switch-based switch discovery. Refer to switches table attributes. Example of core-switch definition:

```
lsdef switch-10-5-23-1
  Object name: switch-10-5-23-1
  groups=switch
  ip=10.5.23.1
  mac=ab:cd:ef:gh:dc
  mgt=switch
  nodetype=switch
  password=admin
  postbootscripts=otherpkgs
  postscripts=syslog,remoteshell,syncfiles
  protocol=telnet
  snmpauth=sha
  snmppassword=userpassword
  snmpusername=snmpadmin
  snmpversion=3
  switchtype=BNT
  usercomment=IBM
  username=root
```

2. Predefine all top-rack switches which connect to core-switch. The attribute **ip** is static IP address for the switch. When `switchdiscover --setup` command is issued, this IP address will replace dhcp IP address on the switch. **nodetype=switch** needs to be set to differentiate between switch-based node discovery or switch-based switch discovery during discovery process. the attribute **switch** is hostname of core-switch and **switchport** is the port number in the core-switch that top-rack switch is connected to.

```
lsdef switch-192-168-5-22
  objtype=node
  groups=switch
  ip=192.168.5.22
  mgt=switch
  nodetype=switch
  switch=switch-10-5-23-1
  switchport=45
  switchtype=BNT
```

3. Add switches to `/etc/hosts` for hostname lookup and `xdsh` command.

```
makehosts switch-192-168-5-23
makehosts switch-192-168-5-22
```

4. Setup Dynamic IP range in network table for discovered switches to use.

```
# tabdump networks
#netname,net,mask,mgtifname,gateway,dhcpserver,tftpserver,nameservers,ntpservers,
→logservers,dynamicrange,staticrange,staticrangeincrement,nodehostname,
→ddnsdomain,vlanid,domain,mtu,comments,disable
"192.168.0.0-255.255.0.0","192.168.0.0","255.255.0.0","enP4p1s0f2","<xcatmaster>",
→,"192.168.3.29","","192.168.5.150-192.168.5.170","",""
```

dhcp should be restarted after setting up dynamic IP range.
Discover Switches

xCAT supports `switchdiscover` command to discover the switches that are attached to the subnets on xCAT management node. Refer to Discovering Switches for more info.

For the switch-based switch discovery, we add `-setup` flag:

```
switchdiscover [noderange|--range ip_ranges][--setup]
```

if `-setup` flag is specified, the command will perform following steps:

1. Use snmp or nmap scan methods to find all switches in the dynamic IP ranges specified by `-range`, the available switches will be stored in switch hash table with hostname, switchtype, vendor info and mac address.

2. Based on mac address for each switch defined in the hash table, call `find_mac` subroutine. The `find_mac` subroutine will go through the switch and switch ports and find matched mac address.
   - If discovered switch didn’t find any predefined switch matches, it will log the message `NO predefined switch matched`.
   - If discovered switch matched with one of pre-defined switch, it will update the predefined switch with

     ```
     otherinterface=x.x.x.x (discovered ip)
     state=matched
     switchtype=type of switch
     usercomment=vendor information
     ```

3. After switches are matched, the command will call config files to set up static IP address, hostname and enable the snmpv3. Currently, BNT and Mellanox switches are supported. The two config files are located in the `/opt/xcat/share/xcat/scripts/config.BNT` and `/opt/xcat/share/xcat/scripts/config.Mellanox`. The log message the switch type is not support for config is displayed if switchtype is something other than BNT or Mellanox.

4. After discovery process, the predefined node attribute in the xCATdb will be updated.

```bash
lsdef switch-192-168-5-22
  groups=switch
  ip=192.168.5.22
  mac=a8:97:dc:02:92:00
  mgt=switch
  nodetype=switch
  password=admin
  postbootscripts=otherpkgs
  postscripts=syslog,remoteshell,syncfiles
  protocol=telnet
  snmpauth=sha
  snmppassword=xcatadminpassw0rd@snmp
  snmpusername=xcatadmin
  snmpversion=3
  status=hostname_configured
  statustime=08-31-2016 15:35:49
  supportedarchs=ppc64
  switch=switch-10-5-23-1
  switchport=45
  switchtype=BNT
  usercomment=IBM Networking Operating System RackSwitch G8052
  username=root
```
Configure switches

The `switchdiscover` command with `--setup` flag will set up switches with static IP address, change the hostname from predefined switches and enable snmpv3 configuration. For other switches configuration, refer to Configure Ethernet Switches and IB Switch Configuration.

These two config files are located in the `/opt/xcat/share/xcat/scripts` directory. The `switchdiscover` process will call the config files with `--all` option. User can call these scripts to setup one of options manually.

1. **configBNT** is for configure BNT switches.

```
./configBNT --help
Usage:
    configBNT [-?|-h|--help]
    configBNT [--switches switchnames] [--all]
    configBNT [--switches switchnames] [--ip]
    configBNT [--switches switchnames] [--name ]
    configBNT [--switches switchnames] [--snmp] [--user snmp_user] [--password snmp_password] [--group snmp_group]
    configBNT [--switches switchnames] [--port port] [--vlan vlan]
```

2. **configMellanox** is for configuring Mellanox switch. The script will configure ntp service on the switch with xCAT MN and will use rsponfig command to
   - enable ssh
   - enable snmp function on the switch
   - enable the snmp trap
   - set logging destination to xCAT MN

```
./configMellanox --help
Usage:
    configMellanox [-?|-h|--help]
    configMellanox [--switches switchnames] [--all]
    configMellanox [--switches switchnames] [--ip]
    configMellanox [--switches switchnames] [--name]
    configMellanox [--switches switchnames] [--config]
```

Switch Status

During the switch-based switch discovery process, there are four states displayed. User may only see `switch_configured` status on node definition if discovery process successfully finished.

**Matched** — Discovered switch is matched to predefined switch, `otherinterfaces` attribute is updated to dhcp IP address, and mac address, `switch type` and `usercomment` also updated with vendor information for the predefined switch.

**ip_configured** — switch is set up to static IP address based on predefined switch IP address. If failure to set up IP address, the status will stay as **Matched**.

**hostname_configured** — switch host name is changed based on predefined switch hostname. If failure to change hostname on the switch, the status will stay as **ip_configured**.

**switch_configured** — snmpv3 is setup for the switches. This should be final status after running `switchdiscover --setup` command. If failure to setup snmpv3, the status will stay as **hostname_configured**.
InfiniBand (Mellanox)

xCAT has the ability to help with Mellanox InfiniBand (IB) adapter installation and network configuration as part of the node provisioning process.

Mellanox OFED Installation Script

Mellanox provides a tested and packaged version of the OpenFabrics Enterprise Distribution (OFED) driver, named Mellanox OFED (MLNX_OFED). To assist with the installation of the MLNX_OFED driver, xCAT provides a sample postscript: mlnxofed_ib_install.v2.

Preparation

Download MLNX_OFED ISO

xCAT only supports installation using the ISO format.
Download the Mellanox OFED ISO file here (MLNX_OFED).

Prepare Installation Script

The mlnxofed_ib_install.v2 is a sample script intended to assist with the installation of the Mellanox OFED drivers. The following support matrix documents the limited number of scenarios that have been verified: support matrix.

1. Copy the mlnxofed_ib_install.v2 to /install/postscripts, renaming to mlnxofed_ib_install.

```bash
    cp /opt/xcat/share/xcat/ib/scripts/Mellanox/mlnxofed_ib_install.v2 \
        /install/postscripts/mlnxofed_ib_install
    # ensure the script has execute permission
    chmod +x /install/postscripts/mlnxofed_ib_install
```

2. Familiarize the options available for the xCAT mlnxofed_ib_install script.
### Option

<table>
<thead>
<tr>
<th>Option</th>
<th>Required</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>-p</code></td>
<td>Yes</td>
<td>The full path to the MLNX_OFED ISO image</td>
</tr>
<tr>
<td><code>-m</code></td>
<td>No</td>
<td>Use this option to pass arguments to the Mellanox OFED installation script <code>mlnxofedinstall</code>. The special keyword <code>-end-</code> must be added to the end of the string to mark the completion of the option list. If nothing is specified, xCAT passes the the following <code>--without-32bit --without-fw-update --force</code></td>
</tr>
<tr>
<td><code>-i</code></td>
<td>For diskless</td>
<td>The image root path of the diskless image</td>
</tr>
<tr>
<td><code>-n</code></td>
<td>For diskless</td>
<td>nodeset status, value is <code>genimage</code></td>
</tr>
</tbody>
</table>

A very basic usage of the install script:

```
/install/postscripts/mlnxofed_ib_install -p /install/<path-to>/MLNX_OFED_LINUX.iso
```

To pass the `--add-kernel-support` option to `mlnxofedinstall`, use the following command:

```
/install/postscripts/mlnxofed_ib_install -p /install/<path-to>/MLNX_OFED_LINUX.iso \
-m --without-32bit --without-fw-update --add-kernel-support --force -end-
```

### Configuration

The process to configure the osimage to install the Mellanox OFED Drivers for Diskful and Diskless scenarios are outlined below.
Diskful Installation

1. Prepare dependency packages in the pkglist

In order for the Mellanox installation script to execute successfully, certain dependency packages are required to be installed on the compute node. xCAT provides sample package list files to help resolve these dependencies. The samples are located at /opt/xcat/share/xcat/ib/netboot/<os>/.

To use the /opt/xcat/share/xcat/ib/netboot/rh/ib.rhels7.ppc64le.pkglist, edit your existing pkglist file for the target osimage and add the following at the bottom:

```
#INCLUDE:/opt/xcat/share/xcat/ib/netboot/rh/ib.rhels7.ppc64le.pkglist#
```

2. Configure the mlnxed_ib_install script to install the MNLX_OFED drivers

xCAT has a concept of postscripts that can be used to customize the node after the operating system is installed. Mellanox recommends that the operating system is rebooted after the drivers are installed, so xCAT recommends using the postscripts attribute to avoid the need for a second reboot. To invoke the mlnxed_ib_install as a postscript

```
chdef -t node -o <node_name> \ 
  -p postscripts="mlnxofed_ib_install -p /install/<path-to>/<MLNX_OFED_LINUX.iso> \ 
  → \ 
  -m --add-kernel-support --force -end-"
```

[Kernel mismatch issue] The Mellanox OFED ISO is built against a series of specific kernel version. If the version of the linux kernel does not match any of the Mellanox offered pre-built kernel modules, you can pass the --add-kernel-support --force argument to the Mellanox installation script to build the kernel modules based on the version you are using.

```
chdef -t node -o <node_name> \ 
  -p postscripts="mlnxofed_ib_install -p /install/<path-to>/<MLNX_OFED_LINUX.iso> \ 
  → \ 
  -m --add-kernel-support --force -end-"
```

3. Provision the node

```
reinstall <node> osimage=
```

4. Verification

- Check the status of openibd service
  
  sysVinit:
  
  ```
  service openibd status
  ```

  systemd:
  
  ```
  systemctl status openibd.service
  ```

- Verify that the Mellanox IB drivers are located at: /lib/modules/<kernel_version>/extra/
- Use the ibv_devinfo command to obtain information about the InfiniBand adapter.

Diskless Installation

1. Prepare dependency packages in the pkglist
In order for the Mellanox installation script to execute successfully, certain dependency packages are required to be installed on the compute node. xCAT provides sample package list files to help resolve these dependencies. The samples are located at /opt/xcat/share/xcat/ib/netboot/<os>/.

To use the /opt/xcat/share/xcat/ib/netboot/rh/ib.rhels7.ppc64le.pkglist, edit your existing pkglist file for the target osimage and add the following at the bottom:

```
#INCLUDE:/opt/xcat/share/xcat/ib/netboot/rh/ib.rhels7.ppc64le.pkglist#
```

2. Configure the mlnxofed_ib_install script to install the MNLX_OFED drivers

Edit the postinstall script on the osimage to invoke the mlnxofed_ib_install install script.

For example, take rhels7.2-ppc64le-netboot-compute:

(a) Find the path to the postinstall script:

```
# lsdef -t osimage -o rhels7.2-ppc64le-netboot-compute -i postinstall
Object name: rhels7.2-ppc64le-netboot-compute
    postinstall=/opt/xcat/share/xcat/netboot/rh/compute.rhels7.ppc64le.postinstall
```

(b) Edit the /opt/xcat/share/xcat/netboot/rh/compute.rhels7.ppc64le.postinstall and add the following:

```
/install/postscripts/mlnxofed_ib_install \ 
- p /install/<path-to >/MLNX_OFED_LINUX.iso - i $1 - n genimage
```

Note: The $1 is a argument that is passed to the the postinstall script at runtime.

---

**Tip: Kernel Mismatch**

The Mellanox OFED ISO is built against a series of specific kernel version. If the version of the linux kernel being used does not match any of the pre-built kernels, pass --add-kernel-support --without-32bit --without-fw-update --force to the Mellanox installation script to build the kernel modules based on the kernel you are using. Example:

```
/install/postscripts/mlnxofed_ib_install \ 
- p /install/<path-to >/MLNX_OFED_LINUX.iso - m --add-kernel-support --without- \ 
-32bit --without-fw-update --force -end- \ 
- i $1 - n genimage
```

3. Generate the diskless image

Use the genimage command to generate the diskless image from the osimage definition

```
genimage <osimage>
```

Use the packimage command to pack the diskless image for deployment

```
packimage <osimage>
```

4. Provision the node

```
rminstall <node> osimage=rhels7.2-ppc64le-netboot-compute
```
5. Verification

- Check the status of `openibd` service
  
  `sysVinit`:
  ```bash
  service openibd status
  ```

  `systemd`:
  ```bash
  systemctl status openibd.service
  ```

- Verify that the Mellanox IB drivers are located at: `/lib/modules/<kernel_version>/extra/`
- Use the `ibv_devinfo` command to obtain information about the InfiniBand adapter.

### MLNX_OFED Support Matrix

The following ISO images and attributes have been verified by the xCAT Team.

**RedHat Enterprise Linux**

<table>
<thead>
<tr>
<th>RHEL 7.2 (ppc64le)</th>
<th>MLNX_OFED_LINUX-3.2-2.0.0.0-rhel7.2-ppc64le.iso</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>OFED ISO</strong></td>
<td>MLNX_OFED_LINUX-3.2-2.0.0.0-rhel7.2-ppc64le.iso</td>
</tr>
<tr>
<td><strong>Attribute Supported</strong></td>
<td>–without-32bit –without-fw-update –add-kernel-support –force</td>
</tr>
<tr>
<td><strong>IB.pkglist</strong></td>
<td>ib.rhels7.ppc64le.pkglist</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>RHEL 7.1 (ppc64)</th>
<th>MLNX_OFED_LINUX-3.2-2.0.0.0-rhel7.1-ppc64.iso</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>OFED ISO</strong></td>
<td>MLNX_OFED_LINUX-3.2-2.0.0.0-rhel7.1-ppc64.iso</td>
</tr>
<tr>
<td><strong>Attribute Supported</strong></td>
<td>–without-32bit –without-fw-update –add-kernel-support –force</td>
</tr>
<tr>
<td><strong>IB.pkglist</strong></td>
<td>ib.rhels7.ppc64.pkglist</td>
</tr>
</tbody>
</table>

**Suse Linux Enterprise Server**

<table>
<thead>
<tr>
<th>SLES 12 (ppc64le)</th>
<th>MLNX_OFED_LINUX-3.2-2.0.0.0-sles12sp1-ppc64le.iso</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>OFED ISO</strong></td>
<td>MLNX_OFED_LINUX-3.2-2.0.0.0-sles12sp1-ppc64le.iso</td>
</tr>
<tr>
<td><strong>Attribute Supported</strong></td>
<td>–without-32bit –without-fw-update –force</td>
</tr>
<tr>
<td><strong>IB.pkglist</strong></td>
<td>ib.sles12.ppc64le.pkglist</td>
</tr>
</tbody>
</table>

**Ubuntu**

<table>
<thead>
<tr>
<th>Ubuntu14.04.3 (ppc64le)</th>
<th>MLNX_OFED_LINUX-3.2-2.0.0.0-ubuntu14.04-ppc64le.iso</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>OFED ISO</strong></td>
<td>MLNX_OFED_LINUX-3.2-2.0.0.0-ubuntu14.04-ppc64le.iso</td>
</tr>
<tr>
<td><strong>Attribute Supported</strong></td>
<td>–without-32bit –without-fw-update –add-kernel-support –force</td>
</tr>
<tr>
<td><strong>IB.pkglist</strong></td>
<td>ib.ubuntu14.ppc64le.pkglist</td>
</tr>
</tbody>
</table>

### Known Issues
Preventing upgrade of the Mellanox Drivers

On RedHat operating systems, after the Mellanox drivers are installed, you may have a requirement to update your operating system to a later version. Some operating systems may ship InfiniBand drivers that are higher version than the Mellanox drivers you have installed and therefor may update the existing drivers.

To prevent this from happening, add the following in the `/etc/yum.conf`

```
exclude=dapl* libib* ibacm infiniband* libmlx* librdma* opensm* ibutils*
```

Development packages in SLES

If using the `--add-kernel-support` attribute on SLES operating systems, you may find problems with installing some dependency packages which are not shipped by the SLES server DVDs. The development rpms are provided by the SDK DVDs. Refer to *Add Additional Software Packages* to configure the SDK repositories.

IB Network Configuration

xCAT provides a script `configib` to help configure the Infiniband adapters on the compute nodes.

The Infiniband adapter is considered an additional interface for xCAT. The process for configuring Infiniband adapters complies with the process of *Configure Additional Network Interfaces*.

Below are an simple example to configure Mellanox IB in Ubuntu 14.04.1 on Power8 LE

If your target Mellanox IB adapter has 2 ports, and you plan to give port ib0 4 different IPs, 2 are IPV4 (20.0.0.3 and 30.0.0.3) and another 2 are IPV6 (1:2::3 and 2:2::3).

1. Define your networks in networks table

```
chdef -t network -o ib0ipv41 net=20.0.0.0 mask=255.255.255.0 mgtifname=ib0
chdef -t network -o ib0ipv42 net=30.0.0.0 mask=255.255.255.0 mgtifname=ib0
chdef -t network -o ib0ipv61 net=1:2::/64 mask=/64 mgtifname=ib0 gateway=1:2::2
chdef -t network -o ib0ipv62 net=2:2::/64 mask=/64 mgtifname=ib0 gateway=
```

2. Define IPs for ib0

```
chdef <node> nicips.ib0="20.0.0.3|30.0.0.3|1:2::3|2:2::3" \nicnetworks.ib0="ib0ipv41|ib0ipv42|ib0ipv61|ib0ipv62" nictypes.ib0="Infiniband"
```

3. Configure ib0

- To configure during node installation

```
chdef <node> -p postscripts="configibcs --ibaports=2" 
.nodeset <node> osimage=<osimagename> 
rsetboot <node> net 
rpower <node> reset
```

- To configure on a node which has had operating system

```
updatenode <node> -P "configibcs --ibaports=2"
```
IB Switch Configuration

Setup the xCAT Database

The Mellanox Switch is only supported in xCAT Release 2.7 or later.

Add the switch ip address in the `/etc/hosts` file

Define IB switch as a node:

```
chdef -t node -o mswitch groups=all nodetype=switch mgt=switch
```

Add the login user name and password to the switches table:

```
tagch switch=mswitch switches.sshusername=admin switches.sshpassword=admin
```

The switches table will look like this:

```
#switch,...,sshusername,sshpassword,switchtype,....
"mswitch","","","MellanoxIB"
```

If there is only one admin and one password for all the switches then put the entry in the xCAT passwd table for the admin id and password to use to login.

```
tagch key=switch passwd.username=admin passwd.password=admin
```

The passwd table will look like this:

```
#key,username,password,cryptmethod,comments,disable
"switch","admin","admin",
```

Setup ssh connection to the Mellanox Switch

To run commands like xdsh and script to the Mellanox Switch, we need to setup ssh to run without prompting for a password to the Mellanox Switch. To do this, first you must add a configuration file. This configuration file is NOT needed for xCAT 2.8 and later.

```
mkdir -p /var/opt/xcat/IBSwitch/Mellanox
cd /var/opt/xcat/IBSwitch/Mellanox
cp /opt/xcat/share/xcat/devicetype/IBSwitch/Mellanox/config .
```

The file contains the following:

```
[main]
[xdsh]
pre-command=cli
post-command=NULL
```

Then run the following:

```
rspconfig mswitch sshcfg=enable
```
**Warning:** For Mellanox switch in manufacturing defaults, the user may need to log in once and answer **no** to the configuration wizard as `rspconfig` will fail when prompted against the wizard.

### Setup syslog on the Switch

Use the following command to consolidate the syslog to the Management Node or Service Nodes, where `ip` is the address of the MN or SN as known by the switch.

```
rspconfig mswitch logdest=<ip>
```

### Configure xdsh for Mellanox Switch

To run xdsh commands to the Mellanox Switch, you must use the `--devicetype` input flag to xdsh. In addition, for xCAT versions less than 2.8, you must add a configuration file, see Setup ssh connection to the Mellanox Switch section.

For the Mellanox Switch the `--devicetype` is `IBSwitch::Mellanox`. See xdsh man page for details.

Now you can run the switch commands from the mn using xdsh. For example:

```
xdsh mswitch -l admin --devicetype IBSwitch::Mellanox 
'enable;configure terminal;show ssh server host-keys'
```

### Commands Supported for the Mellanox Switch

**Setup the snmp alert destination:**

```
rspconfig <switch> snmpdest=<ip> [remove]
```

where “remove” means to remove this ip from the snmp destination list.

**Enable/disble setting the snmp traps.**

```
rspconfig <switch> alert=enable/disable
```

Define the read only community for snmp version 1 and 2.

```
rspconfig <switch> community=<string>
```

**Enable/disble snmp function on the switch.**

```
rspconfig <switch> snmpcfg=enable/disable
```

Enable/disble ssh-ing to the switch without password.

```
rspconfig <switch> sshcfg=enable/disable
```

Setup the syslog remove receiver for this switch, and also define the minimum level of severity of the logs that are sent. The valid levels are: emerg, alert, crit, err, warning, notice, info, debug, none, remove. “remove” means to remove the given ip from the receiver list.

```
rspconfig <switch> logdest=<ip> [<level>]
```
For doing other tasks on the switch, use xdsh. For example:

```
xdsh mswitch -l admin --devicetype IBSwitch::Mellanox 'show logging'
```

Interactive commands are not supported by xdsh. For interactive commands, use ssh.

### Send SNMP traps to xCAT Management Node

First, get [http://www.mellanox.com/related-docs/prod_ib_switch_systems/MELLANOX-MIB.zip](http://www.mellanox.com/related-docs/prod_ib_switch_systems/MELLANOX-MIB.zip) , unzip it. Copy the mib file MELLANOX-MIB.txt to `/usr/share/snmp/mibs` directory on the mn and sn (if the sn is the snmp trap destination.)

Then,

To configure, run:

```
monadd snmpmon
moncfg snmpmon <mswitch>
```

To start monitoring, run:

```
monstart snmpmon <mswitch>
```

To stop monitoring, run:

```
monstop snmpmon <mswitch>
```

To deconfigure, run:

```
mondecfg snmpmon <mswitch>
```

For more details on monitoring the cluster: TODO Monitoring_an_xCAT_Cluster/#snmp-monitoring

### UFM Configuration

UFM server are just regular Linux boxes with UFM installed. xCAT can help install and configure the UFM servers. The XCAT mn can send remote command to UFM through xdsh. It can also collect SNMP traps and syslogs from the UFM servers.

#### Setup xdsh to UFM and backup

Assume we have two hosts with UFM installed, called host1 and host2. First define the two hosts in the xCAT cluster. Usually the network that the UFM hosts are in a different than the compute nodes, make sure to assign correct servicenode and xcatmaster in the noderes table. And also make sure to assign correct os and arch values in the nodetype table for the UFM hosts. For example:

```
mkdef -t node -o host1,host2 groups=ufm,all os=sles11.1 arch=x86_64 servicenode=10.0.0.1
```

Then exchange the SSH key so that it can run xdsh.

```
xdsh host1,host2 -K
```

Now we can run xdsh on the UFM hosts.
Consolidate syslogs

Run the following command to make the UFM hosts to send the syslogs to the xCAT mn:

```
updatenode ufm -P syslog
```

To test, run the following commands on the UFM hosts and see if the xCAT MN receives the new messages in `/var/log/messages`

```
logger xCAT "This is a test"
```

Send SNMP traps to xCAT Management Node

You need to have the Advanced License for UFM in order to send SNMP traps.

1. Copy the mib file to `/usr/share/snmp/mibs` directory on the mn.

```
scp ufmhost:/opt/ufm/files/conf/vol_ufm3_0.mib /usr/share/snmp/mibs
```

Where ufmhost is the host where UFM is installed.

2. On the UFM host, open the `/opt/ufm/conf/gv.cfg` configuration file. Under the `[Notifications]` line, set

```
snmp_listeners = <IP Address 1>[:<port 1>],[<IP Address 2>[:<port 2>]].
```

The default port is 162. For example:

```
ssh ufmhost
vi /opt/ufm/conf/gv.cfg

....
[Notifications]
snmp_listeners = 10.0.0.1
```

Where 10.0.0.1 is the the ip address of the management node.

3. On the UFM host, restart the ufmd

```
service ufmd restart
```

4. From UFM GUI, click on the “Config” tab; bring up the “Event Management” Policy Table. Then select the SNMP check boxes for the events you are interested in to enable the system to send an SNMP traps for these events. Click “OK”.

5. Make sure snmptrapd is up and running on mn and all monitoring servers.

It should have the ‘-m ALL’ flag.

```
ps -ef |grep snmptrapd
root 31866 1 0 08:44 ? 00:00:00 /usr/sbin/snmptrapd -m ALL
```

If it is not running, then run the following commands:
**Firmware Updates**

**Adapter Firmware Update**


Obtain device id:

```
lspci | grep -i mel
```

Check current installed fw level:

```
mstflint -d 0002:01:00.0 q | grep FW
```

Copy or mount firmware to host:

Burn new firmware on each ibaX:

```
mstflint -d 0002:01:00.0 -i <image location> b
```

**Note:** If this is a PureFlex MezzanineP adapter, you must select the correct image for each ibaX device.

**The difference in the firmware image at the end of the file name:**

- `_0.bin (iba0/iba2)`
- `_1.bin (iba1/iba3)`

Verify download successful:

```
mstflint -d 0002:01:00.0 q
```

Activate the new firmware:

```
reboot the image
```

**Note:** The above 0002:01:00.0 device location is used as an example only. Validate your device location using the `lspci` command.

**Mellanox Switch Firmware Upgrade**

This section provides manual procedure to help update the firmware for Mellanox Infiniband (IB) Switches. You can download IB switch firmware like IB6131 (image-PPC_M460EX-SX_3.2.xxx.img) from the Mellanox website [http://www.mellanox.com/page/firmware_table_IBM](http://www.mellanox.com/page/firmware_table_IBM) and place into your xCAT Management Node or server that can communicate to Flex IB6131 switch module. There are two ways to update the MLNX-OS switch package. This process works regardless if updating an internal PureFlex chassis Infiniband switch (IB6131) or for an external Mellanox switch.
Update via Browser

This method is straightforward if your switches are on the public network or your browser is already capable to tunnel to the private address. If neither is the case then you may prefer to use option two.

After logging into the switch (id=admin, pwd=admin)
Select the “System” tab and then the “MLNX-OS Upgrade” option
Under the “Install New Image”, select the “Install via scp” URL: scp://userid@fwhost/directoryofimage/imagename
Select “Install Image”
The image will then be downloaded to the switch and the installation process will begin.
Once completed, the switch must be rebooted for the new package to be activate

Update via CLI

Login to the IB switch:

```
   ssh admin@<switchipaddr>
   enable (get into correct CLI mode. You can use en)
   configure terminal (get into correct CLI mode. You can use co t)
```

List current images and Remove older images to free up space:

```
   show image
   image delete <ibimage>
   (you can paste in ibimage name from show image for image delete)
```

Get the new IB image using fetch with scp to a server that contains new IB image. An example of IB3161 image would be “image-PPC_M460EX-SX_3.2.0291.img” Admin can use different protocol . This image fetch scp command is about 4 minutes.

```
   image fetch ?
   image fetch scp://userid:password@serveripaddr/<full path ibimage location>
```

Verify that new IB image is loaded, then install the new showIB image on IB switch. The install image process goes through 4 stages Verify image, Uncompress image, Create Filesystems, and Extract Image. This install process takes about 9 minutes.

```
   show image
   image install <newibimage>
   (you can paste in new IB image from "show image" to execute image install)
```

Toggle boot partition to new IB image, verify image install is loaded , and that next boot setting is pointing to new IB image.

```
   image boot next
   show image
```

Save the changes made for new IB image:

```
   configuration write
```

Activate the new IB image (reboot switch):
For more information about Mellanox products, refer to http://www.mellanox.com.

1.4.14 PDUs

Power Distribution Units (PDUs) are devices that distribute power to servers in a frame. They have the capability of monitoring the amount of power that is being used by devices plugged into it and cycle power to individual receptacles. xCAT can support two kinds of PDUs, infrastructure PDU (irpdu) and collaborative PDU (crpdu).

The Infrastructure rack PDUs are switched and monitored 1U PDU products which can connect up to nine C19 devices or up to 12 C13 devices and an additional three C13 peripheral devices to a single dedicated power source. The Collaborative PDU is on the compute rack and has the 6x IEC 320-C13 receptacles that feed the rack switches. These two types of PDU have different design and implementation. xCAT has different code path to maintain PDU commands via pdutype.

Discovering PDUs

xCAT provides pdudiscover command to discover the PDUs that are attached to the neighboring subnets on xCAT management node.

```
pdudiscover [<noderange>|--range ipranges] [-r|-x|-z] [-w] [-V|--verbose] [--setup]
```

xCAT uses snmp scan method to discover PDU. Make sure net-snmp-utils package is installed on xCAT MN in order to use snmpwalk command.

Options:
- `--range` Specify one or more IP ranges. Each can be an ip address (10.1.2.3) or an ip range (10.1.2.0/24). If the range is huge, for example, 192.168.1.1/8, the pdu discover may take a very long time to scan. So the range should be exactly specified. It accepts multiple formats. For example: 192.168.1.1/24, 40-41.1-2.3-4.1-100.
- `--the active` network interfaces (eth0, eth1) are on where this command is issued.
- `-r` Display Raw responses.
- `-x` XML formatted output.
- `-z` Stanza formatted output.
- `-w` Writes output to xCAT database.
- `--setup` Process switch-based pdu discovery and configure the PDUs. For crpdu, `--setup` options will configure passwordless, change ip address from dhcp to static, hostname changes and snmp v3 configuration. For irpdu, it will configure ip address and hostname. It required predefined PDU node definition with switch name and switch port attributes for mapping.

Define PDU Objects

1. Define pdu object
mkdef f5pdu3 groups=pdu ip=50.0.0.8 mgt=pdu nodetype=pdu pdutype=irpdu

2. Define switch attribute for pdu object which will be used for pdudiscover –setup options.
chdef f5pdu3 switch=mid08 switchport=3

3. Add hostname to /etc/hosts:
makehosts f5pdu3

4. Verify the SNMP command responds against the PDU:
   snmpwalk -v1 -cpublic -mALL f5pdu3 system

**Infrastructure PDU**

Users can access Infrastructure PDU via telnet and use the **IBM PDU Configuration Utility** to set up and configure the PDU. xCAT supports PDU commands for power management and monitoring through SNMP.

**PDU Commands**

Administrators will need to know the exact mapping of the outlets to each server in the frame. xCAT cannot validate the physical cable is connected to the correct server.

Add a `pdu` attribute to the compute node definition in the form “PDU_Name:outlet”:

```
# Compute server cn01 has two power supplies
# connected to outlet 6 and 7 on pdu=f5pdu3
# chdef cn01 pdu=f5pdu3:6,f5pdu3:7
```

The following commands are supported against a compute node:

- **Check the pdu status for a compute node:**

  ```
  # rpower cn01 pdustat
  cn01: f5pdu3 outlet 6 is on
  cn01: f5pdu3 outlet 7 is on
  ```

- **Power off the PDU outlets for a compute node:**

  ```
  # rpower cn01 pduoff
  cn01: f5pdu3 outlet 6 is off
  cn01: f5pdu3 outlet 7 is off
  ```

- **Power on the PDU outlets for a compute node:**

  ```
  # rpower cn01 pduon
  cn01: f5pdu3 outlet 6 is on
  cn01: f5pdu3 outlet 7 is on
  ```

- **Power cycling the PDU outlets for a compute node:**

  ```
  # rpower cn01 pduon
  cn01: f5pdu3 outlet 6 is on
  cn01: f5pdu3 outlet 7 is on
  ```
The following commands are supported against a PDU:

- To change hostname of IR PDU:

```
# rspconfig f5pdu3 hosname=f5pdu3
```

- To change ip address of IR PDU:

```
# rsconfig f5pdu3 ip=x.x.x.x netmaks=255.x.x.x
```

- Check the status of the full PDU:

```
# rpower f5pdu3 stat
f5pdu3: outlet 1 is on
f5pdu3: outlet 2 is on
f5pdu3: outlet 3 is on
f5pdu3: outlet 4 is on
f5pdu3: outlet 5 is on
f5pdu3: outlet 6 is off
f5pdu3: outlet 7 is off
f5pdu3: outlet 8 is on
f5pdu3: outlet 9 is on
f5pdu3: outlet 10 is on
f5pdu3: outlet 11 is on
f5pdu3: outlet 12 is on
```

- Power off the full PDU:

```
# rpower f5pdu3 off
f5pdu3: outlet 1 is off
f5pdu3: outlet 2 is off
f5pdu3: outlet 3 is off
f5pdu3: outlet 4 is off
f5pdu3: outlet 5 is off
f5pdu3: outlet 6 is off
f5pdu3: outlet 7 is off
f5pdu3: outlet 8 is off
f5pdu3: outlet 9 is off
f5pdu3: outlet 10 is off
f5pdu3: outlet 11 is off
f5pdu3: outlet 12 is off
```

- Power on the full PDU:

```
# rpower f5pdu3 on
f5pdu3: outlet 1 is on
f5pdu3: outlet 2 is on
f5pdu3: outlet 3 is on
f5pdu3: outlet 4 is on
f5pdu3: outlet 5 is on
f5pdu3: outlet 6 is on
f5pdu3: outlet 7 is on
f5pdu3: outlet 8 is on
```

(continues on next page)
f5pdu3: outlet 9 is on
f5pdu3: outlet 10 is on
f5pdu3: outlet 11 is on
f5pdu3: outlet 12 is on

- Power reset the full PDU:

```bash
# rpower f5pdu3 reset
f5pdu3: outlet 1 is reset
f5pdu3: outlet 2 is reset
f5pdu3: outlet 3 is reset
f5pdu3: outlet 4 is reset
f5pdu3: outlet 5 is reset
f5pdu3: outlet 6 is reset
f5pdu3: outlet 7 is reset
f5pdu3: outlet 8 is reset
f5pdu3: outlet 9 is reset
f5pdu3: outlet 10 is reset
f5pdu3: outlet 11 is reset
f5pdu3: outlet 12 is reset
```

- PDU inventory information:

```bash
# rinv f6pdu16
f6pdu16: PDU Software Version: "OPDP_sIBM_v01.3_2"
f6pdu16: PDU Machine Type: "1U"
f6pdu16: PDU Model Number: "dPDU4230"
f6pdu16: PDU Part Number: "46W1608"
f6pdu16: PDU Name: "IBM PDU"
f6pdu16: PDU Serial Number: "4571S9"
f6pdu16: PDU Description: "description"
```

- PDU and outlet power information:

```bash
# rvitals f6pdu15
f6pdu15: Voltage Warning: 0
f6pdu15: outlet 1 Current: 0 mA
f6pdu15: outlet 1 Max Capacity of the current: 16000 mA
f6pdu15: outlet 1 Current Threshold Warning: 9600 mA
f6pdu15: outlet 1 Current Threshold Critical: 12800 mA
f6pdu15: outlet 1 Last Power Reading: 0 Watts
f6pdu15: outlet 2 Current: 0 mA
f6pdu15: outlet 2 Max Capacity of the current: 16000 mA
f6pdu15: outlet 2 Current Threshold Warning: 9600 mA
f6pdu15: outlet 2 Current Threshold Critical: 12800 mA
f6pdu15: outlet 2 Last Power Reading: 0 Watts
f6pdu15: outlet 3 Current: 1130 mA
f6pdu15: outlet 3 Max Capacity of the current: 16000 mA
f6pdu15: outlet 3 Current Threshold Warning: 9600 mA
f6pdu15: outlet 3 Current Threshold Critical: 12800 mA
f6pdu15: outlet 3 Last Power Reading: 217 Watts
```

Note: For BMC based compute nodes, turning the PDU outlet power on does not automatically power on the compute side. Users will need to issue `rpower <node>` on to power on the compute side after the BMC boots.
Collaborative PDU

Collaborative PDU is also referred as Coral PDU, it controls power for compute Rack. User can access PDU via SSH and can use the PduManager command to configure and manage the PDU product.

Pre-Defined PDU Objects

A pre-defined PDU node object is required before running pdudiscover command.

```bash
mkdef coralpdu groups=pdu mgt=pdu nodetype=pdu (required)
```

all other attributes can be set by chdef command or pdudiscover command.

```bash
--switch required for pdudiscover command to do mapping
--switchport required for pdudiscover command to do mapping
--ip ip address of the pdu.
--mac can be filled in by pdudiscover command
--pdutype crpdu(for coral pdu) or irpdu(for infrastructure PDUs)
```

The following attributes need to be set in order to configure snmp with non-default values.

```bash
--community community string for coral pdu
--snmpversion snmp version number, required if configure snmpv3 for coral pdu
--snmpuser snmpv3 user name, required if configure snmpv3 for coral pdu
--authkey auth passphrase for snmpv3 configuration
--authtype auth protocol (MD5|SHA) for snmpv3 configuration
--privkey priv passphrase for snmpv3 configuration
--privtype priv protocol (AES|DES) for snmpv3 configuration
--seclevel security level (noAuthNoPriv|authNoPriv|authPriv) for snmpv3
```

Make sure to run makehosts after pre-defined PDU.

```bash
makehosts coralpdu
```

Configure PDUs

After pre-defining PDUs, user can use pdudiscover –range ip_range –setup to configure the PDUs, or following commands can be used:

- To configure passwordless of Coral PDU:
  ```bash
  # rspconfig coralpdu sshcfg
  ```

- To change hostname of Coral PDU:
  ```bash
  # rspconfig coralpdu hostname=f5pdu3
  ```

- To change ip address of PDU:
  ```bash
  # rsconfig coralpdu ip=x.x.x.x netmaks=255.x.x.x
  ```

- To configure SNMP community string or snmpv3 of PDU (the attribute needs to pre-defined):
Remote Power Control of PDU

Use the rpower command to remotely power on and off PDU.

- To check power stat of PDU:
  
  ```
  # rpower coralpdu stat
  ```

- To power off the PDU:
  
  ```
  # rpower coralpdu off
  ```

- To power on the PDU:
  
  ```
  # rpower coralpdu on
  ```

Coral PDUs have three relays, the following commands are for individual relay support of PDU:

- To check power stat of relay:
  
  ```
  # rpower coralpdu relay=1 stat
  ```

- To power off the relay:
  
  ```
  # rpower coralpdu relay=2 off
  ```

- To power on the relay:
  
  ```
  # rpower coralpdu relay=3 on
  ```

Show Monitor Data

Use the rvitals command to show realtime monitor data(input voltage, current, power) of PDU.

```
# rvitals coralpdu
```

Show manufacture information

Use the rinv command to show MFR information of PDU

```
# rinv coralpdu
```

1.4.15 Port Usage

The following table lists the ports that must be open between the xCAT management node and the nodes it manages, unless otherwise noted. The xCAT service nodes use the same ports as the management node. A service (or protocol) applies to both AIX and Linux, unless stated otherwise. Service names are typical strings that appear in the /etc/services file, or in firewall/IP filtering logs. Local customization of the /etc/services files, daemon configuration
options, like overriding the default port number, and differences in software source implementations, may yield other service information results.

The category of required or optional is difficult to fill in because depending on what function you are running what might be listed here as optional, may actually be required. The Trusted side is behind the firewall, the Non-trusted side is in front of the firewall.

### xCAT Port Usage Table

<table>
<thead>
<tr>
<th>Service Name</th>
<th>Port number</th>
<th>Protocol</th>
<th>Range</th>
<th>Required or optional</th>
</tr>
</thead>
<tbody>
<tr>
<td>xcatdport</td>
<td>3001</td>
<td>tcp</td>
<td></td>
<td>required</td>
</tr>
<tr>
<td>xcatdport</td>
<td>3001</td>
<td>udp</td>
<td></td>
<td>required</td>
</tr>
<tr>
<td>xcatiport</td>
<td>3002</td>
<td>tcp</td>
<td></td>
<td>required</td>
</tr>
<tr>
<td>xcatiport</td>
<td>3002</td>
<td>udp</td>
<td></td>
<td>required</td>
</tr>
<tr>
<td>xcatlport</td>
<td>3003(default)</td>
<td>tcp</td>
<td></td>
<td>optional</td>
</tr>
<tr>
<td>echo-udp</td>
<td>7</td>
<td>udp</td>
<td></td>
<td>required</td>
</tr>
<tr>
<td>ssh-tcp</td>
<td>22</td>
<td>tcp</td>
<td></td>
<td>required</td>
</tr>
<tr>
<td>ssh-udp</td>
<td>22</td>
<td>udp</td>
<td></td>
<td>required</td>
</tr>
<tr>
<td>rsync</td>
<td>873</td>
<td>tcp</td>
<td></td>
<td>required</td>
</tr>
<tr>
<td>rsync</td>
<td>873</td>
<td>udp</td>
<td></td>
<td>required</td>
</tr>
<tr>
<td>domain-tcp</td>
<td>53</td>
<td>tcp</td>
<td></td>
<td>optional</td>
</tr>
<tr>
<td>domain-udp</td>
<td>53</td>
<td>udp</td>
<td></td>
<td>optional</td>
</tr>
<tr>
<td>bootps</td>
<td>67</td>
<td>udp</td>
<td></td>
<td>required on AIX</td>
</tr>
<tr>
<td>dhcp</td>
<td>67</td>
<td>tcp</td>
<td></td>
<td>required on AIX</td>
</tr>
<tr>
<td>dhcpc</td>
<td>68</td>
<td>tcp</td>
<td></td>
<td>required on AIX</td>
</tr>
<tr>
<td>bootpc</td>
<td>68</td>
<td>udp</td>
<td></td>
<td>required on AIX</td>
</tr>
<tr>
<td>tftp-tcp</td>
<td>69</td>
<td>tcp</td>
<td></td>
<td>required</td>
</tr>
<tr>
<td>tftp-udp</td>
<td>69</td>
<td>udp</td>
<td></td>
<td>required</td>
</tr>
<tr>
<td>www-tcp</td>
<td>80</td>
<td>tcp</td>
<td></td>
<td>required</td>
</tr>
<tr>
<td>www-udp</td>
<td>80</td>
<td>udp</td>
<td></td>
<td>required</td>
</tr>
<tr>
<td>kerberos</td>
<td>88</td>
<td>tcp</td>
<td></td>
<td>not supported/used by xCAT anymore</td>
</tr>
<tr>
<td>kerberos</td>
<td>88</td>
<td>udp</td>
<td></td>
<td>not supported/used by xCAT anymore</td>
</tr>
<tr>
<td>sunrpc-udp</td>
<td>111</td>
<td>udp</td>
<td></td>
<td>required on AIX</td>
</tr>
<tr>
<td>shell</td>
<td>514</td>
<td>tcp</td>
<td>1-1023</td>
<td>optional</td>
</tr>
<tr>
<td>rsyslogd</td>
<td>514</td>
<td>tcp</td>
<td></td>
<td>required on AIX</td>
</tr>
<tr>
<td>rsyslogd</td>
<td>514</td>
<td>udp</td>
<td></td>
<td>required on AIX</td>
</tr>
<tr>
<td>kshell</td>
<td>544</td>
<td>tcp</td>
<td>1-1023</td>
<td>required on AIX</td>
</tr>
<tr>
<td>rmc-tcp</td>
<td>657</td>
<td>tcp</td>
<td>1-1023</td>
<td>required for RMC monitoring</td>
</tr>
<tr>
<td>rmc-udp</td>
<td>657</td>
<td>udp</td>
<td>1-1023</td>
<td>required for RMC monitoring</td>
</tr>
<tr>
<td>conserver</td>
<td>782</td>
<td>tcp</td>
<td></td>
<td>required on the mgmt and service nodes</td>
</tr>
<tr>
<td>nim</td>
<td>1058</td>
<td>tcp</td>
<td>1-1023</td>
<td>required on AIX</td>
</tr>
<tr>
<td>nfstd-tcp</td>
<td>2049</td>
<td>tcp</td>
<td>1-1023</td>
<td>required on AIX</td>
</tr>
<tr>
<td>nfstd-udp</td>
<td>2049</td>
<td>udp</td>
<td>1-1023</td>
<td>required on AIX</td>
</tr>
<tr>
<td>pxe</td>
<td>4011</td>
<td>tcp</td>
<td></td>
<td>required on linux</td>
</tr>
<tr>
<td>rpc-mount</td>
<td>100005</td>
<td>see Note2</td>
<td></td>
<td>required on linux</td>
</tr>
<tr>
<td>mount-tcp</td>
<td>see Note1</td>
<td>tcp</td>
<td></td>
<td>required on x86_64 and p8</td>
</tr>
<tr>
<td>mount-udp</td>
<td>see Note1</td>
<td>udp</td>
<td></td>
<td>required on x86_64 and p8</td>
</tr>
<tr>
<td>awk</td>
<td>300</td>
<td>tcp</td>
<td></td>
<td>optional</td>
</tr>
<tr>
<td>ipmi</td>
<td>623</td>
<td>tcp</td>
<td></td>
<td>required on Flex</td>
</tr>
<tr>
<td>ipmi</td>
<td>623</td>
<td>udp</td>
<td></td>
<td>required on Flex</td>
</tr>
<tr>
<td>snmp</td>
<td>161</td>
<td>tcp</td>
<td></td>
<td>required on Flex</td>
</tr>
</tbody>
</table>

Continued on next page
Table 1 – continued from previous page

<table>
<thead>
<tr>
<th>Service Name</th>
<th>Port number</th>
<th>Protocol</th>
<th>Range</th>
<th>Required or optional</th>
</tr>
</thead>
<tbody>
<tr>
<td>snmp</td>
<td>161</td>
<td>udp</td>
<td></td>
<td>required on Flex</td>
</tr>
<tr>
<td>snmptrap</td>
<td>162</td>
<td>tcp</td>
<td></td>
<td>required for snmp monitoring</td>
</tr>
<tr>
<td>snmptrap</td>
<td>162</td>
<td>udp</td>
<td></td>
<td>required for snmp monitoring</td>
</tr>
</tbody>
</table>

- **xcatdport**
  The port used by the xcatd daemon for client/server communication.

- **xcatiport**
  The port used by xcatd to receive install status updates from nodes.

- **xcatlport**
  The port used by xcatd to record command log, you can customize it by edit site table, if you don’t configure it, 3003 will be used by default.

- **echo-udp**
  Needed by RSCT Topology Services.

- **ssh-udp**
  Needed to use ssh. This service defines the protocol for upd. This is required when installing or running updatenode, xdsh,xdcp,psh,pcp through the firewall.

- **rsync**
  Need to use updatenode or xdcpc to rrsync files to the nodes or service nodes.

- **domain-tcp**
  Used when Domain Name Services (DNS) traffic from the Non-trusted nodes and the firewall node to a DNS server is explicitly handled by the firewall. Some firewall applications can be configured to explicitly handle all DNS traffic. This for tcp DNS traffic.

- **domain-udp**
  Used when Domain Name Services (DNS) traffic from the Non-trusted nodes and the firewall node to a DNS server is explicitly handled by the firewall. Some firewall applications can be configured to explicitly handle all DNS traffic. This for udp DNS traffic.

- **bootps**
  Bootp server port needed when installing an Non-trusted AIX or System p node through the firewall. This service is issued by the client to the Management Node, for an install request. It is not required to install the Non-trusted nodes through the firewall or to apply maintenance. This is the reason why the service is considered optional.

- **dhcp**
  Needed to install Linux nodes through the firewall. This is the port for the dhcp server. This service defines the protocol for tcp.

- **dhcpc**
  Needed to install Linux through the firewall. This is the port for the dhcpc client. This service defines the protocol for tcp.

- **bootspc**
  Bootp client port needed when installing an Non-trusted AIX or System p node through the firewall. This service is issued by the Management Node back to the client, in response to an install request from the client. It is not
required to install the Non-trusted nodes through the firewall or to apply maintenance. This is the reason why the service is considered optional.

- **tftp-tcp**
  Needed to install Linux nodes. This service defines the protocol for tcp.

- **tftp-udp**
  Needed to install Linux nodes. This service defines the protocol for udp.

- **www-tcp**
  Needed to use World Wide Web http. This service defines the protocol for tcp.

- **www-udp**
  Needed to use World Wide Web http. This service defines the protocol for udp.

- **kerberos**
  Kerberos Version 5 KDC. Needed if running Kerberos Version 5 remote command authentication. This service defines the protocol for tcp.

- **kerberos**
  Kerberos Version 5 KDC. Needed if running Kerberos Version 5 remote command authentication. This service defines the protocol for udp.

- **sunrpc-udp**
  The portmapper service. Needed when installing a Non-trusted node through the firewall. Specifically required mount request that takes place during node install.

- **shell**
  Used when rsh/rcp is enabled for Standard (std) authentication protocol. Needed for xdsh operations when using rsh for remote commands.

- **rsyslogd**
  Used for system log monitoring. This is for tcp protocol.

- **rsyslogd**
  Used for system log monitoring. This is for udp protocol.

- **kshell**
  Used rsh/rcp is enabled for Kerberos authentication. Not currently supported in xCAT. Network Installation Management client traffic generated by an Non-trusted node during node boot/shutdown. Required if using NIM. AIX only.

- **rmc-tcp**
  Resource Monitoring and Control (RMC) used for hardware monitoring, key exchange. This is for tcp protocol.

- **rmc-udp**
  Resource Monitoring and Control (RMC) used for hardware monitoring, key exchange. This is for udp protocol.

- **conserver**
  Required on the xCAT management node and service nodes. This service defines the protocol for tcp.

- **nfsd-tcp**
Needed to use the AIX mount command. This service defines the protocol for tcp. Required when installing an Non-trusted node through the firewall. Needed when an installp is issued on an Non-trusted node and the resource exists on the Trusted side.

- **nfsd-udp**
  Needed to use the AIX mount command. This service defines the protocol for udp. Required when installing an Non-trusted node through the firewall.

- **pxe**
  Needed to install System x nodes through the firewall. This is the port for the PXE boot server. This service defines the protocol for tcp.

- **rpc-mount**
  Remote Procedure Call (RPM) used in conjunction with NFS mount request. See note 2. ssh-tcp Needed to use ssh. This service defines the protocol for tcp. This is required when installing or running updatenode through the firewall.

- **mount-tcp**
  Needed to use the AIX mount command. This service defines the protocol for tcp. Required when installing an Non-trusted node through the firewall. Needed when installp is issued on an Non-trusted node and the resource exists on the Trusted side. Needed to run updatenode command. See note 1.

- **mount-udp**
  Needed to use the AIX mount command. This service defines the protocol for udp. Needed when installp is issued on an Non-trusted node and the resource exists on the Trusted side. Needed to run updatenode command. See note 1.

- **awk**
  For awk communication during node discovery.

- **impi**
  For ipmi traffic.

- **snmp**
  For SNMP communication to blade chassis.

- **snmptrap**
  For SNMP communication to blade chassis.

**Note 1 - AIX mount**

On AIX, the mountd port range is usually determined at the time of the mount request. Part of the communication flow within a mount command is to query the remote mountd server and find out what ports it is using. The mountd ports are selected dynamically each time the mountd server is initialized. Therefore, the port numbers will vary from one boot to another, or when mountd is stopped and restarted.

Unfortunately, this causes a problem when used through a firewall, as no rule can be defined to handle traffic with a variable primary port. To create a service for mountd (server) traffic that has a fixed port, and one that can be trapped by a rule, you will need to update the /etc/services file on the host that is the target of the mount with new mountd entries for TCP and UDP, where the port numbers are known to be unused (free). The mountd TCP and UDP ports must be different. Any free port number is valid. The mountd must be stopped and started to pick up the new port values.

For example, issuing a mount request on Non-trusted node X, whose target is the Management Server, that is,
mount ms2112:/images /images

would require that the /etc/services file on ms2112 be updated with something similar to the following:

mountd 33333/tcp mountd 33334/udp

For mountd to detect its new port values you must stop and start rpc.mountd. The stopping and starting of mountd takes place on the same host where the /etc/services file mountd updates were made. In the above example, ms2112’s mountd is stopped and started. You can verify that mountd is using the new port definitions by issuing the rpcinfo command.

This procedure shows how to change ports used by mountd:

lssrc -s rpc.mountd

Produces output similar to:

Subsystem Group PID Status rpc.mountd nfs 12404 active

Then

rpcinfo -p ms2112 | grep mount

Produces output similar to:

100005 1 udp 37395 mountd 100005 2 udp 37395 mountd 100005 3 udp 37395 mountd 100005
...
1 tcp 34095 mountd 100005 2 tcp 34095 mountd 100005 3 tcp 34095 mountd

Then

stopsrc -s rpc.mount

Produces output similar to:

0513-044 The rpc.mountd Subsystem was requested to stop.

Update /etc/services with new mountd entries.

Note: Make a backup copy of /etc/services before making changes.

grep mountd /etc/services

Produces output similar to:

mountd 33333/tcp mountd 33334/udp

Then

startsrc -s rpc.mountd

Produces output similar to:

0513-059 The rpc.mountd Subsystem has been started. Subsystem PID is 19536.

Then

rpcinfo -p ms2112 | grep mount
Produces output similar to:

```
100005 1 udp 33334 mountd 100005 2 udp 33334 mountd 100005 3 udp 33334 mountd 100005
→<1 tcp 33333 mountd 100005 2 tcp 33333 mountd 100005 3 tcp 33333 mountd
```

**Note 2**

The rpc-mount service differs from the other service definitions in the following way. There is no associated protocol, because by definition it is UDP based. There is no source port.

### 1.4.16 xCAT probe

To help identify some of the common issues with xCAT, a new tool suite is now available **xCAT probe**.

You can use `xcatprobe -l` to list all valid subcommands, output will be as below

```
# xcatprobe -l
osdeploy  Probe operating system provision process. Supports two modes
→'Realtime monitor' and 'Replay history'.
xcatmn  After xcat installation, use this command to check if xcat has been installed correctly and is ready for use. Before using this command, install 'tftp', 'nslookup' and 'wget' commands.
switch-macmap  To retrieve MAC address mapping for the specified switch, or all the switches defined in 'switches' table in xCAT db.
......
```

**xCATmn**

**xCATmn** can be used to check if xcat has been installed correctly and is ready for use.

**Note:** For several check items(e.g. tftp service, dns service, http service), ‘tftp’, ‘nslookup’ and ‘wget’ are need. If not installed, a warning message will be displayed.

Command is as below

```
xcatprobe xcatmn -i <install_nic> [-V]
```

- `-i`: [Required] Specify the network interface name of provision network on management node.
- `-V`: Output more information for debug.

For example, run command on Management Node

```
xcatprobe xcatmn -i eth0
```

Output will be similar to:

```
# xcatprobe xcatmn -i eth0
[MN]: Sub process 'xcatd: SSL listener' is running → [ OK ]
[MN]: Sub process 'xcatd: DB Access' is running → [ OK ]
[MN]: Sub process 'xcatd: UDP listener' is running → [ OK ]
```

(continues on next page)
[MN]: Sub process 'xcatd: install monitor' is running
→ [ OK ]
[MN]: Sub process 'xcatd: Discovery worker' is running
→ [ OK ]
[MN]: Sub process 'xcatd: Command log writer' is running
→ [ OK ]
[MN]: xcatd is listening on port 3001
→ [ OK ]
[MN]: xcatd is listening on port 3002
→ [ OK ]
[MN]: 'lsxcatd -a' works
→ [ OK ]
[MN]: The value of 'master' in 'site' table is an IP address
→ [ OK ]
[MN]: NIC enp0s1 exists on current server
→ [ OK ]
[MN]: Get IP address of NIC eth0
→ [ OK ]
[MN]: The IP *./*./*. of eth0 equals the value of 'master' in 'site' table
→ [ OK ]
[MN]: IP *./*./*. of NIC eth0 is a static IP on current server
→ [ OK ]
[MN]: *./*./*. belongs to one of networks defined in 'networks' table
→ [ OK ]
[MN]: There is domain definition in 'site' table
→ [ OK ]
[MN]: There is a configuration in 'passwd' table for 'system' for node provisioning
→ [ OK ]
[MN]: There is /install directory on current server
→ [ OK ]
[MN]: There is /tftpboot directory on current server
→ [ OK ]
[MN]: The free space of '/' is less than 12 G
→ [ OK ]
[MN]: SELinux is disabled on current server
→ [ OK ]
[MN]: Firewall is closed on current server
→ [ OK ]
[MN]: HTTP service is ready on *./*./*. *
→ [ OK ]
[MN]: TFTP service is ready on *./*./*. *
→ [ OK ]
[MN]: DNS server is ready on *./*./*. *
→ [ OK ]
[MN]: The size of /var/lib/dhcpd/dhcpd.leases is less than 100M
→ [ OK ]
[MN]: DHCP service is ready on *./*./*. *
→ [ OK ]

```
======================do summary=====================  

[MN]: Check on MN PASS.
→ [ OK ]
```

[MN] means that the verification is performed on the Management Node. Overall status of PASS or FAILED will be displayed after all items are verified.

Service Nodes are checked automatically for hierarchical clusters.

For Service Nodes, the output will contain [SN:nodename] to distinguish different Service Nodes.
detect_dhcp

detect_dhcp can be used to detect the dhcp server in a network for a specific mac address.

image

osdeploy

osdeploy operating system provision process. Supports two modes - ‘Realtime monitor’ and ‘Replay history’.

Realtime monitor: This is a default. This tool with monitor provision state of the node. Trigger ‘Realtime monitor’ before rebooting target node to do provisioning.

Replay history: Used after provisioning is finished to probe the previously completed provisioning.

Note: Currently, hierarchical structure is not supported.

Usage

```
xcatprobe osdeploy -h
xcatprobe osdeploy -n <node_range> [-t <max_waiting_time>] [-V]
xcatprobe osdeploy -n <node_range> -r <xxhxxm> [-V]
```

Options:

- `-n`: The range of nodes to be monitored or replayed.
- `-r`: Trigger ‘Replay history’ mode. Follow the duration of rolling back. Units are ‘h’ (hour) or ‘m’ (minute). If unit is not specified, hour will be used by default.
- `-t`: The maximum time to wait when doing monitor, unit is minutes. default is 60.
- `-V`: Output more information.

- `-r` means replay history of OS provision, if no `-r` means to do realtime monitor.

Realtime monitor

To monitor OS provisioning in real time, open at least 2 terminal windows. One to run osdeploy probe:

```
xcatprobe osdeploy -n cnl [-V]
```

After some pre-checks, the probe will wait for provisioning information, similar to output below:

```
# xcatprobe osdeploy -n c910f03c17k20
The install NIC in current server is enp0s1
  → [INFO]
All nodes which will be deployed are valid
  → [ OK ]
-------------------------------------------------------------
Start capturing every message during OS provision process......
```

Open second terminal window to run provisioning:
nodeset cn1 osimage=<osimage>
rpower cn1 boot

When all the nodes complete provisioning, the probe will exit and display output similar to:

```bash
# xcatprobe osdeploy -n c910f03c17k20
The install NIC in current server is enp0s1
    -> [INFO]
All nodes which will be deployed are valid
  -> [ OK ]
-------------------------------------------------------------
Start capturing every message during OS provision process......
-------------------------------------------------------------
[c910f03c17k20] Use command reinstall to reboot node c910f03c17k20
[c910f03c17k20] Node status is changed to powering-on
[c910f03c17k20] Receive DHCPDISCOVER via enp0s1
[c910f03c17k20] Send DHCPOFFER on 10.3.17.20 back to 42:d0:0a:03:11:14 via enp0s1
[c910f03c17k20] DHCPREQUEST for 10.3.17.20 (10.3.5.4) from 42:d0:0a:03:11:14 via
    -> enp0s1
[c910f03c17k20] Send DHCPACK on 10.3.17.20 back to 42:d0:0a:03:11:14 via enp0s1
[c910f03c17k20] Via TFTP download /boot/grub2/grub2-c910f03c17k20
[c910f03c17k20] Via TFTP download /boot/grub2/powerpc-ieee1275/normal.mod
......
[c910f03c17k20] Postscript: otherpkg exited with code 0
[c910f03c17k20] Node status is changed to booted
[c910f03c17k20] provision completed.(c910f03c17k20)
[c910f03c17k20] provision completed
  -> [ OK ]
All nodes specified to monitor, have finished OS provision process
  -> [ OK ]

==================osdeploy_probe_report=================
All nodes provisioned successfully
  -> [ OK ]
If there is something wrong when provisioning, this probe will exit when timeout is reached or Ctrl+C is pressed by user. The maximum time can be set by using -t as below(default 30 minutes)

```bash
xcatprobe osdeploy -n cn1 -t 30
```

Replay history

To replay history of OS provision from 1 hour 20 minutes ago, use command as

```bash
xcatprobe osdeploy -n cn1 -r 1h20m
```

Outout will be similar to:

```bash
# xcatprobe osdeploy -n c910f03c17k20
The install NIC in current server is enp0s1
    -> [INFO]
All nodes which will be deployed are valid
  -> [ OK ]
Start to scan logs which are later than *********, waiting for a while............
```
discovery

discovery can be used to probe the discovery process, including pre-check for required configuration and realtime monitor of discovery process.

switch-macmap
nodecheck
osimagecheck

1.4.17 RAID

Hardware RAID

Overview

In many new compute machines, disks have been formatted into RAID oriented format in manufacturer, so admin must create raid arrays using these disks manually before provisioning OS. How to configure raid arrays in unattended way for hundreds of machines turns to be a problem.

IBM has offered a tool iprconfig to configure raid for IBM power machine. To leverage this tool, xCAT enabled it in xCAT genesis.ppc64 so that admin can use genesis.ppc64 to configure RAID arrays.

There are two commands (diskdiscover and configraid) shipped in xCAT-genesis-scripts package to support RAID arrays configuration using iprconfig, you can use the runcmd facility to configure raid in the hardware discovery procedure using them, runcmd is a facility which will be run in xcat genesis system. You can also use separated manual steps to use configraid in xcat genesis system shell.

- **diskdiscover**: Scan disk devices in xcat genesis system, give out disks and RAID arrays information.
- **configraid**: Delete RAID arrays, create RAID arrays in xcat genesis system.

Following sections show how to use diskdiscover and configraid, we assume cn1 is compute node in all examples.

Discovering disk devices

Command diskdiscover scans disk devices, it can get the overview of disks and RAID arrays information from compute node; The outputs contain useful information for configraid to configure RAID arrays, user can get pci_id, pci_slot_name, disk names, RAID arrays and other information from the outputs. It should be ran in xcat genesis system. It can be executed without input parameter or with pci_id, pci_id includes PCI vendor and device ID. For example, power8 SAS adapter pci_id is 1014:034a, 1014 is vendor info, 034a is PCI-E IPR SAS Adapter, more info about pci_id refer to http://pci-ids.ucw.cz/read/PC/1014/.

Here are steps to use diskdiscover:

1. Start xCAT genesis system in compute node, let compute node cn1 enter xCAT genesis system shell:
nodeset cn1 shell
rpower cn1 reset

Note: If user modify diskdiscover or configraid scripts, he needs to run the mknb <arch> command before nodeset command to update network boot root image.

2. On xcat management node, executing xdsh to use diskdiscover:

```
xdsh cn1 diskdiscover
```

Or:

```
xdsh cn1 'diskdiscover <pci_id>'
```

The outputs format is as following:

```
# xdsh cn1 diskdiscover
cn1: ------------------------------------------------------------------
cn1: PCI_ID PCI,SLOT_NAME Resource_Path Device Description Status
cn1: ------ ------------- ------------- ------ ----------- --------------
------
cn1: 1014:034a 0001:08:00.0 0:0:0:0 sg0 Function Disk Active
cn1: 1014:034a 0001:08:00.0 0:0:1:0 sg1 0 Array Member Active
 cn1: 0001:08:00.0
 cn1: Name PCI/SCSI Location Description Status
 cn1: ------ ------------------------- ------------------------- -----------------
 cn1: sda 0001:08:00.0/0:2:0:0 RAID 0 Disk Array Optimized
```

Configuring hardware RAID

Command configraid introduction

We can use configraid to delete RAID arrays or create RAID arrays:

```
configraid delete_raid=[all]|"<raid_array_list>"|null
stripe_size=[16|64|256]
create_raid="rl#<raidlevel>|[pci_id#<num]|pci_slot_name#<pci_slot_name>
|disk_names#<sg0>...<sgn}]|disk_num#<number>
```

Here are the input parameters introduction:

1. **delete_raid** : List raid arrays which should be removed.
   - If its value is all, all raid arrays detected should be deleted.
   - If its value is a list of raid array names, these raid arrays will be deleted. Raid array names should be separated by #.
   - If its value is null or there is no delete_raid, no raid array will be deleted.
   - If there is no delete_raid, the default value is null.

2. **stripe_size** : It is optional used when creating RAID arrays. If stripe size is not specified, it will default to the recommended stripe size for the selected RAID level.
3. **create_raid**: To create a raid array, add a line beginning with `create_raid`, all attributes keys and values are separated by `#`. The formats are as followings:

- **rl** means RAID level, RAID level can be any supported RAID level for the given adapter, such as 0, 10, 5, 6. **rl** is a mandatory attribute for every `create_raid`. Supported RAID level is depend on physical server’s RAID adapter.

- User can select disks based on following attributes value. User can find these value based on `diskdiscover` outputs as above section described.
  
  (a) **pci_id** is PCI vendor and device ID.

  (b) **pci_slot_name** is the specified PCI location. If using **pci_slot_name**, this RAID array will be created using disks from it.

  (c) **disk_names** is a list of advanced format disk names. If using **disk_names**, this RAID array will be created using these disks.

- **disk_num** is the number of disks this RAID array will contain, default value is all unused disks in its pci slot.

More examples of input parameters:

1. Delete all original RAID arrays, create one RAID 10 array from pci_id 1014:034a, it uses the first two available disks:

   ```
   delete_raid=all create_raid="rl#10|pci_id#1014:034a|disk_num#2"
   ```

2. Delete original RAID arrays sda and sdb on compute node, create one RAID 0 array from pci slot 0001:08:00.0, its RAID level is 0, it uses first two disks:

   ```
   delete_raid="sda#sdb" create_raid="rl#0|pci_slot_name#0001:08:00.0|disk_num#2"
   ```

3. Create one RAID array from pci_id 1014:034a, RAID level is 0, stripe_size is 256kb, using first two available disks:

   ```
   stripe_size=256 create_raid="rl#0|pci_id#1014:034a|disk_num#2"
   ```

4. Create two RAID arrays, RAID level is 0, one array uses one disks from pci_id 1014:034a, the other array uses two disks from pci_slot_name 0001:08:00.0:

   ```
   create_raid="rl#0|pci_id#1014:034a|disk_num#1" create_raid="rl#0|pci_slot_name #0001:08:00.0|disk_num#2"
   ```

5. Create two RAID arrays, RAID level is 0, one array uses disks sg0 and sg1, the other array uses disks sg2 and sg3:

   ```
   create_raid="rl#0|disk_names#sg0#sg1" create_raid="rl#0|disk_names#sg2#sg3"
   ```

### Configuring RAID arrays process

Command `configraid` is running in xcat genesis system, its log is saved under `/tmp` on compute node genesis system.
Configuring RAID in hardware discovery procedure

1. Using `runcmd` facility to configure raid in the hardware discovery procedure, after configuring RAID, compute node enter xcat genesis system shell. In the following example, `configraid` deletes all original RAID arrays, it creates one RAID 0 array with first two disks from `pci_id 1014:034a`:

```
nodeSet cn1 runcmd="configraid delete_raid=all create_raid=rl#0|pci_id 1014:034a|disk_num#2",shell
rpower cn1 reset
```

2. Using `rcons` to monitor the process:

```
rcons cn1
```

Configuring RAID manually in xcat genesis system shell

1. Starting xCAT genesis system in compute node, let compute node `cn1` enter xCAT genesis system shell:

```
nodeSet cn1 shell
rpower cn1 reset
```

2. On xcat management node, executing `xdsh` to use `configraid` to configure RAID:

```
xsh cn1 'configraid delete_raid=all create_raid="rl#0|pci_id#1014:034a|disk_num#2",shell
```

Monitoring and debugging RAID configuration process

1. Creating some RAID level arrays take very long time, for example, If user creates RAID 10, it will cost tens of minutes or hours. During this period, you can use xCAT `xdsh` command to monitor the progress of raid configuration.

```
xsh cn1 iprconfig -c show-config
```

2. Logs for `configraid` is saved under `tmp` in compute node genesis system. User can login compute node and check `configraid` logs to debug.

3. When configuring RAID in hardware discovery procedure, user can use `rcons` command to monitor or debug the process:

```
rcons cn1
```

1.4.18 Rest API

xCAT provides REST API (also called a web services API) that is currently implemented as a front end (translation layer) to xcatd. This provides programmatic access to xCAT from any language. This document describes how to set it up and use it.

**NOTE:** This doc is working with xCAT 2.8.4 and later.
Set Up Web Service for Rest API

The following steps describe how to setup the Web Service for xCAT management node to offer the Rest API service.

Enable the HTTPS protocol for REST API

To improve the security between the REST API clients and server, enabling the secure transfer protocol (https) is the default configuration.

- [RHEL6/7/8 (x86_64/ppc64/ppc64le) and RHEL5 (x86_64)]
  
  ```
  yum install mod_ssl
  service httpd restart
  yum install perl-JSON
  ```

- [RHEL5 (ppc64)]

  Uninstall httpd.ppc64 and install httpd.ppc:
  
  ```
  rpm -e --nodeps httpd.ppc64
  rpm -i httpd.ppc mod_ssl.ppc
  ```

- [SLES10/11/12 (x86_64/ppc64)]

  ```
  a2enmod ssl
  a2enflag SSL
  /usr/bin/gensslcert
  cp /etc/apache2/vhosts.d/vhost-ssl.template /etc/apache2/vhosts.d/vhost-ssl.conf
  Insert line 'NameVirtualHost *:443' before the line '## SSL Virtual Host Context'
  /etc/init.d/apache2 restart
  zypper install perl-JSON
  ```

- [Ubuntu]

  ```
  sudo a2enmod ssl
  ln -s ../sites-available/default-ssl.conf /etc/apache2/sites-enabled/ssl.conf
  sudo service apache2 restart
  # verify it is loaded:
  sudo apache2ctl -t -D DUMP_MODULES | grep ssl
  apt-get install libjson-perl
  ```

Note: If use of non-secure HTTP protocol is required, edit /etc/httpd/conf.d/xcat-ws.conf for RHEL or /etc/apache2/conf.d/xcat-ws.conf for others and change RewriteEngine On to RewriteEngine Off, then restart httpd or apache.

Enable the Certificate of HTTPs Server (Optional)

Enabling the certificate functionality of https server is useful for the Rest API client to authenticate the server.

The certificate for xcatd has already been generated when installing xCAT, it can be reused by the https server. To enable the server certificate authentication, the hostname of xCAT MN must be a fully qualified domain name (FQDN).
The REST API client also must use this FQDN when accessing the https server. If the hostname of the xCAT MN is not a FQDN, you need to change the hostname first.

Typically the hostname of the xCAT MN is initially set to the NIC which faces to the cluster (usually an internal/private NIC). If you want to enable the REST API for public client, set the hostname of xCAT MN to one of the public NIC.

To change the hostname, edit `/etc/sysconfig/network` (RHEL) or `/etc/HOSTNAME` (SLES) and run:

```
hostname <newFQDN>
```

After changing the hostname, run the `xcatconfig` command to generate a new server certificate based on the correct hostname:

```
xcatconfig -c
```

**Note:** If you had previously generated a certificate for non-root userids to use xCAT, you must regenerate them using `/opt/xcat/share/xcat/scripts/set-up-local-client.sh <username>`

The steps to configure the certificate for https server:

```
export sslcfgfile=/etc/httpd/conf.d/ssl.conf       # rhel
export sslcfgfile=/etc/apache2/vhosts.d/vhost-ssl.conf # sles
export sslcfgfile=/etc/apache2/sites-enabled/ssl.conf # ubuntu

sed -i 's/^[\s\w]*SSLCertificateFile.*$/\1SSLCertificateFile /etc/xcat/cert/
  →server-cred.pem/' $sslcfgfile
sed -i 's/^[\s\w]*SSLCertificateKeyFile.*$/\1 SSLCertificateKeyFile /etc/xcat/cert/
  →server-cred.pem/' $sslcfgfile

service httpd restart       # rhel
service apache2 restart     # sles/ubuntu
```

The REST API client needs to download the xCAT certificate CA from the xCAT http server to authenticate the certificate of the server.

```
cd /root
wget http://<xcat MN>/install/postscripts/ca/ca-cert.pem
```

When accessing the REST API, the certificate CA must be specified and the FQDN of the https server must be used. For example:

```
curl -X GET --cacert /root/ca-cert.pem 'https://<FQDN of xCAT MN>/xcatws/nodes?
  →userName=root&userPW=<root-pw>'
```

**Attention:** Some operations like ‘create osimage’ (i.e. copycds) may require a longer time to complete and may result in a “504 Gateway Timeout” error. To avoid this, modify the `httpd.conf` file and extend the timeout to a larger value: `Timeout: 600`

**Set Up an Account for Web Service Access**

User needs a username and password to access the REST API. When the REST API request is passed to xcatd, the username and password will be verified based on the `xCAT passwd Table`, and then xcatd will look in the `xCAT policy Table` to see if the user is allowed to perform the requested operation.
The account with key of `xcat` will be used for the REST API authentication. The username and password should be passed in as the attributes of URL:

- **userName** Pass the username of the account
- **userPW** Pass the password of the account (xCAT 2.10)
- **password** Pass the password of the account (xCAT earlier than 2.10)

You can use the root userid for your API calls, but we recommend you create a new userid (for example `wsuser`) for the API calls and give it the specific privileges you want it to have.

### Use root Account

The certificate and ssh keys for `root` account has been created during the install of xCAT. The public ssh key also has been uploaded to compute node so that xCAT MN can ssh to CN without password. Then the only thing left to do is to add the password for the `root` in the passwd table.

```bash
$ tabch key=xcat,username=root passwd.password=<root-pw>
```

### Use non-root Account

Create new user and setup the password and policy rules.

```bash
# create a user
useradd -u <wsuid> <wsuser>
# set the password
passwd <wsuser>
# add password to passwd table
$ tabch key=xcat,username=<wsuser> passwd.password=<wspw>
# add user to policy table
mkdef -t policy 6 name=<wsuser> rule=allow
```

**Note:** Using the `tabch` command, you can use the salted password from `/etc/shadow` into the xCAT password table instead of a clear text password.

Identical user with the same name and uid need to be created on each compute node.

```bash
# create a user
useradd -u <wsuid> <wsuser>
# set the password
passwd <wsuser>
```

Create the SSL certificate under that user’s home directory so that user can be authenticated to xCAT. This is done by running the following command on the Management node as root:

```bash
/opt/xcat/share/xcat/scripts/setup-local-client.sh <wsuser>
```

When running this command you’ll see SSL certificates created. Enter “y” where prompted and take the defaults.

To enable the POST method of resources like nodeshell, nodedcopy, updating and filesyncing for the non-root user, you need to enable the ssh communication between xCAT MN and CN without password. Log in as `<username>` and run following command:
xdsh <noderange> -K

Run a test request to see if everything is working:

curl -X GET --cacert /root/ca-cert.pem 'https://<xcat-mn-host>/xcatws/nodes?userName=<wsuser>&userPW=<wspw>'

or if you did not set up the certificate:

curl -X GET -k 'https://<xcat-mn-host>/xcatws/nodes?userName=<wsuser>&userPW=<wspw>'

You should see some output that includes your list of nodes.

If errors returned, check /var/log/httpd/ssl_error_log on xCAT MN.

Note: When passwords are changed, make sure to update the xCAT passwd table. The REST API service uses passwords stored there to authenticate users.

How to Use xCAT Rest API

The Resource Categories

The API lets you query, change, and manage the resources in following categories:

- Token Resources
- Node Resources
- Osimage Resources
- Network Resources
- Policy Resources
- Group Resources
- Global Configuration Resources
- Service Resources
- Table Resources

The Authentication Methods for REST API

xCAT REST API supports two ways to authenticate the access user: user account (username + password) and access token (acquired by username + password).

User Account

Follow the steps in WEB Service Setup, you can create an account for yourself. Then use that username and password to access the https server.

The general format of the URL used in the REST API call is:
where:

- **FQDN of xCAT MN**: the hostname of the xCAT management node. It also can be the IP of xCAT MN if you don’t want to enable the web server certificate
- **resource**: one of the xCAT resources listed above
- **user**: the userid that the operation should be run on behalf of. See the previous section on how to add/authorize a userid.
- **pw**: the password of the userid (can be the salted version from /etc/shadow)

Example:

```
curl -X GET -k 'https://<FQDN of xCAT MN>/xcatws/nodes?userName=root&userPW=cluster'
```

### Access Token

xCAT also supports the use the Access Token to replace the using of username+password in every access. Before accessing any resource, you need get a token with your account (username+password)

```
# curl -X POST -k \\
'https://<FQDN of xCAT MN>/xcatws/tokens?pretty=1' -H Content-Type:application/json --data \\
'{"userName":"root","userPW":"cluster"}'
{
  "token":{
    "id":"5cabd675-bc2e-4318-b1d6-831fd1f32f97",
    "expire":"2014-3-10 9:56:12"
  }
}
```

Then in the subsequent REST API access, the token can be used to replace the user account (username+password)

```
curl -X GET -k -H X-Auth-Token:5cabd675-bc2e-4318-b1d6-831fd1f32f97 'https://<FQDN of xCAT MN>/xcatws/<resource>?<parameters>
```

The default validity of a token is 1 day. This default can be changed by the setting of `tokenexpiredays` attribute in `site` table.

```
chdef -t site clustersite tokenexpiredays=<days>
```

To make tokens valid forever use “never”.

```
chdef -t site clustersite tokenexpiredays=never
```

If an old token has expired, you will get a ‘Authentication failure’ error. You will need to reacquire a token for your account.

### The Common Parameters for Resource URI

xCAT REST API supports several common parameters in the resource URI to enable specific output:

- **pretty=1** - It is used to format the json output for easier viewing on the screen.
• **debug=1** - It is used to display more debug messages for a REST API request.

```
https://<xCAT MN>/xcatws/nodes?debug=1
```

• **xcoll=1** - It is used to specify that the output should be grouped with the values of objects.

```
GET https://<xCAT MN>/xcatws/nodes/node1,node2,node3/power?xcoll=1
{
    "node2":{
        "power":"off"
    },
    "node1,node3":{
        "power":"on"
    }
}
```

**Note:** All the above parameters can be used together like following:

```
https://<xCAT MN>/xcatws/nodes?pretty=1&debug=1
```

### The Output of REST API request

xCAT REST API only supports the [JSON](http://www.json.org/) formatted output.

### When an Error occurs during the operation

(i.e. there’s error/errorcode in the output of xcat xml response):

When error happens, for all the GET/PUT/POST/DELETE methods, the output will only include ‘error’ and ‘error-code’ properties:

```
{
    error:
    {
        msg1,
        msg2,
        ...
    },
    errorcode: error_number
}
```

### When NO Error occurs during the operation

(i.e. there’s no error/errorcode in the output of xcat xml response):

**For the GET method**

If the output can be grouped by the object (resource) name, and the information being returned are attributes of the object, then use the object name as the hash key and make the value be a hash of its attributes/values:
If the output can be grouped by the object (resource) name, but the information being returned is not attributes of the object, then use the object name as the hash key and make the value be an array of strings:

```
{ 
  object1: [ 
    msg1, 
    msg2, 
    ... 
  ], 
  object2: [ 
    msg1, 
    msg2 
    ... 
  ], 
}
```

An example of this case is the output of reventlog:

```
{ 
  "node1": [ 
    "09/07/2013 10:05:02 Event Logging Disabled, Log Area Reset/Cleared (SELFullness)" , 
    ... 
  ], 
}
```

If the output is not object related, put all the output in a list (array):

```
[ 
  msg1, 
  msg2, 
  ... 
]
```

**For the PUT/DELETE methods**

There will be no output for operations that succeeded. (We made this decision because the output for them not formatted, and no program will read it if xcat indicates the operation has succeeded.)
For POST methods

Since POST methods can either be creates or general actions, there is not much consistency. In the case of a create, the rule is the same as PUT/DELETE (no output if successful). For actions that have output that matters (e.g. nodeshell, filesyncing, sw, postscript), the rules are like the GET method.

Testing the API

Normally you will make REST API calls from your code. You can use any language that has REST API bindings (most modern languages do).

An Example of How to Use xCAT REST API from Python

Refer to the file /opt/xcat/ws/xcatws-test.py:

```
./xcatws-test.py --user wsuser --password cluster_rest --xcatmn <FQDN of xCAT MN>
```

An Example of How to Use xCAT REST API from PERL

Refer to the file /opt/xcat/ws/xcatws-test.pl:

```
./xcatws-test.pl -m GET -u "https://127.0.0.1/xcatws/nodes?userName=root&userPW=cluster"
```

An Example Script of How to Use curl to Test Your xCAT REST API Service

It can be used as an example script to access and control xCAT resources. From the output message, you also could get the idea of how to access xCAT resources.

```
./xcatws-test.sh
./xcatws-test.sh -u root -p cluster
```

But for exploration and experimentation, you can make API calls from your browser or by using the `curl` command.

To make an API call from your browser, use the desired URL from this document. To simplify the test step, all the examples for the resources use ‘curl -k’ for unsecure http connection and use the ‘username+password’ to authenticate the user.

```
curl -X GET -k 'https://myserver/xcatws/nodes?userName=xxx&userPW=xxx&pretty=1'
```

Examples of making an API call using curl

- To query resources:
curl -X GET -k 'https://xcatmnhost/xcatws/nodes?userName=xxx&userPW=xxx&pretty=1'

- To change attributes of resources:

  curl -X PUT -k 'https://xcatmnhost/xcatws/nodes/{noderange}?userName=xxx&userPW=xxx' -H Content-Type:application/json --data '{"room":"hi","unit":"7"}''

- To run an operation on a resource:

  curl -X POST -k 'https://xcatmnhost/xcatws/nodes/{noderange}?userName=xxx&userPW=xxx' -H Content-Type:application/json --data '{"groups":"wstest"}''

- To delete a resource:

  curl -X DELETE -k 'https://xcatmnhost/xcatws/nodes/{noderange}?userName=xxx&userPW=xxx'

### Web Service Status Codes

Here are the HTTP defined status codes that the Web Service can return:

- 401 Unauthorized
- 403 Forbidden
- 404 Not Found
- 405 Method Not Allowed
- 406 Not Acceptable
- 408 Request Timeout
- 409 Conflict
- 410 Gone
- 411 Length Required
- 412 Precondition Failed
- 413 Request Entity Too Large
- 414 Request-URI Too Long
- 415 Unsupported Media Type
- 416 Requested Range Not Satisfiable
- 417 Expectation Failed
- 418 I’m a teapot
- 422 Unprocessable Entity
- 503 Service Unavailable
- 200 OK
- 201 Created

### References

- REST: [http://rest.elkstein.org/2008/02/what-is-rest.html](http://rest.elkstein.org/2008/02/what-is-rest.html)
- HTTP Status codes: [http://www.w3.org/Protocols/rfc2616/rfc2616-sec10.html](http://www.w3.org/Protocols/rfc2616/rfc2616-sec10.html)
- HTTP Request Tool: [http://soft-net.net/SendHTTPTool.aspx](http://soft-net.net/SendHTTPTool.aspx) (haven’t tried it yet)
- HTTP BASIC Security: [http://httpd.apache.org/docs/2.2/mod/mod_auth_basic.html](http://httpd.apache.org/docs/2.2/mod/mod_auth_basic.html)
xCAT Rest API Resources

Token Resources

The URI list which can be used to create tokens for account.

[URI:/tokens] - The authentication token resource.

POST - Create a token.

Returns:
- An array of all the global configuration list.

Example:
Acquire a token for user ‘root’.

```
curl -X POST -k 'https://127.0.0.1/xcatws/tokens?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"userName":"root","userPW":"cluster"}'

{
  "token":{
    "id":"a6e89b59-2b23-429a-b3fe-d16807dd19eb",
    "expire":"2014-3-8 14:55:0"
  }
}
```

Node Resources

The URI list which can be used to create, query, change and manage node objects.

[URI:/nodes] - The node list resource.

This resource can be used to display all the nodes which have been defined in the xCAT database.

GET - Get all the nodes in xCAT.

The attributes details for the node will not be displayed.

Refer to the man page: lsdef

Returns:
- Json format: An array of node names.
Example:
Get all the node names from xCAT database.

```
curl -X GET -k 'https://127.0.0.1/xcatws/nodes?userName=root&userPW=cluster&pretty=1'
[
  "node1",
  "node2",
  "node3",
]
```

[URI:/nodes/{noderange}] - The node resource

GET - Get all the attributes for the node {noderange}.

The keyword ALLRESOURCES can be used as {noderange} which means to get node attributes for all the nodes.
Refer to the man page: lsdef

Returns:

- Json format: An object which includes multiple ‘<name> : {att:value, attr:value ... }’ pairs.

Example:
Get all the attributes for node ‘node1’.

```
curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1?userName=root&userPW=cluster&pretty=1'
{
  "node1":{
    "profile":"compute",
    "netboot":"xnba",
    "arch":"x86_64",
    "mgt":"ipmi",
    "groups":"all",
    ...
  }
}
```

PUT - Change the attributes for the node {noderange}.

Refer to the man page: chdef

Parameters:

- Json format: An object which includes multiple ‘att:value’ pairs. DataBody: {attr1:v1,att2:v2,... }.

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: 
  {error:[msg1,msg2,...],errocode:erronum}.

Example:
Change the attributes mgt=dfm and netboot=yaboot.

```
curl -X PUT -k 'https://127.0.0.1/xcatws/nodes/node1?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"mgt":"dfm","netboot":"yaboot"}'
```

1.4. Advanced Topics
xCAT3 Documentation, Release 2.14.5

POST - Create the node {noderange}.
Refer to the man page: mkdef
Parameters:
• Json format:
An object which includes
tions:{opt1:v1,opt2:v2},attr1:v1,att2:v2,. . . }.

multiple

‘att:value’

pairs.

DataBody:

{op-

Returns:
• No output when execution is successful. Otherwise output the error information in the Standard Error Format:
{error:[msg1,msg2. . . ],errocode:errornum}.
Example:
Create a node with attributes groups=all, mgt=dfm and netboot=yaboot
curl -X POST -k 'https://127.0.0.1/xcatws/nodes/node1?userName=root&userPW=cluster&
˓→pretty=1' -H Content-Type:application/json --data '{"options":{"--template":"x86_
˓→64kvmguest-template"},'

DELETE - Remove the node {noderange}.
Refer to the man page: rmdef
Returns:
• No output when execution is successful. Otherwise output the error information in the Standard Error Format:
{error:[msg1,msg2. . . ],errocode:errornum}.
Example:
Delete the node node1
curl -X DELETE -k 'https://127.0.0.1/xcatws/nodes/node1?userName=root&userPW=cluster&
˓→pretty=1'

[URI:/nodes/{noderange}/attrs/{attr1,attr2,attr3 . . . }] - The attributes resource for the node
{noderange}
GET - Get the specific attributes for the node {noderange}.
The keyword ALLRESOURCES can be used as {noderange} which means to get node attributes for all the nodes.
Refer to the man page: lsdef
Returns:
• Json format: An object which includes multiple ‘<name> : {att:value, attr:value . . . }’ pairs.
Example:
Get the attributes {groups,mgt,netboot} for node node1
curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1/attrs/groups,mgt,netboot?
˓→userName=root&userPW=cluster&pretty=1'
{
(continues on next page)

948

Chapter 1. Table of Contents


"node1":{
  "netboot":"xnba",
  "mgt":"ipmi",
  "groups":"all"
}
}

[URI:/nodes/{noderange}/host] - The mapping of ip and hostname for the node {noderange}

POST - Create the mapping of ip and hostname record for the node {noderange}.

Refer to the man page: makehosts

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format:
  `{error:[msg1,msg2...],errocode:erronum}`.

Example:

Create the mapping of ip and hostname record for node ‘node1’.

```
curl -X POST -k 'https://127.0.0.1/xcatws/nodes/node1/host?userName=root&
  →userPW=cluster&pretty=1'
```

[URI:/nodes/{noderange}/dns] - The dns record resource for the node {noderange}

POST - Create the dns record for the node {noderange}.

The prerequisite of the POST operation is the mapping of ip and noderange for the node has been added in the
/etc/hosts.

Refer to the man page: makedns

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format:
  `{error:[msg1,msg2...],errocode:erronum}`.

Example:

Create the dns record for node ‘node1’.

```
curl -X POST -k 'https://127.0.0.1/xcatws/nodes/node1/dns?userName=root&
  →userPW=cluster&pretty=1'
```

DELETE - Remove the dns record for the node {noderange}.

Refer to the man page: makedns

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format:
  `{error:[msg1,msg2...],errocode:erronum}`.
Example:
Delete the dns record for node node1

```
curl -X DELETE -k 'https://127.0.0.1/xcatws/nodes/node1/dns?userName=root&userPW=cluster&pretty=1'
```

[URI:/nodes/{noderange}/dhcp] - The dhcp record resource for the node {noderange}

POST - Create the dhcp record for the node {noderange}.

Refer to the man page: makedhcp

Returns:
- No output when execution is successful. Otherwise output the error information in the Standard Error Format: {error:[msg1,msg2,...],errocde:errnum}.

Example:
Create the dhcp record for node 'node1'.

```
curl -X POST -k 'https://127.0.0.1/xcatws/nodes/node1/dhcp?userName=root&userPW=cluster&pretty=1'
```

DELETE - Remove the dhcp record for the node {noderange}.

Refer to the man page: makedhcp

Returns:
- No output when execution is successful. Otherwise output the error information in the Standard Error Format: {error:[msg1,msg2,...],errocde:errnum}.

Example:
Delete the dhcp record for node node1

```
curl -X DELETE -k 'https://127.0.0.1/xcatws/nodes/node1/dhcp?userName=root&userPW=cluster&pretty=1'
```

[URI:/nodes/{noderange}/nodestat] - The attributes resource for the node {noderange}

GET - Get the running status for the node {noderange}.

Refer to the man page: nodestat

Returns:
- An object which includes multiple entries like: <nodename> : { nodestat : <node state> }

Example:
Get the running status for node node1

```
curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1/nodestat?userName=root&userPW=cluster&pretty=1'
```
curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1/nodestat?userName=root&userPW=cluster&pretty=1'
{
  "node1":{
    "nodestat":"noping"
  }
}

[URI:/nodes/{noderange}/nodels] - Lists the nodes, noderange cannot start with /

**GET - Lists the nodes.**

Refer to the man page: *nodels*

**Returns:**
- Json format: An array of node names.

**Example:**
Get the node names from xCAT database.

```bash
curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node[1-3]/nodels?userName=root&userPW=cluster&pretty=1'
[
  "node1",
  "node2",
  "node3",
]
```

[URI:/nodes/{noderange}/subnodes] - The sub-nodes resources for the node {noderange}

**GET - Return the Children nodes for the node {noderange}.**

Refer to the man page: *rscan*

**Returns:**
- Json format: An object which includes multiple `<name> : {att:value, attr:value ... }` pairs.

**Example:**
Get all the children nodes for node ‘node1’.

```bash
curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1/subnodes?userName=root&userPW=cluster&pretty=1'
{
  "cmm01node09":{
    "mpa":"ngpcmm01",
    "parent":"ngpcmm01",
    "serial":"1035CDB",
    "mtm":"789523X",
    "cons":"fsp",
    "hwtype":"blade",
    "objtype":"node",
  }
```

(continues on next page)
"groups":"blade,all,p260",
"mgt":"fsp",
"nodetype":"ppc,osi",
"slotid":"9",
"hcp":"10.1.9.9",
"id":"1"
},
...

[URI:/nodes/{noderange}/power] - The power resource for the node {noderange}

GET - Get the power status for the node {noderange}.

Refer to the man page: rpower

Returns:

- An object which includes multiple entries like: <nodename> : { power : <powerstate> }

Example:

Get the power status.

curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1/power?userName=root&
-userPW=cluster&pretty=1'
{
  "node1":{
    "power":"on"
  }
}

PUT - Change power status for the node {noderange}.

Refer to the man page: rpower

Parameters:

- Json Formatted DataBody: {action:on/off/reset ...}.

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: {error:[msg1,msg2...],errocode:errornum}.

Example:

Change the power status to on

curl -X PUT -k 'https://127.0.0.1/xcatws/nodes/node1/power?userName=root&
-userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"action":"on"}'

[URI:/nodes/{noderange}/energy] - The energy resource for the node {noderange}
GET - Get all the energy status for the node {noderange}.

Refer to the man page: `renergy`

**Returns:**

- Json format: An object which includes multiple ‘<name> : {att:value, attr:value ... }’ pairs.

**Example:**

Get all the energy attributes.

```bash
curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1/energy?userName=root&
userPW=cluster&pretty=1'
{
  "node1":{
    "cappingmin":"272.3 W",
    "cappingmax":"354.0 W"
    ...
  }
}
```

PUT - Change energy attributes for the node {noderange}.

Refer to the man page: `renergy`

**Parameters:**

- Json format: An object which includes multiple ‘att:value’ pairs. DataBody: {powerattr:value}.

**Returns:**

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: 
  {error:[msg1,msg2...],errocode:erronum}.

**Example:**

Turn on the cappingstatus to [on]

```bash
curl -X PUT -k 'https://127.0.0.1/xcatws/nodes/node1/energy?userName=root&
userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"cappingstatus":
"on"}'
```

**[URI:/nodes/{noderange}/energy/{cappingmaxmin,cappingstatus,cappingvalue ...}] - The specific energy attributes resource for the node {noderange}**

GET - Get the specific energy attributes cappingmaxmin,cappingstatus,cappingvalue ... for the node {noderange}.

Refer to the man page: `renergy`

**Returns:**

- Json format: An object which includes multiple ‘<name> : {att:value, attr:value ... }’ pairs.

**Example:**

Get the energy attributes which are specified in the URI.
curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1/energy/cappingmaxmin,
cappingstatus?userName=root&userPW=cluster&pretty=1'
{
    "node1":{
        "cappingmin":"272.3 W",
        "cappingmax":"354.0 W"
    }
}

[URI:/nodes/{noderange}/sp/{community|ip|netmask|...}] - The attribute resource of service processor for the node {noderange}

GET - Get the specific attributes for service processor resource.

Refer to the man page: rspconfig

Returns:

• Json format: An object which includes multiple ‘<name> : {att:value, attr:value ... }’ pairs.

Example:

Get the snmp community for the service processor of node1.

curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1/sp/community?userName=root&userPW=cluster&pretty=1'
{
    "node1":{
        "SP SNMP Community":"public"
    }
}

PUT - Change the specific attributes for the service processor resource.

Refer to the man page: rspconfig

Parameters:

• Json format: An object which includes multiple ‘att:value’ pairs. DataBody: {community:public}.

Returns:

• No output when execution is successful. Otherwise output the error information in the Standard Error Format: {error:[msg1,msg2,...],errocode:erronum}.

Example:

Set the snmp community to [mycommunity].

curl -X PUT -k 'https://127.0.0.1/xcatws/nodes/node1/sp/community?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"value":"mycommunity"}'}
[URI:/nodes/{noderange}/nextboot] - The temporary bootorder resource in next boot for the node {noderange}

**GET - Get the next bootorder.**

Refer to the man page: `rsetboot`

**Returns:**
- Json format: An object which includes multiple `<name> : {att:value, attr:value ... }` pairs.

**Example:**
Get the bootorder for the next boot. (It’s only valid after setting.)

```
curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1/nextboot?userName=root&userPW=cluster&pretty=1'
{
  "node1":{
    "nextboot":"Network"
  }
}
```

**PUT - Change the next boot order.**

Refer to the man page: `rsetboot`

**Parameters:**
- Json format: An object which includes multiple `att:value` pairs. DataBody: `{order:net/hd}`.

**Returns:**
- No output when execution is successful. Otherwise output the error information in the Standard Error Format: `{error:[msg1, msg2...], errocode:errornum}`.

**Example:**
Set the bootorder for the next boot.

```
curl -X PUT -k 'https://127.0.0.1/xcatws/nodes/node1/nextboot?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"order":"net"}'
```

[URI:/nodes/{noderange}/bootstate] - The boot state resource for node {noderange}.

**GET - Get boot state.**

Refer to the man page: `nodeset`

**Returns:**
- Json format: An object which includes multiple `<name> : {att:value, attr:value ... }` pairs.

**Example:**
Get the next boot state for the node1.

---

1.4. **Advanced Topics** 955
curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1/bootstate?userName=root&userPW=cluster&pretty=1'
{
    "node1":{
        "bootstat":"boot"
    }
}

**PUT - Set the boot state.**

Refer to the man page: *nodeset*

**Parameters:**

- Json format: An object which includes multiple ‘att:value’ pairs. DataBody: {osimage:xxx}/{state:offline}.

**Returns:**

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: {error:[msg1,msg2,...],errocode:erronum}.

**Example:**

Set the next boot state for the node1.

curl -X PUT -k 'https://127.0.0.1/xcatws/nodes/node1/bootstate?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"osimage":"rhels6.4-x86_64-install-compute"}'

**[URI:/nodes/{noderange}/vitals] - The vitals resources for the node {noderange}**

**GET - Get all the vitals attributes.**

Refer to the man page: *rvitals*

**Returns:**

- Json format: An object which includes multiple `<name> : {att:value, attr:value ... }` pairs.

**Example:**

Get all the vitails attributes for the node1.

curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1/vitals?userName=root&userPW=cluster&pretty=1'
{
    "node1":{
        "SysBrd Fault":"0",
        "CPUs":"0",
        "Fan 4A Tach":"3330 RPM",
        "Drive 15":"0",
        "SysBrd Vol Fault":"0",
        "nvDIMM Flash":"0",
        "Progress":"0"
    }
}
[URI:/nodes/{noderange}/vitals/{temp|voltage|wattage|fanspeed|power|leds...}] - The specific vital attributes for the node {noderange}

GET - Get the specific vitals attributes.

Refer to the man page: rvitals

Returns:

- Json format: An object which includes multiple ‘<name> : {att:value, attr:value ... }’ pairs.

Example:

Get the ‘fanspeed’ vitals attribute.

curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1/vitals/fanspeed?userName=root&userPW=cluster&pretty=1'

```
{
  "node1":{
    "Fan 1A Tach":"3219 RPM",
    "Fan 4B Tach":"2688 RPM",
    "Fan 3B Tach":"2560 RPM",
    "Fan 4A Tach":"3330 RPM",
    "Fan 2A Tach":"3293 RPM",
    "Fan 1B Tach":"2592 RPM",
    "Fan 3A Tach":"3182 RPM",
    "Fan 2B Tach":"2592 RPM"
  }
}
```

[URI:/nodes/{noderange}/inventory] - The inventory attributes for the node {noderange}

GET - Get all the inventory attributes.

Refer to the man page: rinv

Returns:

- Json format: An object which includes multiple ‘<name> : {att:value, attr:value ... }’ pairs.

Example:

Get all the inventory attributes for node1.

curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1/inventory?userName=root&userPW=cluster&pretty=1'

```
{
  "node1":{
    "DIMM 21 ":"8GB PC3-12800 (1600 MT/s) ECC RDIMM",
    "DIMM 1 Manufacturer ":"Hyundai Electronics",
    "Power Supply 2 Board FRU Number ":"94Y8105",
    "DIMM 9 Model ":"HMT31GR7EF4C-PB",
    "DIMM 8 Manufacture Location ":"01",
    "DIMM 13 Manufacturer ":"Hyundai Electronics",
    "DASD Backplane 4 ":"Not Present",
    ...
  }
}
```
[URI:/nodes/{noderange}/inventory/{pci|model...}] - The specific inventory attributes for the node {noderange}

GET - Get the specific inventory attributes.

Refer to the man page: *rinv*

Returns:
- Json format: An object which includes multiple `<name> : {att:value, attr:value ... }` pairs.

Example:
Get the ‘model’ inventory attribute for node1.

```
curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1/inventory/model?userName=root&userPW=cluster&pretty=1'
{
  "node1":{
    "System Description":"System x3650 M4",
    "System Model/MTM":"7915C2A"
  }
}
```

[URI:/nodes/{noderange}/eventlog] - The eventlog resource for the node {noderange}

GET - Get all the eventlog for the node {noderange}.

Refer to the man page: *reventlog*

Returns:
- Json format: An object which includes multiple `<name> : {att:value, attr:value ... }` pairs.

Example:
Get all the eventlog for node1.

```
curl -X GET -k 'https://127.0.0.1/xcatws/nodes/node1/eventlog?userName=root&userPW=cluster&pretty=1'
{
  "node1":{
    "eventlog":[
      "03/19/2014 15:17:58 Event Logging Disabled, Log Area Reset/Cleared (SEL Fullness)"
    ]
  }
}
```

DELETE - Clean up the event log for the node {noderange}.

Refer to the man page: *reventlog*

Returns:
- No output when execution is successful. Otherwise output the error information in the Standard Error Format: `{error:[msg1,msg2...],errocode:erronum}`.
Example:
Delete all the event log for node1.

```
curl -X DELETE -k 'https://127.0.0.1/xcatws/nodes/node1/eventlog?userName=root&
userPW=cluster&pretty=1'
```

```

["eventlog":
  "SEL cleared"],
"name":"node1"
```
[URI:/nodes/{noderange}/updating] - The updating resource for the node {noderange}

POST - Update the node with file syncing, software maintenance and rerun postscripts.

Refer to the man page: updatenode

Returns:

- An array of messages for performing the node updating.

Example:

Initiate an updatenode process.

curl -X POST -k 'https://127.0.0.1/xcatws/nodes/node2/updating?userName=root&userPW=cluster&pretty=1'

```json
[  "There were no syncfiles defined to process. File synchronization has completed.",  "Performing software maintenance operations. This could take a while, if there are packages to install. ",  "node2: Wed Mar 20 15:01:43 CST 2013 Running postscript: ospkgs",  "node2: Running of postscripts has completed." ]
```

[URI:/nodes/{noderange}/filesyncing] - The filesyncing resource for the node {noderange}

POST - Sync files for the node {noderange}.

Refer to the man page: updatenode

Returns:

- An array of messages for performing the file syncing for the node.

Example:

Initiate an file syncing process.

curl -X POST -k 'https://127.0.0.1/xcatws/nodes/node2/filesyncing?userName=root&userPW=cluster&pretty=1'

```json
[  "There were no syncfiles defined to process. File synchronization has completed." ]
```

[URI:/nodes/{noderange}/sw] - The software maintenance for the node {noderange}

POST - Perform the software maintenance process for the node {noderange}.

Refer to the man page: updatenode

Returns:

- Json format: An object which includes multiple `<name> : {att:value, attr:value . . . }` pairs.
Example:

Initiate an software maintenance process.

```
curl -X POST -k 'https://127.0.0.1/xcatws/nodes/node2/sw?userName=root&userPW=cluster&--pretty=1'
{
   "node2": [
      " Wed Apr  3 09:05:42 CST 2013 Running postscript: ospkgs",
      " Unable to read consumer identity",
      " Postscript: ospkgs exited with code 0",
      " Wed Apr  3 09:05:44 CST 2013 Running postscript: otherpkgs",
      " ./otherpkgs: no extra rpms to install",
      " Postscript: otherpkgs exited with code 0",
      " Running of Software Maintenance has completed."
   ]
}
```

**[URI:/nodes/{noderange}/postscript] - The postscript resource for the node {noderange}**

**POST - Run the postscripts for the node {noderange}.

Refer to the man page: updatenode**

**Parameters:**

- Json format: An object which includes multiple ‘att:value’ pairs. DataBody: {scripts:[p1,p2,p3,...]}

**Returns:**

- Json format: An object which includes multiple ‘<name> : {att:value, attr:value ... }’ pairs.

**Example:**

Initiate an updatenode process.

```
curl -X POST -k 'https://127.0.0.1/xcatws/nodes/node2/postscript?userName=root&userPW=cluster&--pretty=1' -H Content-Type:application/json --data '{"scripts":["syslog","remoteshell"]}'
{
   "node2": [
      " Wed Apr  3 09:01:33 CST 2013 Running postscript: syslog",
      " Shutting down system logger: [ OK ]",
      " Starting system logger: [ OK ]",
      " Postscript: syslog exited with code 0",
      " Wed Apr  3 09:01:33 CST 2013 Running postscript: remoteshell",
      " Stopping sshd: [ OK ]",
      " Starting sshd: [ OK ]",
      " Postscript: remoteshell exited with code 0",
      " Running of postscripts has completed."
   ]
}
```

**[URI:/nodes/{noderange}/nodeshell] - The nodeshell resource for the node {noderange}**
POST - Run the command in the shell of the node \{noderange\}.

Refer to the man page: \textit{xdsh}

\textbf{Parameters:}

- Json format: An object which includes multiple ‘att:value’ pairs. DataBody: set environment \{ENV:\{en1:v1,en2:v2\}\}, raw command \{raw:\{op1,op2\}\}, direct command \{command:\{cmd1,cmd2\}\}.

\textbf{Returns:}

- Json format: An object which includes multiple ‘<name> : {att:value, attr:value …}’ pairs.

\textbf{Example:}

Run the ‘date’ command on the node2.

```
curl -X POST -k 'https://127.0.0.1/xcatws/nodes/node2/nodeshell?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"command": ["date -r", "ls"]}'
```

```
"node2": [
    "Wed Apr 3 08:30:26 CST 2013",
    "testline1",
    "testline2"
]
```

[\textbf{URI:}/\textbf{nodes}/\{noderange\}/\textbf{nodecopy}] - The nodecopy resource for the node \{noderange\}

\textbf{POST - Copy files to the node \{noderange\}.}

Refer to the man page: \textit{xdep}

\textbf{Parameters:}

- Json format: An object which includes multiple ‘att:value’ pairs. DataBody: \{src:\{file1, file2\}, target:dir\}.

\textbf{Returns:}

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: \{error:\{msg1, msg2…\}, errocode: errornum\}.

\textbf{Example:}

Copy files /tmp/f1 and /tmp/f2 from xCAT MN to the node2:/tmp.

```
curl -X POST -k 'https://127.0.0.1/xcatws/nodes/node2/nodecopy?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"src": ["/tmp/f1", "/tmp/f2"], "target": "/tmp"}'
```

```
no output for succeeded copy.
```

[\textbf{URI:}/\textbf{nodes}/\{noderange\}/\textbf{vm}] - The virtualization node \{noderange\}.

The node should be a virtual machine of type kvm, esxi …
PUT - Change the configuration for the virtual machine {noderange}.

Refer to the man page: `chvm`

Parameters:
- **Json format**: An object which includes multiple ‘att:value’ pairs. **DataBody**: Set memory size - `{“memorysize”:”sizeofmemory(MB)”}` Add new disk - `{“adddisk”:”sizeofdisk1(GB),sizeofdisk2(GB)”}` Purge disk - `{“purgedisk”:”scsi_id1,scsi_id2”}`

Returns:
- No output when execution is successful. Otherwise output the error information in the Standard Error Format: `{error:[msg1,msg2,...],errocode:erronum}`.

**Example1:**
Set memory to 3000MB.
```
curl -X PUT -k 'https://127.0.0.1/xcatws/nodes/node1/vm?userName=root&userPW=cluster& pretty=1' -H Content-Type:application/json --data '{"memorysize":"3000"}'
```

**Example2:**
Add a new 20G disk.
```
curl -X PUT -k 'https://127.0.0.1/xcatws/nodes/node1/vm?userName=root&userPW=cluster& pretty=1' -H Content-Type:application/json --data '{"adddisk":"20G"}'
```

**Example3:**
Purge the disk ‘hdb’.
```
curl -X PUT -k 'https://127.0.0.1/xcatws/nodes/node1/vm?userName=root&userPW=cluster& pretty=1' -H Content-Type:application/json --data '{"purgedisk":"hdb"}'
```

POST - Create the vm node {noderange}.

Refer to the man page: `mkvm`

Parameters:
- **Json format**: An object which includes multiple ‘att:value’ pairs. **DataBody**: Set CPU count - `{“cpu-count”:”numberofcpu”}` Set memory size - `{“memorysize”:”sizeofmemory(MB)”}` Set disk size - `{“disk-size”:”sizeofdisk”}` Do it by force - `{“force”:”yes”}`

Returns:
- No output when execution is successful. Otherwise output the error information in the Standard Error Format: `{error:[msg1,msg2,...],errocode:erronum}`.

**Example:**
Create the vm node1 with a 30G disk, 2048M memory and 2 cpus.
```
curl -X POST -k 'https://127.0.0.1/xcatws/nodes/node1/vm?userName=root&userPW=cluster& pretty=1' -H Content-Type:application/json --data '{"disksize":"30G","memorysize":"2048","cpucount":"2"}'
```
DELETE - Remove the vm node {noderange}.

Refer to the man page: `rmvm`

Parameters:

- **Json format**: An object which includes multiple ‘att:value’ pairs. **DataBody**:
  - Purge disk - 
    ```json
    {"purge":"yes"}  
    {"force":"yes"}
    ```

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: 
  ```json
  {error:[msg1,msg2,...],errocode:errornum}.
  ```

Example:

Remove the vm node1 by force and purge the disk.

```bash
$ curl -X DELETE -k 'https://127.0.0.1/xcatws/nodes/node1/vm?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"force":"yes","purge":"yes"}'
```

[URL:/nodes/{noderange}/vmclone] - The clone resource for the virtual node {noderange}.

The node should be a virtual machine of kvm, esxi ...

POST - Create a clone master from node {noderange}. Or clone the node {noderange} from a clone master.

Refer to the man page: `clonevm`

Parameters:

- **Json format**: An object which includes multiple ‘att:value’ pairs. **DataBody**:
  - Clone a master named “mastername” - 
    ```json
    {"tomaster":"mastername"}
    ```
  - Clone a node from master “mastername” - 
    ```json
    {"frommaster":"mastername"}
    ```
  - Use Detach mode - 
    ```json
    {"detach":"yes"}
    ```
  - Do it by force - 
    ```json
    {"force":"yes"}
    ```

Returns:

- The messages of creating Clone target.

Example1:

Create a clone master named “vmmaster” from the node1.

```bash
$ curl -X POST -k 'https://127.0.0.1/xcatws/nodes/node1/vmclone?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"tomaster":"vmmaster","detach":"yes"}'
```

Example2:

Clone the node1 from the clone master named “vmmaster”.

```bash
$ curl -X POST -k 'https://127.0.0.1/xcatws/nodes/node1/vmclone?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"tomaster":"vmmaster","detach":"yes"}''
```
curl -X POST -k 'https://127.0.0.1/xcatws/nodes/node1/vmclone?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"frommaster": "vmmaster"}'

[URI:/nodes/{noderrange}/vmmigrate] - The virtualization resource for migration.

The node should be a virtual machine of kvm, esxi ...

**POST - Migrate a node to target node.**

Refer to the man page: `rmigrate`

**Parameters:**

- Json format: An object which includes multiple ‘att:value’ pairs. DataBody: {“target”:”targethost”}.

**Example:**

Migrate node1 to target host host2.

```
curl -X POST -k 'https://127.0.0.1/xcatws/nodes/node1/vmmigrate?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"target":"host2"}'
```

**Osimage resources**

URI list which can be used to query, create osimage resources.

**[URI:/osimages] - The osimage resource.**

**GET - Get all the osimage in xCAT.**

Refer to the man page: `lsdef`

**Returns:**

- Json format: An array of osimage names.

**Example:**

Get all the osimage names.

```
curl -X GET -k 'https://127.0.0.1/xcatws/osimages?userName=root&userPW=cluster&pretty=1'
```

```
[ "sles11.2-x86_64-install-compute",
  "sles11.2-x86_64-install-iscsi",
  "sles11.2-x86_64-install-iscsiibft",
  "sles11.2-x86_64-install-service"
]
```
POST - Create the osimage resources base on the parameters specified in the Data body.

Refer to the man page: copycds

Parameters:

- Json format: An object which includes multiple ‘attr:value’ pairs. DataBody:
  {iso:isodnamefile:filename.params:[{attr1:value1,attr2:value2}]}  

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: 
  {error:[msg1,msg2...],errocode:errno}.  

Example1:

Create osimage resources based on the ISO specified

```bash
curl -X POST -k 'https://127.0.0.1/xcatws/osimages?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"iso":="/iso/RHEL6.4-20130130.0-Server-ppc64-DVD1.iso"}''
```

Example2:

Create osimage resources based on an xCAT image or configuration file

```bash
curl -X POST -k 'https://127.0.0.1/xcatws/osimages?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"file":="/tmp/sles11.2-x86_64-install-compute.tgz"}''
```

[URI:/osimages/{imgname}] - The osimage resource

GET - Get all the attributes for the osimage {imgname}.

The keyword ALLRESOURCES can be used as {imgname} which means to get image attributes for all the osimages.

Refer to the man page: lsdef

Returns:

- Json format: An object which includes multiple ‘<name> : {att:value, attr:value ...}’ pairs.

Example:

Get the attributes for the specified osimage.

```bash
curl -X GET -k 'https://127.0.0.1/xcatws/osimages/sles11.2-x86_64-install-compute?userName=root&userPW=cluster&pretty=1' |  
"sles11.2-x86_64-install-compute":{  
  "provmethod":"install",  
  "profile":"compute",  
  "template":"/opt/xcat/share/xcat/install/sles/compute.sles11.tmpl",  
  "pkglist":"/opt/xcat/share/xcat/install/sles/compute.sles11.pkglist",  
  "osvers":"sles11.2",  
  "osarch":"x86_64",  
  "osname":"Linux",  
  "imagetype":"linux",  
  "otherpkgdir": "/install/post/otherpkgs/sles11.2/x86_64",  
};
```

(continues on next page)
PUT - Change the attributes for the osimage \{imgname\}.

Refer to the man page: \textit{chdef}

Parameters:

- Json format: An object which includes multiple ‘att:value’ pairs. DataBody: \{attr1:v1,attr2:v2…\}

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: \{error:[msg1,msg2…],errocode:erronum\}.

Example:

Change the ‘osvers’ and ‘osarch’ attributes for the osimage.

```bash
curl -X PUT -k 'https://127.0.0.1/xcatws/osimages/sles11.2-ppc64-install-compute/?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{
  "osvers":"sles11.3","osarch":"x86_64"}'
```

POST - Create the osimage \{imgname\}.

Refer to the man page: \textit{mkdef}

Parameters:

- Json format: An object which includes multiple ‘att:value’ pairs. DataBody: \{attr1:v1,attr2:v2\}

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: \{error:[msg1,msg2…],errocode:erronum\}.

Example:

Create a osimage obj with the specified parameters.

```bash
curl -X POST -k 'https://127.0.0.1/xcatws/osimages/sles11.3-ppc64-install-compute/?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{
  "osvers":"sles11.3","osarch":"ppc64","osname":"Linux","provmethod":"install",
  "profile":"compute"'}
```

DELETE - Remove the osimage \{imgname\}.

Refer to the man page: \textit{rmdef}

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: \{error:[msg1,msg2…],errocode:erronum\}.
Example:
Delete the specified osimage.

```
curl -X DELETE -k 'https://127.0.0.1/xcatws/osimages/sles11.3-ppc64-install-compute?userName=root&userPW=cluster&pretty=1'
```

**[URI:/osimages/{imgname}/attrs/attr1,attr2,attr3 ...] - The attributes resource for the osimage {imgname}**

**GET - Get the specific attributes for the osimage {imgname}**.

The keyword ALLRESOURCES can be used as {imgname} which means to get image attributes for all the osimages.

Refer to the man page: *lsdef*

**Returns:**
- Json format: An array of attr:value pairs for the specified osimage.

**Example:**
Get the specified attributes.

```
curl -X GET -k 'https://127.0.0.1/xcatws/osimages/sles11.2-ppc64-install-compute/attrs/imagetype,osarch,osname,provmethod?userName=root&userPW=cluster&pretty=1'
```

```
{
   "sles11.2-ppc64-install-compute":{
      "provmethod":"install",
      "osname":"Linux",
      "osarch":"ppc64",
      "imagetype":"linux"
   }
}
```

**[URI:/osimages/{imgname}/instance] - The instance for the osimage {imgname}**

**POST - Operate the instance of the osimage {imgname}**.

Refer to the man page: :doc:` </guides/admin-guides/references/>`

**Parameters:**
- Json format: An object which includes multiple ‘att:value’ pairs. DataBody: {action:genpackexport,params:[{attr1:value1,attr2:value2...}]}

**Returns:**
- No output when execution is successful. Otherwise output the error information in the Standard Error Format: {error:[msg1,msg2...],errocode:errornum}.

**Example:**
Generates a stateless image based on the specified osimage

```
curl -X POST -k 'https://127.0.0.1/xcatws/osimages/sles11.2-x86_64-install-compute/instance?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"action":"gen"}'
```
Example 2:
Packs the stateless image from the chroot file system based on the specified osimage

```
curl -X POST -k 'https://127.0.0.1/xcatws/osimages/sles11.2-x86_64-install-compute/instance?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"action": "pack"}'
```

Example 3:
Exports an xCAT image based on the specified osimage

```
curl -X POST -k 'https://127.0.0.1/xcatws/osimages/sles11.2-x86_64-install-compute/instance?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"action": "export"}'
```

DELETE - Delete the stateless or statelite image instance for the osimage {imgname} from the file system

Refer to the man page: `rmimage`

**Returns:**
- No output when execution is successful. Otherwise output the error information in the Standard Error Format: `{error: [msg1, msg2, ...], errocode: errornum}`.

Example:
Delete the stateless image for the specified osimage

```
curl -X DELETE -k 'https://127.0.0.1/xcatws/osimages/sles11.2-x86_64-install-compute/instance?userName=root&userPW=cluster&pretty=1'
```

Network Resources

The URI list which can be used to create, query, change and manage network objects.

**[URI:/networks] - The network list resource.**

This resource can be used to display all the networks which have been defined in the xCAT database.

**GET - Get all the networks in xCAT.**

The attributes details for the networks will not be displayed.

Refer to the man page: `lsdef`

**Returns:**
- Json format: An array of networks names.

Example:
Get all the networks names from xCAT database.
POST - Create the networks resources base on the network configuration on xCAT MN.

Refer to the man page: `makenetworks`

**Parameters:**
- JSON format: An object which includes multiple `att:value` pairs. DataBody: `{attr1:v1,att2:v2,...}`.

**Returns:**
- No output when execution is successful. Otherwise output the error information in the Standard Error Format: `{error:[msg1,msg2,...],errocode:errno}`.

**Example:**
Create the networks resources base on the network configuration on xCAT MN.

```bash
curl -X POST -k 'https://127.0.0.1/xcatws/networks?userName=root&userPW=cluster&pretty=1'
```

**[URL:/networks/{netname}] - The network resource**

**GET - Get all the attributes for the network `{netname}`.**

The keyword ALLRESOURCES can be used as `{netname}` which means to get network attributes for all the networks.

Refer to the man page: `lsdef`

**Returns:**
- JSON format: An object which includes multiple `<name> : {att:value, attr:value ...}` pairs.

**Example:**
Get all the attributes for network ‘network1’.

```bash
curl -X GET -k 'https://127.0.0.1/xcatws/networks/network1?userName=root&userPW=cluster&pretty=1'
```

```json
{
    "network1":{
        "gateway": "<xcatmaster>",
        "mask": "255.255.255.0",
        "mgtifname": "eth2",
        "net": "10.0.0.0",
        "tftpserver": "10.0.0.119",
        ...
    }
}
```
PUT - Change the attributes for the network {netname}.

Refer to the man page: `chdef`

Parameters:


Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: `{error:[msg1,msg2...],errocode:errornum}`.

Example:

Change the attributes mgtifname=eth0 and net=10.1.0.0.

```
curl -X PUT -k 'https://127.0.0.1/xcatws/networks/network1?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"mgtifname":"eth0","net":"10.1.0.0"}''
```

POST - Create the network {netname}. DataBody: `{attr1:v1,att2:v2...}`.

Refer to the man page: `mkdef`

Parameters:


Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: `{error:[msg1,msg2...],errocode:errornum}`.

Example:

Create a network with attributes gateway=10.1.0.1, mask=255.255.0.0

```
curl -X POST -k 'https://127.0.0.1/xcatws/networks/network1?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"gateway":"10.1.0.1","mask":"255.255.0.0"}''
```

DELETE - Remove the network {netname}.

Refer to the man page: `rmdef`

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: `{error:[msg1,msg2...],errocode:errornum}`.

Example:

Delete the network network1

```
curl -X DELETE -k 'https://127.0.0.1/xcatws/networks/network1?userName=root&userPW=cluster&pretty=1'`
```

1.4. Advanced Topics
[URI:/networks/{netname}/attrs/attr1,attr2, ...] - The attributes resource for the network {netname}.

GET - Get the specific attributes for the network {netname}.

The keyword ALLRESOURCES can be used as {netname} which means to get network attributes for all the networks. Refer to the man page: *lsdef*

Returns:

- Json format: An object which includes multiple `<name> : {att:value, attr:value ... }` pairs.

Example:

Get the attributes {groups,mgt,netboot} for network network1

```
curl -X GET -k 'https://127.0.0.1/xcatws/networks/network1/attrs/gateway,mask,mgtifname,net,tftpserver?userName=root&userPW=cluster&pretty=1'
```

```
{
   "network1":{
      "gateway":"9.114.34.254",
      "mask":"255.255.255.0",
    }
```

Policy Resources

The URI list which can be used to create, query, change and manage policy entries.

[URI:/policy] - The policy resource.

GET - Get all the policies in xCAT.

It will display all the policy resource. Refer to the man page: *lsdef*

Returns:

- Json format: An object which includes multiple `<name> : {att:value, attr:value ... }` pairs.

Example:

Get all the policy objects.

```
curl -X GET -k 'https://127.0.0.1/xcatws/policy?userName=root&userPW=cluster&pretty=1'
```

```
[
   "1",
   "1.2",
   "2",
   "4.8"
]
```
[URI:/policy/{policy_priority}] - The policy resource

GET - Get all the attributes for a policy {policy_priority}.

It will display all the policy attributes for one policy resource.
The keyword ALLRESOURCES can be used as {policy_priority} which means to get policy attributes for all the policies.
Refer to the man page: lsdef

Returns:
• Json format: An object which includes multiple ‘<name> : {att:value, attr:value ... }’ pairs.

Example:
Get all the attribute for policy 1.

curl -X GET -k 'https://127.0.0.1/xcatws/policy/1?userName=root&userPW=cluster&pretty=1'
{
  "1":{
    "name":"root",
    "rule":"allow"
  }
}

PUT - Change the attributes for the policy {policy_priority}.

It will change one or more attributes for a policy.
Refer to the man page: chdef

Parameters:
• Json format: An object which includes multiple ‘att:value’ pairs. DataBody: {attr1:v1,att2:v2,...}.

Returns:
• No output when execution is successful. Otherwise output the error information in the Standard Error Format: {error:[msg1,msg2,...],errocode:errornum}.

Example:
Set the name attribute for policy 3.

curl -X PUT -k 'https://127.0.0.1/xcatws/policy/3?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"name":"root"}"

POST - Create the policy {policyname}. DataBody: {attr1:v1,att2:v2...}.

It will create a new policy resource.
Refer to the man page: chdef

Parameters:
• Json format: An object which includes multiple ‘att:value’ pairs. DataBody: {attr1:v1,att2:v2,...}.
Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: `{error:[msg1,msg2,...],errocode:errornum}`.

Example:
Create a new policy 10.

```
curl -X POST -k 'https://127.0.0.1/xcatws/policy/10?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"name":"root","commands":"rpower "}'
```

DELETE - Remove the policy `{policy_priority}`.

Remove one or more policy resource.
Refer to the man page: `rmdef`

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: `{error:[msg1,msg2,...],errocode:errornum}`.

Example:
Delete the policy 10.

```
curl -X DELETE -k 'https://127.0.0.1/xcatws/policy/10?userName=root&userPW=cluster&pretty=1'
```

`[URI:/policy/{policyname}/attrs/{attr1,attr2,attr3,...}]` - The attributes resource for the policy `{policy_priority}`

GET - Get the specific attributes for the policy `{policy_priority}`.

It will get one or more attributes of a policy.

The keyword ALLRESOURCES can be used as `{policy_priority}` which means to get policy attributes for all the policies.

Refer to the man page: `lsdef`

Returns:

- Json format: An object which includes multiple `<name> : {att:value, attr:value ...}` pairs.

Example:
Get the name and rule attributes for policy 1.

```
curl -X GET -k 'https://127.0.0.1/xcatws/policy/1/attrs/name,rule?userName=root&userPW=cluster&pretty=1'
{
   "1":{
      "name":"root",
      "rule":"allow"
   }
}
```
Group Resources

The URI list which can be used to create, query, change and manage group objects.

[URI:/groups] - The group list resource.

This resource can be used to display all the groups which have been defined in the xCAT database.

GET - Get all the groups in xCAT.

The attributes details for the group will not be displayed.

Refer to the man page: lsdef

Returns:
- Json format: An array of group names.

Example:
Get all the group names from xCAT database.

```
curl -X GET -k 'https://127.0.0.1/xcatws/groups?userName=root&userPW=cluster&pretty=1'
[
   "__mgmtnode",
   "all",
   "compute",
   "ipmi",
   "kvm",
]
```

[URI:/groups/{groupname}] - The group resource

GET - Get all the attributes for the group {groupname}.

Refer to the man page: lsdef

Returns:
- Json format: An object which includes multiple `<name> : {att:value, attr:value ... }` pairs.

Example:
Get all the attributes for group ‘all’.

```
curl -X GET -k 'https://127.0.0.1/xcatws/groups/all?userName=root&userPW=cluster&pretty=1'
{
   "all":{
      "members":"zxnode2,nodexxx,node1,node4"
   }
}
```
PUT - Change the attributes for the group {groupname}.

Refer to the man page: chdef

Parameters:

- Json format: An object which includes multiple ‘att:value’ pairs. DataBody: {attr1:v1,att2:v2,...}.

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: {error:[msg1,msg2,...],errocode:errornum}.

Example:

Change the attributes mgt=dfm and netboot=yaboot.

```
curl -X PUT -k 'https://127.0.0.1/xcatws/groups/all?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data ':{"mgt":"dfm","netboot":"yaboot"}'
```

[URI:/groups/{groupname}/attrs/{attr1,attr2,attr3 ...}] - The attributes resource for the group {groupname}

GET - Get the specific attributes for the group {groupname}.

Refer to the man page: lsdef

Returns:

- Json format: An object which includes multiple ‘<name> : {att:value, attr:value ...}’ pairs.

Example:

Get the attributes {mgt,netboot} for group all

```
curl -X GET -k 'https://127.0.0.1/xcatws/groups/all/attrs/mgt,netboot?userName=root&userPW=cluster&pretty=1'
```

```
{
  "all":{
    "netboot":"yaboot",
    "mgt":"dfm"
  }
}
```

Global Configuration Resources

The URI list which can be used to create, query, change global configuration.

[URI:/globalconf] - The global configuration resource.

This resource can be used to display all the global configuration which have been defined in the xCAT database.
GET - Get all the xCAT global configuration.

It will display all the global attributes.
Refer to the man page: *lsdef*

**Returns:**

- Json format: An object which includes multiple `<name> : {att:value, attr:value ... }` pairs.

**Example:**

Get all the global configuration

```
curl -X GET -k 'https://127.0.0.1/xcatws/globalconf?userName=root&userPW=cluster&pretty=1'
```

```
"clustersite":{
   "xcatconfdir": "/etc/xcat",
   "tftpdir": "/tftpboot",
   ...
  }
}
```

[URI:/globalconf/attrs/{attr1,attr2 ...}] - The specific global configuration resource.

GET - Get the specific configuration in global.

It will display one or more global attributes.
Refer to the man page: *lsdef*

**Returns:**

- Json format: An object which includes multiple `<name> : {att:value, attr:value ... }` pairs.

**Example:**

Get the ‘master’ and ‘domain’ configuration.

```
curl -X GET -k 'https://127.0.0.1/xcatws/globalconf/attrs/master,domain?userName=root&userPW=cluster&pretty=1'
```

```
"clustersite":{
   "domain": "cluster.com",
   "master": "192.168.1.15"
  }
}
```

PUT - Change the global attributes.

It can be used for changing/adding global attributes.
Refer to the man page: *chdef*

**Parameters:**

- Json format: An object which includes multiple ‘att:value’ pairs. DataBody: `{attr1:v1,att2:v2, ... }`
Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: 
  \{error:[msg1,msg2,...],errocode:errornum\}.

Example:

Change/Add the domain attribute.

```
curl -X PUT -k 'https://127.0.0.1/xcatws/globalconf/attrs/domain?userName=root&
  →userPW=cluster&pretty=1' -H Content-Type:application/json --data '{"domain":
  →"cluster.com"}'
```

**DELETE - Remove the site attributes.**

Used for fremove one or more global attributes.

Refer to the man page: *chdef*

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: 
  \{error:[msg1,msg2,...],errocode:errornum\}.

Example:

Remove the domain configure.

```
curl -X DELETE -k 'https://127.0.0.1/xcatws/globalconf/attrs/domain?userName=root&
  →userPW=cluster&pretty=1'
```

**Service Resources**

The URI list which can be used to manage the host, dns and dhcp services on xCAT MN.

[URI:/services/dns] - The dns service resource.

**POST - Initialize the dns service.**

Refer to the man page: *makedns*

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: 
  \{error:[msg1,msg2,...],errocode:errornum\}.

Example:

Initialize the dns service.

```
curl -X POST -k 'https://127.0.0.1/xcatws/services/dns?userName=root&userPW=cluster&
  →pretty=1'
```
[URI:/services/dhcp] - The dhcp service resource.

POST - Create the dhcpd.conf for all the networks which are defined in the xCAT Management Node.

Refer to the man page: \textit{makedhcp}

Returns:
\begin{itemize}
\item No output when execution is successful. Otherwise output the error information in the Standard Error Format:
\{error:\[msg1,msg2,…\],errocode:errornum\}.
\end{itemize}

Example:
Create the dhcpd.conf and restart the dhcpd.

\begin{verbatim}
curl -X POST -k 'https://127.0.0.1/xcatws/services/dhcp?userName=root&userPW=cluster&pretty=1'
\end{verbatim}

[URI:/services/host] - The hostname resource.

POST - Create the ip/hostname records for all the nodes to /etc/hosts.

Refer to the man page: \textit{makehosts}

Returns:
\begin{itemize}
\item No output when execution is successful. Otherwise output the error information in the Standard Error Format:
\{error:\[msg1,msg2,…\],errocode:errornum\}.
\end{itemize}

Example:
Create the ip/hostname records for all the nodes to /etc/hosts.

\begin{verbatim}
curl -X POST -k 'https://127.0.0.1/xcatws/services/host?userName=root&userPW=cluster&pretty=1'
\end{verbatim}

[URI:/services/slpnodes] - The nodes which support SLP in the xCAT cluster

GET - Get all the nodes which support slp protocol in the network.

Refer to the man page: \textit{lsslp}

Returns:
\begin{itemize}
\item Json format: An object which includes multiple ‘<name> : {att:value, attr:value …}’ pairs.
\end{itemize}

Example:
Get all the nodes which support slp in the network.

\begin{verbatim}
curl -X GET -k 'https://127.0.0.1/xcatws/services/slpnodes?userName=root&userPW=cluster&pretty=1'
\end{verbatim}

(continues on next page)
"serial":"100037A",
"mtm":"789392X",
"hwtype":"cmm",
"side":"2",
"objtype":"node",
"nodetype":"mp",
"groups":"cmm,all,cmm-zet",
"mgt":"blade",
"hidden":0,
},
...

[URI:/services/slpnodes/{CEC|FRAME|MM|IVM|RSA|HMC|CMM|IMM2|FSP...}] - The slp nodes with specific service type in the xCAT cluster

GET - Get all the nodes with specific slp service type in the network.

Refer to the man page: lsslp

Returns:
  • Json format: An object which includes multiple `<name> : {att:value, attr:value ... }` pairs.

Example:
Get all the CMM nodes which support slp in the network.

```
curl -X GET -k 'https://127.0.0.1/xcatws/services/slpnodes/CMM?userName=root&userPW=cluster&pretty=1'
{
  "ngpcmm01":{
    "mpa":"ngpcmm01",
    "otherinterfaces":"10.1.9.101",
    "serial":"100037A",
    "mtm":"789392X",
    "hwtype":"cmm",
    "side":2,
    "objtype":"node",
    "nodetype":"mp",
    "groups":"cmm,all,cmm-zet",
    "mgt":"blade",
    "hidden":0,
  },
  "Server--SNY014BG27A01K":{
    "mpa":"Server--SNY014BG27A01K",
    "otherinterfaces":"10.1.9.106",
    "serial":"100CF0A",
    "mtm":"789392X",
    "hwtype":"cmm",
    "side":1,
    "objtype":"node",
    "nodetype":"mp",
    "groups":"cmm,all,cmm-zet",
```
Table Resources

URI list which can be used to create, query, change table entries.

[URI:/tables/{tablelist}/nodes/{noderange}] - The node table resource

For a large number of nodes, this API call can be faster than using the corresponding nodes resource. The disadvantage is that you need to know the table names the attributes are stored in.

GET - Get attributes of tables for a noderange.

Returns:
- An object containing each table. Within each table object is an array of node objects containing the attributes.

Example1:
Get all the columns from table nodetype for node1 and node2.

curl -X GET -k 'https://127.0.0.1/xcatws/tables/nodetype/nodes/node1,node2?userName=root&userPW=cluster&pretty=1'

Example2:
Get all the columns from tables nodetype and noderes for node1 and node2.

curl -X GET -k 'https://127.0.0.1/xcatws/tables/nodetype,noderes/nodes/node1,node2?userName=root&userPW=cluster&pretty=1'

(continues on next page)
"noderes": [
    {
        "installnic": "mac",
        "netboot": "xnba",
        "name": "node1",
        "nfsserver": "192.168.1.15"
    },
    {
        "installnic": "mac",
        "netboot": "pxe",
        "name": "node2",
        "proxydhcp": "no"
    }
],

"nodetype": [
    {
        "provmethod": "rhels6.4-x86_64-install-compute",
        "profile": "compute",
        "arch": "x86_64",
        "name": "node1",
        "os": "rhels6.4"
    },
    {
        "provmethod": "rhels6.3-x86_64-install-compute",
        "profile": "compute",
        "arch": "x86_64",
        "name": "node2",
        "os": "rhels6.3"
    }
]}

PUT - Change the node table attributes for {noderange}.

Parameters:

- A hash of table names and attribute objects. DataBody: {table1:{attr1:v1,attr2:v2,...}}.

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: {error:[msg1,msg2,...],errocode:erronum}.

Example:

Change the nodetype.arch and noderes.netboot attributes for nodes node1,node2.

curl -X PUT -k 'https://127.0.0.1/xcatws/tables/nodetype,noderes/nodes/node1,node2?userName=root&userPW=cluster&pretty=1' -H Content-Type:application/json --data '{
    "nodetype": {"arch": "x86_64"},
    "noderes": {"netboot": "xnba"}
}'

[URI:/tables/{tablelist}/nodes/nodes/{noderange}/{attrlist}] - The node table attributes resource

For a large number of nodes, this API call can be faster than using the corresponding nodes resource. The disadvantage is that you need to know the table names the attributes are stored in.
GET - Get table attributes for a noderange.

Returns:
- An object containing each table. Within each table object is an array of node objects containing the attributes.

Example:
Get OS and ARCH attributes from nodetype table for node1 and node2.

```bash
curl -X GET -k 'https://127.0.0.1/xcatws/tables/nodetype/nodes/node1,node2/os,arch?userName=root&userPW=cluster&pretty=1'
```

```
{
  "nodetype": [
    {
      "arch": "x86_64",
      "name": "node1",
      "os": "rhels6.4"
    },
    {
      "arch": "x86_64",
      "name": "node2",
      "os": "rhels6.3"
    }
  ]
}
```

[URI:/tables/{tablelist}/rows] - The non-node table resource

Use this for tables that don’t have node name as the key of the table, for example: passwd, site, networks, policy, etc.

GET - Get all rows from non-node tables.

Returns:
- An object containing each table. Within each table object is an array of row objects containing the attributes.

Example:
Get all rows from networks table.

```bash
curl -X GET -k 'https://127.0.0.1/xcatws/tables/networks/rows?userName=root&userPW=cluster&pretty=1'
```

```
{
  "networks": [
    {
      "netname": "192.168.13.0-255.255.255.0",
      "gateway": "192.168.13.254",
      "staticrangeincrement": "1",
      "net": "192.168.13.0",
      "mask": "255.255.255.0"
    },
    {
      "netname": "192.168.12.0-255.255.255.0",
      "gateway": "192.168.12.254",
      "staticrangeincrement": "1"
    }
  ]
}
```
[URI:/tables/{tablelist}/rows/{keys}] - The non-node table rows resource

Use this for tables that don’t have node name as the key of the table, for example: passwd, site, networks, policy, etc. {keys} should be the name=value pairs which are used to search table. e.g. {keys} should be [net=192.168.1.0,mask=255.255.255.0] for networks table query since the net and mask are the keys of networks table.

GET - Get attributes for rows from non-node tables.

Returns:

- An object containing each table. Within each table object is an array of row objects containing the attributes.

Example:

Get rows from networks table where net=192.168.1.0,mask=255.255.255.0.

```bash
curl -X GET -k 'https://127.0.0.1/xcatws/tables/networks/rows/net=192.168.1.0,mask=255.255.255.0?userName=root&userPW=cluster&pretty=1'
```

PUT - Change the non-node table attributes for the row that matches the {keys}.

Parameters:

- A hash of attribute names and values. DataBody: {attr1:v1,att2:v2,...}.

Returns:

- No output when execution is successful. Otherwise output the error information in the Standard Error Format: {error:[msg1,msg2,...],errocode:errornum}.

Example:

Create a route row in the routes table.
DELETE - Delete rows from a non-node table that have the attribute values specified in {keys}.

Returns:
- No output when execution is successful. Otherwise output the error information in the Standard Error Format: 
  {error:[msg1,msg2...],errocode:erronum}.

Example:
Delete rows from routes table where routename=privnet.

curl -X DELETE -k 'https://127.0.0.1/xcatws/tables/routes/rows/routename=privnet?'

[URI:/tables/{tablelist}/rows/{keys}/{attrlist}] - The non-node table attributes resource

Use this for tables that don’t have node name as the key of the table, for example: passwd, site, networks, policy, etc.

GET - Get specific attributes for rows from non-node tables.

Returns:
- An object containing each table. Within each table object is an array of row objects containing the attributes.

Example:
Get attributes mgtifname and tftpserver from networks table for each row where
net=192.168.1.0,mask=255.255.255.0.

curl -X GET -k 'https://127.0.0.1/xcatws/tables/networks/rows/net=192.168.1.0,

1.4.19 Security

The security of a system covers a wide range of elements, from the security of system deployment and configuration, to
the security of the system management, and the security of the software that is running on the system. This document
will only discuss security features that are currently implemented in xCAT, not address the OS or any additional
software packages that might be installed.
OpenSSL Configuration

xCAT does not ship OpenSSL RPMS nor does it statically link to any OpenSSL libraries. Communication between the xCAT client and daemon utilizes OpenSSL and the administrator can configure SSL_version and SSL_cipher that should be used by xCAT daemons.

The configuration is stored in the xCAT site table using the `site.xcatsslversion` and `site.xcatsslciphers` variables.

Configuration

By default, xCAT ships with TLSv1 configured. The current highest SSL version that can be supported is TLSv1.2.

- For rhels7.x and sles12.x and higher:

  ```
  chtab key=xcatsslversion site.value=TLSv12
  ```

- For ubuntu 14.x and higher:

  ```
  chtab key=xcatsslversion site.value=TLSv1_2
  ```

- For AIX 7.1.3.x:

  ```
  chtab key=xcatsslversion site.value=TLSv1_2
  ```

If running > TLSv1, it is possible to disable insecure ciphers. Here’s an example of one possible configuration:

````
"xcatsslciphers","kDH:kEDH:kRSA:!SSLv3:!SSLv2:!aNULL:!eNULL:!MEDIUM:!LOW:!MD5:!EXPORT:!CAMELLIA:!ECDH",,
```

After making any changes to these configuration values, `xcatd` must be restarted:

```
service restart xcatd
```

If any mistakes have been made and communication is lost to xCAT, use `XCATBYPASS` to fix/remove the bad configuration:

```
XCATBYPASS=1 tabedit site
```

Validation

Use the `openssl` command to validate the SSL configuration is valid and expected.

- To check whether TLSv1 is supported by xcatd:

  ```
  openssl s_client -connect 127.0.0.1:3001 -tls1
  ```

- To check if SSLv3 is disabled on xcatd:

  ```
  openssl s_client -connect localhost:3001 -ssl3
  ```

You should get a response similar to:
Transmission Channel

The xCAT daemon uses SSL to only allow authorized users to run xCAT commands. All xCAT commands are initiated as an xCAT client, even when run commands from the xCAT management node. This client opens an SSL socket to the xCAT daemon, sends the command and receives responses through this one socket. xCAT has configured the certificate for root, if you nee to authorize other users, refer to the section below.

The SSL Certificates in xCAT

The xCAT daemon on the management node and service node listens on a SSL socket on port 3001, the communications on the SSL socket include:

1. the xCAT requests from xCAT Clients
2. the xCAT requests forwarded from other xCAT daemons, for example, the requests forwarded between xCAT daemons on management node and service nodes
3. some special xCAT requests from compute nodes, such as getcredentials, getpostscript, litefile, etc.

xCAT creates 1 CA certificate and 2 credentials (private key and certificate pairs):

1. xCAT CA certificate(ca.pem):
   • a self-signed certificate used as Certificate Authority in xcatd SSL communication;
   • generated by /opt/xcat/share/xcat/scripts/setup-xcat-ca.sh script on xCAT installation;
   • will be generated (or updated) on xCAT management node when:
     – install or update xCAT when “/etc/xcat/ca” directory does not exist
     – or run xcatconfig -f|--force
     – or run xcatconfig -c|--credentials
   • files on management node:
     – /etc/xcat/ca/ca-cert.pem
     – /etc/xcat/cert/ca.pem ,copied by /opt/xcat/share/xcat/scripts/setup-server-cert.sh
     – /root/.xcat/ca.pem ,copied by /opt/xcat/share/xcat/scripts/setup-local-client.sh
   • file on service node: /root/.xcat/ca.pem
   • distribution path: /etc/xcat/cert/ca.pem (MN) ===(run xcatconfig command)=== > /install/postscripts/_xcat/ca.pem (MN) ===(node provision/updatenode)=== > /xcatpost/_xcat/ca.pem (SN and CN) ===(run “servicenode” postscript)=== > /root/.xcat/ca.pem (SN)

2. xCAT server credential(server-cred.pem):
   • a concatenation of server private key and certificate(signed with xCAT CA certificate)
• generated by /opt/xcat/share/xcat/scripts/setup-server-cert.sh on xCAT installation;

• will be generated (or updated) on xCAT management node when:
  – install or update xCAT when /etc/xcat/cert directory does not exist
  – or run xcatconfig -f|--force
  – or run xcatconfig -c|--credentials

• file on management node: /etc/xcat/cert/server-cred.pem
• file on service node: /etc/xcat/cert/server-cred.pem
• distribution path: /etc/xcat/cert/server-cred.pem (MN) ==(run xcatserver script called by servicenode postscript)===>/etc/xcat/cert/server-cred.pem(SN)

3. xCAT client credential(client-cred.pem):
• a concatenation of client private key and certificate (signed with xCAT CA certificate)

• generated by /opt/xcat/share/xcat/scripts/setup-local-client.sh on xCAT installation

• will be generated (or updated) on xCAT management node when:
  – install or update xCAT when /root/.xcat/client-key.pem does not exist;
  – or run xcatconfig -f|--force
  – or run xcatconfig -c|--credentials

• file on management node: /root/.xcat/client-cred.pem
• file on service node: /root/.xcat/client-cred.pem
• distribution path: /root/.xcat/client-cred.pem (MN) ==(run xcatclient script called by servicenode postscript")===>/root/.xcat/client-cred.pem(SN)

The usage of the credentials in the xCAT SSL communication is:
Commands Access Control

Except SSL channel, xCAT only authorize root on the management node to run xCAT commands by default. But xCAT can be configured to allow both non-root users and remote users to run limited xCAT commands. For remote users, we mean the users who triggers the xCAT commands from other nodes and not have to login to the management node. xCAT uses the policy table to control who has authority to run specific xCAT commands. For a full explanation of the policy table, refer to policy man page.

Granting Users xCAT Privileges

To give a non-root user all xCAT command privileges, run `tabedit policy` and add a line:

```
"6","<username>",,,,,,,,"allow",,
```

Where `<username>` is the name of the user that you are granting privileges to. This user can now perform all xCAT commands, including changing the policy table to grant rights to other users, so this should be used with caution.

To grant a user ability to run `nodels` command:

```
"6","<username>",,,,,,,,"nodels",,,"allow",,
```
To grant all users the ability to run `nodels`:

```
"6.1","*","nodels",,"allow",,
```

CLI can also be used:

```
chdef -t policy -o 6.1 name=\* commands=nodels rule=allow
```

**Note** Make sure the directories that contain the xCAT commands are in the user’s `$PATH`. If not, add them to `$PATH` as appropriate in your system.

```
echo $PATH | grep xcat
/opt/xcat/bin:/opt/xcat/sbin: ........
```

**Extra Setup for Remote Commands**

To give a user the ability to run remote commands (`xdsh, xdcp, psh, pcp`) in some node, in addition to above steps, also need to run below steps:

```
su - <username>
xdsh <noderange> -K
```

This will setup the user and root ssh keys for the user under the `$HOME/.ssh` directory of the user on the nodes. The root ssh keys are needed for the user to run the xCAT commands under the xcatd daemon, where the user will be running as root. **Note:** the uid and the password for the user on the management node, should match the uid and password on the managed nodes.

**Set Up Login Node (Remote Client)**

In some cases, you don’t want your non-root user login to management node but still can run some xCAT commands. This time, you need setup a login node (i.e. remote client) for these users.

Below are the steps of how to set up a login node.

1. Install the xCAT client

   In order to avoid dependency problems on different distros, we recommend creating repository first by referring to links below.

   - Configure xCAT Software Repository in RHEL
   - Configure the Base OS Repository in SUSE
   - Configure the Base OS Repository in Ubuntu

   Then install xCAT-client.

   **[RHEL]**

   ```
yum install xCAT-client
   ```

   **[SUSE]**

   ```
zypper install xCAT-client
   ```

   **[Ubuntu]**
apt-get install xCAT-client

2. Configure login node

When running on the login node, the environment variable `XCATHOST` must be export to the name or address of the management node and the port for connections (usually 3001).

`export XCATHOST=<myManagementServer>:3001`

Using below command to add xCAT commands to your path.

`source /etc/profile.d/xcat.sh`

The userids and groupids of the non-root users should be kept the same on the login node, the management node, service nodes and compute nodes.

The remote not-root user still needs to set up the credentials for communication with management node. By running the `/opt/xcat/share/xcat/scripts/setup-local-client.sh <username>` command as root in management node, the credentials are generated in `<username>`’s `$HOME/.xcat` directory in management node. These credential files must be copied to the `<username>`’s `$HOME/.xcat` directory on the login node. **Note:** After scp, in the login node, you must make sure the owner of the credentials is `<username>`.

Setup your policy table on the management node with the permissions that you would like the non-root id to have.

At this time, the non-root id should be able to execute any commands that have been set in the policy table from the Login Node.

If any remote shell commands (psh,xdsh) are needed, then you need to follow *Extra Setup For Remote Commands*.

**Auditing**

xCAT logs all xCAT commands run by the xcatd daemon to both the syslog and the auditlog table in the xCAT database. The commands that are audited can be “ALL” xCAT commands or a list provided by the admin. The auditlog table allows the admin to monitor any attacks against the system or simply over use of resources. The auditlog table is store in the xCAT database and contains the following record.

```
# tabdump -d auditlog
recid: The record id.
audittime: The timestamp for the audit entry.
userid: The user running the command.
clientname: The client machine, where the command originated.
clienttype: Type of command: cli,java,webui,other.
command: Command executed.
noderange: The noderange on which the command was run.
args: The command argument list.
status: Allowed or Denied.
comments: Any user-provided notes.
disable: Do not use. tabprune will not work if set to yes or 1
```

**Password Management**

xCAT is required to store passwords for various logons so that the application can login to the devices without having to prompt for a password. The issue is how to securely store these passwords.
Currently xCAT stores passwords in passwd table. You can store them as plain text, you can also store them as MD5 ciphertext.

Here is an example about how to store a MD5 encrypted password for root in passwd table.

```
tabch key=sys passwd.username=root passwd.password=`openSSL passwd -1 <password>`
```

During the provisioning, the root password will be set on the compute nodes. By default, xCAT stores the encrypted hash of password into installation files directly for better performance.

For example, /etc/shadow in stateless image for stateless nodes or installation files (/install/autoinst/ <node>) for stateful nodes.

You can enable secureroot feature for more secure consideration.

```
chdef -t site secureroot=1
```

Then, after the new packimage or nodeset command, the root password hash can only be acquired on-the-fly with strict security control.

### Nodes Inter-Access in The Cluster

xCAT performs the setup for root to be able to ssh without password from the Management Node(MN) to all the nodes in the cluster. All nodes are able to ssh to each other without password or being prompted for a known_host entry, unless restricted. Nodes cannot ssh back to the Management Node or Service Nodes without a password by default.

xCAT generates, on the MN, a new set of ssh hostkeys for the nodes to share, which are distributed to all the nodes during install. If ssh keys do not already exist for root on the MN, it will generate an id_rsa public and private key pair.

During node install, xCAT sends the ssh hostkeys to /etc/ssh on the node, the id_rsa private key and authorized_keys file to root’s .ssh directory on the node to allow root on the MN to ssh to the nodes without password. This key setup on the node allows the MN to ssh to the node with no password prompting.

On the MN and the nodes, xCAT sets the ssh configuration file to strictHostKeyChecking no, so that a known_host file does not have to be built in advanced. Each node can ssh to every other cluster node without being prompted for a password, and because they share the same ssh host keys there will be no prompting to add entries to known_hosts.

On the MN, you will be prompted to add entries to known_hosts file for each node once. See makeknownhosts command for a quick way to build a known_hosts file on the MN, if your nodes are defined in the xCAT database.

### Restricting Node to Node SSH

By default, all nodes installed by one management node are able to ssh to each without password. But there is an attribute sshbetweengroups in site table. This attributes defaults to ALLGROUPS, which means we setup ssh between all nodes during the install or when you run xdsh -K, or updatenode -k as in the past. This attribute can be used to define a comma-separated list of groups and only the nodes in those groups will be setup with ssh between the nodes. The attribute can be set to NOGROUPS, to indicate no nodes (groups) will be setup. Service Nodes will always be setup with ssh between service nodes and all nodes. It is unaffected by this attribute. This also only affects root userid setup and does not affect the setup of devices.

This setting of site.sshbetweengroups will only enable root ssh between nodes of the compute1 and compute 2 groups and all service nodes.

```
"sshbetweengroups","compute1,compute2","
```
Secure Zones

You can set up multiple zones in an xCAT cluster. A node in the zone can ssh without password to any other node in the zone, but not to nodes in other zones. Refer to Zones for more information.

1.4.20 Performance Tuning

xCAT supports clusters of all sizes. This document is a collection of hints, tips, and special considerations when working with large clusters, especially a single server (management node or service node) manages more than 128 nodes.

The information in this document should be viewed as example data only. Many of the suggestions are based on anecdotal experiences and may not apply to your particular environment. Suggestions in different sections of this document may recommend different or conflicting settings since they may have been provided by different people for different cluster environments. Often there is a significant amount of flexiblity in most of these settings – you will need to resolve these differences in a way that works best for your cluster.

System Tuning Settings for Linux

Adjusting Operating System tunables can improve large scale cluster performance, avoid bottlenecks, and prevent failures. The following sections are a collection of suggestions that have been gathered from various large scale HPC clusters. You should investigate and evaluate the validity of each suggestion before applying them to your cluster.

1. Tuning Linux ulimits:

The open file limits are important to high concurrence network services, such as xcatd. For a large cluster, it is required to increase the number of open file limit to avoid Too many open files error. The default value is 1024 in most OS distributions, to add below configuration in /etc/security/limits.conf to increase to 14096.

```
* soft nofile 14096
* hard nofile 14096
```

2. Tuning Network kernel parameters:

There might be hundreds of hosts in a big network for large cluster, tuning the network kernel parameters for optimum throughput and latency could improve the performance of distributed application. For example, adding below configuration in /etc/sysct1.conf to increase the buffer size and queue length of xCAT SSL listener service access point (port 3001).

```
net.core.rmem_max = 33554432
net.core.wmem_max = 33554432
net.core.rmem_default = 65536
net.core.wmem_default = 65536
net.core.somaxconn = 8192
net.ipv4.tcp_rmem = 4096 33554432 33554432
net.ipv4.tcp_wmem = 4096 33554432 33554432
net.ipv4.tcp_mem= 33554432 33554432 33554432
net.ipv4.route.flush=1
net.core.netdev_max_backlog=1500
```

And if you encounter Neighbour table overflow error, it means there are two many ARP requests and the server cannot reply. Tune the ARP cache with below parameters.
Tuning xCAT Daemon Attributes

For large clusters, you consider changing the default settings in site table to improve the performance on a large-scale cluster or if you are experiencing timeouts or failures in these areas:

consoleondemand: When set to yes, conserver connects and creates the console output for a node only when the user explicitly opens the console using rcons or wcons. Default is no on Linux, yes on AIX. Setting this to yes can reduce the load conserver places on your xCAT management node. If you need this setup, you may then need to consider setting up multiple servers to run the conserver daemon, and specify the correct server on a per-node basis by setting each node’s conserver attribute.

nodestatus: If set to n, the nodelist.status column will not be updated during the node deployment, node discovery and power operations. Default is y, always update nodelist.status. Setting this to n for large clusters can eliminate one node-to-server contact and one xCAT database write operation for each node during node deployment, but you will then need to determine deployment status through some other means.

precreatemypostscripts: (yes/1 or no/0, only for Linux). Default is no. If yes, it will instruct xcat at nodeset and updatenode time to query the database once for all of the nodes passed into the command and create the mypostscript file for each node, and put them in a directory in site.tftpdir (such as: /tftpboot). This prevents xcatd from having to create the mypostscript files one at a time when each deploying node contacts it, so it will speed up the deployment process. (But it means that if you change database values for these nodes, you must rerun nodeset.) If precreatemypostscripts is set to no, the mypostscript files will not be generated ahead of time. Instead they will be generated when each node is deployed.

tvloglocal: if set to 1, syslog on the service node will not get forwarded to the mgmt node. The default is to forward all syslog messages. The tradeoff on setting this attribute is reducing network traffic and log size versus having local management node access to all system messages from across the cluster.

skiptables: a comma separated list of tables to be skipped by dumpxCATdb. A recommended setting is auditlog, eventlog because these tables can grow very large. Default is to skip no tables.

dhcplease: The lease time for the DHCP client. The default value is 43200.

xcatmaxconnections: Number of concurrent xCAT protocol requests before requests begin queueing. This applies to both client command requests and node requests, e.g. to get postscripts. Default is 64.

xcatmaxbatchconnections: Number of concurrent xCAT connections allowed from the nodes. Number must be less than xcatmaxconnections.

useflowcontrol: If yes, the postscript processing on each node contacts xcatd on the MN/SN using a lightweight UDP packet to wait until xcatd is ready to handle the requests associated with postscripts. This prevents deploying nodes from flooding xcatd and locking out admin interactive use. This value works with the xcatmaxconnections and xcatmaxbatch attributes. If the value is no, nodes sleep for a random time before contacting xcatd, and retry. The default is no. Not supported on AIX.

These attributes may be changed based on the size of your cluster. For a large cluster, it is better to enable useflowcontrol and set xcatmaxconnection = 356, xcatmaxbatchconnections = 300. Then the daemon will only allow 300 concurrent connections from the nodes. This will allow 56 connections still to be available on the management node for xCAT commands (e.g nodels).
Tuning the Database Server

1. MariaDB database

MariaDB: Tuning Server Parameters

According to this documentation, the two most important variables to configure are `key_buffer_size` and `table_open_cache`.

2. PostgreSQL database

PostgreSQL: Server Configuration

Tuning httpd for xCAT node deployments

In xCAT, the Operation System provisioning over network is heavily relying on the web server (Apache 2.x). However, Apache 2.x is a general-purpose web server, the default settings may not allow enough simultaneous HTTP client connections to support a large cluster.

1. Tuning MaxRequestWorkers directive

By default, httpd is configured to use `prefork` module for MPM, which has a limit of 256 simultaneous requests. If any slow httpd response issue was hit during OS provisioning, you can increase `MaxRequestWorkers` directive for greater performance.

For example, to avoid some nodes provisioning failure when rebooting all nodes in a large hierarchy stateless cluster (one service node is serving 270 compute nodes). It is suggested to increased the value from 256 to 1000.

On Red Hat, change (or add) these directives in:

```
/etc/httpd/conf/httpd.conf
```

On SLES (with Apache2), change (or add) these directives in:

```
/etc/apache2/server-tuning.conf
```

1. Having httpd Cache the Files It Is Serving

Note: this information was contributed by Jonathan Dye and is provided here as an example. The details may have to be changed for distro or apache version.

This is simplest if you set `noderes.nfsserver` to a separate apache server, and then you can configure it to reverse proxy and cache. For some reason `mod_mem_cache` doesn’t seem to behave as expected, so you can use `mod_disk_cache` to achieve a similar result: make a tmpfs on the apache server and configure its mountpoint to be the directory that CacheRoot points to. Also tell it to ignore `/install/autoinst` since the caching settings are really aggressive. Do a recursive wget to warm the cache and watch the tmpfs fill up. Then do a bunch of kickstart installs. Before this, the apache server on the xcat management node may have been a bottleneck during kickstart installs. After this change, it no longer should be.

Here is the apache config file:

```
ProxyRequests Off # don't be a proxy, just allow the reverse proxy
CacheIgnoreCacheControl On
CacheStoreNoStore On
CacheIgnoreNoLastMod On
CacheRoot /var/cache/apache2/tmpfs
CacheEnable disk /install
```

(continues on next page)
CacheDisable /install/autoinst
CacheMaxFileSize 1073741824

# CacheEnable mem /               # failed attempt to do in-memory caching
# MCacheSize 20971520
# MCacheMaxObjectSize 524288000

# through ethernet network
# ProxyPass /install http://172.21.254.201/install

# through IB network
ProxyPass /install http://192.168.111.2/install

For more Apache 2.x tuning, see the external web page: Apache Performance Tuning

1.4.21 SoftLayer

Using xCAT in SoftLayer

1.4.22 System Clone (sysclone)

Using System Clone to Deploy Diskful Node

When we want to deploy large numbers of nodes which have the same configuration, the simplest way is to clone. This means the user can customize and tweak one node’s configuration according to his needs. They can verify it’s proper operation, then make this node as template. They can capture an osimage from this template node, and deploy the rest of the nodes with this osimage quickly. xCat (2.8.2 and above) provides this feature which we call Sysclone to help you handle this scenario.

List of Supported Arch and OS

<table>
<thead>
<tr>
<th>xCAT version</th>
<th>OS</th>
<th>Tested Version</th>
<th>ARCH</th>
<th>Feature</th>
</tr>
</thead>
<tbody>
<tr>
<td>2.8.2 and later</td>
<td>CentOS</td>
<td>6.3 5.9</td>
<td>x86_64</td>
<td>Basic clone node</td>
</tr>
<tr>
<td></td>
<td>RHEL</td>
<td>6.4 5.9</td>
<td>x86_64</td>
<td>Basic clone node</td>
</tr>
<tr>
<td>2.8.3 and later</td>
<td>SLES</td>
<td>11.3 10.4</td>
<td>x86_64</td>
<td>Basic clone node</td>
</tr>
<tr>
<td>2.8.5 and later</td>
<td>CentOS</td>
<td>6.3</td>
<td>x86_64</td>
<td>Add feature: update delta changes(has limitation)</td>
</tr>
<tr>
<td></td>
<td>RHEL</td>
<td>6.4</td>
<td>x86_64</td>
<td>Add feature: update delta changes(has limitation)</td>
</tr>
<tr>
<td></td>
<td>SLES</td>
<td>11.3</td>
<td>x86_64</td>
<td>Add feature: update delta changes</td>
</tr>
<tr>
<td></td>
<td>SLES</td>
<td>10.x</td>
<td>x86_64</td>
<td>Not support any more</td>
</tr>
<tr>
<td>2.9 and later</td>
<td>RHEL</td>
<td>6.4</td>
<td>ppc64</td>
<td>Basic clone node/update delta changes/LVM</td>
</tr>
<tr>
<td></td>
<td>SLES</td>
<td>11.3</td>
<td>ppc64</td>
<td>Basic clone node/update delta changes</td>
</tr>
<tr>
<td></td>
<td>RHEL</td>
<td>7.0</td>
<td>ppc64</td>
<td>Basic clone node/update delta changes/LVM</td>
</tr>
<tr>
<td></td>
<td>RHEL</td>
<td>6.4 7.0</td>
<td>x86_64</td>
<td>support LVM</td>
</tr>
</tbody>
</table>

Using Sysclone to Install Nodes

This document describes how to install and configure a template node (called golden client), capture an image from this template node, then using this image to deploy other nodes (called target nodes) quickly.
Prepare the xCAT Management Node for Support Sysclone

To configure xCAT management node refer to section **Install Guides**

To support Sysclone, we need to install some extra rpms on management node and the golden client.

1. Download the xcat-dep tarball (xcat-dep-XXX.tar.bz2) which includes extra rpms needed by Sysclone. (You might already have the xcat-dep tarball on management node. If not, go to xcat-dep and get the latest xCAT dependency tarball.)

2. Install systemimager server on management node

   - **[RH/CentOS]**:
     
     ```bash
     yum -y install systemimager-server
     ```

   - **[SLES]**:

     ```bash
     zypper -n install systemimager-server
     ```

   **[Note]** You may ignore the following messages when installing systemimager-server:

   ```bash
   BEGIN failed--compilation aborted at /usr/lib/systemimager/perl/SystemImager/Config.pm line 13.
   Compilation failed in require at /usr/lib/systemimager/perl/SystemImager/Server.pm line 17.
   BEGIN failed--compilation aborted at /usr/lib/systemimager/perl/SystemImager/Server.pm line 17.
   Compilation failed in require at /usr/sbin/si_mkrsyncd_conf line 28.
   BEGIN failed--compilation aborted at /usr/sbin/si_mkrsyncd_conf line 28.
   ```

3. Copy the xcat-dep-XXX.tar.bz2 file to directory `/install/post/otherpkgs/<os>/<arch>/xcat/` of the management node according your golden client’s OS version and system architecture, then decompress it:

   - **[CentOS6.3 and x86_64]**:

     ```bash
     mkdir -p /install/post/otherpkgs/CentOS6.3/x86_64/xcat
cp xcat-dep-*.tar.bz2 /install/post/otherpkgs/CentOS6.3/x86_64/xcat
cd /install/post/otherpkgs/CentOS6.3/x86_64/xcat
tar jxvf xcat-dep-*.tar.bz2
     ```

   - **[SLES11.3 and x86_64]**:

     ```bash
     mkdir -p /install/post/otherpkgs/SLES11.3/x86_64/xcat
cp xcat-dep-*.tar.bz2 /install/post/otherpkgs/SLES11.3/x86_64/xcat
cd /install/post/otherpkgs/SLES11.3/x86_64/xcat
tar jxvf xcat-dep-*.tar.bz2
     ```

   - **[RHEL6.4 and ppc64]**:

     ```bash
     mkdir -p /install/post/otherpkgs/rhels6.4/ppc64/xcat
cp xcat-dep-*.tar.bz2 /install/post/otherpkgs/rhels6.4/ppc64/xcat
cd /install/post/otherpkgs/rhels6.4/ppc64/xcat
tar jxvf xcat-dep-*.tar.bz2
     ```
Install and Configure the Golden Client

The Golden Client acts as a regular node for xCAT, it just has some extra rpms to support clone. When you deploy golden client with xCAT, you just need to add a few additional definitions to the image which will be used to deploy golden client.

For information of how to install a regular node, refer to section Diskful Installation

To support clone, add ‘otherpkglist’ and ‘otherpkgdir’ attributes to the image definition which will be used to deploy golden client, then deploy golden client as normal. Once deployed, the golden client will have extra rpms to support cloning. If you have deployed your golden client already, use updatenode command to push these extra rpms to golden client. CentOS shares the same pkglist file with RHEL. For example:

- **[RH6.4 and x86_64]:**

  ```bash
  chdef -t osimage -o <osimage-name> otherpkglist=/opt/xcat/share/xcat/install/rh/
  →sysclone.rhel6.x86_64.otherpkgs.pkglist
  chdef -t osimage -o <osimage-name> -p otherpkgdir=/install/post/otherpkgs/rhel6.
  →4/x86_64
  updatenode <golden-cilent> -S
  ```

- **[CentOS6.3 and x86_64]:**

  ```bash
  chdef -t osimage -o <osimage-name> otherpkglist=/opt/xcat/share/xcat/install/rh/
  →sysclone.rhel6.x86_64.otherpkgs.pkglist
  chdef -t osimage -o <osimage-name> -p otherpkgdir=/install/post/otherpkgs/CentOS6.
  →3/x86_64
  updatenode <golden-cilent> -S
  ```

- **[SLES11.3 and x86_64]:**

  ```bash
  chdef -t osimage -o <osimage-name> otherpkglist=/opt/xcat/share/xcat/install/sles/
  →sysclone.sles11.x86_64.otherpkgs.pkglist
  chdef -t osimage -o <osimage-name> -p otherpkgdir=/install/post/otherpkgs/SLES11.
  →3/x86_64
  updatenode <golden-cilent> -S
  ```

- **[RH6.3 and ppc64]:**

  ```bash
  chdef -t osimage -o <osimage-name> otherpkglist=/opt/xcat/share/xcat/install/rh/
  →sysclone.rhel6.ppc64.otherpkgs.pkglist
  chdef -t osimage -o <osimage-name> -p otherpkgdir=/install/post/otherpkgs/rhel6.
  →3/ppc64
  updatenode <golden-cilent> -S
  ```

**[Note]:** If you install systemimager RPMs on CentOS 6.5 node by above steps, you maybe hit a failure. This is a known issue with CentOS6.5. Refer to known issue section for help.

Capture Image from Golden Client

On Management node, use xCAT command `imgcapture` to capture an image from the golden-client.:

```bash
imgcapture <golden-client> -t sysclone -o <mycomputeimage>
```

When `imgcapture` is running, it pulls the image from the golden-client, and creates an image files system and a corresponding osimage definition on the xcat management node. You can use command below to check the osimage attributes.
lsdef -t osimage <mycomputeimage>

Install the target nodes with the image from the golden-client

To install the target nodes with the image captured from golden client.

- [x86_64]:

  nodeset <target-node> osimage=<mycomputeimage>
  rsetboot <target-node> net
  rpower <target-node> boot

- [ppc64]:

  nodeset <target-node> osimage=<mycomputeimage>
  rnetboot <target-node>

Update Nodes Later On

If, at a later time, you need to make changes to the golden client (install new rpms, change config files, etc.), you can capture the changes and push them to the already cloned nodes without a need to restart cloned nodes. This process will only transfer the deltas, so it will be much faster than the original cloning.

[Limitation]: In xcat2.8.5, this feature has limitation on RHEL and CentOS. When your delta changes related bootloader, it would encounter error. This issue will be fixed in xcat higher version. So up to now, in RHEL and CentOS, this feature just update files not related bootloader.

Update delta changes:
1. Make changes to your golden node (install new rpms, change config files, etc.).
2. From the mgmt node, capture the image using the same command as before. Assuming <myimagename> is an existing image, this will only sync the changes to the image on the Management node:

   imgcapture <golden-client> -t sysclone -o <myimagename>

3. To synchronize the changes to your target nodes do the following:
   1. If you are running xCAT 2.8.4 or older:

      From one of the nodes you want to update, test the update to see which files will be updated:

      xdsh <target-node> -s 'si_updateclient --server <mgmtnode-ip> --dry-run --yes'

      If it lists files and directories that you do not think should be updated, you need to add them to the exclude list in 3 places
      - On the golden node: /etc/systemimager/updateclient.local.exclude
      - On the mgmt node: /install/sysclone/images/<myimagename>/etc/systemimager/updateclient.local.exclude
      - On all of the nodes to be updated: /etc/systemimager/updateclient.local.exclude

      From the mgmt node, push the updates out to the other nodes:
2. If you are running xCAT 2.8.5 or later:
You could push the updates out to the other nodes quickly by below command:

```
updatenode <target-node-range> -S
```

**Known Issue**

**Can not install systemimager RPMs in CentOS6.5 by yum**

If you install systemimager RPMs on CentOS 6.5 node using `yum`, you may experience some problems due to CentOS6.5 itself. If that happens, copy related RPMs to CentOS 6.5 node and install them by hand.

- **On management node:**

```
[root@MN]# cd /<path-to-xcat-dep>/xcat-dep
[root@MN xcat-dep]# scp systemimager-client-4.3.0-0.1.noarch.rpm \
    systemconfigurator-2.2.11-1.noarch.rpm \
    systemimager-common-4.3.0-0.1.noarch.rpm \
    perl-AppConfig-1.52-4.noarch.rpm <CentOS-node-ip>:/
```

- **On golden client:**

```
[root@CentOS6.5 node]# cd /<savepath>
[root@CentOS6.5 node]# rpm -ivh perl-AppConfig-1.52-4.noarch.rpm
[root@CentOS6.5 node]# rpm -ivh systemconfigurator-2.2.11-1.noarch.rpm
[root@CentOS6.5 node]# rpm -ivh systemimager-common-4.3.0-0.1.noarch.rpm
[root@CentOS6.5 node]# rpm -ivh systemimager-client-4.3.0-0.1.noarch.rpm
```

**Kernel panic at times when install target node with rhels7.0 in Power 7 server**

When you clone rhels7.0 image to target node which is Power 7 server lpar, you may hit Kernel panic problem at times after boot loader grub2 download kernel and initrd. This is an known issue but without a resolution. For now, we recommend you try again.

**1.4.23 Zones**

**Overview**

XCAT supports the concept of zones within a single xCAT cluster managed by one Management Node. The nodes in the cluster can be divided up into multiple zones that have different ssh keys managed separately.

Each defined zone has its own root’s ssh RSA keys, so that any node can ssh without a password to any other node in the same zone, cannot ssh without being prompted for a password to nodes in another zone.

Currently XCAT changes root ssh keys on the service nodes (SN) and compute nodes (CN) that are generated at install time to the root ssh keys from the Management node. It also changes the ssh hostkeys on the SN and CN to a set of pre-generated hostkeys from the MN. Putting the RSA public key in the authorized-keys file on the service nodes and compute nodes allows passwordless ssh to the Service Nodes (SN) and the compute nodes from the Management Node (MN). Today, by default, all nodes in the xCAT cluster are setup to be able to passwordless ssh to other nodes.
except when using the site sshbetweennodes attribute. More on that later. The pre-generated hostkey makes all nodes look like the same to ssh, so you are never prompted for updates to known_hosts.

The new support only addresses the way we generate and distribute root’s ssh RSA keys. Hostkey generation and distribution is not affected. It only supports setting up zones for the root userid. Non-root users are not affected. The Management node (MN) and Service Nodes (SN) are still setup so that root can ssh without password to the nodes from the MN and SN’s for xCAT command to work. Also, the SN’s should be able to ssh to each other with a password. Compute nodes and Service Nodes are not setup by xCAT to be able to ssh to the Management Node without being prompted for a password. This is to protect the Management Node.

In the past, the setup allowed compute nodes to be able to ssh to the SN’s without a password. Using zones, will no longer allow this to happen. Using zones only allows compute nodes to ssh without password to compute node, unless you add the service node into the zone which is not considered a good idea.

But add service node into a zone is not a good idea. Because:

- IF you put the service node in a zone, it will no longer be able to ssh to the other servicenodes with being prompted for a password.
- Allowing the compute node to ssh to the service node, could allow the service node to be compromised, by anyone who gained access to the compute node.
- It is recommended to not put the service nodes in any zones and then they will use the default zone which today will assign the root’s home directory ssh keys as in previous releases. More on the default zone later.

If you do not wish to use zones, your cluster will continue to work as before. The root ssh keys for the nodes will be taken from the Management node’s root’s home directory ssh keys or the Service node’s root’s home directory ssh keys (hierarchical case) and put on the nodes when installing, running xdsh -K or updatenode -k. To continue to operate this way, do not define a zone. The moment you define a zone in the database, you will begin using zones in xCAT.

**Configure Zones**

Setting up zones only applies to nodes. We will still use the MN root ssh keys on any devices, switches, hardware control. All ssh access to these devices is done from the MN or SN. The commands that distribute keys to these entities will not recognize zones (e.g. rspconfig, xdsh -K --devicetype). You should never define, the Management Node in a zone. The zone commands will not allow this.

The ssh keys will be generated and store in /etc/xcat/sshkeys/<zonename>/.ssh directory. You must not change this path. XCAT will manage and sync this directory to the service nodes as need for hierarchy.

When using zones, the site table sshbetweennodes attribute is no longer use. You will get a warning that it is no longer used, if it is set. You can just remove the setting to get rid of the warning. The zone table sshbetweennodes attribute is used so this can be assigned for each zone. When using zones, the attribute can only be set to yes/no. Lists of nodegroups are not supported as was supported in the site table sshbetweennodes attributes. With the ability of creating zones, you should be able to setup your node groups to allow or not allow passwordless root ssh as before.

There are three commands to support zones:

- **mkzone** - creates the zones
- **chzone** - changes a previously created zone
- **rmzone** - removes a zone

**Note:** It is highly recommended that you only use the zone commands for creating and maintaining your zones. They do a lot of maintaining of tables and directories for the zones when they are running.
Create Zones

The first time you run `mkzone`, it is going to create two zones. It will create the zone you request, but automatically add the xCAT default zone. This command creates the two zones, but does not assign it to any nodes. There is a new attribute on the nodes called `zonename`. As long as it is not defined for the node, then the node will use what is currently defined in the database as the defaultzone.

**Note:** if zones are defined in the zone table, there must be one and only one default zone. If a node does not have a zonename defined and there is no defaultzone in the zone table, it will get an error and no keys will be distribute.

For example:

```
#mkzone zone1
#lsdef -t zone -l
Object name: xcatdefault
  defaultzone=yes
  sshbetweennodes=yes
  sshkeydir=/root/.ssh
Object name: zone1
  defaultzone=no
  sshbetweennodes=yes
  sshkeydir=/etc/xcat/sshkeys/zone1/.ssh
```

Another example which makes the zone and defines the nodes in the mycompute group in the zone and also automatically creates a group on each node by the zonename is the following:

```
#makezone zone2 -a mycompute -g
#lsdef mycompute
Object name: node1
  groups=zone2,mycompute
  postbootstrapscripts=otherpkgs
  postscripts=syslog,remoteshell,syncfiles
  zonename=zone2
```

At this time we have only created the zone, assigned the nodes and generated the SSH RSA keys to be distributed to the node. To setup the ssh keys on the nodes in the zone, run the following `updatenode` command. It will distribute the new keys to the nodes, it will automatically sync the zone key directory to any service nodes and it will regenerated your `mypostscript.<nodename>` files to include the zonename, if you are using `precreatemypostscripts` enabled.

```
updatenode mycompute -k
```

You can also use the following command but it will not regenerated the `mypostscript.<nodename>` file.

```
xdsh mycompute -K
```

If you need to install the nodes, then run the following commands. They will do everything during the install that the `updatenode` did. Running `nodeset` is very important, because it will regenerate the `mypostscript` file to include the zonename attribute.

```
nodeset mycompute osimage=<mycomputeimage>
rsetboot mycompute net
rpower mycompute boot
```
Change Zones

After you create a zone, you can use the `chzone` command to make changes. Some of the things you can do are the following:

- Add nodes to the zone
- Remove nodes from the zone
- Regenerated the keys
- Change sshbetweennodes setting
- Make it the default zone

The following command will add node1-node10 to zone1 and create a group called zone1 on each of the nodes.

```
chzone zone1 -a node1-node10 -g
```

The following command will remove node20-node30 from zone1 and remove the group zone1 from those nodes.

```
chzone zone1 -r node20-node30 -g
```

The following command will change zone1 such that root cannot ssh between the nodes without entering a password.

```
#chzone zone1 -s no
#lsdef -t zone zone1
Object name: zone1
  defaultzone=no
  sshbetweennodes=no
  sshkeydir=/etc/xcat/sshkeys/zone1/.ssh
```

The following command will change zone1 to the default zone.

**Note:** you must use the `-f` flag to force the change. There can only be one default zone in the `zone` table.

```
#chzone zone1 -f --defaultzone
#lsdef -t zone -l
Object name: xcatdefault
  defaultzone=no
  sshbetweennodes=yes
  sshkeydir=/root/.ssh
Object name: zone1
  defaultzone=yes
  sshbetweennodes=no
  sshkeydir=/etc/xcat/sshkeys/zone1/.ssh
```

Finally, if your root ssh keys become corrupted or compromised you can regenerate them.

```
chzone zone1 -K
```

or

```
chzone zone1 -k <path to SSH RSH private key>
```

As with the `mkzone` commands, these commands have only changed the definitions in the database, you must run the following to distribute the keys.
The `rmzone` command will remove a zone from the database. It will also remove the zone name from the `zonename` attribute on all the nodes currently defined in the zone and as an option `-g` will remove the group zonename from the nodes. The zonename attribute will be undefined, which means the next time the keys are distributed, they will be picked up from the defaultzone. It will also remove the `/etc/xcat/sshkeys/<zonename>` directory.

Note: `rmzone` will always remove the zonename defined on the nodes in the zone. If you use other xCAT commands and end up with a zonename defined on the node that is not defined in the zone table, when you try to distribute the keys you will get errors and the keys will not be distributed.

`rmzone zone1 -g`

If you want to remove the default zone, you must use the `-f` flag. You probably only need this to remove all the zones in the zone table. If you want to change the default zone, you should use the `chzone` command.

Note: if you remove the default zone and nodes have the `zonename` attribute undefined, you will get errors when you try to distribute keys.

`rmzone zone1 -g -f`

As with the other zone commands, after the location of a nodes root ssh keys has changed you should use one of the following commands to update the keys on the nodes:

`updatenode mycompute -k`

or

`xdsh mycompute -K`
By managing the inventory file under source control system, you can manage the xCAT cluster definition under source control. This section presents a typical step-by-step scenario on how to manage cluster inventory data under git.

1. create a directory /git/cluster under git directory to hold the cluster inventory

```bash
mkdir -p /git/cluster
cd /git/cluster
git init
```

2. export the current cluster configuration to a inventory file “mycluster.yaml” under the git directory created above

```bash
xcat-inventory export --format=yaml >/git/cluster/mycluster.yaml
```

3. check diff and commit the cluster inventory file(commit no: c95673)

```bash
cd /git/cluster
git diff
git add /git/cluster/mycluster.yaml
git commit /git/cluster/mycluster.yaml -m "$(date "+%Y_%m_%d_%H_%M_%S")": initial
→cluster inventory data; blah-blah"
```

4. ordinary cluster maintenance and operation: replaced bad nodes, turn on xcatdebugmode...

5. cluster setup is stable now, export and commit the cluster configuration(commit no: c95673)

```bash
xcat-inventory export --format=yaml >/git/cluster/mycluster.yaml
cd /git/cluster
git diff
git add /git/cluster/mycluster.yaml
git commit /git/cluster/mycluster.yaml -m $(date "+%Y_%m_%d_%H_%M_%S")": replaced
→bad nodes; turn on xcatdebugmode; blah-blah"
```

6. ordinary cluster maintenance and operation, some issues are founded in current cluster, need to restore the current cluster configuration to commit no c95673

```bash
cd /git/cluster
git checkout c95673
xcat-inventory import -f /git/cluster/mycluster.yaml
```

Notice:

1. The cluster inventory data exported by xcat-inventory does not include intermidiate data, transiate data and historical data in xCAT DataBase, such as node status, auditlog table

2. We suggest you backup your xCAT database by dumpxCATdb before your trial on this feature, although we have run sufficient test on this

**Define and create your first xCAT cluster easily**

The inventory templates for 2 kinds of typical xCAT cluster is shipped. You can create your first xCAT cluster easily by making several modifications on the template. The templates can be found under `/opt/xcat/share/xcat/inventory_templates` on management node with xcat-inventory installed.

Currently, the inventory templates includes:

1. When you import the inventory data to xCAT Database in step 6, there are 2 modes: clean mode and update mode. If you choose the clean mode by xcat-inventory import -c|--clean, all the objects definitions that are not included in the inventory file will be removed; Otherwise, only the objects included in the inventory file will be updated or inserted. Please choose the proper mode according to your need.
1. flat_cluster_template.yaml:
   a flat baremetal cluster, including openbmc controlled PowerLE servers, IPMI controlled Power
   servers(commented out), X86_64 servers(commented out)

2. flat_kvm_cluster_template.yaml: a flat KVM based Virtual Machine cluster, including PowerKVM based VM
   nodes, KVM based X86_64 VM nodes(commented out)

The steps to create your first xCAT cluster is:

1. create a customized cluster inventory file “mycluster.yaml” based on flat_cluster_template.yaml

   ```shell
   cp /opt/xcat/share/xcat/inventoryTemplates/flat_cluster_template.yaml /git/
   →cluster/mycluster.yaml
   ```

2. customize the cluster inventory file “mycluster.yaml” by modifying the attributes in the line under token
   #CHANGEME according to the setup of your physical cluster. You can create new node definition by duplicating
   and modifying the node definition in the template.

3. import the cluster inventory file

   ```shell
   xcat-inventory import -f /git/cluster/mycluster.yaml
   ```

Now you have your 1st xCAT cluster, you can start bring up the cluster by provision nodes.

### 1.5 Questions & Answers

#### 1.5.1 DNS, Hostname, Alias

**Q: When there are multiple NICs, how to generate /etc/hosts records?**

When there are multiple NICs, and you want to use confignetwork to configure these NICs, suggest to use hosts

table to configure the installation NIC (installnic) and to use nics table to configure secondary NICs. Refer to

the following example to generate /etc/hosts records.

**Best practice example:**

- There are 2 networks in different domains: mgtnetwork and pubnetwork
- mgtnetwork is xCAT management network
- There are 2 adapters in system node1: eth0 and eth1
- Add installnic eth0 10.5.106.101 record in /etc/hosts, its alias is mgtnic
- hostnames node1-pub and node1.public.com are for nic eth1, IP is 192.168.30.101

**Steps:**

1. Add networks entry in networks table:

   ```shell
   chdef -t network mgtnetwork net=10.0.0.0 mask=255.0.0.0 domain=cluster.com
   chdef -t network pubnetwork net=192.168.30.0 mask=255.255.255.0 domain=public.com
   ```

2. Create node1 with installnic IP 10.5.106.101, its alias is mgtnic:

   ```shell
   chdef node1 ip=10.5.106.101 hostnames=mgtnic groups=all
   ```

3. Configure eth1 in nics table:
4. Check node1 definition:

```
lsdef node1
Object name: node1
    groups=all
    ip=10.5.106.101
    hostnames=mgtnic
    nicaliases.eth1=node1.public.com
    nichostnamesuffixes.eth1=-pub
    nicips.eth1=192.168.30.101
    nicnetworks.eth1=pubnetwork
    nictypes.eth1=Ethernet
    postbootscripts=otherpkgs
    postscripts=syslog,remoteshell,syncfiles
```

5. Execute makehosts -n to generate /etc/hosts records:

```
makehosts -n
```

6. Check results in /etc/hosts:

```
10.5.106.101 node1 node1.cluster.com mgtnic
192.168.30.101 node1-pub node1.public.com
```

7. Edit /etc/resolv.conf, xCAT management node IP like 10.5.106.2 is nameserver:

```
search cluster.com public.com
nameserver 10.5.106.2
```

8. Execute makedns -n to configure DNS

**Q: How to configure aliases?**

There are 3 methods to configure aliases:

1. Use hostnames in hosts table to configure aliases for the installnic.

2. If you want to use script confignetwork to configure secondary NICs, suggest to use aliases in nics table to configure aliases. Refer to Configure Aliases

3. If you want to generate aliases records in /etc/hosts for secondary NICs and you don’t want to use the script confignetwork to configure these NICs, suggest to use otherinterfaces in hosts table to configure aliases. Refer to following example:

   - If you want to add node1-hd 20.1.1.1 in hosts table, and don’t use confignetwork to configure it, you can add otherinterfaces like this:

   ```
   chdef node1 otherinterfaces=node1-hd:20.1.1.1
   ```

   - After executing makehosts -n, you can get records in /etc/hosts like following:

   ```
   20.1.1.1 node1-hd
   ```
Note: If suffixes or aliases for the same IP are configured in both hosts table and nics table, will cause conflicts. makehosts will use values from nics table. The values from nics table will over-write that from hosts table to create /etc/hosts records.

Q: How to handle the same short hostname in different domains?

You can follow the best practice example.

Best practice example:

• There are 2 networks in different domains: mgtnetwork and pubnetwork
• mgtnetwork is xCAT management network
• Generate 2 records with the same hostname in /etc/hosts, like:

<table>
<thead>
<tr>
<th>IP Address</th>
<th>Hostname</th>
</tr>
</thead>
<tbody>
<tr>
<td>10.5.106.101</td>
<td>node1.cluster.com</td>
</tr>
<tr>
<td>192.168.20.101</td>
<td>node1.public.com</td>
</tr>
</tbody>
</table>

• Nameserver is xCAT management node IP

Steps:

1. Add networks entry in networks table:

```
chdef -t network mgtnetwork net=10.0.0.0 mask=255.0.0.0 domain=cluster.com
chdef -t network pubnetwork net=192.168.30.0 mask=255.255.255.0 domain=public.com
```

2. Create node1 with ip=10.5.106.101, xCAT can manage and install this node:

```
chdef node1 ip=10.5.106.101 groups=all
```

3. Create node1-pub with ip=192.168.30.101, this node is only used to generate /etc/hosts records for public network, can use _unmanaged group name to label it:

```
chdef node1-pub ip=192.168.30.101 hostnames=node1.public.com groups=_unmanaged
```

4. Execute makehosts -n to generate /etc/hosts records:

```
makehosts -n
```

5. Check results in /etc/hosts:

```
10.5.106.101 node1 node1.cluster.com
192.168.30.101 node1-pub node1.public.com
```

6. Edit /etc/resolv.conf, for example, xCAT management node IP is 10.5.106.2:

```
search cluster.com public.com
nameserver 10.5.106.2
```

7. Execute makedns -n to configure DNS

Q: When to use hosts table and nics table?

hosts table is used to store IP addresses and hostnames of nodes. makehosts use these data to create /etc/hosts records. nics table is used to stores secondary NICs details. Some scripts like confignetwork use data
from `nics` table to configure secondary NICs. `makehosts` also use these data to create `/etc/hosts` records for each NIC.

## 1.6 Reference Implementation

Reference documentation created for management of large clusters using xCAT.

### 1.6.1 CORAL

CORAL stands for Collaboration of Oak Ridge, Argonne, and Livermore and is solution that IBM is building for the Department of Energy to superseed its current cluster of Supercomputers.

**Cluster Management**

**Scalability**

**Python framework**

When testing the scale up of xCAT commands against OpenBMC REST API, it was evident that the Perl framework of xCAT did not scale well and was not sending commands to the BMCs in a true parallel fashion.

The team investigated the possibility of using Python framework. This support is implemented using Python 2.x framework.

**Installation**

A new RPM is created that contains the Python code: `xCAT-openbmc-py`. The Python code requires aditional Python libraries that may not be available as an operating system provided package. The following will help resolve the dependencies.

**Using RPM (recommended)**

**Note:** Supported only on RHEL 7.5 for POWER9

**Note:** In a hierachical environment xCAT-openbmc-py must be installed on both Management and Service nodes. On Service node xCAT-openbmc-py can be installed directly by following instructions in Install xCAT-openbmc-py on MN, or xCAT-openbmc-py can be installed on Service node from Management node by following instructions in Install xCAT-openbmc-py on SN from MN

### Install xCAT-openbmc-py on MN

The following repositories should be configured on your Management Node.

- RHEL 7.5 OS repository
• RHEL 7.5 Extras repository
• RHEL 7 EPEL repository (https://fedoraproject.org/wiki/EPEL)
• Fedora28 repository (for gevent and greenlet)

1. Configure RHEL 7.5 OS repository
2. Configure RHEL 7.5 Extras repository
3. Configure EPEL repository

```
```

4. Create a local Fedora28 repository and configure the MN to the FC28 Repo

Here’s an example to configure the Fedora 28 repository at /install/repos/fc28

(a) Make the target repository directory on the MN:

```
mkdir -p /install/repos/fc28/ppc64le/Packages
```

(b) Download the rpms:

```
cd /install/repos/fc28/ppc64le/Packages
wget https://www.rpmfind.net/linux/fedora-secondary/releases/28/Everything/ppc64le/os/Packages/p/python2-gevent-1.2.2-2.fc28.ppc64le.rpm
wget https://www.rpmfind.net/linux/fedora-secondary/releases/28/Everything/ppc64le/os/Packages/p/python2-greenlet-0.4.13-2.fc28.ppc64le.rpm
```

(c) Create a repository in that directory:

```
cd /install/repos/fc28/ppc64le/
createrepo .
```

(d) Create a repo file /etc/yum.repos.d/fc28.repo and set its contents:

```
[fc28]
name=Fedora28 yum repository for gevent and greenlet
baseurl=file:///install/repos/fc28/ppc64le/
enabled=1
gpgcheck=0
```

5. Install xCAT-openbmc-py:

```
yum install xCAT-openbmc-py
```

Install xCAT-openbmc-py on SN from MN

**Attention:** Instructions below assume Service node has access to the Internet. If not, a local EPEL repository would need to be configured on the Management node, similar to the RHEL Extras repository.

1. Copy Packages directory containing gevent and greenlet rpms from /install/repos/fc28/ppc64le to the directory pointed to by otherpkgdir attribute of the osimage.
# Display the directory of otherpkgdir
lsdef -t osimage rhels7.5-ppc64le-install-service -i otherpkgdir -c

# Create Packages directory
mkdir /install/post/otherpkgs/rhels7.5-alternate/tpc64le/xcat/Packages

# Copy rpms
cp /install/repos/fc28/tpc64le/Packages/*.rpm /install/post/otherpkgs/rhels7.5-alternate/tpc64le/xcat/Packages

2. Configure otherpkglist attribute of the osimage

chdef -t osimage rhels7.5-ppc64le-install-service otherpkglist=/opt/xcat/share/xcat/install/rh/service.rhels7.5-ppc64le.otherpkgs.pkglist

3. Add the following entries to the contents of /opt/xcat/share/xcat/install/rh/service.rhels7.5-ppc64le.otherpkgs.pkglist

   ...
   xcat/Packages/python2-gevent
   xcat/Packages/python2-greenlet
   xcat/xcat-core/xCAT-openbmc-py

4. Choose one of the 3 methods below to complete the installation

**Install on diskful SN using updatenode**

If SN was installed without xCAT-openbmc-py package, updatenode can be used to install that package.

1. Sync EPEL repository and key file

   rsync -v /etc/yum.repos.d/epel.repo root@<SN>:/etc/yum.repos.d/
   rsync -v /etc/pki/rpm-gpg/RPM-GPG-KEY-EPEL-7 root@<SN>:/etc/pki/rpm-gpg/

2. Update packages on SN

   updatenode <SN> -S

**Install on diskful SN using rinstall**

1. Configure synclists attribute of osimage

   chdef -t osimage rhels7.5-ppc64le-install-service synclists=/install/custom/netboot/compute.synclist

2. Add the following to the contents of /install/custom/netboot/compute.synclist

   ...
   /etc/yum.repos.d/epel.repo -> /etc/yum.repos.d/epel.repo
   /etc/pki/rpm-gpg/RPM-GPG-KEY-EPEL-7 -> /etc/pki/rpm-gpg/RPM-GPG-KEY-EPEL-7

3. Install SN

   rinstall <SN> osimage=rhels7.5-ppc64le-install-service
Install on diskless SN using reinstall

1. Add EPEL online repository `https://dl.fedoraproject.org/pub/epel/7/ppc64le` to `pkgdir` attribute of osimage:

   ```
   chdef -t osimage -o rhels7.5-ppc64le-netboot-service -p pkgdir=https://dl.fedoraproject.org/pub/epel/7/ppc64le
   ```

2. Install diskless SN

   ```
   genimage rhels7.5-ppc64le-netboot-service
   packimage rhels7.5-ppc64le-netboot-service
   rinstall <SN> osimage=rhels7.5-ppc64le-netboot-service
   ```

Disable Python Framework

By default, if `xcat-openbmc-py` is installed and Python files are there, xCAT will default to running the Python framework.

A site table attribute is created to allow the ability to control between Python and Perl.

- To disable all Python code and revert to the Perl implementation:

  ```
  chdef -t site clustersite openbmcperl=ALL
  ```

- To disable single commands, specify a command separated lists:

  ```
  chdef -t site clustersite openbmcperl="rpower,rbeacon"
  ```

Performance

Supported Commands

The following commands are currently supported:

<table>
<thead>
<tr>
<th>Command</th>
<th>Support</th>
<th>Release</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>rpower</td>
<td>Yes</td>
<td>2.13.11</td>
<td></td>
</tr>
<tr>
<td>rinv</td>
<td>Yes</td>
<td>2.13.11</td>
<td></td>
</tr>
<tr>
<td>rbeacon</td>
<td>Yes</td>
<td>2.13.11</td>
<td></td>
</tr>
<tr>
<td>rspconfig</td>
<td>No</td>
<td>2.14</td>
<td></td>
</tr>
<tr>
<td>rsetboot</td>
<td>Yes</td>
<td>2.13.11</td>
<td></td>
</tr>
<tr>
<td>rvitals</td>
<td>Yes</td>
<td>2.13.11</td>
<td></td>
</tr>
<tr>
<td>rflash</td>
<td>No</td>
<td></td>
<td></td>
</tr>
<tr>
<td>reventlog</td>
<td>No</td>
<td>2.14</td>
<td></td>
</tr>
</tbody>
</table>

Data

The following graph shows performance gains in the Python code implementation of `mgt=openbmc` when compared to the Perl implementation.
**rpower <noderange> state**

This chart gathers data points on a single 18-node frame, up to 4 frames (72-nodes).

---

**Power9 Firmware Update**

**IPMI Firmware Update**

The process for updating firmware on the IBM Power9 Server (Boston) is documented below.

**Collect the required files**

Collect the following files and put them into a directory on the Management Node.

- pUpdate utility
- .pnor for host
- .bin for bmc

If running `rflash` in Hierarchy, the firmware files/directory must be accessible on the Service Nodes.

**Flash Firmware**

Using xCAT `rflash` command, specify the directory containing the files with the `-d` option.

```
rflash <noderange> -d /path-to-directory/
```

The `pUpdate` utility is leveraged in doing the firmware update against the target node and will do the following:

- power off the host
- flash bmc and reboot
• flash host
• power on the host
Monitor the progress for the nodes by looking at the files under /var/log/xcat/rflash/.

Validation

Use the `rinv` command to validate firmware level:

```
rinv <noderange> firm | xcoll
```

OpenBMC Firmware Update

Unattended Firmware Flash

Unattended flash of OpenBMC firmware will do the following events:
1. Upload both BMC firmware file and Host firmware file
2. Activate both BMC firmware and Host firmware
3. If BMC firmware becomes activate, reboot BMC to apply new BMC firmware, or else, `rflash` will exit
4. If BMC itself state is `NotReady`, `rflash` will exit
5. If BMC itself state is `Ready`, and use `--no-host-reboot` option, `rflash` will not reboot the compute node
6. If BMC itself state is `Ready`, and do not use `--no-host-reboot` option, `rflash` will reboot the compute node to apply Host firmware

Use the following command to flash the firmware unattended:

```
rflash <noderange> -d /path/to/directory
```

Use the following command to flash the firmware unattended and not reboot the compute node:

```
rflash <noderange> -d /path/to/directory --no-host-reboot
```

If there are errors encountered during the flash process, take a look at the manual steps to continue flashing the BMC.

Validation

Use one of the following commands to validate firmware levels are in sync:

- Use the `rinv` command to validate firmware level:

  ```
rinv <noderange> firm -V | grep -i ibm | grep "\*" | xcoll
```

- Use the `rflash` command to validate the firmware level:

  ```
rflash <noderange> -l | grep "\*" | xcoll
```
Manual Firmware Flash

The sequence of events that must happen to flash OpenBMC firmware is the following:

1. Power off the Host
2. Upload and Activate BMC
3. Reboot the BMC (applies BMC)
4. Upload and Activate Host
5. Power on the Host (applies Host)

Power off Host

Use the rpower command to power off the host:

```bash
rpower <noderange> off
```

Upload and Activate BMC Firmware

Use the rflash command to upload and activate the Host firmware:

```bash
rflash <noderange> -a /path/to/obmc-phosphor-image-witherspoon.ubi.mtd.tar
```

If running rflash in Hierarchy, the firmware files must be accessible on the Service Nodes.

**Note:** If a .tar file is provided, the -a option does an upload and activate in one step. If an ID is provided, the -a option just does activate the specified firmware. After firmware is activated, use the rflash <noderange> -l to view. The rflash command shows (*) as the active firmware and (+) on the firmware that requires reboot to become effective.

Reboot the BMC

Use the rpower command to reboot the BMC:

```bash
rpower <noderange> bmcreboot
```

The BMC will take 2-5 minutes to reboot, check the status using: rpower <noderange> bmcstate and wait for BMCReady to be returned.

**Known Issue:** On reboot, the first call to the BMC after reboot, xCAT will return Error: BMC did not respond within 10 seconds, retry the command.. Please retry.

Upload and Activate Host Firmware

Use the rflash command to upload and activate the Host firmware:

```bash
rflash <noderange> -a /path/to/witherspoon.pnor.squashfs.tar
```
If running `rflash` in Hierarchy, the firmware files must be accessible on the Service Nodes.

**Note:** The `-a` option does an upload and activate in one step, after firmware is activated, use the `rflash <noderange> -l` to view. The `rflash` command shows (*) as the active firmware and (+) on the firmware that requires reboot to become effective.

### Power on Host

User the `rpower` command to power on the Host:

```
rpower <noderange> on
```

### Validation

Use one of the following commands to validate firmware levels are in sync:

- Use the `rinv` command to validate firmware level:
  
  ```
  rinv <noderange> firm -V | grep -i ibm | grep "\*" | xcoll
  ```

- Use the `rflash` command to validate the firmware level:
  
  ```
  rflash <noderange> -l | grep "\*" | xcoll
  ```

### Known Issues

**xCAT Genesis Base**

**Note:** Please rebuild `xCAT-genesis-base` with `xCAT-genesis-builder` version equal and newer than 2.13.10 before updating `xCAT` 2.13.10 and higher.

`xCAT` ships a `xCAT-genesis-base` package as part of xcat-deps. This is a light-weight diskless linux image based on Fedora (Fedora26, currently) that is used by `xCAT` to do hardware discovery.

To support the Power9 hardware, changes are made to the kernel in the Red Hat Enterprise distribution that are not yet available in the Fedora kernels. Without that support, running the scripts in `xCAT` discovery caused segmentation faults described in this issue: [https://github.com/xcat2/xcat-core/issues/3870](https://github.com/xcat2/xcat-core/issues/3870)

**Work-around**

`xCAT` cannot ship a kernel based on RHEL distribution, so the customer needs to build a version of the `xCAT-genesis-base` on-site using a server running Red Hat Enterprise Linux.

1. Download the latest timestamp version of the `xCAT-genesis-builder` RPM provided here: [http://xcat.org/files/xcat/xcat-dep/2.x_Linux/beta/](http://xcat.org/files/xcat/xcat-dep/2.x_Linux/beta/)

2. Install the `xCAT-genesis-builder` RPM on a node that is installed with the RHEL version being deployed.

3. Build the `xCAT-genesis-base` RPM:
   
   ```
   /opt/xcat/share/xcat/netboot/genesis/builder/buildrpm
   ```

4. Install this package on top of the `xCAT` install and execute: `mknb ppc64`
HA

HA Solution Overview

While a xCAT management node xcatmn1 is running as a primary management node, another node - xcatmn2 can be configured to act as primary management node in case xcatmn1 becomes unavailable. The process is manual and requires disabling primary xcatmn1 and activating backup xcatmn2. Both nodes require access to shared storage described below. Use of Virtual IP is also required.

An interactive sample script xcatha.py is available to guide through the steps of disabling and activation of xCAT management nodes. Dryrun option in that script allows viewing the actions without executing them.

Configure and Activate Primary xCAT Management Node

Disable And Stop All Related Services on Primary xCAT Management Node

Before configuring Virtual IP and shared data, make sure to stop related services. Since primary management node may become unavailable at any time, all related services should be configured to not auto start at boot time.

Use xcatha.py -d to disable and stop all related services:

```bash
./xcatha.py -d
2018-06-22 03:43:51,600 - INFO - [xCAT] Shutting down services:
... goconserver
... conserver
... ntpd
... dhcpd
... named
... xcatd
... postgresql
Y
... ...
[xCAT] Disabling services from starting on reboot:
... goconserver
... conserver
... ntpd
... dhcpd
... named
... xcatd
... postgresql
Y
```

Configure Virtual IP

Existing xCAT management node IP should be configured as Virtual IP address, the Virtual IP address should be non-persistent, it needs to be re-configured right after the management node is rebooted. This non-persistent Virtual IP address is designed to avoid ip address conflict when the original primary management node is recovered with this Virtual IP address configured. Since the Virtual IP is non-persistent, the network interface should have a persistent IP address.

1. Configure another IP on primary management node for network interface as static IP, for example, 10.5.106.70:
(a) Configure 10.5.106.70 as static IP:

```bash
ip addr add 10.5.106.70/8 dev eth0
```

(b) Edit `ifcfg-eth0` file as:

```
DEVICE="eth0"
BOOTPROTO="static"
NETMASK="255.0.0.0"
IPADDR="10.5.106.70"
ONBOOT="yes"
```

(c) If want to take new static ip effect immediately, login `xcatmn1` using 10.5.106.70, and restart network service, then add original static IP on primary management node 10.5.106.7 as Virtual IP

```bash
ssh 10.5.106.70 -l root
service network restart
ip addr add 10.5.106.7/8 brd + dev eth0 label eth0:0
```

2. Add 10.5.106.70 into `postgresql` configuration file on primary management node

(a) Add 10.5.106.70 into `/var/lib/pgsql/data/pg_hba.conf`:

```
host all all 10.5.106.7/32 md5
```

(b) Add 10.5.106.70 into `listen_addresses` variable in `/var/lib/pgsql/data/postgresql.conf`:

```
listen_addresses = 'localhost,10.5.106.7,10.5.106.70'
```

3. Modify provision network entry `mgtifname` as `eth0:0` on primary management node:

```
tabedit networks
"10_0_0_0-255_0_0_0","10.0.0.0","255.0.0.0","eth0:0","10.0.0.103","<xcatmaster>","",",","",","","","","1500",""
```

### Configure Shared Data

The following xCAT directory structure should be accessible from primary xCAT management node:

```
/etc/xcat
/install
~/.xcat
/var/lib/pgsql
/tftpboot
```

### Synchronize `/etc/hosts`

Since the `/etc/hosts` is used by xCAT commands, the `/etc/hosts` should be synchronized between the primary management node and backup management node.
Synchronize Clock

It is recommended that the clocks are synchronized between the primary management node and backup management node.

Activate Primary xCAT Management Node

Use `xcatha.py interactive activate xcatmn1`:

```
./xcatha.py -a
[Admin] Verify VIP 10.5.106.7 is configured on this node
Continue? [[Y]es/[N]o]:
Y
[Admin] Verify that the following is configured to be saved in shared storage and accessible from this node:
... /install
... /etc/xcat
... /root/.xcat
... /var/lib/pgsql
... /tftpboot
Continue? [[Y]es/[N]o]:
Y
[xCAT] Starting up services:
... postgresql
... xcatd
... named
... dhcpd
... ntpd
... conserver
... goconserver
Y
2018-06-24 22:13:09,428 - INFO - ===> Start all services stage <===
    domain=cluster.com
Handling bybc0607 in /etc/hosts.
Handling localhost in /etc/hosts.
Handling bybc0609 in /etc/hosts.
Handling localhost in /etc/hosts.
Getting reverse zones, this may take several minutes for a large cluster.
Completed getting reverse zones.
Restarting named
Restarting named complete
Updating DNS records, this may take several minutes for a large cluster.
Completed updating DNS records.
DNS setup is completed
Renamed existing dhcp configuration file to /etc/dhcp/dhcpd.conf.xcatbak

Warning: No dynamic range specified for 10.0.0.0. If hardware discovery is being used, a dynamic range is required.
```
Activate Backup xCAT Management Node to be Primary Management Node

1. Install xCAT on backup xCAT management node xcatmn2 with local disk
2. Switch to PostgreSQL database
3. Disable and deactivate services using xcatha.py -d on both xcatmn2 and xcatmn1
4. Remove Virtual IP from primary xCAT Management Node xcatmn1:
   ```
   ip addr del 10.5.106.7/8 dev eth0:0
   ```
5. Configure Virtual IP on xcatmn2
6. Add Virtual IP into /etc/hosts file
   ```
   10.5.106.7 xcatmn1 xcatmn1.cluster.com
   ```
7. Connect the following xCAT directories to shared data on xcatmn2:
   ```
   /etc/xcat
   /install
   ~/.xcat
   /var/lib/pgsql
   /tftpboot
   ```
8. Add static management node network interface IP 10.5.106.5 into PostgreSQL configuration file
   (a) Add 10.5.106.5 into /var/lib/pgsql/data/pg_hba.conf:
   ```
   host all all 10.5.106.5/32 md5
   ```
   (b) Add 10.5.106.5 into listen_addresses variable in /var/lib/pgsql/data/postgresql.conf:
   ```
   listen_addresses = 'localhost,10.5.106.7,10.5.106.70,10.5.105.5'
   ```
9. Use xcatha.py -a to start all related services on xcatmn2
10. Modify provision network entry mgtifname as eth0:0:
    ```
    tabedit networks
    "10_0_0_0-255_0_0_0","10.0.0.0","255.0.0.0","eth0:0","10.0.0.103","<xcatmaster>",
    "1500","
    ```

Unplanned failover: primary xCAT management node is not accessible

If primary xCAT management node becomes not accessible before being deactivated and backup xCAT management node is activated, it is recommended that the primary node is disconnected from the network before being rebooted. This will ensure that when services are started on reboot, they do not interfere with the same services running on the backup xCAT management node.
1.6.2 PERCS

See documentation here: https://sourceforge.net/p/xcat/wiki/XCAT_Power_775_Hardware_Management/

1.7 Troubleshooting

This chapter introduces the methods of troubleshooting a xCAT cluster. It includes the following parts.

1.7.1 Operating System Installation

The ability to access the installer or to collect logs during the installation process can be helpful when debugging installation problems.

A new attribute is provided in the site table called xcatdebugmode.

- xcatdebugmode=0: Diagnostic entries will be shown in corresponding log files.
- xcatdebugmode=1: Diagnostic entries will be shown in corresponding log files and debug port will be opened.
- xcatdebugmode=2: Diagnostic entries will be shown in corresponding log files, debug port will be opened and SSH access is enabled.

Supported OS:

- RHEL: 6.7 and above
- SLES: 11.4 and above
- UBT: 14.04.3 and above

The following behavior is supported during OS installation:

<table>
<thead>
<tr>
<th>xcatdebugmode</th>
<th>RHEL</th>
<th>SLES</th>
<th>UBT</th>
<th>RHEL</th>
<th>SLES</th>
<th>UBT</th>
<th>RHEL</th>
<th>SLES</th>
<th>UBT</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Y</td>
<td>Y</td>
<td>Y</td>
<td>Y</td>
<td>Y</td>
<td>Y</td>
<td>Y</td>
<td>Y</td>
<td>Y</td>
</tr>
<tr>
<td>1</td>
<td>N</td>
<td>N</td>
<td>N</td>
<td>Y</td>
<td>Y</td>
<td>Y</td>
<td>Y</td>
<td>Y</td>
<td>Y</td>
</tr>
<tr>
<td>2</td>
<td>N</td>
<td>N</td>
<td>N</td>
<td>N</td>
<td>N</td>
<td>N</td>
<td>Y</td>
<td>Y</td>
<td>Y</td>
</tr>
</tbody>
</table>

- Y - the behavior is supported by OS at specified xcatdebugmode level.
- N - the behavior is not supported.

Next chapter introduces the procedures on how to troubleshoot operating system installation.

Log Collection: Collecting logs of the whole installation process

The ability to collect logs during the installation (diskful and diskless) can be enabled by setting the “site.xcatdebugmode” to different levels (0,1,2), which is quite helpful when debugging installation problems.
The diskful provision logs:

<table>
<thead>
<tr>
<th>xcatdebugmode</th>
<th>0</th>
<th>1</th>
<th>2</th>
</tr>
</thead>
<tbody>
<tr>
<td>OS Distribution</td>
<td>RHEL</td>
<td>SLES</td>
<td>UBT</td>
</tr>
<tr>
<td>Pre-Install</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>log MN</td>
<td>N</td>
<td>N</td>
<td>N</td>
</tr>
<tr>
<td>log CN</td>
<td>C1</td>
<td>C1</td>
<td>C2</td>
</tr>
<tr>
<td>Installer</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>log MN</td>
<td>N</td>
<td>N</td>
<td>N</td>
</tr>
<tr>
<td>log CN</td>
<td>C3</td>
<td>C3</td>
<td>C3</td>
</tr>
<tr>
<td>Post-Install</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>log MN</td>
<td>M2</td>
<td>M3</td>
<td>M3</td>
</tr>
<tr>
<td>log CN</td>
<td>C1</td>
<td>C1</td>
<td>C2</td>
</tr>
<tr>
<td>PostBootScript</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>log MN</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>log CN</td>
<td>C1</td>
<td>C1</td>
<td>C2</td>
</tr>
</tbody>
</table>

The diskless provision logs:

<table>
<thead>
<tr>
<th>xcatdebugmode</th>
<th>0</th>
<th>1</th>
<th>2</th>
</tr>
</thead>
<tbody>
<tr>
<td>OS Distribution</td>
<td>RHEL</td>
<td>SLES</td>
<td>UBT</td>
</tr>
<tr>
<td>Provision</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>log MN</td>
<td>N</td>
<td>M3</td>
<td>M3</td>
</tr>
<tr>
<td>log CN</td>
<td>N</td>
<td>N</td>
<td>N</td>
</tr>
<tr>
<td>PostBootScript</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>log MN</td>
<td>M3</td>
<td>M3</td>
<td>M4</td>
</tr>
<tr>
<td>log CN</td>
<td>C1</td>
<td>C1</td>
<td>C2</td>
</tr>
</tbody>
</table>

- **Pre-Install** logs: the logs of pre-installation scripts, including:
  - `%pre` section in anaconda,
  - `<pre-scripts/>` section for SUSE and `partman/early_command` and `preseed/early_command` sections for ubuntu.
  - STDOUT and STDERR of the scripts
  - debug trace output of bash scripts with `set -x`

- **Installer** logs: the logs from the os installer itself, i.e, the logs of installation program (anaconda, autoyast and `preseed`, etc.)

- **Post-Install** logs: the logs of post-installation scripts, including
  - `%post` section in anaconda,
  - `<chroot-scripts/>` and `<post-scripts/>` sections for SUSE and `preseed/late_command` section for ubuntu.
  - STDOUT and STDERR of the scripts
  - debug trace output of bash scripts with `set -x`

- **Provision** logs: the logs during the diskless provision.

- **PostBootScript** logs: the logs during the post boot scripts execution, which are specified in `postbootscripts` attribute of node and osimage definition and run during the 1st reboot after installation.

MN: the logs forwarded to management node:

- M1: the installer logs will be forwarded to the MN in `/var/log/xcat/computes.log` file.
- M2: the error messages will be forwarded to `/var/log/xcat/computes.log` file on MN only when critical error happens.
• M3: the installation logs will be forwarded to /var/log/xcat/computes.log file on MN.
• M4: the debug trace(set -x or -o xtrace) of bash scripts enabled.
• N: the logs will not be forwarded to MN.

CN: the logs on compute node:
• C1 - the installation logs will be saved to /var/log/xcat/xcat.log file on CN.
• C2 - the debug trace(set -x or -o xtrace) of bash scripts enabled.
• C3 - the installer logs will be saved to the CN in /var/log/anaconda for RHEL, /var/log/YaST2 for SLES, /var/log/installer for UBT.
• N - the logs will not be saved to CN.

Enabling Debug Port: Running commands in the installer from MN

This mode is supported with debug level set to 1 or 2

xCAT creates a service inside the installer, listening on port 3054. It executes commands sent to it from the xCAT MN and returns the response output.

The command runcmdinstaller can be used to send request to installer:

Usage: runcmdinstaller <node> "<command>"

Note: Make sure all the commands are quoted by ""

To list all the items under the /etc directory in the installer: runcmdinstaller c910f03c01p03 "ls /etc"

SSH Access: Accessing the installer via “ssh”

This mode is supported with debug level set to 2

When ssh access to the installer is enabled, the admin can login into the installer through:

1. For RHEL, the installation won’t halt, just login into the installer with ssh root@<node>.
2. For SLES, the installation will halt after the ssh server is started, the console output looks like:

```
*** sshd has been started ***

*** login using 'ssh -X root@<node>' ***
*** run 'yast' to start the installation ***
```

Just as the message above suggests, the admin can open 2 sessions and run ssh -X root@<node> with the configured system password in the passwd table to login into the installer, then run yast to continue installation in one session and inspect the installation process in the installer in the other session.

After the installation is finished, the system requires a reboot. The installation will halt again before the system configuration, the console output looks like:

```
*** Preparing SSH installation for reboot ***
*** NOTE: after reboot, you have to reconnect and call yast.ssh ***
```

Just as the message above suggests, the admin should run ssh -X root@<node> to access the installer and run yast.ssh to finish the installation.
Note: For sles12, during the second stage of an SSH installation YaST freezes. It is blocked by the SuSE-Firewall service because the `SYSTEMCTL_OPTIONS` environment variable is not set properly. Workaround: When logged in for the second time to start the second stage of the SSH installation, call `yast.ssh` with the `--ignore-dependencies` as follows:

```
SYSTEMCTL_OPTIONS=--ignore-dependencies yast.ssh
```

3. For UBT, the installation will halt on the message in the console similar to:

```
[!!] Continue installation remotely using SSH
```

Start SSH
To continue the installation, please use an SSH client to connect to the IP address `<node>` and log in as the "installer" user. For example:

```
ssh installer@<node>
```

The fingerprint of this SSH server's host key is:

`<SSH_host_key>`

Please check this carefully against the fingerprint reported by your SSH client.

`<Continue>`

Just as the message above suggests, the admin can run `ssh installer@<node>` with the password “cluster” to login into the installer, the following message shows on login:

```
[!!] Configuring d-i
```

This is the network console for the Debian installer. From here, you may start the Debian installer, or execute an interactive shell.

To return to this menu, you will need to log in again.

Network console option:

```
Start installer
Start installer (expert mode)
Start shell
```

The admin can open 2 sessions and then select “Start installer” to continue installation in one session and select “Start shell” in the other session to inspect the installation process in the installer.

### 1.8 Developers

This page is for developers interested in working with xCAT.
1.8.1 Contributor and Maintainer Agreements

We welcome developers willing to contribute to the xCAT project to help make it better. Follow the guidelines below.

Contributors

- Sign our Contributor License Agreement (CLA). You can find the CLA [here](#).
- If you are contributing on behalf of your employer, we’ll need a signed copy of our Corporate Contributor License Agreement (CCLA). You can find the CCLA [here](#).
- Fork the repo, make your changes, and open pull requests!

Maintainers

If you are an experienced xCAT user and plan to contribute to the xCAT code regularly, you can request to become an xCAT Maintainer (includes git push access) by first sending an email to the xCAT users mailing list (xcat-user@lists.sourceforge.net).

- If approved, complete and sign our xCAT Maintainer License Agreement, then scan and email a PDF file to xcat-legal@lists.sourceforge.net.
- Additional information can be found in our maintainers guide below:

Maintainers Guide

The roles and responsibilities of the maintainers are:

- set the direction for the xCAT project, including architectural and design decisions
- commit code (new function or fixes) to the xCAT Git repository (either their own code, or on behalf of another contributor - see below)
- review requests for xCAT contributors to become maintainers (All such requests will be subject to a vote by current maintainers)
- review and help resolve technical concerns or problems regarding the project

All decisions by the maintainers are made by consensus.

When a maintainer merges a pull request for a contributor they must:

- Require that each code contributor complete and sign the CLA [here](#) or CCLA [here](#) email a PDF copy to xcat-legal@lists.sourceforge.net.
- Require that all code be contributed under the EPL.

xCAT is licensed under the Eclipse Public License.

1.8.2 GitHub

Developers are encouraged to fork the xcat2 repositories, make changes, and submit pull requests. This mechanism allows for better collaboration and gives the community a chance to review and provide feedback before the code is pulled into the product.

GitHub provides excellent documentation on Collaborating and the following is only provided as a quick reference.
Getting Started

Fork a repository

Forking a repository is taking a copy of a GitHub repository and associating it to your own account space so you can make changes to the code base. Since you own this copy, you will have fetch/push access to the repository.

We will first create a fork on the xcat2/xcat-core project so that we can work on functions without affecting the mainline (or upstream) code. Additionally, by creating a fork, you are able to generate pull request so that the changes can be easily seen and reviewed by other community members.

- In GitHub UI, find a project that you want to fork and click on the “Fork” icon.

  ![Fork button](image)

  **Note:** The target is your own account space

- After the fork is created, there is a copy of the repository under your own account

  `<userid>/xcat-core`
  
  `xcat2/xcat-core`

Clone the forked repository

- On your development machine, clone the forked repository from your account:

  **Note:** Ensure the clone is from `<userid>/xcat-core` and not `xcat2/xcat-core`

  ```bash
  $ git clone git@github.com:<userid>/xcat-core.git
  ```

  This now becomes the origin remote repository:

  ```bash
  $ git remote -v
  origin git@github.com:<userid>/xcat-core.git (fetch)
  origin git@github.com:<userid>/xcat-core.git (push)
  ```

Configure an upstream repository

- In order to get updates from the upstream project: `xcat2/xcat-core`, you will need to add another remote repository to fetch from.

  ```bash
  $ git remote add upstream git@github.com:xcat2/xcat-core.git
  ```

  View the configured repositories:

  ```bash
  $ git remote -v
  origin git@github.com:<userid>/xcat-core.git (fetch)
  origin git@github.com:<userid>/xcat-core.git (push)
  upstream git@github.com:xcat2/xcat-core.git (fetch)
  upstream git@github.com:xcat2/xcat-core.git (push)
  ```
Changing Code and Pull Requests

Syncing a Fork

Note: The examples below all reference the master branch

Before the Syncing

References: https://help.github.com/articles/syncing-a-fork/

From time to time, your master branch will start to fall behind the upstream/master because changes are being pulled into the xcat2/xcat-core project from other developers.

Temporarily Stashing work (optional)

If working on changes in another branch, it’s recommended to stash the work before switching to the master branch so the pull does not wipe out any uncommitted changes. To stash work in the current branch:

1. Add (not commit) any untracked files and directories:

   $ git add <untracked_files_and_directories>

2. Stash the work:

   $ git stash

Switch and Update the master branch of your forked copy

1. Switch to the master branch.

   $ git checkout master

2. Pull the commits from the upstream master (xcat2/xcat-core) to your local master branch.

   $ git pull upstream master
   remote: Counting objects: 38, done.
   remote: Compressing objects: 100% (15/15), done.
3. Push the commits from upstream merged to your local master to your forked copy in GitHub:

\$ git push origin master

After the Syncing

Your fork master branch should now be even with xcat2/xcat-core

Unstashing work (optional)

If work has been stashed, to continue back where you left off, switch to the target branch and run: `git stash pop`

Creating Branches

Note: To more easily keep the forked repository and upstream repositories in sync, we recommended that you keep your master branch free from changes and create branches to contain the changes in function you are working on.

Local Branches

Git branches are very light weight and easy to create. Simply use the `git branch <branch_name>` command.

Since we are using pull requests to merge changes back to the upstream project, you will need to have your changes committed to a branch on GitHub (calling this a “remote branch”) so that GitHub can detect differences and pull requests can be created.
Remote Branches


From GitHub

- Under your repository, click on the Branch dropdown and type in a name for the new branch, then hit enter.
  
  In the example below, creating a new branch off ‘master’ called DOC_MERGE

  ![GitHub Interface](image)

- Since we created the branch from the UI, a refresh needs to be done in order to see the new branch. Refresh by fetching from the origin repository:

  ```bash
  $ git fetch origin
  Enter passphrase for key '/home/vhu/.ssh/github/id_rsa':
  From github.com:whowutwut/xcat-doc
  * [new branch]  DOC_MERGE -> origin/DOC_MERGE
  ```

- Show the remote branches: `git branch -r`

  ```bash
  $ git branch -r
  origin/HEAD -> origin/master
  origin/large_cluster
  origin/master
  origin/DOC_MERGE   === NEW BRANCH
  origin/sync
  upstream/master
  ```

From Command Line (CLI)

- Create a branch:
$ git branch
  * master

$ git branch skeleton

$ git branch
  * master
  skeleton

- Push the newly created branch to origin (on GitHub):

$ git push origin skeleton
Enter passphrase for key '/home/vhu/.ssh/github/id_rsa':
Total 0 (delta 0), reused 0 (delta 0)
To git@github.com:whowutwut/xcat-doc.git
  * [new branch] skeleton -> skeleton

Verify that the branch is there by looking at the remote branches:

$ git branch -r
  origin/HEAD -> origin/master
  origin/master
  origin/skeleton  <=== HERE IT IS
  upstream/master

**Changing Code**

**Checkout Branch**

Checkout and switch to the branch using `git checkout -b`

$ git checkout -b mybranch origin/mybranch
Branch mybranch set up to track remote branch mybranch from origin.
Switched to a new branch 'mybranch'

**Changing the code**

Now you are ready to make changes related to your function in this branch

**Multiple Remote Branches**

It may take days before your pull request is properly reviewed and you want to keep changes out of that branch so in the event that you are asked to fix something, you can push directly to the branch with the active pull request.

Creating additional branches will allow you to work on different tasks/enhancements at the same time. You can easily manage your working changes between branches with `git stash`.

**Committing code and pushing to remote branch**

Once your code is ready....
1. Commit the code to your local branch:

```
$ git add <files>
$ git commit | git commit -m "<comments>"
```

2. Push the changes to your remote branch:

```
$ git push origin <branch name>
```

**Pull Requests**

**Creating Pull Requests**

Once your changes are ready to be submitted to the xcat team, the easiest way to generate a pull request is from the GitHub UI.

1. Under your project, click on the “branches” link

2. Find the branch that contains your changes and click on the “New pull request” button

3. Submit the pull request!
Changing Pull Request

After submitting a pull request, you may get comments from reviewer that something needs to be changed. Then you can use following steps to change your pull request.

1. Change any code and add them to be tracked in git

   $ git checkout <mybranch>
   $ vi <files>
   $ git add <files>

2. Commit the change to last commit in the branch instead of creating a new commit. This step is useful to keep the change of this pull request in one commit instead of multiple ones.

   $ git commit --amend

3. Push the new commit to remote repository. Then the commit will be displayed in pull request automatically.

   $ git push origin <mybranch> -f

Resolving Conflicts in the Pull Request

During the reviewing of your pull request, another pull request may be merged which contains changes that conflicts with your change so that your pull request can no longer be merged automatically. You can use following steps to resolve the conflicts.

1. Update the upstream, replace <upstream> with the name if your upstream repo

   $ git fetch <upstream>

2. Checkout to your working branch

   $ git checkout <mybranch>

3. rebase your branch to the master branch in the <upstream>

   $ git rebase <upstream>/master

4. In the previous step, If there are conflicts, the rebase will stop and you will see CONFLICT messages for certain files. Edit the files to resolve the conflicts manually and then use git add the re-add the files to be tracked in git.

   $ vi <files>
   $ git add <files>

5. Continue the rebase repeat the step above for any additional conflicts

   $ git rebase --continue

6. Once the rebase is complete and conflicts are resolved, force push the change to your repository

   $ git push origin <mybranch> -f

If all the conflicts are resolved, the pull request should automatically turn green again and is able to be merged automatically.
Reviewing Pull Requests as a Maintainer

When you are looking over a pull request, you can merge the changes into your own temporary branch to give the code or changes a try before merging into the parent project.

1. From the merge request, click on the command line instructions link:

2. Then under Step 1, there are instruction for creating a temp branch and pulling the changes from the pull request:

   ![Merging via command line](image)

   **Deleting Branches**

   **From Command Line**

   Switch off the branch that you want to delete. Most of the time, switching to master will allow you to delete a working branch:

   ```
   $ git checkout master
   $ git branch -D mybranch
   ```

   Delete the remote branch off GitHub:

   ```
   $ git push origin --delete mybranch
   ```

   Enter passphrase for key `/home/vhu/.ssh/github/id_rsa`:

   To git@github.com:whowutwut/xcat-doc.git

   Verify branch is gone:
Sync up GitHub and Local Machine

There are times when you delete the branch off your local machine or from GitHub and it’s become out of sync, you sync up the list, run the following:

```bash
git remote prune origin
```

1.8.3 Guides

Documentation

Guidelines for xCAT Documentation

The following guidelines should be followed when making changes to the xCAT documentation to help create consistency in the documentation.

Document Structure

Section Structure

xCAT doc page may have 4 levels of title at most:

The First Title
===============

The Second Title
----------------

The Third Title
```````````````

The Forth Title
'''''''''''''''

List Structure

Bullet Lists

• Bullet one

The Content.
• Bullet Two
  The Content.

* Bullet one
  The Content.
+ Bullet Two
  The Content.

Enumerated List

1. Item 1
   1. item a
   2. item b
2. Item 2
   1. item a

1. Item 1
   a) item a
   b) item b
2. Item 2
   a) item a

Include another file

To add contents of a document file inside another file, use .. include::. This is useful when a common information needs to be displayed in multiple files, without the use of a hyperlink.

.. include:: config_common.rst

Note: Do not put customized link targets, such as .. _my_link_target: inside the file to be included. If you do, a warning for a duplicate label will be displayed during the documentation build process.

Index file

Index.rst files contain the .. toctree:: tag. Files listed under that tag will have links to them displayed in the left side navigation area. If a documentation file does not wish to be accessible from the navigation area, do not list it under the .. toctree::.

Note: If a file is not listed under the .. toctree:: it might generate a warning during the documentation build WARNING: document isn't included in any toctree. To eliminate such warning, add the file to the exclude_patterns list in the docs/source/conf.py file. However, do not add a file to the exclude_patterns list if it contains a customized link target, such as .. _my_link_target:. This link target will not be visible to other files and a WARNING: undefined label: will be displayed during the documentation build.

Hyperlinks -> Internal Links -> External Links

Add links to refer other web page is a very common way in writing document, it’s very helpful to reduce the doc duplication and make docs easy to understand. Following are several ways to add a link in the xCAT documentation.
• **Add an Internal Link to “Customized Link Target”**

Customized Link Target means a user defined Link Target.

Define a Link Target named my_link_target:

```
.. _my_link_target:
**Customized Link Target**
```

This part of content is a link target which can be linked by other content.

Link to the customized link target my_link_target my link:

```
:ref:`my link <my_link_target>`
```

**Usage:** This method is used to add a Link Target in any page that can be referred by any other pages.

• **Add an Internal Link to Current Page**

Link to an internal section in current page: Guidelines for xCAT Documentation:

```
`Guidelines for xCAT Documentation`
```

**Usage:** Every title of a section is an auto-generated ‘link target’, so you can use it directly. But it's only available inside the current page.

• **Add an Internal Link to Other Page via File Path**

Link to page http://server/overview/support_list.html with **absolute file path**

```
:doc:`support list </overview/support_list>`
```

Link to page http://server/overview/support_list.html with **relative file path**

```
:doc:`support list </../overview/support_list>`
```

**Usage:** When you want to link to another whole page but don’t want to make a Customized Link Target in that source page, you can use the file path to link it directly.

• **Add an External Link**

Link to an external web page: google:

```
`google <http://www.goole.com>`
```

**Usage:** When you want to link to a page which does not belong to xCAT documentation.

**Note:** The https:// keyword must be added before the web page URL.

• **Add a Link with Explicit URL Displayed**

Link to http://www.google.com:

```
http://www.google.com
```

**Usage:** Make a link and display the URL.
Add OS or ARCH Specific Contents

When writing a common xCAT doc, we always encounter the case that certain small part of content needs to be OS or ARCH specific. In this case, use the following format to add specific branches.

The keyword in the [] can be an OS name or ARCH name, or any name which can distinguish the content from other part.

The valid keyword includes: **RHEL**, **SLES**, **UBUNTU**, **CENTOS**, **X86_64**, **PPC64**, **PPC64LE**. If the keyword is an OS, it can be postfixed with an OS version e.g. RHEL7.

- **[RHEL7]**
  This part of description is for [rh7] specific.
- **[SLES]**
  This part of description is for [sles] specific.
- **[PPC64LE]**
  This part of description is for [ppc64le] specific.

```
**[RHEL7]**

This part of description is for [rh7] specific.
```

Miscellaneous

Add a Comment

The sentence started with .. will be a comment that won’t be displayed in the doc.

```
.. This is a comment
```

Add Literal Block

If you want to add a paragraph of code or something that don’t want to be interpreted by browser:

```
If you want to add a paragraph of code or something that don't want to be interpreted:

#lsdef node1
#tabdump
```

Decorate Word

If you want to display one or several words to be **Literal Word**:

```
If you want to display one or several words to be `Literal Word`
```

If you want to make a **strong emphasis** of the word:

```
If you want to make a **strong emphasis** of the word:
```
Add a Table

Add a table in the doc:

<table>
<thead>
<tr>
<th>Header 1</th>
<th>Header 2</th>
<th>Header 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>body row 1</td>
<td>column 2</td>
<td>column 3</td>
</tr>
<tr>
<td>body row 2</td>
<td>Cells may span columns.</td>
<td></td>
</tr>
<tr>
<td>body row 3</td>
<td>Cells may span rows.</td>
<td>• Cells</td>
</tr>
<tr>
<td>body row 4</td>
<td></td>
<td>• contain</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• blocks.</td>
</tr>
</tbody>
</table>

Add Footnotes

This is the first example of footnotes\(^1\).

This is the second example of footnotes\(^2\).

This \textit{is} the first example of footnotes \([1]\).

This \textit{is} the second example of footnotes \([2]\).

.. \([1]\) First footnote

.. \([2]\) Second footnote

Code Development

Code Standard for Perl

This document gives out a Code Standard for Perl programming in xCAT. All the Perl code which is checked in to xCAT code repository should follow this standard.

This document does not give the coding rules one by one, but give a piece of example code. You need to follow the example code strictly.

This standard referred to the Perl code style from perldoc: \url{http://perldoc.perl.org/perlstyle.html}

\(^1\) First footnote

\(^2\) Second footnote
Tidy Your Code

Meanwhile, you are recommended to use following command line to tidy your code:

```
perltidy -w -syn -g -opt -i=4 -nt -io -nbbc -kbl=2 -pscf=-c -aws \\
   -pt=2 -bbc -nolc <orig_code> -o <formatted_code>
```

How to install perltidy tool:

- **[RHEL]**
  
  ```
yum install perltidy.noarch
  ```

- **[UBUNTU]**
  
  ```
apt-get install perltidy
  ```

Code Standard Example:

```perl
#!/usr/bin/perl

# This is a perl program example to demo the recommended
# style to write perl code

use strict;
use warnings;

#--------------------------------------------------------------------------------
=head3 subroutine_example

Descriptions:
  This a subroutine to demo how to write perl code
Arguments:
  param1: The first parameter
  param2: The second parameter
  param3: The third parameter
Returns:
  0 - success
  0 - fail
=cut

#--------------------------------------------------------------------------------
sub subroutine_example {
  my ($param1, $param2, $param3) = @_;  
  print "In the subroutine subroutine_example.\n";
  return 0;
}

# Declare variables
my $a_local_scale;
my @a_local_array;
my %a_local_hash;
```

(continues on next page)
$a\_local\_scale = 1;
@a\_local\_array = ("a", "b", "c");

@a\_local\_hash = {
    "v1" => 1,
    "v2" => 2,
    "v3" => 3,
};

# Demo how to check the key of hash
if (@a\_local\_hash and
    defined($a\_local\_hash{v1}) and
    defined($a\_local\_hash{v2}) and
    defined($a\_local\_hash{v3})) {
    # Calculate the sum of values
    my $sum\_of\_values = $a\_local\_hash{v1}
        + $a\_local\_hash{v2}
        + $a\_local\_hash{v3};

    print "The sum of values: $sum\_of\_values.\n";
}

# Demo how to check whether the array is empty
if (@a\_local\_array) {
    print "Has element in array: " . join(', ', @a\_local\_array) . "\n";
} elsif ($a\_local\_scale) {
    print "The value of a scale variable: $a\_local\_scale.\n";
} else {
    # None of above
    print "Get into the default path.\n";
}

# Call the subroutine subroutine_example()
subroutine_example($a\_local\_scale, \@a\_local\_array, %a\_local\_hash);
exit 0;

Building Source Code

xcat-core

Clone the xCAT project from GitHub:

cd xcat-core
./buildcore.sh
xcat-deps

The xcat-deps package is currently owned and maintained by the core development on our internal servers. Use the packages created at: http://xcat.org/download.html#xcat-dep

man pages

The xCAT man pages are written in Perl POD files and automatically get built into the xCAT rpms. The content in the .pod files are always the master.

In the past, the man pages were converted into html files and uploaded to SourceForge. In moving to ReadTheDocs we want to also provide the man pages as references in the documentation. To convert the pods to rst, we are using The Perl module: pod2rst.

The following steps will help configure pod2rst and be able to generate the changes .rst files to push to GitHub.

1. Download the following Perl modules:
   - Pod-POM-View-Restructured-0.02
   - Pod-POM-2.00

2. For each of the above Perl modules:
   - [as root] Extract and build the Perl module
     
     perl Makefile.PL
     make
     make install

   - [as non-root] Extract and build the Perl module using PREFIX to specify a directory that you have write permission
     
     mkdir ~/perllib
     perl Makefile.PL PREFIX=~/perllib
     make
     make install

3. Execute the script create_man_pages.py to generate the .rst files into xcat-core/docs:
   - [as root]
     
     cd xcat-core
     ./create_man_pages.py

   - [as non root]
     
     cd xcat-core
     ./create_man_pages.py --prefix=~/perllib

Debug Problems
Tips

1.9 Need Help

xCAT is now on GitHub!

For support, we encourage the use of the GitHub issues system.

- xcat-core
- confluent
- documentation issues can be opened against xcat-core project

The older email list is still available: xcat-user@list.sourceforge.net

1.10 Security Notices

1.10.1 2018 Notices

2018-06-12 - OpenSSL Vulnerabilities

Jun 12, 2018, OpenSSL announced the following security advisories: https://www.openssl.org/news/secadv/20180612.txt

Advisory CVEs

- CVE-2018-0732 - Client DoS due to large DH parameter (Severity: Low)

Please see the security bulletin above for patch, upgrade, or suggested work around information.

Action

xCAT uses OpenSSL for client-server communication but does not ship it.

It is highly recommended to keep your OpenSSL levels up-to-date with the indicated versions in the security bulletins to prevent any potential security threats. Obtain the updated software packages from your Operating system distribution channels.

1.10.2 2017 Notices

2017-12-12 - TLS Vulnerabilities

Dec 12, 2017, TLS implementations may disclose side channel information via discrepancies between valid and invalid PKCS#1 padding

Advisory CVEs

Summary

Transport Layer Security (TLS) is a mechanism for a security transport over network connections, and is defined in RFC 5246. TLS may utilize RSA cryptography to secure the connection, and section 7.4.7 describes how client and server may exchange keys. Implementations that don’t closely follow the descriptions in RFC 5246 may leak information to an attacker when they handle PKCS #1 v1.5 padding errors in ways that lets the attacker distinguish between valid and invalid messages. An attacker may utilize discrepancies in TLS error messages to obtain the pre-master secret key private RSA key used by TLS to decrypt sensitive data. This type of attack has become known as a Bleichenbacher attack. CERT/CC previously published CERT Advisory CA-1998-07 for this type of attack.

Action

Consider the following recommended actions:

1. Disable TLS RSA
2. Apply an update (if available)

xCAT uses OpenSSL for client-server communication but does not ship it.

It is highly recommended to keep your OpenSSL levels up-to-date. Obtain the updated software packages from your Operating system distribution channels.

2017-12-07 - OpenSSL Vulnerabilities

Dec 07, 2017, OpenSSL announced the following security advisories: https://www.openssl.org/news/secadv/20171207.txt

Advisory CVEs

- CVE-2017-3737 - Read/write after SSL object in error state (Severity: Moderate)
  
  This issue does not affect OpenSSL 1.1.0.
  
  OpenSSL 1.0.2 users should upgrade to 1.0.2n

- CVE-2017-3738 - rsaz_1024_mul_avx2 overflow bug on x86_64 (Severity: Low)
  
  Due to the low severity of this issue we are not issuing a new release of OpenSSL 1.1.0 at this time. The fix will be included in OpenSSL 1.1.0h when it becomes available. The fix is also available in commit e502cc86d in the OpenSSL git repository.
  
  OpenSSL 1.0.2 users should upgrade to 1.0.2n

Please see the security bulletin above for patch, upgrade, or suggested work around information.

Action

xCAT uses OpenSSL for client-server communication but does not ship it.

It is highly recommended to keep your OpenSSL levels up-to-date with the indicated versions in the security bulletins to prevent any potential security threats. Obtain the updated software packages from your Operating system distribution channels.
2017-08-28 - OpenSSL Vulnerabilities

Aug 28, 2017, OpenSSL announced the following security advisories: https://www.openssl.org/news/secadv/20170828.txt

Advisory CVEs

• CVE-2017-3735 - Malformed X.509 IPAddressFamily could cause OOB read (Severity: Low)

If an X.509 certificate has a malformed IPAddressFamily extension, OpenSSL could do a one-byte buffer overflow. The most likely result would be an erroneous display of the certificate in text format.

As this is a low severity fix, no release is being made. The fix can be found in the source repository (1.0.2, 1.1.0, and master branches); see https://github.com/openssl/openssl/pull/4276. This bug has been present since 2006.

Please see the security bulletin above for patch, upgrade, or suggested work around information.

Action

xCAT uses OpenSSL for client-server communication but does not ship it.

It is highly recommended to keep your OpenSSL levels up-to-date with the indicated versions in the security bulletins to prevent any potential security threats. Obtain the updated software packages from your Operating system distribution channels.

2017-02-16 - OpenSSL Vulnerabilities

Feb 16, 2017, OpenSSL announced the following security advisories: https://www.openssl.org/news/secadv/20170216.txt

Advisory CVEs

• CVE-2017-3733 - Encrypt-Then-Mac renegotiation crash (Severity:High)

OpenSSL 1.1.0 users should upgrade to 1.1.0e

This issue does not affect OpenSSL version 1.0.2.

Please see the security bulletin above for patch, upgrade, or suggested work around information.

Action

xCAT uses OpenSSL for client-server communication but does not ship it.

It is highly recommended to keep your OpenSSL levels up-to-date with the indicated versions in the security bulletins to prevent any potential security threats. Obtain the updated software packages from your Operating system distribution channels.

2017-01-27 - OpenSSL Vulnerabilities

Jan 26, 2017, OpenSSL announced the following security advisories: https://www.openssl.org/news/secadv/20170126.txt
Advisory CVEs

- CVE-2017-3731 - Truncated packet could crash via OOB read (Severity: Moderate)
- CVE-2017-3730 - Bad (EC)DHE parameters cause a client crash (Severity: Moderate)
- CVE-2017-3732 - BN_mod_exp may produce incorrect results on x86_64 (Severity: Moderate)
- CVE-2016-7055 - Montgomery multiplication may produce incorrect results (Severity: Low)

Please see the security bulletin above for patch, upgrade, or suggested work around information.

Action

xCAT uses OpenSSL for client-server communication but does not ship it.

It is highly recommended to keep your OpenSSL levels up-to-date with the indicated versions in the security bulletins to prevent any potential security threats. Obtain the updated software packages from your Operating system distribution channels.

1.10.3 2016 Notices

2016-11-30 - Removal of Service Stream Password

It has been brought to our attention that the xCAT product has hard-coded default passwords for the HMC/FSP to allow for IBM Service to connect to customer machines for L2/L3 support activities. This creates a security vulnerability where third parties could potentially gain root level access using these weak, hard coded passwords.

Example:

```bash
create_pwd => "netsDynPwdTool --create dev FipSdev",
password => "FipSdev"
```

In response, xCAT will remove these hard-coded password and interfaces from the xCAT code.

Action

No action is required for xCAT 2.12.3, and higher.

If running older versions of xCAT, update xCAT to a higher level code base that has the hard-coded default passwords removed.

The following table describes the recommended update path:

<table>
<thead>
<tr>
<th>xCAT Version</th>
<th>Action</th>
<th>Release Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>2.13, or newer</td>
<td>No applicable</td>
<td></td>
</tr>
<tr>
<td>2.12.x</td>
<td>Update to 2.12.3, or higher</td>
<td>2.12.3 Release Notes</td>
</tr>
<tr>
<td>2.11.x</td>
<td>Update to 2.12.3, or higher</td>
<td>2.12.3 Release Notes</td>
</tr>
<tr>
<td>2.10.x</td>
<td>Update to 2.12.3, or higher</td>
<td>2.12.3 Release Notes</td>
</tr>
<tr>
<td>2.9.x, or older</td>
<td>Update to: • 2.9.4, or higher for AIX • 2.12.3, or higher for LINUX</td>
<td>2.9.4 Release Notes</td>
</tr>
</tbody>
</table>
2016-08-24 - OpenSSL Vulnerabilities (Sweet32)

SWEET32: Birthday attacks against TLS ciphers with 64bit block size

CVE-2016-2183

Description: OpenSSL could allow a remote attacker to obtain sensitive information, caused by an error in the in the Triple-DES on 64-bit block cipher, used as a part of the SSL/TLS protocol. By capturing large amounts of encrypted traffic between the SSL/TLS server and the client, a remote attacker able to conduct a man-in-the-middle attack could exploit this vulnerability to recover the plaintext data and obtain sensitive information.

CVE-2016-6329

Description: OpenVPN could allow a remote attacker to obtain sensitive information, caused by an error in the in the Triple-DES on 64-bit block cipher, used as a part of the SSL/TLS protocol. By capturing large amounts of encrypted traffic between the SSL/TLS server and the client, a remote attacker able to conduct a man-in-the-middle attack could exploit this vulnerability to recover the plaintext data and obtain sensitive information.

A detailed description of this issue can be seen in the following blog posting: https://www.openssl.org/blog/blog/2016/08/24/sweet32/

Advisory CVEs

- CVE-2016-2183
- CVE-2016-6329

Action

xCAT uses OpenSSL for client-server communication but does not ship it. It is highly recommended to keep your OpenSSL levels up-to-date with the indicated versions in the security bulletins to prevent any potential security threats. Obtain the updated software packages from your Operating system distribution channels.

2016-08-16 - OpenSSL Vulnerabilities

This vulnerability has no fix available at this time (other then mentioned patches below)

Issue: https://bugzilla.redhat.com/show_bug.cgi?id=1359615

Patch: https://github.com/openssl/openssl/commit/0ed26acce328ec16a3aa635f1ca37365e8c7403a

Advisory CVEs

CVE-2016-2180 - OpenSSL is vulnerable to a denial of service, caused by an out-of-bounds read in the TS_OBJ_print_bio function.

Action

xCAT uses OpenSSL for client-server communication but does not ship it. It is highly recommended to keep your OpenSSL levels up-to-date to prevent any potential security threats.
2016-05-03 - OpenSSL Vulnerabilities (ANS.1 encoder)

May 3, 2016 OpenSSL announced the following security advisories: https://www.openssl.org/news/secadv/20160503.txt

Advisory CVEs

- CVE-2016-2108 - **Memory corruption in the ASN.1 encoder** (Severity: High)
  This issue affects all OpenSSL version prior to April 2015
  OpenSSL 1.0.2 users should upgrade to 1.0.2c OpenSSL 1.0.1 users should upgrade to 1.0.1o

- CVE-2016-2107 - **Padding oracle in AES-NI CBC MAC check** (Severity: High)
  This issue was introduced as part of the fix for Lucky 13 padding attack (CVE-2013-0169)
  OpenSSL 1.0.2 users should upgrade to 1.0.2h OpenSSL 1.0.1 users should upgrade to 1.0.1t

- CVE-2016-2105 - **EVP_EncodeUpdate overflow** (Severity: Low)
  OpenSSL 1.0.2 users should upgrade to 1.0.2h OpenSSL 1.0.1 users should upgrade to 1.0.1t

- CVE-2016-2106 - **EVP_EncryptUpdate overflow** (Severity: Low)
  OpenSSL 1.0.2 users should upgrade to 1.0.2h OpenSSL 1.0.1 users should upgrade to 1.0.1t

- CVE-2016-2109 - **ASN.1 BIO excessive memory allocation** (Severity: Low)
  OpenSSL 1.0.2 users should upgrade to 1.0.2h OpenSSL 1.0.1 users should upgrade to 1.0.1t

- CVE-2016-2176 - **EBCDIC overread** (Severity: Low)
  OpenSSL 1.0.2 users should upgrade to 1.0.2h OpenSSL 1.0.1 users should upgrade to 1.0.1t

Action

xCAT uses OpenSSL for client-server communication but does not ship it.

It is recommended to keep your OpenSSL levels up-to-date with the indicated versions in the security bulletins to prevent any potential security threats.

2016-03-01 - OpenSSL Vulnerabilities (DROWN)

March 1, 2016 OpenSSL announced the following security advisories: https://www.openssl.org/news/secadv/20160301.txt

Advisory CVEs

- CVE-2016-0800 - **Cross-protocol attack on TLS using SSLv2 (DROWN)** (Severity: High)
  This issue affects OpenSSL versions 1.0.1 and 1.0.2.
  OpenSSL 1.0.2 users should upgrade to 1.0.2g OpenSSL 1.0.1 users should upgrade to 1.0.1s

- CVE-2016-0705 - **Double-free in DSA code** (Severity: Low)
  This issue affects OpenSSL versions 1.0.2 and 1.0.1.
  OpenSSL 1.0.2 users should upgrade to 1.0.2g OpenSSL 1.0.1 users should upgrade to 1.0.1s
• CVE-2016-0798 - **Memory leak in SRP database lookups** (Severity:Low)
  This issue affects OpenSSL versions 1.0.2 and 1.0.1.
  OpenSSL 1.0.2 users should upgrade to 1.0.2g OpenSSL 1.0.1 users should upgrade to 1.0.1s

• CVE-2016-0797 - **BN_hex2bn/BN_dec2bn NULL pointer deref/heap corruption** (Severity:Low)
  This issue affects OpenSSL versions 1.0.2 and 1.0.1.
  OpenSSL 1.0.2 users should upgrade to 1.0.2g OpenSSL 1.0.1 users should upgrade to 1.0.1s

• CVE-2016-0797 - **Fix memory issues in BIO_*printf functions** (Severity:Low)
  This issue affects OpenSSL versions 1.0.2 and 1.0.1.
  OpenSSL 1.0.2 users should upgrade to 1.0.2g OpenSSL 1.0.1 users should upgrade to 1.0.1s

• CVE-2016-0702 - **Side channel attack on modular exponentiation** (Severity:Low)
  This issue affects OpenSSL versions 1.0.2 and 1.0.1.
  OpenSSL 1.0.2 users should upgrade to 1.0.2g OpenSSL 1.0.1 users should upgrade to 1.0.1s

• CVE-2016-0703 - **Divide-and-conquer session key recovery in SSLv2** (Severity:High)
  This issue affected OpenSSL versions 1.0.2, 1.0.1l, 1.0.0q, 0.9.8ze and all earlier versions. It was fixed in OpenSSL 1.0.2a, 1.0.1m, 1.0.0r and 0.9.8zf

• CVE-2016-0704 - **Bleichenbacher oracle in SSLv2** (Severity:Moderate)
  This issue affected OpenSSL versions 1.0.2, 1.0.1l, 1.0.0q, 0.9.8ze and all earlier versions. It was fixed in OpenSSL 1.0.2a, 1.0.1m, 1.0.0r and 0.9.8zf

**Action**

xCAT uses OpenSSL for client-server communication but does not ship it. Regarding CVE-2016-0800, xCAT also does not use SSLv2 layer but uses the newer TLS transport layer security.

It is recommended to keep your OpenSSL levels up-to-date with the indicated versions in the security bulletins to prevent any potential security threats.

**2016-01-28 - OpenSSL Vulnerabilities**

*Jan 28, 2016* OpenSSL announced the following security advisories: [https://mta.openssl.org/pipermail/openssl-announce/2016-January/000061.html](https://mta.openssl.org/pipermail/openssl-announce/2016-January/000061.html)

**Advisory CVEs**

• CVE-2016-0701 - **DH small subgroups** (Severity:High)
  This issue affects OpenSSL version 1.0.2. OpenSSL 1.0.2 users should upgrade to 1.0.2f

• CVE-2015-3197 - **SSLv2 doesn’t block disabled ciphers** (Severity:Low)
  This issue affects OpenSSL versions 1.0.2 and 1.0.1.
  OpenSSL 1.0.2 users should upgrade to 1.0.2f OpenSSL 1.0.1 users should upgrade to 1.0.1r
Action

xCAT uses OpenSSL for client-server communication but does not ship it.

It is recommended to keep your OpenSSL levels up-to-date with the indicated versions in the security bulletins to prevent any potential security threats.

2016-01-15 - OpenSSL Vulnerabilities (SLOT)

A detailed description of this issue can be seen in the following blog posting: http://www.mitls.org/pages/attacks/SLOT

Advisory CVEs

CVE-2015-7575 - TLS 1.2 Transcript Collision attacks against MD5 in key exchange protocol (SLOT)

Action

xCAT uses OpenSSL for client-server communication but does not ship it.

It is highly recommended to keep your OpenSSL levels up-to-date with the indicated versions in the security bulletins to prevent any potential security threats. Obtain the updated software packages from your Operating system distribution channels.

Disable MD5 authentication in the cipher list using the site table keyword xcatsslciphers.

1. Check if MD5 is already disabled: tabdump site | grep xcatssl
2. If nothing is set, add ALL:!MD5 to the cipher list: chtab key=xcatsslciphers site. value='ALL:!MD5'
3. Restart xcat: service xcatd restart

1.10.4 2015 Notices

2015-12-03 - OpenSSL Vulnerabilities

OpenSSL announced security fixes on 12/03/15 in the following bulletin: http://openssl.org/news/secadv/20151203.txt

Advisory CVEs

• CVE-2015-3193 - BN_mod_exp may produce incorrect results on x86_64 (Severity:Moderate)

OpenSSL 1.0.2 users should upgrade to 1.0.2e

• CVE-2015-3194 - Certificate verify crash with missing PSS parameter (Severity:Moderate)

OpenSSL 1.0.2 users should upgrade to 1.0.2e OpenSSL 1.0.1 users should upgrade to 1.0.1q

• CVE-2015-3195 - X509_ATTRIBUTE memory leak (Severity:Moderate)

OpenSSL 1.0.2 users should upgrade to 1.0.2e OpenSSL 1.0.1 users should upgrade to 1.0.1q
OpenSSL 1.0.0 users should upgrade to 1.0.0t OpenSSL 0.9.8 users should upgrade to 0.9.8zh

• CVE-2015-3196 - Race condition handling PSK identify hint (Severity:Low)
OpenSSL 1.0.2 users should upgrade to 1.0.2d OpenSSL 1.0.1 users should upgrade to 1.0.1p OpenSSL 1.0.0 users should upgrade to 1.0.0t

- CVE-2015-1794 - **Anon DH ServerKeyExchange with 0 p parameter** (Severity:Low)
  OpenSSL 1.0.2 users should upgrade to 1.0.2e

**Action**

xCAT uses OpenSSL for client-server communication but **does not** ship it. It is recommended to keep your OpenSSL levels up-to-date with the indicated versions in the security bulletins to prevent any potential security threats.

### 2015-05-20 - OpenSSL Vulnerabilities (LOGJAM)

A Logjam vulnerability attacks openssl and web services on weak (512-bit) Diffie-Hellman key groups. Refer to the following documents for details.

Main site: https://weakdh.org/

Server test: https://weakdh.org/sysadmin.html

Refer to the following openssl link for more details regarding the fix: https://www.openssl.org/blog/blog/2015/05/20/logjam-freak-upcoming-changes/

OpenSSL 1.0.2 users should upgrade to 1.0.2b OpenSSL 1.0.1 users should upgrade to 1.0.1n

**Action**

xCAT uses OpenSSL for client-server communication but **does not** ship it. It uses the default ciphers from openssl. It also allows the user to customize it through site.xcatsslversion and site.xcatsslciphers. Make sure you do not enable DH or DHE ciphers.

Get the latest openssl package from the os distros and upgrade it on all the xCAT management nodes, the service nodes and xCAT client nodes.

### 2015-05-19 - OpenSSL Vulnerabilities (VENOM)

**Advisory CVEs**

- **CVE-2015-3456** - (aka VENOM) is a security flaw in the QEMU's Floppy Disk Controller (FDC) emulation.

VENOM vulnerability could expose virtual machines on unpatched host systems

A new vulnerability known as VENOM has been discovered, which could allow an attacker to escape a guest virtual machine (VM) and access the host system along with other VMs running on this system. The VENOM bug could potentially allow an attacker to steal sensitive data on any of the virtual machines on this system and gain elevated access to the host'\'s local network and its systems.

The VENOM bug (CVE-2015-3456) exists in the virtual Floppy Disk Controller for the open-source hypervisor QEMU, which is installed by default in a number of virtualization infrastructures such as Xen hypervisors, the QEMU client, and Kernel-based Virtual Machine (KVM). VENOM does not affect VMware, Microsoft Hyper-V, and Bochs hypervisors.
Action

xCAT does not ship any rpms that have QEMU component directly. However xCAT does make system calls to QEMU when doing KVM/Xen visualization. If you are using xCAT to manage KVM or Xen hosts and quests, get the latest rpms that have QEMU component from the os distro and do a upgrade on both xCAT management node and the KVM/Xen hosts.

2015-04-03 - OpenSSL Vulnerabilities (BAR MITZVAH)

The RC4 Bar mitzvah attack is an attack on the SSL/TLS protocols when both the client and server have RC4 enabled.


Action

xCAT uses OpenSSL shipped with OS distribution for client-server communication. It does not use RC4 ciphers explicitly. However, it allows user to specify xcatsslciphers on the site table for ssl communication. It is recommended that the user not specify RC4 ciphers to avoid the Bar mitzvah attack.

It is also recommended that the user go to the OS distribution to get latest OpenSSL package for the fix of this problem.

2015-03-24 - OpenSSL Vulnerabilities

OpenSSL 1.0.2 introduced the “multiblock” performance improvement. This feature only applies on 64 bit x86 architecture platforms that support AES NI instructions. A defect in the implementation of “multiblock” can cause a segmentation fault within OpenSSL, thus enabling a potential DoS attack.

This issue affects OpenSSL version: 1.0.2

Action

xCAT uses OpenSSL for client-server communication but does not ship it. Upgrade OpenSSL to 1.0.2a or higher.

2015-03-12 - OpenSSL Vulnerabilities (FREAK)

OpenSSL announced security fixes on 01/08/15 in the following bulletin: https://www-origin.openssl.org/news/secadv/20150108.txt
Advisory CVEs

- CVE-2015-0204 RSA silently downgrades to EXPORT_RSA [Client] (Severity: Low)

FREAK vulnerability CVE-2015-0204 is involved when ‘RSA_EXPORT’ ssl cipher suit is used in ssl server/client.

Action

xCAT does not use RSA_EXPORT ciphers for ssl communication by default. However, xCAT does allow user to choose the ciphers from the site.xcatsslciphers attribute.

Make sure you do not put RSA_EXPORT related ciphers in this attribute.

It is recommended that you upgrade openssl to 1.0.1L and upper version for the fix of this problem. Go to the os distribution to get the latest openssl package.